

Linear Regression

*** *More slides here*

https://github.com/gSchool/DSI_Lectures/tree/master/linear-regression

Overview

Machine Learning

- Regression vs Classification
- Supervised vs Unsupervised

Other models that use linear regression

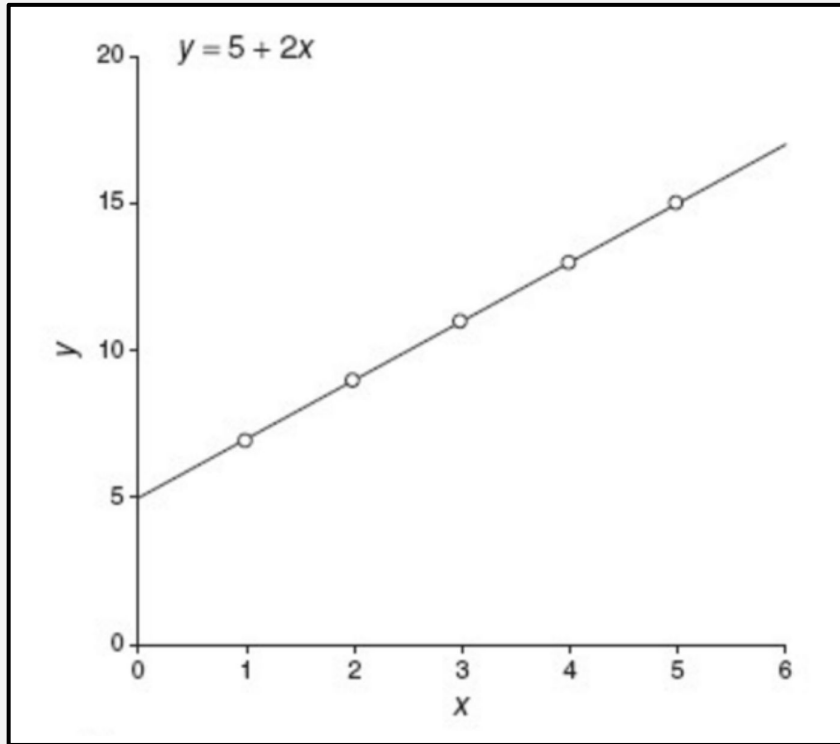
- Logistic Regression
- Multilayer Perceptrons (Deep Learning)

Getting Started

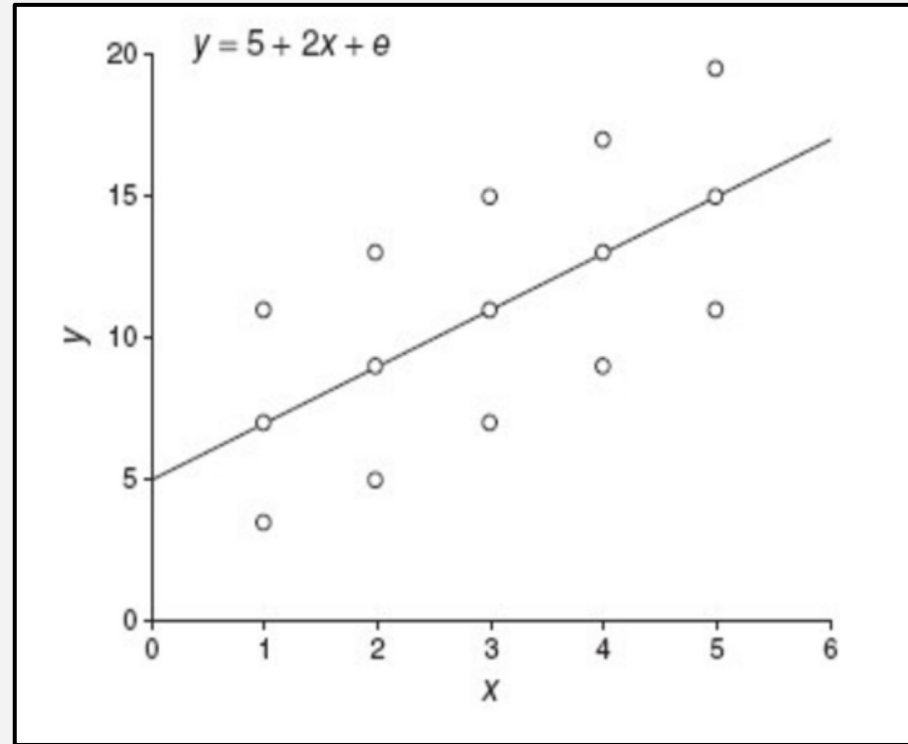
Interactive Linear Regression Demonstrations

