Ryan Henning

Galvanize

June 2, 2016

Support Vector Machines (SVMs) Lecture

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Support Vector Machines (SVMs) Lecture

- 1. Gain an intuition about the *purpose* and *power* of SVMs.
- 2. Explore (some) of the mathematics behind SVMs.
- **3.** Supercharge SVMs with kernels and soft margins.
- **4.** Gain an intuition about the Bias-Variance tradeoff while using SVMs.

A rough history

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Maximum Margin Classifier: (morning lecture)

1963: Vapnik, Chervonenkis

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This is the modern Support Vector Machine (SVM).

### **Outline**

#### **Review**

### Supervised Learning

Notation

Hyperplanes

#### Motivation

Binary Classification

Margin

Maximum Margin Classifier

#### **SVMs**

Soft Margin

Kernels

Grid Search

**High level:** What is supervised learning?

### High level:

Learn an unknown function from a set of labeled training data.

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Learn an unknown function from a set of labeled training data.

- Our training data is limited and finite. A useful algorithm must generalize well to "unseen" data.
- Example: Children learning colors.
- Support Vector Machines (SVMs) are a supervised learning algorithm.

## **Outline**

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### **Notation**

#### Goal:

Learn a model of a function  $F: X \to Y$  from a training set D.

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Learn a model of a function  $F: X \to Y$  from a training set D.

$$D = \{(x^{(1)}, t^{(1)}), \dots, (x^{(m)}, t^{(m)})\}, \text{ where}$$

- ▶  $x^{(j)} \in X$  is often called the "input".
- ▶  $t^{(j)} \in Y$  is often called the "label" or "target".

# Notation (cont.)

$$F:X\to Y$$

- ▶ Often,  $X = \mathbb{R}^n$
- ▶ Often, Y is a finite set (i.e. a classification task)

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$$F: X \rightarrow Y$$

- ▶ Often,  $X = \mathbb{R}^n$
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We want our learned model to generalize well.

Explain the concept of "generalization error".

# Notation (cont.)

$$F: X \rightarrow Y$$

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We want our learned model to generalize well.

Generalization error is a measure of the model's performance on all possible "unseen" data.

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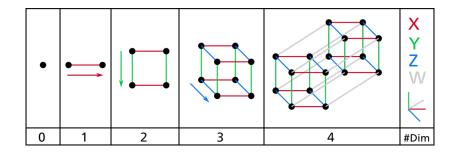
Soft Margin

Kernels

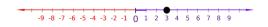
Grid Search

### **Dimensions**

Basic stuff, I know.



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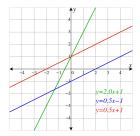
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How do you split this space?

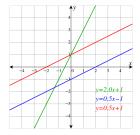


Split a line (1D) with a point (0D).

 $<sup>^1</sup>$ By HakunamentaMathsIsFun at en.wikipedia [CC0], from Wikimedia Commons, Public Domain

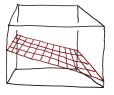


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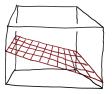


Split a plane (2D) with a line (1D).

<sup>&</sup>lt;sup>1</sup>By ElectroKid (talk • contribs). Original: HiTe. (Modification from the original work.) [CC BY-SA 1.0



How do you split this space?



Split space (3D) with a plane (2D).

## 4D, 5D, etc...

Hard to visualize... :/

In general, an n-dimensional space can be separated by an (n-1)-dimensional hyperplane.

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In general, an n-dimensional space can be separated by an (n-1)-dimensional hyperplane.

In an *n*-dimensional space any hyperplane can be defined by  $w \in \mathbb{R}^n$  and  $b \in \mathbb{R}$ . The hyperplane includes all  $x \in \mathbb{R}^n$  where:

$$w_0x_0 + w_1x_1 + ... + w_{n-1}x_{n-1} - b = 0$$

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usually written:

$$w \cdot x - b = 0$$

## **How to interpret** w and b

So, w and b define a hyperplane. Is there an interpretation of w and b that can help us visualize this hyperplane?

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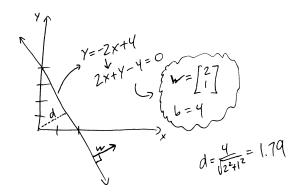
•  $\frac{w}{||w||}$  is the hyperplane's normal vector.

## **How to interpret** *w* and *b*

So, w and b define a hyperplane. Is there an interpretation of w and b that can help us visualize this hyperplane?

