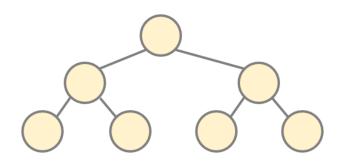
External Memory (Algorithms and Data Structures)



fine and they can be stored in the

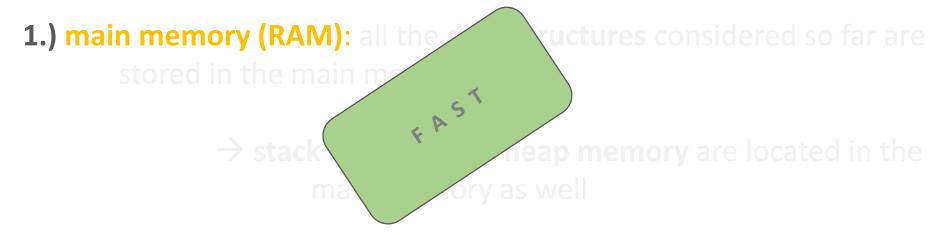
main memory (RAM)

WHAT IF WE WANT TO STORE > 1GB HUGE DATA?

There are **2** types of memory:

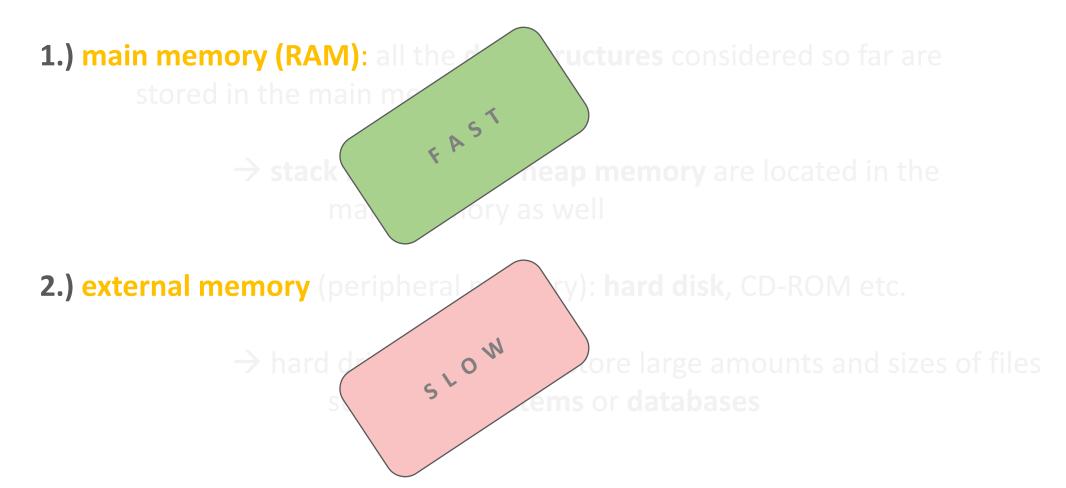
- 1.) main memory (RAM): all the data structures considered so far are stored in the main memory
 - → stack memory and heap memory are located in the main memory as well
- 2.) external memory (peripheral memory): hard disk, CD-ROM etc.
 - → hard drive storage can store large amounts and sizes of files such as **file systems** or **databases**

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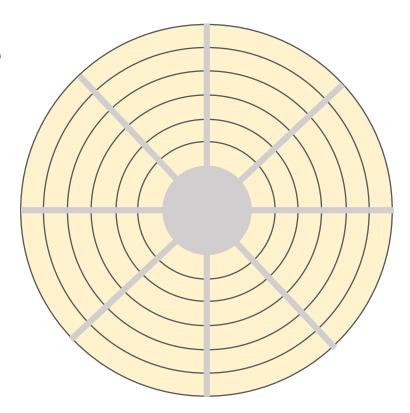
There are **2** types of memory:



EXTERNAL MEMORY

hard drive disk (HDD) is one or more rigid rapidly rotating platters coated with magnetic material

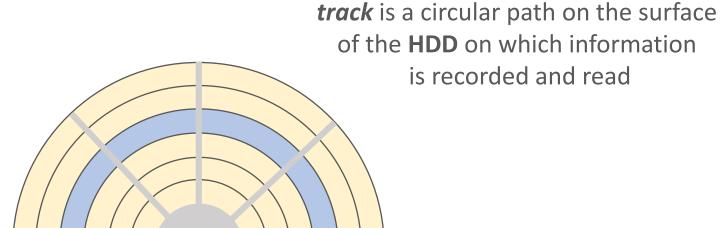
CAN RETAIN DATA EVEN
WHEN POWERED OFF !!!



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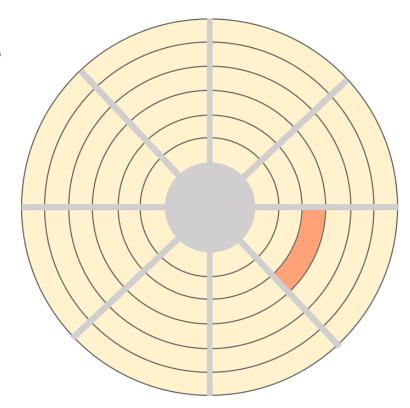
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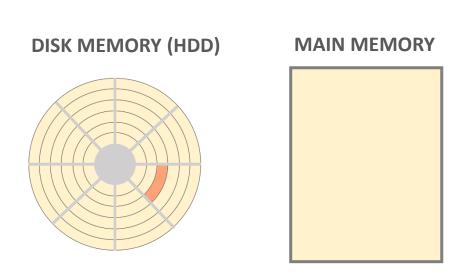
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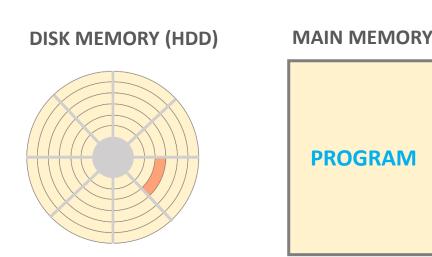
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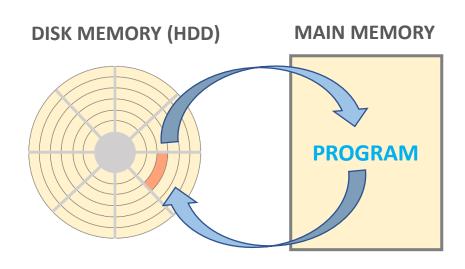
a block is a subdivision of the hard drive disk (HDD) storing512 bytes



- the data located on the hard drive disk (HDD) can not be processed explicitly
- it must be brought into the main memory
- in the main memory (RAM) we can use either the stack memory or the heap memory
- we can manipulate (read or write) the blocks which means at least **512 bytes**
- ACCESSING THE BLOCKS IS SLOW !!!

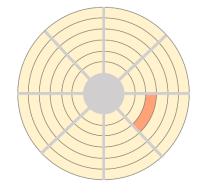


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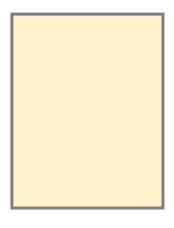
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DISK MEMORY (HDD)



organizing the data efficiently
stored on the hard drive disk (HDD)
has something to do with database
management systems (DBMS)

MAIN MEMORY



storing the data efficiently on the main memory (RAM) has something to do with data structures

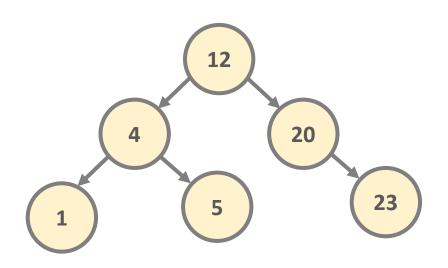
External Memory Access Time (Algorithms and Data Structures)

- accessig items on the external memory (HDD) is way slower than manipulating the mian memory
- we need totally different data structures

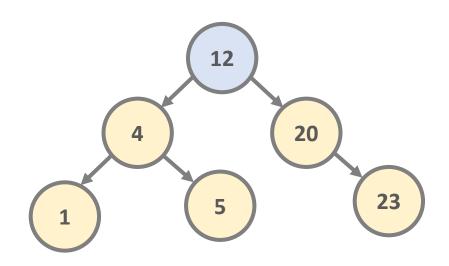
EXTERNAL MEMORY ACCES TIME: 12 ms

RAM ACCESS TIME: 0.0001 ms

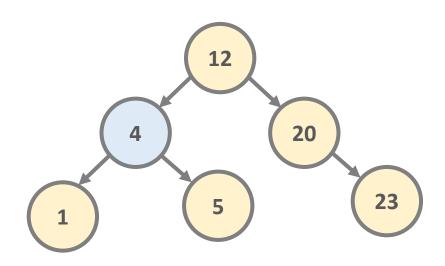
• so far we have manipulated data present on the main memory but now we have to fetch the data from the external memory first



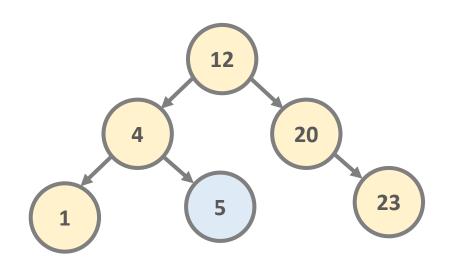
- recursive approaches are working quite fine when using the main memory (RAM)
- doing the same on the external memory (HDD) is slow because of the access time
- we can manipulate (read or write) the blocks which means at least 512 bytes
- ACCESSING THE BLOCKS IS SLOW !!!
- conclusion: we should minimize the amount of read operations
- this is why B-trees are shallow structures



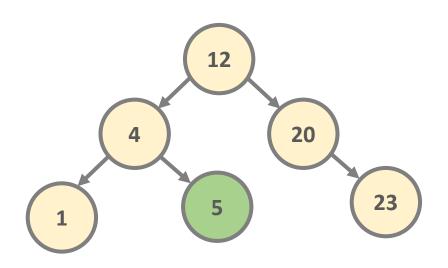
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B-Trees (Algorithms and Data Structures)

- it was first constructed in 1971 by Rudolf Bayer and Ed McCreight
- B-trees are self balancing tree like data structures
- supports operations such as insertion, deletion, sequential access and searching in O(logN) time complexity
- the nodes may have more than 2 children + multipley keys
- B-tree data sturctures are optimized for systems that read and write large blocks of data
- B-trees are a good example of a data structure for external memory
- commonly used in databases and filesystems

Every node may have multiple children (more than 2) but the running time is still O(logN) logartithmic

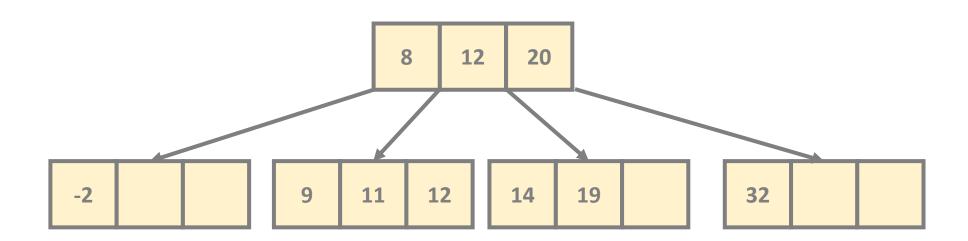
$$\log_b N = \frac{\log_a N}{\log_a b}$$

$$\log_a b \text{ is just a constant so does not matter}$$

> we can change the base of the logarithm and the running time complexity for the algorithm stay the same

$$O(c * log N) = c * O(log N) = O(log N)$$

thats why the **branching factor** does not matter in the running time complexities



B-TREE PROPERTIES

- 1.) all the nodes of the tree structure can contain m keys so it may have m+1 children (branching factor)
- 2.) every node is at least half full so contain at least $\frac{m}{2}$ items
- 3.) if the N number of items in a node is less than $\frac{m}{2}$ then we merge it with another node and if N>m then we split the node
- 4.) all leaf nodes are at the same level (balanced)

B-Trees Insertion (Algorithms and Data Structures)

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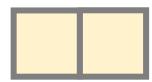
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ı

INSERT(2)

INSERT(3)

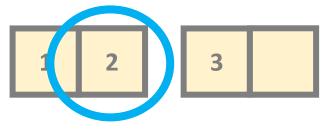
INSERT(3)



INSERT(3)

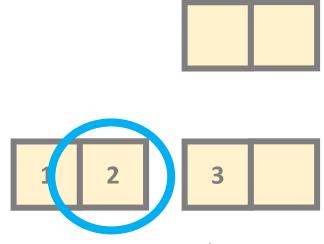
1 2

INSERT(3)



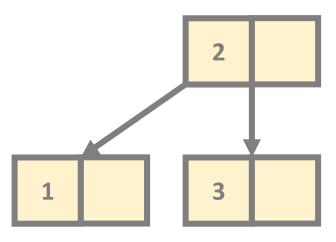
we always promote the **middle value** in these cases

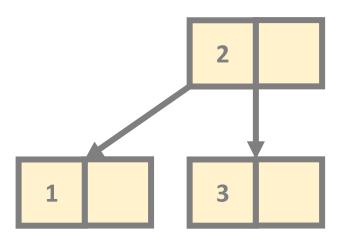
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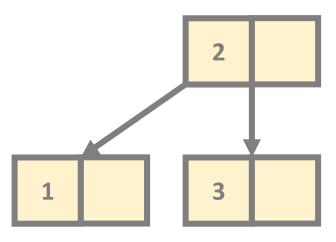


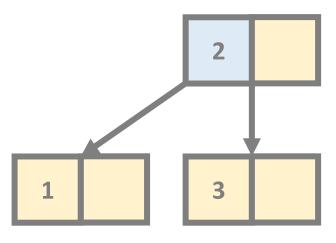
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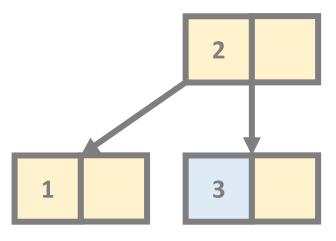
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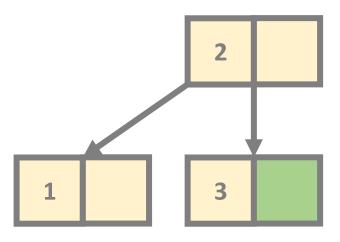


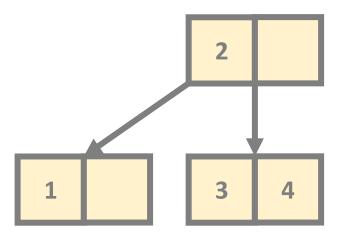


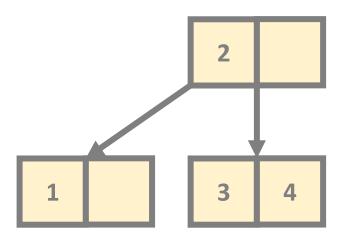


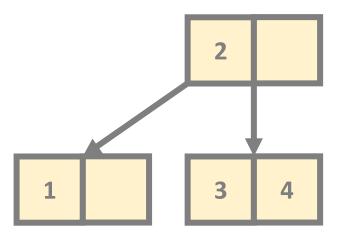


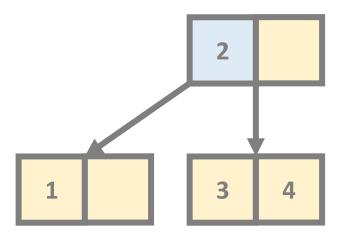


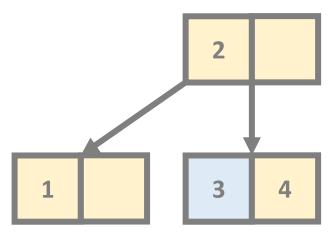


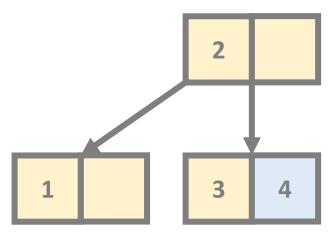


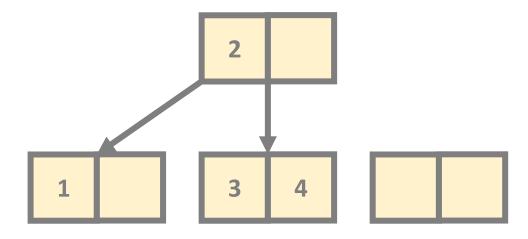


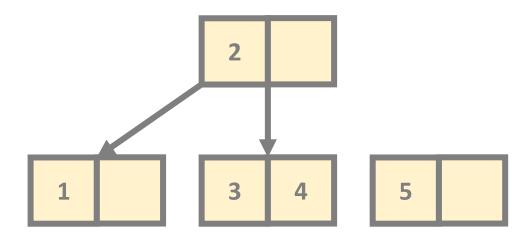




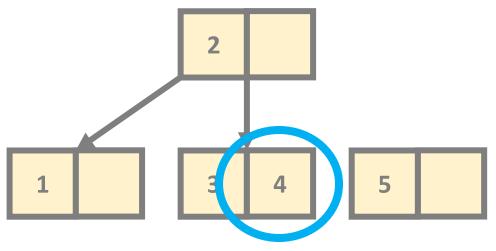




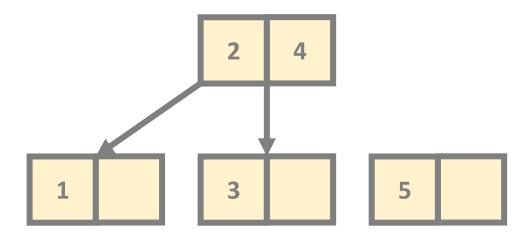


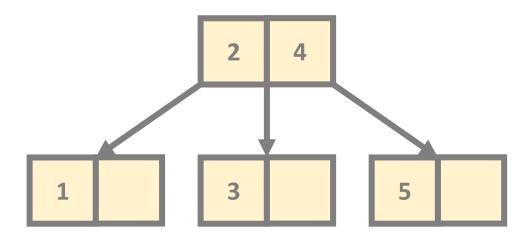


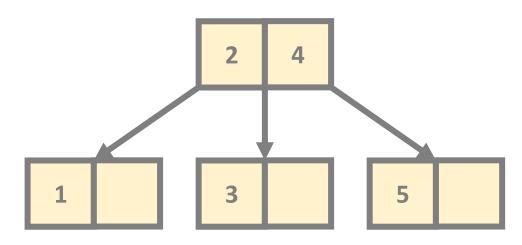
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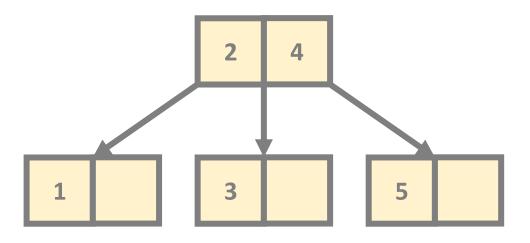


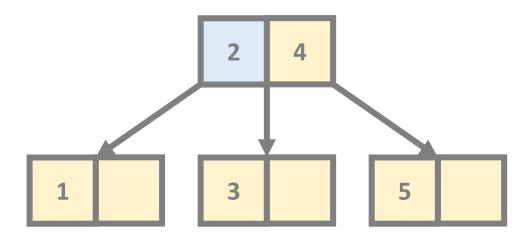
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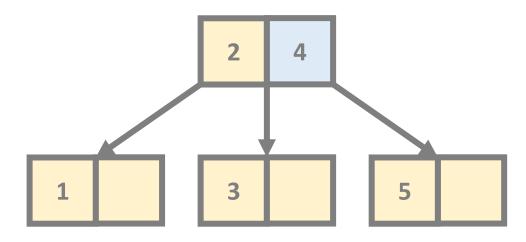


