### Introduction to Time Series

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## **Objectives**

- ▶ Define key time series concepts
- Use graphical tools to analyze time series data
- ► Train and evaluate ARIMA models using Python's StatsModels
- ▶ Describe Exponential Smoothing (ETS) model

Caveat: we focus on forecasting the mean and not quantiles.

# Agenda

- 1. Define key time series concepts and properties
- 2. Describe ARIMA model
- 3. Use Box-Jenkins work-flow to estimate an ARIMA model
  - 3.1 Use graphical tools to pick an ARIMA model
  - 3.2 Estimate/forecast/evaluate an ARIMA model
  - 3.3 Model selection
- 4. Describe ETS model

#### References

A couple helpful references, arranged by increasing difficulty:

- Hyndman & Athanasopoulos: "Forecasting: principles and practice"
- ► Enders: "Applied Econometric Time Series"
- ► Hamilton: "Time Series Analysis"

# A little religion: Python vs. R

In most cases, you can use Python or R, depending on your preference:

- ▶ In Python, use StatsModels + Pandas:
  - Pandas: to manipulate data and dates
  - StatsModels: to estimate core time series models
- ▶ In R, Hyndman's forecast package is outstanding:
  - Use lubridate to manipulate dates
  - ▶ For serious forecasting, R is vastly superior
  - Only serious option for ETS
- ► Galvanize is a Python shop, so . . . we will use Python

# Introduction

### Time series data

Time series data is a sequence of observations of some quantity of interest, which are collected over time, such as:

- ► GDP
- ▶ The price of toilet paper or a stock
- Demand for a good
- Unemployment
- ▶ Web traffic (clicks, logins, posts, etc.)

### Definition

We assume a time series,  $\{y_t\}$ , has the following properties:

- $\triangleright$   $y_t$  is an observation of the level of y at time t
- ▶  $\{y_t\}$  is time series, i.e., the collection of observations:
  - ▶ May extend back to t = 0 or  $t = -\infty$ , depending on the problem.
  - ▶ E.g.,  $t \in \{0, ..., T\}$

### Assumptions

#### We assume:

- Discrete time:
  - Sampling at regular intervals
  - ... even if process is continuous
- Evenly spaced observations
- No missing observations

### Caveat: only one observation?

Time series are hard to model because we only observe one realization of the path of the process:

- Often have limited data
- Must impose structure such as assumptions of about correlation – in order to model
- Must project beyond support of the data.

Furthermore, in practice executives often ask for forecasts to CYA. . .

# Components of a time series

Think of a time series as consisting of several different components:

- Trend
- Seasonality
- Periodic
- Irregular

Can be additive or multiplicative

# Example decomposition from Hyndman et al.

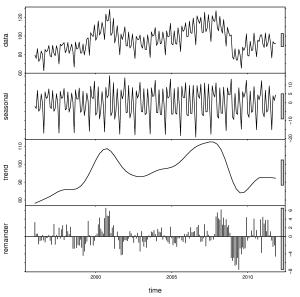


Figure 1:



# Example time series from Hyndman et al.

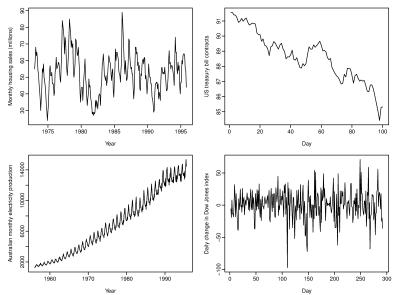


Figure 2:



## Two popular models

#### Two common models:

- ► ARIMA(p,d,q):
  - A benchmark model
  - Captures key aspects of time series data
- Exponential smoothing (ETS):
  - Smooths out irregular shocks to model trend and seasonality
  - Updates forecast with linear combination of past forecast and current value
  - Also known as a "State space model"

