### **Estimation**

### Morning Objectives

This morning we'll talk about estimating statistical distributions from observed data

- Review what the expected value and variance of a random variable are
- Use Method of Moments (MOM), Maximum Likelihood Estimation (MLE), and Maximum A Posteriori (MAP) to estimate a parametric distribution from observed data
- Understand how Kernel Density Estimation (KDE) estimates a non-parametric distribution from observed data

# Why Estimate Distributions?

### Why estimate distributions?

#### Example 1

 You have data on how many people order cakes every day at your bakery, and you want to estimate the probability of selling out

#### Example 2

► You have data on how often your car breaks down, and you want to know your chances of safely crossing the country in it

#### ► Example 3

You have data on how many people visit your website each day, and you want to know the probability of your servers being overloaded

#### Econometrician's Philosophy

If you lack the information to determine the value directly, estimate the value to the best of your ability using the information you do have



Figure 1:At least you tried

#### Review

#### **Expected Value**

If X is a discrete random variable with k possible outcomes and P(X=x) the value of its probability mass function at x, then the expected value of X is

$$E[X] = \sum_{i=1}^{n} x_i P(X = x_i)$$

If X is a continuous random variable and f(x) the value its probability density function at x, then the expected value of X is

$$E[X] = \int_{-\infty}^{\infty} x f(x) dx$$

(Same idea, except replace the summation with an integral and probabilities with probability densities)

# Useful Properties of $E[\cdot]$

▶ If *a* is a constant:

$$E[a] = a$$

▶ If X is a random variable and a is a constant:

$$E[aX] = aE(X]$$

▶ If X and Y are random variables and a and b are constants:

$$E[aX + bY] = aE[X] + bE[Y]$$

#### Moments of a Random Variable X

▶ *n*<sup>th</sup> Raw Moment:

$$\mu_n = E[X^n]$$

n<sup>th</sup> Central Moment:

$$\mu'_n = E[(X - E[X])^n]$$

$$E[X] = \mu_1 = \mu$$

For a discrete random variable X with n possible outcomes:

$$\mu_1 = \mu = \sum_{i=1}^n x_i P(X = x_i)$$

For a continuous random variable X:

$$\mu_1 = \mu = \int_{-\infty}^{\infty} x f(x) dx$$

#### 2<sup>nd</sup> Central Moment: Variance

The *variance* of a random variable X is the expected value of the square difference from the mean:

$$E[(X - E[X])^2] = \mu'_2 = Var(X) = \sigma^2$$

For a discrete random variable X with n possible outcomes:

$$\mu'_2 = \sigma^2 = \sum_{i=1}^n (x_i - \mu)^2 P(X = x_i)$$

For a continuous random variable X:

$$\mu_2' = \sigma^2 = \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx$$

# Useful Properties of $Var(\cdot)$

▶ If *a* is a constant:

$$Var(a) = 0$$

▶ If X is a random variable and a is a constant:

$$Var(aX) = a^2 Var(X)$$

▶ If X and Y are random variables and a and b are constants:

$$Var(aX + bY) = a^2 Var(X) + b^2 Var(Y) + 2abCov(X, Y)$$

 $\mu_2$  as a function of  $\mu$  and  $\sigma^2$ ?

 $\mu_2$  as a function of  $\mu$  and  $\sigma^2$ ?

# **Estimating Distributions**

#### Parametric vs. Non-Parametric Methods

Parametric and non-parametric procedures are two broad classifications of statistical methods.

#### **Parametric**

Make assumptions about the shape and parameters of the underlying population distribution the data was sampled from. E.g., B(n,p),  $N(\mu,\sigma)$ , or  $P(\lambda)$ 

#### Parametric vs. Non-Parametric Methods

#### Non-Parametric

 Do not rely on assumptions about the shape and parameters of the underlying population distribution the data was sampled from

Non-Parametric methods are more flexible but generally have less power than corresponding parametric methods. Interpretation with non-parametric methods can also be difficult, e.g., what does the wiggly curve mean?

### **Estimating Distributions**

#### **Parametric**

- Method of Moments (MOM)
- Maximum Likelihood Estimation (MLE)
- Maximum a Posteriori (MAP)

#### Non-Parametric

Kernel Density Estimation (KDE)

# Method of Moments (MOM)

Derive equations related to raw sample and population moments:

$$E[X], E[X^2], E[X^3], ...$$

#### Method

- 1. Equate the first raw sample moment  $M_1 = \frac{1}{N} \sum X_i$  to the first raw population moment  $E[X] = \mu_1 = \mu$
- 2. Equate the second raw sample moment  $M_2 = \frac{1}{N} \sum X_i^2$  to the second raw population moment  $E[X^2] = \mu_2 = \mu^2 + \sigma^2$
- Continue until you have as many equations as you have parameters
- 4. Solve for parameters

Your website visitor log shows the following number of visits for each of the last seven days: [6,4,7,4,9,3,5]. What's the probability of zero visitors tomorrow?

Suppose we flip a coin N times again, and get H heads. Use MOM to estimate p, the probability of flipping a head.

Suppose we have data sampled from a symmetric uniform distribution with unknown bounds  $X \sim U(-b,b)$ . Estimate using MLE.

# Maximum Likelihood Estimation (MLE)

#### Law of Likelihood:

▶ If  $P(X|H_1) > P(X|H_2)$ , then the evidence supports  $H_1$  over  $H_2$ 

#### Question:

▶ Which hypothesis does the evidence most strongly support?

#### Answer:

- ▶ The hypothesis H that maximizes P(X|H)
  - which is found via MLE...

