



Figure 1: Model overview. We split an image into fixed-size patches, linearly embed each of them, add position embeddings, and feed the resulting sequence of vectors to a standard Transformer encoder. In order to perform classification, we use the standard approach of adding an extra learnable “classification token” to the sequence. The illustration of the Transformer encoder was inspired by Vaswani et al. (2017).

### 3 METHOD

In model design we follow the original Transformer (Vaswani et al., 2017) as closely as possible. An advantage of this intentionally simple setup is that scalable NLP Transformer architectures – and their efficient implementations – can be used almost out of the box.

#### 3.1 VISION TRANSFORMER (ViT)

An overview of the model is depicted in Figure 1. The standard Transformer receives as input a 1D sequence of token embeddings. To handle 2D images, we reshape the image  $\mathbf{x} \in \mathbb{R}^{H \times W \times C}$  into a sequence of flattened 2D patches  $\mathbf{x}_p \in \mathbb{R}^{N \times (P^2 \cdot C)}$ , where  $(H, W)$  is the resolution of the original image,  $C$  is the number of channels,  $(P, P)$  is the resolution of each image patch, and  $N = HW/P^2$  is the resulting number of patches, which also serves as the effective input sequence length for the Transformer. The Transformer uses constant latent vector size  $D$  through all of its layers, so we flatten the patches and map to  $D$  dimensions with a trainable linear projection (Eq. 1). We refer to the output of this projection as the patch embeddings.

Similar to BERT’s [class] token, we prepend a learnable embedding to the sequence of embedded patches ( $\mathbf{z}_0^0 = \mathbf{x}_{\text{class}}$ ), whose state at the output of the Transformer encoder ( $\mathbf{z}_L^0$ ) serves as the image representation  $\mathbf{y}$  (Eq. 4). Both during pre-training and fine-tuning, a classification head is attached to  $\mathbf{z}_L^0$ . The classification head is implemented by a MLP with one hidden layer at pre-training time and by a single linear layer at fine-tuning time.

Position embeddings are added to the patch embeddings to retain positional information. We use standard learnable 1D position embeddings, since we have not observed significant performance gains from using more advanced 2D-aware position embeddings (Appendix D.4). The resulting sequence of embedding vectors serves as input to the encoder.

The Transformer encoder (Vaswani et al., 2017) consists of alternating layers of multiheaded self-attention (MSA, see Appendix A) and MLP blocks (Eq. 2, 3). Layernorm (LN) is applied before every block, and residual connections after every block (Wang et al., 2019; Baevski & Auli, 2019).