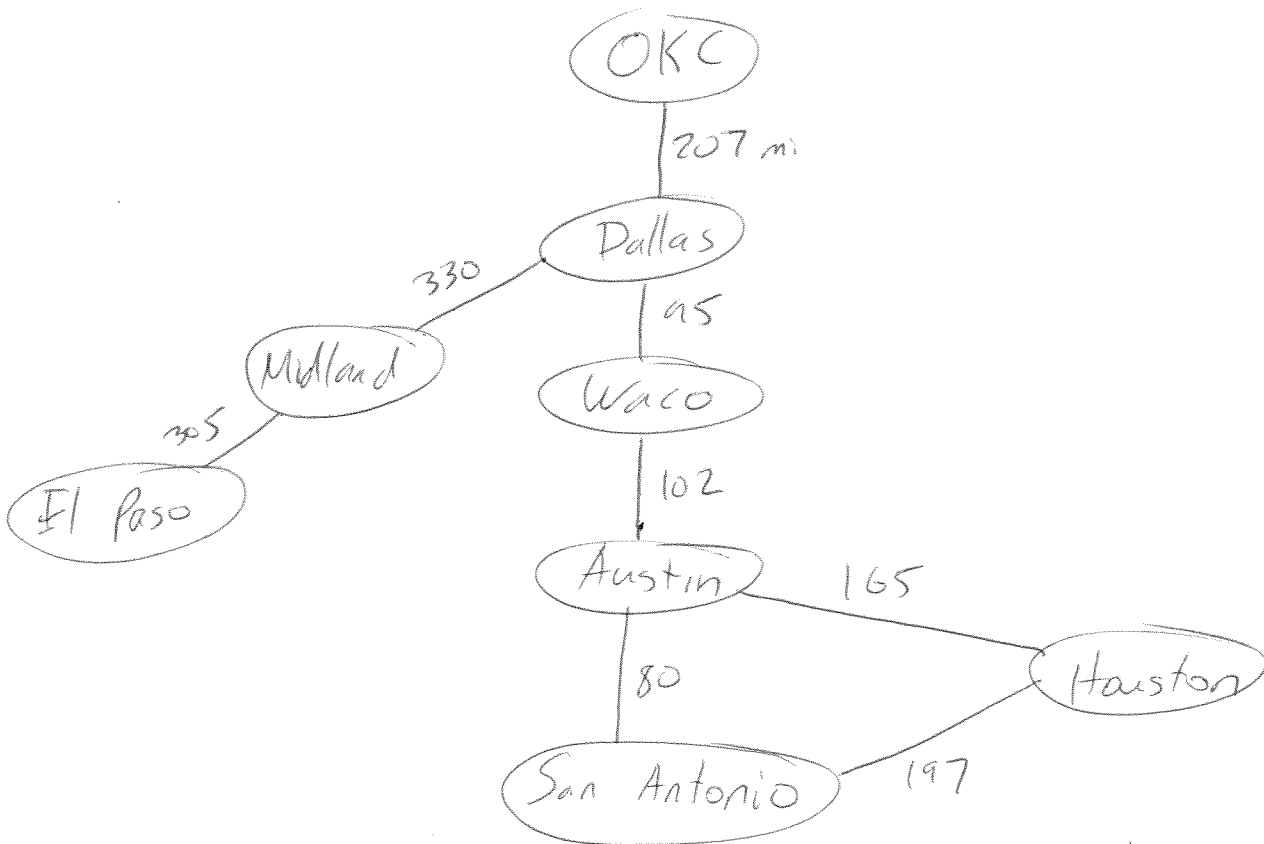


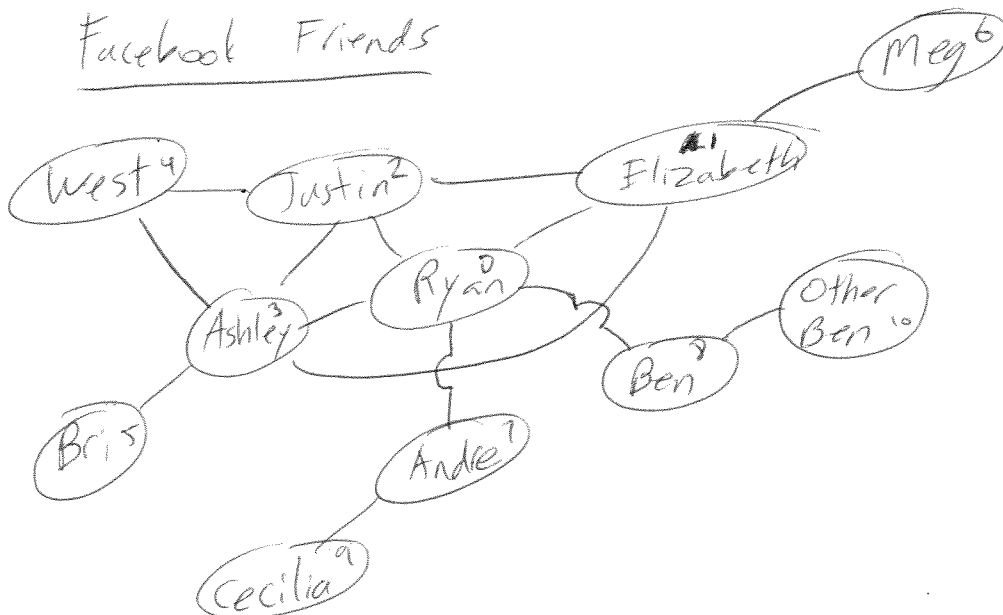
Example Graphs

