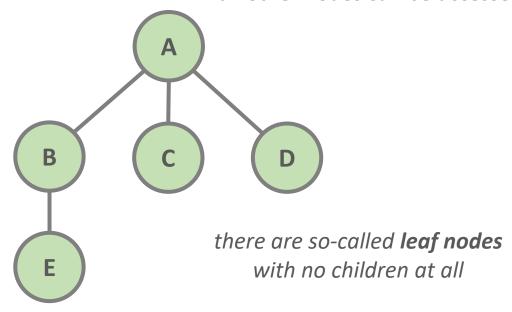
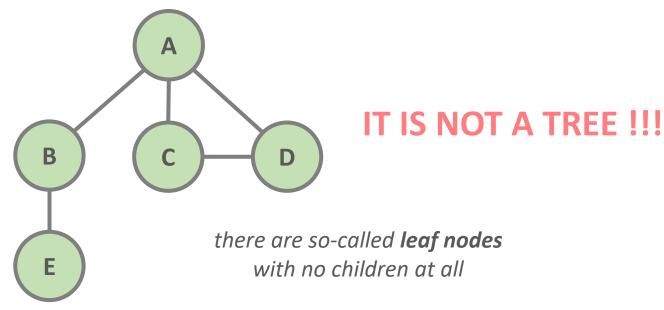
Binary Search Trees (Algorithms and Data Structures)

- arrays can manipulate the last item in **O(1)** constant running time complexity that is quite fast
- linked lists can manipulate the first item of the data structure fast
- searching for an arbitrary item takes **O(N)** linear running time for both data structures
- WHAT IF THE ARRAY DATA STRUCTURE IS SORTED?
- we can seach for arbitrary item in O(logN) logaritmic time complexity
- this is the concept behind binary search

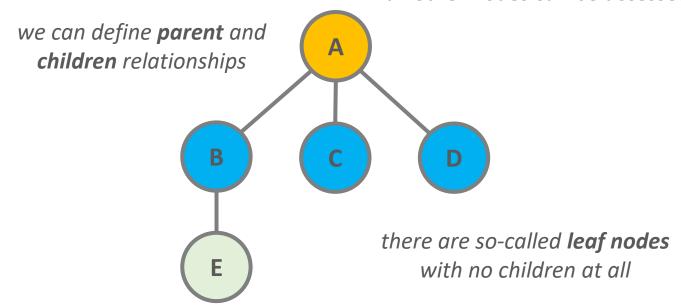
we have access to the **root node** exclusively all other nodes can be accessed via the root node



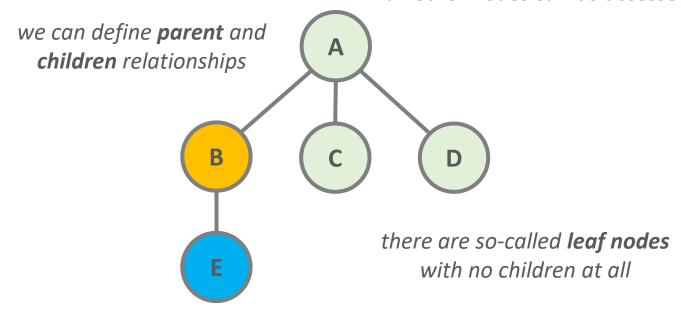
we have access to the **root node** exclusively all other nodes can be accessed via the root node

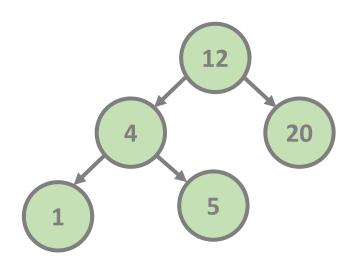


we have access to the **root node** exclusively all other nodes can be accessed via the root node

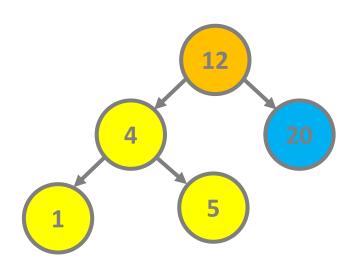


we have access to the **root node** exclusively all other nodes can be accessed via the root node

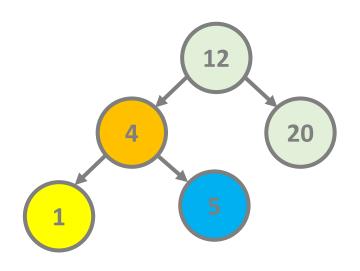




- every node in the tree can have at most 2 children (left child and right child)
- left child is smaller than the parent node
- right child is greater than the parent node
- we can access the root node exclusively and all other nodes can be accessed via the root node

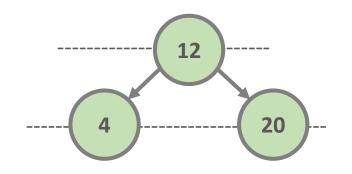


- every node in the tree can have at most 2 children (left child and right child)
- left child is smaller than the parent node
- right child is greater than the parent node
- we can access the root node exclusively and all other nodes can be accessed via the root node



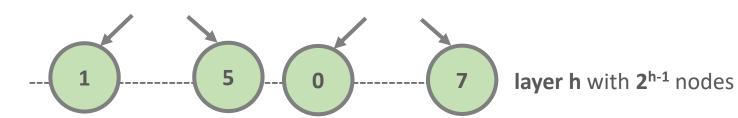
- every node in the tree can have at most 2 children (left child and right child)
- left child is smaller than the parent node
- right child is greater than the parent node
- we can access the root node exclusively and all other nodes can be accessed via the root node

EVERY DECISION CAN GET RID OF HALF OF THE DATA (LIKE WITH BINARY SEARCH)
AND THIS IS HOW WE CAN ACHIEVE O(logN) RUNNING TIME

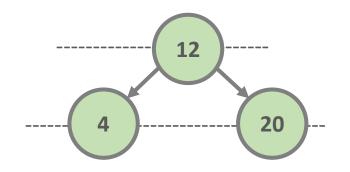


layer 1 with 20 nodes

layer 2 with 2¹ nodes



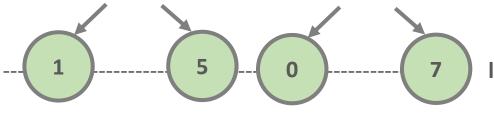
The **height of a tree** is the number of edges on the longest downward path between the **root** and a **leaf node**. The number of layers the tree contains.



layer 1 with 20 nodes

layer 2 with 21 nodes

• • •

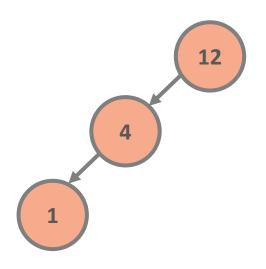


layer h with 2^{h-1} nodes

how many **N** nodes are there in a complete binary search tree with **h** height?

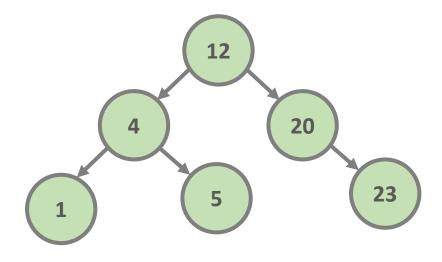
$$2^{h-1} = N$$
 $log_2 2^{h-1} = log_2 N$
 $h = log_2 N + 1$
 $h = O(log N)$

- the logarithmic O(logN) running time is valid only when the tree structure is balanced
- we should keep the height of a tree at a minimum which is h=logN
- the tree structure may became **imbalanced** which means the number of nodes significantly differ in the subtrees
- if the tree is imbalanced so the **h=logN** relation is no more valid then the operations' running time is no more **O(logN)** logarithmic



IMBALANCED TREE

in an **imbalanced tree** the running time of operations can be reduced to even **O(N)** linear Running time complexity



BALANCED TREE

in a **balanced tree** the running time of operations are **O(logN)** always

- binary search trees are data structures so the aim is to be able to store items efficiently
- it keeps the keys in sorted order so that lookup and other operations can use the principle of binary search with O(logN) running time
- each comparison allows the operations to skip over half of the tree, so that each operation takes time proportional to the logarithm of the number of items stored in the tree
- this is much better than **O(N)** the linear time required to find items by key in an unsorted array but slower than the corresponding operations on hash tables with **O(1)**

Binary Search Trees (Algorithms and Data Structures)

INSERT(12)

INSERT(12)





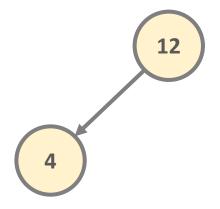
INSERT(4)

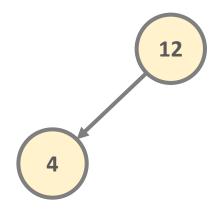


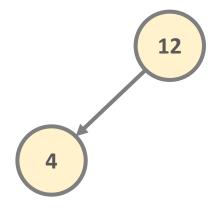
INSERT(4)

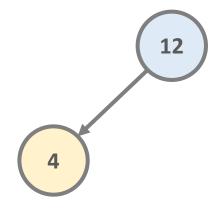


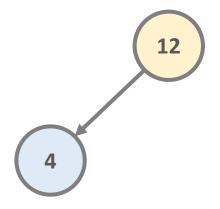
INSERT(4)

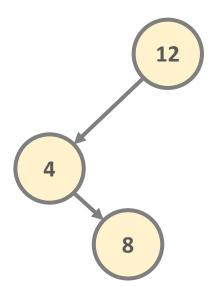


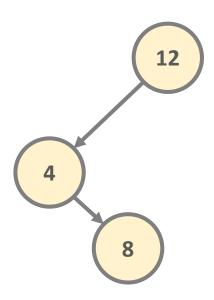




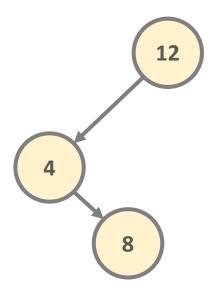




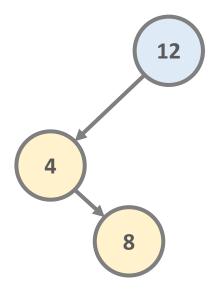




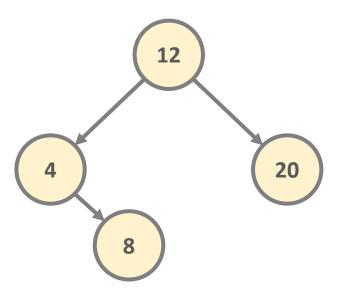
INSERT(20)

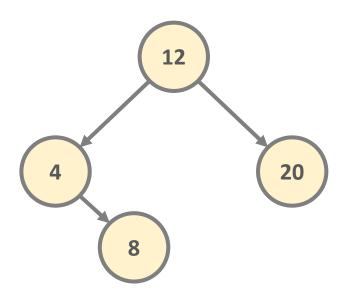


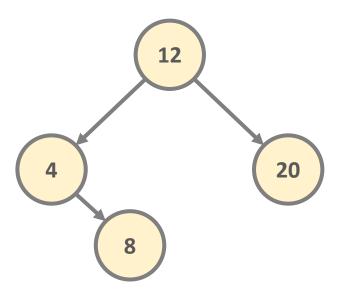
INSERT(20)

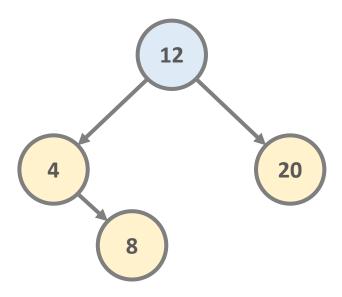


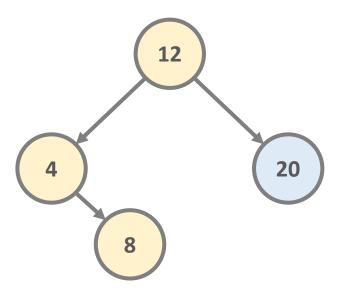
INSERT(20)

