### Bayesian Inference

Darren Reger Lecture for Galvanize DSI

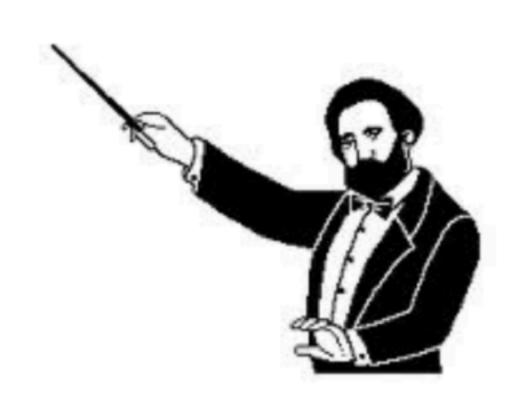
Adapted example from Jim Berger's book, the Likelihood Principle

#### Experiment 1:

A fine classical musician says he's able to distinguish Haydn from Mozart. Small excerpts are selected at random and played for the musician. Musician makes 10 correct guesses in exactly 10 trials.

#### Experiment 2:

Drunken man says he can correctly guess what face of the coin will fall down, mid air. Coins are tossed and the drunken man shouts out guesses while the coins are mid air. Drunken man correctly guesses the outcomes of the 10 throws.





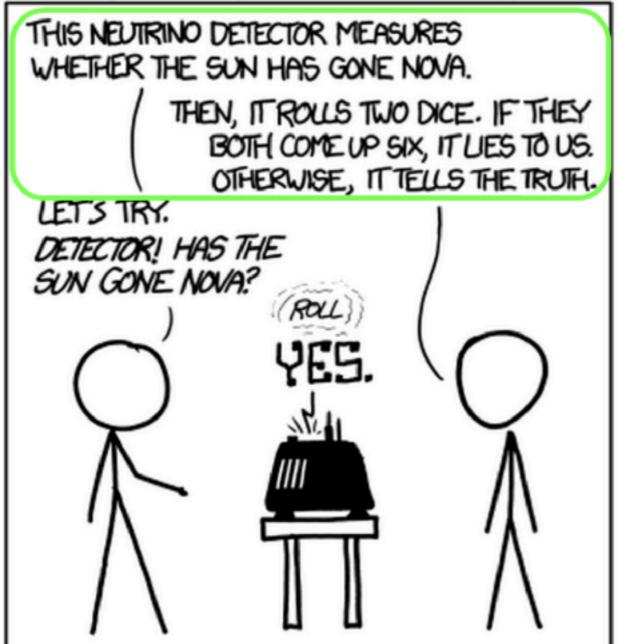
Frequentist: "They're both so skilled! I have as much confidence in musician's ability to distinguish Haydn and Mozart as I do the drunk's to predict coin tosses"

Bayesian: "I don't know man..."

 A Bayesian would incorporate some prior confidence about the musician's ability and the drunk's.

Ho: Sun has not exploded...

DID THE SUN JUST EXPLODE? (IT'S NIGHT, SO WE'RE NOT SURE.)



Evidence collecting process

Evidence!

FREQUENTIST STATISTICIAN:

THE PROBABILITY OF THIS RESULT HAPPENING BY CHANCE IS = 0.027. SINCE P<0.05, I CONCLUDE THAT THE SUN HAS EXPLODED.

BAYESIAN STATISTICIAN:



Frequentist Probability
Long-run frequency of an outcome

+

Subjective Probability
A measure of degree of belief

=

Bayesian Probability
Consider both subjective belief and long-run frequency

### Bayesian Inference

- So we have our beliefs
- And we have our evidence
  - A Frequentist considers the evidence
  - A Bayesian considers both
    - A Bayesian isn't forced to keep beliefs the same forever; she can <u>update</u> her <u>beliefs</u> based on <u>evidence</u>

### Bayesian vs. Frequentist

#### Boils Down to What is Fixed?

- Frequentist:
  - lacktriangle Data are a repeatable random sample  $\longrightarrow$  there is a **frequency**
  - Underlying parameters remain constant during this repeatable process
  - → Parameters are fixed
- Bayesian:
  - Data are observed from a realized sample
  - Parameters are unknown and described probabilistically
  - → Data are fixed

### Bayesian vs. Frequentist

#### **General Inference**

- Frequentist:
  - Point estimates and standard errors
  - Deduction from  $P(data|H_0)$ , by setting  $\alpha$  in advance
  - P-value determines acceptance of  $H_0$  or  $H_1$
- Bayesian:
  - Start with a prior  $\pi(\theta)$  and calculate the posterior  $\pi(\theta|data)$
  - Broad descriptions of the posterior distribution such as means and quantiles

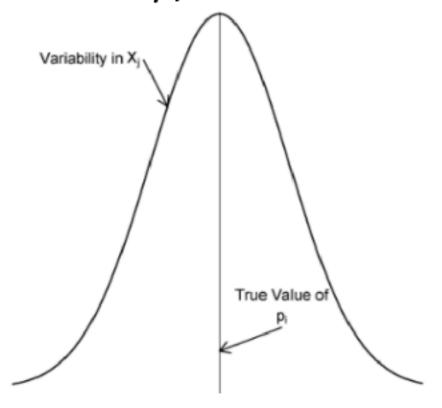
Frequentist:  $P(data|H_0)$  is the sampling distribution given fixed parameter

Bayesian:  $P(\theta)$  is the prior distribution of the parameter (before the data are seen),  $P(\theta|data)$  is the posterior distribution of the parameter after seeing the data.

