1.Image preprocessing

```
import json
import os
import glob
import numpy as np
from PIL import Image
from tqdm import tqdm
from torchvision.transforms import functional as F
# 라벨 정보
labels = ['crease', 'crescent_gap', 'inclusion', 'oil_spot',
           'punching_hole', 'rolled_plt', 'silk_spot',
           'waist_folding', 'water_spot', 'welding_line']
def crop_and_save_image(json_path, output_dir, train_ratio=0.9) :
    with open(json_path, 'r', encoding='utf-8') as f:
         json_data = json.load(f)
    # train, val folder create
    train_dir = os.path.join(output_dir, 'train')
    val dir = os.path.join(output dir, 'val')
    os.makedirs(train_dir, exist_ok=True)
    os.makedirs(val_dir, exist_ok=True)
    output dir = "ex02 dataset"
    ex02 dataset
         train
         val
    # labels folder create
    for label in labels:
         train_label_dir = os.path.join(train_dir, label)
         os.makedirs(train_label_dir, exist_ok=True)
         val_label_dir = os.path.join(val_dir, label)
         os.makedirs(val_label_dir, exist_ok=True)
    for filename in tqdm(json_data.keys()) :
         json_image = json_data[filename]
         width = json_image['width']
         height = json_image['height']
         file_name = json_image['filename']
         bboxes = json image['anno']
         # image loader
         image path = os.path.join('./metal data/images', file name)
         image = Image.open(image_path)
         image = image.convert("RGB")
         for bbox_idx, bbox in enumerate(bboxes):
             label_name = bbox['label']
```

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bbox_xyxy = bbox['bbox']
             x1, y1, x2, y2 = bbox_xyxy
             # bounding box crop
             cropped_image = image.crop((x1, y1, x2, y2))
             # padding
             width_, height_ = cropped_image.size
             if width_ > height_:
                 padded_image = Image.new(cropped_image.mode, (width_,width_), (0,))
                 padding = (0, int((width_ - height_) /2))
             else:
                 padded_image = Image.new(cropped_image.mode, (height_, height_), (0,))
                 padding = (int((height - width )/2), 0)
             padded_image.paste(cropped_image, padding)
             # image resize
             size=(255,255)
             resize_image = F.resize(cropped_image, size)
             # train val label folder image save
             if np.random.rand() < train_ratio :</pre>
                 save_dir = os.path.join(train_dir, label_name)
             else:
                 save dir = os.path.join(val dir, label name)
             os.makedirs(save dir. exist ok=True)
             save_path = os.path.join(save_dir, f"{filename}_{label_name}_{bbox_idx}.png")
             padded image.save(save path)
if __name__ == "__main__":
    json_path = "./metal_data/anno/annotation.json"
    output_dir = "./metal_dataset"
    crop_and_save_image(json_path,output_dir)
```

2. CustumDataset 클래스 만들기

```
import os
import cv2
import glob

from torch.utils.data import Dataset
from PIL import Image, ImageFile

class MyDataset(Dataset):
    def __init__(self, data_dir, transforms=None):
        self.data_dir = glob.glob(os.path.join(data_dir, "*", "*.png"))
        self.transforms = transforms
        self.label_dict = self.create_label_dict()

def create_label_dict(self):
        label_dict = {}
```

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for filepath in self.data_dir:
         label = os.path.basename(os.path.dirname(filepath))
         if label not in label_dict:
             label_dict[label] = len(label_dict)
    return label_dict
def __getitem__(self, item):
    image filepath = self.data dir[item]
    img = cv2.imread(image filepath)
    img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
    label = os.path.basename(os.path.dirname(image_filepath))
    label_idx = self.label_dict[label]
    if self.transforms is not None:
         img = self.transforms(image=img)['image']
    return img, label_idx
def __len__(self):
    return len(self.data_dir)
```