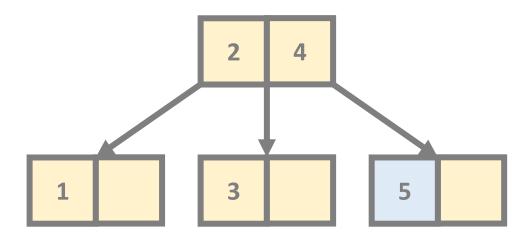


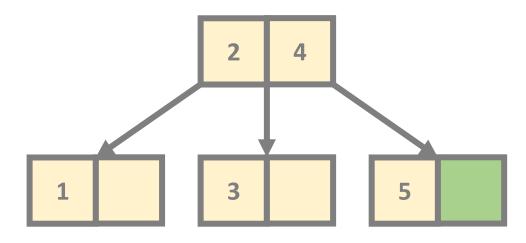


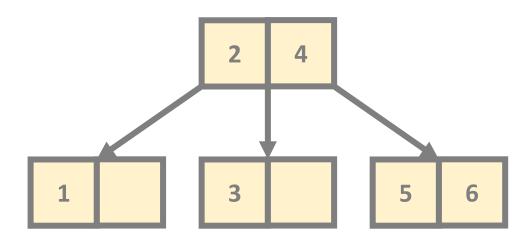


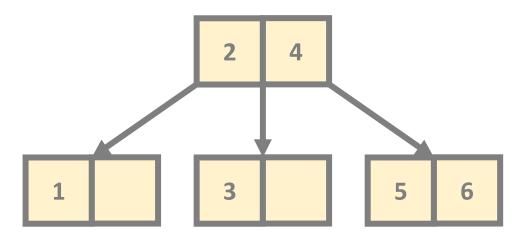


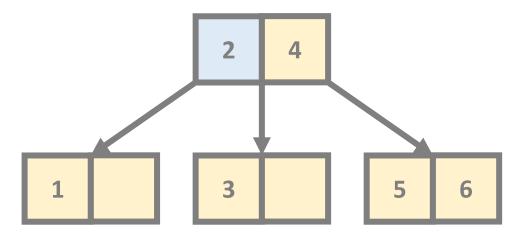


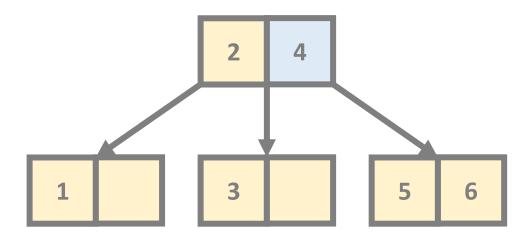


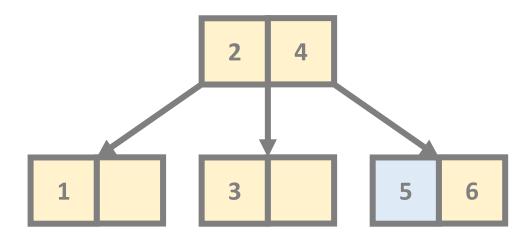


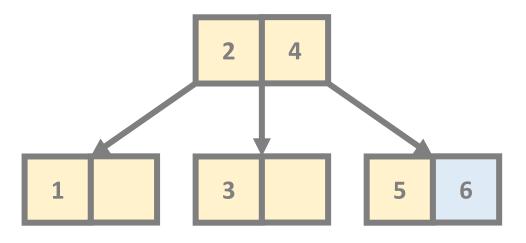


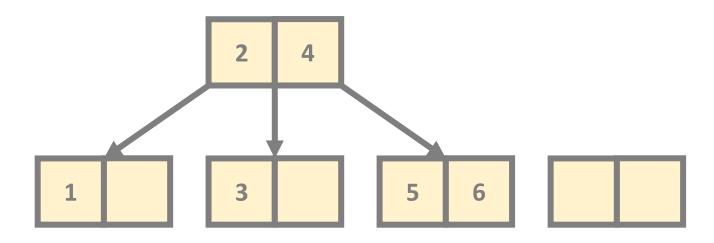




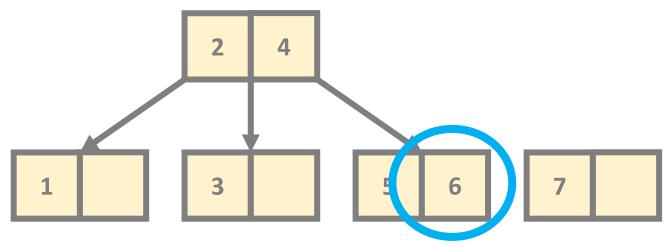




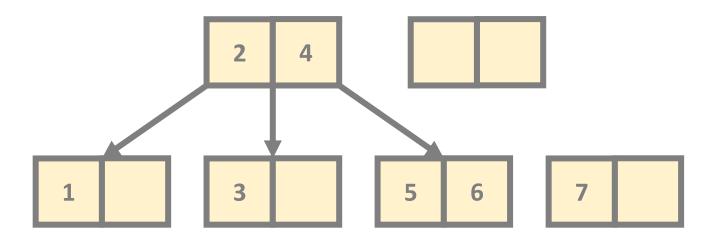


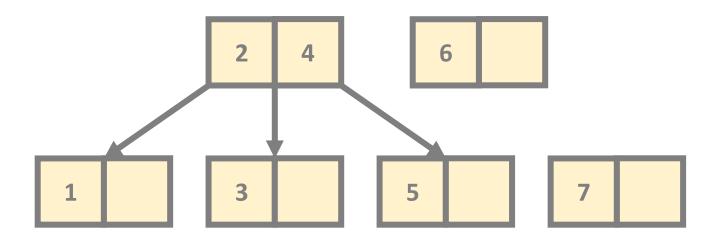


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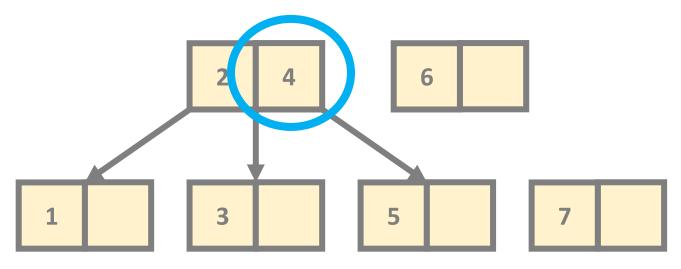
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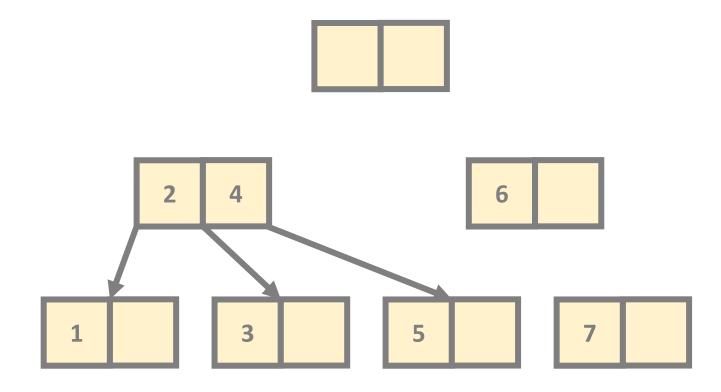


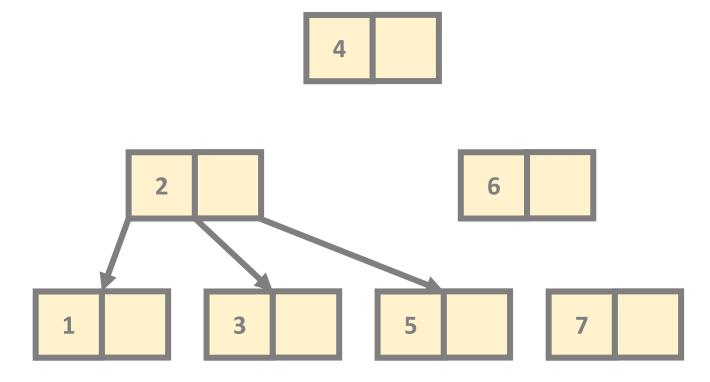


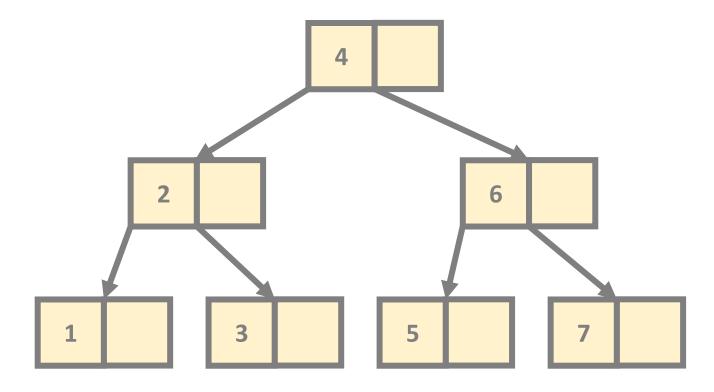
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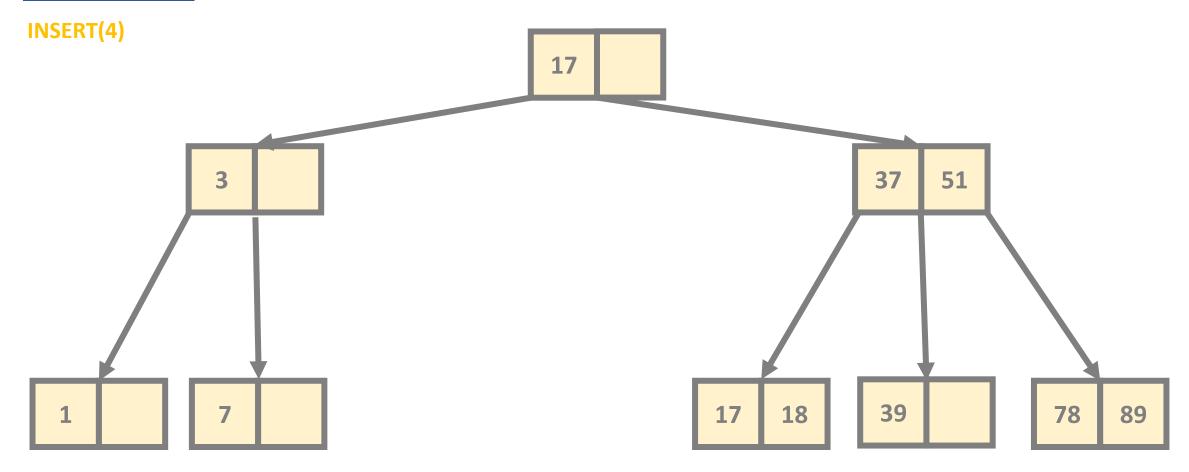
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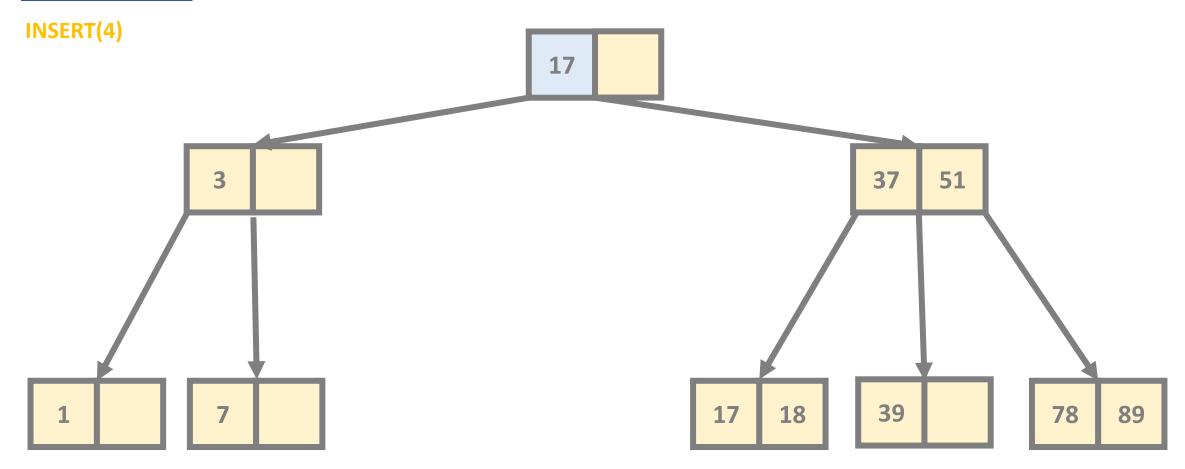


