Estimation & Sampling

Overview

- Review
 - Expected Value, Variance
- Statistics
 - Parametric vs. Non-Parametric
- Inference
 - MOM, MLE, MAP
 - KDE
- Sampling
 - CLT
 - Population Inference
 - Confidence Intervals
 - Bootstrapping

Review - Expectation

Discrete: Probability weighted average of all possible values

$$E(X) = x_1 * p_1 + x_2 * p_2 + \dots + x_k * p_k$$

 Continuous: Same idea, except replace Σ with integral, and replace probabilities with probability densities

$$E(X) = \int_{-\infty}^{\infty} x * f(x) dx$$

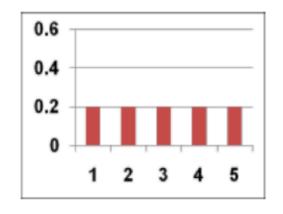
Review - Variance

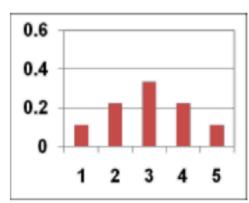
Intuition

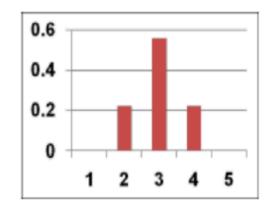
- Measures how much "spread" there is in a set of numbers
- The mean squared distance of random variable X from the mean, μ.

$$\operatorname{Var}(X) = \left[\mathbb{E}\left[(X - \mu)^2 \right] \right]$$

$$\begin{aligned} \operatorname{Var}(X) &= \operatorname{E}\left[(X - \operatorname{E}[X])^2\right] \\ &= \operatorname{E}\left[X^2 - 2X\operatorname{E}[X] + (\operatorname{E}[X])^2\right] \\ &= \operatorname{E}\left[X^2\right] - 2\operatorname{E}[X]\operatorname{E}[X] + (\operatorname{E}[X])^2 \\ &= \operatorname{E}\left[X^2\right] - (\operatorname{E}[X])^2 \end{aligned}$$







Review - Variance

 Discrete: Probability weighted average of all possible deviations from mean, squared.

Suppose discrete r.v. X can take on k distinct values.

$$E(X) = \mu$$

$$Var(X) = E[(X - \mu)^{2}] = \sum_{i=1}^{k} p_{i} * (x_{i} - \mu)^{2}$$

 Continuous: Same idea, except replace Σ with integral, and replace probabilities p_i with probability densities f(x)

$$Var(X) = \sigma^2 = \int (x - \mu)^2 f(x) dx$$

Modeling – Parametric vs. Nonparametric

Parametric

- Assumes data comes from a type of probability distribution and makes inferences about the parameters
- For example, $Normal(\mu, \sigma^2)$, $Poisson(\lambda)$
- May make use of some common sample statistics

$$\left(\bar{x} = \frac{1}{n} \sum_{i=1}^{n} x_i\right) \left(s^2 = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x})^2\right)$$

Non-parametric

 Unlike parametric case, non-parametric statistics make no assumptions about the probability distributions from which the variables arise

Inference – MOM and MLE

Method of Moments (MOM) and Method of Maximum Likelihood (MLE) are two parameter estimation strategies.

- $Normal(\underline{\mu}, \underline{\sigma}^2), Poisson(\underline{\lambda})$
- May or may not result in the same estimate

For fixed set of data and underlying statistical model...

• MOM – Derive equations related to population moments What's a moment? $E(X), E(X^2), E(X^3)...$

first second third moment moment moment

MLE – Set values of parameters to maximize the likelihood f(n)

Inference – MOM

MOM – Derive equations related to population moments What's a moment? $E(X), E(X^2), E(X^3)...$

$$X_i \underset{\text{iid}}{\sim} Binomial(N,\underline{p}), \quad i=1,2,...,n$$
 Assume data comes from some distribution $\Rightarrow E(X_i) = Np$

$$\bar{x} = Np - \text{Compute first moment from sample data}.$$

$$\hat{p} = \frac{\bar{x}}{N} \longleftarrow \text{ Estimate parameter } p \\ \text{based on first moment}$$

Inference - MOM

$$X_i \sim Uniform(-\theta,\underline{\theta}), \quad i=1,2,...,n$$
 Again, assume data comes from some distribution $\Rightarrow E(X_i)=0$

E(X) does not depend on parameters, so first moment doesn't help, but...

$$Var(X_i) = \frac{\theta^2}{3}$$

Compute first and second moments from **sample data**.

