

# 有限差分法和有限体积法在计算流体中的应用

## 结构化网格有限体积法

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- ① 引言
- ② 有限体积法公式推导
- ③ 边界条件

## ① 引言

## ② 有限体积法公式推导

## ③ 边界条件

# 引言

- 1965, Harlow and Welch 在美国 Los Alamos 国家实验室提出。

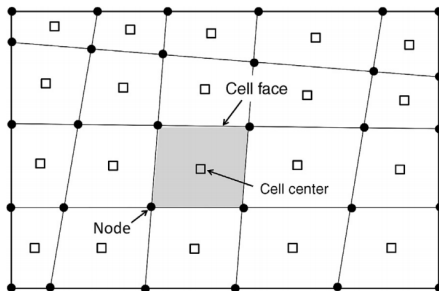
## ① 引言

## ② 有限体积法公式推导

## ③ 边界条件

# 引言

- cells
- faces
- nodes
- $\bar{\phi}_o = \frac{1}{V_o} \int_{V_o} \phi dV$



# 一维扩散方程

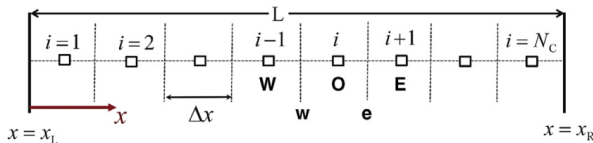
一维扩散方程为 (泊松方程):

$$\frac{d}{dx} \Gamma \left[ \frac{d\phi}{dx} \right] = -S_\phi$$

通量:

$$J = -\Gamma \frac{d\phi}{dx}$$

# 一维 FVM 离散 stencil



$$\int_w^e \frac{d}{dx} \Gamma \left[ \frac{d\phi}{dx} \right] dx = \int_w^e -S_\phi dx$$

$$\Downarrow$$

$$\Gamma \frac{d\phi}{dx} \Big|_{e,i} - \Gamma \frac{d\phi}{dx} \Big|_{w,i} = -S_i \Delta x_i$$

$$\Downarrow$$

$$J_{e,i} - J_{w,i} = S_i \Delta x_i$$



# 守恒性

局部守恒:

$$J_{e,i} - J_{w,i} = S_i \Delta x_i$$

整体守恒:

$$J_{e,N_C} - J_{w,1} = S_1 \Delta x_1 + S_2 \Delta x_2 + \cdots + S_{N_C} \Delta x_{N_C} = \int_{x_L}^{x_R} S dx$$

相对于有限差分法, 有限体积法无论什么样的网格类型都可以保证守恒性与网格无关。

# 精度分析

泰勒公式：

$$\phi_{i+1} = \phi_e + \frac{\Delta x}{2} \frac{d\phi}{dx} \Big|_e + \frac{1}{2} \left( \frac{\Delta x}{2} \right)^2 \frac{d^2\phi}{dx^2} \Big|_e + \frac{1}{6} \left( \frac{\Delta x}{2} \right)^3 \frac{d^3\phi}{dx^3} \Big|_e + \dots$$

$$\phi_i = \phi_e - \frac{\Delta x}{2} \frac{d\phi}{dx} \Big|_e + \frac{1}{2} \left( \frac{\Delta x}{2} \right)^2 \frac{d^2\phi}{dx^2} \Big|_e - \frac{1}{6} \left( \frac{\Delta x}{2} \right)^3 \frac{d^3\phi}{dx^3} \Big|_e + \dots$$

⇓

$$\frac{d\phi}{dx} \Big|_e = \frac{\phi_{i+1} - \phi_i}{\Delta x} - \frac{\Delta x^2}{24} \frac{d^3\phi}{dx^3} \Big|_e + \dots$$

⇓

$$\Gamma_{e,i} \frac{\phi_{i+1} - \phi_i}{\Delta x} - \Gamma_{w,i} \frac{\phi_i - \phi_{i-1}}{\Delta x} = -S_i \Delta x \quad \forall i = 2, \dots, N_c - 1$$

