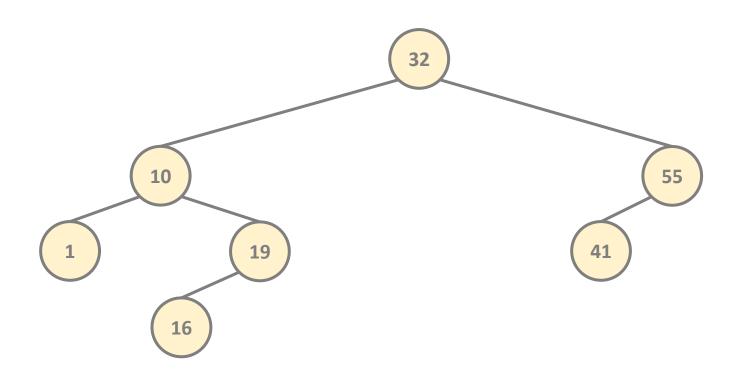
Priority Queues (Algorithms and Data Structures)

- it is an abstract data type such as queue
- every item has an additional property the so-called **priority** value
- in a priority queue an element with **high priority** is served before an element with lower priority
- priority queues are usually implemented with heap data structures but it can be implemented with self balancing trees as well
- it is very similar to queues with some modification: the highest priority element is retrieved first



Sometimes we do not specify the **priority** for example when implementing heap data structures

- → the value of an integer (or float) can be interpreted as a priority
- → so we can omit the priority when inserting new integers or floats

For example: the priority of **10** will be greater than that of **5** because **10>5** so there is no need to store the priority in another variable

The concept of priority queues naturally suggest a **sorting algorithm** where we have to insert all the elements to be sorted into a **priority queue**

- → remove the items one by one from the priority queue and it yields the sorted order
- → if we take out a given item then it will be the one with the highest priority value
- → this is exactly how **heapsort** works

Heap Data Structure (Algorithms and Data Structures)

Heaps

- heaps are basically binary trees
- two main binary heap types: min heap and max heap
- it was first constructed back in 1964 by J. W. J. Williams

1.) MAX HEAP

In a **max heap** the keys of parent nodes are always greater than or equal to those of the children. The highest key (max value) is in the root node.

2.) MIN HEAP

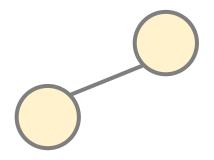
In a **min heap** the keys of parent nodes are less than or equal to those of the children and the lowest key (min item) is in the root node

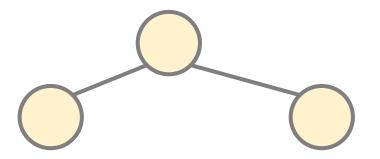
Heaps

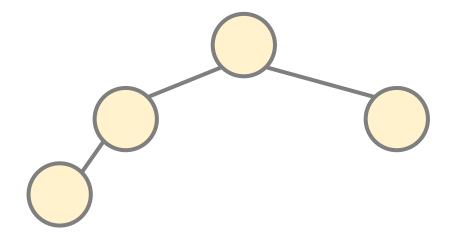
- heaps are basically binary trees
- two main binary heap types: min heap and max heap
- it is **complete** so it cannot be imbalanced
- we insert every new item to the next available place
- APPLICATIONS: Dijkstra's algorithm, Prim's algorithm

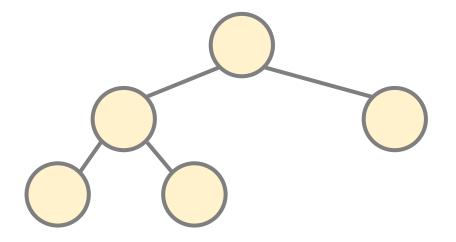
"Bad programmers worry about the code. Good programmers worry about **data structures** and their relationships"

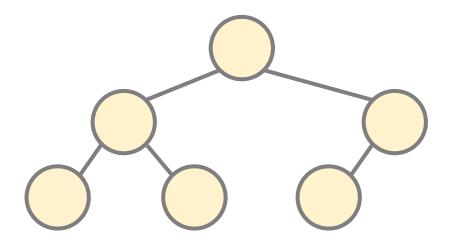


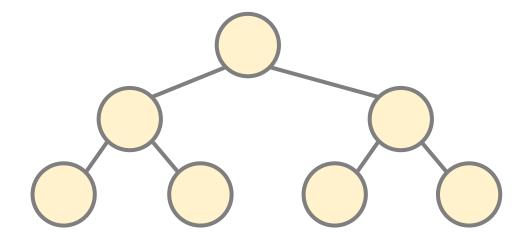




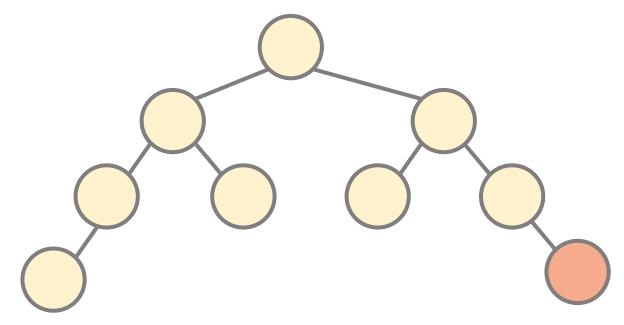








1.) COMPLETENESS: we construct the **heap** from left to right across each row – of course the last row may not be fully complete



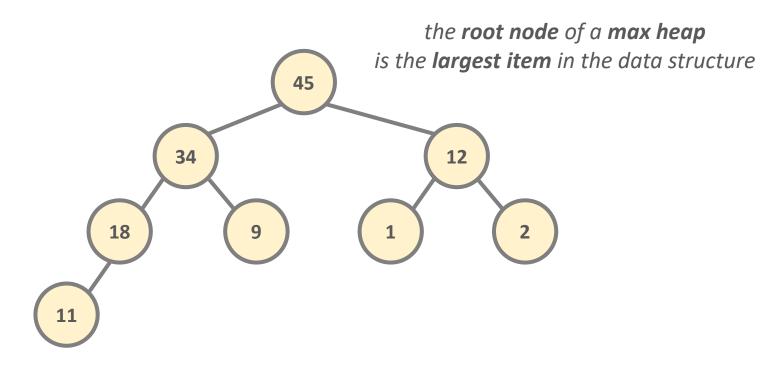
it is not a valid heap because he **completeness property** is violated

2.) HEAP PROPERTY: every node can have 2 children so heaps are almost-complete binary trees.

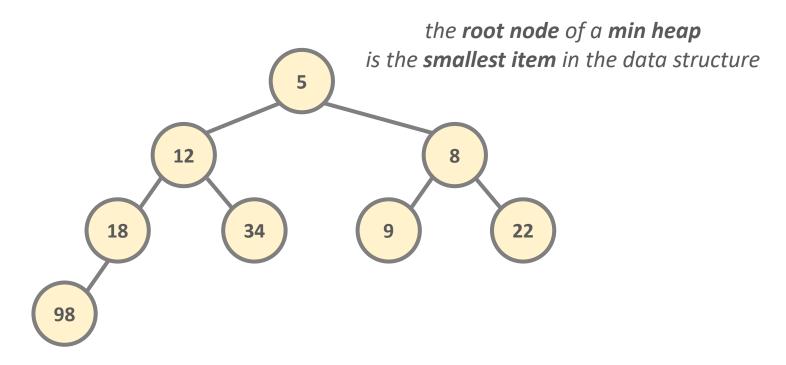
→ min heap: the parent node is always smaller than the child nodes (left and right nodes)

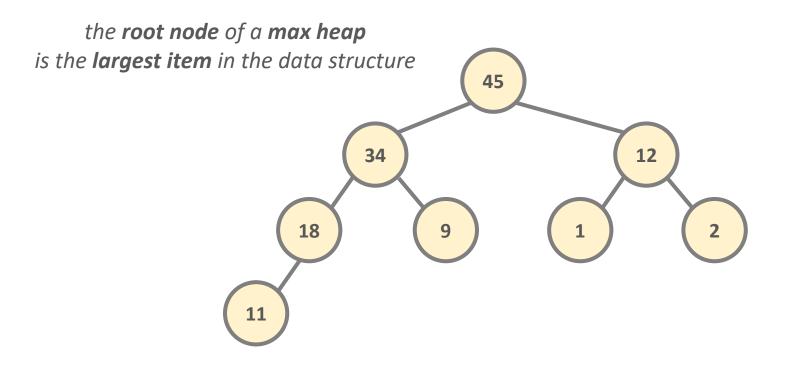
→ max heap: the parent node is always greater than the child nodes (left and right nodes)

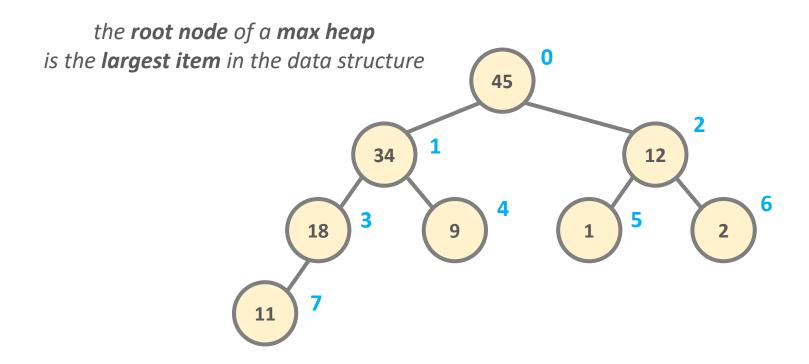
2.) HEAP PROPERTY: every node can have 2 children so heaps are almost-complete binary trees.

