

Probability and Statistics

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- Probability Distributions
- Joint and Conditional Probability Distributions
- Bayes' Rule
- Mean and Variance
- Properties of Gaussian Distribution
- Maximum Likelihood Estimation

Probability

- A sample space S is the set of all possible outcomes of a conceptual or physical, repeatable experiment. (S can be finite or infinite.)
 - E.g., S may be the set of all possible outcomes of a dice roll: S
 (1 2 3 4 5 6)
 - E.g., S may be the set of all possible nucleotides of a DNA site: S
 (A C G T)
 - E.g., S may be the set of all possible time-space positions of an aircraft on a radar screen.
- An Event A is any subset of S
 - Seeing "1" or "6" in a dice roll; observing a "G" at a site; UA007 in space-time interval

Three Key Ingredients in Probability Theory

A sample space is a collection of all possible outcomes

Random variables X represents **outcomes** in sample space

Probability of a random variable to happen p(x) = p(X = x)

$$p(x) = p(X = x)$$

$$p(x) \ge 0$$

Continuous variable

Continuous probability distribution
Probability density function
Density or likelihood value
Temperature (real number)
Gaussian Distribution

$$\int_{x} p(x)dx = 1$$

Discrete variable

Discrete probability distribution
Probability mass function
Probability value
Coin flip (integer)
Bernoulli distribution

$$\sum_{x \in A} p(x) = 1$$

Continuous Probability Functions

- Examples:
 - Uniform Density Function:

$$f_x(x) = \begin{cases} \frac{1}{b-a} & for \ a \le x \le b \\ 0 & otherwise \end{cases}$$

Exponential Density Function:

$$f_x(x) = \frac{1}{\mu} e^{-\frac{x}{\mu}} \qquad for \ x \ge 0$$

$$F_x(x) = 1 - e^{\frac{-x}{\mu}} \qquad for \ x \ge 0$$

Gaussian(Normal) Density Function

$$f_x(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Discrete Probability Functions

- Examples:
 - Bernoulli Distribution:

$$\begin{cases} 1 - p & for \ x = 0 \\ p & for \ x = 1 \end{cases}$$

In Bernoulli, just a **single** trial is conducted

Binomial Distribution:

•
$$P(X = k) = {n \choose k} p^k (1-p)^{n-k}$$

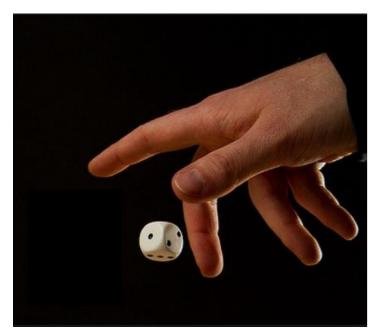
k is number of successes

n-k is number of failures

 $\binom{n}{k}$ The total number of ways of selection **k** distinct combinations of **n** trials, **irrespective of order**.

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Example



X = Throw a dice



Y = Flip a coin

X and **Y** are random variables

N = total number of trials

 n_{ii} = Number of occurrence

X

$$y_{j=2} = tail$$
 $x_{i=1} = 1$ $x_{i=2} = 2$ $x_{i=3} = 3$ $x_{i=4} = 4$ $x_{i=5} = 5$ $x_{i=6} = 6$ $x_{i=6} = 6$

		\mathbf{X}							
		-	$x_{i=2}=2$					C_{j}	
Y	$y_{j=2} = tail$	$n_{ij} = 3$	$n_{ij}=4$	$n_{ij}=2$	$n_{ij} = 5$	$n_{ij}=1$	$n_{ij} = 5$	20	
	$y_{j=1} = head$	$n_{ij}=2$	$n_{ij}=2$	$n_{ij}=4$	$n_{ij}=2$	$n_{ij}=4$	$n_{ij}=1$	15	
	C_i	5	6	6	7	5	6	N=35	