- <http://setosa.io/ev/ordinary-least-squares-regression/>
- https://phet.colorado.edu/sims/html/least-squares-regression/latest/least-squares-regression_en.html
- <http://miabellaai.net/demo.html>

Exact Fit



Inexact Fit



The Model

Simple Linear Regression

- The World
 - what you're presuming the world looks like:

$$Y = \beta_0 + \beta_1 X + \epsilon$$

- β_0 and β_1 are unknown constants that represent the intercept and slope
- ϵ , the error term, is i.i.d $N(0, \sigma^2)$

- The Model
 - what you've created from data to estimate the world:

$$\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x$$

- $\hat{\beta}_0$ and $\hat{\beta}_1$ are model coefficient estimates
- \hat{y} indicates the prediction of Y based on $X = x$

Matrix Form

$$\mathbf{Y}_{n \times 1} = \mathbf{X}_{n \times p} \boldsymbol{\beta}_{p \times 1} + \boldsymbol{\epsilon}_{n \times 1}$$

Target:

$$\mathbf{X} = \begin{bmatrix} 1 & X_{1,1} & X_{1,2} & \cdots & X_{1,p-1} \\ 1 & X_{2,1} & X_{2,2} & \cdots & X_{2,p-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & X_{n,1} & X_{n,2} & \cdots & X_{n,p-1} \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

- Coefficient Matrix $\boldsymbol{\beta}$

$$\boldsymbol{\beta} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_{p-1} \end{bmatrix}$$

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

Linear Regression Libraries

- StatsModels
 - http://www.statsmodels.org/dev/generated/statsmodels.regression.linear_model.OLS.html
- Scikit Learn
 - http://scikit-learn.org/stable/modules/generated/sklearn.linear_model.LinearRegression.html

DEMO #1

Model Evaluation

Statsmodels Summary

OLS Regression Results						
Dep. Variable:	mpg		R-squared:	0.708		
Model:	OLS		Adj. R-squared:	0.704		
Method:	Least Squares		F-statistic:	186.9		
Date:	Mon, 05 Mar 2018		Prob (F-statistic):	9.82e-101		
Time:	12:20:06		Log-Likelihood:	-1120.1		
No. Observations:	392		AIC:	2252.		
Df Residuals:	386		BIC:	2276.		
Df Model:	5					
Covariance Type:	nonrobust					
	coef	std err	t	P> t	[0.025	0.975]
const	46.2643	2.669	17.331	0.000	41.016	51.513
cylinders	-0.3979	0.411	-0.969	0.333	-1.205	0.409
displacement	-8.313e-05	0.009	-0.009	0.993	-0.018	0.018
weight	-0.0052	0.001	-6.351	0.000	-0.007	-0.004
acceleration	-0.0291	0.126	-0.231	0.817	-0.276	0.218
hp	-0.0453	0.017	-2.716	0.007	-0.078	-0.012
Omnibus:	38.561	Durbin-Watson:	0.865			
Prob(Omnibus):	0.000	Jarque-Bera (JB):	52.737			
Skew:	0.706	Prob(JB):	3.53e-12			
Kurtosis:	4.111	Cond. No.	3.87e+04			

RMSE

RSE (aka RMSE)

$$RSE = RMSE = \sqrt{\frac{RSS}{n-p-1}} = \sqrt{\frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n-p-1}}$$

R squared

Coefficient of Determination $\rightarrow R^2 = \frac{SSR}{SST} = 1 - \frac{SSE}{SST}$

Sum of Squares Total $\rightarrow SST = \sum (y - \bar{y})^2$

Sum of Squares Regression $\rightarrow SSR = \sum (y' - \bar{y}')^2$

Sum of Squares Error $\rightarrow SSE = \sum (y - y')^2$

t-statistic

Suppose we wish to test

$$H_0: \beta_1 = \beta_{1,0}$$

$$H_1: \beta_1 \neq \beta_{1,0}$$

$$\frac{\hat{\beta}_1 - \beta_{1,0}}{se(\hat{\beta}_1)}$$

P-value

From the df and the t-statistic, find the p-value:

<https://faculty.washington.edu/heagerty/Books/Biostatistics/TABLES/t-Tables/>

Confidence interval

From the df and percent, find the t-statistic:

<https://faculty.washington.edu/heagerty/Books/Biostatistics/TABLES/t-Tables/>

$$\text{Beta} \pm t(df) * SE$$

DEMO #2

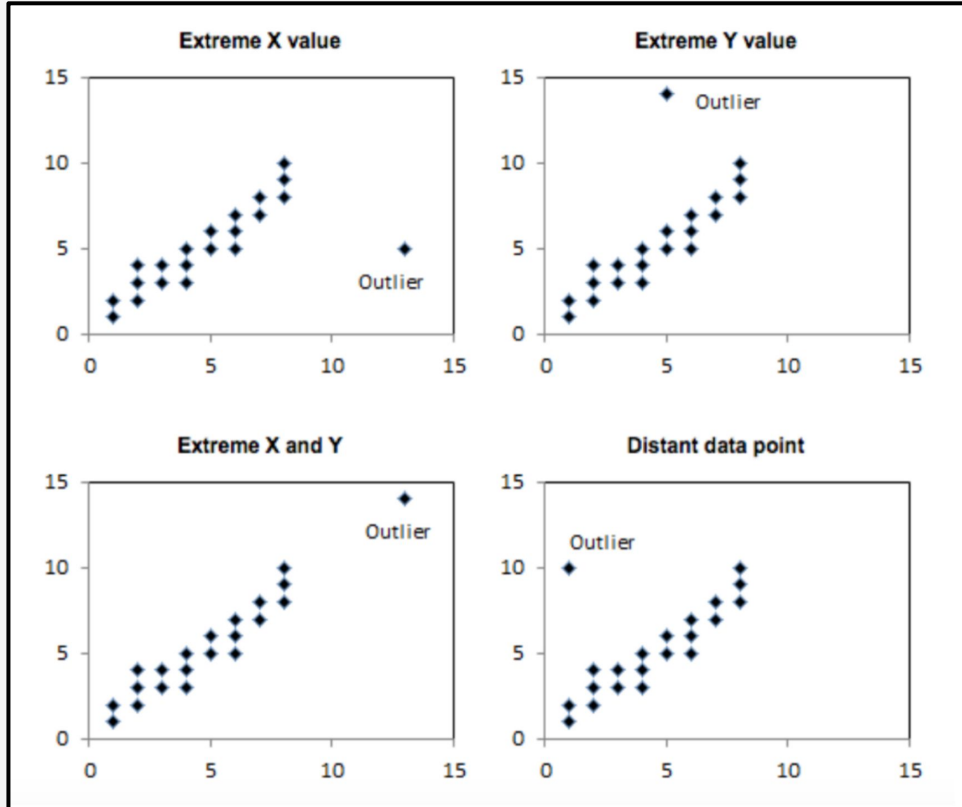
Assumptions of Linear Regression

- Assumptions of Linear Regression
 - Linearity
 - We assume it's possible
 - Constant Variance (Homoscedasticity)
 - Our variance shouldn't change as y or X gets bigger
 - Independence of Errors
 - We should gain no information from knowing the error of a different data point
 - Normality of Errors
 - Errors should be normally distributed
 - Lack of Multicollinearity
 - We shouldn't be measuring the same thing in multiple ways

We can't always meet these assumptions, and often have to find ways to combat that reality.