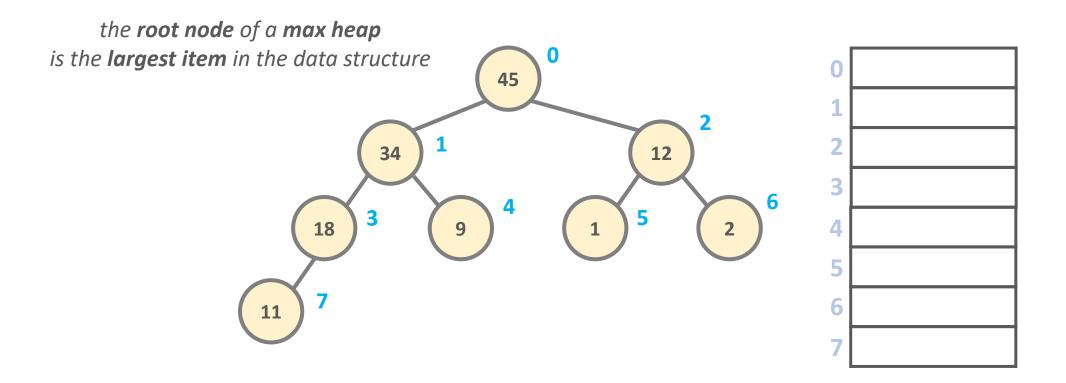


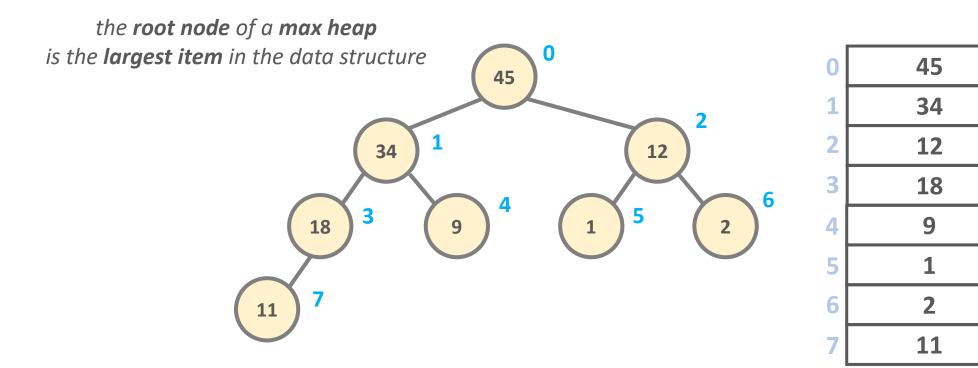
2.) HEAP PROPERTY: every node can have 2 children so heaps are almost-complete binary trees.

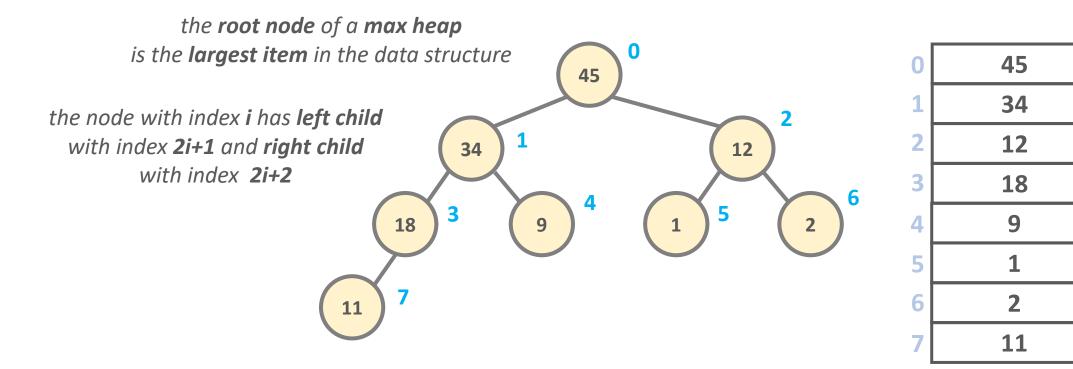




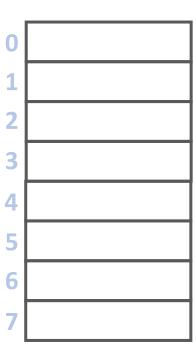








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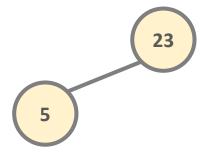


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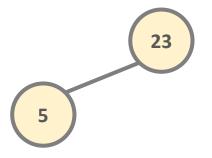


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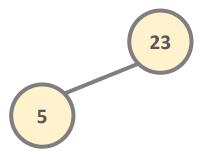


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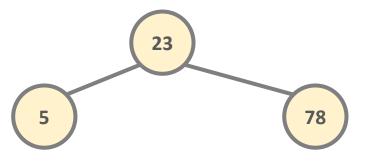
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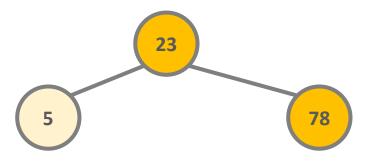


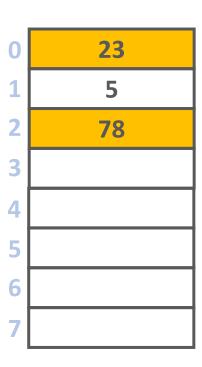
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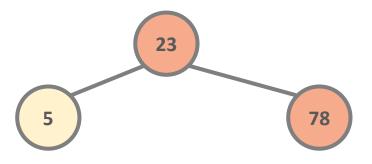
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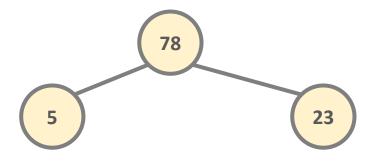
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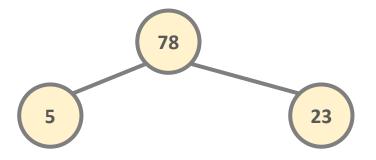


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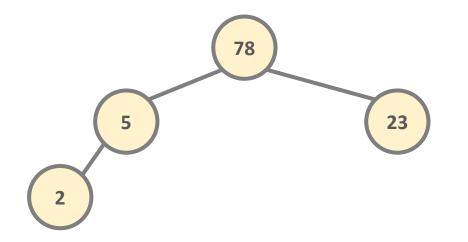
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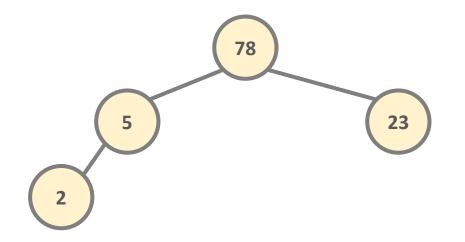


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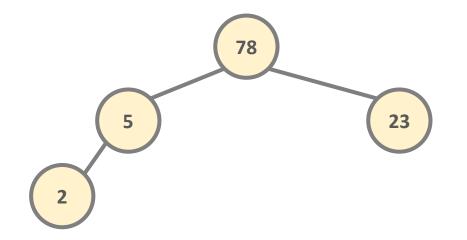


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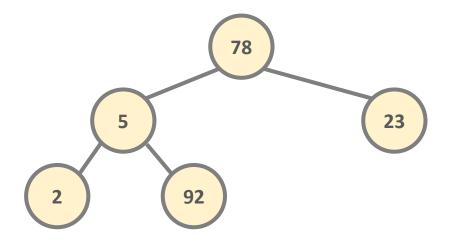
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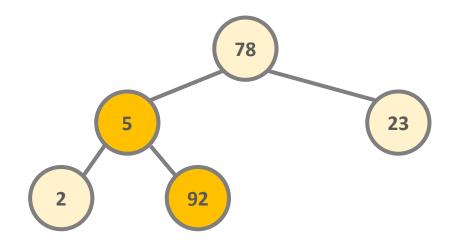