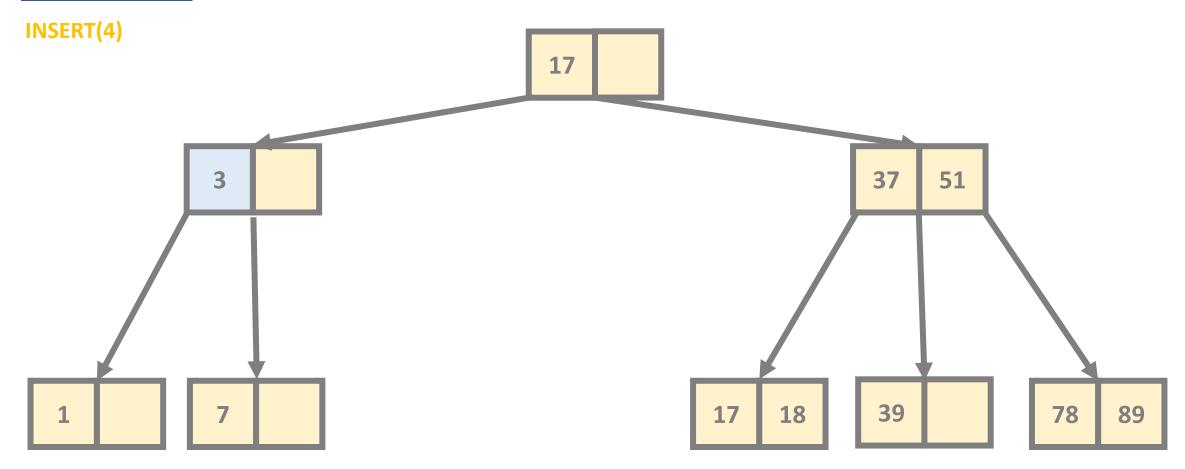


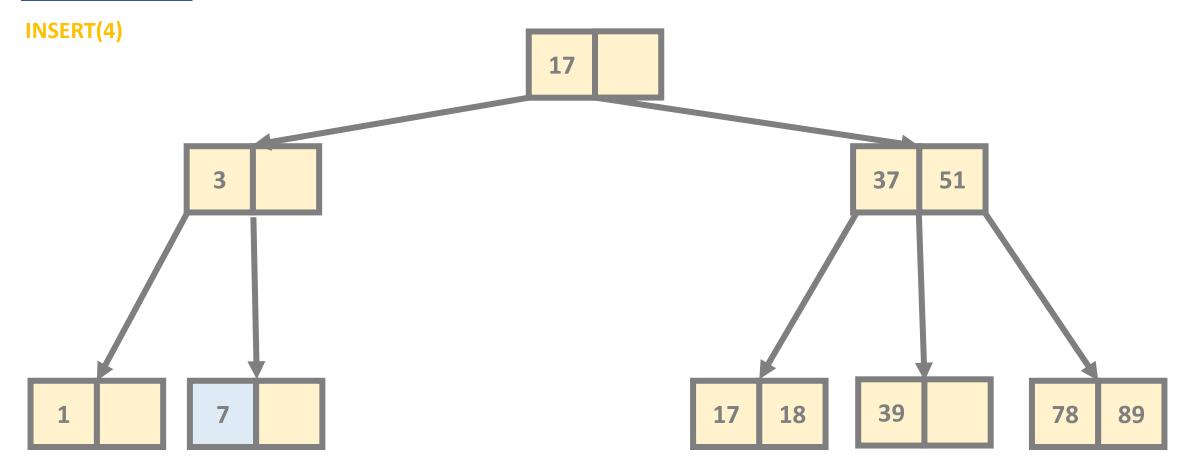


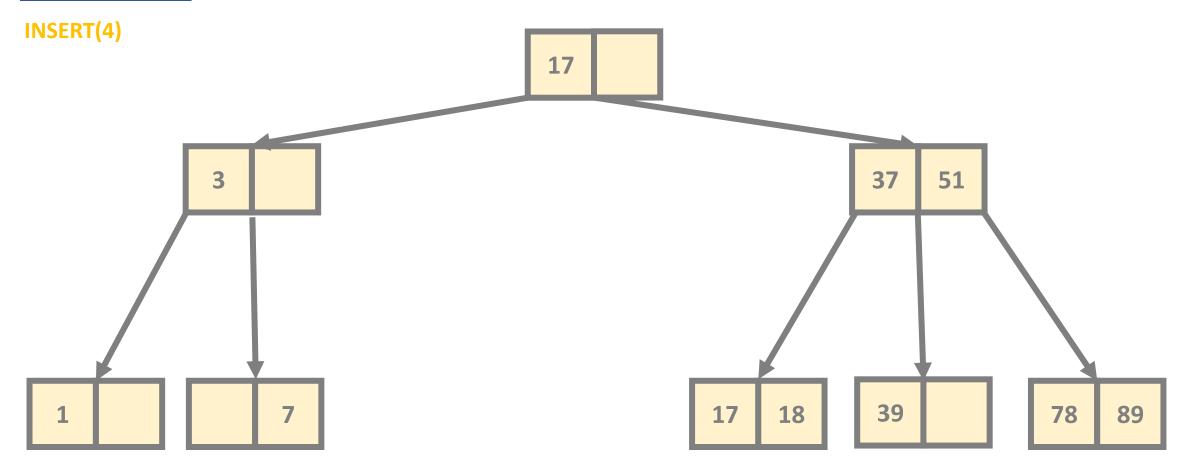


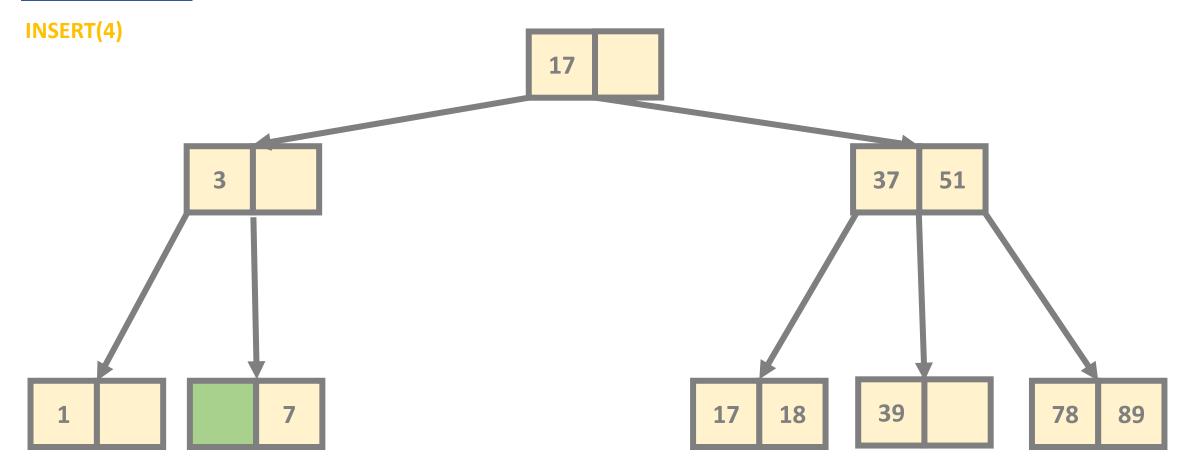


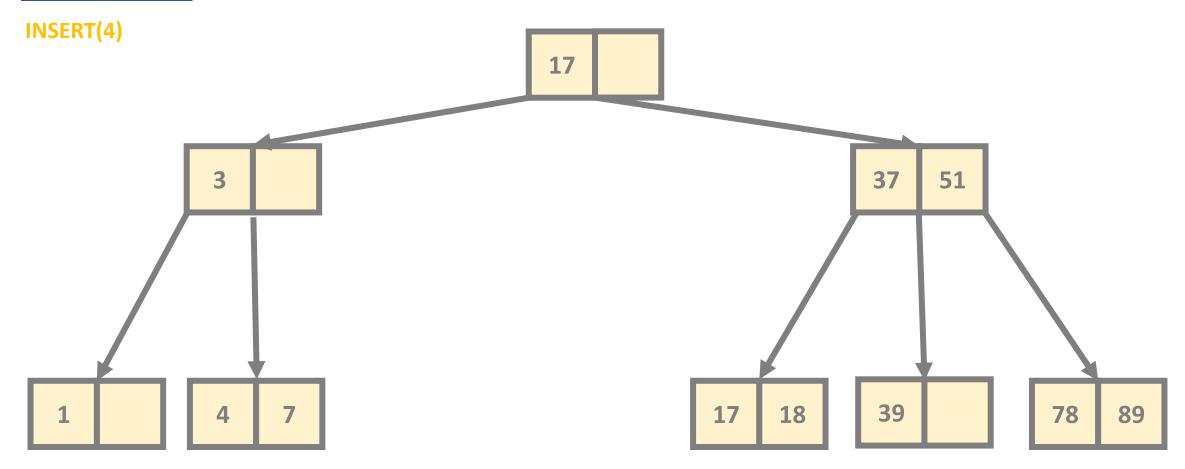


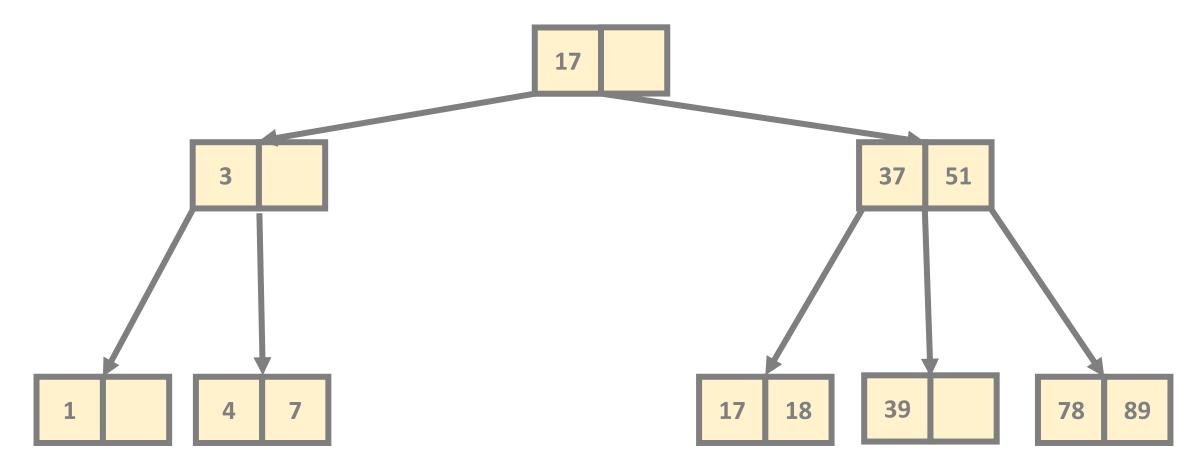


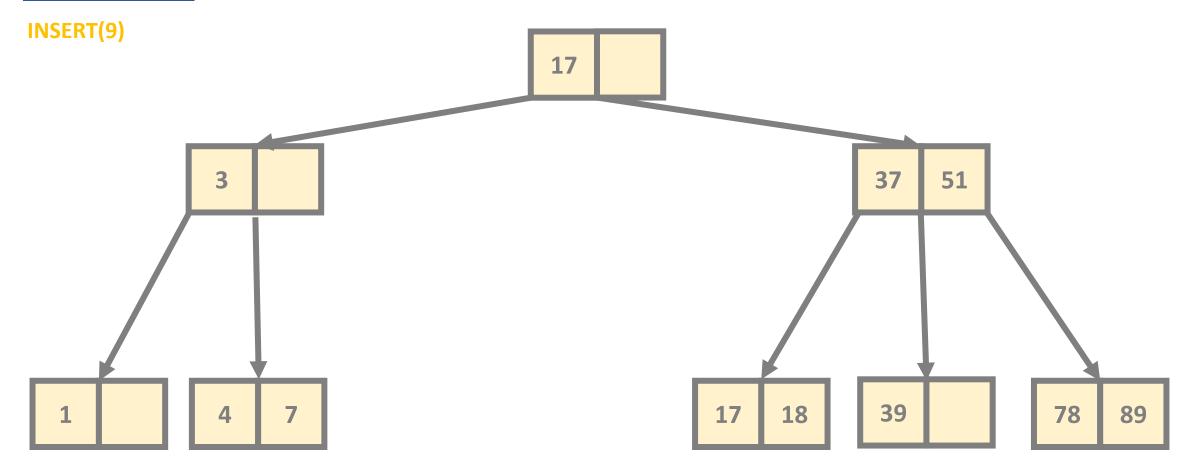


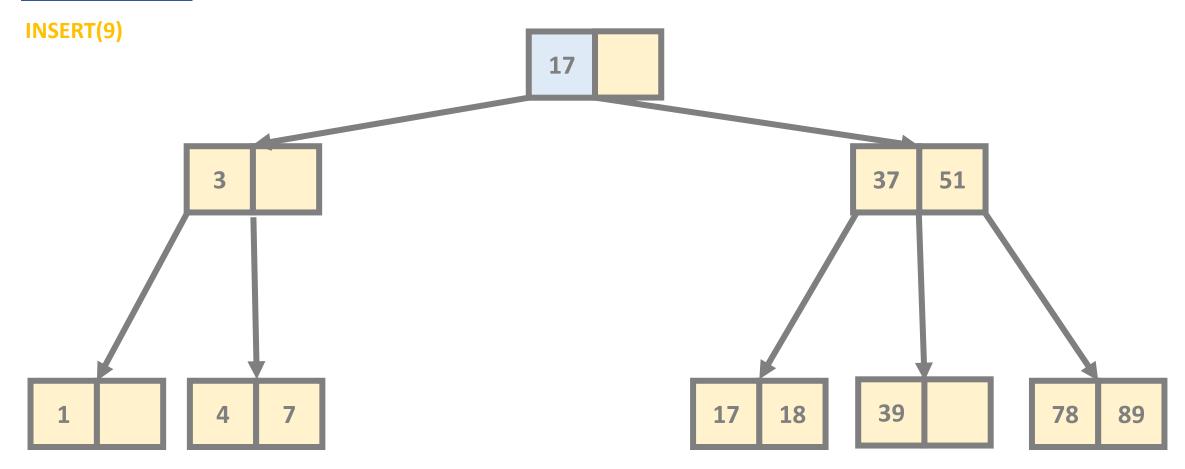


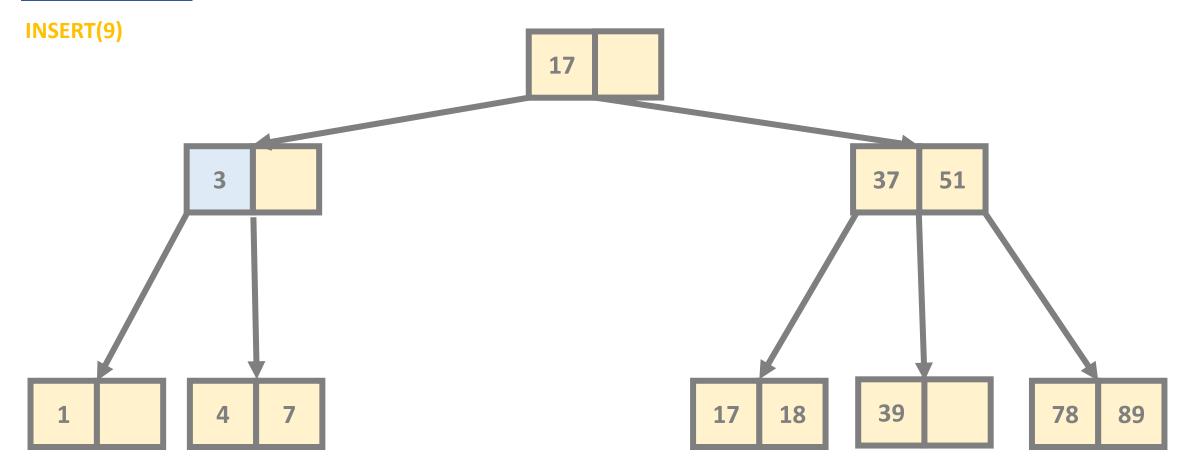


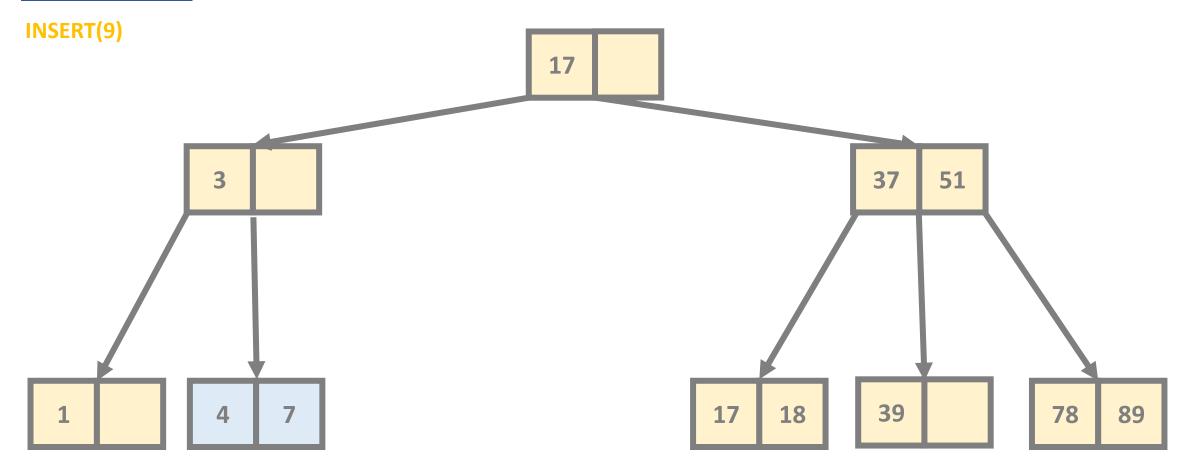


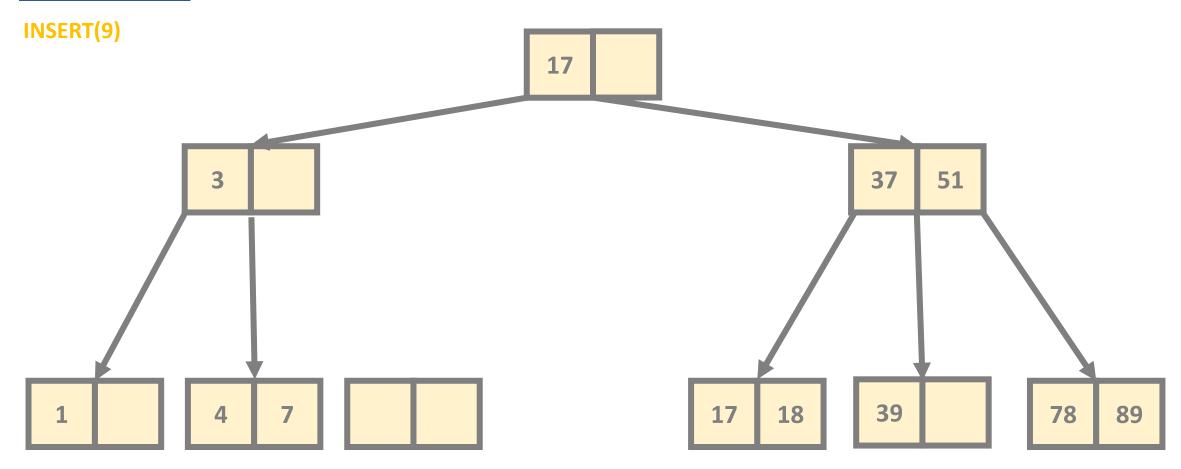


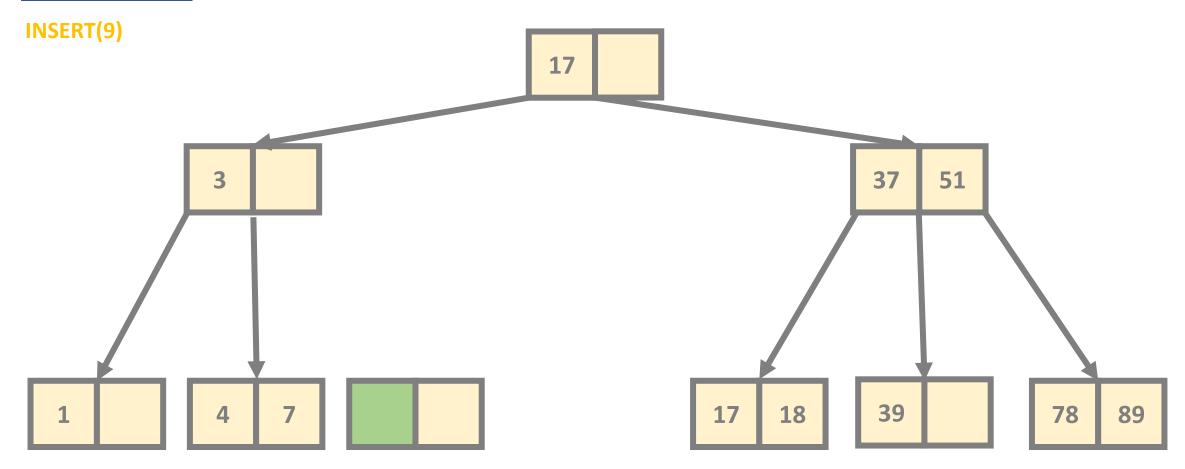


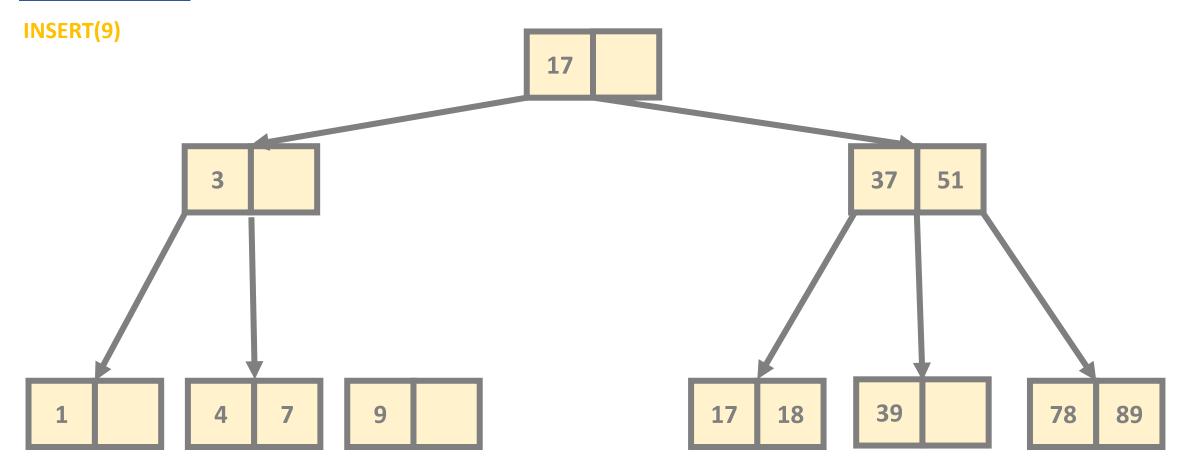


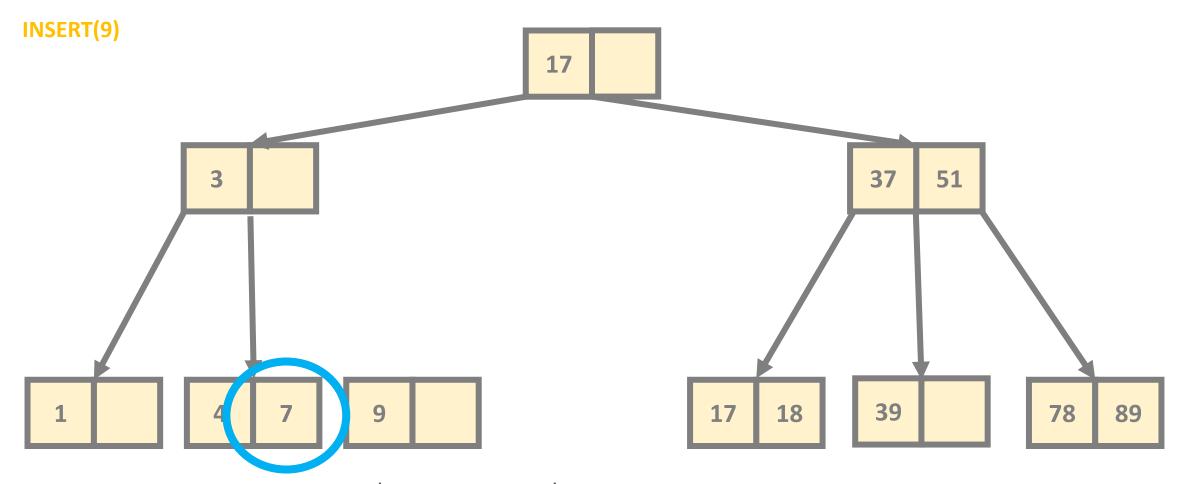




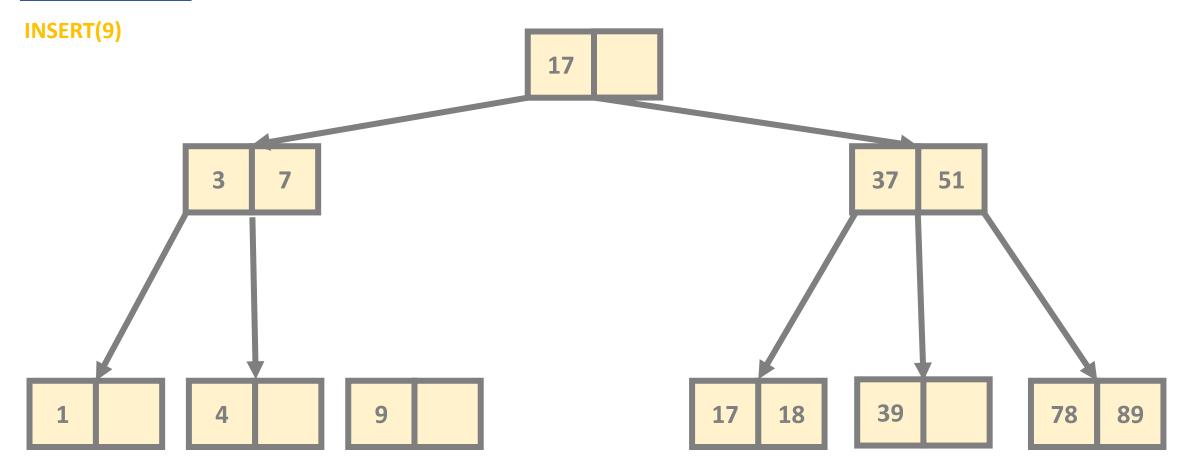


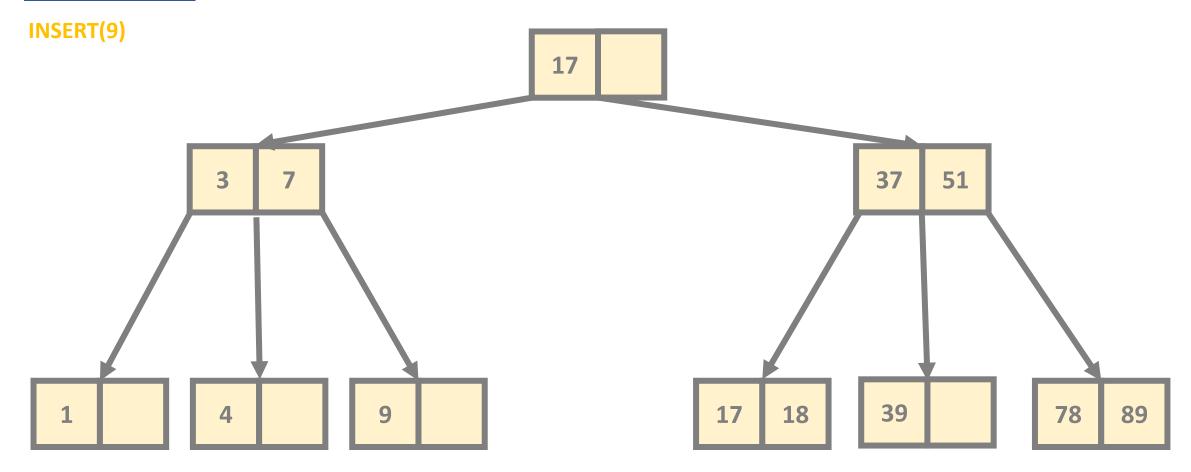


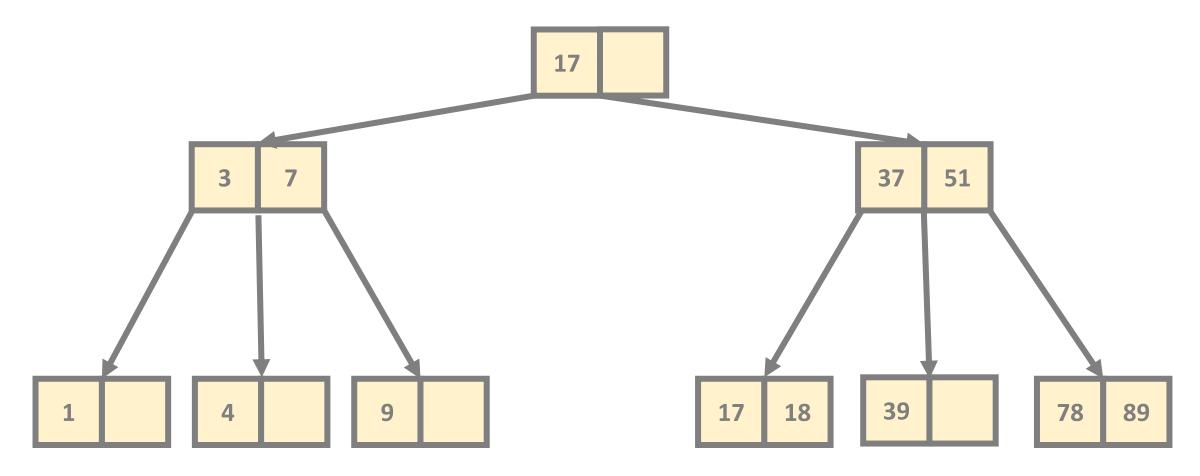


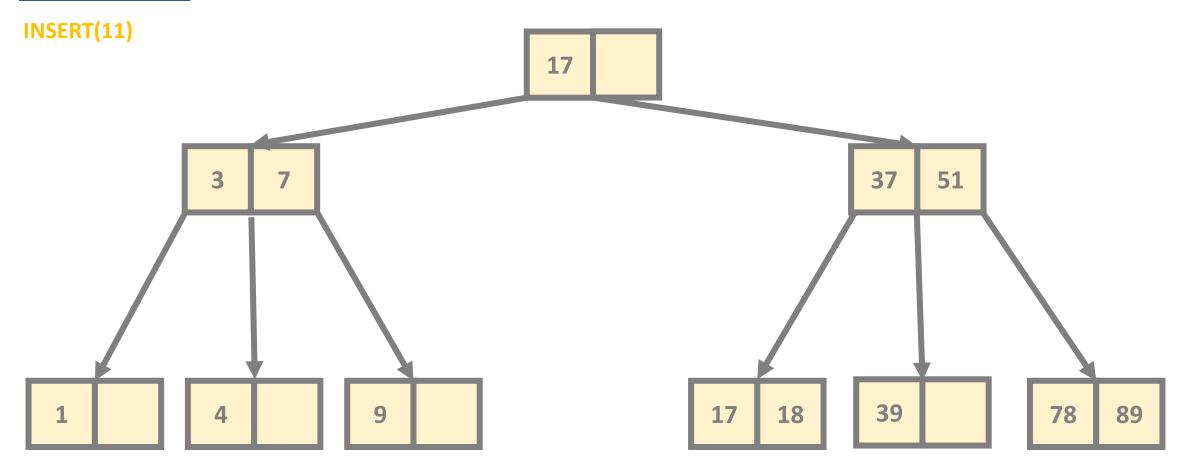


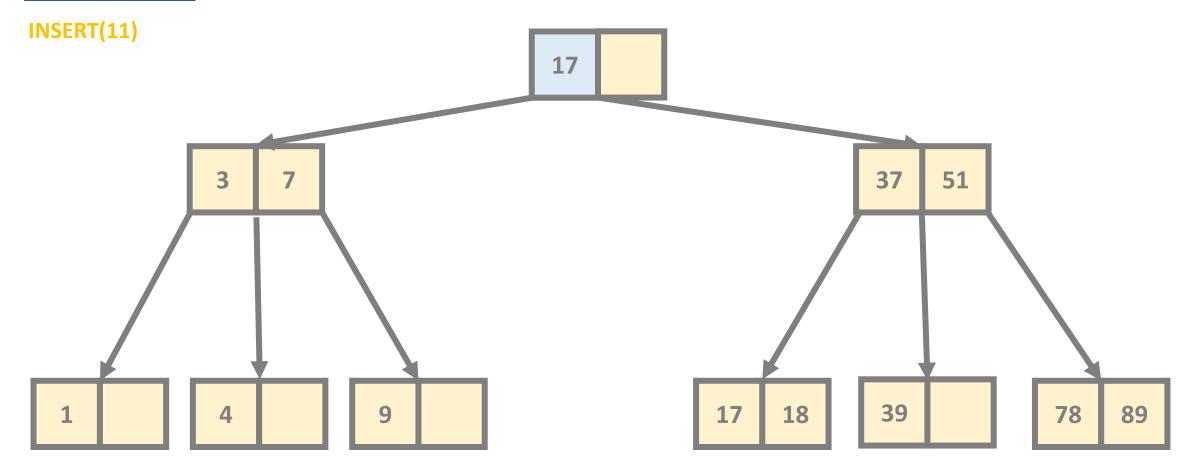
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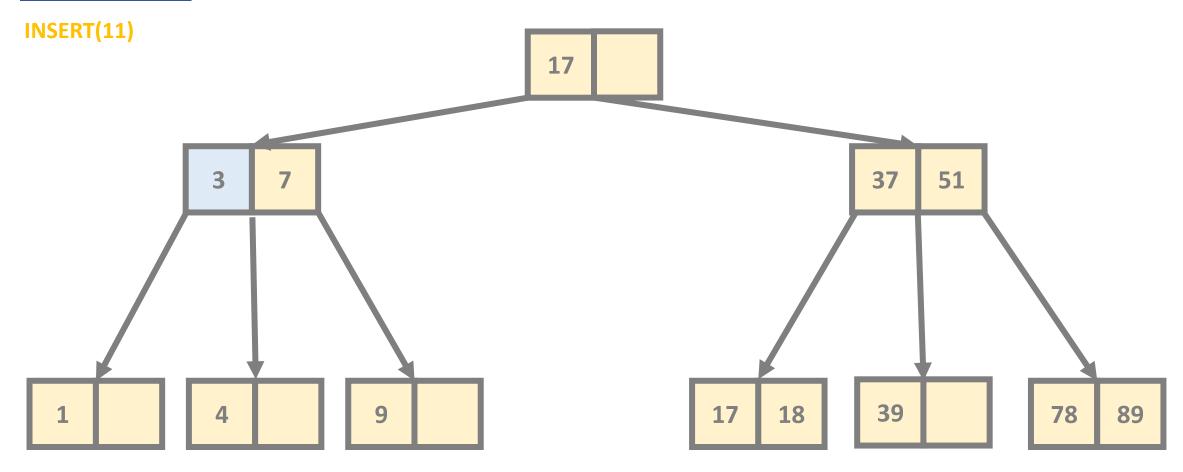