- $ightharpoonup \frac{w}{||w||}$  is the hyperplane's normal vector.
- $ightharpoonup \frac{b}{||w||}$  is the hyperplane's distance from the origin.

# Example in 2D



### **Outline**

#### Review

Supervised Learning

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#### Motivation

Binary Classification

Margin

Maximum Margin Classifier

#### **SVMs**

Soft Margin

Kernels

Grid Search

## Binary Classification

A supervised learning problem

Recall, we're trying to learn  $F: X \to Y$ .

- ▶ Let,  $X = \mathbb{R}^n$
- ▶ For binary classification,  $Y = \{-1, 1\}$

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### **Binary Classification**

A supervised learning problem

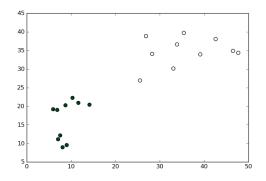
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- ▶ Let,  $X = \mathbb{R}^n$
- For binary classification, Y = {−1,1} We're using -1 instead of 0 for future mathematical convenience.

Big idea: Let's have our model find a hyperplane that splits our n-dimensional data X into the set where y=-1 and the set where y=1.

### **Binary Classification: Example**

How many ways can we use a hyperplane to classify this dataset correctly?



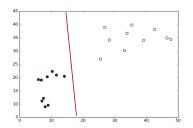
$$X = \mathbb{R}^2$$

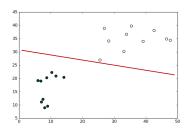
$$Y = \{-1, 1\}$$



### **Binary Classification: Example**

Two Example Solutions





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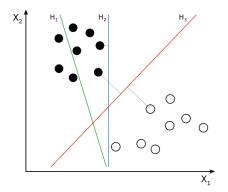
### **Defining Margin**

The distance from the hyperplane to the nearest training-data point.

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### **Defining Margin**

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- ► As margin increases, VC-dimension decreases, meaning variance decreases

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First, some house cleaning: What happens to the hyperplane when we scale w and b by some factor c?

Setup

We need to define a "canonical" w and b. This will help later.

Let

$$|w \cdot x^{(i)} - b| = 1$$

where  $x^{(i)}$  is the closest point to the hyperplane.

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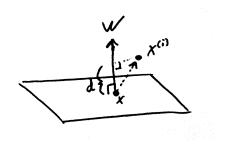
Let

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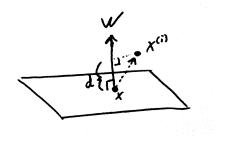
There will be a unique scaled w and b to achieve this.

#### Margin



#### Margin

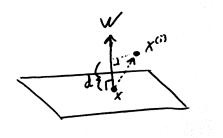
$$\left|\frac{w}{||w||}\cdot(x^{(i)}-x)\right|=d$$



#### Margin

$$\left|\frac{w}{||w||}\cdot(x^{(i)}-x)\right|=d$$

$$\frac{|w \cdot x^{(i)} - w \cdot x|}{||w||} = d$$

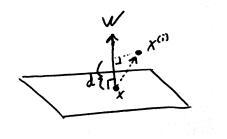


#### Margin

$$\left| \frac{w}{||w||} \cdot (x^{(i)} - x) \right| = d$$

$$\frac{|w \cdot x^{(i)} - w \cdot x|}{||w||} = d$$

$$\frac{|w \cdot x^{(i)} - b - w \cdot x + b|}{||w||} = d$$



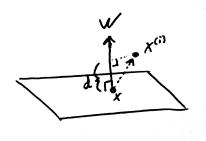
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$$\frac{|w \cdot x^{(i)} - b - w \cdot x + b|}{||w||} = d$$
1

$$\frac{1}{||w||} = d = margin$$



First Attempt

Maximize 
$$\frac{1}{||w||}$$

subject to:

$$|w\cdot x^{(i)}-b|\geq 1,$$

for all 
$$x^{(i)} \in D$$

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... but we don't know how to solve this optimization problem. Let's reformulate.

Reformulated

Minimize 
$$\frac{1}{2}||w||^2$$

subject to:

$$y^{(i)}(w \cdot x^{(i)} - b) \ge 1,$$
  
for all  $(y^{(i)}, x^{(i)}) \in D$ 

Reformulated

Minimize 
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subject to:

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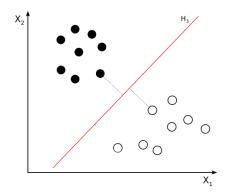
... plus more steps... and we eventually get a quadratic programming formulation.