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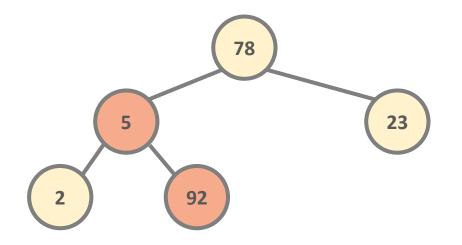
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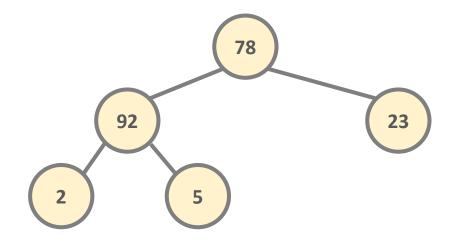


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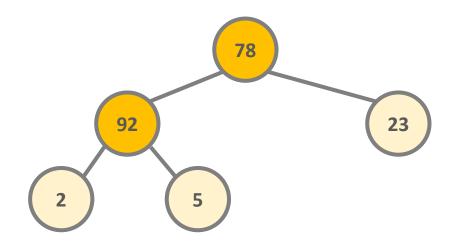


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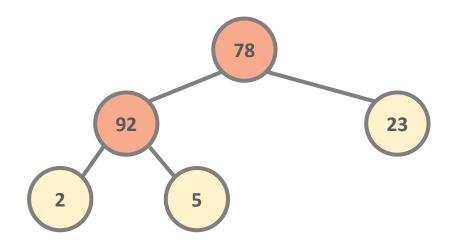




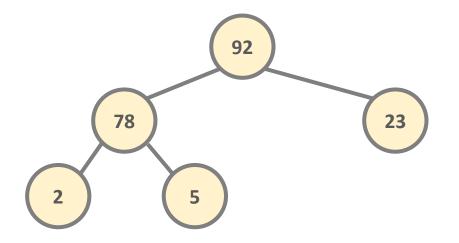
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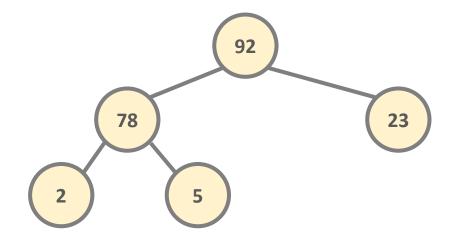
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0	78
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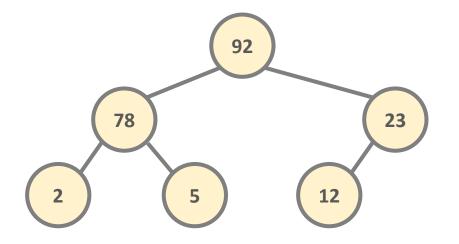


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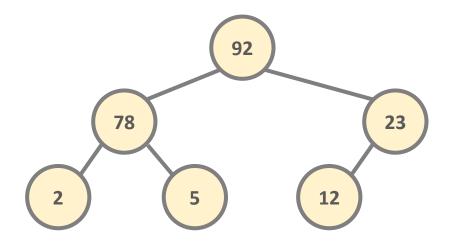


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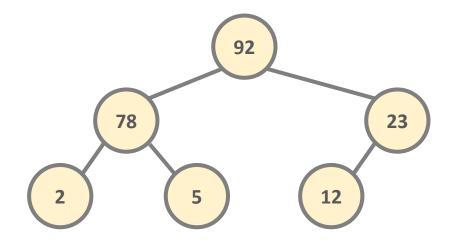


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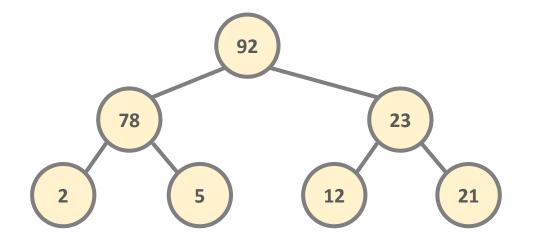
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INSERT(21)

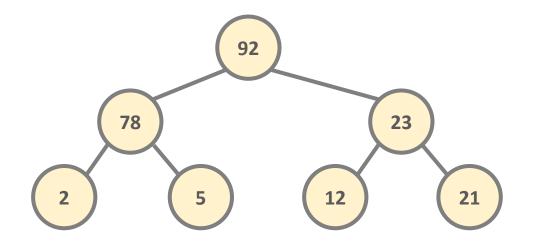


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INSERT(21)

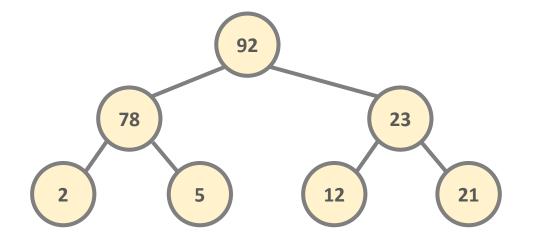


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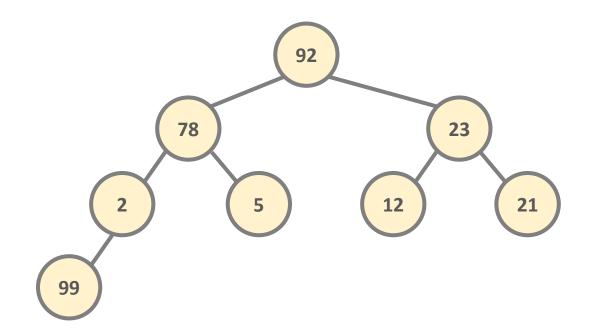
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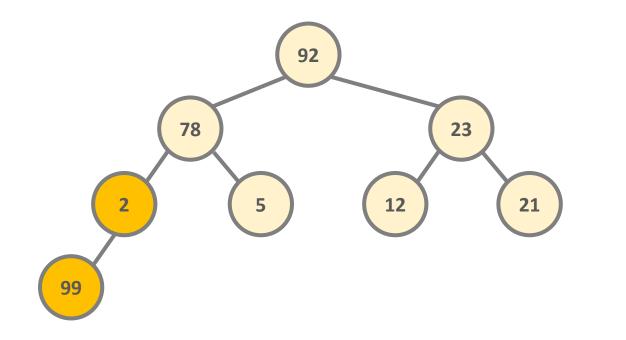


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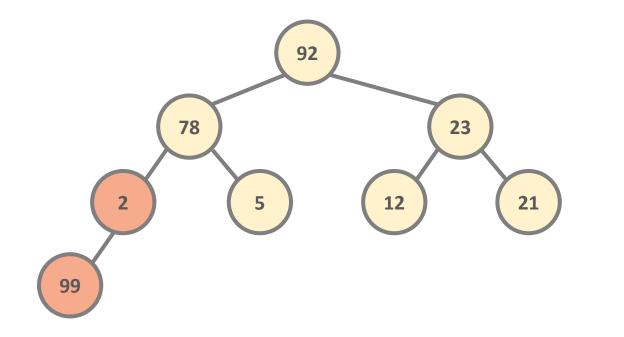
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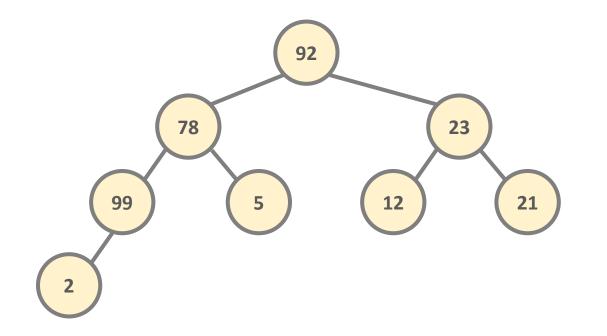
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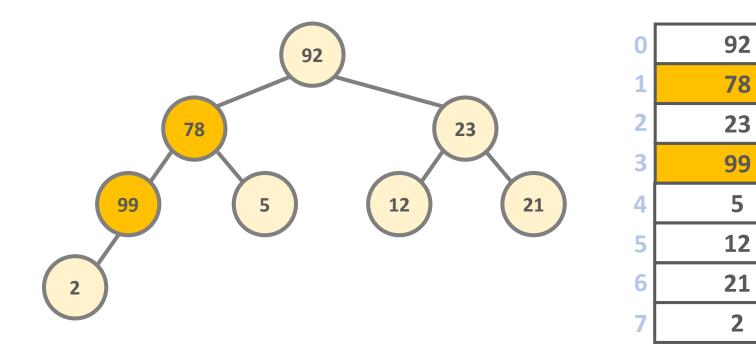
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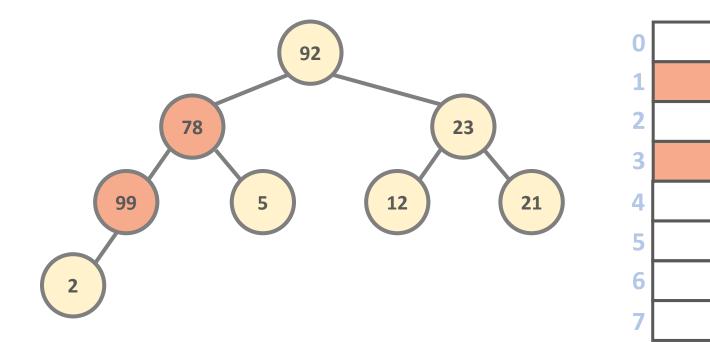