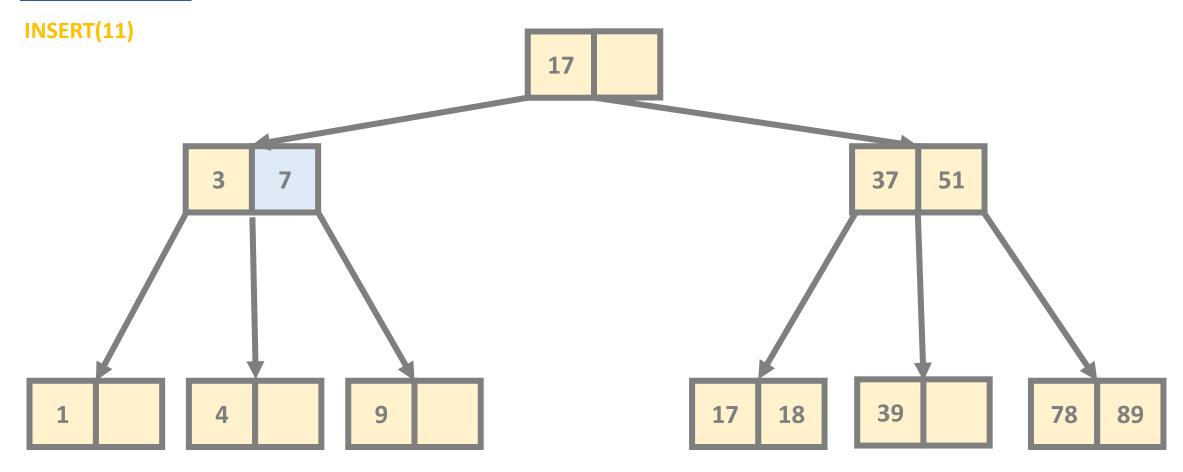


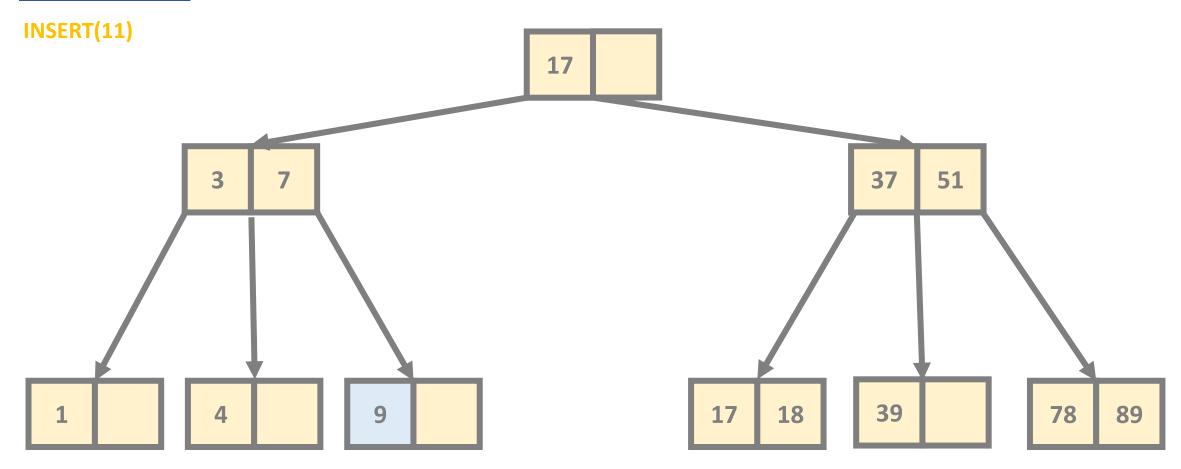


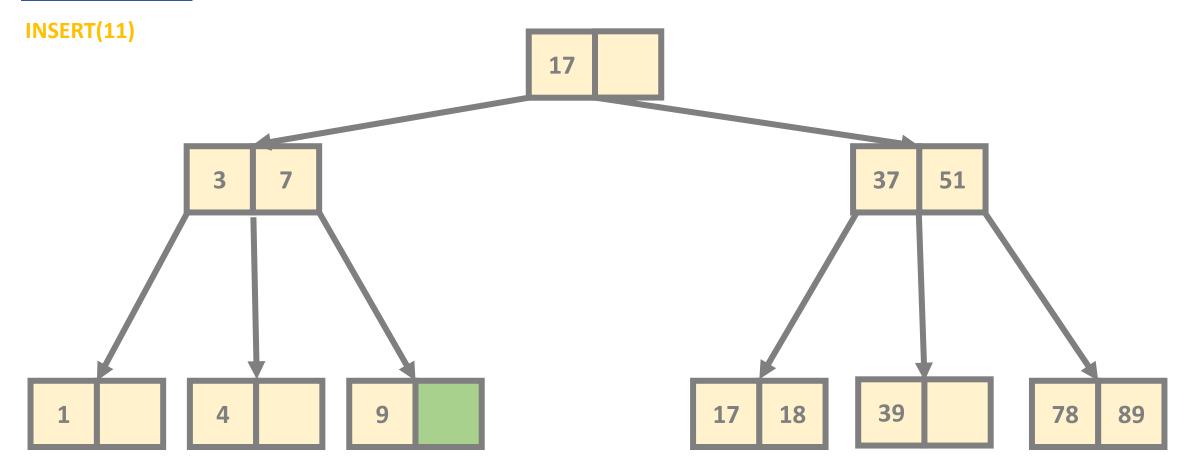


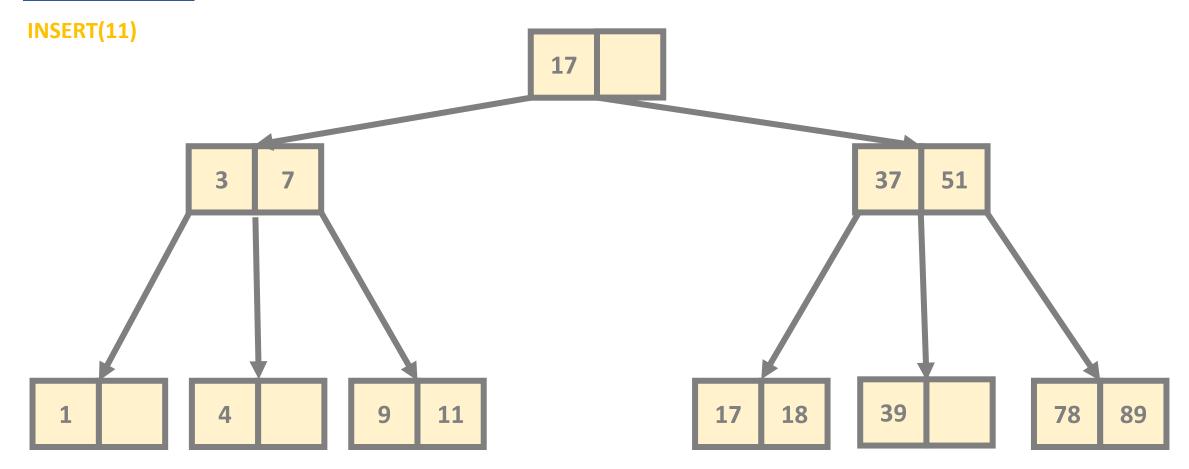


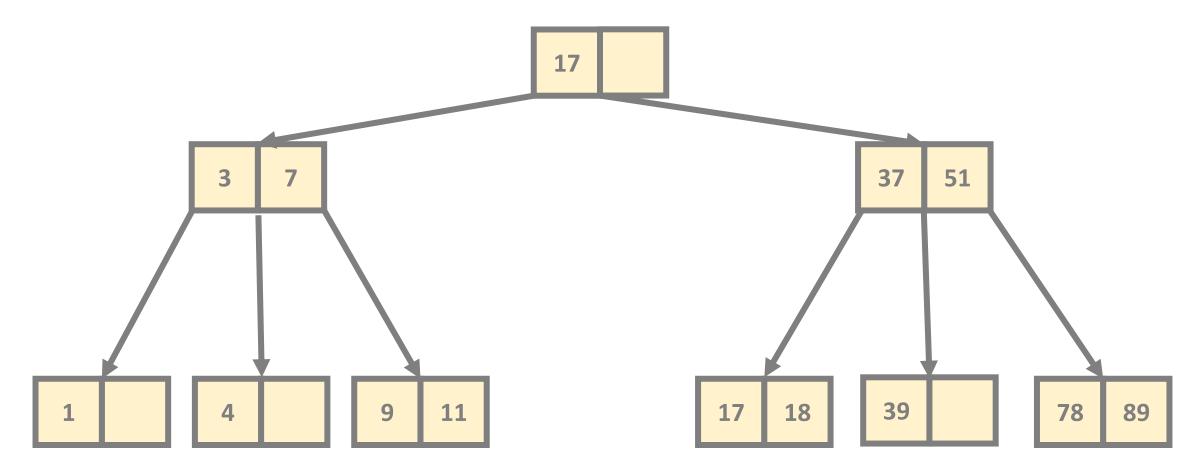


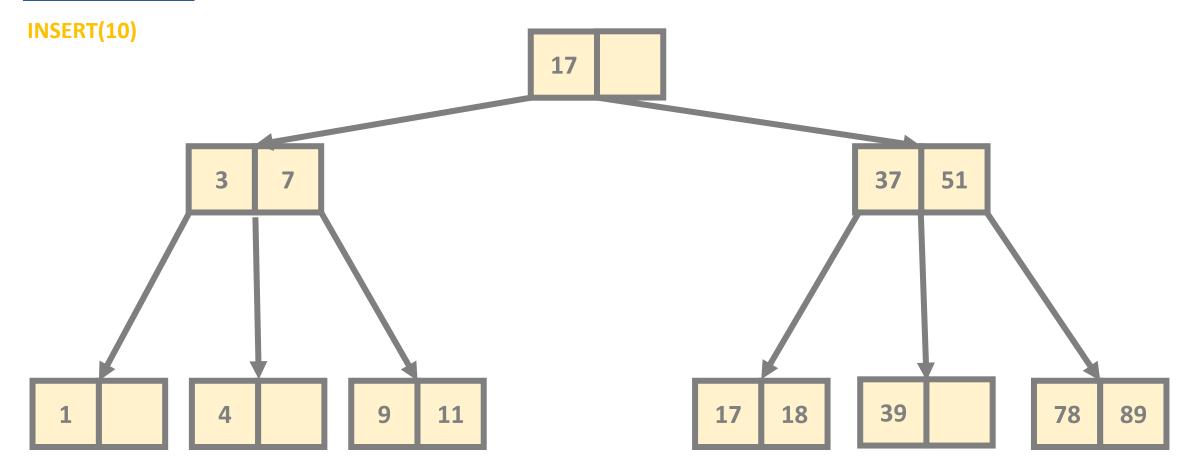


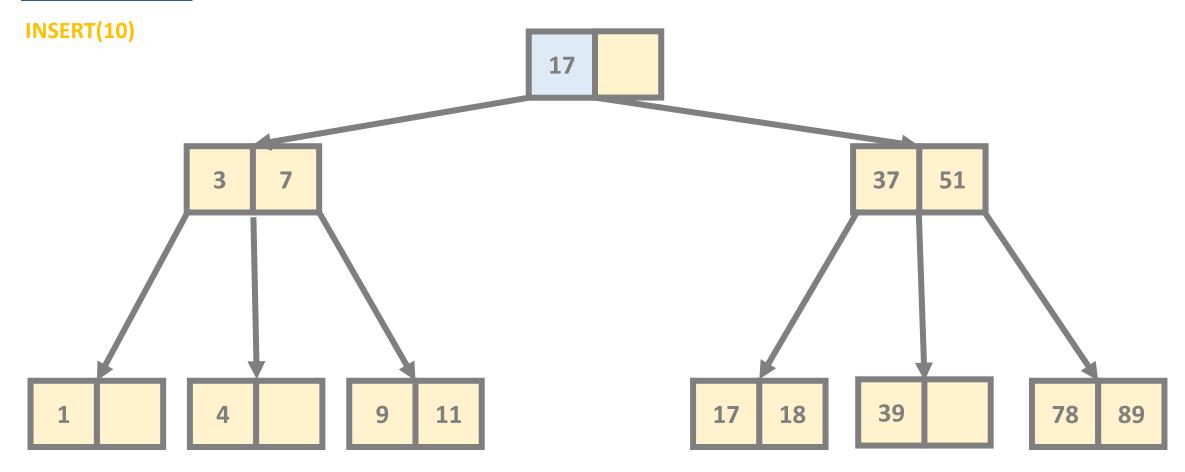


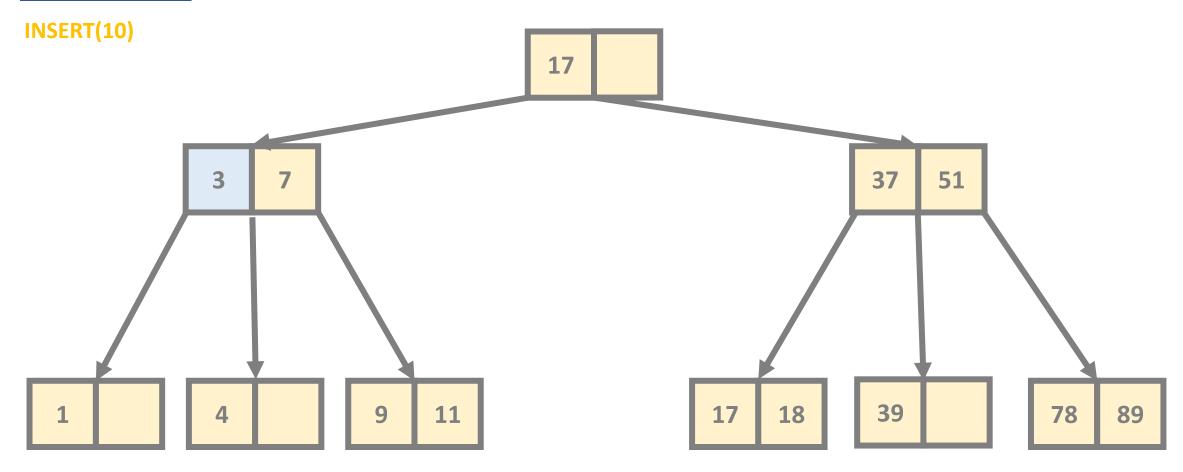


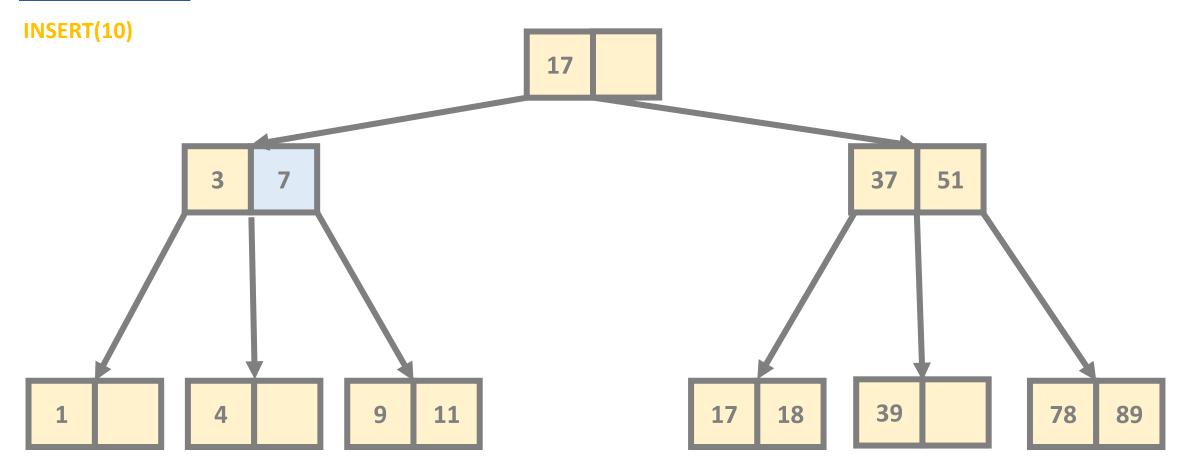


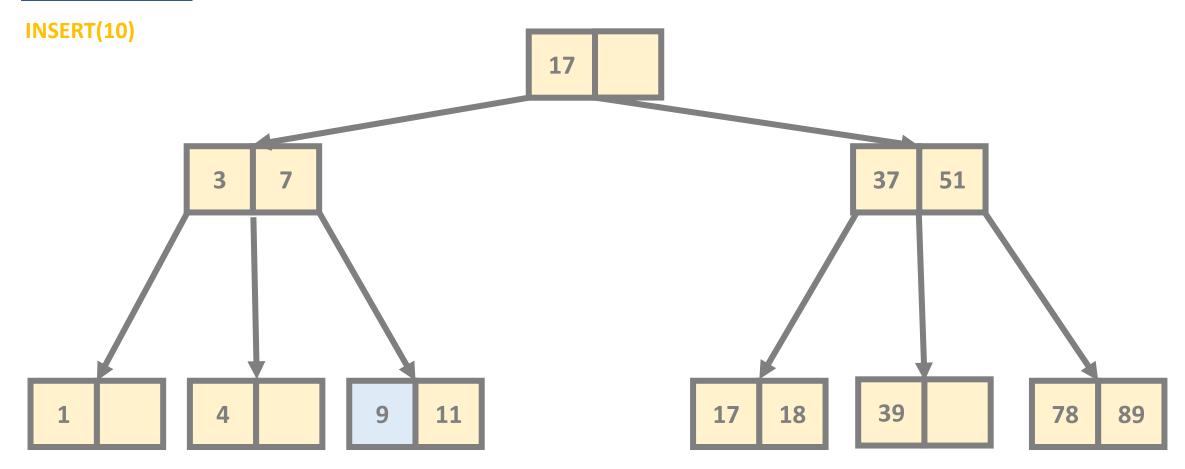


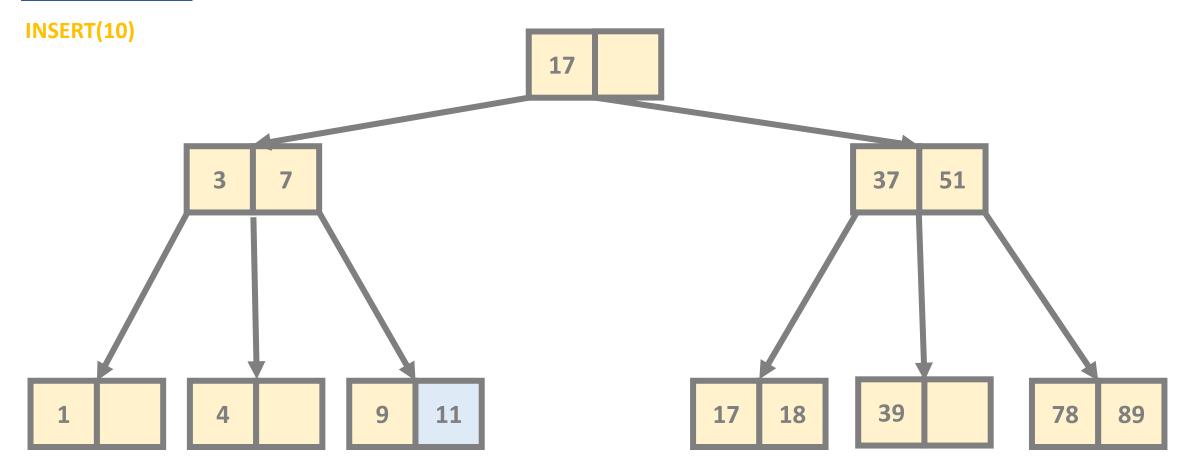