Residuals

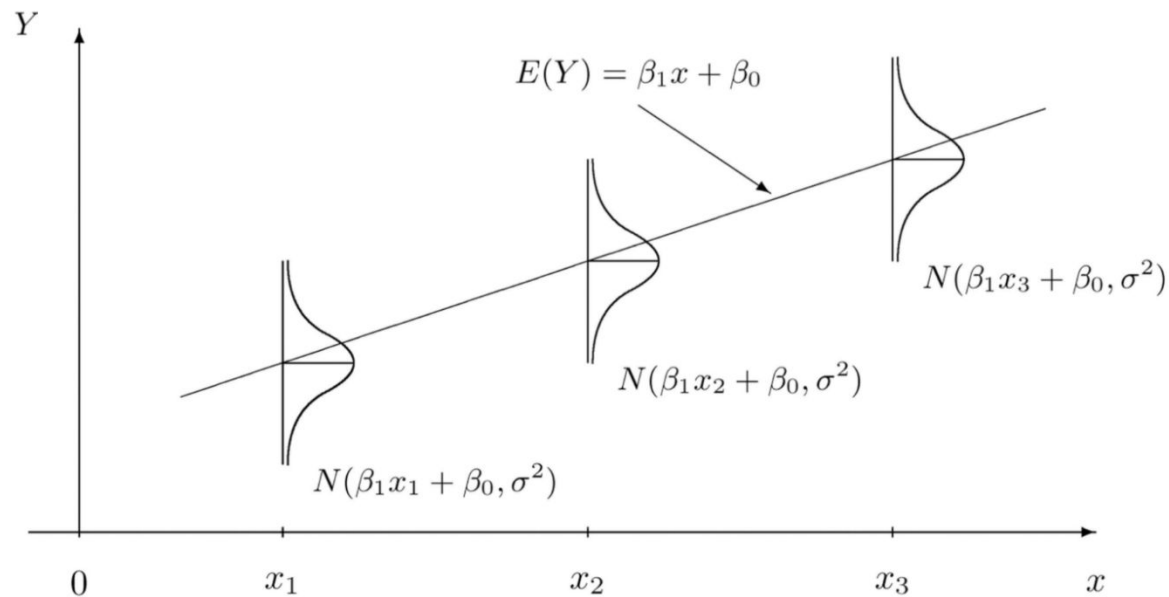
Types of Outliers



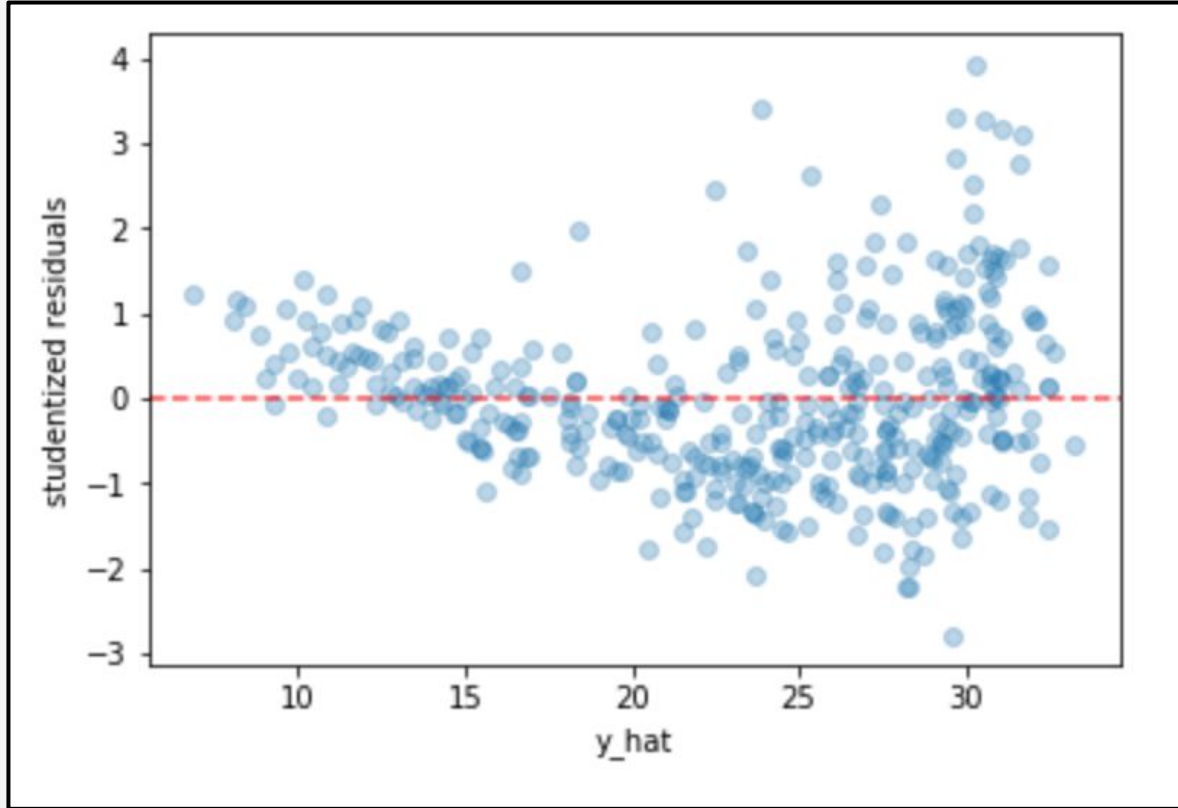
Residuals

$$Y_i = \beta_0 + x_i \beta_1 + \epsilon_i, \epsilon_i \stackrel{i.i.d.}{\sim} \text{Normal}(0, \sigma^2)$$