Roads & Cities (major highways only)

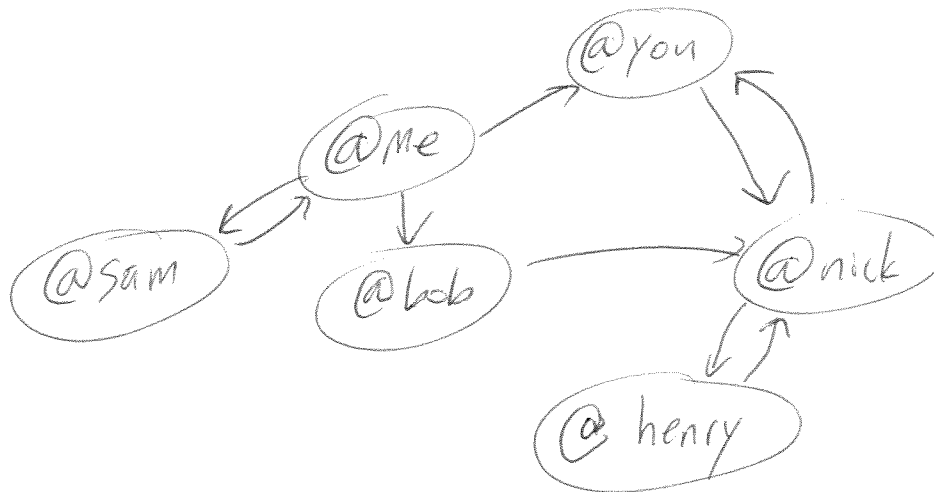
→ perhaps we only do busses...



