

WYATT LUONG

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EDUCATION

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| California State University Los Angeles | Bachelor of Electrical and Computer Engineering Overall GPA: 3.63 Related Coursework: Circuit Analysis, Technical, Oral, and Written Communication, Embedded Programming, Electric Machines, Signals and Systems, Electronics, and Digital Engineering | August 2017-Present |
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EXPERIENCE

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| American Society of Mechanical Engineers – <i>Electrical Engineer Member</i> ; Los Angeles, CA | September 2019 - Present |
| <ul style="list-style-type: none">• Critiqued motor drivers for the robot's motor based on the researched datasheets• Learned how to code Arduino with previous coding experience in a short time.• Identified methods to apply PID (Proportional, Integral and Derivative) concept to operate GPS• Tested the range of the wireless RC controller to ensure functionality• Integrated RC controller onto Arduino to output signals to control the robot wirelessly | |
| NASA Direct Stem – <i>NASA research trainee</i> ; Los Angeles, CA | September 2019 - Present |
| <ul style="list-style-type: none">• Learned Python and applied real life situations using statistical functions from NumPy• Experimented mathematical models through programming | |
| Association for Computing Machinery - <i>Member</i> ; Los Angeles, CA | February 2019 - April 2019 |
| <ul style="list-style-type: none">• Learned how to make a website through HTML and CSS through Visual Studios• Coordinated with other members to help with their website project | |
| Society of Hispanic Engineering and Science - <i>Member</i> ; Los Angeles, CA | January 2018 - May 2018 |
| <ul style="list-style-type: none">• Supervised one team to work on the soda-dispenser project• Helped the team with designing the exterior of the soda dispenser | |

ACADEMIC PROJECTS

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| EE 3450 Robotic Arm (Code + Prototype) – <i>Group In-Class Project</i> | Fall 2019 |
| <ul style="list-style-type: none">• Drafted the robotic arm schematic and theory that corresponds with the design and code• Investigated plans to utilize robotic arm payload when operational• Recorded timeline of the project through progress steps and videos | |
| EE 2450 3D Printer (Code only) – <i>Group In-Class Project</i> | Fall 2018 |
| <ul style="list-style-type: none">• Investigated the situation and tasks on how to program 3-D printer in C programming language• Collaborated with other members on project through GitHub and organized project reports• Integrated user interface by adding in the choice of shapes, 3-D object statistic data, and material inventory control | |
| ENGR 1500 Remotely Operated Underwater Vehicle – <i>Group In-Class Project</i> | Fall 2017 |
| <ul style="list-style-type: none">• Researched the concepts of buoyancy and viscosity before testing the ROV• Designed the vehicle with only the PVC pipes and the propellers from a 3D printer• Tested how the ROV can move underwater with an RC controller installed | |

HONORS

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| • Dean's List (4 semesters) | Spring 2018 - Spring 2020 |
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ADDITIONAL INFORMATION

Computer Skills: Python, MS Excel, Word, C, Java, HTML5, and CSS3

Work Eligibility: Eligible to work in the U.S. with no restrictions