### **Support Vectors**

The maximum margin hyperplane is defined only by the points that touch the margin. These are called the "support vectors".

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### sklearn's interface

LogisticRegression vs SVC

#### LogisticRegression:

▶ Link

#### SVC:

▶ Link

(end of morning lecture)

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### **Soft Margin Motivation**

#### What if:

- 1. Your data isn't linearly separable?
- 2. Your data is noisy / has outliers?

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#### What if:

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Soft Margins address these problems.

### **Soft Margin**

The C hyperparameter

An extension to Maximum Margin Classifiers adds a  ${\it C}$  constant that gives the misclassification error penalty.

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An extension to Maximum Margin Classifiers adds a  ${\it C}$  constant that gives the misclassification error penalty.

**Large** C: Harder margins: value classification accuracy over a large margin

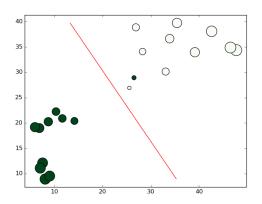
The C hyperparameter

An extension to Maximum Margin Classifiers adds a  $\mathcal{C}$  constant that gives the misclassification error penalty.

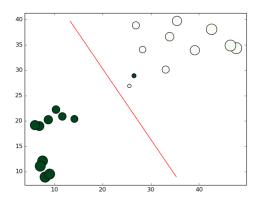
**Large** *C*: Harder margins: value classification accuracy over a large margin

**Small** *C*: Softer margins: value a large margin over classification accuracy

Inseparable Data

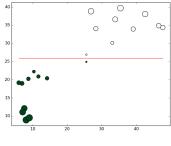


#### Inseparable Data

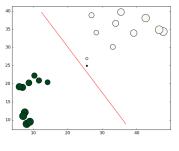


Only possible with a soft margin.

#### **Outliers in Data**



Hard Margin



Soft Margin

scikit-learn code

```
from sklearn.svm import SVC ... svc = SVC(C=1.0, kernel='linear') svc. fit (x, y)
```

SVC supports the  $\it C$  parameter as the soft-margin hyperparameter.

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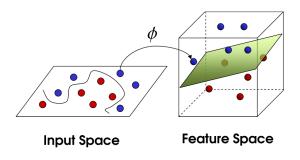
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The idea...

Idea: If data is inseparable in its input space, maybe it will be separable in a higher-dimensional space.





<sup>&</sup>lt;sup>1</sup>Unknown source

Back to the math...

In our optimization problem to maximize the margin, we eventually end up optimizing a vector alpha  $\alpha^{(i)}, i \in [1, m]$  in the following equation:

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$$\mathcal{L}(\alpha) = \sum_{i=1}^{m} \alpha^{(i)} - \frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} y^{(i)} y^{(j)} \alpha^{(i)} \alpha^{(j)} (x^{(i)} \cdot x^{(j)})$$

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Creating a kernel...

$$\phi(x^{(i)}) \cdot \phi(x^{(j)}) \in \mathbb{R}$$

... this is just a real number.

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What if we never applied  $\phi$  and we never took the dot product, but we instead replaced this whole thing with a "kernel function".

Creating a kernel...

$$\phi(x^{(i)}) \cdot \phi(x^{(j)}) \in \mathbb{R}$$

... this is just a real number.

What if we never applied  $\phi$  and we never took the dot product, but we instead replaced this whole thing with a "kernel function".

$$K(x^{(i)}, x^{(j)}) = \phi(x^{(i)}) \cdot \phi(x^{(j)}) \in \mathbb{R}$$

Why is this so cool?

- ▶ Saves some computation. We never need to compute  $\phi$ .
- Opens new possibilities. A kernel can operate in infinite dimensions!

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- ▶ Saves some computation. We never need to compute  $\phi$ .
- Opens new possibilities. A kernel can operate in infinite dimensions!