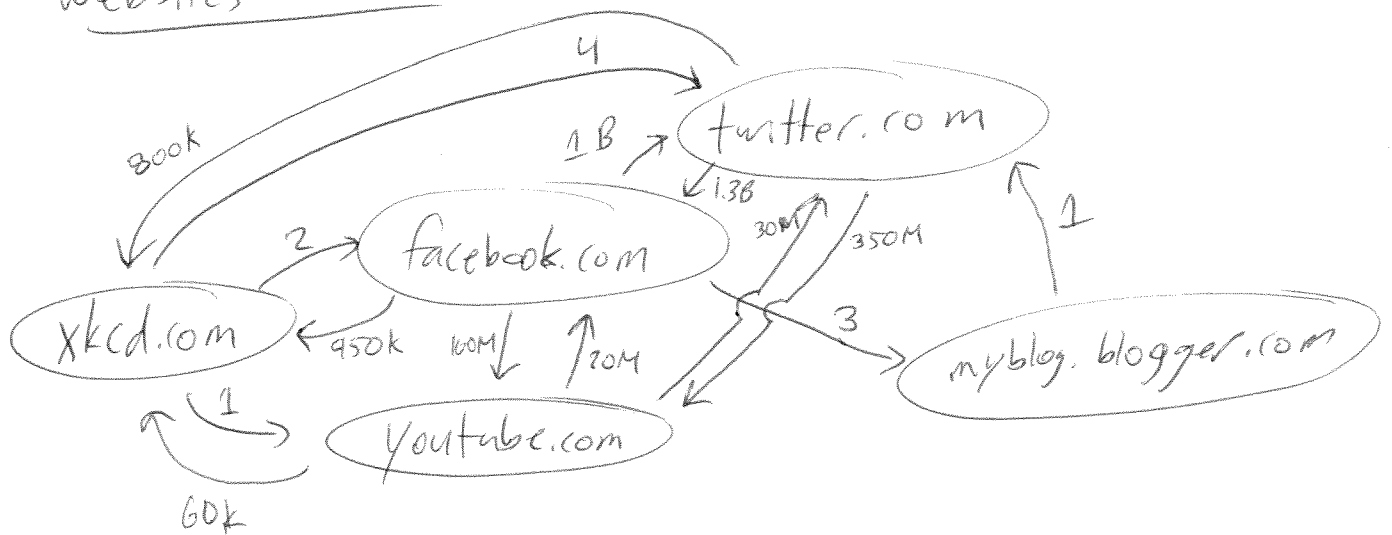
Facebook Friends



Twitter



Websites & Links



Graph Theory : Graphs - The ultimate data structure (+ misc other topics)

- Example graphs (draw each on board)

- Cities & Roads (undirected, weighted) \rightarrow create what we'll later call an "adj. mat."
- Facebook friends (undirected, unweighted) \rightarrow create what we'll later call an "adj. list"
- Twitter followers (directed, unweighted) \rightarrow the list of friends for now.
- Websites & Links (directed, weighted by # of links?) \rightarrow create ...

- Define a graph:

A pair (V, E) , where

V is a set of vertices (aka, nodes)

E is a set of edges (aka, connections)

~~$E \subseteq V \times V$~~

$$E = \{ \dots, (v_i, v_j, w_k), \dots \mid (v_i, v_j) \in V^2, w_k \in \mathbb{R} \}$$

- Terminology:

Vertex (Node), Edge (connection), Directed/Undirected,

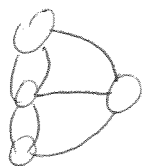
Weighted/Unweighted, Neighbor, Degree,

Complete (edges between all pairs), Connected, Path, Cycle,

Subgraph, Connected component (subgraph that is connected)

- Why Graph "Theory"? Let's give the first "theorem".

By Euler in 1736 (what didn't that guy do?):



Eulerian Path: iff zero or two odd degrees

Eulerian ~~Path~~ Circuit: iff exactly two odd degrees

- TSP, NP-Hard

- More question we could ask:

precise { Shortest path between two nodes? \rightarrow (roads...)
Shortest path between all pairs of nodes?

ambiguous { How to find "missing" edges? \rightarrow (friends...)
How to identify "important" nodes? \rightarrow (social influencers)

- How to represent in a program:

- Adjacency Matrix

	a	b	c	d	e
a	0	5	∞	∞	∞
b	5	0	∞	10	4
c	∞	∞	0	-	-
d	∞	10	-	0	-
e	∞	4	-	-	0

\rightarrow not nec. ∞

\rightarrow directed vs undirected
 \rightarrow weighted vs unweighted

Storage: $O(n^2)$

~~AE~~ $n = |V|$

Lookup: $O(1)$

- Adjacency List (Map):