# Maximum Likelihood Estimation (MLE)

Set values of parameters to values that will maximize the likelihood function

Assume  $X_1, X_2, ..., X_n$  are *i.i.d.*, then the likelihood function is their joint density function:

$$\mathcal{L}(\theta|x_1,x_2,\ldots,x_n)=f(x_1,x_2,\ldots,x_n|\theta)=\prod_{i=1}^n f(x_i|\theta)$$

# Maximum Likelihood Estimation (MLE)

 Maximizing the likelihood function is the same as maximizing the log likelihood function which simplifies calculations

$$\ell(\theta|x_1, x_2, \dots, x_n) = log \mathcal{L}(\theta|x_1, x_2, \dots, x_n) = \sum_{i=1}^n log f(x_i|\theta)$$

$$\hat{\theta}_{MLE} = \underset{\theta \in \Theta}{arg \max} log \mathcal{L}(\theta|x_1, x_2, \dots, x_n)$$

Suppose that  $x_1, \ldots, x_n \sim N(\mu, \sigma)$ . Estimate  $\mu$  and  $\sigma$  using MLE.

Ignoring some constants, the likelihood function is

$$\mathcal{L}(\mu, \sigma) = \prod_{\sigma} \frac{1}{\sigma} \exp\left(-\frac{1}{2\sigma^2} (x_i - \mu)^2\right)$$
$$= \frac{1}{\sigma^n} \exp\left(-\frac{1}{2\sigma^2} \sum_{\sigma} (x_i - \mu)^2\right)$$
$$= \frac{1}{\sigma^n} \exp\left(-\frac{nS^2}{2\sigma^2}\right) \exp\left(-\frac{n(\bar{x} - \mu)^2}{2\sigma^2}\right)$$

where  $\bar{x}$  is the sample mean and  $S^2 = \frac{1}{n} \sum (x_i - \bar{x})^2$  is a biased estimator for the variance.

The log-likelihood is

$$\ell(\mu, \sigma) = -n \log \sigma - \frac{nS^2}{2\sigma^2} - \frac{n(\bar{x} - \mu)^2}{2\sigma^2}$$

Maximizing this gives estimates  $\hat{\mu}_{MLE} = \bar{x}$  and  $\hat{\sigma}_{MLE} = S$ .

Suppose we flip a coin N times and get H heads. Using MLE, estimate how biased the coin is. I.e., estimate p, the probability of getting head.

# Maximum A Posteriori (MAP)

▶ Generalization of MLE in which we assume a prior distribution g over Θ and go one step further to calculate the posterior distribution

$$f(\theta|x) = \frac{f(x|\theta)g(\theta)}{\int_{\Theta} f(x|\theta)g(\theta)d\theta} \propto f(x|\theta)g(\theta)$$

▶ To find the optimal  $\theta$  we find

$$\hat{\theta}_{MAP} = rg \max_{\theta \in \Theta} f(x|\theta)g(\theta)$$

▶ To get MLE, assume a uniform prior on  $\theta$  so that the function g disappears from the arg max above

#### MLE vs. MAP

▶ MLE finds  $\theta$  to maximize  $f(x|\theta)$ 

$$\hat{\theta}_{MLE} = \argmax_{\theta \in \Theta} f(x|\theta)$$

• Whereas MAP finds  $\theta$  to maximize  $f(\theta|x) \propto f(x|\theta)g(\theta)$ 

$$\hat{\theta}_{MAP} = rg \max_{\theta \in \Theta} f(x|\theta)g(\theta)$$

# Kernel Density Estimation (KDE)

Kernel Density Estimation is used to estimate the pdf of a random variable and is essentially a data smoothing problem.

► KDE estimates a distribution empirically given data by summing kernels centered at each point. The density function of the kernel density estimate is:

$$\hat{f}_h(x) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{x - x_i}{h}\right)$$

 $K(\cdot)$  is a *kernel*: a non-negative function that integrates to one and has mean zero; a kernel is another word for a density function of a distribution with mean 0. The parameter h, a smoothing parameter, is called the *bandwidth*, and it's analogous to the width of bins in a histogram.

### Kernel Density Estimation (KDE) - Example

Closely related to histograms, but can be made smooth by using a suitable kernel.

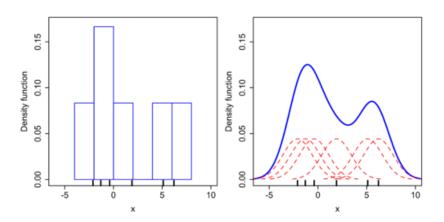


Figure 2:Histograms and KDEs

### Histogram Troubles

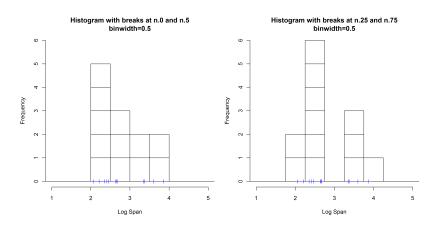


Figure 3:Histogram Troubles

#### Bandwidth Selection

- ► A free parameter which exhibits a strong influence on the resulting estimate
- ► The most common optimality criterion used to select the parameter is the mean integrated squared error

$$MISE(h) = E \int_{-\infty}^{\infty} (\hat{f}_h(x) - f(x))^2 dx$$

#### Bandwidth Selection

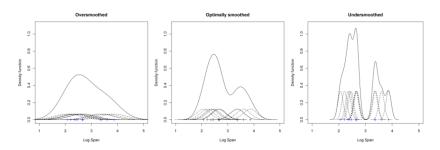


Figure 4:Am I too smooth? Not smooth enough?

#### Questions

- MOM vs. MLE
  - What do they solve for?
  - ▶ How does each approach the tackle the problem?
- How about MAP?
  - ► How does it relate to the MLE?