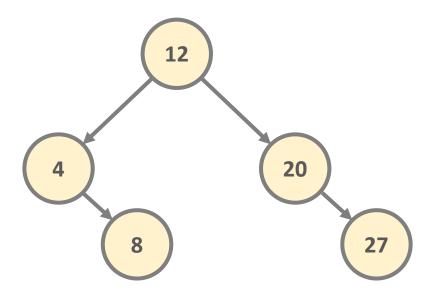


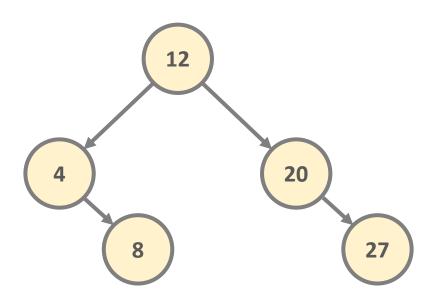


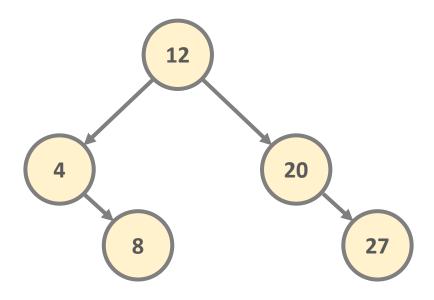


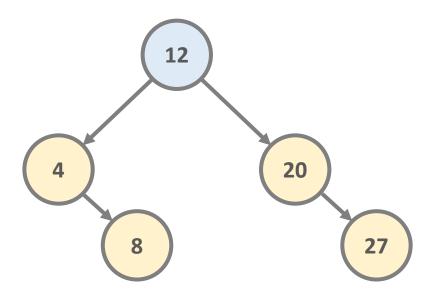


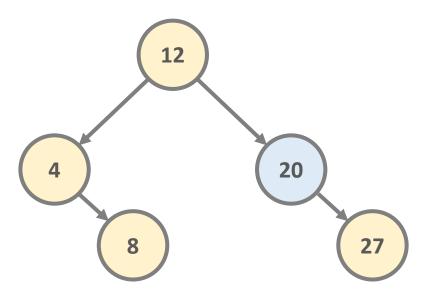


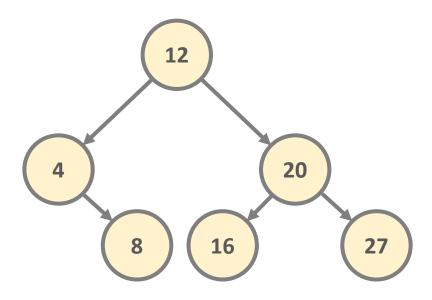


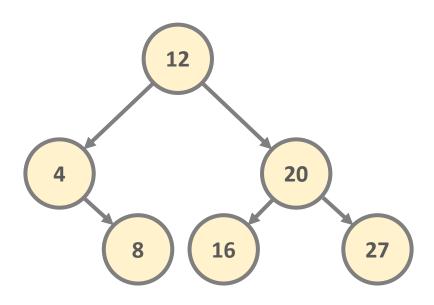


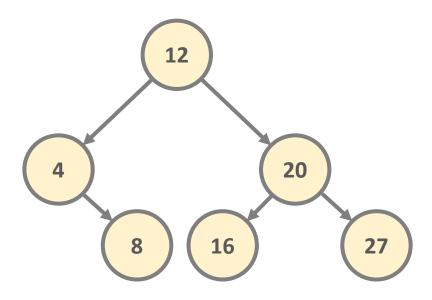


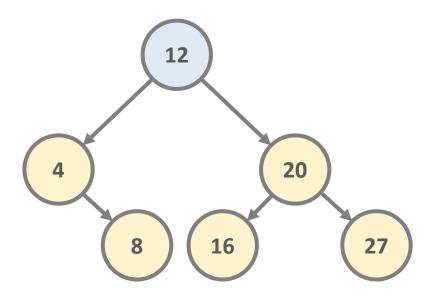


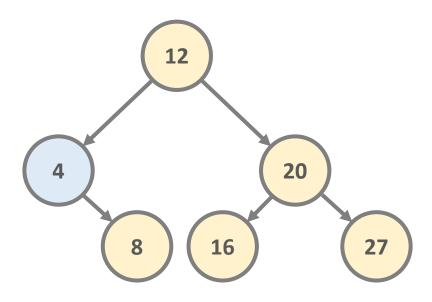


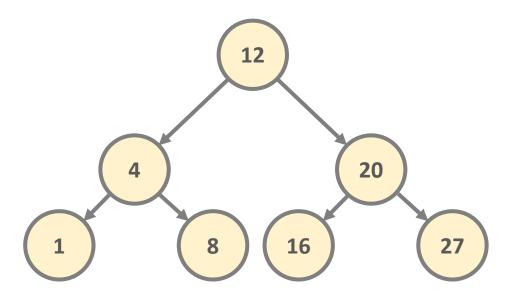


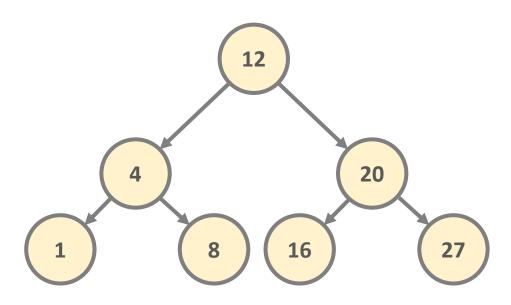


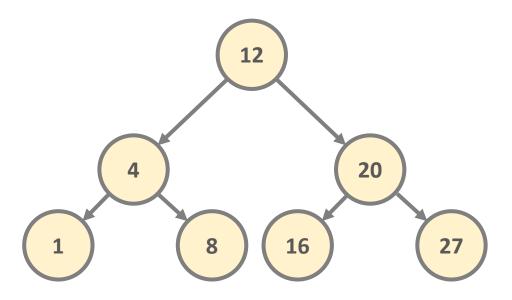


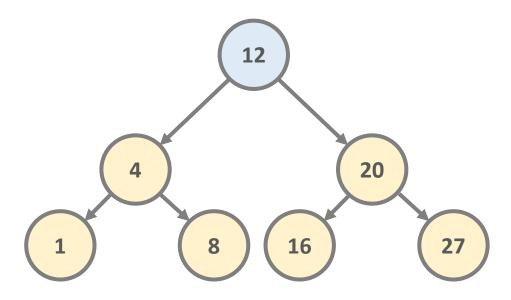


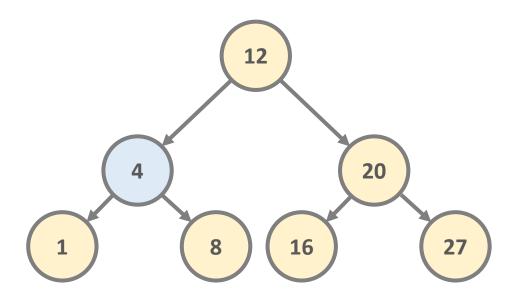


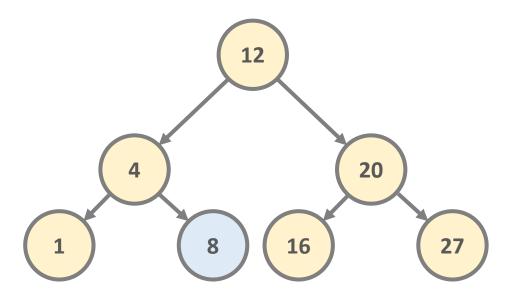


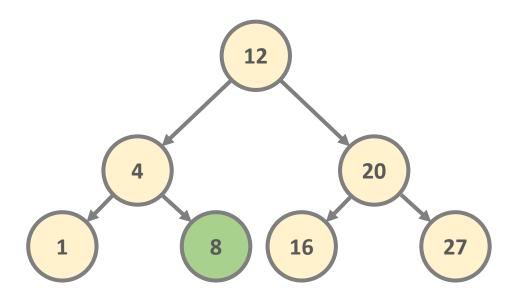


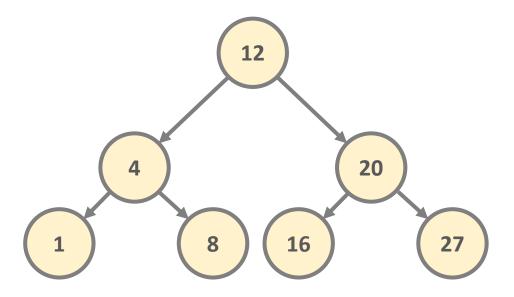


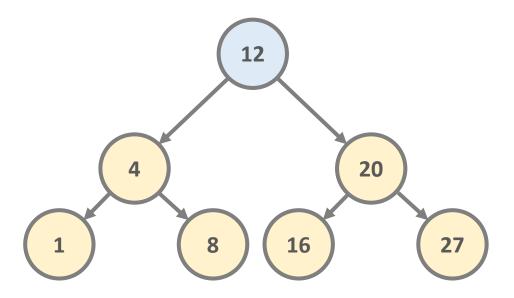


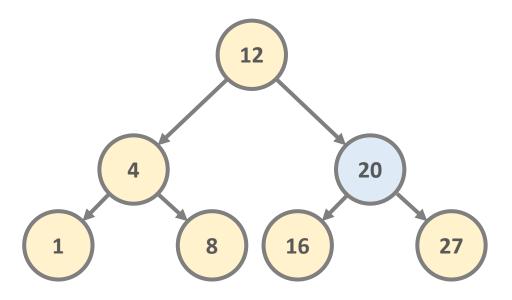


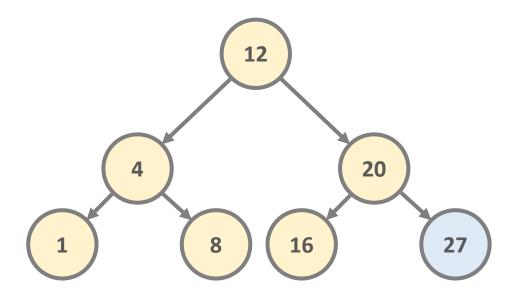


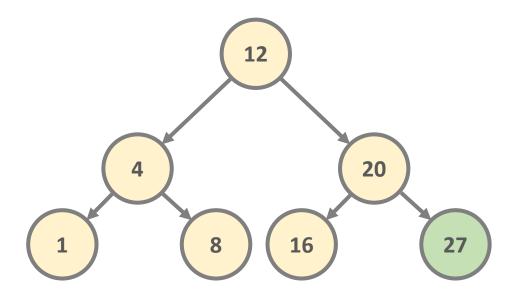




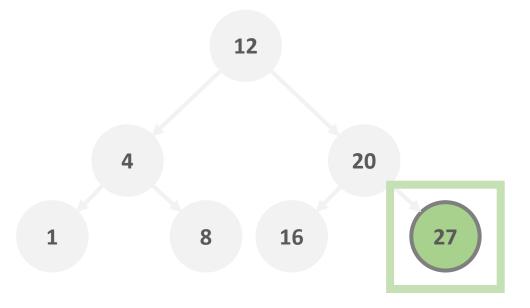




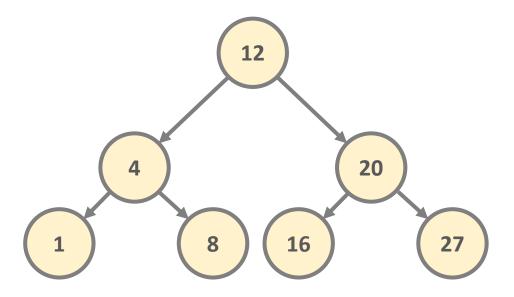


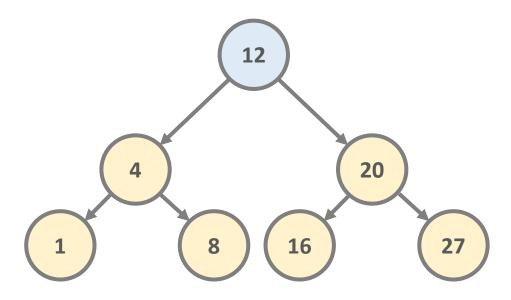


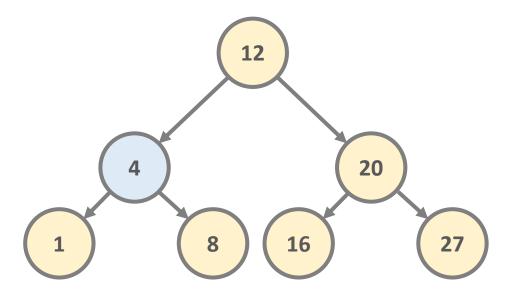
SEARCH MAX()

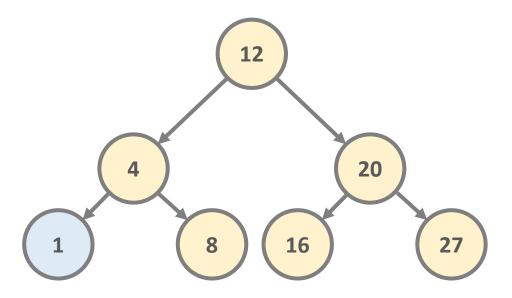


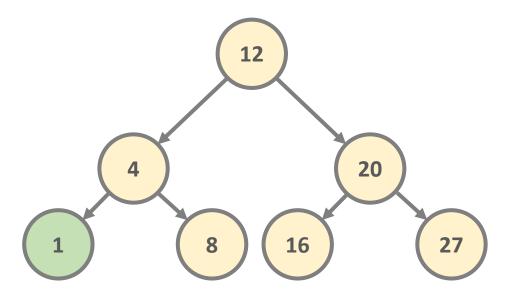
the **maximum** item in the binary search tree is the **rightmost** item in the tree



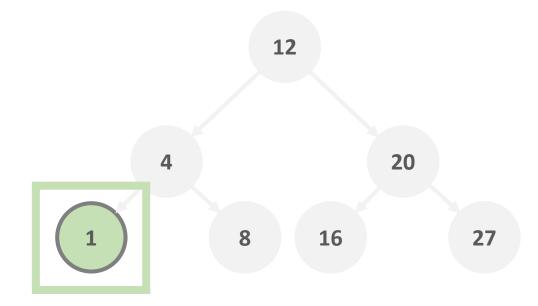






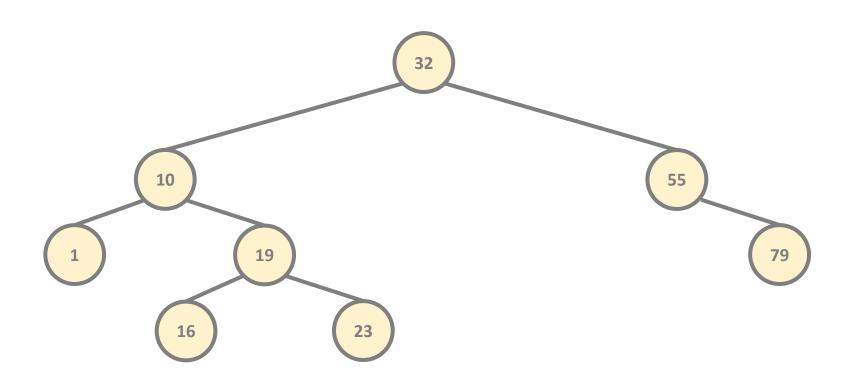


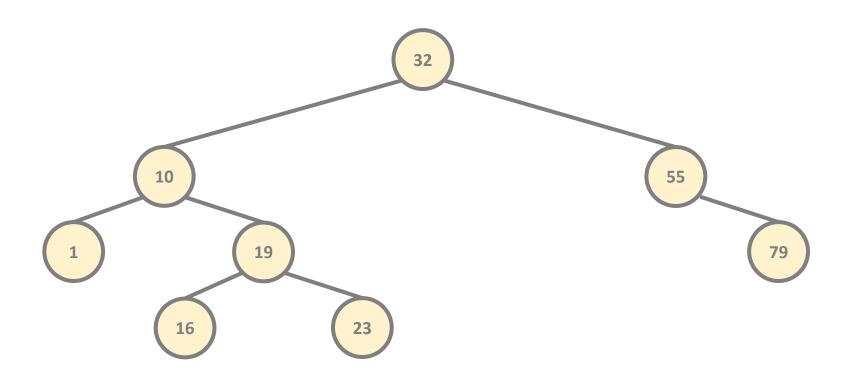
SEARCH MIN()