#### **Notation**

#### Some notation, following Hyndman:

- $\triangleright$   $y_t$ : the level of some value of interest at time t
- $ightharpoonup \epsilon_t$ : the value of a shock,  $\epsilon$ , at time t
- $\hat{y}_{t+h|t}$  is the forecast for  $y_{t+h}$  based on the information available at time t

# Lags

### Often models use past values to predict future:

- ► AR(1):  $y_t = \phi \cdot y_{t-1} + \epsilon_t$
- ► MA(1):  $y_t = y_{t-1} + \epsilon_t + \psi \cdot \epsilon_{t-1}$
- Easier to write with lag operators:

$$\mathbb{L}: x_t \mapsto x_{t-1}$$

▶ Now, AR(1) is  $y_t = \phi \cdot \mathbb{L} y_t + \epsilon_t$ 

## Concepts: basic statistics

First, we review some basic statistics:

- expectation:
  - $\mathbb{E}[g(x)] \equiv \int g(x) \cdot f(x) dx$
  - $\triangleright$  g(x) is an arbitrary function
  - f(x) is the probability density function
- mean:
  - A 'typical' value
  - $\mu(x) = \mathbb{E}[x]$
- variance:
  - A measure of volatility or the spread of a distribution
  - ▶  $Var[x_t] = \mathbb{E}[(x_t \mu(x_t)) * (x_t \mu(x_t))^T]$
- standard deviation:

# Concepts: time series (1/2)

To understand persistence of a time series, examine:

- autocovariance:
  - How much a lag predicts a future value of a time series
  - $acov(x_t, x_{t-h}) \equiv \mathbb{E}[(x_t \mu(x_t)) * (x_{t-h} \mu(x_{t-h})))]$
  - ▶ Often written as  $\gamma(s,t)$  or  $\gamma(h)$  for this case
- autocorrelation:
  - A dimensionless measure of the influence of one lag upon another
  - ▶ Helps determine which ARIMA model to use

$$\mathtt{acorr}[x_t] = \frac{\mathtt{acov}[x_t, x_{t+h}]}{(\sigma(x_t) * \sigma(x_{t+h}))}$$

• Often written as  $\rho(t) \equiv \gamma(t)/\gamma(0)$  for this case

# Concepts: time series (2/2)

### Special time series (easier to forecast):

- ➤ To forecast, need mean, variance, and correlation to be stable over time
- strictly stationary:
  - $\{x_t\}$  is strictly stationary if  $f(x_1,...,x_t) = f(x_{1+h},...,x_{t+h}), \forall h$
- weakly stationary
  - ▶ mean is constant for all periods:  $\mu(x_t) = \mu(x_{t+h}), \forall h$
  - ightharpoonup autocorrelation, ho(s,t), depends only on |s-t|
- white noise:
  - ▶  $acov(x_t, x_{t+h}) = var[x_t]$  iff h = 0 and 0 otherwise
  - is (weakly) stationary
  - ▶ is a key building block of time series models

## Analog principles

Analog principle: replace expectations with sample averages when calculating statistics

- ▶ Intuition: the Weak Law of Large Numbers
- Examples:
  - Mean:  $\mathbb{E}[x] \to \frac{1}{N} \sum_{i=1}^{N} x_i$
  - ▶ In general:  $\mathbb{E}[g(x)] \rightarrow \frac{1}{N} \sum_{i=1}^{N} g(x_i)$
- ▶ Sometimes, we replace N with N-1 (e.g., for the variance):
  - ▶ So the statistic is *consistent*
  - ▶ E.g.,  $\mathbb{E}[\overline{x}] = \mathbb{E}[x_i] = \mu(x)$
  - I.e., the estimator is unbiased

### ARIMA models

#### ARIMA introduction

#### ARIMA is a benchmark model:

- ARIMA(p,d,q) consists of:
  - AR(p): persistence of history through AR terms
  - ► I(d): trend
  - MA(q): influence of past shocks through MA terms
- Can add higher order lags for seasonality
- If your fancy algorithm doesn't beat ARIMA, use ARIMA!