Recall
$$Var(X) = E(X^2) - [E(X)]^2$$

$$\Rightarrow s^2 = \frac{\theta^2}{3}$$

Estimate parameter Θ based on first moment and second moments.

Inference – MLE

MLE – Set values of parameters to maximize the likelihood f(n) First off...what's a likelihood function?

- Since we assume $x_1, x_2, ... x_n$ are i.i.d., we have the joint density function

$$f(x_1, x_2, ..., x_n | \theta) = f(x_1 | \theta) * f(x_2 | \theta) * f(x_3 | \theta) * ... * f(x_n | \theta)$$

 Just call this joint density the "Likelihood", and the log of that joint density the "Log Likelihood" just to make calculus easier)

$$\mathcal{L}(\theta|x_1,...,x_n) = f(x_1,x_2,...,x_n|\theta) = \prod_{i=1}^n f(x_i|\theta) \text{ "Likelihood"}$$

$$log\mathcal{L}(\theta|x_1,...,x_n) = \sum_{i=1}^n log[f(x_i|\theta)] \text{ "Log Likelihood"}$$

Parameter estimate is simply the one that maximizes the likelihood f(n)

$$\hat{\theta}_{mle} = \underset{\theta \in \Theta}{argmax} \ log\mathcal{L}(\theta|x_1, ..., x_n)$$

Inference - MLE

MLE – Set values of parameters to maximize the likelihood f(n).

$$X_i \sim Binomial(N,p), \ i=1,2,...,n \qquad \text{As with MOM, assume data comes from some distribution}$$

$$\Rightarrow \ f(x_i) = \binom{N}{x_i} p^{x_i} (1-p)^{N-x_i}$$

$$\Rightarrow \ \mathcal{L}(p|x) = \prod_{i=1}^n \binom{N}{x_i} p^{x_i} (1-p)^{N-x_i} \qquad \text{Define Likelihood}$$

$$\Rightarrow \ log \mathcal{L}(p|x) = \sum_{i=1}^n \log \binom{N}{x_i} + x_i \log p \qquad \text{Log Likelihood}$$

$$+ (N-x_i) \log (1-p)$$

$$\Rightarrow \ \frac{\partial log \mathcal{L}(p|x)}{\partial p} = \sum_{i=1}^n \left[\frac{x_i}{\widehat{p}} - \frac{N-x_i}{1-\widehat{p}} \right] = 0$$

$$\Rightarrow \ \hat{p} = \frac{\overline{x}}{N}$$
 Estimate parameter using some calculus!

Inference - MLE

Logistic Regression

– For each data point, have feature vector, x_i , and observed response y_i

$$\mathcal{L}(\beta_0, \beta | x_1, ..., x_n) = \prod_{i=1}^n p(x_i)^{y_i} (1 - p(x_i))^{1-y_i}$$

Can think of each observation as a Bernoulli trial where probabilities are estimated by your Logistic Model

Pick coefficients that maximize the joint likelihood!

Inference – MLE

Logistic Regression

– For each data point, have feature vector, x_i , and observed response y_i

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Pick coefficients that maximize the joint likelihood!

Note: no closed form solution, but no matter! We can use some numerical method, such as Gradient Descent.

MOM vs. MLE

- MOM introduced in 1894. Some say MLE has supplanted MOM.
- Still MOM has some good qualities
 - Fairly simple
 - Useful if MLE computationally intractable
 - Can be useful as stepping stone to solving MLE
 - First approximation to solutions of likelihood equations

Inference – MAP

- Maximum a posteriori (MAP) mode of the posterior distribution
 - For MLE, we have

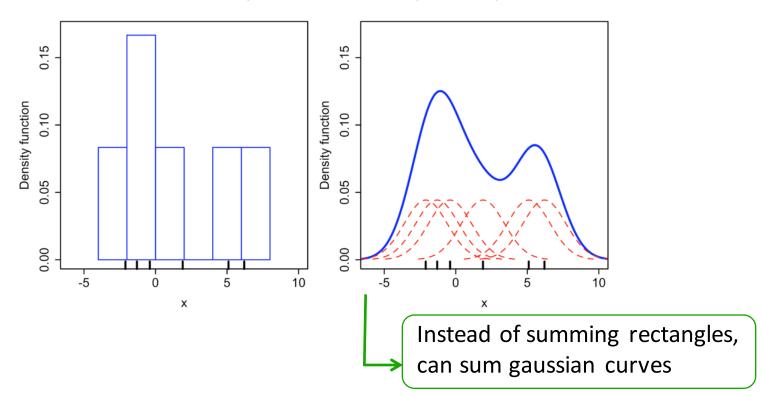
$$\hat{\theta}_{mle} = \underset{\theta \in \Theta}{argmax} \ f(x|\theta) = \underset{\theta \in \Theta}{argmax} \ log\mathcal{L}(\theta|x_1, ..., x_n)$$