Probability:

$$p(X=x_i)=\frac{c_i}{N}$$

Joint probability:

$$p(X = x_i, Y = y_j) = \frac{n_{ij}}{N}$$

Conditional probability:

$$p(Y = y_j | X = x_i) = \frac{n_{ij}}{c_i}$$

Sum rule

$$p(X = x_i) = \sum_{i=1}^{L} p(X = x_i, Y = y_j) \Rightarrow p(X) = \sum_{Y} P(X, Y)$$

Product rule

$$p(X = x_i, Y = y_j) = \frac{n_{ij}}{N} = \frac{n_{ij}}{c_i} \frac{c_i}{N} = p(Y = y_j | X = x_i) p(X = x_i)$$
$$p(X, Y) = p(Y | X) p(X)$$

Conditional Independence

Examples:

```
P(Virus | Drink Beer) = P(Virus)
  iff Virus is independent of Drink Beer
  P(Flu | Virus; DrinkBeer) = P(Flu | Virus)
  iff Flu is independent of Drink Beer, given Virus
  P(Headache | Flu; Virus; DrinkBeer) =
  P(Headache | Flu; DrinkBeer)
  iff Headache is independent of Virus, given Flu and Drink Beer
Assume the above independence, we obtain:
  P(Headache;Flu;Virus;DrinkBeer)
  =P(Headache | Flu; Virus; DrinkBeer) P(Flu | Virus; DrinkBeer)
   P(Virus | Drink Beer) P(DrinkBeer)
  =P(Headache|Flu;DrinkBeer) P(Flu|Virus) P(Virus) P(DrinkBeer)
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Bayes' Rule

- P(X|Y)= Fraction of the worlds in which X is true given that Y is also true.
- For example:
 - H="Having a headache"
 - F="Coming down with flu"
 - P(Headche|Flu) = fraction of flu-inflicted worlds in which you have a headache. How to calculate?
- Definition:

$$P(X|Y) = \frac{P(X,Y)}{P(Y)} = \frac{P(Y|X)P(X)}{P(Y)}$$

Corollary:

$$P(X,Y) = P(Y|X)P(X)$$

This is called Bayes Rule

Bayes' Rule

•
$$P(Headache|Flu) = \frac{P(Headache,Flu)}{P(Flu)}$$

= $\frac{P(Flu|Headache)P(Headache)}{P(Flu)}$

Other cases:

$$P(Y|X) = \frac{P(X|Y)P(Y)}{P(X|Y)P(Y) + P(X|\neg Y)P(\neg Y)}$$

•
$$P(Y = y_i | X) = \frac{P(X|Y)P(Y)}{\sum_{i \in S} P(X|Y = y_i)P(Y = y_i)}$$

•
$$P(Y|X,Z) = \frac{P(X|Y,Z)P(Y,Z)}{P(X,Z)} = \frac{P(X|Y,Z)P(Y,Z)}{P(X|Y,Z)P(Y,Z)}$$

$$\frac{P(X|Y,Z)P(Y,Z)+P(X|\neg Y,Z)P(\neg Y,Z)}{P(X|Y,Z)P(Y,Z)+P(X|\neg Y,Z)P(\neg Y,Z)}$$

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Mean and Variance