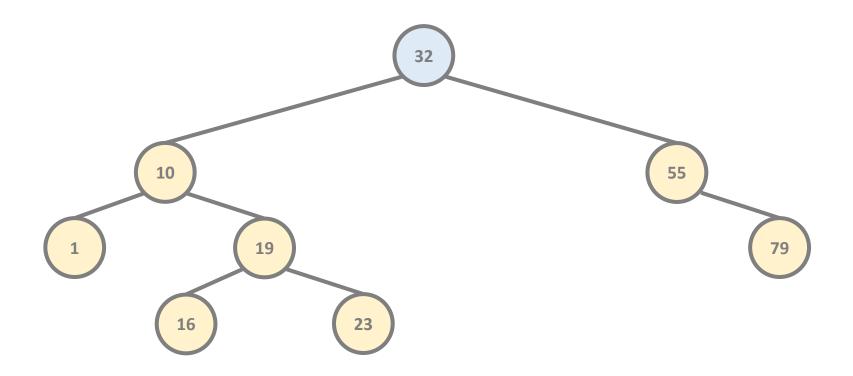


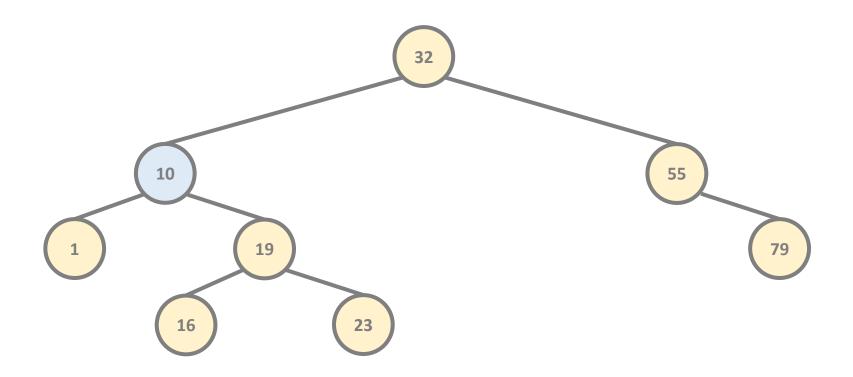
the **minimum** item in the binary search tree is the **leftmost** item in the tree

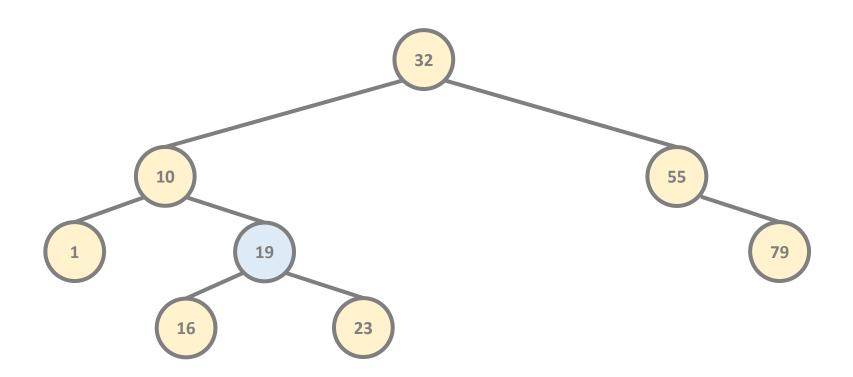
Binary Search Trees (Algorithms and Data Structures)

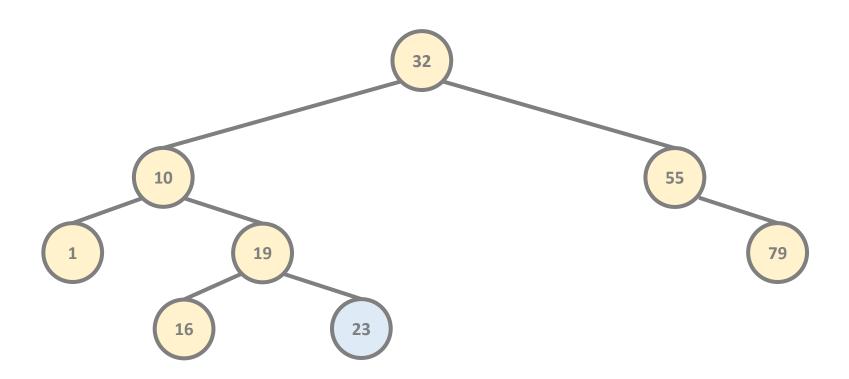




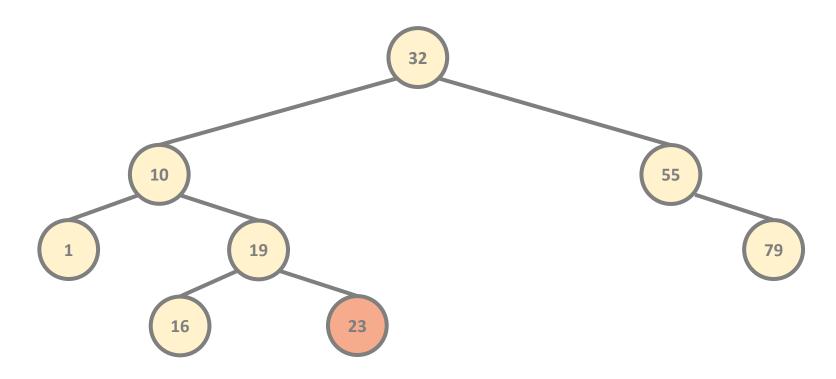




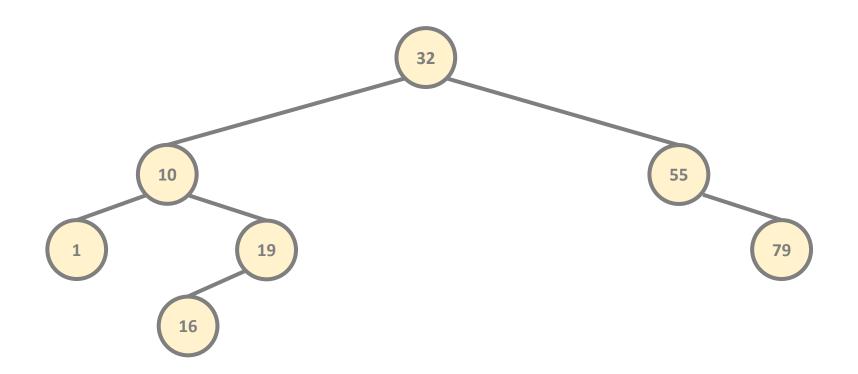


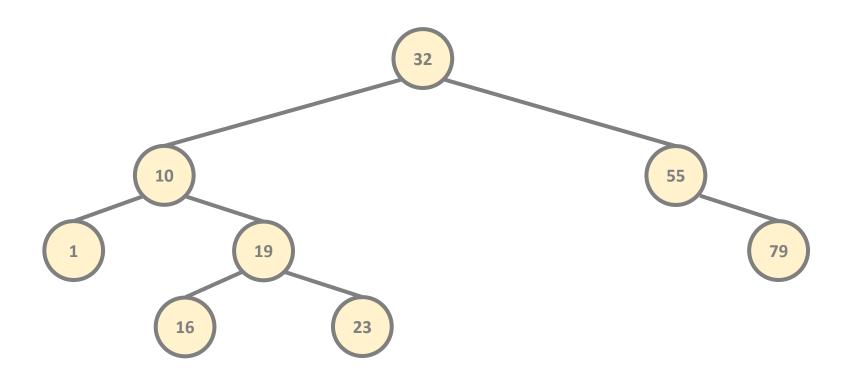


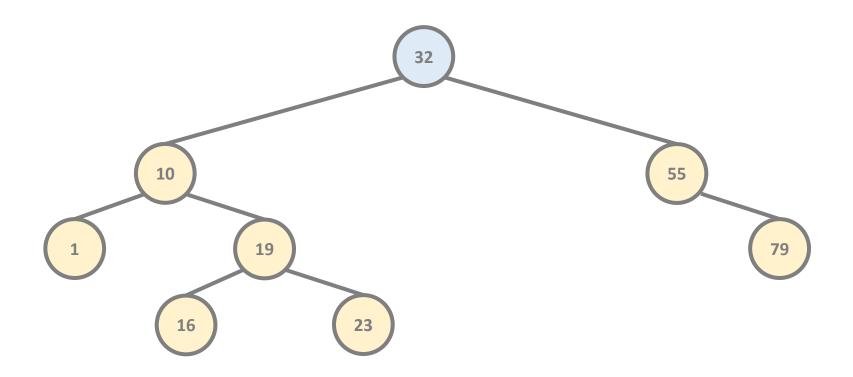
1.) REMOVING A LEAF NODE

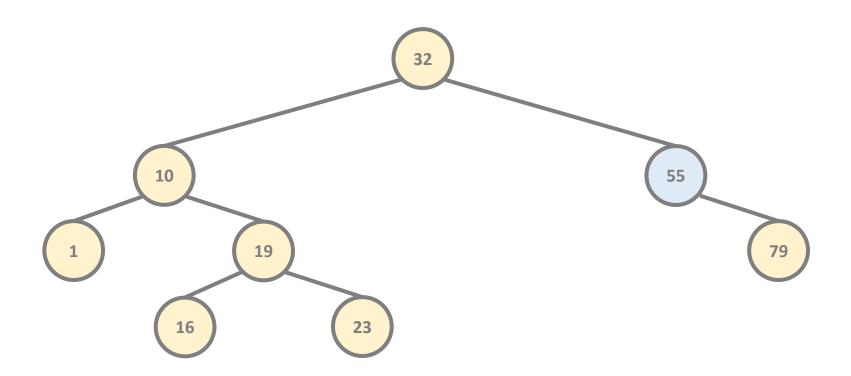


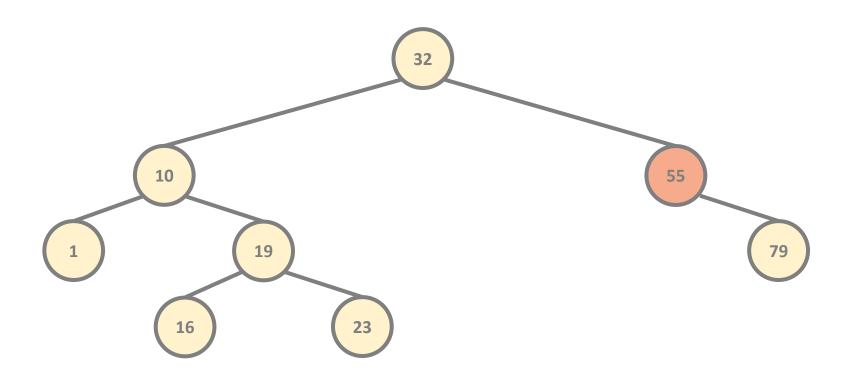
basically we just have to notify the parent that the child has been removed - the node will be removed by the **garbage collector** -