— For MAP, we assume a prior g over Θ , and go one step further to get the posterior.

$$\begin{split} \theta &\mapsto f(\theta|x) = \frac{f(x|\theta)\,g(\theta)}{\int_{\vartheta \in \Theta} f(x|\vartheta)\,g(\vartheta)\,d\vartheta} &\longleftarrow \text{Simply get Posterior using Bayes} \\ \hat{\theta}_{map} &= \underset{\theta \in \Theta}{argmax}\,\frac{f(x|\theta)\,g(\theta)}{\int_{\vartheta} f(x|\vartheta)\,g(\vartheta)\,d\vartheta} = \underset{\theta \in \Theta}{argmax}f(x|\theta)\,g(\theta). \end{split}$$

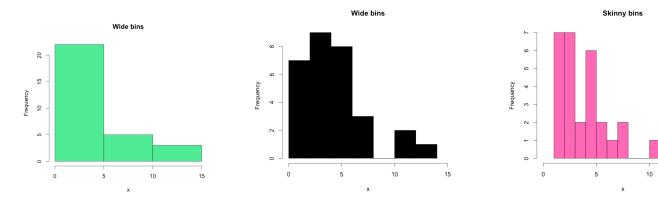
Inference – KDE

- Kernel Density Estimation (KDE)
 - Non-parametric way to estimate pdf of a random variable
 - Really, a data smoothing problem
 - Very similar to histograms
 - *Data*: $x_1 = -2.1$, $x_2 = -1.3$, $x_3 = -0.4$, $x_4 = 1.9$, $x_5 = 5.1$, $x_6 = 6.2$

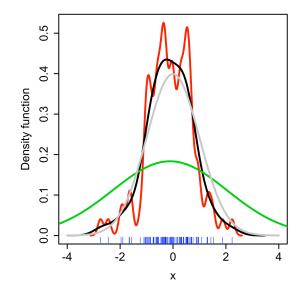


Inference – KDE

- Kernel Density Estimation (KDE)
 - Varying Bandwidth (for histograms)



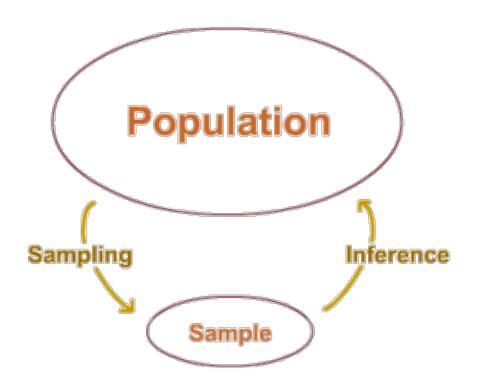
Instead, can use Gaussian kernels



Which bandwidth seems to be overfitting? Underfitting?

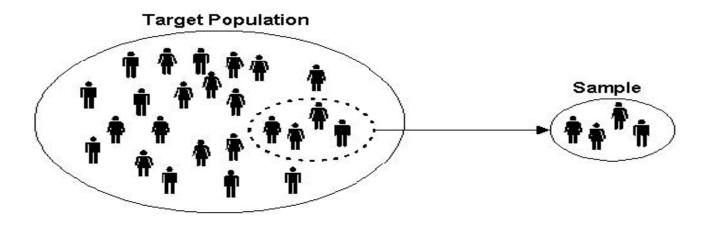
Statistical Data Discovery in General

- Start with a question/hypothesis
- Design an experiment
- Collect data
- Analyze
- Check the results
- Repeat? Redesign?