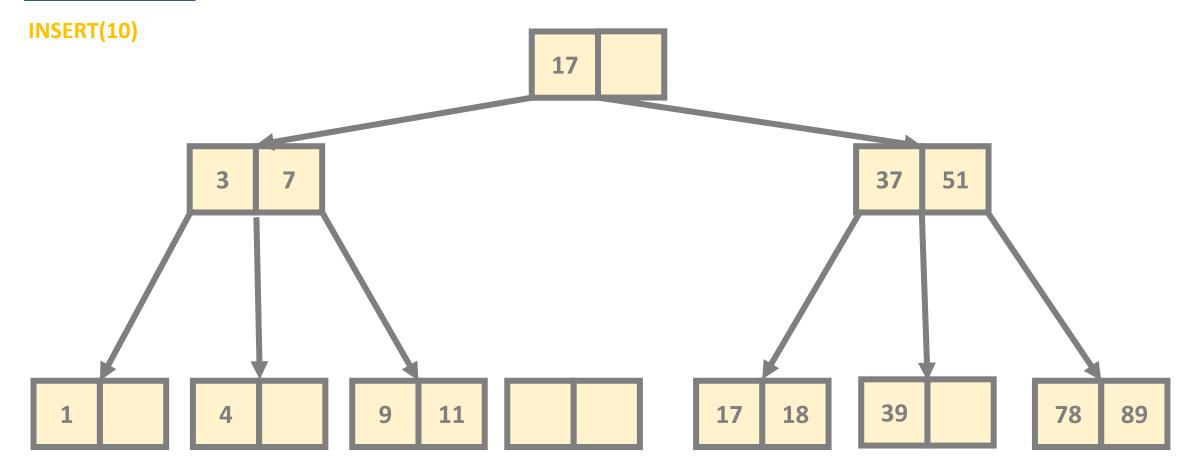


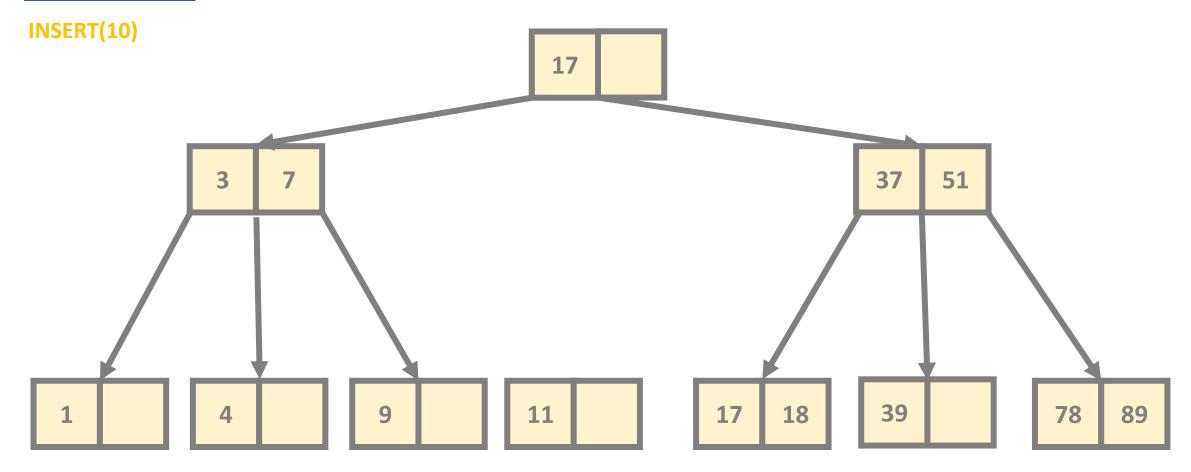


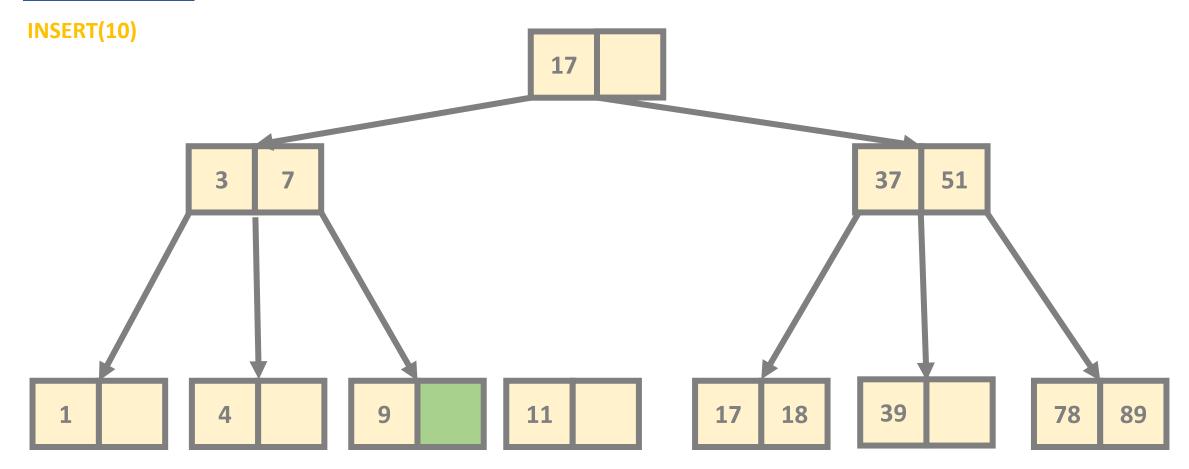


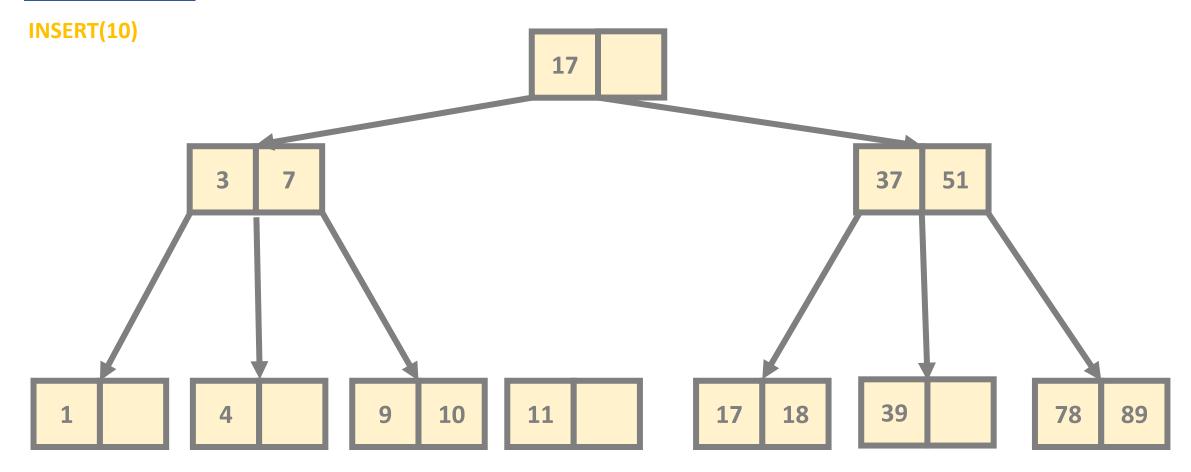


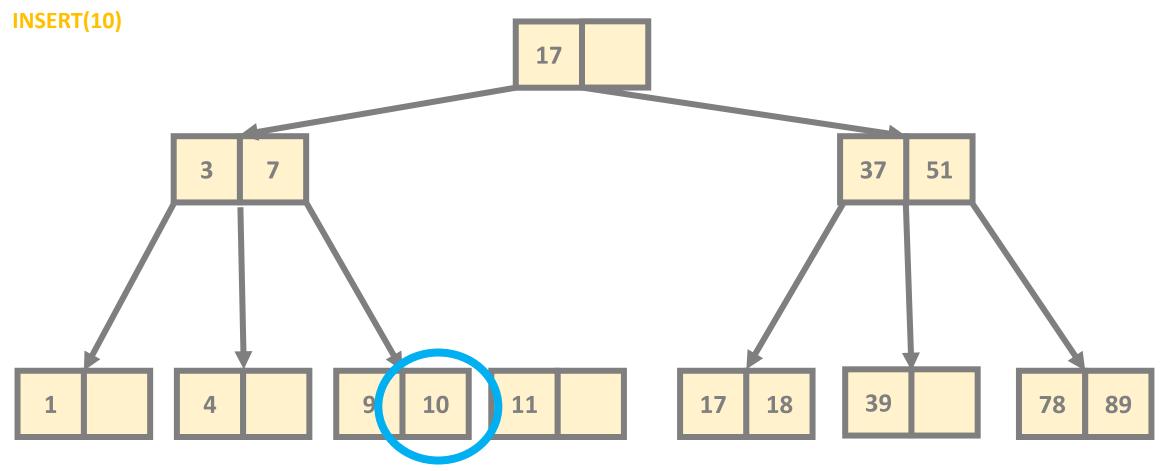




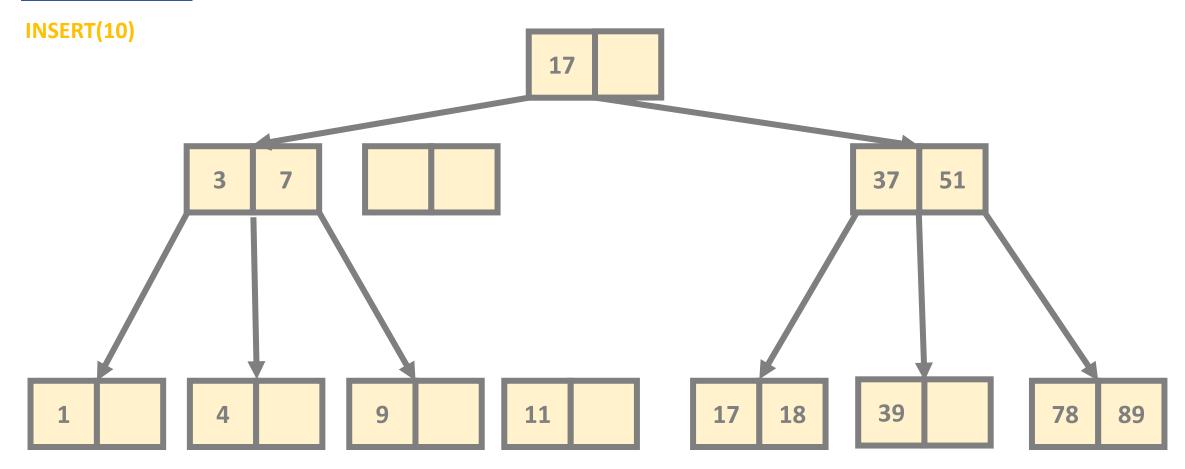


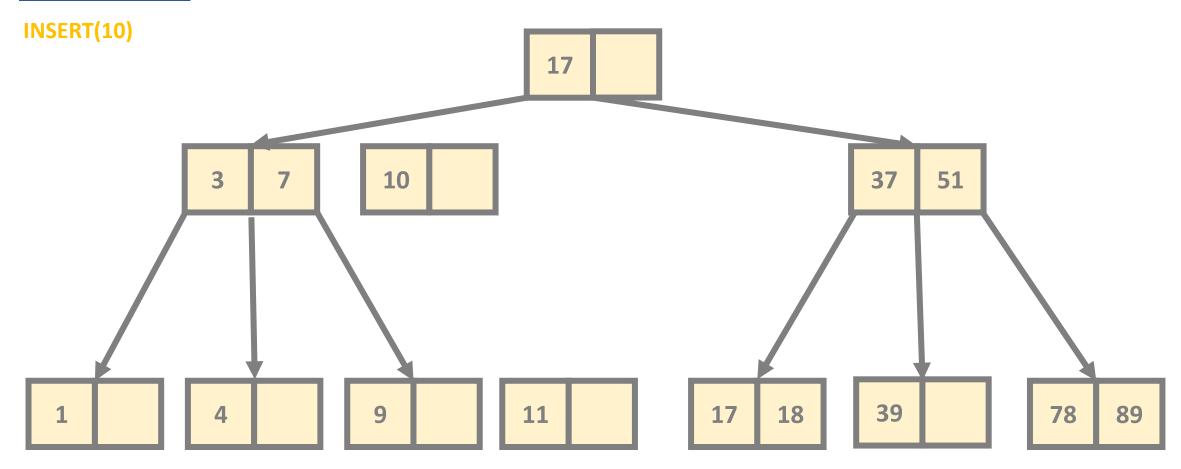


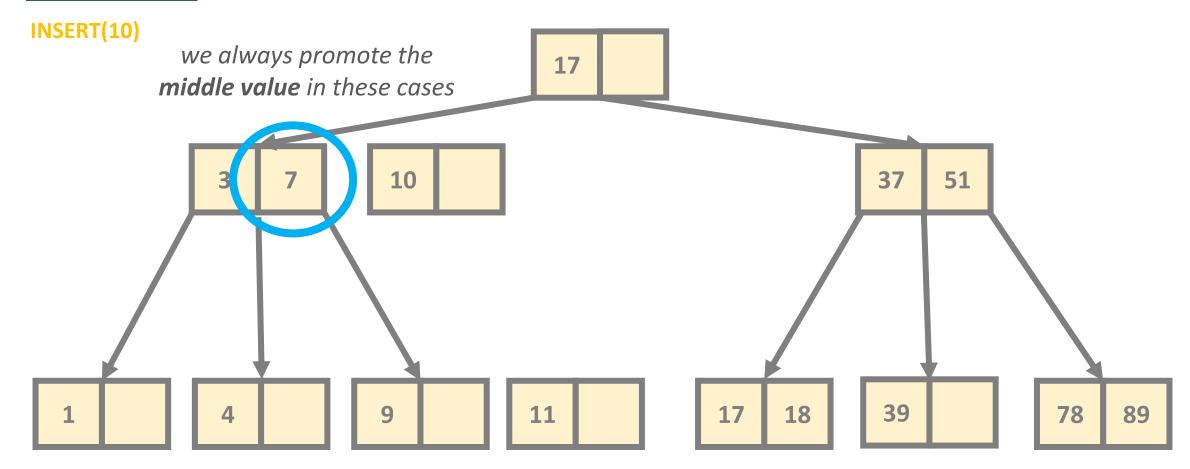


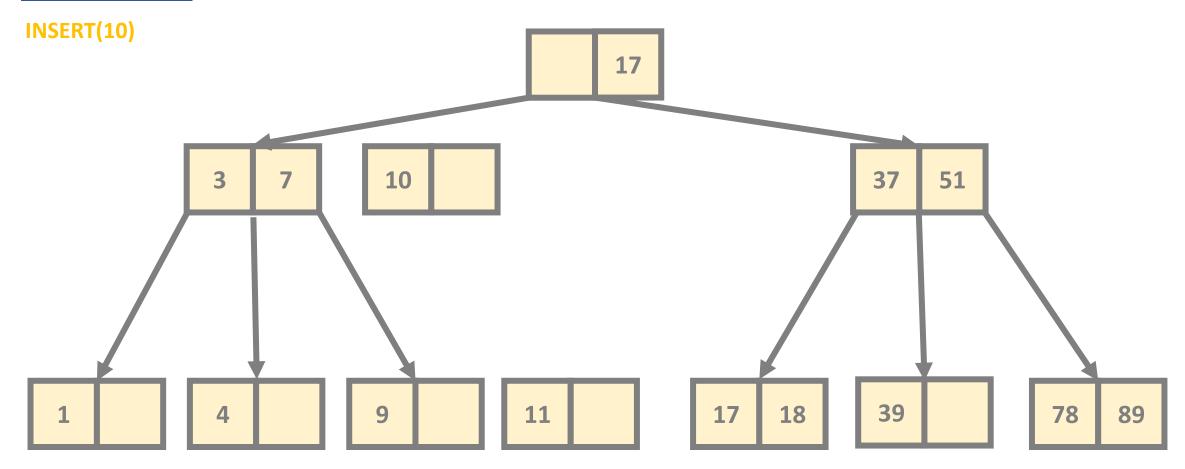


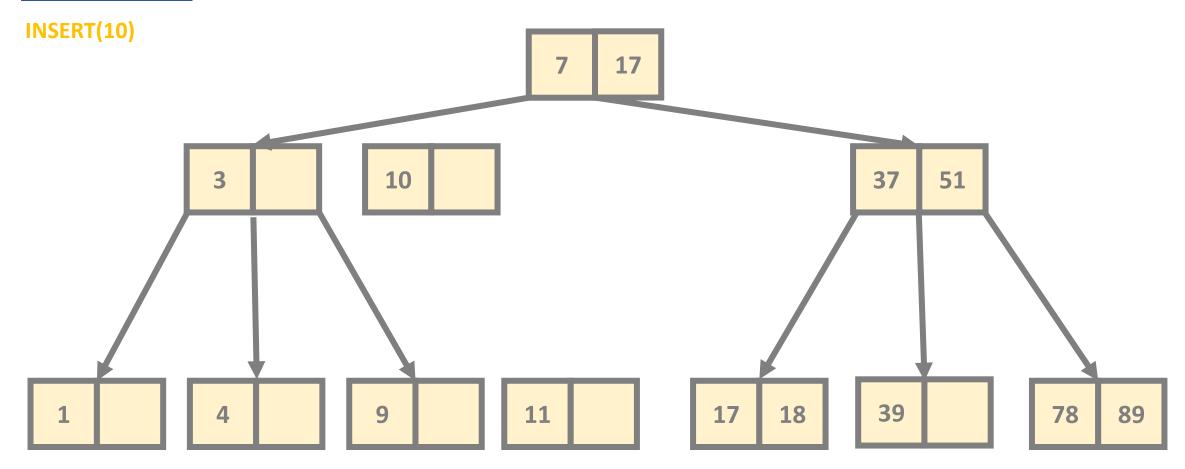
we always promote the **middle value** in these cases