Terms: AR(p)

An AR(p) model captures the persistence of past history.

- ► AR(p) means auto-regressive of order p:  $y_t = \phi_1 \cdot y_{t-1} + ... + \phi_p \cdot y_{t-p} + \epsilon_t$
- Often, written with lag operators and polynomials:  $\Phi(\mathbb{L}) \cdot y_t = \epsilon_t$ , where  $\Phi(\cdot)$  is polynomial of order p.

# Terms: MA(q)

An MA(q) model captures the persistence of past shocks.

- ► MA(q) means moving average of order q:  $y_t = \epsilon_t + \psi_1 \cdot \epsilon_{t-1} + ... + \psi_q \cdot \epsilon_{t-q}$
- ▶ Often, written with lag operators and polynomials:  $y_t = \Psi(\mathbb{L}) \cdot \epsilon_t$ , where  $\Psi(\cdot)$  is polynomial of order q.
- ▶ Do not confuse with computing the moving average of  $\{y_t\}$ , which is often used to aggregate data.

# Terms: I(d)

An I(d) model captures the non-stationary trend.

- ▶ I(d) means integrated of order d:  $y_t = y_{t-1} + \mu + \epsilon_t$
- d is how many times you must difference the series so that it is stationary
- ▶ Usually,  $d \in \{0, 1, 2\}$
- Differencing should remove the trend component
- Example: random walk (with drift)
- Compute differences with np.diff(n=d) or pd.Series.diff(periods=d) to turn ARIMA into ARMA.

#### ARIMA models

An ARIMA(p,d,q) is a general model which includes AR, I, and MA:

- AR(p): AR of order p
- ▶ I(d): I of order d
- MA(q): MA of order q

#### Remarks:

- AR, I, and/or MA may be missing from a general ARIMA model
- ► May also include seasonal components . . . Specify as ARIMA(p,d,q)(P,D,Q)
- ▶ If  $d = 0 \Rightarrow ARIMA$  becomes ARMA

# Box-Jenkins methodology

Use Box-Jenkins's approach to fit an ARIMA model:

- 1. Exploratory data analysis (EDA):
  - plot series, ACF, PACF
  - identify hypotheses, models, and data issues
  - aggregate to an appropriate grain
- 2. Fit model(s)
  - Difference until stationary
  - ► Test for a unit root (Augmented Dicky-Fuller (ADF))
  - Transform until variance is stable
- 3. Examine residuals: are they white noise?
- 4. Test and evaluate on out of sample data
- 5. Worry about:
  - structural breaks
  - forecasting for large h with limited data => need a "panel of experts"
  - seasonality, periodicity



# Modeling flow chart from Hyndman et al.

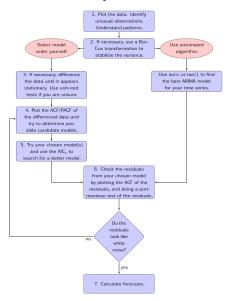


Figure 3:

# Graphical tools

Plot data to develop understanding of data and possible models:

- Key diagnostic plots:
  - ightharpoonup Plot series  $y_t$  vs t
  - ▶ Plot autocorrelation function (ACF), i.e.,  $\rho(h)$  vs. h
  - Plot partial autocorrelation function (PACF)
- Repeat for first and second differences, if necessary:
  - Compute differences with np.diff(n=d) or pd.Series.diff(periods=d)
  - ▶ Transform series, if necessary, e.g,  $y_t \rightarrow \log(y_t)$
  - ▶ Check stationarity: i.e., no trend and constant variance

# Autocorrelation function (ACF)

Shows likely order of the MA(q) part of the ARIMA(p,d,q) model:

- ▶ Plots  $\rho(h)$  vs. lags h
- Find largest significant spike
- ▶ Consider order q, where q = largestlag

```
import statsmodels.api as sm
data = sm.tsa.arma_generate_sample(ar=[ 0.7, 0.0, 0.3],
    ma=[0.2, -0.1], 100)
sm.graphics.tsa.plot_acf(data, ax=ax, lags=28,
        alpha=0.05)
plt.show()
```

# Partial autocorrelation function (PACF)

Shows likely order of the AR(p) part of the ARIMA(p,d,q) model:

- ▶ Plots partial autocorrelation vs. lags h
- Partial autocorrelation uses a regression method to compute effect of just a single lag but not intermediate lags like ACF
- ▶ Consider order p, where p =largest lag

```
import statsmodels.api as sm
data = sm.tsa.arma_generate_sample(ar=[ 0.7, 0.0, 0.3],
    ma=[0.2, -0.1], 100)
sm.graphics.tsa.plot_pacf(data, ax=ax, lags=28,
        alpha=0.05)
plt.show()
```

# Example: plotting series, ACF, and PACF (1/3)

You will do this all the time, so create a helper function:

```
def tsplot(data, lags=28):
    fig = plt.figure(figsize=(15,10))
    ax1 = fig.add subplot(311)
    ax1.plot(data)
    ax1.set title('y t vs. t')
    ax2 = fig.add subplot(312)
    sm.graphics.tsa.plot acf(data, lags=lags, ax=ax2)
    ax3 = fig.add_subplot(313)
    sm.graphics.tsa.plot_pacf(data, lags=lags, ax=ax3)
    fig.show()
    return fig
```

# Example: diagnostic plots (2/3)

# Example: diagnostic plots (3/3)

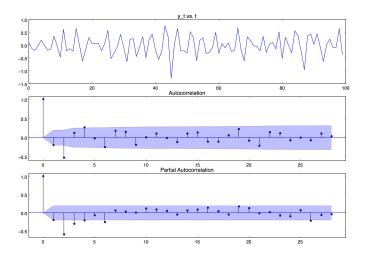


Figure 4: Three diagnostic plots

### Practical advice

### Questions to ask

#### Look at the time series plots and ask:

- Is it stationary?
- ▶ Is there a trend?
- Is the variance stable?
- Are there seasonal or periodic components?
- What AR and MA terms are likely present?
- ▶ Are there structural breaks in the data?
- ▶ Do I have enough data to forecast at horizon h?

# Stabilizing the time series

You need to stabilize the time series before estimating a model:

- Transform data to stabilize variance:
  - $ightharpoonup y_t \leftarrow \log(y_t)$
  - Verify via Box-Cox test
  - Verify by plotting
- Transform data so series is stationary:
  - Compute first or second difference
  - $\triangleright$   $y_t \leftarrow \mathbb{L}y_t$  or  $y_t \leftarrow \mathbb{L}^2 y_t$
  - Verify by portmanteau test

### Fit an ARIMA model

#### To fit a model:

- Split data into train set (earlier observations) and test set (later observations)
- ➤ To forecast at horizon h, train should have at least 3 × h observations plus h test observations
  - I.e., you cannot forecast demand in two years if you only have three months of data
  - If these conditions are violated, you need a 'panel of experts'
  - More data is better, especially if seasonality is present
- To identify optimal order of model:
  - Examine ACF and PACF
  - Difference until stationary
  - Number of differences is order q for I(q)
  - Use sm.tsa.arma\_order\_select\_ic to generate and compare several models
  - Use cross validation



# Example: (1/2)

```
import statsmodels.api as sm
data = sm.datasets.macrodata.load pandas()
df = data.data
df.index = pd.Index(
    sm.tsa.datetools.dates_from_range('1959Q1', '2009Q3'))
v = df.m1
X = df[['realgdp', 'cpi']]
model = sm.tsa.ARIMA(endog=y, order=[1,1,1])
# model2 = sm.tsa.ARIMA(endog=y, order=[1,1,1], exog=X)
results = model.fit()
results.summary()
```