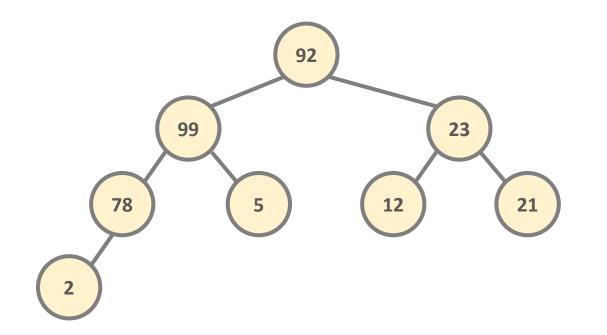
0	92
1	78
2	23
3	2
4	5
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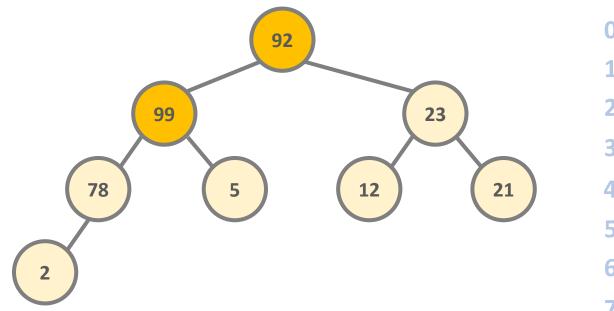
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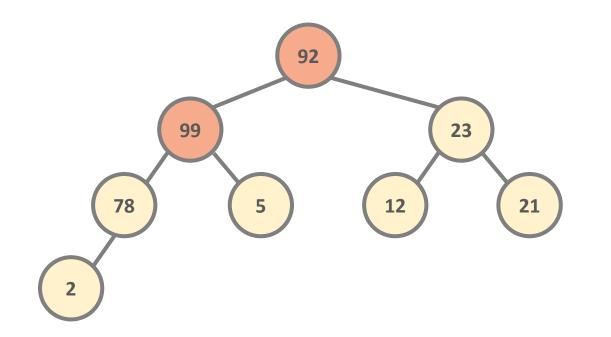




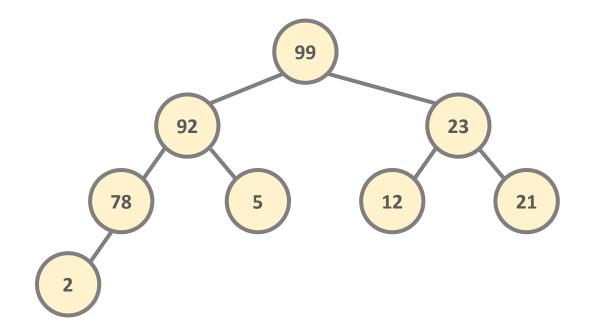
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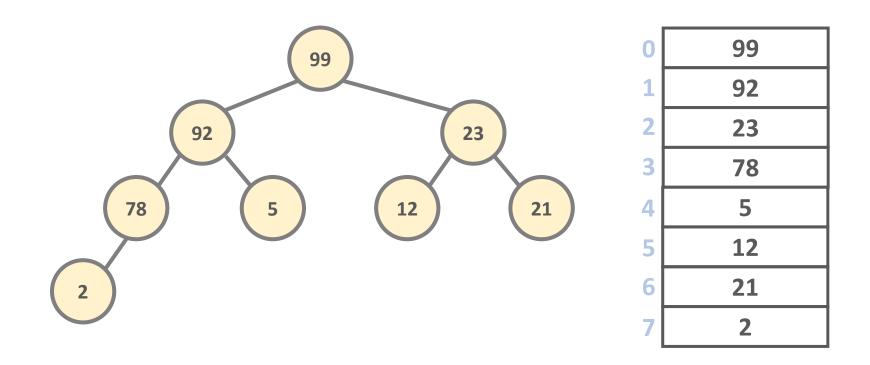
0	92
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7	2



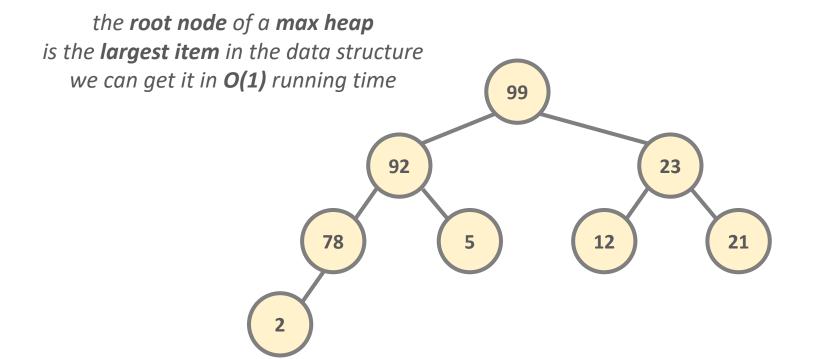
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7	2



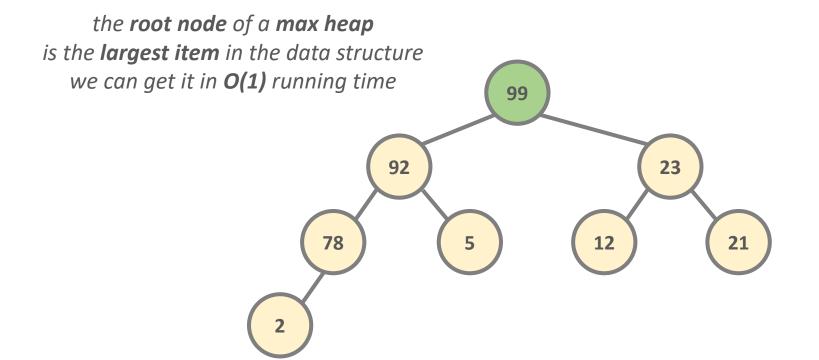
0	99
1	92
2	23
3	78
4	5
5	12
6	21
7	2



WE CAN GET THE MAX (MIN) ITEM IN O(1) RUNNING TIME
- of course after that we have to rearrange the tree -

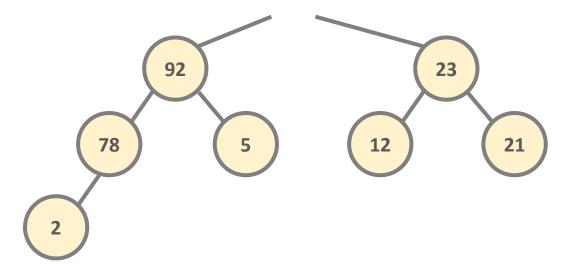


0	99
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7	2



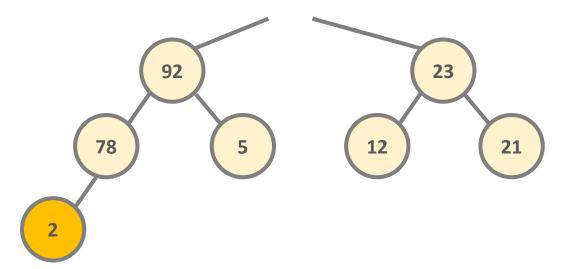
0	99
1	92
2	23
3	78
4	5
5	12
6	21
7	2

the **root node** of a **max heap**is the **largest item** in the data structure
we can get it in **O(1)** running time