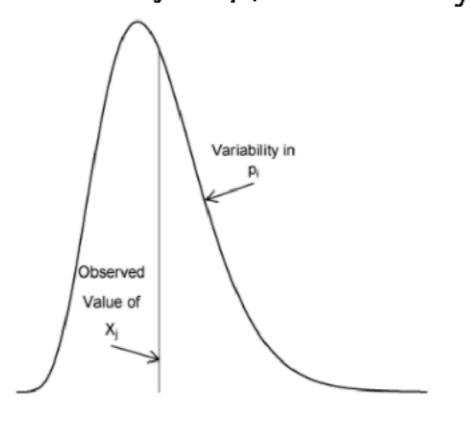
### Bayesian vs. Frequentist

#### General Inference

Frequentist: Describe the variability in  $X_j$  for a fixed value of  $p_i$ 



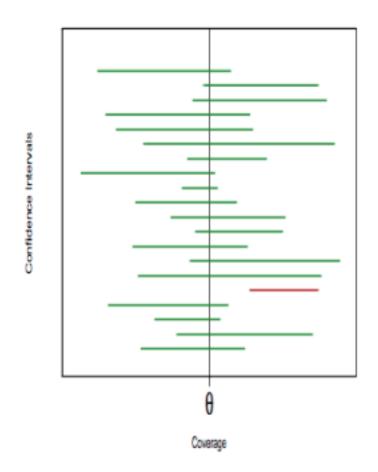
Bayesian: Describe the variability in  $p_i$  for fixed  $X_j$ 



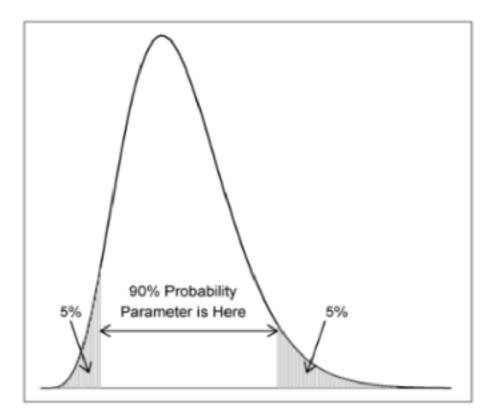
### Intervals

Frequentist: A collection of intervals, 90% of them contain the true unknown parameter

Bayesian: An interval has a 90% chance of containing the true unknown parameter



#### Distribution of Parameter



## Steps for Bayesian Inference

- Specify a probability model for unknown parameter values that includes some prior knowledge about the parameters if available
- Update knowledge about the unknown parameters by conditioning this probability model on observed data
- Evaluate the fit of the model to the data and the sensitivity of the conclusions to the assumptions

### Bayesian Inference

Bayes Rule:

$$P(A|B) = \frac{P(B|A)P(A)}{P(B|A)P(A) + P(B|A^C)P(A^C)}$$

Posterior Distribution:

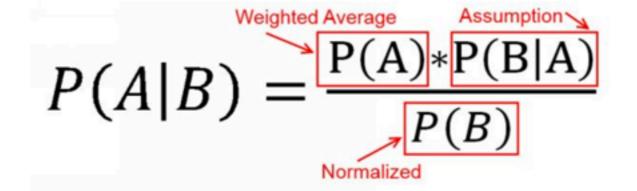
$$\pi(\theta|\mathbf{x}) = \frac{f(\mathbf{x}|\theta)\pi(\theta)}{\int_{\theta\in\Theta} f(\mathbf{x}|\theta)\pi(\theta)d\theta}$$

- lacktriangle prior  $\pi( heta)$  describes our current knowledge about heta
- likelihood  $f(\mathbf{x}|\theta)$  is the distribution of the data for a given  $\theta$
- posterior  $\pi(\theta|\mathbf{x})$  is our updated knowledge about  $\theta$  after seeing the data



### How do we get a prior?

- Previous studies, published research
- Researcher's intuition
- Expert opinion
- Can also use non-informative prior



To solve all of these problems we will follow these steps

- Determine what we want the probability of, and what we are observing
- Estimate initial probabilities for all of the possible answers
- For each of the initial possible answers, assume it is true and calculate the probability of getting our observation with that possibility being true
- 4. Multiply the initial probabilities (Step 2) by the probabilities based on our observation (Step 3) for each of the initial possible answers
- 5. Normalize the results (divide the each probability by the sum of the total probabilities so that the new total probability is 1)
- 6. Repeat Steps 2-5 over and over for each new observation

# Boardwork Examples: 1) Good barbers 2) Marbles in a bag interview question

### Coin Flipping Priors