# Example: (2/2)

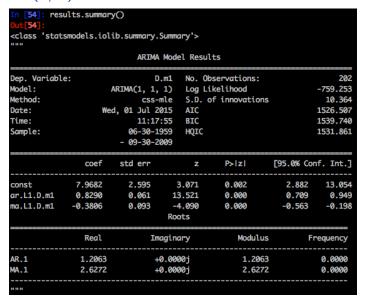


Figure 5: Example: summary output from ARIMA model

#### Prediction intervals

A forecast of  $\{y_t\}$  at time t + h computes:

- $\hat{y}_{t+h|t}$ , the expected mean of  $y_t$  at time t+h conditional on the information available at t
- ► The *prediction interval* 
  - A interval containing future realization of the mean  $y_{t+h}$  with probability  $1-\alpha$
  - The prediction interval increases the further you forecast into the future
- A prediction interval is not a confidence interval:
  - $\blacktriangleright$  A prediction interval contains the future realization of a random variable with  $\Pr=1-\alpha$
  - $\blacktriangleright$  A confidence interval contains the true value of a parameter with  ${\rm Pr}=1-\alpha$
- See Hyndman's blog post for further discussion



# Forecasting

Can use results.forecast to compute out of sample predictions:

- ▶ Use alpha to choose appropriate prediction interval, e.g., 80%, 90%, 95%, etc.
- lacktriangle Do not use the prediction interval to forecast quantiles of  $\hat{y}_{t+h|t}$
- Note: documentation incorrectly refers to the prediction interval as the confidence interval
- Can supply (forecasted) value of exogenous predictors
- >> y\_hat, stderr, pred\_int = results.forecast(steps=h,
   alpha=0.05)

## Forecast: prediction intervals

Prediction plot includes a *prediction interval*:

- ▶ Contains future realization of  $y_{t+h}$  with probability  $1 \alpha$
- ▶ A prediction interval is not a confidence interval

```
results.plot_predict('2009Q3', '2014Q4', dynamic=True,
    plot_insample=True)
plt.show()
```

# Example: prediction intervals

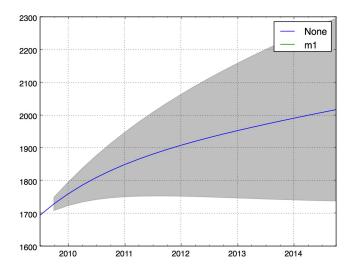


Figure 6: Prediction plot

#### **Evaluate**

#### Trust but verify:

- Check residuals are white noise:
  - Examine ACF
  - Compute portmanteau (Box-Pierce, Box-Ljung) test to see if residuals are correlated
- Check solver converged!
- Remember: simple models tend outperform fancy models on new data
- Compare any forecast against the benchmark forecast
  - Choose a benchmark such as mean or random walk with drift
  - ► Fit model on training set and evaluate on test set
  - ► To compare multiple forecasts, use a sliding window

### Common metrics

It is common to use several metrics for evaluation:

► Root mean squared error:  $RMSE \equiv \sqrt{\sum (y_{t+h} - \hat{y}_{t+h|t})^2}$ 

Mean average error.

$$MAE \equiv \frac{1}{H} \sum |y_{t+h} - \hat{y}_{t+h|t}|$$

Mean average percentage error.

$$MAPE \equiv \frac{1}{H} \sum \left| \frac{y_{t+h} - \hat{y}_{t+h|t}}{y_{t+h}} \right|$$

#### Model selection

#### Use information criterion to evaluate models:

- Several information criteria exist: AIC, AICc, BIC
  - Essentially, log-likelihood plus penalty for adding parameters
  - Measures fit vs. parsimony of model
  - Different criteria have different finite sample properties
- Choose model with lowest information criterion
- Especially helpful if you have limited data
- Popular, pre-ML method, but consider cross-validation if you have enough data

# Tips & Tricks

#### Some hard won wisdom:

- Work at the appropriate level of aggregation (grain):
  - Don't use 5 minute resolution data to forecast at h = one month
- Don't forecast beyond what the data will support
  - You should have 4 × h amount of data to forecast at horizon h
- Err on the side of simplicity
- Or, take a machine learning approach:
  - Try a set of lags and differences plus other predictors
  - Use regularization and/or variable selection
  - See Taieb & Hyndman for an approach which uses boosting.