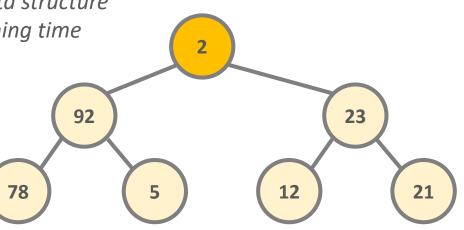
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1	92
2	23
3	78
4	5
5	12
6	21
7	2

the **root node** of a **max heap**is the **largest item** in the data structure
we can get it in **O(1)** running time



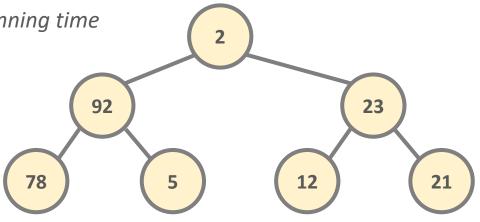
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1	92
2	23
3	78
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5	12
6	21
7	2

the **root node** of a **max heap**is the **largest item** in the data structure
we can get it in **O(1)** running time



0	2
1	92
2	23
3	78
4	5
5	12
6	21
7	2

the **root node** of a **max heap** is the **largest item** in the data structure we can get it in **O(1)** running time

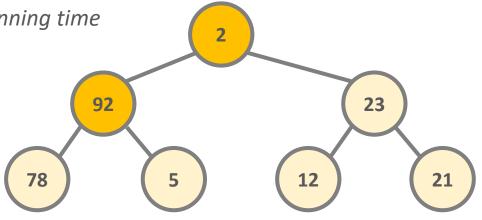


we have to check starting with the root node to the leaf nodes whether to swap the items in order to verify the **heap properties**

0	2
1	92
2	23
3	78
4	5
5	12
6	21
7	

HEAPIFY OPERATION

the **root node** of a **max heap** is the **largest item** in the data structure we can get it in **O(1)** running time

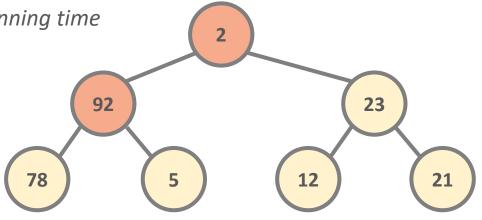


we have to check starting with the root node to the leaf nodes whether to swap the items in order to verify the **heap properties**

0	2
1	92
2	23
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HEAPIFY OPERATION

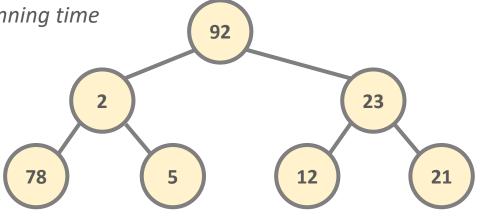
the **root node** of a **max heap** is the **largest item** in the data structure we can get it in **O(1)** running time



we have to check starting with the root node to the leaf nodes whether to swap the items in order to verify the **heap properties**

0	2
1	92
2	23
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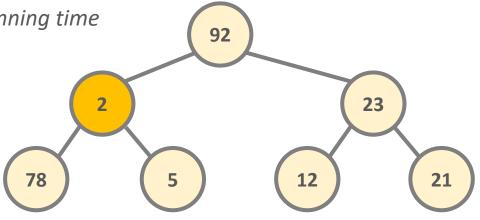
the **root node** of a **max heap**is the **largest item** in the data structure
we can get it in **O(1)** running time



we have to check starting with the root node to the leaf nodes whether to swap the items in order to verify the **heap properties**

0	92
1	2
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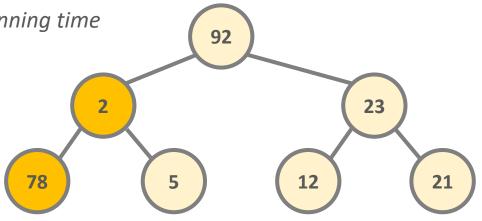
the **root node** of a **max heap** is the **largest item** in the data structure we can get it in **O(1)** running time



we have to check starting with the root node to the leaf nodes whether to swap the items in order to verify the **heap properties**

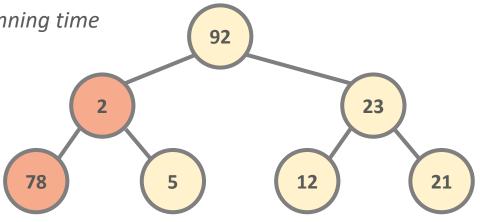
0	92
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the **root node** of a **max heap** is the **largest item** in the data structure we can get it in **O(1)** running time



we have to check starting with the root node to the leaf nodes whether to swap the items in order to verify the **heap properties**

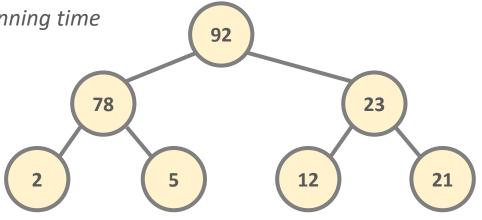
the **root node** of a **max heap** is the **largest item** in the data structure we can get it in **O(1)** running time



we have to check starting with the root node to the leaf nodes whether to swap the items in order to verify the **heap properties**

0	92
1	2
2	23
3	78
4	5
5	12
6	21
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the **root node** of a **max heap** is the **largest item** in the data structure we can get it in **O(1)** running time



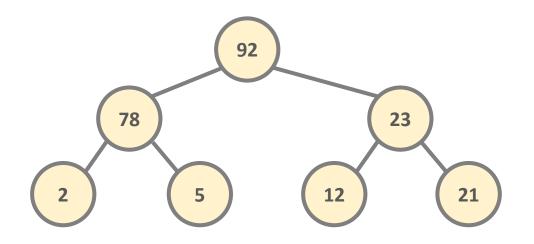
we have to check starting with the root node to the leaf nodes whether to swap the items in order to verify the **heap properties**

0	92
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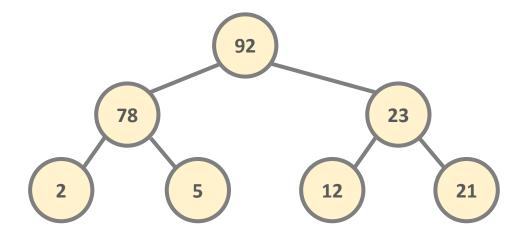
HEAPIFY OPERATION in O(logN)

Heap Data Structure (Algorithms and Data Structures)

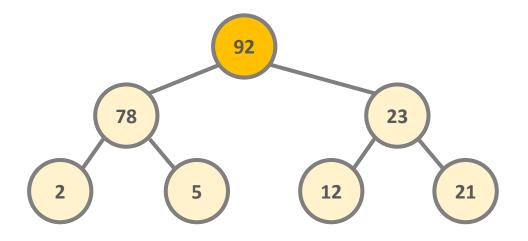
- removing the root node (and usually this is the case) can be done in O(logN) running time
- what if we want to remove an arbitrary item?
- first we have to find it in the array with O(N) linear search and then we can remove it in O(logN)
- REMOVING AN ARBITRARY ITEM TAKES O(N) TIME
- this is the same if we want to **find an item** in a heap
- heaps came to be to find and manipulate the root node (max or min item) in an efficient manner



0	92
1	78
2	23
3	2
4	5
5	12
6	21
7	

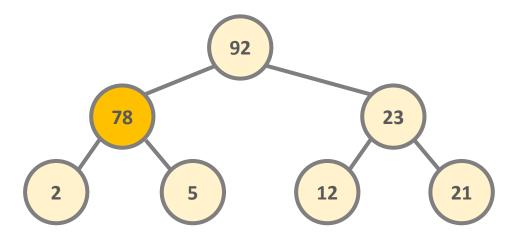


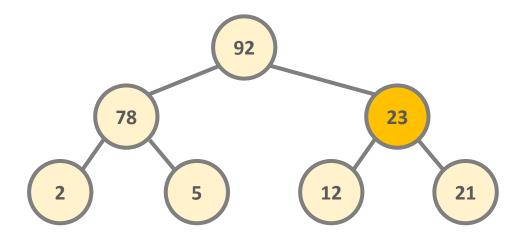
0	92
1	78
2	23
3	2
4	5
5	12
6	21
7	



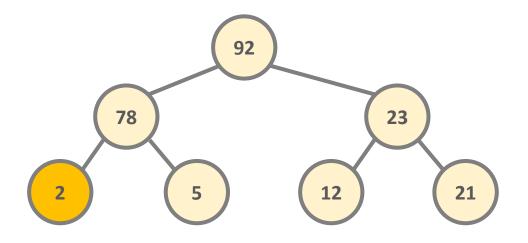
)	92
L	78
2	23
3	2
1	5
5	12
5	21
7	

REMOVE(12)