{ a: {b: 5},
b: {a: 5, d: 10, e: 4},
c: { },
d: {b: 10, e: -},
e: {b: 4, d: -}}

\rightarrow directed vs. undirected
weighted vs un-

$n = |V|$ $c = |E|$

Storage: $O(\sum \text{degree})$

Lookup: $O(\log n + \log c)$

Graph

- Code now... Queue, Stack, Algs...

```

import pandas as pd
from pprint import pprint
from collections import deque

def build_friends_adj_list():
    """
    Builds and returns an adjacency list that representing the friends graph
    on the whiteboard.
    """
    n = ['Ryan', 'Elizabeth', 'Justin', 'Ashley', 'West', 'Bri',
         'Meg', 'Andre', 'Ben', 'Cecilia', 'Other Ben']
    adj_list = {n[0] : {n[1], n[2], n[3], n[7], n[8]},
                n[1] : {n[0], n[2], n[3], n[6]},
                n[2] : {n[0], n[1], n[3], n[4]},
                n[3] : {n[0], n[2], n[1], n[5], n[4]},
                n[4] : {n[2], n[3]},
                n[5] : {n[3]},
                n[6] : {n[1]},
                n[7] : {n[0], n[9]},
                n[8] : {n[0], n[10]},
                n[9] : {n[7]},
                n[10]: {n[8]}}
    return adj_list

def bfs_visit_all(graph, start_node):
    """
    INPUT:
        - graph: an adjacency list representation of an unweighted graph
        - start_node: the starting point in the graph, from which will will
                      begin our exploration

    This function will traverse the graph in a breadth-first way.
    This function implements the breadth-first-search (BFS) algorithm.
    """
    next_nodes = deque([start_node])
    found_nodes = set([start_node])

    while len(next_nodes) > 0:
        node = next_nodes.popleft()    # <-- using as a queue!

        print "I'm now visiting node:", node

        for neighbor in graph[node]:
            if neighbor not in found_nodes:
                next_nodes.append(neighbor)
                found_nodes.add(neighbor)

def dfs_visit_all(graph, start_node):
    """
    INPUT:
        - graph: an adjacency list representation of an unweighted graph
        - start_node: the starting point in the graph, from which will will
                      begin our exploration
    """

```

This function will traverse the graph in a depth-first way.
 This function implements the depth-first-search (DFS) algorithm.

NOTICE THE ONLY CHANGE IS THAT WE'RE USING A STACK NOW!

```
'''
next_nodes = deque([start_node])
found_nodes = set([start_node])

while len(next_nodes) > 0:
    node = next_nodes.pop()    # <-- using as a stack!

    print "I'm now visiting node:", node

    for neighbor in graph[node]:
        if neighbor not in found_nodes:
            next_nodes.append(neighbor)
            found_nodes.add(neighbor)
```

```
def bfs_visit_all_limit(graph, start_node, max_depth):
```

```
'''
INPUT:
    - graph: an adjacency list representation of an unweighted graph
    - start_node: the starting point in the graph, from which will will
      begin our exploration
```

This function will traverse the graph in a breadth-first way.
 This function implements the breadth-first-search (BFS) algorithm.

This function will quit when we reach a certain max_depth.

```
'''
next_nodes = deque([(start_node, 0)]) # <-- NEW: using tuples
found_nodes = set([start_node])

while len(next_nodes) > 0:
    node, depth_here = next_nodes.popleft() # <-- NEW

    print "I'm now visiting node:", node

    if depth_here + 1 <= max_depth: # <-- NEW
        for neighbor in graph[node]:
            if neighbor not in found_nodes:
                next_nodes.append((neighbor, depth_here+1)) # <-- NEW
                found_nodes.add(neighbor)
```

```
def dfs_visit_all_recursive(graph, node, found_nodes=None):
```

```
'''
INPUT:
    - graph: an adjacency list representation of an unweighted graph
    - node: the starting point in the graph, from which will will
      begin our exploration
    - found_nodes: if not None, the set of nodes we've already processed
```

This function will traverse the graph in a depth-first way.

This function implements the depth-first-search (DFS) algorithm.

This version uses recursion.

DEMO STACK OVERFLOW!!!! (i.e. add a bug and run)

```
'''
```

```
if found_nodes is None:
```

```
    found_nodes = set([node])
```

```
else:
```

```
    found_nodes.add(node)
```

```
print "I'm now visiting node:", node
```

```
for neighbor in graph[node]:
```

```
    if neighbor not in found_nodes:
```

```
        dfs_visit_all_recursive(graph, neighbor, found_nodes)
```

```
def connected_component(graph, start_node):
```

```
'''
```

```
INPUT:
```

```
- graph: an adjacency list representation of an unweighted graph
```

```
- start_node: the starting point in the graph, from which will will  
begin our exploration
```

```
RETURN:
```

```
- set_of_nodes: the set of nodes in this connected component
```

This function will return the nodes in the connected component that contains start_node.

```
'''
```

```
found_nodes = set()
```

```
dfs_visit_all_recursive(graph, start_node, found_nodes)
```

```
return found_nodes
```

```
def build_cities_adj_matrix():
```

```
'''
```