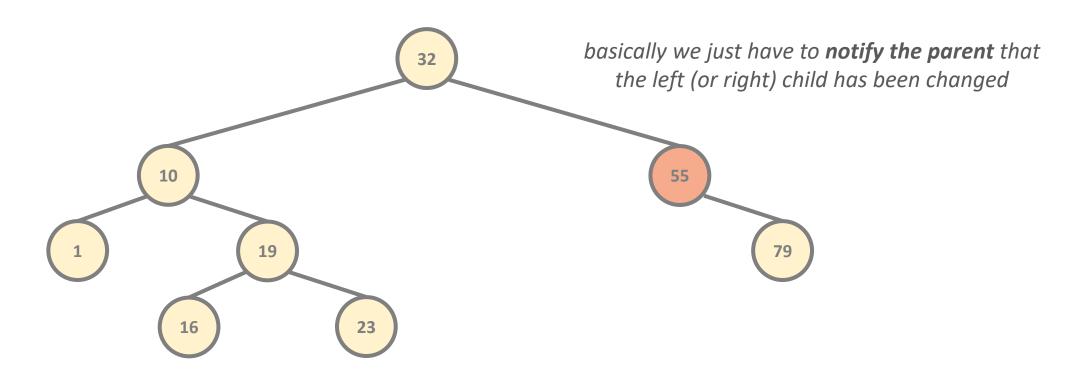


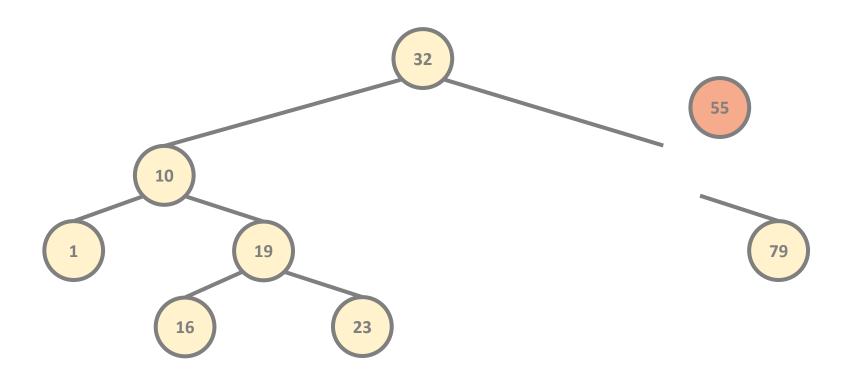


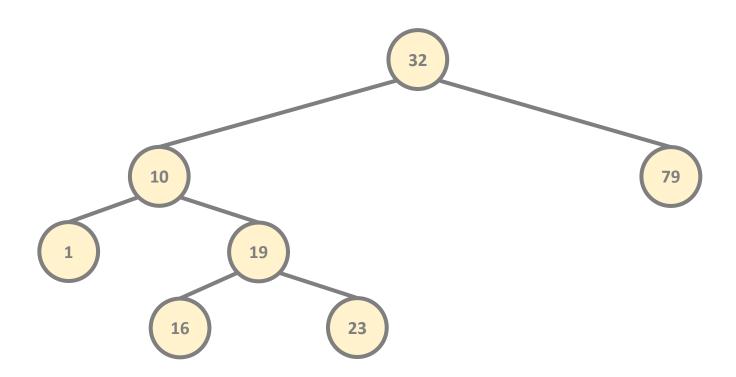


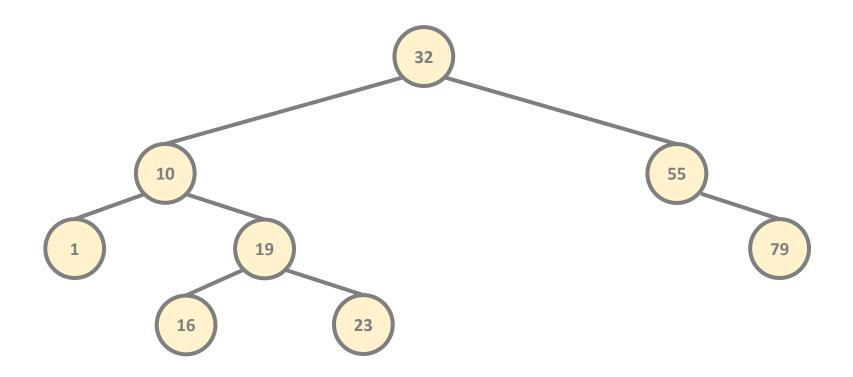


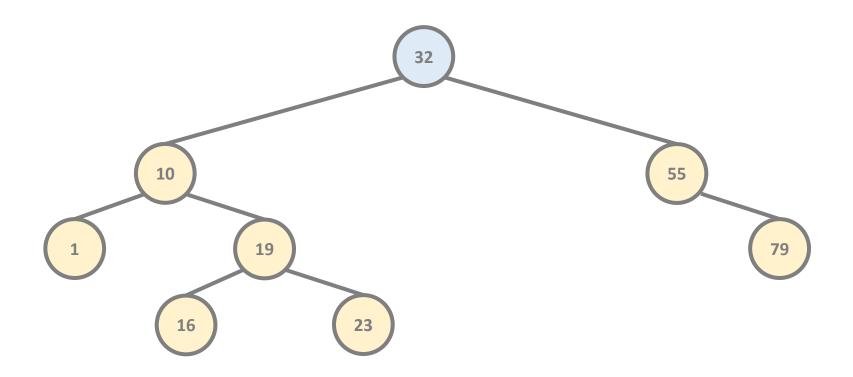


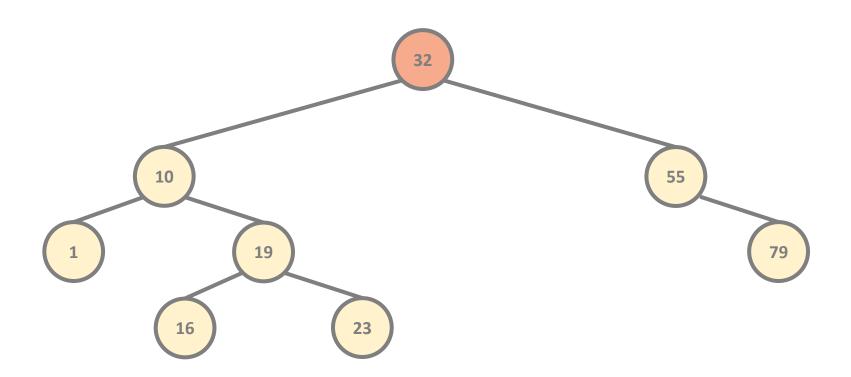


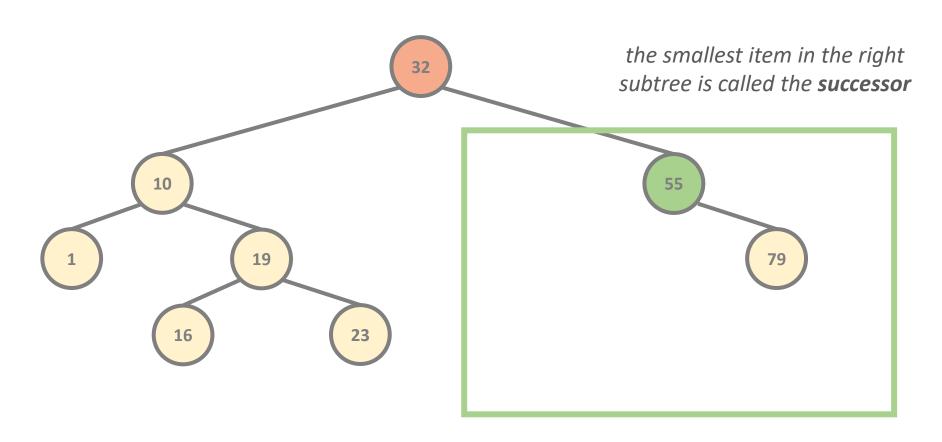


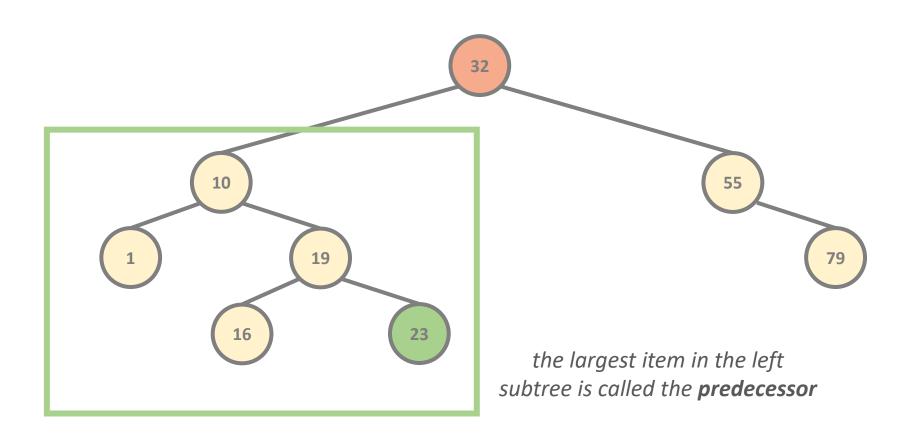


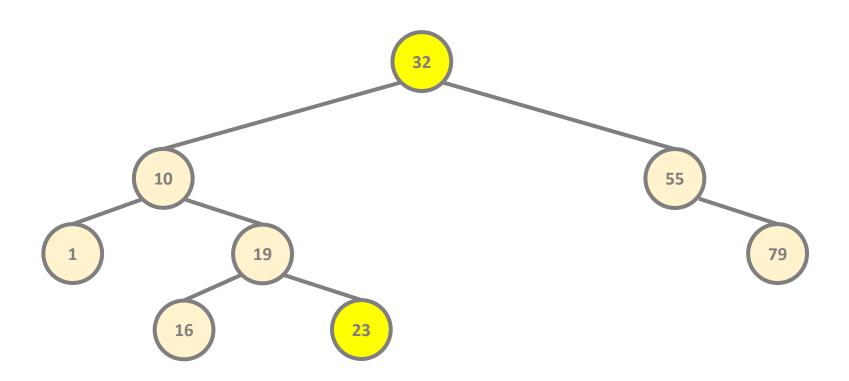




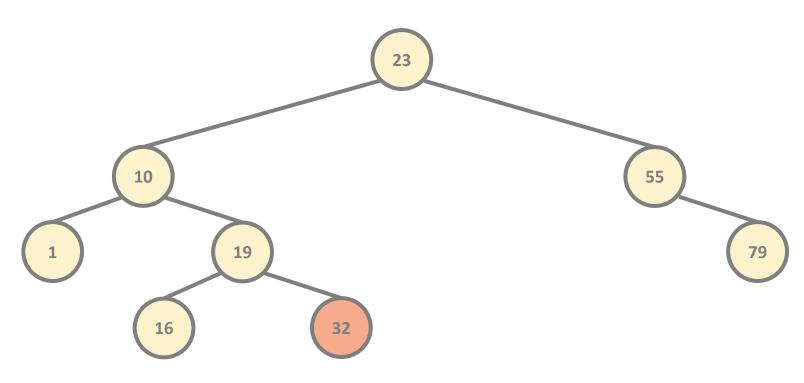




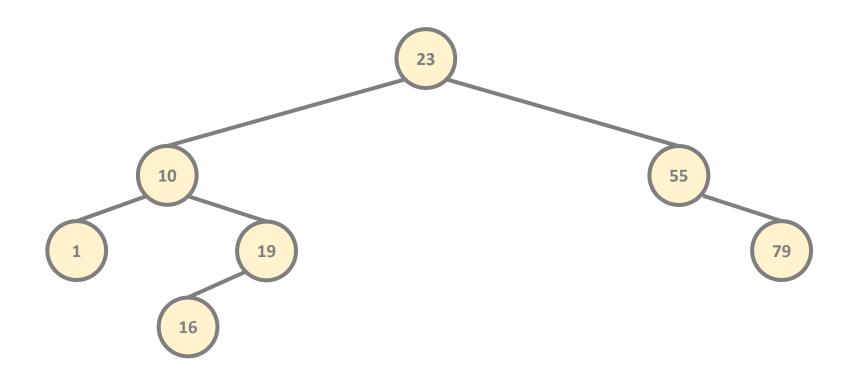




3.) REMOVING A NODE WITH TWO CHILDREN



we know how to deal with leaf nodes (mathematical reduction)



Binary Search Trees (Algorithms and Data Structures)

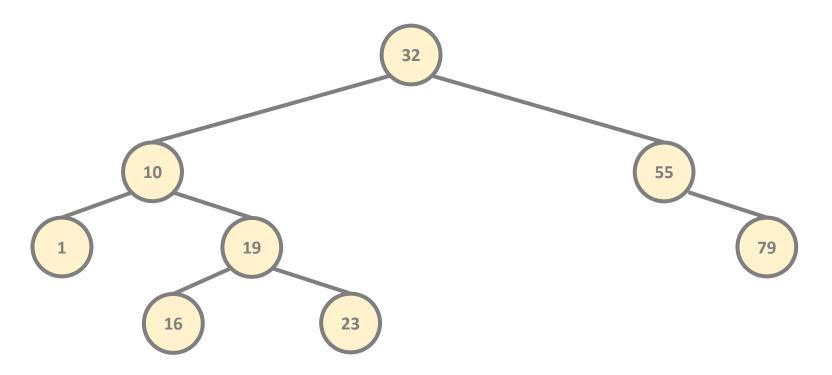
Tree traversal means visiting every node of the binary search tree exactly once in O(N) linear running time