Getting (Good) Data

 A sample should be representative of the population (junk in = junk out)

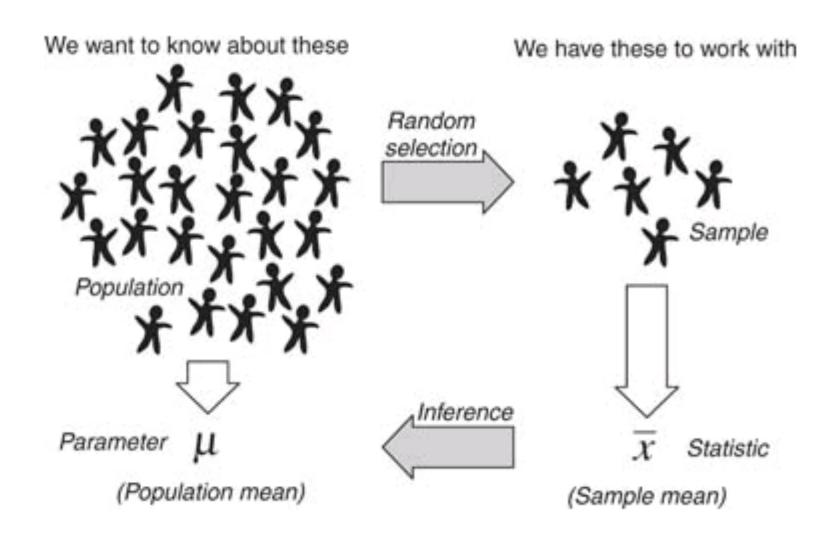


 Random sampling is often the best way to achieve this

Sampling Methods

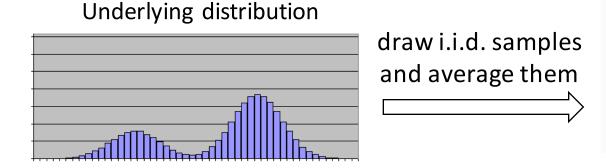
- Simple random sampling (SRS)
 - The easiest most widespread form of sampling
 - Each subject has an equal chance to being in the sample
- Other common sampling methods:
 - Systematic sampling
 - Stratified sampling
 - Cluster sampling

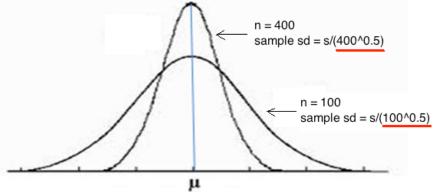
Sampling and Inference



Central Limit Theorem

 Given certain conditions, the mean of a sufficiently large number of i.i.d. random variables, will be approximately normal, regardless of the underlying distribution.





Central Limit Theorem

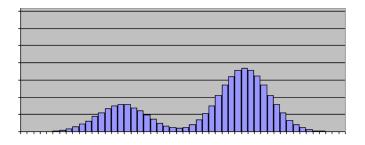
Not only is the sample mean normally distributed, we have....

$$\bar{X} \sim Normal(\mu, \frac{\sigma^2}{n})$$

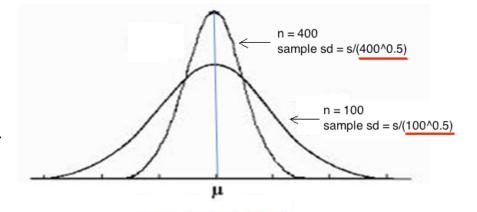
 $\bar{X} \sim Normal(\mu, \frac{\sigma^2}{n})$ And as usual, from any normally distributed random variable, we can derive a standard normal variable. In this case...

$$Z = \frac{\bar{X} - \mu}{\sigma / \sqrt{n}}$$

Underlying distribution



draw i.i.d. samples and average them



Confidence Interval

- A confidence interval (CI) is an interval estimate of a population parameter
- They are typically stated at 95% confidence level, but they can be shown at any confidence level, e.g. 50%, 90%, 99%
- The confidence interval for the mean is given by

$$(\overline{x} - 1.96 \frac{\sigma}{\sqrt{n}}, \overline{x} + 1.96 \frac{\sigma}{\sqrt{n}})$$
 or $\overline{x} \pm 1.96 \frac{\sigma}{\sqrt{n}}$

Confidence Interval - cont

• Since we do not know σ , if N > 30, we can substitute s for it

$$\overline{x} \pm 1.96 \frac{s}{\sqrt{n}}$$

When N is small, we would use

$$\overline{\mathbf{x}} \pm \mathbf{t}_{(\alpha/2, \mathbf{n}-1)} \frac{s}{\sqrt{n}}$$

Resampling

- Resampling: drawing repeated samples from the given data
- Common resampling techniques:
 - Bootstrapping
 - Jackknifing
 - Cross-validation
 - Permutation tests