Expectation: The mean value, center of mass, first moment:

$$E_X[g(X)] = \int_{-\infty}^{\infty} g(x)p_X(x)dx = \mu$$

- N-th moment: $g(x) = x^n$
- N-th central moment: $g(x) = (x \mu)^n$
- Mean: $E_X[X] = \int_{-\infty}^{\infty} x p_X(x) dx$
 - $E[\alpha X] = \alpha E[X]$
 - $E[\alpha + X] = \alpha + E[X]$
- Variance(Second central moment): $Var(x) = E_X[(X E_X[X])^2] = E_X[X^2] E_X[X]^2$
 - $Var(\alpha X) = \alpha^2 Var(X)$
 - $Var(\alpha + X) = Var(X)$

For Joint Distributions

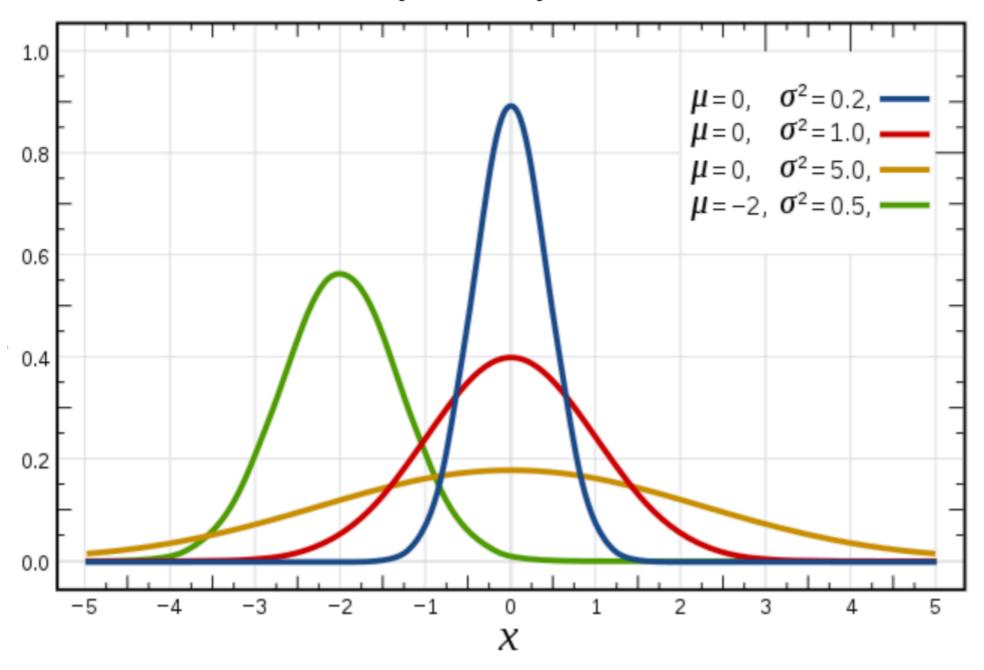
- Expectation and Covariance:
 - $\bullet E[X+Y] = E[X] + E[Y]$
 - $cov(X,Y) = E[(X E_X[X])(Y E_Y(Y))] = E[XY] E[X]E[Y]$
 - Var(X + Y) = Var(X) + 2cov(X, Y) + Var(Y)

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Gaussian Distribution

• Gaussian Distribution:
$$f(x|\mu,\sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Probability density function



Probability versus likelihood

Multivariate Gaussian Distribution

$$p(x|\mu,\Sigma) = \frac{1}{(2\pi)^{n/2}|\Sigma|^{1/2}} \exp\{-\frac{1}{2}(x-\mu)^{\mathsf{T}}\Sigma^{-1}(x-\mu)\}$$

• Moment Parameterization $\mu = E(X)$

$$\Sigma = Cov(X) = E[(X - \mu)(X - \mu)^{\mathsf{T}}]$$

- Mahalanobis Distance $\Delta^2 = (x \mu)^T \Sigma^{-1} (x \mu)$
- Tons of applications (MoG, FA, PPCA, Kalman filter,...)

Properties of Gaussian Distribution

 The linear transform of a Gaussian r.v. is a Gaussian. Remember that no matter how x is distributed

$$E(AX + b) = AE(X) + b$$
$$Cov(AX + b) = ACov(X)A^{T}$$

this means that for Gaussian distributed quantities:

$$X \sim N(\mu, \Sigma) \rightarrow AX + b \sim N(A\mu + b, A\Sigma A^{\mathsf{T}})$$

The sum of two independent Gaussian r.v. is a Gaussian

$$Y = X_1 + X_2, X_1 \perp X_2 \rightarrow \mu_y = \mu_1 + \mu_2, \Sigma_y = \Sigma_1 + \Sigma_2$$

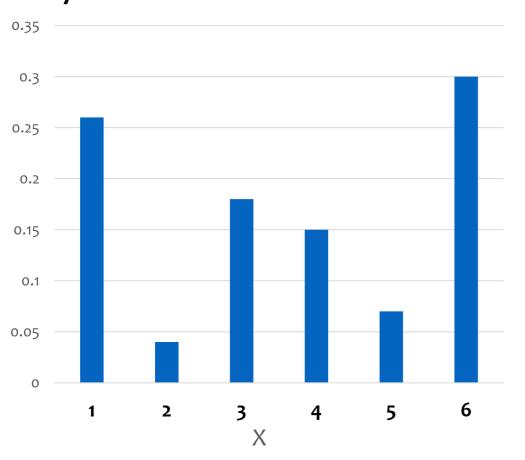
 The multiplication of two Gaussian functions is another Gaussian function (although no longer normalized)