1.) pre-order traversal

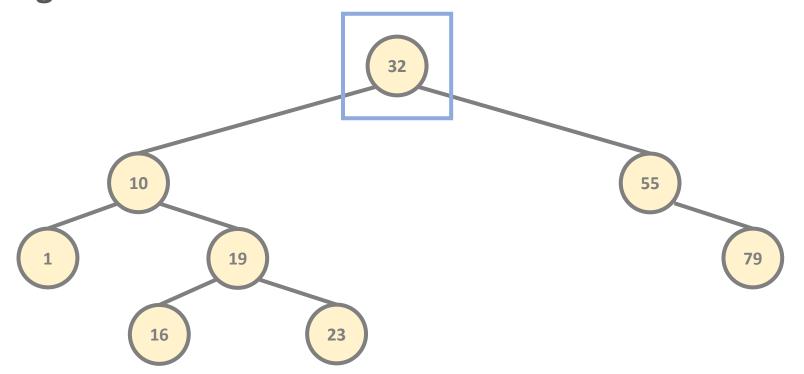
2.) in-order traversal

3.) post-order traversal

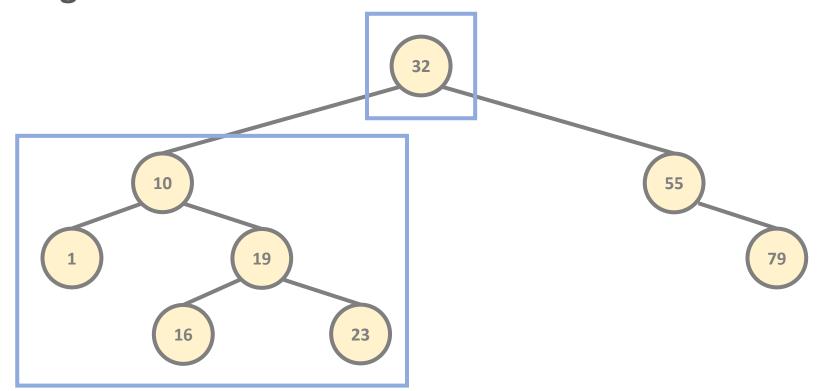
PRE-ORDER TRAVERSAL



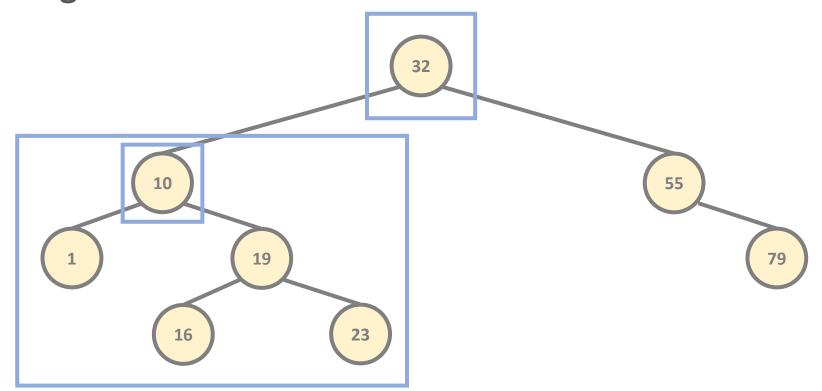
PRE-ORDER TRAVERSAL



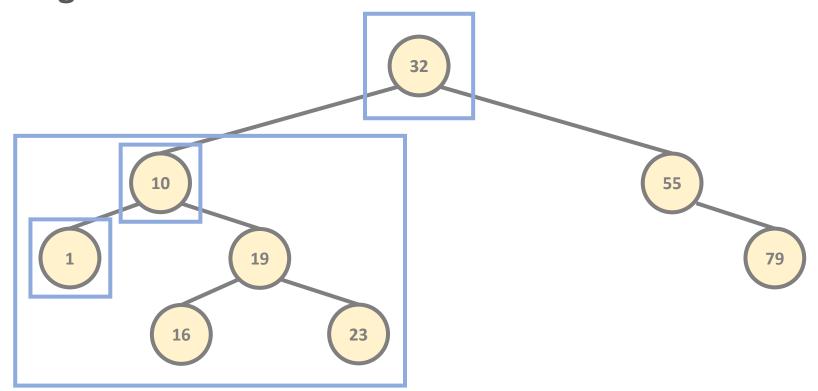
PRE-ORDER TRAVERSAL



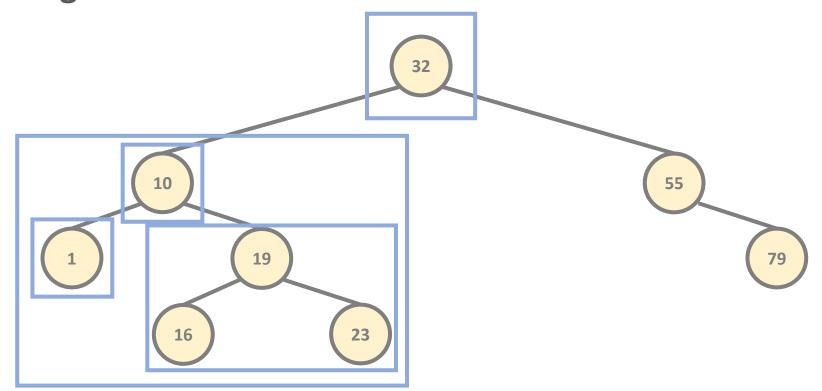
PRE-ORDER TRAVERSAL



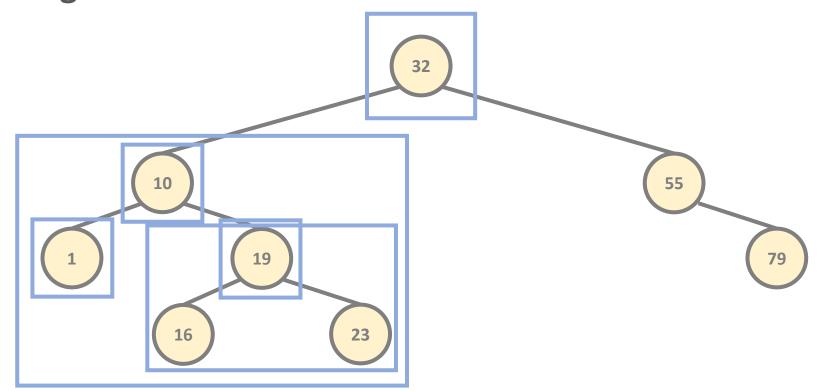
PRE-ORDER TRAVERSAL



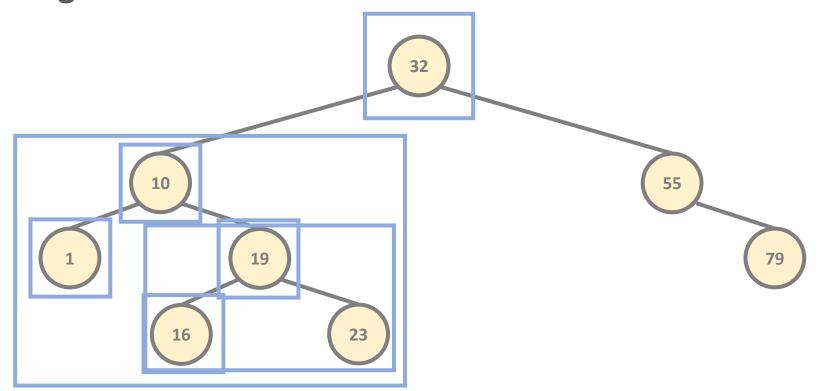
PRE-ORDER TRAVERSAL



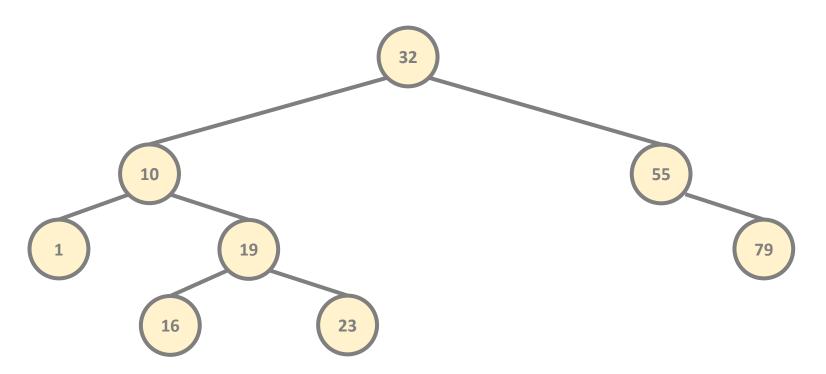
PRE-ORDER TRAVERSAL



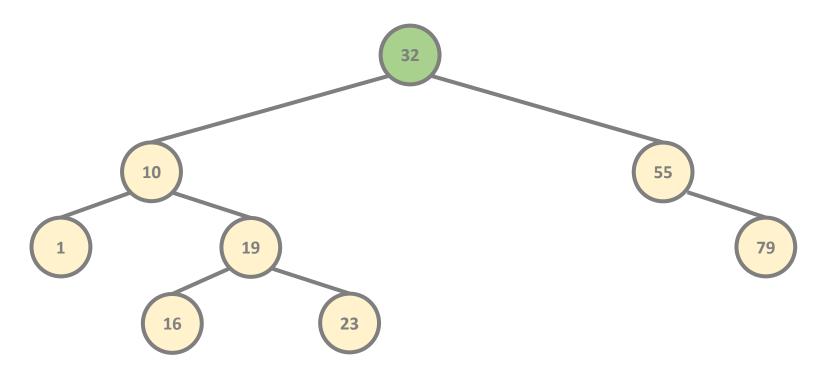
PRE-ORDER TRAVERSAL



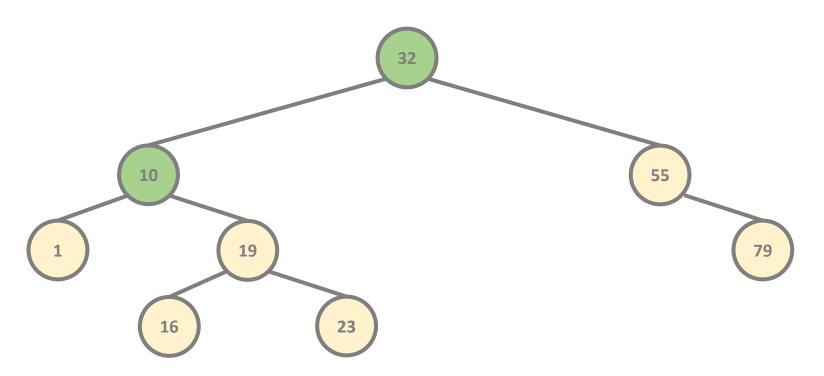
PRE-ORDER TRAVERSAL



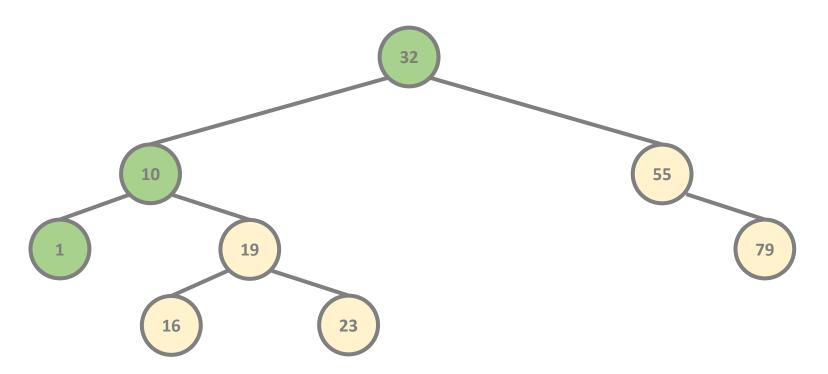
PRE-ORDER TRAVERSAL



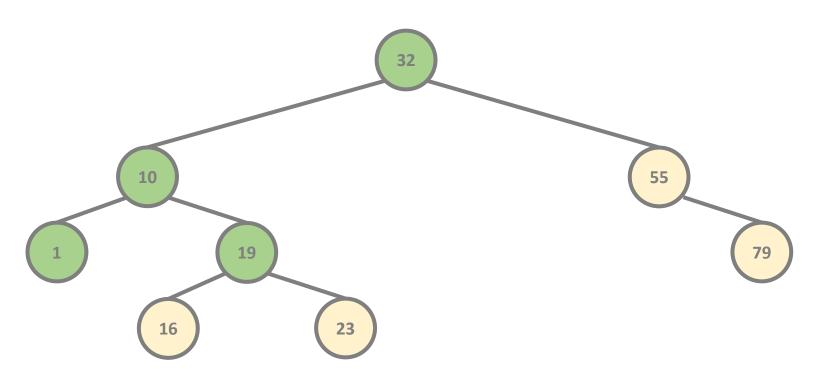
PRE-ORDER TRAVERSAL



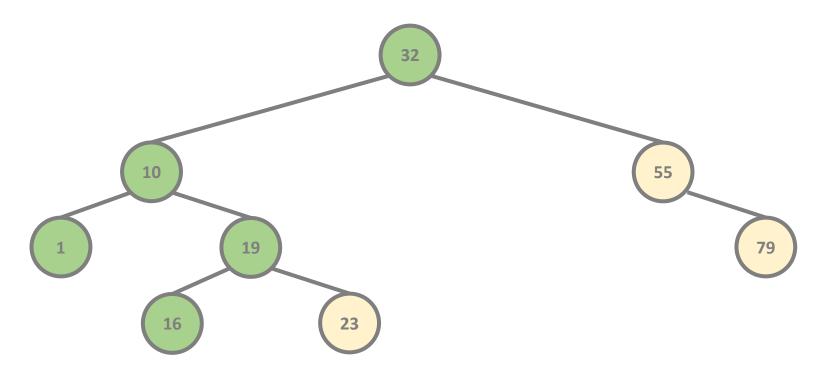
PRE-ORDER TRAVERSAL



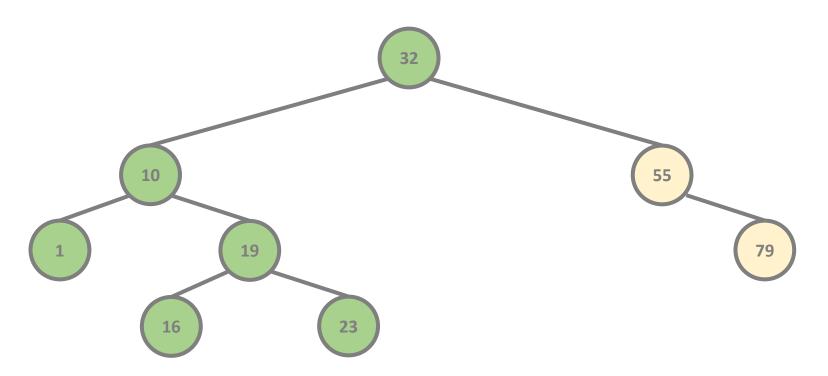
PRE-ORDER TRAVERSAL



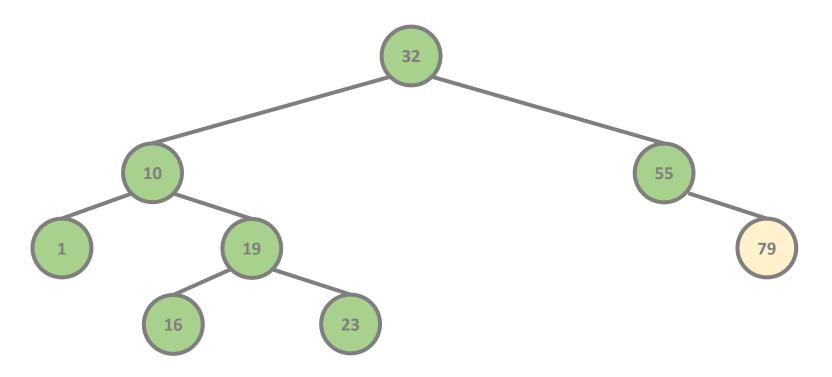
PRE-ORDER TRAVERSAL



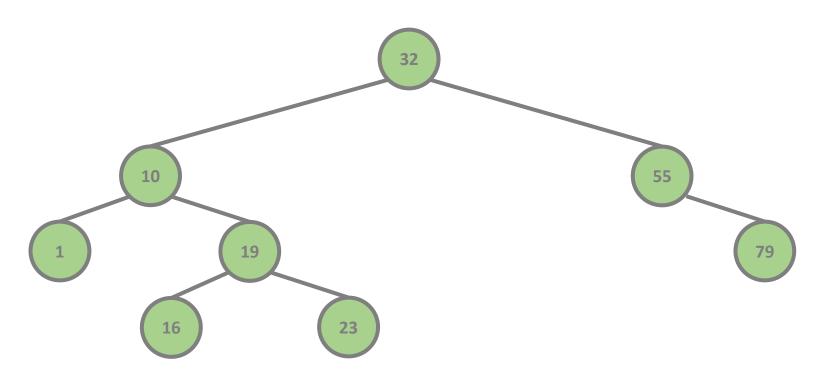
PRE-ORDER TRAVERSAL



PRE-ORDER TRAVERSAL

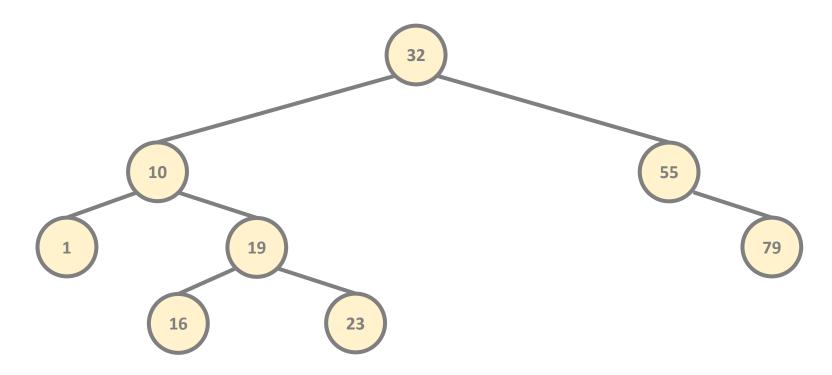


PRE-ORDER TRAVERSAL



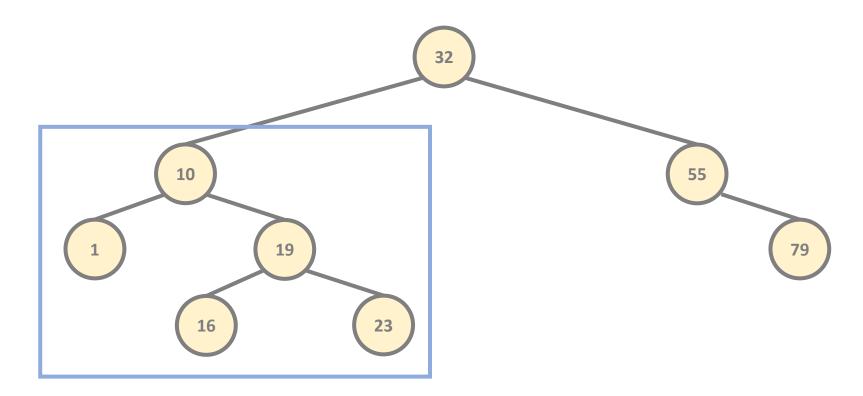
POST-ORDER TRAVERSAL

We visit the **left subtree** of the binary tree then the **right subtree** and finally the **root node** in a recursive manner