You can use any  $K(x^{(i)}, x^{(j)})$  as long as there **exists** some  $\phi$  such that

$$K(x^{(i)}, x^{(j)}) = \phi(x^{(i)}) \cdot \phi(x^{(j)})$$

... but you don't have to know what  $\phi$  actually **is!** 

$$K(x^{(i)}, x^{(j)}) = (1 + x^{(i)} \cdot x^{(j)})^d$$

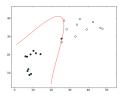
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lacktriangledown equivalent to the dot product in the d-order  $\phi$  space

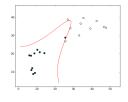
$$K(x^{(i)}, x^{(j)}) = (1 + x^{(i)} \cdot x^{(j)})^d$$

- lacktriangledown equivalent to the dot product in the d-order  $\phi$  space
- ► requires an extra hyper-parameter, d, for "degree"

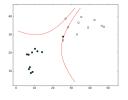
#### **Example**



svc = SVC(C=10000.0, kernel='poly', degree=3)



svc = SVC(C=10000.0, kernel='poly', degree=5)



svc = SVC(C=10000.0, kernel='poly', degree=10)

(Radial Basis Function)

$$K(x^{(i)}, x^{(j)}) = \exp(-\gamma ||x^{(i)} - x^{(j)}||^2)$$

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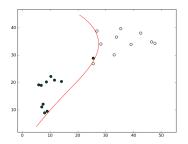
 equivalent to the dot product in the Hilbert space of infinite dimensions

(Radial Basis Function)

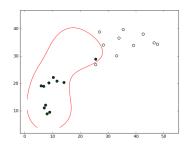
$$K(x^{(i)}, x^{(j)}) = \exp(-\gamma ||x^{(i)} - x^{(j)}||^2)$$

- equivalent to the dot product in the Hilbert space of infinite dimensions
- $\triangleright$  requires an extra hyper-parameter,  $\gamma$ , "gamma"

#### **Examples**

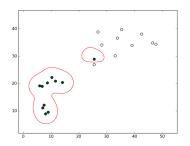


$$svc = SVC(C=10000.0, kernel='rbf', gamma=0.001)$$

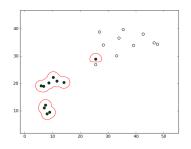


$$svc = SVC(C=10000.0, kernel='rbf', gamma=0.01)$$

#### More Examples



$$svc = SVC(C=10000.0, kernel='rbf', gamma=0.1)$$



$$svc = SVC(C=10000.0, kernel='rbf', gamma=1.0)$$

**Variance** 

## **Bias-Variance tradeoff**

**Explanation** 

Bias

**Explanation** 

#### **Bias**

A high-"bias" model makes many assumptions and prefers to solve problems a certain way.

#### **Variance**

**Explanation** 

#### Bias

A high-"bias" model makes many assumptions and prefers to solve problems a certain way.

E.g. A linear SVM looks for dividing hyperplanes in the input space *only*.

#### Variance

**Explanation** 

#### **Bias**

A high-"bias" model makes many assumptions and prefers to solve problems a certain way.

E.g. A linear SVM looks for dividing hyperplanes in the input space *only*.

For complex data, high-bias models often *underfit* the data.

#### Variance

**Explanation** 

#### **Bias**

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E.g. A linear SVM looks for dividing hyperplanes in the input space *only*.

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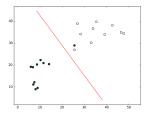
#### Variance

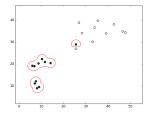
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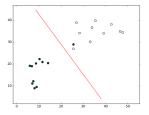
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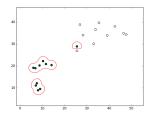




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#### Example





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Which is a better fit for this dataset?

## **Outline**

#### Review

Supervised Learning

Notation

Hyperplanes

#### Motivation

Binary Classification

Margin

Maximum Margin Classifier

#### **SVMs**

Soft Margin

Kernels

Grid Search

Hyperparameter Tuning

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Let's find *C* and *gamma* by searching through values we expect might work well.

Hyperparameter Tuning

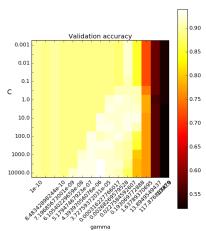
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Use cross-validation accuracy to determine which values are best.

**Hyperparameter Tuning** 

Let's find *C* and *gamma* by searching through values we expect might work well.

Use cross-validation accuracy to determine which values are best.



code

```
svc rbf = SVC(kernel='rbf')
param_space = {'C':
                       np.logspace(-3, 4, 15),
               'gamma': np.logspace(-10, 3, 15)}
grid_search = GridSearchCV(svc_rbf, param_space,
                          scoring='accuracy', cv=10)
grid search.fit(x, y)
print grid search.grid scores
print grid search.best params
print grid search.best score
print grid search.best estimator
```