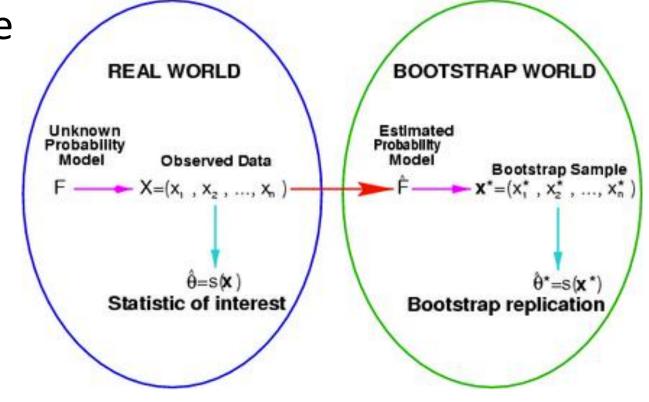
Bootstrapping

 Estimates the sampling distribution of an estimator by sampling with replacement from the original sample

Often used to estimate the standard errors

and confidence intervals of a population

parameter

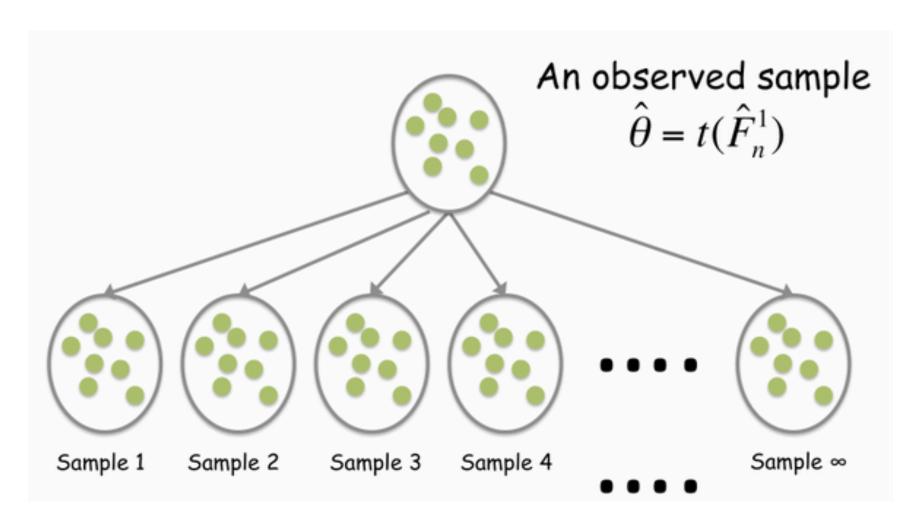


How To Bootstrap

To pull oneself up by one's bootstrap..



Bootstrapping



Bootstrap Variance Estimation

1. Draw
$$X_1^*, ..., X_n^* \sim \hat{F}_n$$

1. Compute
$$\hat{\theta}^* = t(X_1^*, ..., X_n^*)$$

1. Repeat steps 1 and 2, B times, to get $\hat{\theta}_1^*, \dots, \hat{\theta}_B^*$

2. Let
$$v_{boot} = \frac{1}{B} \sum_{b=1}^{B} (\hat{\theta}_b^* - \frac{1}{B} \sum_{r=1}^{B} \hat{\theta}_r^*)^2$$

$$(\hat{se}_{boot} = \sqrt{v_{boot}})$$

Bootstrap Confidence Intervals

Percentile method

$$C_n = (\theta_{\alpha/2}^*, \theta_{1-\alpha/2}^*)$$

The Normal interval

$$\hat{\theta} \pm z_{\alpha/2} \hat{se}_{boot}$$

When Do We Use Bootstrapping?

- When the theoretical distribution of the statistic is complicated or unknown
- When the sample size is too small
- When estimating the variance of a statistic using a small pilot sample for power calculations

Questions

- MOM vs. MLE
 - What do they solve for?
 - How does each approach tackle the problem?
- How about MAP?
 - How does it relate to the MLE?
- What's bootstrapping?
 - When might I think of using it?
 - What are the steps to setting up a bootstrap estimate?

Questions

- MOM vs. MLE
 - What do they solve for? Parameter Estimation
 - How does each approach tackle the problem?
 - Both assume a specific distribution already.
 - MOM uses moment matching to get at parameters
 - MLE asks what parameter would maximize the likelihood of the resulting data
- How about MAP?
 - How does it relate to the MLE? Similar to MLE, but need to account for Prior
- What's bootstrapping? Random sampling w/ replacement technique
 - When might I think of using it? Want sense of accuracy of some sample estimate
 - What are the steps to setting up a bootstrap estimate?
 - Sample w/ replacement, B times → Compute B estimates from B samples → Get Standard Errors, Confidence Intervals, etc.