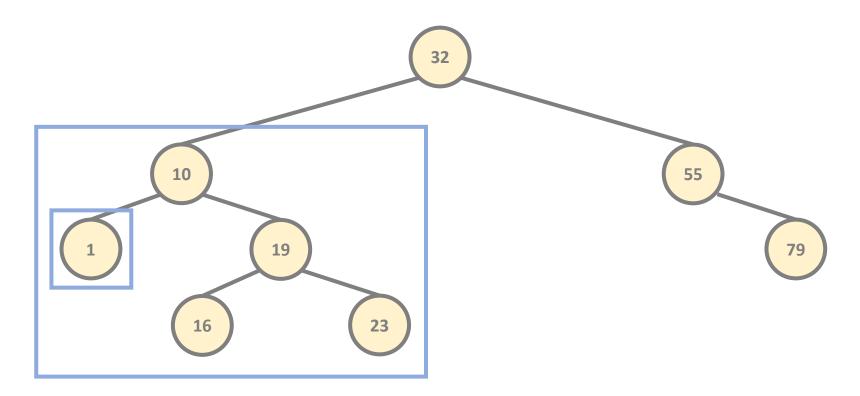


POST-ORDER TRAVERSAL

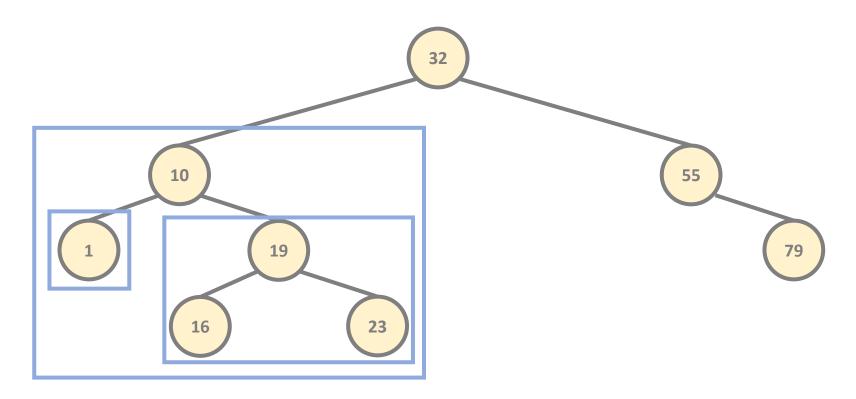
We visit the **left subtree** of the binary tree then the **right subtree** and finally the **root node** in a recursive manner