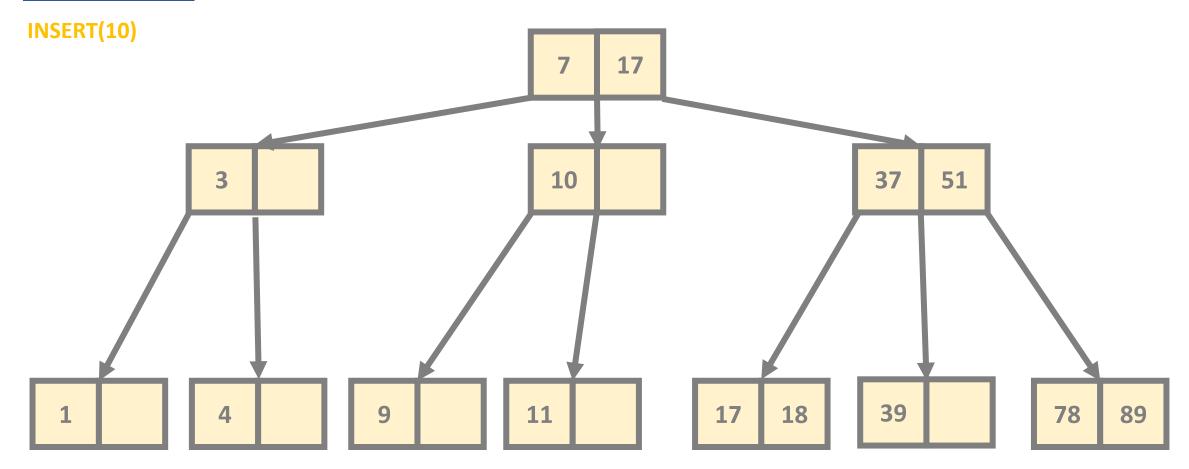










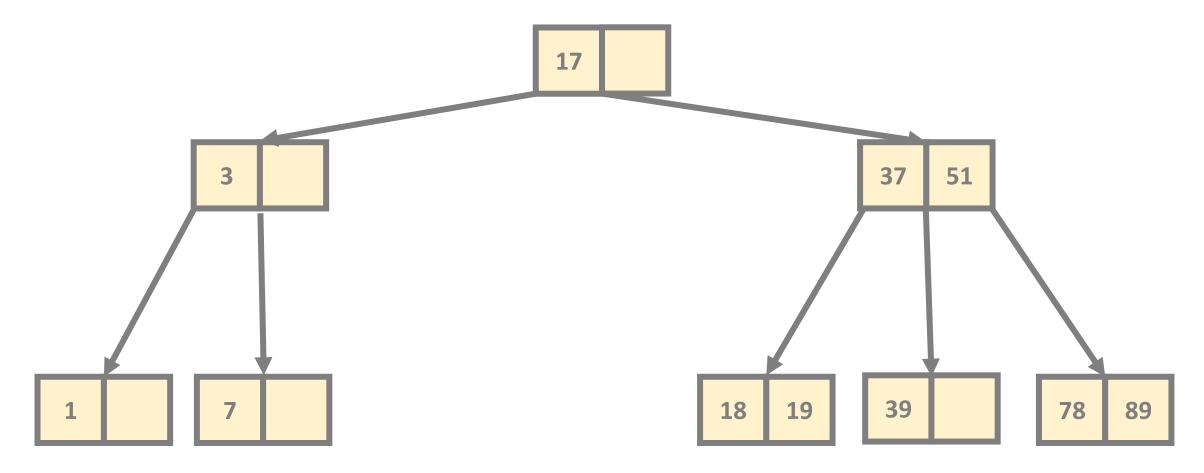


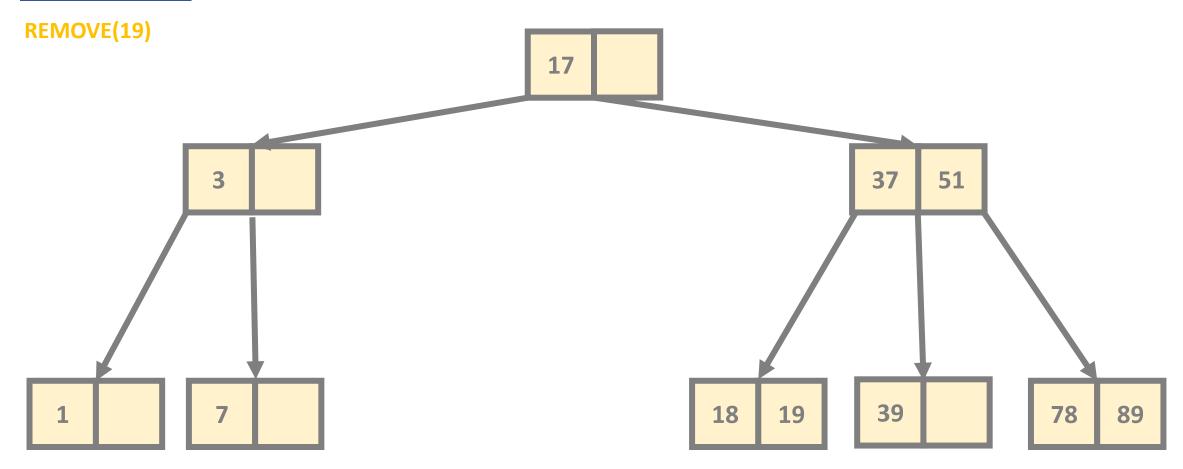
B-Trees Removal (Algorithms and Data Structures)

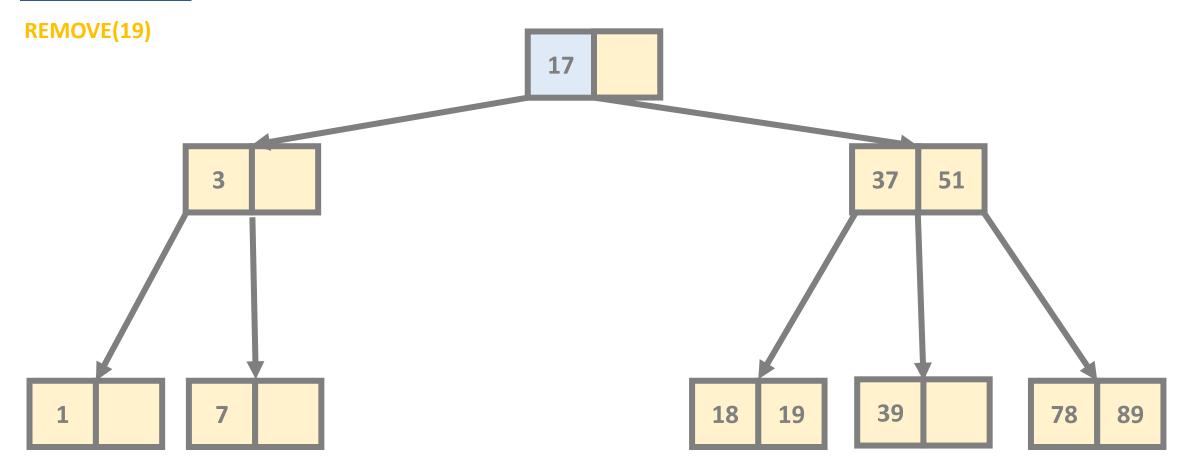
B-Tree Removal

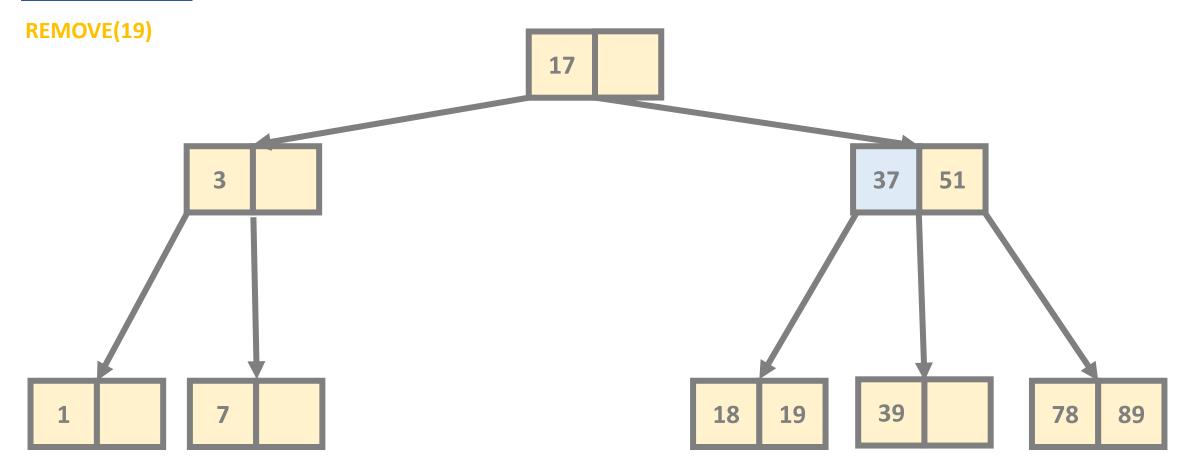
1.) REMOVING AN INTERNAL ITEM

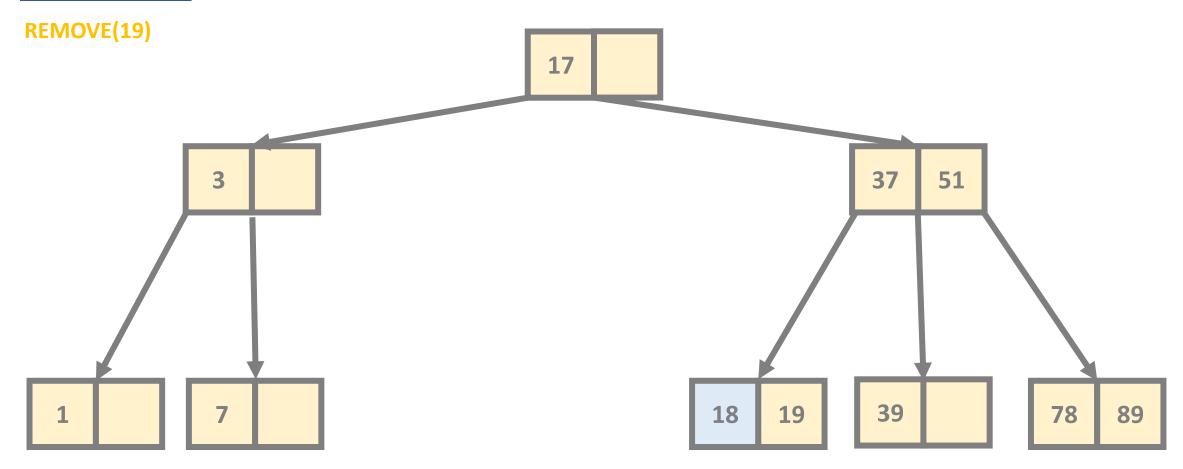
We remove an item from the node and does not violate the B-tree properties so the number of items remains in the range $\left[\frac{m}{2}, m\right]$

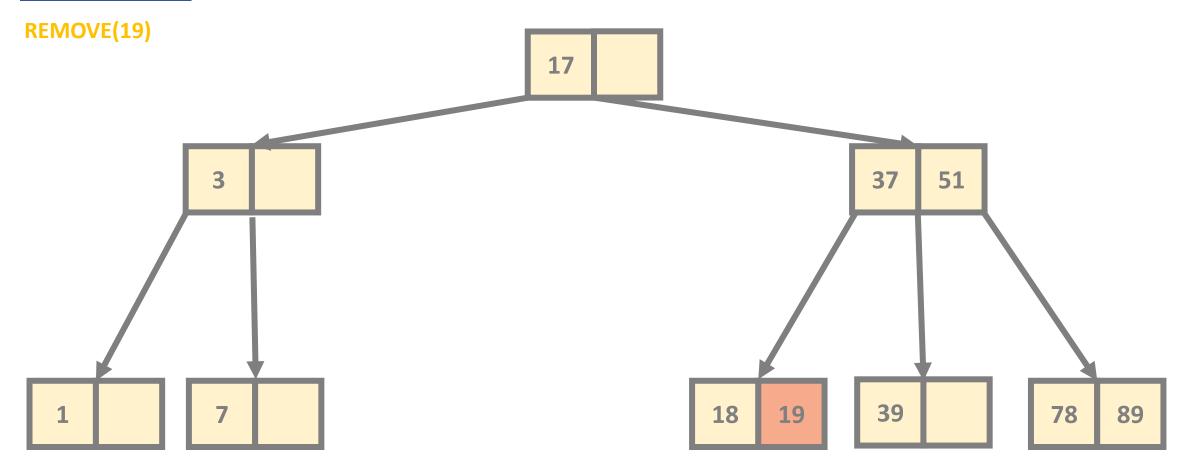


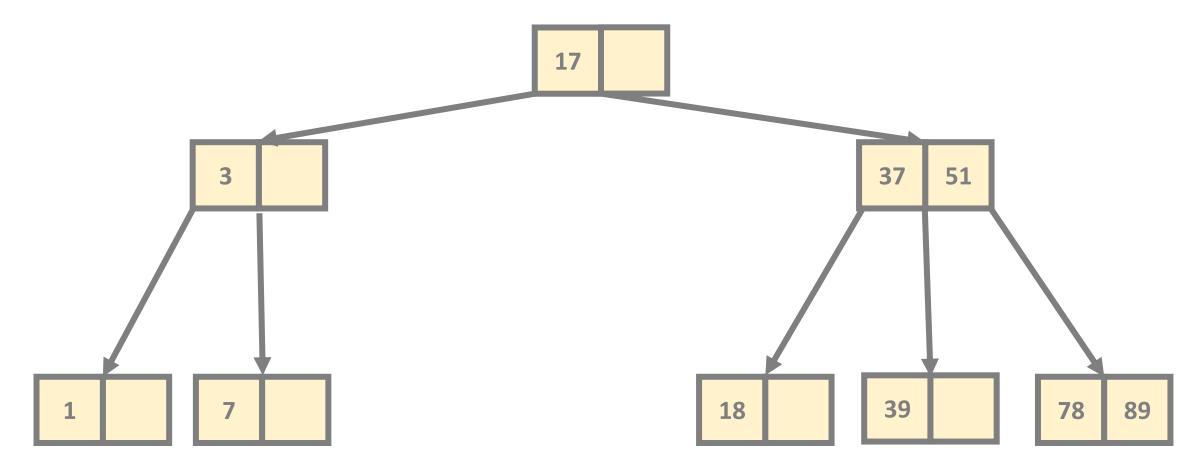










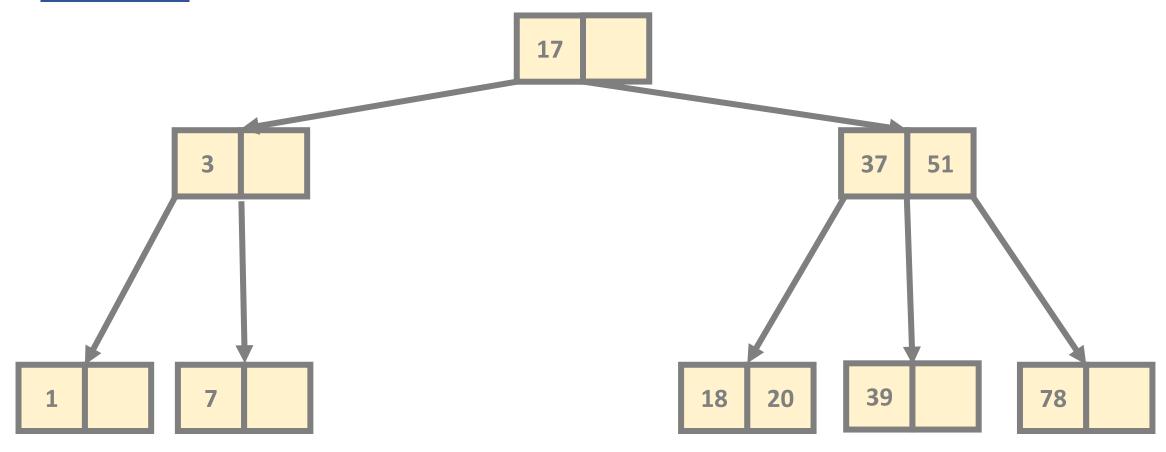


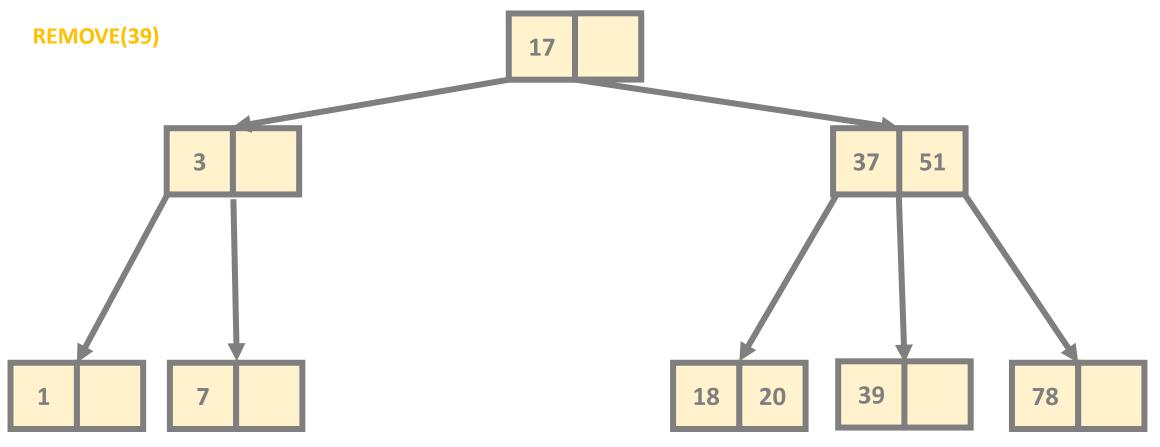
B-Tree Removal

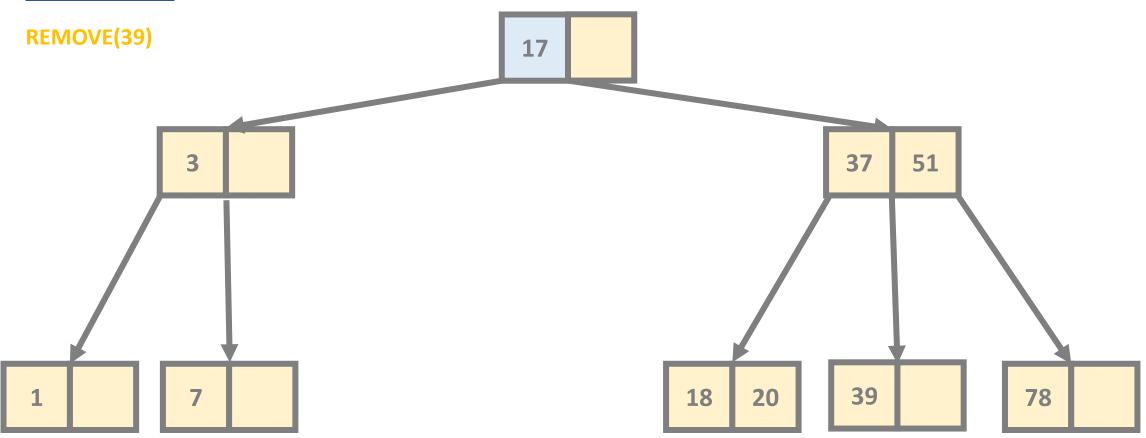
2.) REMOVING A INTERNAL ITEM

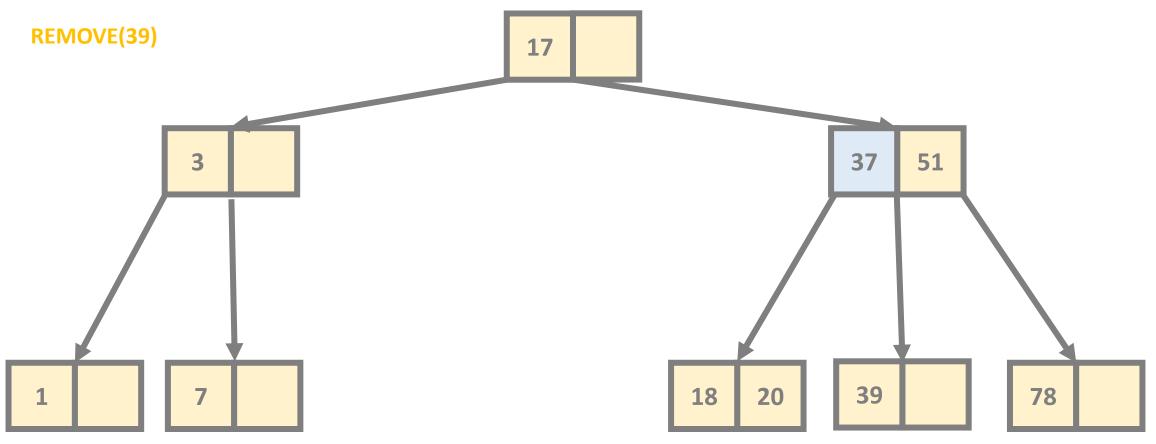
We remove an item from the node and the **B-tree properties are violated** as there will be less than $\frac{m}{2}$ items in the given node

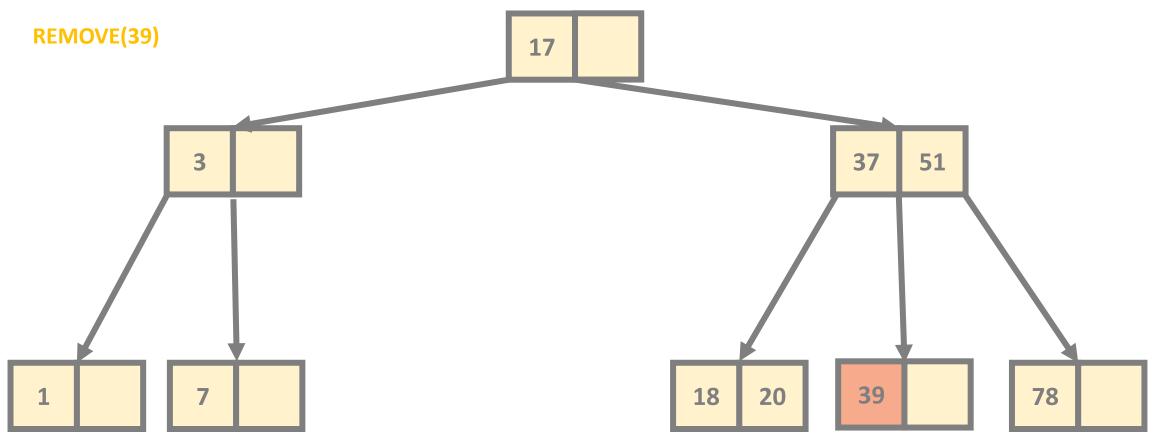
WE CAN GET AN ITEM FROM THE LEFT SIBLING !!!