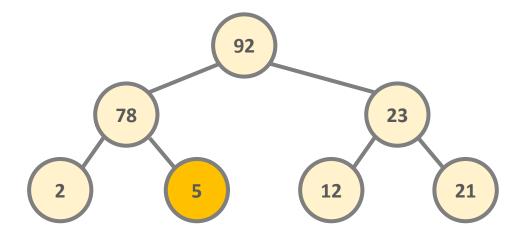




0	92
1	78
2	23
3	2
4	5
5	12
6	21
7	

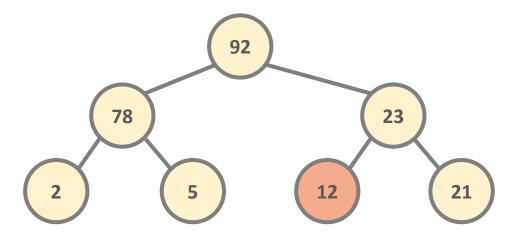


0	92
1	78
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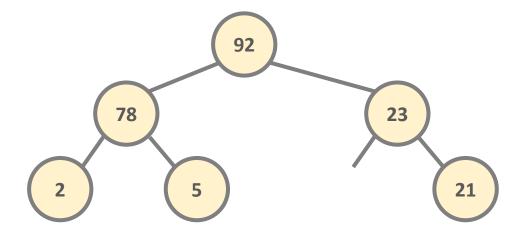


0	92
1	78
2	23
3	2
4	5
5	12
6	21
7	

REMOVE(12)



REMOVE(12)

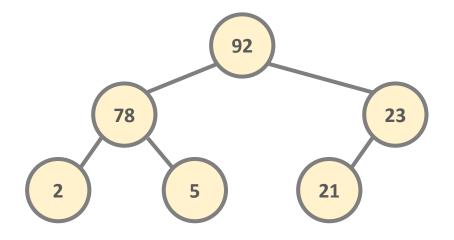


there can not be a "hole" in the data structure and in these cases we use the last item in the heap

0	92
1	78
2	23
3	2
4	5
5	
6	21
7	

<u>Heaps</u>

REMOVE(12)

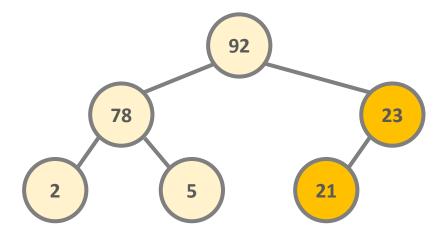


we have to check **recursively** up to the root node whether the **heap peoperties** are violated or not

0	92
1	78
2	23
3	2
4	5
5	21
6	
7	

<u>Heaps</u>

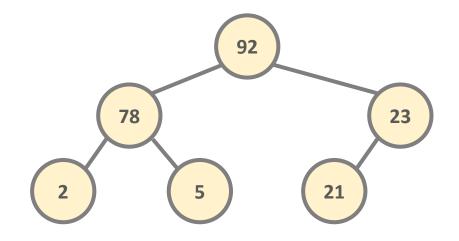
REMOVE(12)



we have to check **recursively** up to the root node whether the **heap peoperties** are violated or not

0	92
1	78
2	23
3	2
4	5
5	21
6	
7	

REMOVE(12)



REMOVING AN ITEM: $O(N) + O(\log N) = O(N)$

0	92
1	78
2	23
3	2
4	5
5	21
6	
7	

(Algorithms and Data Structures)

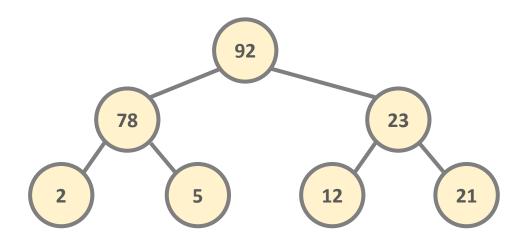
- it was constructed back in 1964 by J. W. J. Williams
- heapsort is a comparison-based sorting algorithm
- uses heap data structure rather than a linear-time search to find the maximum
- it is a bit **slower in practice** on most machines than a well-implemented quicksort
- but it has the advantage of a more favorable **O(NlogN)** worst-case running time complexity

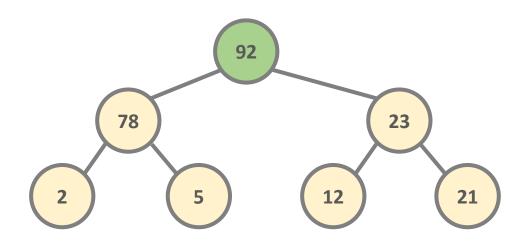
- heapsort is an in-place algorithm
- **DOES NOT NEED ADDITIONAL MEMORY** of course we have to store the **N** items
- but it is **not** a **stable sort** which means it does not keep the relative order of items with same values
- first we have to construct the heap data structure from the numbers we want to sort
- we have to consider the items one by one in O(N) and we have to insert them into the heap in O(logN) so the total runing time will be O(NlogN)

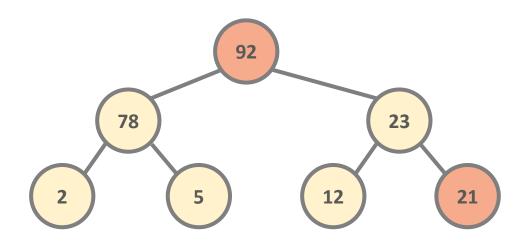
1.) we take the **root node** (include it in the solution set) and swap it with the last item

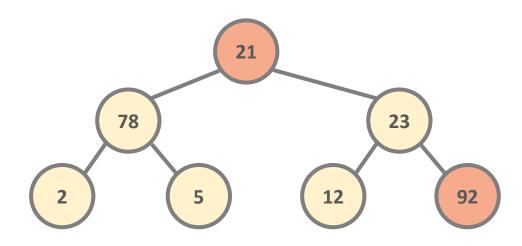
2.) do heapify starting with the root node because the heap properties may be violated

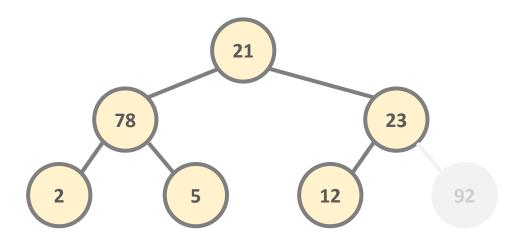
3.) we do it N times (for all the items in the data structue)