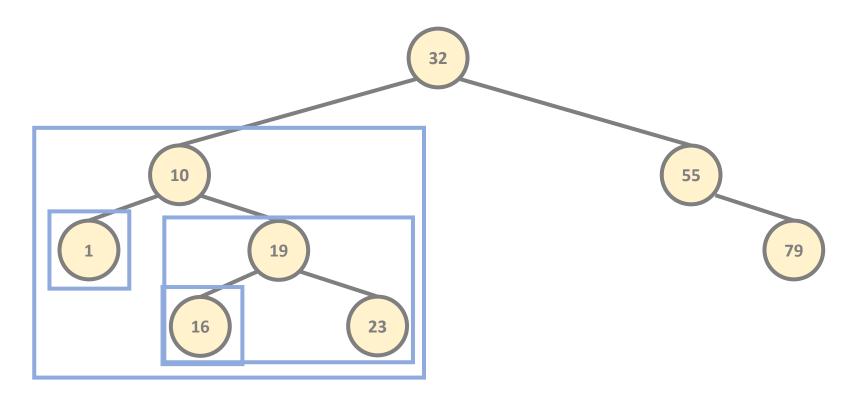
POST-ORDER TRAVERSAL



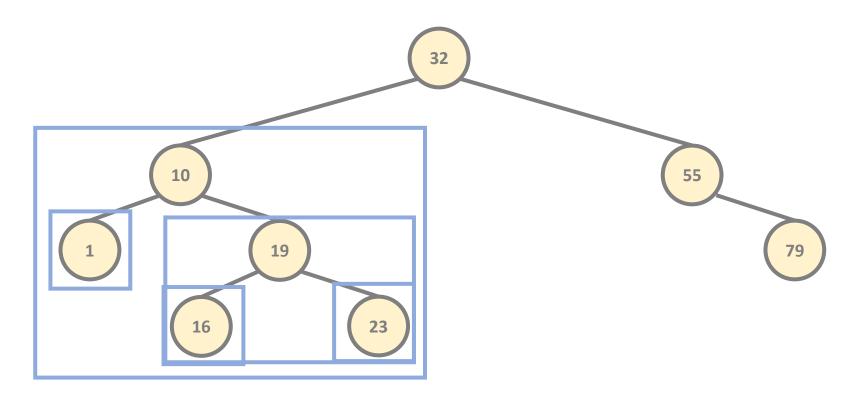
POST-ORDER TRAVERSAL



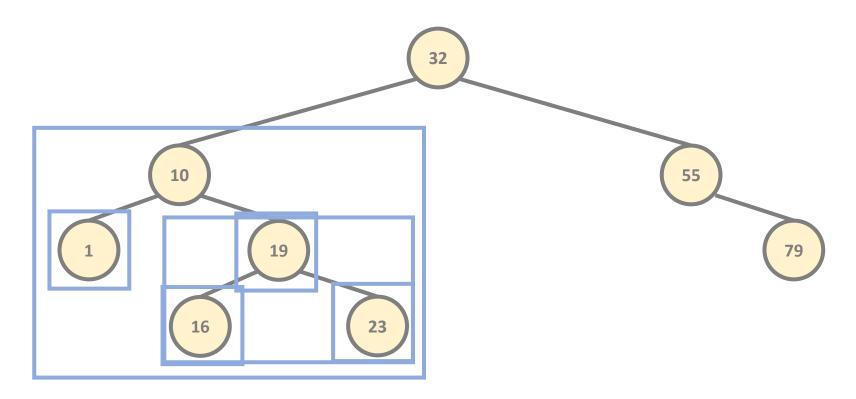
POST-ORDER TRAVERSAL



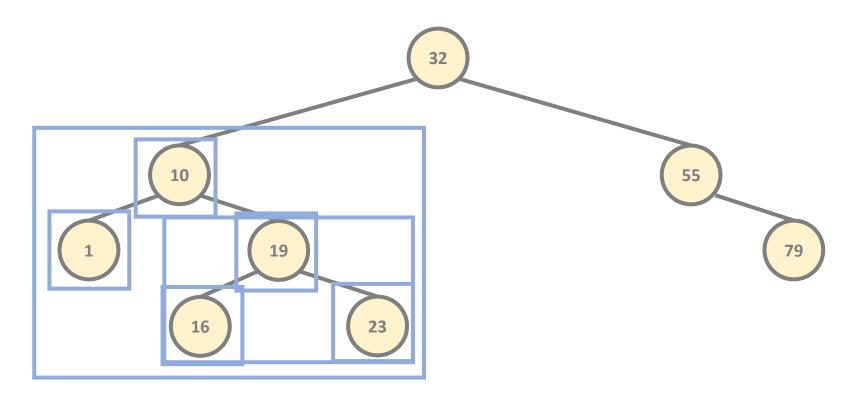
POST-ORDER TRAVERSAL



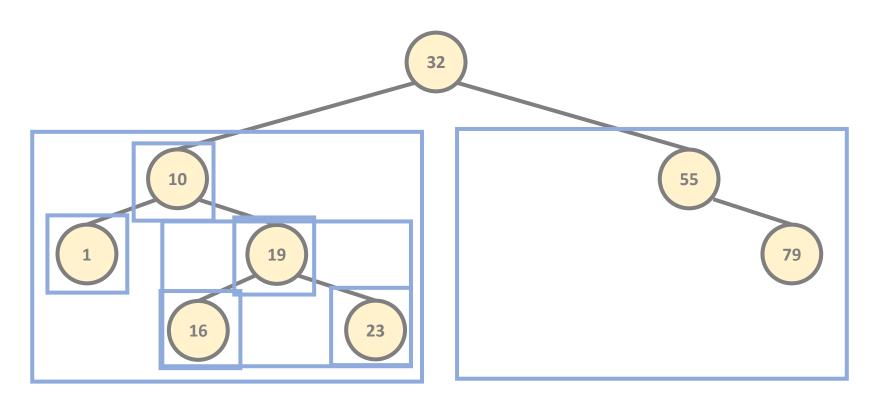
POST-ORDER TRAVERSAL



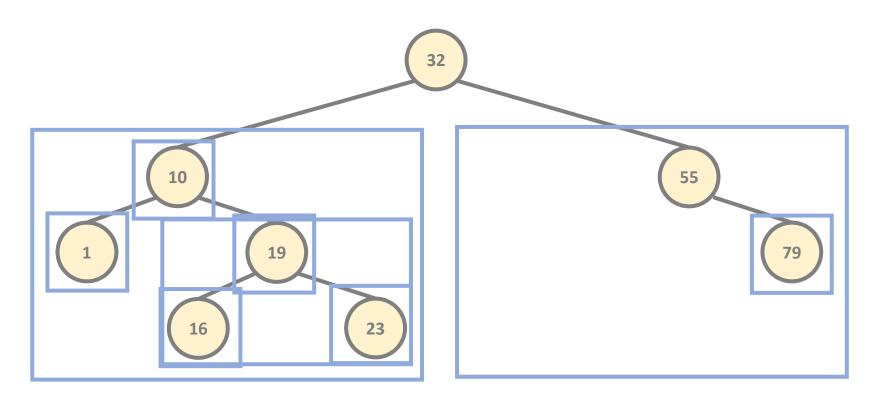
POST-ORDER TRAVERSAL



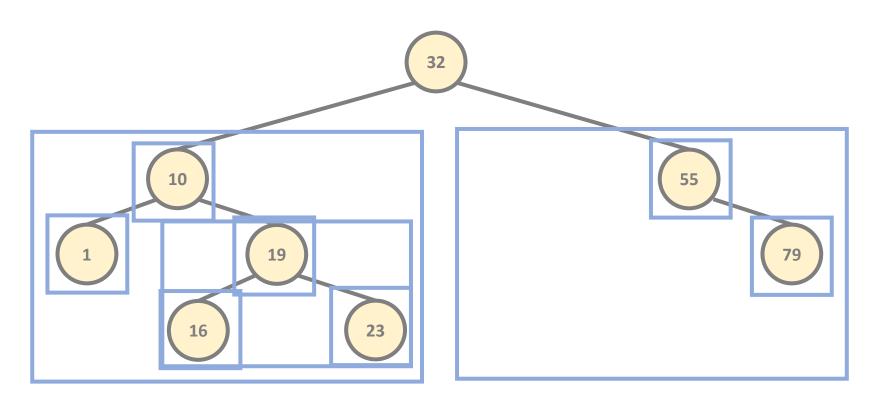
POST-ORDER TRAVERSAL



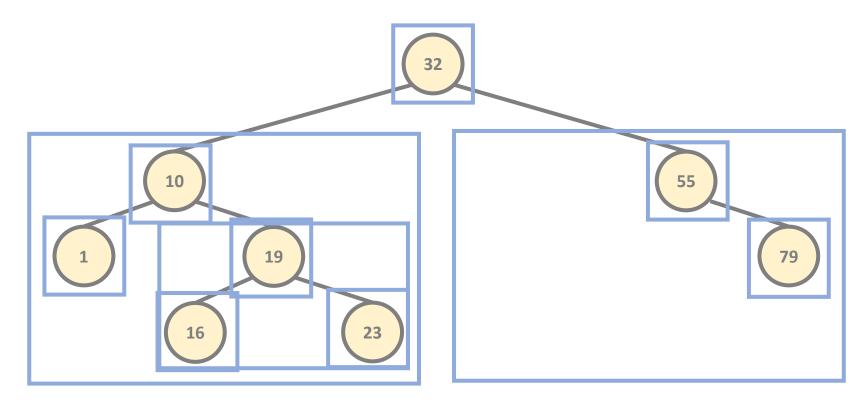
POST-ORDER TRAVERSAL



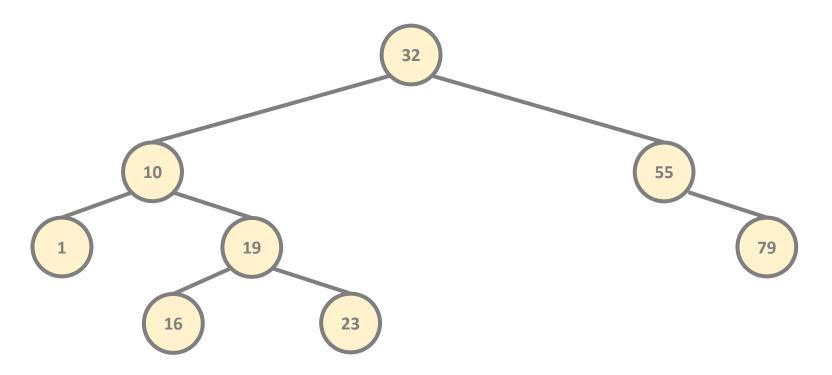
POST-ORDER TRAVERSAL



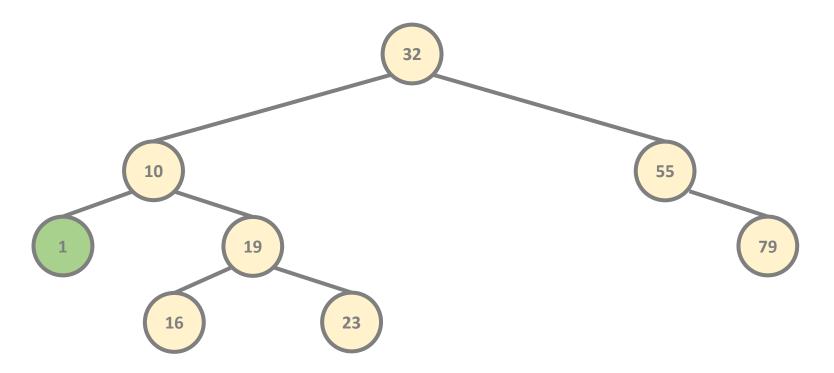
POST-ORDER TRAVERSAL



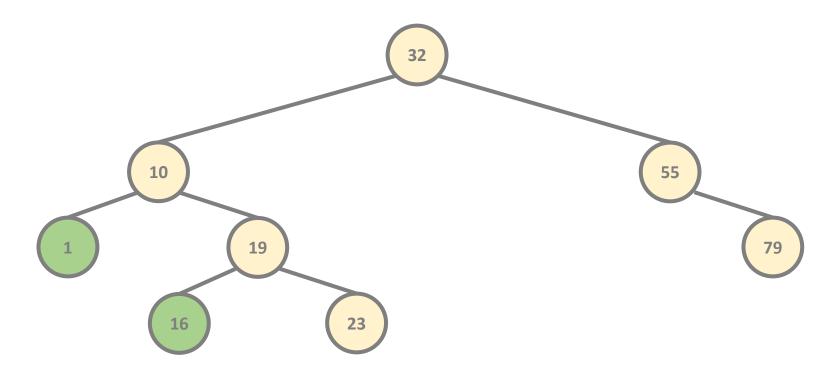
POST-ORDER TRAVERSAL



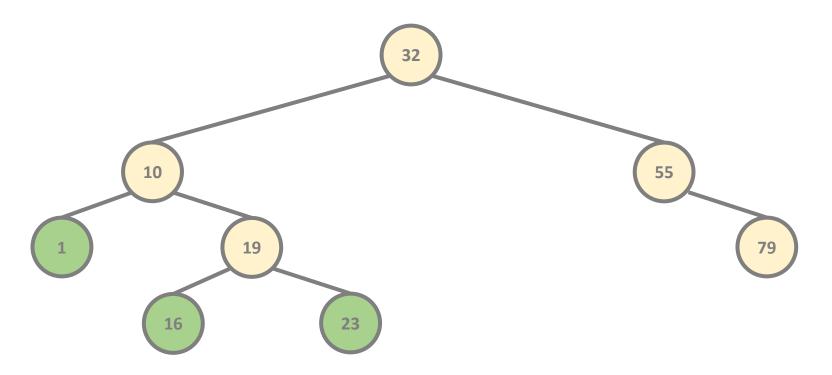
POST-ORDER TRAVERSAL



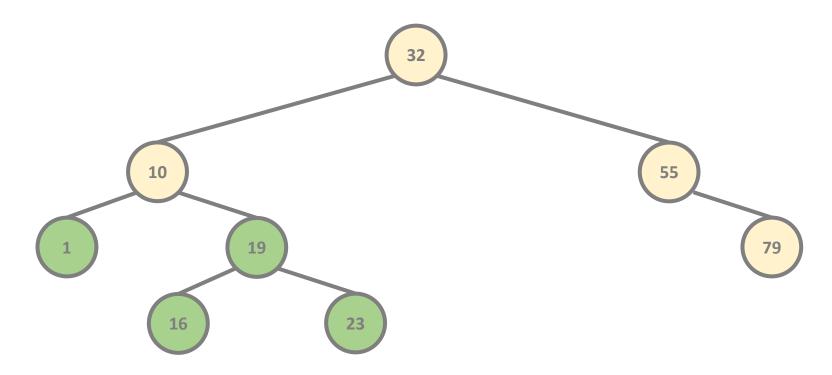
POST-ORDER TRAVERSAL



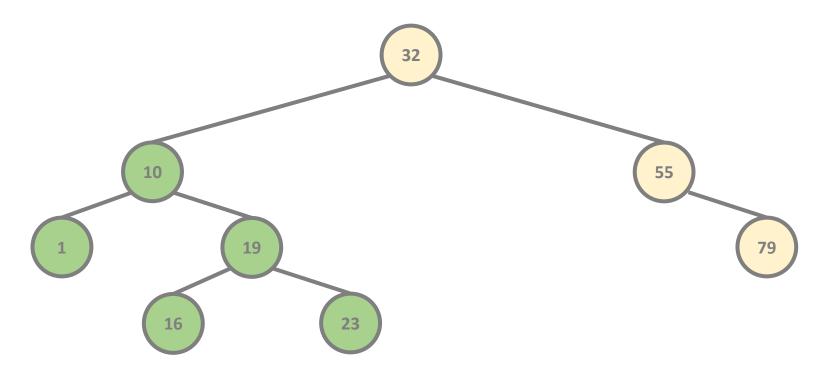
POST-ORDER TRAVERSAL



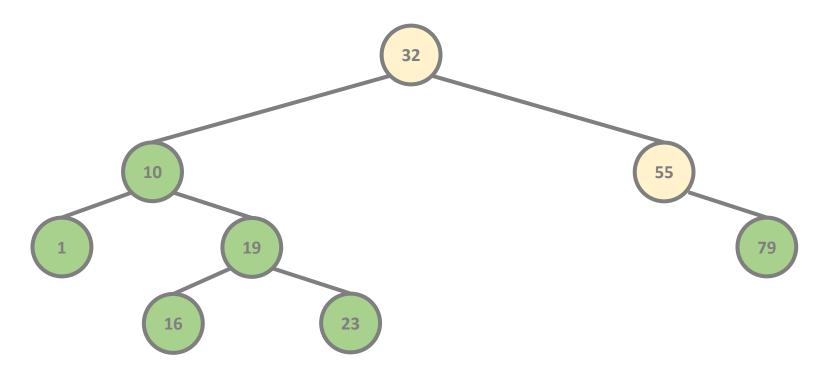
POST-ORDER TRAVERSAL



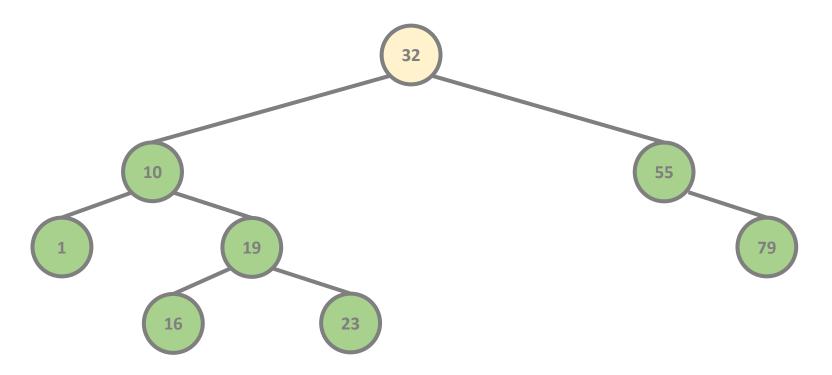
POST-ORDER TRAVERSAL



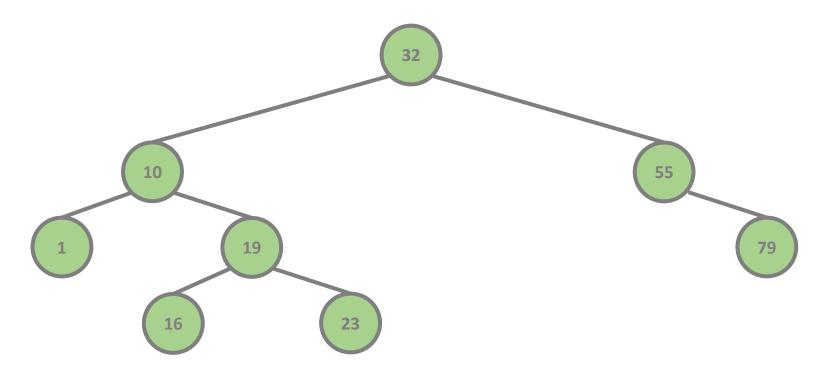
POST-ORDER TRAVERSAL



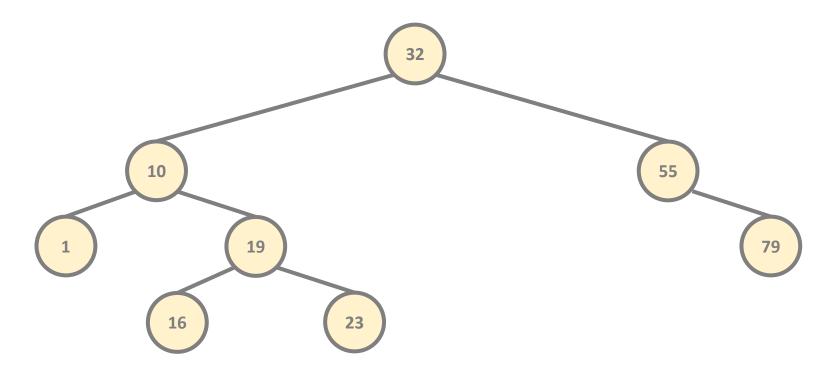
POST-ORDER TRAVERSAL



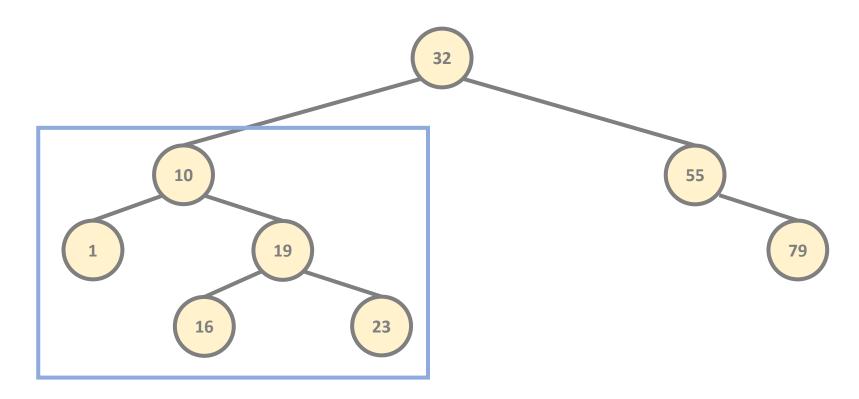
POST-ORDER TRAVERSAL



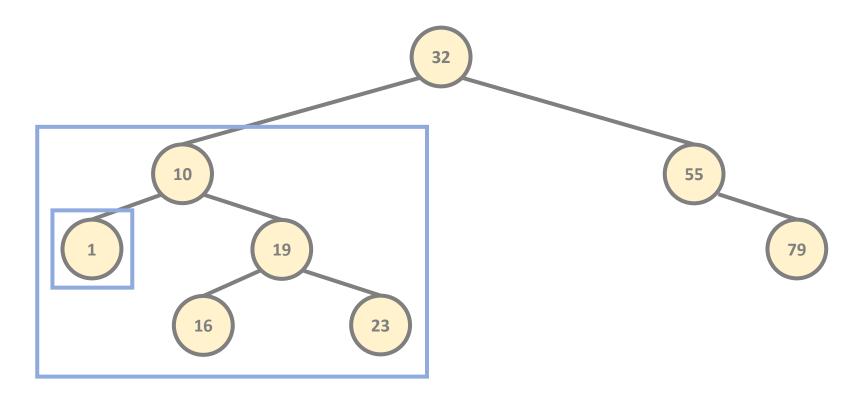
IN-ORDER TRAVERSAL (SORTED ORDER)



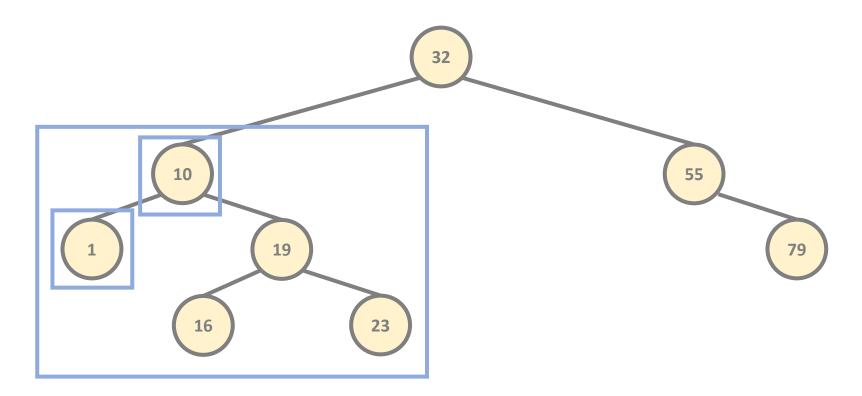
IN-ORDER TRAVERSAL (SORTED ORDER)



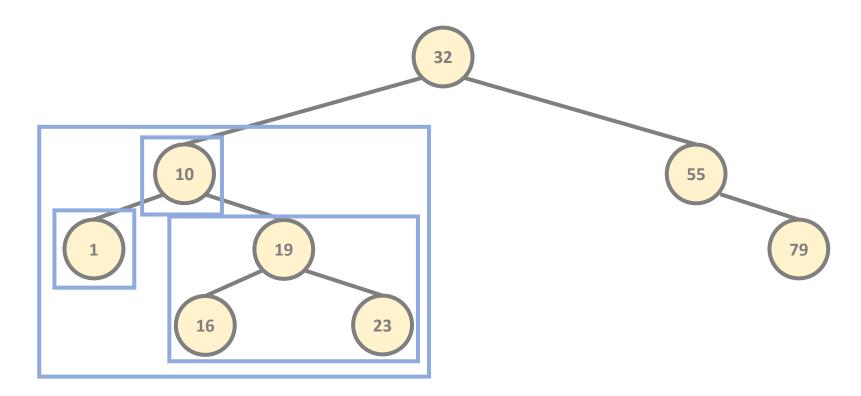
IN-ORDER TRAVERSAL (SORTED ORDER)



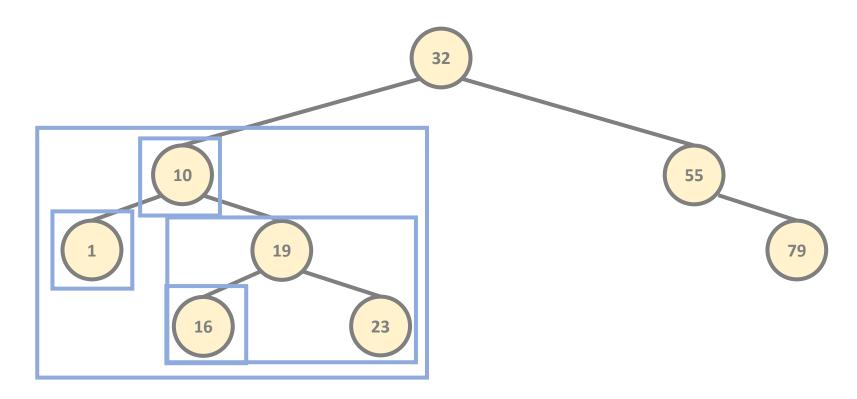
IN-ORDER TRAVERSAL (SORTED ORDER)