# 均匀网格

扩散系数 = 1:

$$\frac{\phi_{i+1} - 2\phi_i + \phi_{i-1}}{\Delta x^2} = -S_i \quad \forall i = 2, \dots, N_c - 1$$

扩散系数变化:

$$\begin{aligned} \Gamma_{e,i} &= \frac{\Gamma_i + \Gamma_{i+1}}{2}, \Gamma_{w,i} = \frac{\Gamma_i + \Gamma_{i-1}}{2} \\ \left( \frac{\Gamma_i + \Gamma_{i+1}}{2\Delta x} + \frac{\Gamma_i + \Gamma_{i-1}}{2\Delta x} \right) \phi_i &- \left( \frac{\Gamma_i + \Gamma_{i+1}}{2\Delta x} \right) \phi_{i+1} \\ &- \left( \frac{\Gamma_i + \Gamma_{i-1}}{2\Delta x} \right) \phi_{i-1} = S_i \Delta x \end{aligned}$$

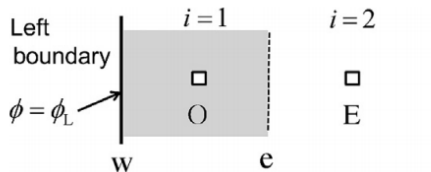
## ① 引言

## ② 有限体积法公式推导

## ③ 边界条件

# 引言

- Dirichlet
- Neumann
- Robin



# Dirichlet Condition

泰勒公式展开:

$$\phi_O = \phi_w + \frac{\Delta x}{2} \frac{d\phi}{dx} \Big|_w + \frac{1}{2} \left( \frac{\Delta x}{2} \right)^2 \frac{d^2\phi}{dx^2} \Big|_w + \frac{1}{6} \left( \frac{\Delta x}{2} \right)^3 \frac{d^3\phi}{dx^3} \Big|_w + \dots$$

整理可得:

$$\frac{d\phi}{dx} \Big|_w = \frac{2}{\Delta x} (\phi_O - \phi_w) - \frac{\Delta x}{4} \frac{d^2\phi}{dx^2} \Big|_w + \dots$$

几阶格式?

## 二阶格式

泰勒公式展开:

$$\phi_E = \phi_w + \frac{3\Delta x}{2} \frac{d\phi}{dx} \Big|_w + \frac{1}{2} \left( \frac{3\Delta x}{2} \right)^2 \frac{d^2\phi}{dx^2} \Big|_w + \frac{1}{6} \left( \frac{3\Delta x}{2} \right)^3 \frac{d^3\phi}{dx^3} \Big|_w + \dots$$

$\Downarrow$

$$\begin{aligned} \frac{d\phi}{dx} \Big|_w &= \frac{9\phi_O - \phi_E - 8\phi_w}{3\Delta x} + \frac{1}{8} \Delta x^2 \frac{d^3\phi}{dx^3} \Big|_w + \dots \\ &= \frac{9\phi_O - \phi_E - 8\phi_L}{3\Delta x} + \frac{1}{8} \Delta x^2 \frac{d^3\phi}{dx^3} \Big|_w + \dots \end{aligned}$$

# 扩散系数

一阶格式：

$$\Gamma_O = \Gamma_w + \frac{\Delta x}{2} \frac{d\Gamma}{dx} \Big|_w + \dots$$

⇓

$$\Gamma_w = \Gamma_O$$

二阶格式：

$$\Gamma_w = \frac{3\Gamma_O - \Gamma_E}{2}$$



## 左端

扩散系数变化:

$$\frac{\Gamma_1 + \Gamma_2}{2} \left( \frac{\phi_2 - \phi_1}{\Delta x} \right) - \frac{3\Gamma_1 - \Gamma_2}{2} \left( \frac{9\phi_1 - \phi_2 - 8\phi_L}{3\Delta x} \right) = -S_1 \Delta x$$