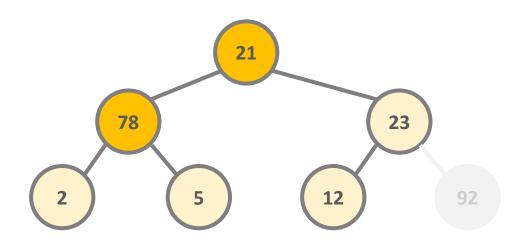


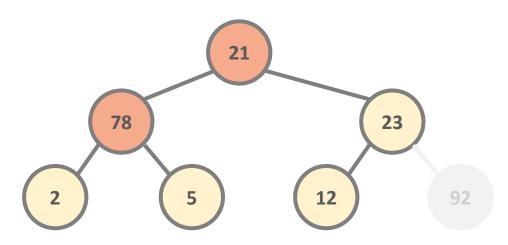


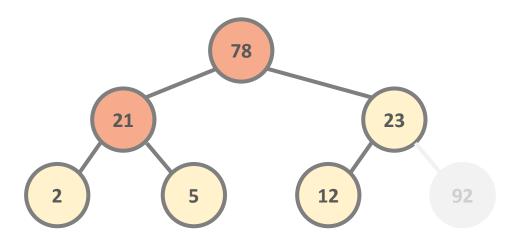


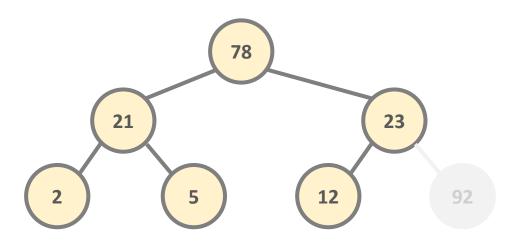


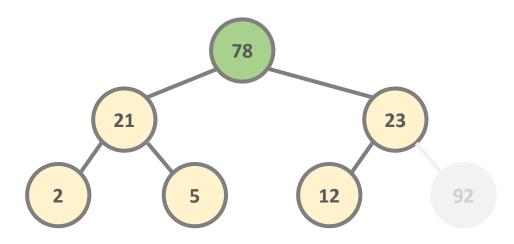


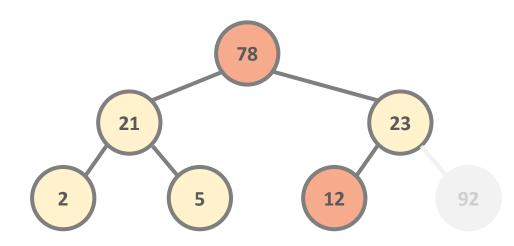


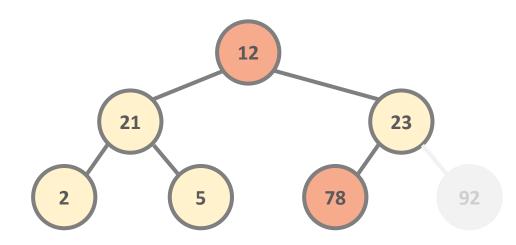


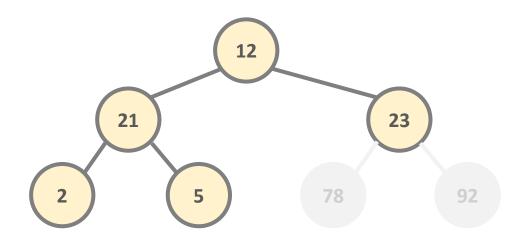


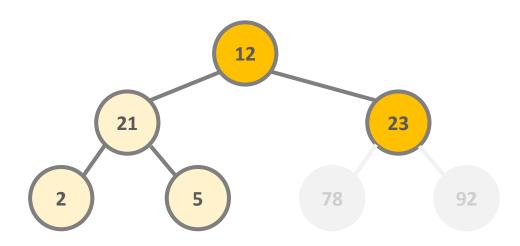


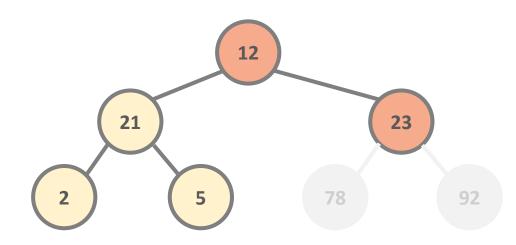


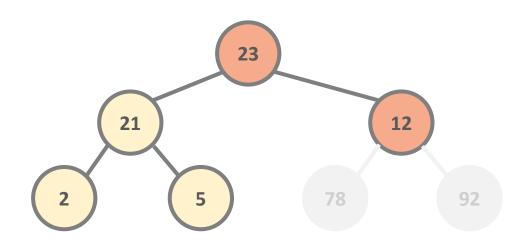


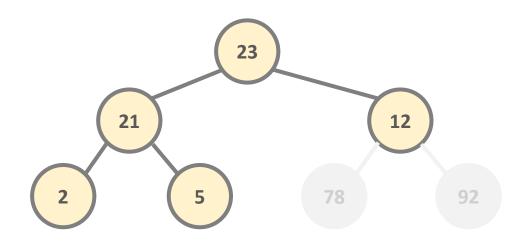


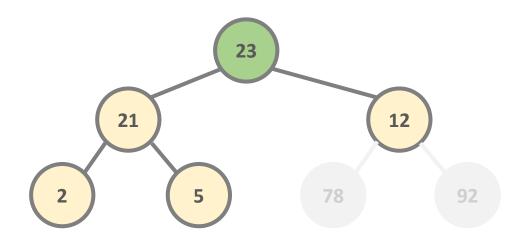


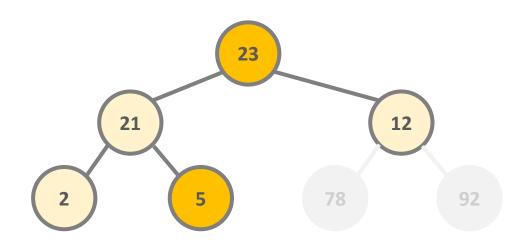


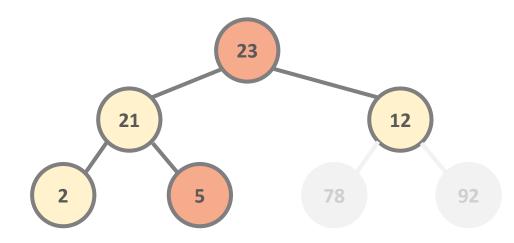


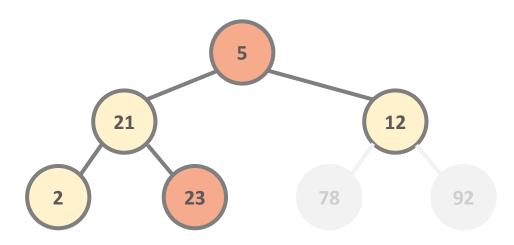


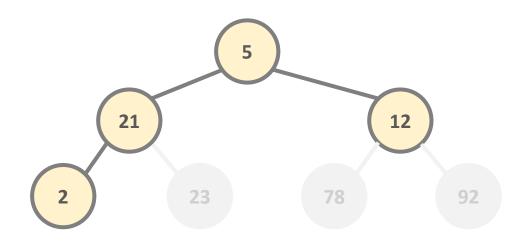


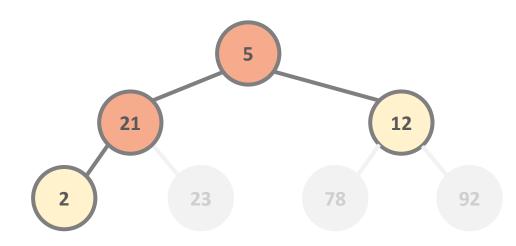


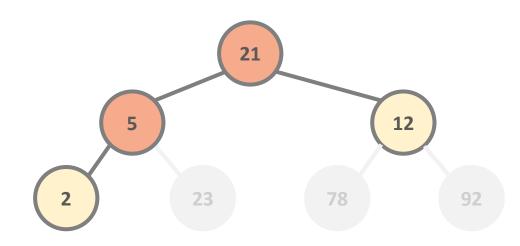


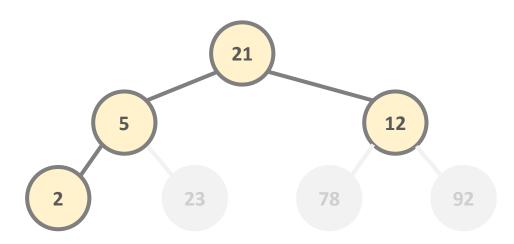


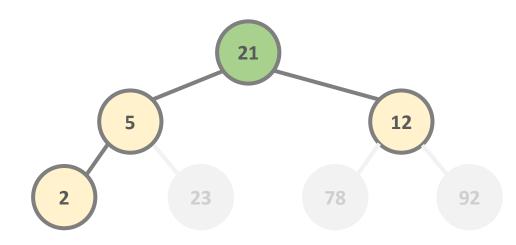


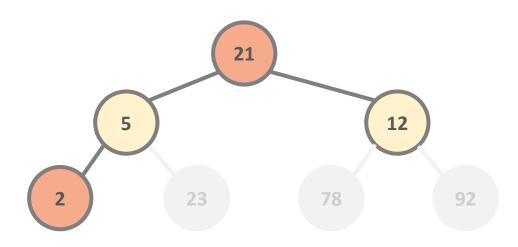


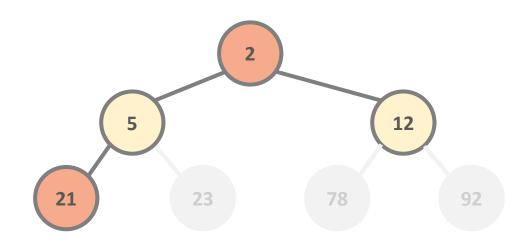


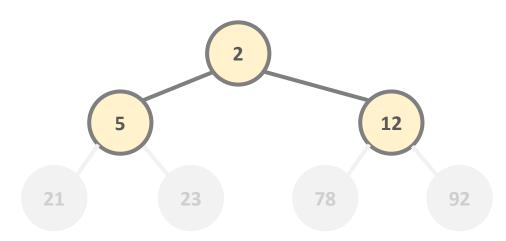


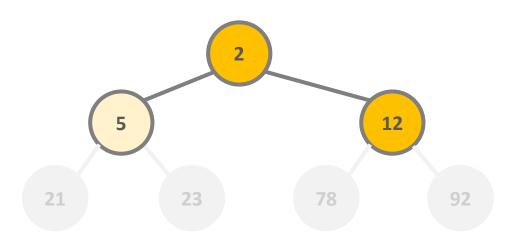


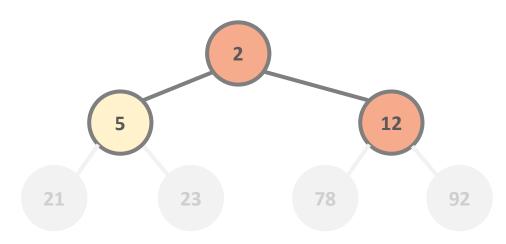


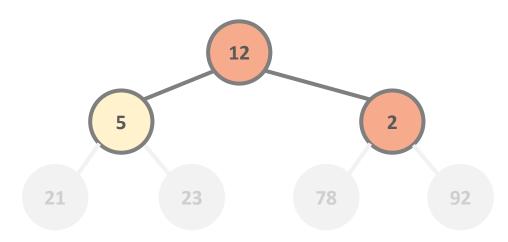


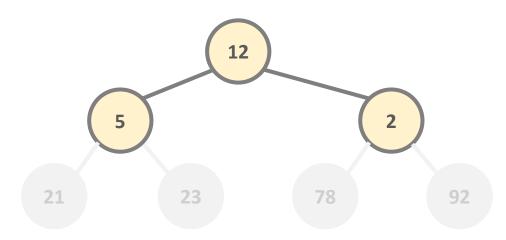


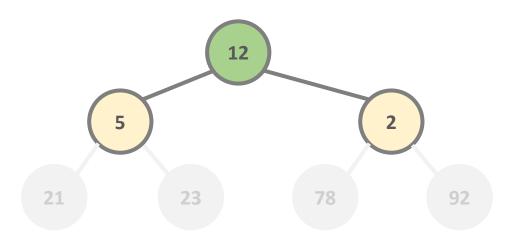


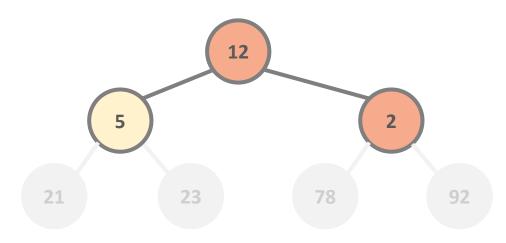


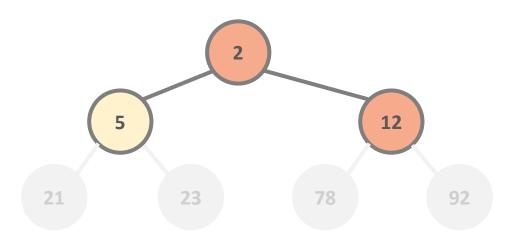


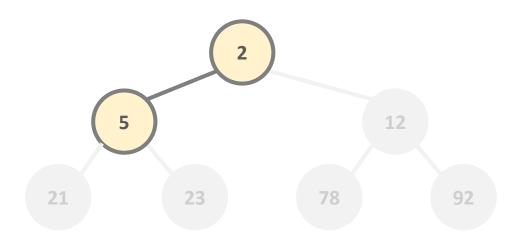


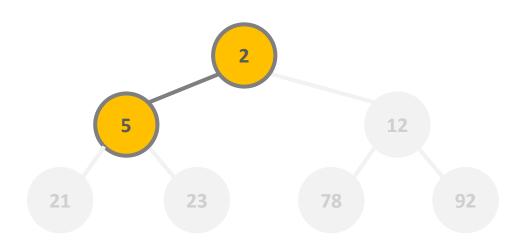


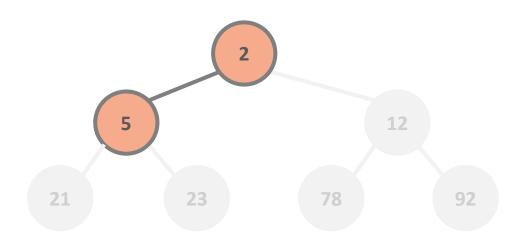


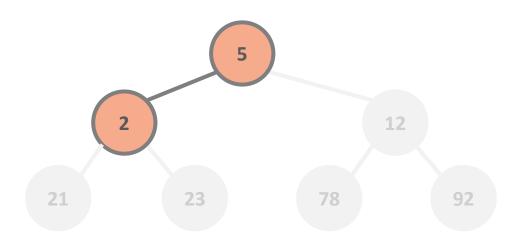


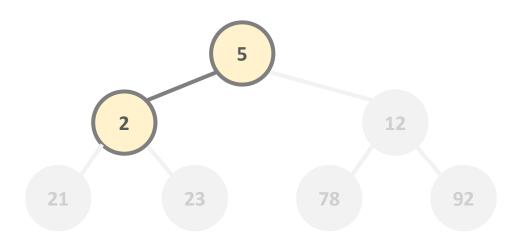


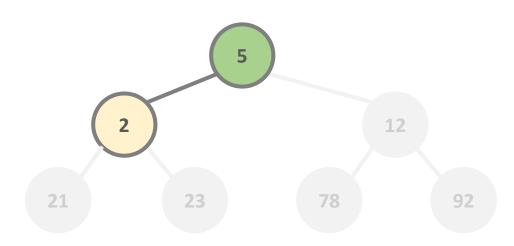


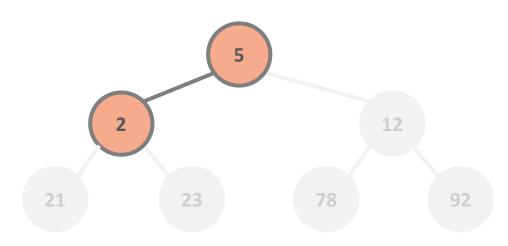