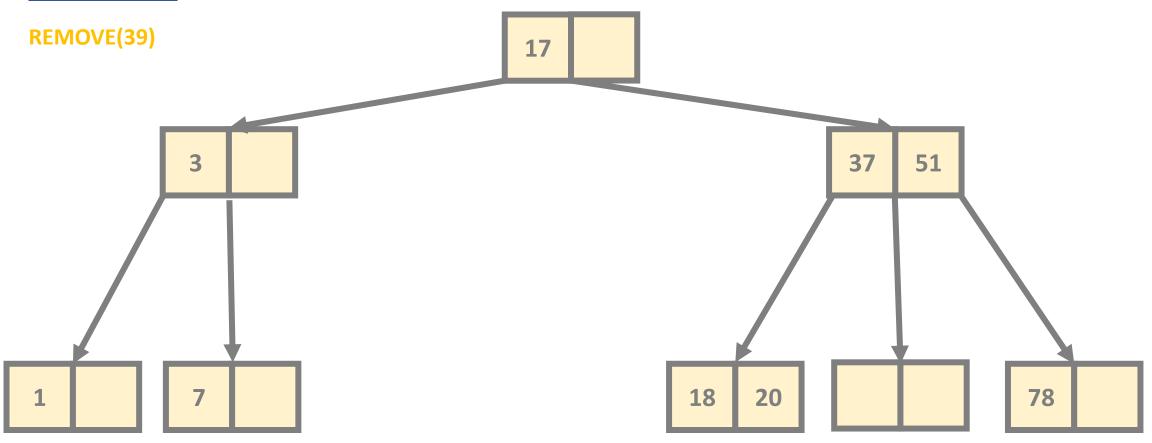


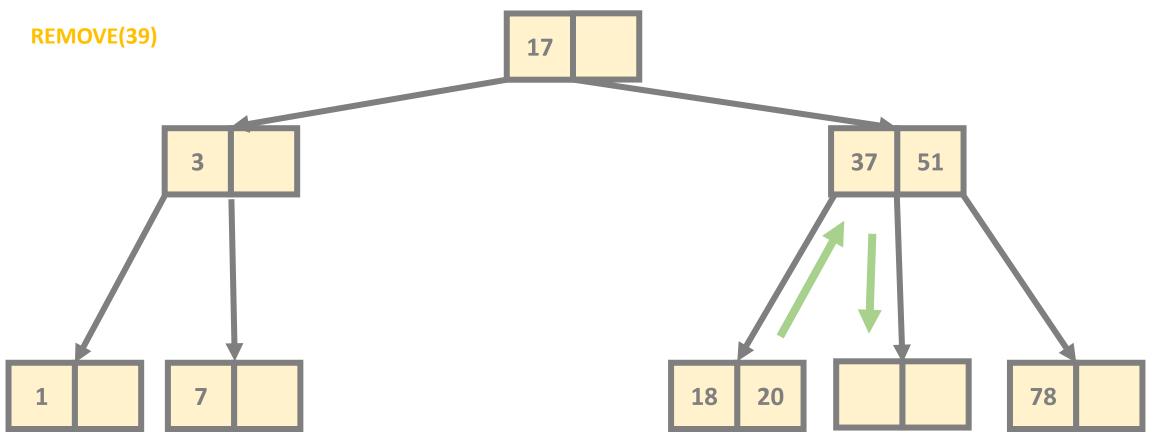


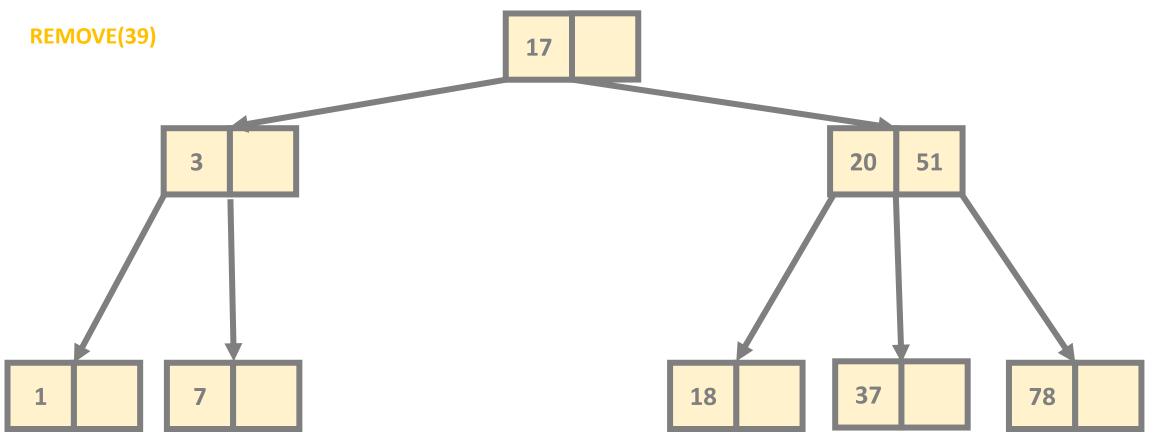


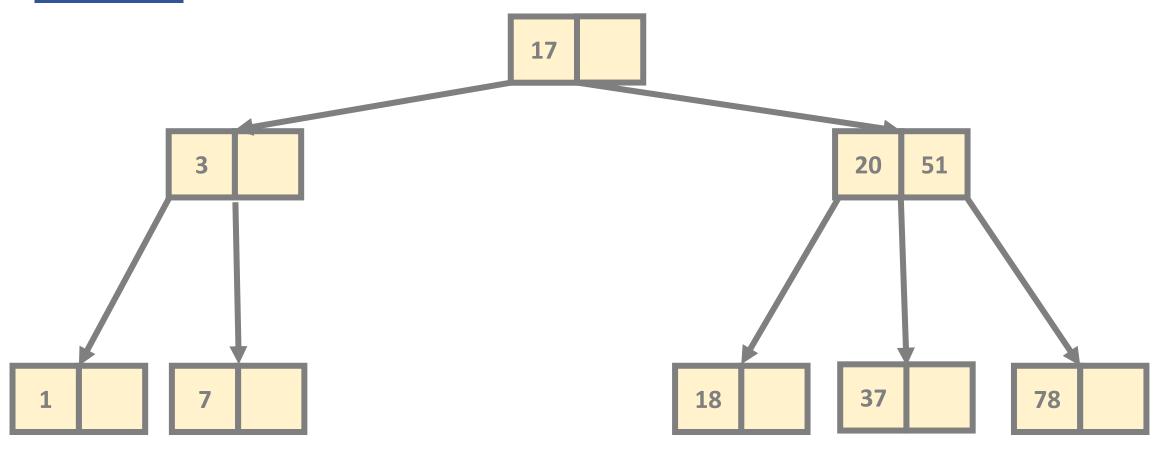










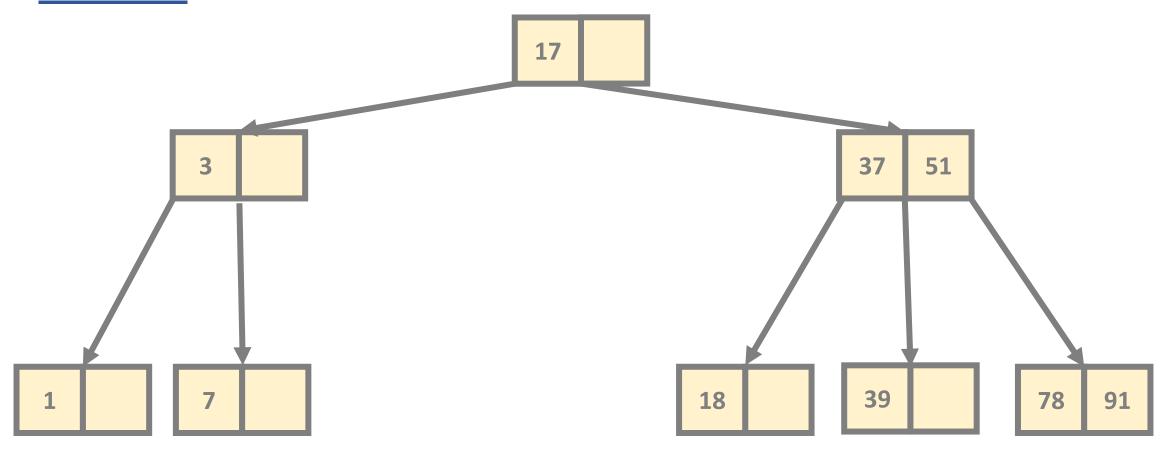


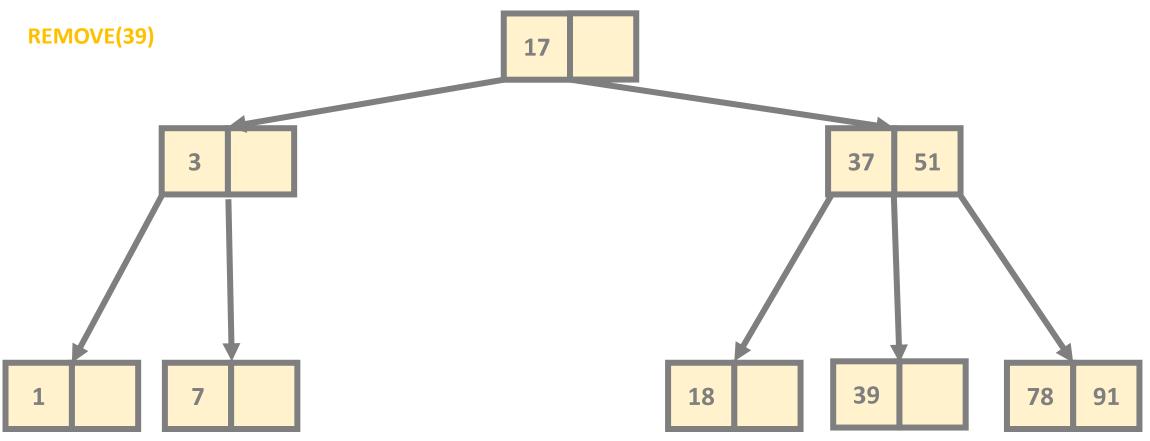
B-Tree Removal

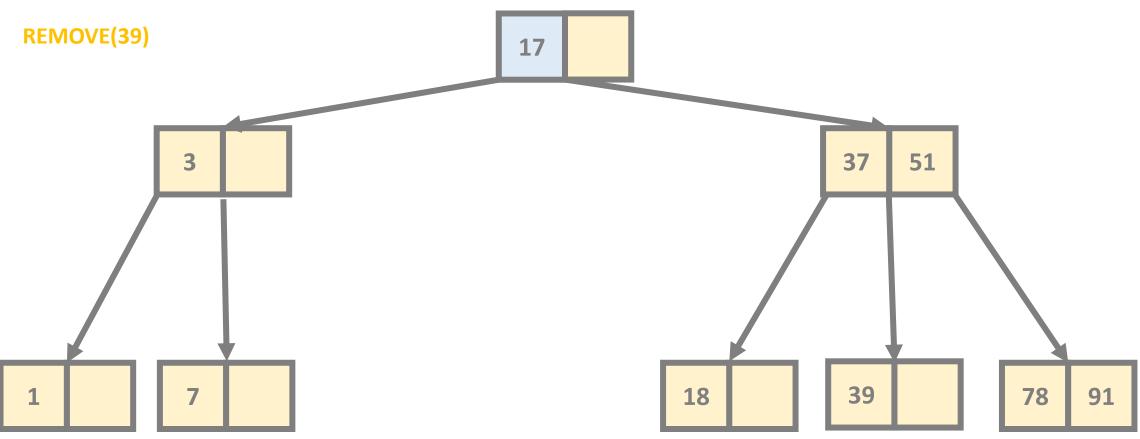
3.) REMOVING A INTERNAL ITEM

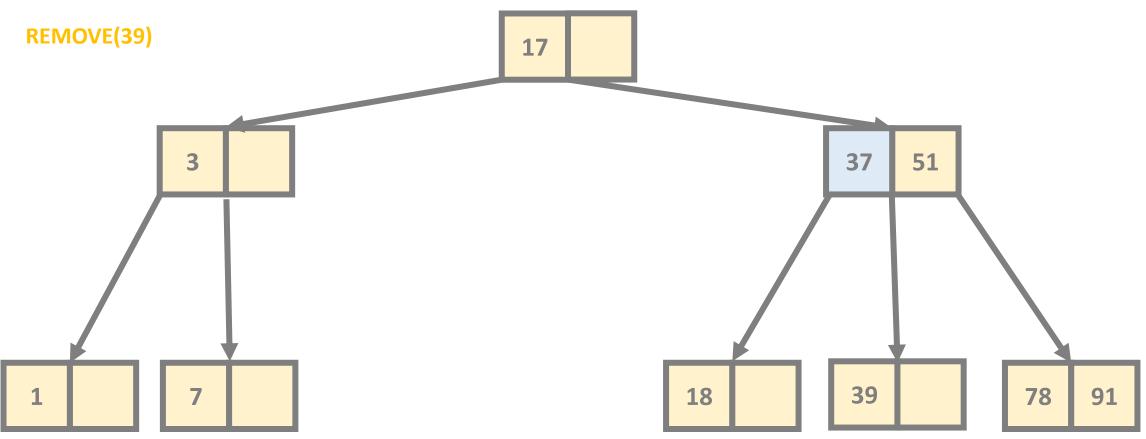
We remove an item from the node and the **B-tree properties are violated** as there will be less than $\frac{m}{2}$ items in the given node

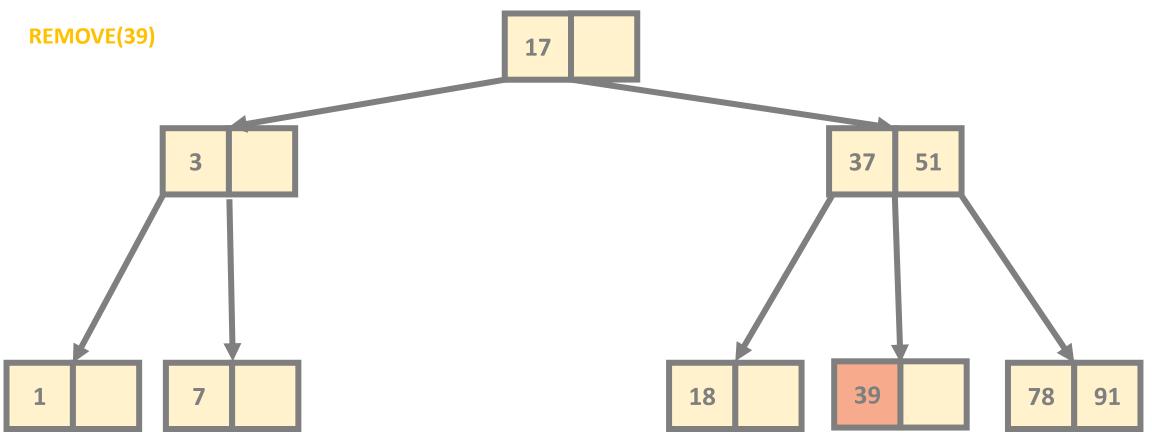
WE CAN GET AN ITEM FROM THE RIGHT SIBLING !!!