⇓

$$\begin{aligned} & \frac{\Gamma_1 + \Gamma_2}{2} \left( \frac{\phi_2 - \phi_1}{\Delta x} \right) - \frac{3\Gamma_1 - \Gamma_2}{2} \left( \frac{9\phi_1 - \phi_2}{3\Delta x} \right) \\ &= -S_1 \Delta x - \frac{3\Gamma_1 - \Gamma_2}{2} \left( \frac{8\phi_L}{3\Delta x} \right) \end{aligned}$$

## 右端

扩散系数变化:

$$\begin{aligned} & \frac{3\Gamma_{N_c} + \Gamma_{N_c-1}}{2} \left( \frac{-9\phi_{N_c} - \phi_{N_c-1}}{3\Delta x} \right) - \frac{\Gamma_{N_c} + \Gamma_{N_c-1}}{2} \left( \frac{\phi_{N_c} - \phi_{N_c-1}}{\Delta x} \right) \\ &= -S_{N_c}\Delta x - \frac{3\Gamma_{N_c} - \Gamma_{N_c-1}}{2} \left( \frac{8\phi_R}{3\Delta x} \right) \end{aligned}$$

## 有限差分

$$\begin{bmatrix}
 1 & 0 & \dots & \dots & \dots & & & & & & \\
 \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} & 0 & \dots & & & & & & \\
 & \ddots & \ddots & \ddots & & & & & & & \\
 \dots & 0 & \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} & 0 & \dots & & & & \\
 & & 0 & \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} & 0 & & & & \\
 & & \dots & 0 & \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} & 0 & \dots & & \\
 & & & & \ddots & \ddots & \ddots & \ddots & & & \\
 0 & & & \dots & 0 & \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} & & & \\
 0 & & & & & \dots & 0 & 1 & & & 
 \end{bmatrix}
 \begin{bmatrix}
 \phi_1 \\
 \phi_2 \\
 \vdots \\
 \phi_{i-1} \\
 \phi_i \\
 \phi_{i+1} \\
 \vdots \\
 \phi_{N-1} \\
 \phi_N
 \end{bmatrix}
 =
 \begin{bmatrix}
 \phi_L \\
 -S_2 \\
 \vdots \\
 -S_{i-1} \\
 -S_i \\
 -S_{i+1} \\
 \vdots \\
 -S_{N-1} \\
 \phi_R
 \end{bmatrix}.$$

(6.25)

# 有限体积

$$\begin{bmatrix}
 \frac{-4}{(\Delta x)^2} & \frac{4}{3(\Delta x)^2} & 0 & \dots & \dots & 0 \\
 \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} & 0 & \dots & 0 \\
 & \ddots & \ddots & \ddots & & \\
 \dots & 0 & \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} & 0 & \dots & 0 \\
 & & 0 & \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} & 0 & \\
 & & \dots & 0 & \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & 0 & \dots \\
 & & & & \ddots & \ddots & \ddots & \\
 0 & & & \dots & 0 & \frac{1}{(\Delta x)^2} & \frac{-2}{(\Delta x)^2} & \frac{1}{(\Delta x)^2} \\
 0 & & & & \dots & 0 & \frac{4}{3(\Delta x)^2} & \frac{-4}{(\Delta x)^2}
 \end{bmatrix}
 \begin{bmatrix}
 \phi_1 \\
 \phi_2 \\
 \vdots \\
 \phi_{i-1} \\
 \phi_i \\
 \phi_{i+1} \\
 \vdots \\
 \phi_{N_C-1} \\
 \phi_{N_C}
 \end{bmatrix}
 =
 \begin{bmatrix}
 -S_1 - \frac{8}{3(\Delta x)^2} \phi_L \\
 -S_2 \\
 \vdots \\
 -S_{i-1} \\
 -S_i \\
 -S_{i+1} \\
 \vdots \\
 -S_{N_C-1} \\
 -S_{N_C} - \frac{8}{3(\Delta x)^2} \phi_R
 \end{bmatrix}.$$

(6.26)