3. Train

```
import pandas as pd
import torch.nn as nn
import torch
import torchvision
import albumentations as A
from albumentations.pytorch import ToTensorV2
from torchvision.models.efficientnet import efficientnet_b0, EfficientNet
from torch.optim import AdamW
from torch.nn import CrossEntropyLoss
from tqdm import tqdm
from torch.utils.data import DataLoader
from metal 0717 02 Customdata import MyDataset
import cv2
def train(model, train_loader, val_loader, epochs, optimizer, criterion, device):
    best val acc = 0.0
    train losses = []
    val_losses = []
    train_accs = []
    val_accs = []
    print("Train ....")
    for epoch in range(epochs):
         train_loss = 0.0
         val_loss = 0.0
         val_acc = 0.0
         train_acc = 0.0
         model.train()
         # tqdm
         train_loader_iter = tqdm(train_loader, desc=(f"Epoch : {epoch + 1}/{epochs}"),
```

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leave=False)
         for i, (data, target) in enumerate(train_loader_iter):
             data = data.to(device, dtype=torch.float)
             target = target.to(device)
             optimizer.zero grad()
             outputs = model(data)
             loss = criterion(outputs, target)
             loss.backward()
             optimizer.step()
             train_loss += loss.item()
             # acc
             _, pred = torch.max(outputs, 1)
             train_acc += (pred == target).sum().item()
             train_loader_iter.set_postfix({"Loss": loss.item()})
         train_loss /= len(train_loader)
         train_acc = train_acc / len(train_loader.dataset)
         # eval
         model.eval()
         with torch.no grad():
             for data, target in val loader:
                  data = data.to(device, dtype=torch.float)
                  target = target.to(device)
                  output = model(data)
                  pred = output.argmax(dim=1, keepdim=True)
                  val acc += pred.eq(target.view as(pred)).sum().item()
                  val_loss += criterion(output, target).item()
         val loss /= len(val loader)
         val_acc = val_acc / len(val_loader.dataset)
         train_losses.append(train_loss)
         train_accs.append(train_acc)
         val_losses.append(val_loss)
         val_accs.append(val_acc)
         # save model
         if val acc > best val acc:
             torch.save(model.state_dict(), "./ex01_0714.pt")
             best val acc = val acc
         print(f"Epoch [{epoch + 1}/{epochs}], Train loss [{train loss:.4f}], "
                f"Val loss [{val_loss:.4f}], Train ACC [{train_acc:.4f}], "
                f"Val ACC [{val_acc:.4f}]")
    torch.save(model.state_dict(), "./metal_0717_last.pt")
    return model, train_losses, val_losses, train_accs, val_accs
def main():
    device = torch.device("cuda" if torch.cuda.is available() else "cpu")
    model = efficientnet b0(pretrained=True)
    model._fc = nn.Linear(1280, 10)
```

```
model = model.to(device)
    # aug
    train_transforms = A.Compose([
        A.Resize(width=225, height=225),
        A.RandomShadow(),
        A.RandomBrightnessContrast(),
        A.HorizontalFlip(),
        A.VerticalFlip(),
        ToTensorV2(),
    ])
    val_transforms = A.Compose([
        A.Resize(width=255, height=255),
        ToTensorV2()
    ])
    # dataset dataloader
    train_dataset = MyDataset("./metal_dataset/train/", transforms=train_transforms)
    val_dataset = MyDataset("./metal_dataset/val/", transforms=val_transforms)
    train_loader = DataLoader(train_dataset, batch_size=64, shuffle=True)
    val_loader = DataLoader(val_dataset, batch_size=64, shuffle=False)
    # loss function optimizer, epochs
    epochs = 40
    criterion = CrossEntropyLoss().to(device)
    optimizer = AdamW(model.parameters(), Ir=0.001, weight_decay=1e-2)
    train(model, train_loader, val_loader, epochs, optimizer, criterion, device)
if __name__ == "__main__":
    main()
```

```
Epoch: 1/40: 0%| | 0/51 [00:00<?, ?it/s]Train ....

Epoch: 2/40: 0%| | 0/51 [00:00<?, ?it/s]Epoch [1/40], Train loss [1.0581], Val loss [0.5727], Train ACC [0.7702], Val ACC [0.8347]

Epoch: 3/40: 0%| | 0/51 [00:00<?, ?it/s]Epoch [2/40], Train loss [0.3563], Val loss [0.3645], Train ACC [0.8974], Val ACC [0.8943]

Epoch: 3/40: 94%| | 48/51 [01:14<00:04, 1.57s/it, Loss=0.309]
```

최종적으로 모델이 훈련 중에 있습니다.