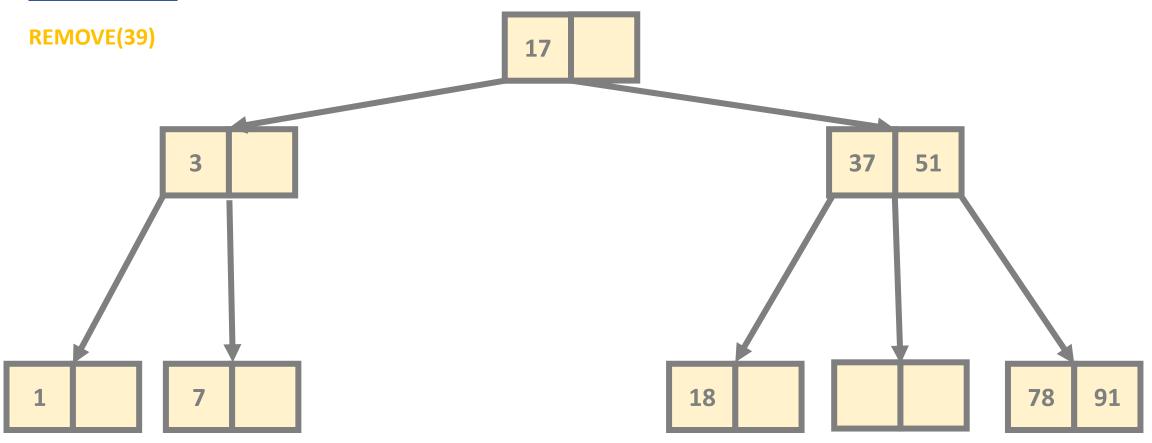


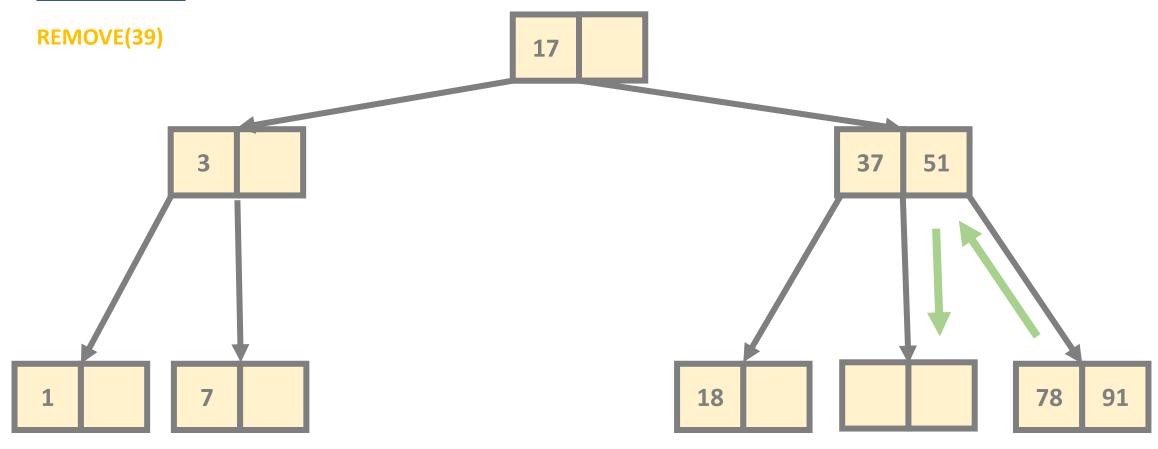


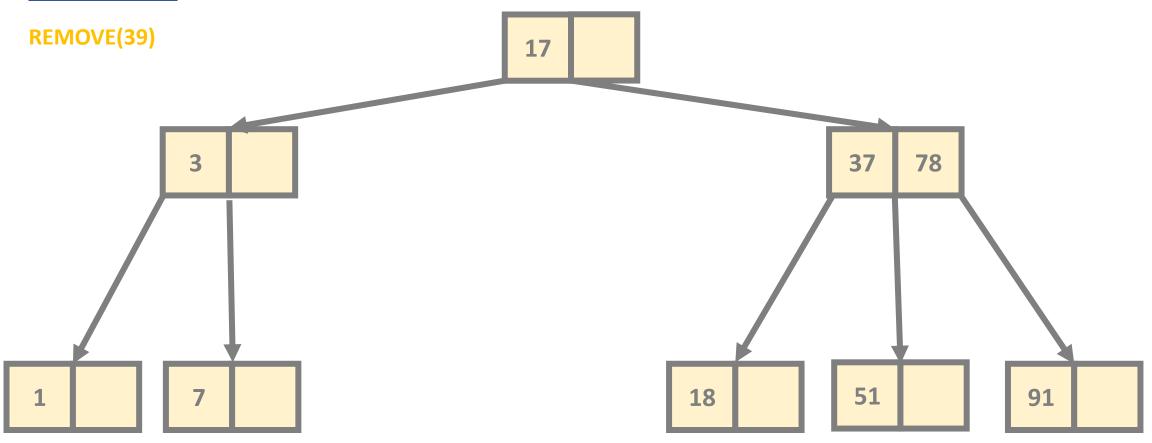


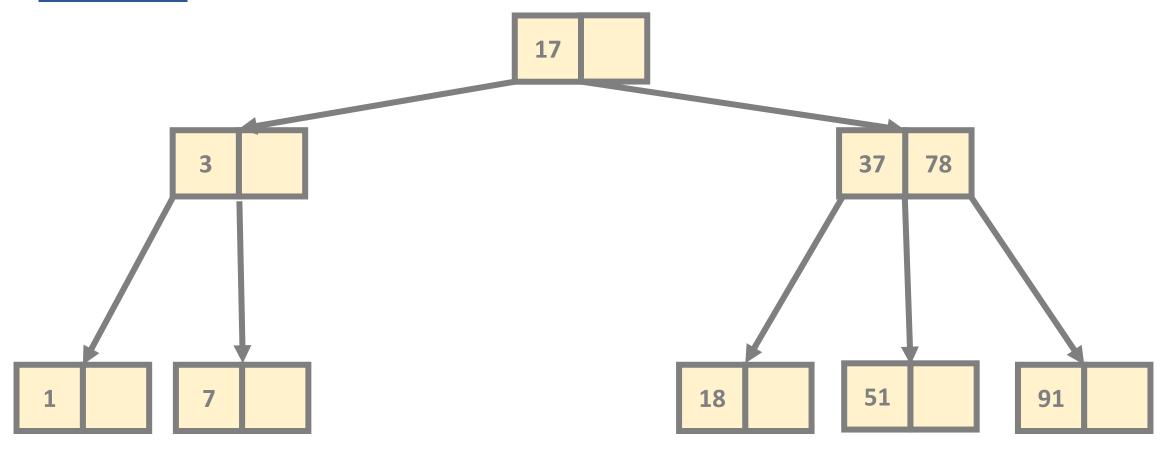










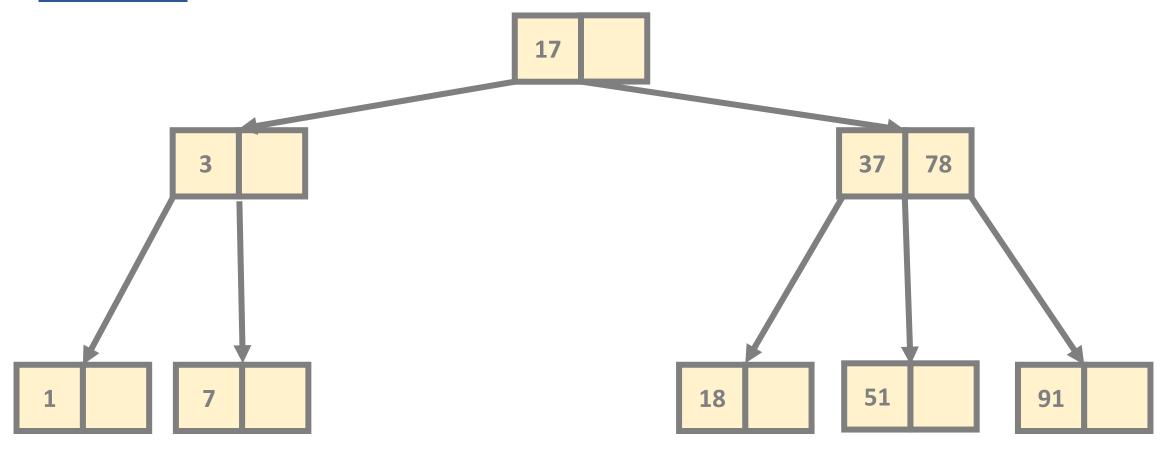


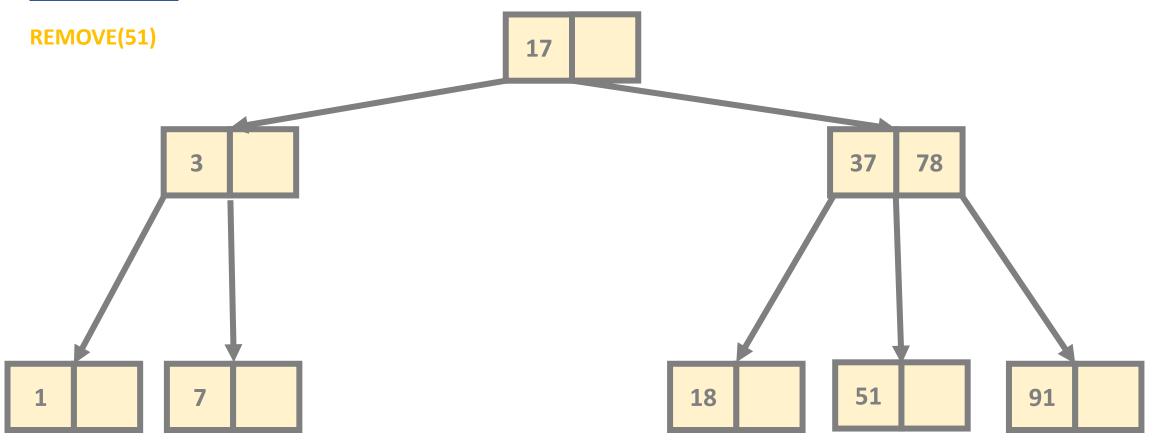
B-Tree Removal

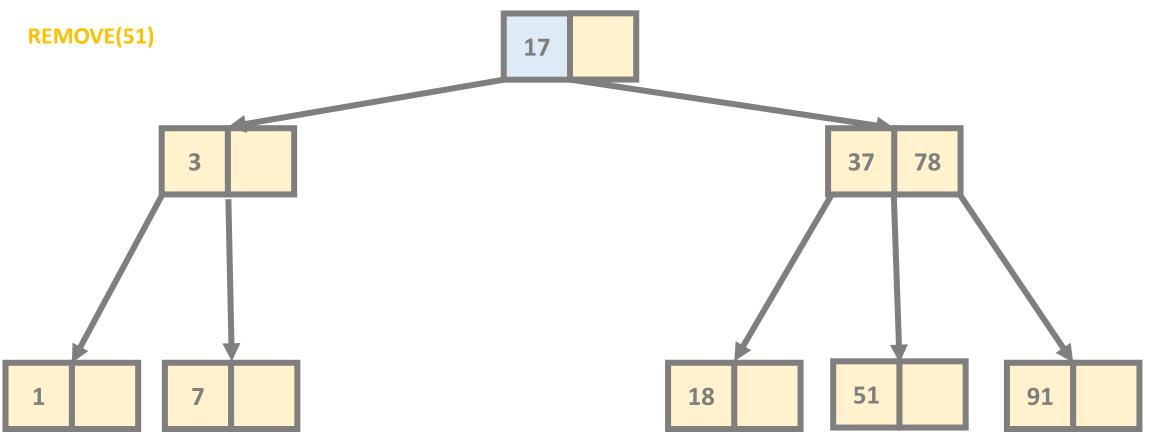
4.) REMOVING A INTERNAL ITEM

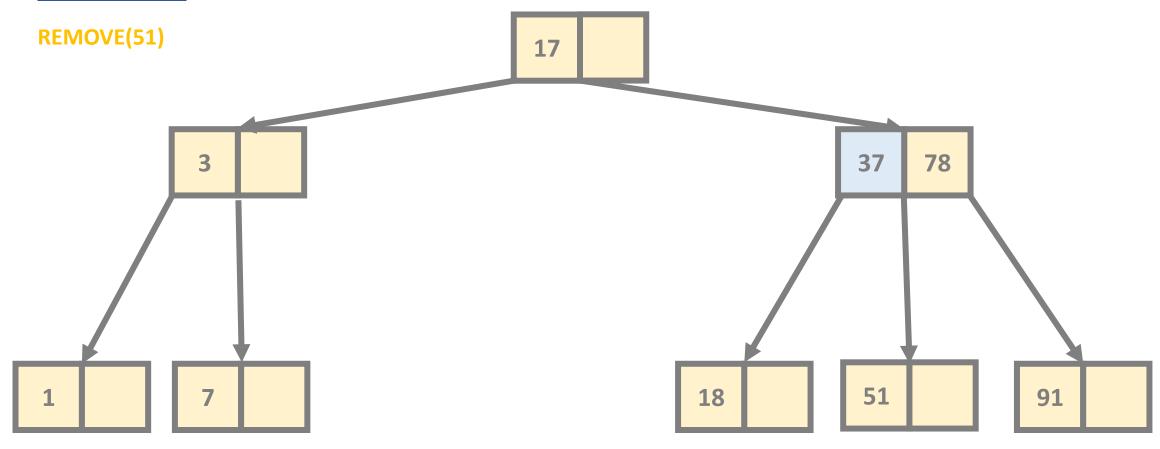
We remove an item from the node and the **B-tree properties are violated** as there will be less than $\frac{m}{2}$ items in the given node

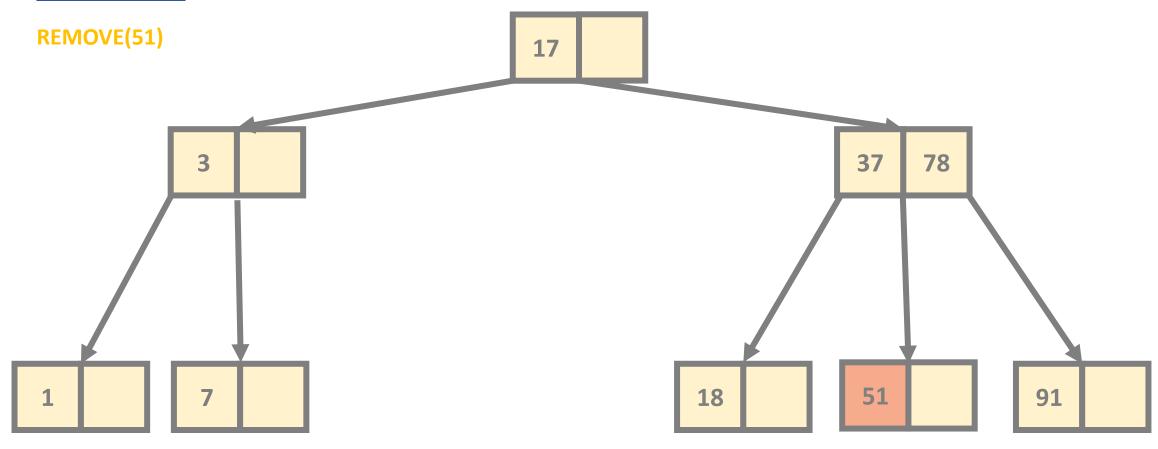
THERE IS NO ADDITIONAL ITEMS IN THE SIBLINGS SO
WE HAVE NO OTHER OPTION BUT TO MERGE NODES !!!

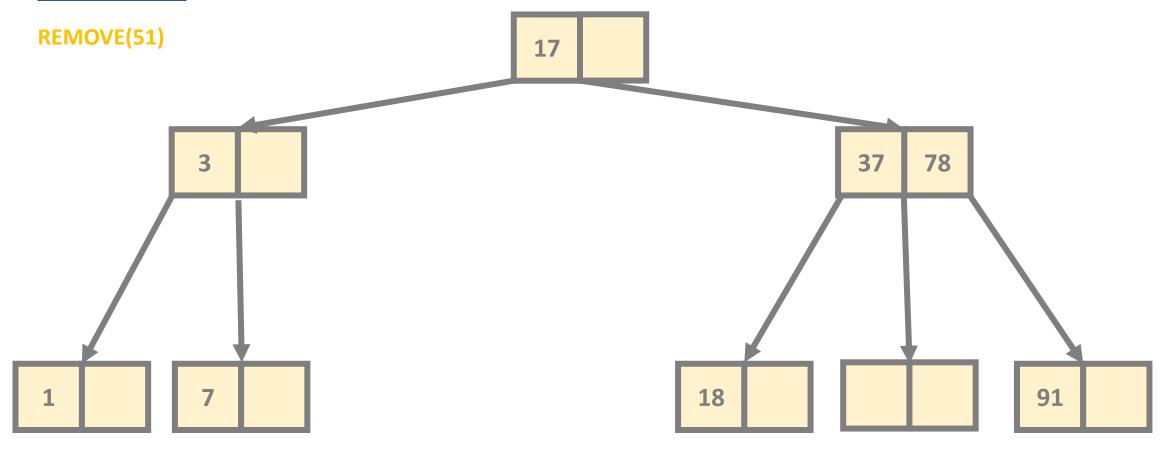


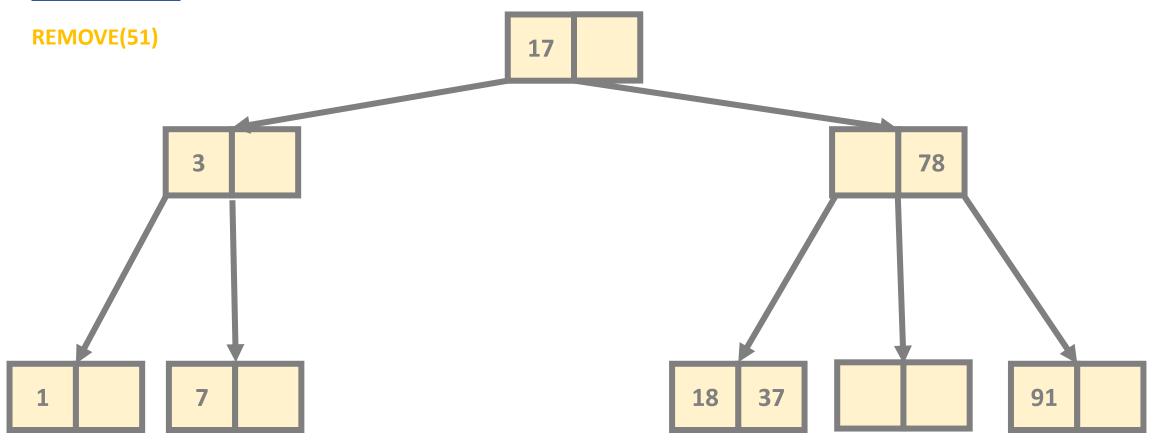


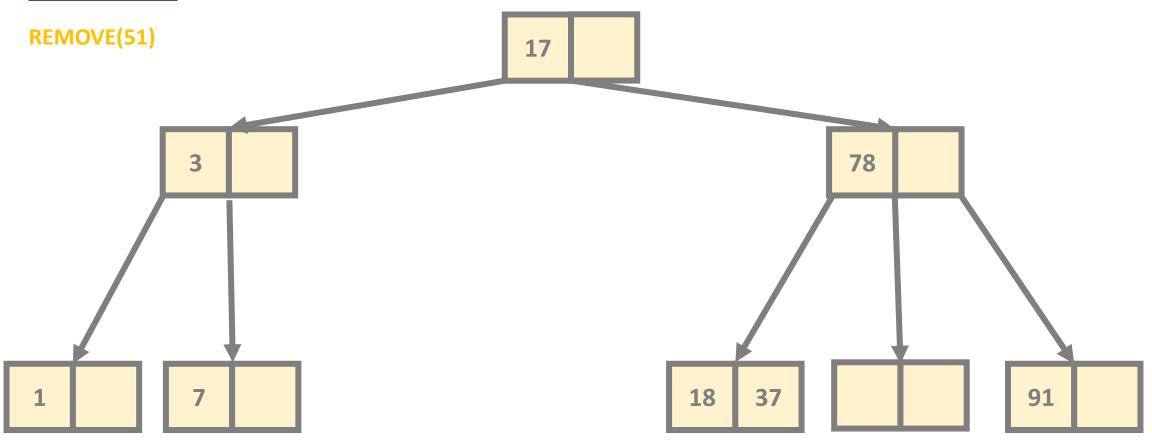


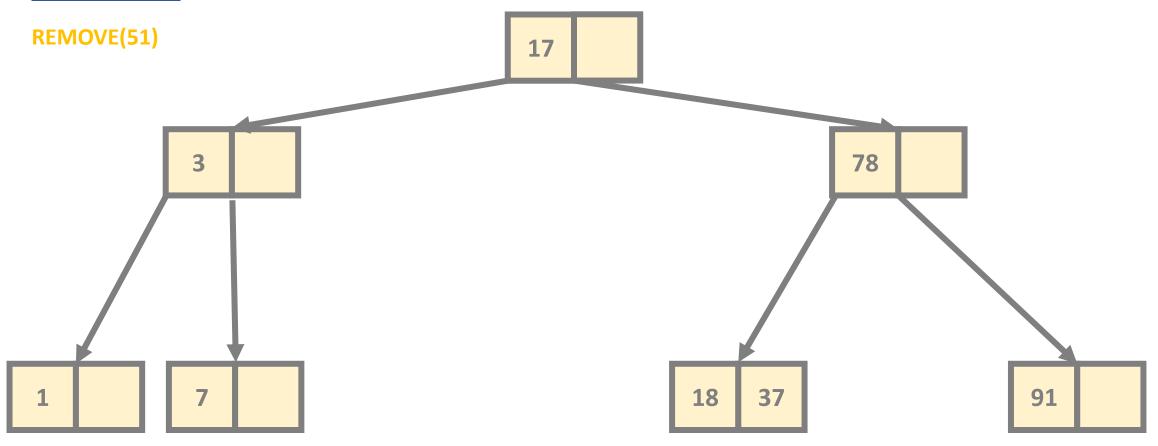


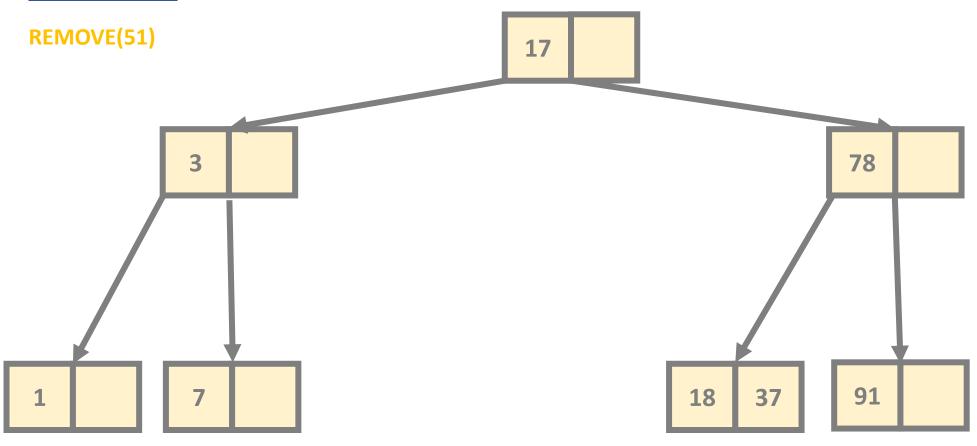












B-Tree Variants (Algorithms and Data Structures)

B-Trees Advantages and Disadvantages

- there are several advantages of B-trees
- there is a guaranteed O(logN) logarithmic running time
- BUT THERE MAY BE SEVERAL EMPTY CELLS
- we can decrease the h height of the B-tree
- this is why better variants came to be

B* Trees

- B* trees keep each node at least $\frac{2}{3}$ full instead of just $\frac{1}{2}$ by redistributing keys until 2 child nodes are full
- then splitting the **2** full nodes into **3** nodes each $\frac{2}{3}$ full
- as a result nodes are generally fuller and trees are more shallow which means faster searches
- data can be shared between siblings or neighboring nodes this is why the implementation is quite complex

B+ Trees

- it is the original B-tree like tree structure
- but the **leaf nodes are connected** with references (pointers) in a linked list manner
- the primary value of a B+ tree is in storing data for efficient retrieval in a block-oriented storage context like file systems
- almost every operating system (*MacOS*, *Linux* or *Windows*) rely heavily on **B+ trees**
- NTFS file system is first constructed at Microsoft
- APFS (Apple File System) is the file system of MacOS