Intercept Error/Noise



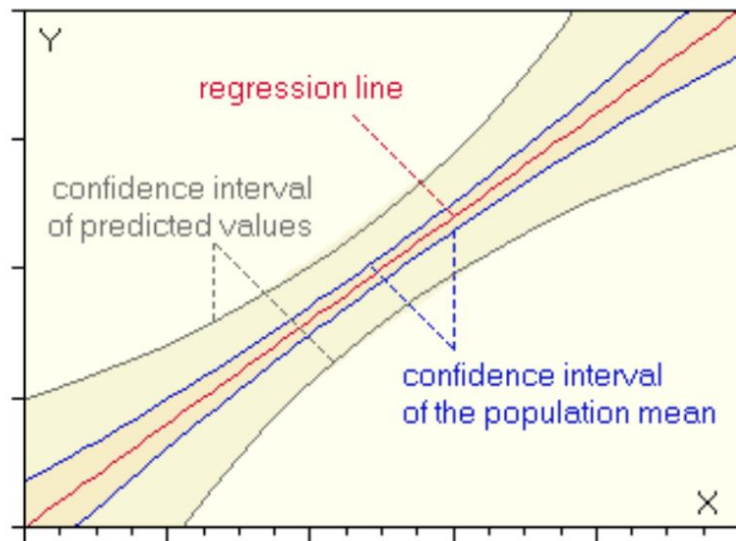
Studentized Residuals



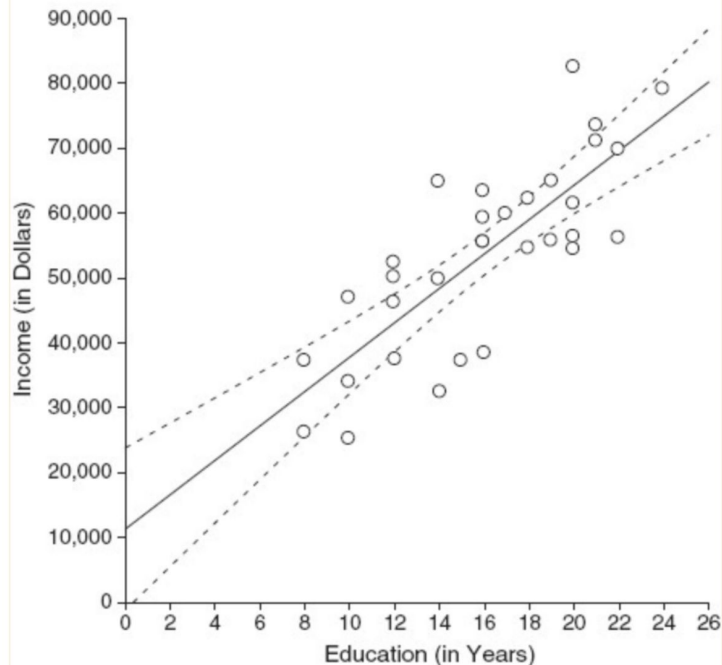
Studentized Residuals

Studentized Residuals
have a t-distribution...

$$r_i = \frac{\hat{\epsilon}_i}{\hat{\sigma}\sqrt{1 - h_{ii}}}$$



Even better still, we can "**Studentize**" the errors by dividing, not by the "global" standard error for our model, but by the standard error of our model at the particular value of y where the residual occurred. Our confidence intervals change depending on how much data we have seen in a particular region. If we've seen a lot of data, our intervals are tight; otherwise, they are wide. So, it takes "more" for a data point to be considered an outlier if it is in a region in which we have little data.