Builds and returns an adjacency matrix representing the cities graph on the whiteboard.

```
'''
```

```
inf = float('inf')
```

```
cities = ['OKC', 'Dallas', 'Waco', 'Austin', 'San Antonio',  
          'Houston', 'Midland', 'El Paso']
```

```
adj_matrix = [[ 0, 207, inf, inf, inf, inf, inf, inf],  
               [207, 0, 95, inf, inf, inf, 330, inf],  
               [inf, 95, 0, 102, inf, inf, inf, inf],  
               [inf, inf, 102, 0, 80, 165, inf, inf],  
               [inf, inf, inf, 80, 0, 197, inf, inf],  
               [inf, inf, inf, 165, 197, 0, inf, inf],  
               [inf, 330, inf, inf, inf, inf, 0, 305],  
               [inf, inf, inf, inf, inf, inf, 305, 0]]
```

```
graph = pd.DataFrame(adj_matrix, index=cities, columns=cities)
```

```
return graph
```

```
def floyd_warshall(graph):
```

```

'''
INPUT:
    - graph: an adjacency matrix representation of a graph
RETURN:
    - a pandas dataframe of the length of the shortest path between
      all pairs of nodes

DISCUSS BIG-O OF THIS!!!!
'''
d = graph.copy()
n = d.shape[0]
for i in xrange(n):
    for j in xrange(n):
        for k in xrange(n):
            if d.iloc[i,k] > d.iloc[i,j] + d.iloc[j,k]:
                d.iloc[i,k] = d.iloc[i,j] + d.iloc[j,k]
return d

if __name__ == '__main__':
    friend_graph = build_friends_adj_list()
    pprint(friend_graph)

    bfs_visit_all(friend_graph, 'Ryan')
    print

    dfs_visit_all(friend_graph, 'Ryan')
    print

    bfs_visit_all_limit(friend_graph, 'Ryan', 1)
    print

    dfs_visit_all_recursive(friend_graph, 'Ryan')
    print

    print connected_component(friend_graph, 'Ryan')

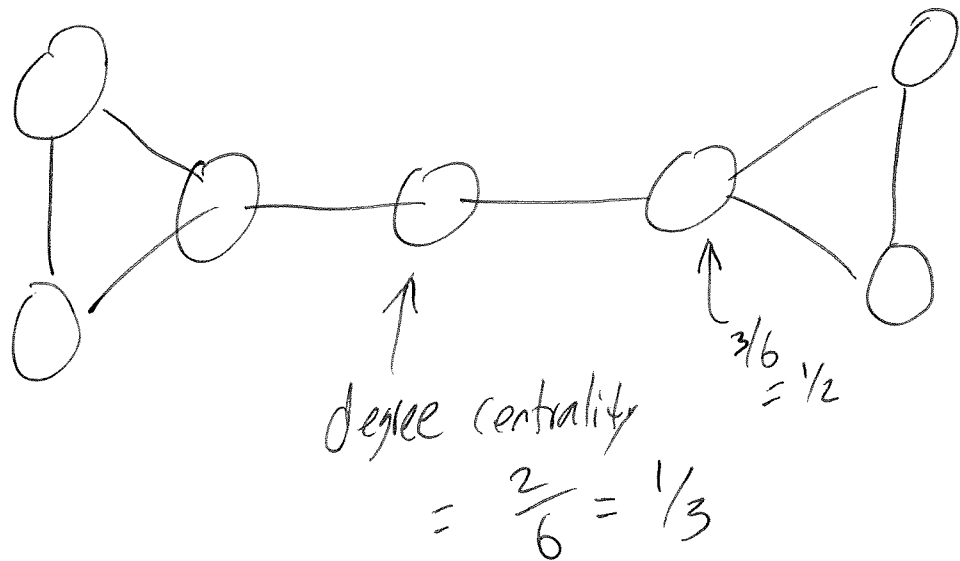
    city_graph = build_cities_adj_matrix()
    print city_graph

    print floyd_warshall(city_graph)

```


Centrality

degree centrality: $\frac{\text{degree of } v}{n-1}$

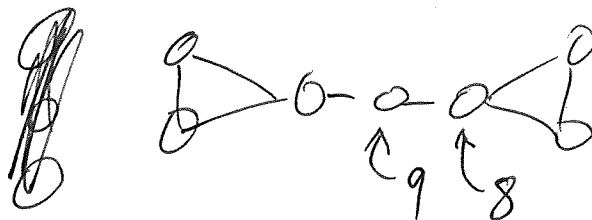


betweenness centrality:

betweenness $(v) = \sum_{s \neq v \neq t} \% \text{ of shortest paths from } s \text{ to } t \text{ through } v$

$= \sum_{s \neq v \neq t} \frac{\sigma_{st}(v)}{\sigma_{st}}$

betweenness centrality $(v) = \frac{\text{betweenness}(v)}{(n-1)(n-2)}$



★ Mention betweenness centrality