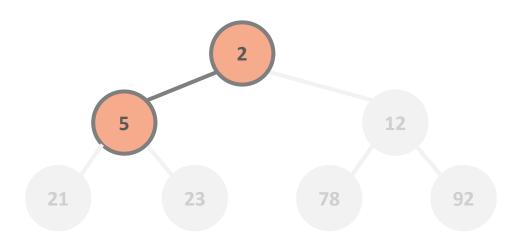


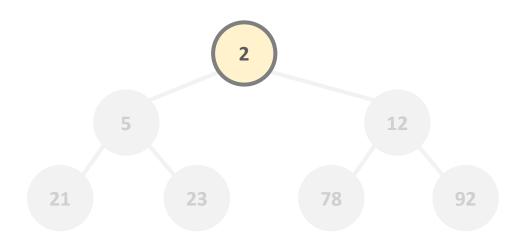


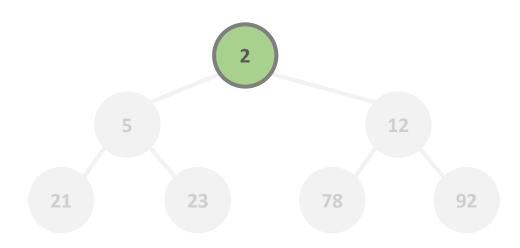


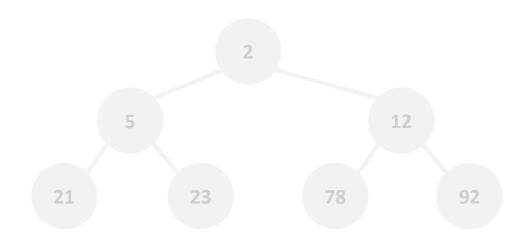












Advanced Heaps (Algorithms and Data Structures)

Binomial Heaps

- similar to a binary heap but also supports quick merging of two heaps
- it is important as an implementation of the **mergeable heap** abstract data type (*meldable heap*)
- which is a **priority queue** basically + supporting merge operation
- a binomial heap is implemented as a collection of trees
- the O(logN) logarithmic insertion time complexity can be reduced to O(1) constant time complexity with the help of binomial heaps

Fibonacci Heaps

- Fibonacci heaps are faster than the classic binary heap
- Dijkstra's shortest path algorithm and **Prim's spanning tree algorithm** run faster if they rely on Fibonacci heap instead of binary heaps
- but very hard to implement efficiently so usually does not worth the effort
- unlike binary heaps it can have several children the number of children are usually kept low
- we can achieve O(1) running time for insertion operation instead of O(logN) logarithmic running time
- every node has degree at most O(logN) and the size of a subtree rooted in a node of degree k is at least F_{k+2} where F_k is the k-th Fibonacci number

Heaps Running Time

BINARY	BINOMIAL	FIBONACCI
O(1)	O(1)	O(1)
O(logN)	O(logN)	O(logN)
O(logN)	O(1)	0(1)
O(logN)	O(logN)	O(1)
-	O(logN)	0(1)
	O(1) O(logN) O(logN) O(logN)	O(1) O(1) O(logN) O(logN) O(logN) O(1) O(logN) O(logN)

Fibonacci-heaps are hard to implement but they are **extremely powerful**