

Low Rank Approximations, PCA, and CCA

Abhinav Gopal, Shrey Vasavada, William McEachen,
Grace Kull, Jai Bansal

- What is a low rank approximation?
 - Large amounts of data is expensive
 - Furthermore, some *unimportant* aspects of data reflect noise
 - How do we create an approximation of the data with just the important features?
- Option: Reduce features
 - How? Choose the most “important” features of the matrix
 - Decompose to svd and only use the top “k” values
 - $\sum_{i \in (1 \dots k)} \mathbf{u}_i \sigma_i \mathbf{v}_i^T$

- Notice from the previous slide that our low rank approximation's column space was the k vectors v_i
- These vectors represent the directions of most variance in our data
- Idea: Use these vectors in $Xw = y$ prediction tasks
 - Project X onto these important directions, and use this projection to predict y .

- This brings us to PCA!
- Procedure
 - Compute SVD for matrix X
 - Get the top k eigenvectors V_i^T and choose these eigenvectors
 - Get the principal components by finding $Z_k = XV_k$
 - Get the approximation for X by doing ZV_k^T
 - Use this approximation and do least squares

- Great, but flawed, way to approximate a matrix and eliminate noise.
 - Why? Relies on the assumption that the largest variance directions are the most important ones.
- Very easy to modify data in order to render PCA useless
- What is the workaround?
 - We try to find the actual correlation between X and y .

- This brings us to CCA
 - Canonical Correlation Analysis
- CCA uses the pearson correlation coefficient in order to determine the relationship between X and y .

$$\begin{aligned}\hat{\rho}(x, y) &= \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2 \cdot \sum_{i=1}^n (y_i - \bar{y})^2}} \\ &= \frac{\tilde{x}^\top \tilde{y}}{\sqrt{\tilde{x}^\top \tilde{x} \cdot \tilde{y}^\top \tilde{y}}} \quad \text{where } \tilde{x} = x - \bar{x}, \tilde{y} = y - \bar{y}\end{aligned}$$

- Goal: To Solve

$$\max_{\mathbf{u}, \mathbf{v}} \rho(\mathbf{X}_{rv}^T \mathbf{u}, \mathbf{Y}_{rv}^T \mathbf{v}) = \max_{\mathbf{u}, \mathbf{v}} \frac{\text{Cov}(\mathbf{X}_{rv}^T \mathbf{u}, \mathbf{Y}_{rv}^T \mathbf{v})}{\sqrt{\text{Var}(\mathbf{X}_{rv}^T \mathbf{u}) \text{Var}(\mathbf{Y}_{rv}^T \mathbf{v})}}$$

- \mathbf{X}_{rv} and \mathbf{Y}_{rv} are both real vectors that correspond to the size of \mathbf{X} and \mathbf{Y} .
- With some algebra, we find that the problem becomes

$$\max_{\mathbf{u}, \mathbf{v}} \frac{\mathbf{u}^T \mathbf{X}^T \mathbf{Y} \mathbf{v}}{\underbrace{\sqrt{\mathbf{u}^T \mathbf{X}^T \mathbf{X} \mathbf{u} \cdot \mathbf{v}^T \mathbf{Y}^T \mathbf{Y} \mathbf{v}}}_{\hat{\rho}(\mathbf{X}\mathbf{u}, \mathbf{Y}\mathbf{v})}}$$

- Whiten the X and Y matrices (make their covariance 0) by
 - Use $W_x = U_x S_x^{-1/2} U_x^T$
 - Use $W_y = U_y S_y^{-1/2} U_y^T$
 - SVD of $X^T X = U_x S_x V_x^T$
 - SVD of $Y^T Y = U_y S_y V_y^T$
 - Use $X_w = X W_x$, $Y_w = Y W_y$

- With the change of variables $\mathbf{u}_w = \mathbf{W}_x^{-1}\mathbf{u}$ and $\mathbf{v}_w = \mathbf{W}_y^{-1}\mathbf{v}$, the max expression becomes:

- $$\max_{\mathbf{u}_w, \mathbf{v}_w} \frac{\mathbf{u}_w^\top \mathbf{X}_w^\top \mathbf{Y}_w \mathbf{v}_w}{\underbrace{\sqrt{\mathbf{u}_w^\top \mathbf{u}_w \cdot \mathbf{v}_w^\top \mathbf{v}_w}}_{\hat{\rho}(\mathbf{X}_w \mathbf{u}_w, \mathbf{Y}_w \mathbf{v}_w)}}$$

- Now, let's decorrelate \mathbf{X}_w and \mathbf{Y}_w , making $(\mathbf{X}_w \mathbf{D}_x)^\top (\mathbf{Y}_w \mathbf{D}_y)$
- We decorrelate them with the choice of
 - \mathbf{U} for \mathbf{D}_x and \mathbf{V} for \mathbf{D}_y , where $\mathbf{U}\mathbf{S}\mathbf{V}^\top = \mathbf{X}_w^\top \mathbf{Y}_w$

- Changing variables with
 - $\mathbf{u}_d = \mathbf{D}_x^T \mathbf{u}_w$ and $\mathbf{v}_d = \mathbf{D}_y^T \mathbf{v}_w$, the maximization becomes the following:

$$\begin{array}{l} \max \mathbf{u}_d^T \mathbf{S} \mathbf{v}_d \\ \|\mathbf{u}_d\|=1 \\ \|\mathbf{v}_d\|=1 \end{array}$$

- Finally, we get the associated eigenvectors of interest!
 - $\mathbf{U} = \mathbf{W}_x \mathbf{D}_x \mathbf{U}_d, \mathbf{V} = \mathbf{W}_y \mathbf{D}_y \mathbf{V}_d$, with

$$\mathbf{U}_d = \begin{bmatrix} \mathbf{I}_k \\ \mathbf{0}_{p-k,k} \end{bmatrix} \in \mathbb{R}^{p \times k}$$

$$\mathbf{V}_d = \begin{bmatrix} \mathbf{I}_k \\ \mathbf{0}_{q-k,k} \end{bmatrix} \in \mathbb{R}^{q \times k}$$