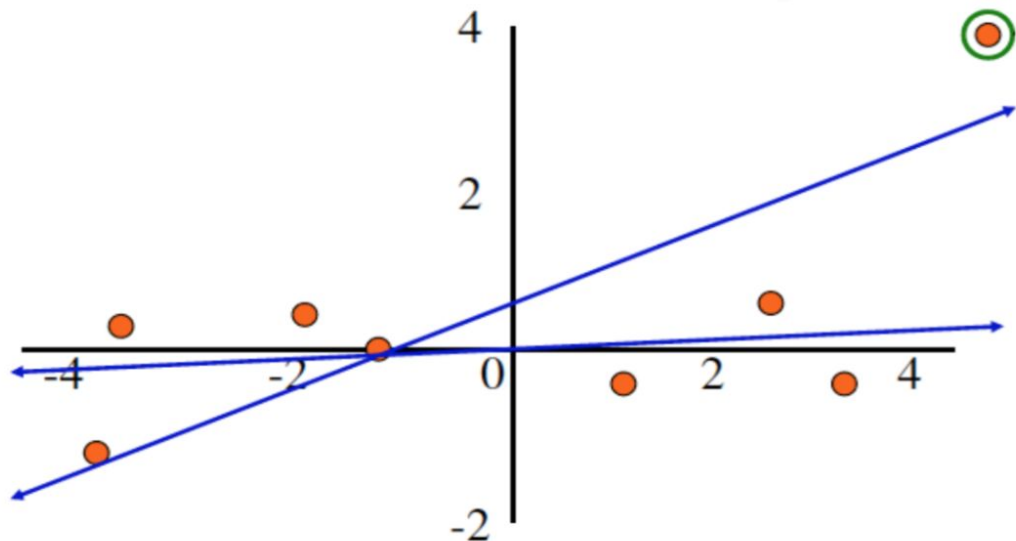
Studentized Residuals

Leverage

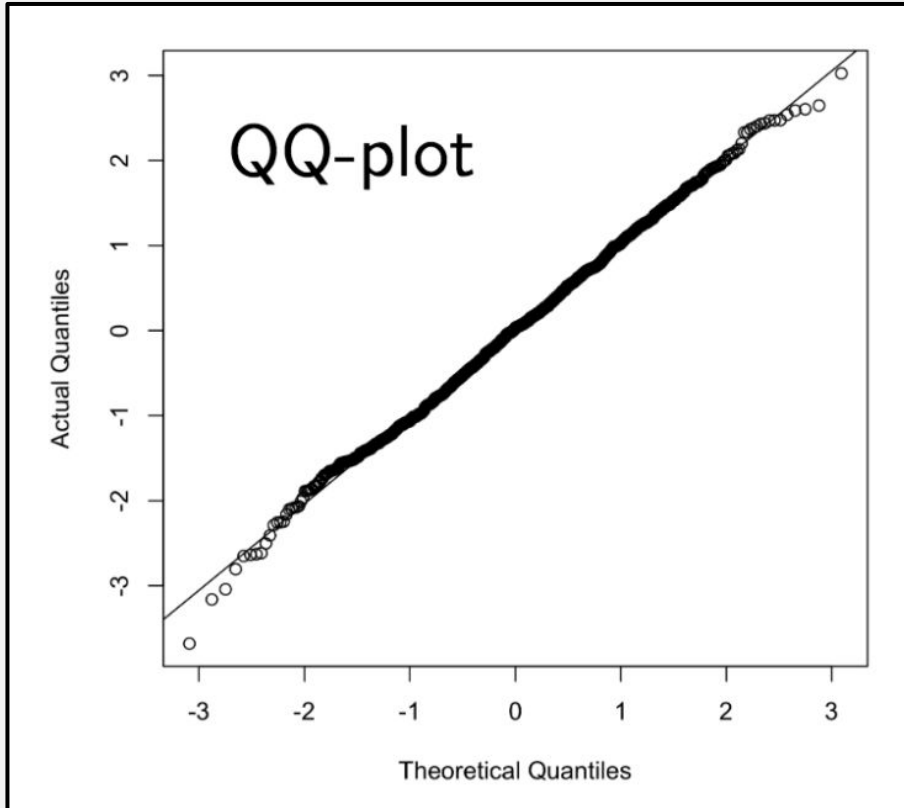
The *hat* matrix H “puts the hat on” \mathbf{Y} projecting \mathbf{Y} onto the (least squares) closest vector to \mathbf{Y} in the column space of \mathbf{x} , $\hat{\mathbf{Y}} \in \mathcal{R}(\mathbf{x})$

$$H = \mathbf{x}(\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T$$

$$\begin{aligned}\hat{\mathbf{Y}} &= \mathbf{x}(\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T \mathbf{Y} \\ &= H\mathbf{Y}\end{aligned}$$



QQ Plots



If a set of observations is approximately normally distributed, a normal quantile-quantile (QQ) plot of the observations will result in an approximately straight line.

DEMO #3