Principal Component Algorithm:

Setup: X is a dataset: nxp matrix.

Motation:

E1:K is the matrix eneated from E by discarding the last n-K columns.

(E) (E1:K!)

discarded.

Center the matrix X by subtracting the column means. I discarded. Assumption: From now on, X is centered.

Step # 2:

Compute the sample covariance matrix  $\Omega = \frac{1}{n} \times^t \times$ .

Compute the eigenvectors  $\{e_1, e_2, ..., e_p\}$  and eigenvalues  $\{\lambda_1, \lambda_2, ..., \lambda_p\}$  of  $\Omega$ .

Return:

each column is an eigenvector

The matrix of eigenvectors  $E = (e_1 e_2 \dots e_p)$ 

The vector of eigenvalues  $\Pi = (\lambda, \lambda_2 \cdots \lambda_p)$ 

Properties:

The projection of X onto the subspace spanned by {e1, e2, ..., ep} preserves the maximum variance (out of all K-dim subspaces).

- (2) The matrix product X E 1:K gives the coordinates of X in the reduced basis {e,, e, ..., ex}.
- 3) The matrix product (XEI:K) EI:K gives the best reconstruction of X using only K dimensions. ("best" K-dim subspace")

The sum of eigenvalues  $\sum_{j=1}^{K} \lambda_{j}$  gives the total variance of the projection of X onto  $E_{1:K}$ The ratio of sums  $\sum_{j=1}^{K} \lambda_{j}$  gives the percentage of variance preserved  $\sum_{j=1}^{K} \lambda_{j}$  when projecting X onto  $E_{1:K}$ .