

W. Nicholas Greene

Robust Robotics Group
Computer Science and Artificial Intelligence Laboratory (CSAIL)
Massachusetts Institute of Technology (MIT)
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Research Interests

High-speed autonomous navigation in unknown environments
Dense simultaneous localization and mapping (SLAM) and real-time 3D reconstruction
Parallel algorithms leveraging graphics processing units (GPUs)
Micro-aerial vehicles (MAVs)

Education

S.M. Aeronautics and Astronautics

2014–Present

Massachusetts Institute of Technology, Cambridge, MA.

Adviser: Nicholas Roy

Concentration: Autonomous Systems

B.S.E. Electrical Engineering

2006–2010

Princeton University, Princeton, NJ.

Concentration: Signal Processing

Senior Project: “Testing Residual-PCA Traffic Anomaly Detection Schemes”

Additional Coursework: Harvard CSCI-E 124 Algorithms and Data Structures (A-), Stanford CS229 Machine Learning (A), Udacity CS373 Programming a Robotic Car (“Highest Distinction”), Coursera Control of Mobile Robots (“Distinction” - 94.3 percent)

Research Experience

Robust Robotics Group

2012–Present

MIT Computer Science and Artificial Intelligence Laboratory (CSAIL), Cambridge, MA.

Conducting research for high-speed autonomous MAV navigation under Professor Nicholas Roy.

Current focus on estimating dense 3D geometry from low-SWaP onboard sensors.

Advanced Sensor Techniques Group

2010–2014

MIT Lincoln Laboratory, Lexington, MA.

Developed passive sonar localization and tracking algorithms for faint, acoustic targets in challenging underwater environments.

Recursive Bayesian state estimation algorithms currently deployed on *Los Angeles*-class and *Virginia*-class submarines.

Developed and integrated feature extraction tools for use in a mild traumatic brain injury (mTBI) detection system.

Autonomous Systems Division

2009

Jet Propulsion Laboratory (JPL), Pasadena, CA.

Conducted computer vision and object detection research under Senior Engineer Thomas Lu.

Applied various feature selection and extraction strategies to an existing multi-stage automatic target recognition system previously developed at JPL.

Work accepted for publication at the SPIE symposium on Defense, Security, and Sensing, in April 2010.

Koch Laboratory

2008

California Institute of Technology, Pasadena, CA.

Conducted computer vision and object recognition research under Professor Christof Koch.

Improved upon the existing object recognition algorithm H-MAX using biologically inspired preprocessing, weighted SVMs, and hyperfeature mining.

Teaching Experience

Open Robotics Laboratory *MIT, Cambridge, MA.*

2012-Present

Helped develop Lincoln Laboratory-sponsored introductory robotics course using the Robot Operating System (ROS) for MIT's Independent Activities Period.

Prepared course lectures and programming assignments.

Assisted students during in-class laboratory projects.

Lectured on robotic localization and navigation.

6-8th Grade Math and English *Premier Academy, West Covina, CA.*

2007

Taught Algebra I, Geometry, English, and Phonics to middle school students at a preparatory summer school.

Prepared class lectures, activities, homework, quizzes, and tests.

Publications

W. N. Greene, K. Ok, P. Lommel, N. Roy. "Multi-Level Mapping: Real-time Dense Monocular SLAM." IEEE International Conference on Robotics and Automation (ICRA), Stockholm, 2016.

K. Ok, W. N. Greene, N. Roy. "Simultaneous Tracking and Rendering: Real-time Monocular Localization for MAVs." IEEE International Conference on Robotics and Automation (ICRA), Stockholm, 2016.

L. Keyes, J. Su, T. Quatieri, B. Evans, J. Lacirignola, T. Vian, W. Greene, D. Strom, A. Dai. "FY12 Line-Supported Bio-Medical Initiative Program: Multi-modal Early Detection Interactive Classifier (MEDIC) for Mild Traumatic Brain Injury (mTBI) Triage." MIT Lincoln Laboratory Project Report LSP-41, November 2012.

L. Reilly-Raska, J. Su, P. Bisso, J. Braun, B. Evans, W. Greene, J. Lacirignola, R. Lippmann, T. Quatieri, W. Streilein, T. Vian. "FY11 Line-Supported Bio-Next Program: Multi-modal Early Detection Interactive Classifier (MEDIC) for Mild Traumatic Brain Injury (mTBI) Triage." MIT Lincoln Laboratory Project Report PR-LSP-34, April 2012.

W.N. Greene, Y. Zhang, T.T. Lu, T.S. Chiao. "Feature extraction and selection strategies for automated target recognition." SPIE Vol. 7703, Independent Component Analyses, Wavelets, Neural Networks, Biosystems, and Nanoengineering VIII, April, 2010.

W.N. Greene, J. Harel, C. Koch. "Improving object recognition using informative feature selection and biologically inspired image-preprocessing." Summer Undergraduate Research Fellowship (SURF) Abstract Book, August 2008.

Awards

NSF Graduate Research Fellowship *MIT, Cambridge, MA*

2014

Draper Fellowship *Draper, Cambridge, MA*

2014

Summer Undergraduate Research Fellowship *Jet Propulsion Laboratory, Pasadena, CA*

2009

Summer Undergraduate Research Fellowship *California Institute of Technology, Pasadena, CA*

2008

Professional Societies

IEEE Member

2011-Present

IEEE Robotics and Automation Society

2011-Present

Software Skills

Languages: C/C++, Python, Matlab, Java

Operating Systems: Linux/Unix, Windows, Mac OS

Libraries: CUDA/OpenCL, OpenCV, OpenGL, NumPy, SciPy, Eigen, LCM, ROS