# Advanced ARIMA techniques

#### For more complicated situations:

- Add Fourier terms to capture periodic behavior
- Add other covariates which can improve prediction
- Use a vector autoregressive integrated moving average model (VARIMA) to capture dynamics of a system of equations

# Exponential smoothing (ETS) models

#### ETS introduction

#### Exponential smoothing models are a benchmark model:

- ► Robust performance
- Easy to explain to non-technical stakeholders
- Easy to estimate with limited computational resources
- Forecast well because of parsimony

### The model

### The model consists of smoothing equations for

- Forecast
- Level
- Trend (optional)
- Seasonality (optional)

#### Remarks:

- Can use either an additive or multiplicative specification
- Can use a state space formulation

# Example: simple exponential smoothing – ETS(ANN)

Simple exponential smoothing updates forecast based on latest realization of  $y_t$ :

- Forecast equation:  $\hat{y}_{t+1|t} = \ell_t$
- Level equation:  $\ell_t = \alpha \cdot y_t + (1 \alpha) \cdot \ell_{t-1}$

If  $y_t = \hat{y}_{t|t-1} + \epsilon_t$ , can use *error correction* formulation:

- $y_t = \ell_{t-1} + \epsilon_t$
- $\ell_t = \ell_{t-1} + \alpha \cdot \epsilon_t$

# Example: Holt's linear model – ETS(AAN)

ETS(AAN) adds slope to the model to better handle a trend:

- ▶ Forecast equation:  $\hat{y}_{t+h|t} = \ell_t + h \cdot b_t$
- ▶ Level equation:  $\ell_t = \alpha \cdot y_t + (1 \alpha) \cdot (\ell_{t-1} + b_{t-1})$
- ▶ Trend equation:  $b_t = \beta^* \cdot (\ell_t \ell_{t-1}) + (1 \beta^*) \cdot b_{t-1}$

# Hyndman's taxonomy

Hyndman categorizes exponential smoothing models as ETS:

- E for type of error
- T for type of trend
- S for type of seasonality

#### Typical values are:

- A for additive
- M for multiplicative
- N for none
- A<sub>d</sub> for additive damped
- ▶ *M<sub>d</sub>* for multiplicative damped

## Example:

ETS makes it easy to describe the type of model you want to use:

- ETS(AAN):
  - Has additive error and trend but no seasonality
  - Simple exponential smoothing
  - ▶ I.e., Holt's linear method, 'double exponential smoothing'
- ► ETS(AAA):
  - Holt-Winters' method
  - Adds seasonality

## The ETS model

#### Python provides partial support for ETS:

- See Panda's pandas.stats.moments.ewma
- User unfriendly
- ▶ Best to use R's ets function in the forecast package

## ETS vs. ARIMA

#### ARIMA features & benefits:

- Benchmark model for almost a century
- Much easier to estimate with modern computational resources
- Easy to diagnose models graphically
- Easy fit using Box-Jenkins

#### ETS features & benefits:

- Can handle non-linear and non-stationary processes
- Can be computed with limited computational resources
- Not always a subset of ARIMA
- Easier to explain to non-technical stakeholders

# Summary

# Summary

You should now be able to answer the following questions:

- ▶ What are the steps in the Box-Jenkins's approach?
- ▶ How much data do I need to forecast at horizon *h*?
- How should I evaluate a forecast?
- What are the benefits of ARIMA vs. ETS?