$$N(a,A)N(b,B) \propto N(c,C),$$

where $C = (A^{-1} + B^{-1})^{-1}, c = CA^{-1}a + CB^{-1}b$

Central Limit Theorem

Probability mass function of a biased dice



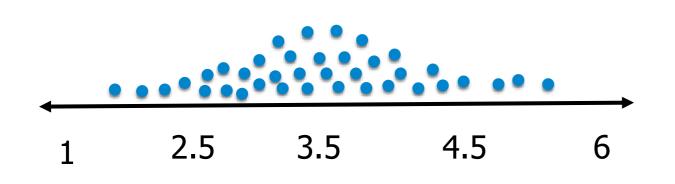
Let's say, I am going to get a sample from this pmf having a size of n = 4

$$S_1 = \{1,1,1,6\} \Rightarrow E(S_1) = 2.25$$

$$S_2 = \{1,1,3,6\} \Rightarrow E(S_2) = 2.75$$

•

$$S_m = \{1,4,6,6\} \Rightarrow E(S_m) = 4.25$$



According to CLT, it will follow a bell curve distribution (normal distribution)

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Maximum Likelihood Estimation

- Probability: inferring probabilistic quantities for data given fixed models (e.g. prob. of events, marginals, conditionals, etc).
- Statistics: inferring a model given fixed data observations (e.g. clustering, classification, regression).

Main assumption:

Independent and identically distributed random variables i.i.d

Maximum Likelihood Estimation

For Bernoulli (i.e. flip a coin):

Objective function:
$$P(x_i|\theta) = \theta^{x_i}(1-\theta)^{1-x_i}$$
 $x_i \in \{0,1\}$ or $\{head, tail\}$

$$L(\theta|X) = L(\theta|X = x_1, X = x_2, X = x_3, ..., X = x_n)$$

i.i.d assumption

$$L(\theta|X) = \prod_{i=1}^{n} P(x_i|\theta)$$

$$L(\theta|X) = \prod_{i=1}^{n} P(x_i|\theta) = \prod_{i=1}^{n} p^{x_i} (1-p)^{1-x_i}$$

$$L(\theta|X) = \theta^{x_1} (1 - \theta)^{1 - x_1} \times \theta^{x_2} (1 - \theta)^{1 - x_2} \dots \times \theta^{x_n} (1 - \theta)^{1 - x_n} = \theta^{\sum x_i} (1 - \theta)^{\sum (1 - x_i)}$$

We don't like multiplication, let's convert it into summation

What's the trick?

Take the log

$$L(\theta|X) = \theta^{\sum x_i} (1 - \theta)^{\sum (1 - x_i)}$$

$$logL(\theta|X) = l(\theta|X) = \log(\theta) \sum_{i=1}^{n} x_i + \log(1-\theta) \sum_{i=1}^{n} (1-x_i)$$

How to optimize θ ?

$$\frac{\partial l(\theta|X)}{\partial \theta} = 0 \qquad \frac{\sum_{i=1}^{n} x_i}{\theta} - \frac{\sum_{i=1}^{n} (1 - x_i)}{1 - \theta} = 0$$

$$\theta = \frac{1}{n} \sum_{i=1}^{n} x_i$$