

Section 4.5: Backtracking

Backtracking (as a general technique)

- finds all (or some) solutions to a computational problem
- typically builds candidate solutions incrementally by trying each possible value
- to conceptually keep track of candidate solutions, each one is represented as a node in a tree (called the **search tree**)
- the algorithm traverses the tree in depth first order
- a process called **pruning** is used to eliminate branches or subtrees of the search tree when a partial candidate (and all choices thereafter) will not result in a solution

Suppose we need to solve a problem where a solution is of the form $x[1], x[2], \dots, x[n]$ and the values of $x[i]$ are elements of a set S of size n . (The elements of S could be any type and depend on the problem being solved.)

The general form for the backtracking algorithm is as follows:

```
// assume the scope of the array x is global
backtrack(n) {
    rbacktrack(1, n)
}

rbacktrack(k, n) {           // fills position k of array x
    for each x[k] in S        // systematically try each value of S
        if (bound(k))         // pruning step
            if (k == n) {
                // output solution
                // stop if only one solution is desired
            }
            else
                rbacktrack(k+1, n) // recursively fill position k+1
}

bound(k) {
    // a function that assumes that x[1], x[2], ..., x[k-1] is a
    // partial solution and x[k] has been assigned a value to try
    // returns true if x[1], x[2], ..., x[k] is a partial solution
    // returns false otherwise
}
```