# Neumann Condition

第二类边界条件:

$$\left. \frac{d\phi}{dx} \right|_{x=x_L} = \left. \frac{d\phi}{dx} \right|_{w,l} = J_L$$

则方程变为:

$$\frac{\Gamma_1 + \Gamma_2}{2} \left( \frac{\phi_2 - \phi_1}{\Delta x} \right) - \frac{3\Gamma_1 - \Gamma_2}{2} J_L = -S_1 \Delta x$$

$\Downarrow$

$$\frac{\Gamma_1 + \Gamma_2}{2} \left( \frac{\phi_2 - \phi_1}{\Delta x} \right) = -S_1 \Delta x + \frac{3\Gamma_1 - \Gamma_2}{2} J_L$$

# Neumann Condition

后处理时需要知道边界值：

$$\left. \frac{d\phi}{dx} \right|_w = \left( \frac{9\phi_1 - \phi_2 - 8\phi_L}{3\Delta x} \right) = J_L$$

⇓

$$\phi_L = \frac{9\phi_1 - \phi_2 - 3J_L\Delta x}{8}$$

# Robin Condition

第三类边界条件:

$$\alpha\phi_{w,1} + \beta \frac{d\phi}{dx} \Big|_{w,1} = \gamma$$

泰勒公式展开:

$$\phi_O = \frac{\gamma}{\alpha} - \frac{\beta}{\alpha} \frac{d\phi}{dx} \Big|_w + \frac{\Delta x}{2} \frac{d\phi}{dx} \Big|_w + \frac{1}{2} \left( \frac{\Delta x}{2} \right)^2 \frac{d^2\phi}{dx^2} \Big|_w + \frac{1}{6} \left( \frac{\Delta x}{2} \right)^3 \frac{d^3\phi}{dx^3} \Big|_w + \dots$$

$$\phi_E = \frac{\gamma}{\alpha} - \frac{\beta}{\alpha} \frac{d\phi}{dx} \Big|_w + \frac{3\Delta x}{2} \frac{d\phi}{dx} \Big|_w + \frac{1}{2} \left( \frac{3\Delta x}{2} \right)^2 \frac{d^2\phi}{dx^2} \Big|_w + \frac{1}{6} \left( \frac{3\Delta x}{2} \right)^3 \frac{d^3\phi}{dx^3} \Big|_w + \dots$$

# Robin Condition

推导可得：

$$\left. \frac{d\phi}{dx} \right|_w = \frac{9\phi_O - \phi_E - \frac{8\gamma}{\alpha}}{3\Delta x - \frac{8\beta}{\alpha}} + \frac{\frac{3}{8}\Delta x^3}{3\Delta x - \frac{8\beta}{\alpha}} \left. \frac{d^3\phi}{dx^3} \right|_w$$

边界上：

$$\frac{\Gamma_1 + \Gamma_2}{2} \left( \frac{\phi_2 - \phi_1}{\Delta x} \right) - \frac{3\Gamma_1 - \Gamma_2}{2} \frac{9\phi_1 - \phi_2 - \frac{8\gamma}{\alpha}}{3\Delta x - \frac{8\beta}{\alpha}} = -S_1 \Delta x$$

⇓

$$\begin{aligned} & \frac{\Gamma_1 + \Gamma_2}{2} \left( \frac{\phi_2 - \phi_1}{\Delta x} \right) - \frac{3\Gamma_1 - \Gamma_2}{2} \frac{9\alpha\phi_1 - \alpha\phi_2}{3\alpha\Delta x - 8\beta} \\ &= -S_1 \Delta x - \frac{3\Gamma_1 - \Gamma_2}{2} \frac{8\gamma}{3\alpha\Delta x - 8\beta} \end{aligned}$$



# Robin Condition

后处理:

$$\alpha\phi_L + \beta \frac{9\phi_1 - \phi_2 - 8\phi_L}{3\Delta x} = \gamma$$

推出:

$$\phi_L = \frac{3\Delta x\gamma - 9\beta\phi_1 + \beta\phi_2}{3\alpha\Delta x - 8\beta}$$

*Thanks!*