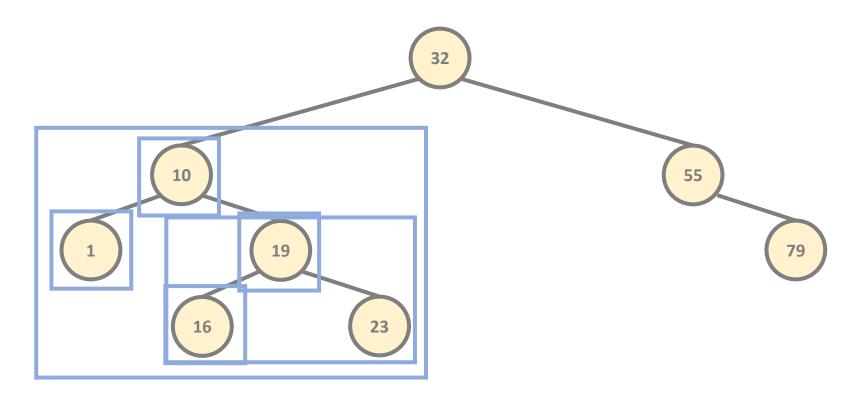
IN-ORDER TRAVERSAL (SORTED ORDER)



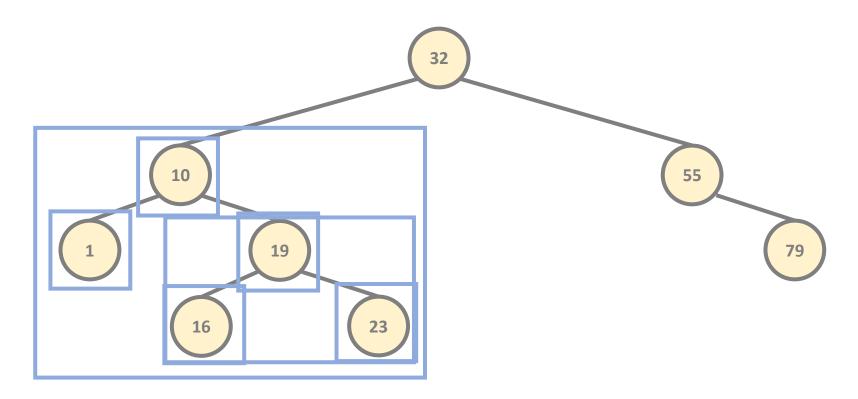
IN-ORDER TRAVERSAL (SORTED ORDER)



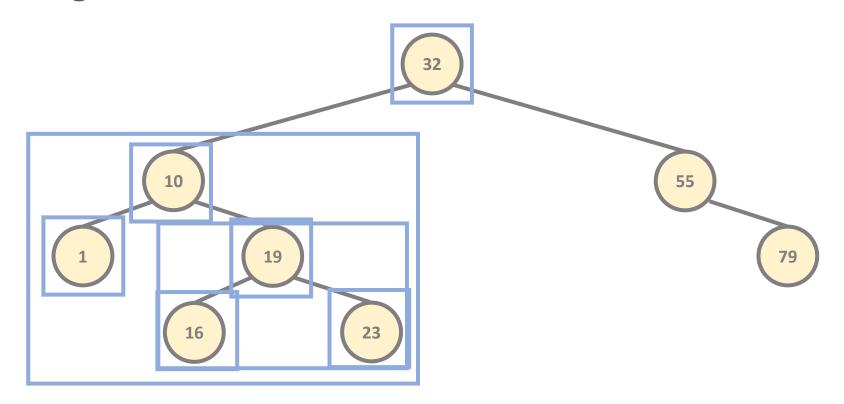
IN-ORDER TRAVERSAL (SORTED ORDER)



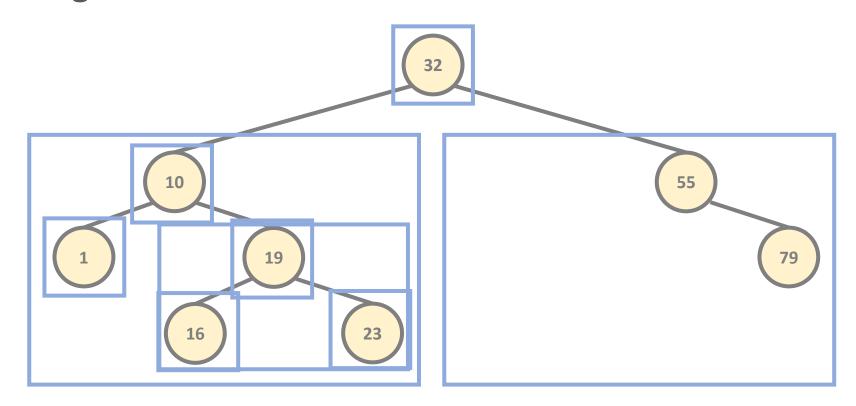
IN-ORDER TRAVERSAL (SORTED ORDER)



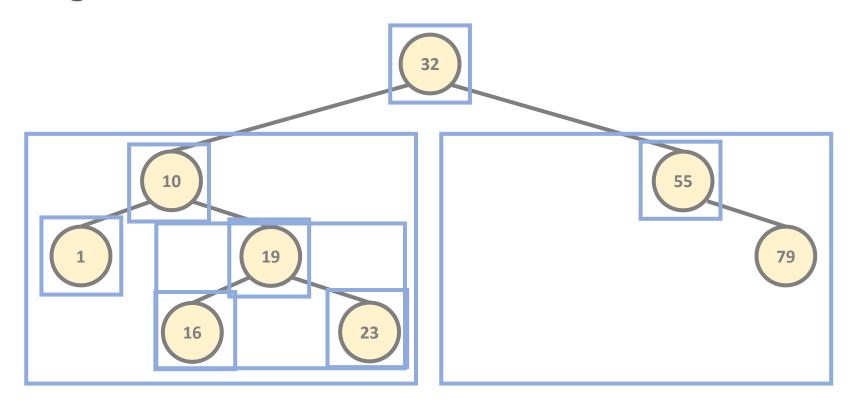
IN-ORDER TRAVERSAL (SORTED ORDER)



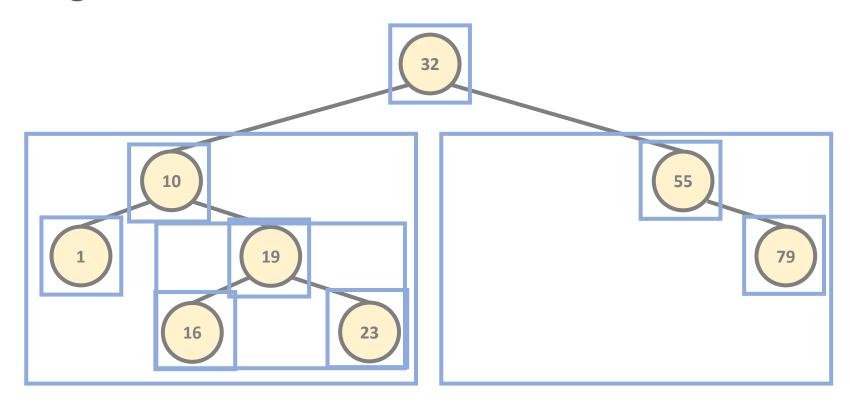
IN-ORDER TRAVERSAL (SORTED ORDER)



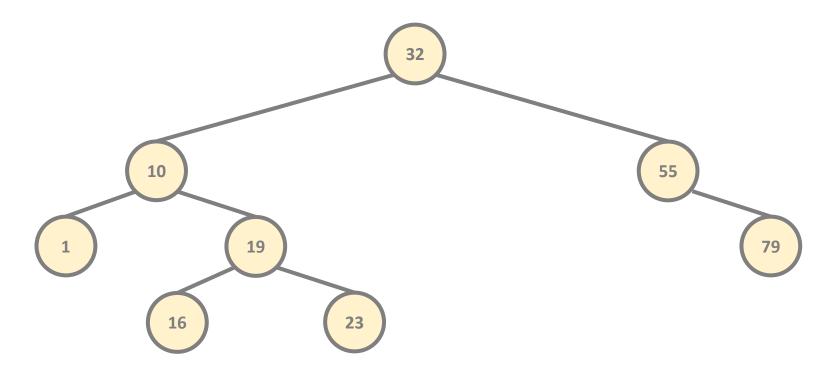
IN-ORDER TRAVERSAL (SORTED ORDER)



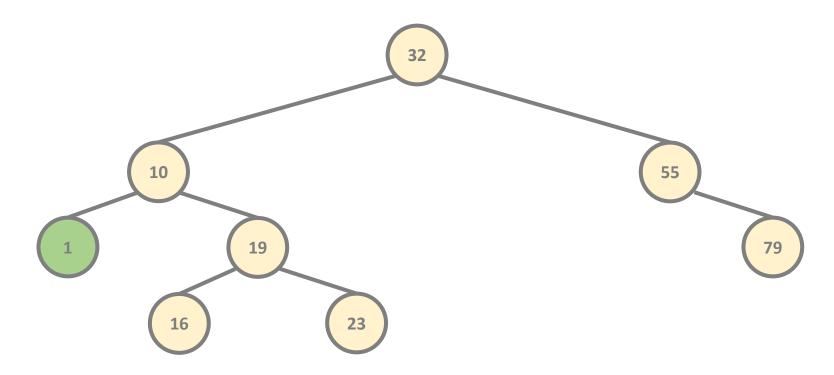
IN-ORDER TRAVERSAL (SORTED ORDER)



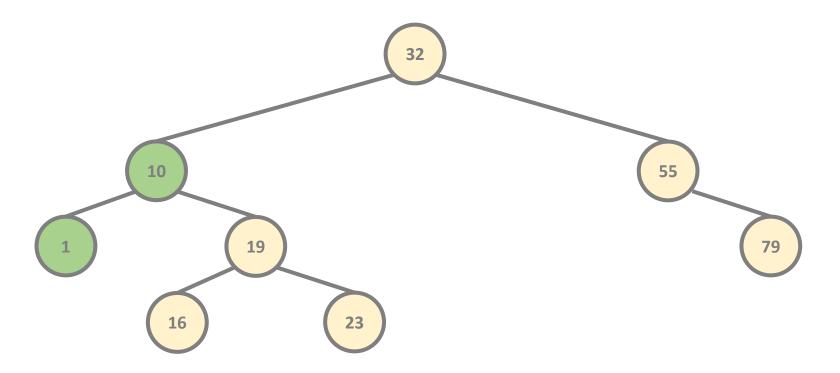
IN-ORDER TRAVERSAL (SORTED ORDER)



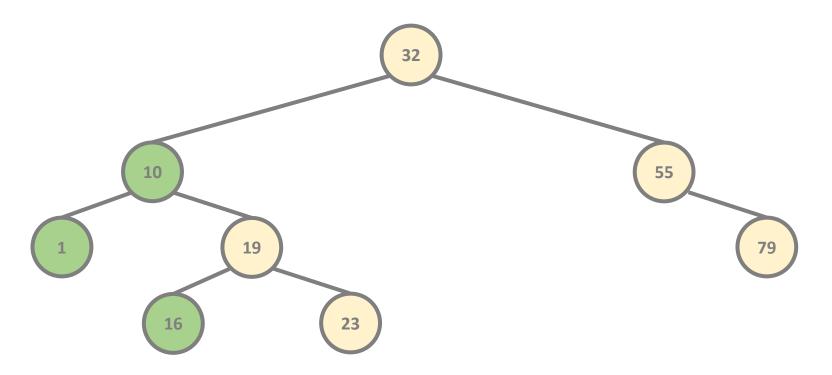
IN-ORDER TRAVERSAL (SORTED ORDER)



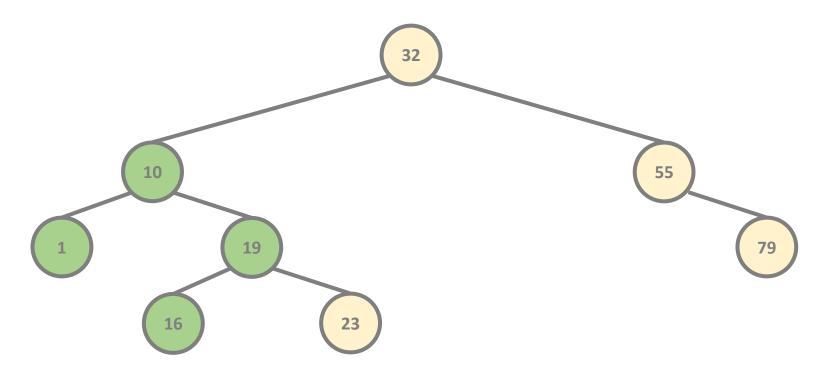
IN-ORDER TRAVERSAL (SORTED ORDER)



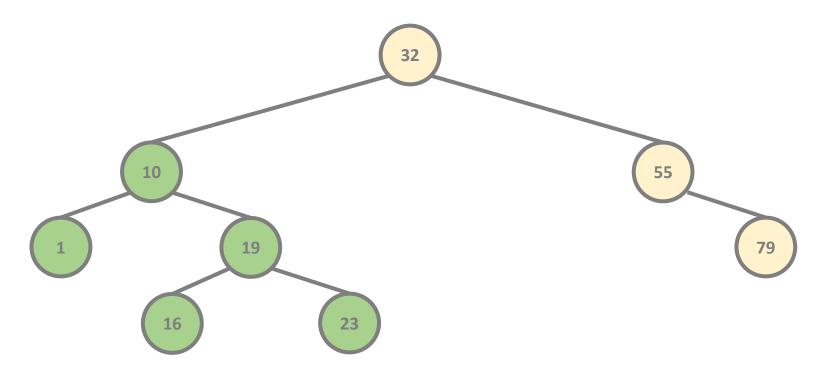
IN-ORDER TRAVERSAL (SORTED ORDER)



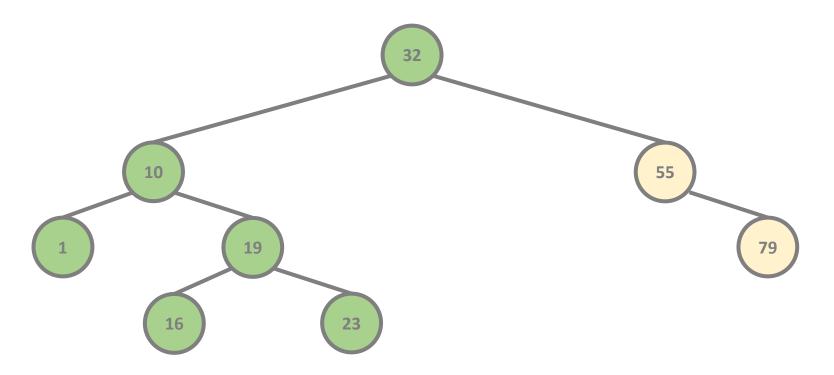
IN-ORDER TRAVERSAL (SORTED ORDER)



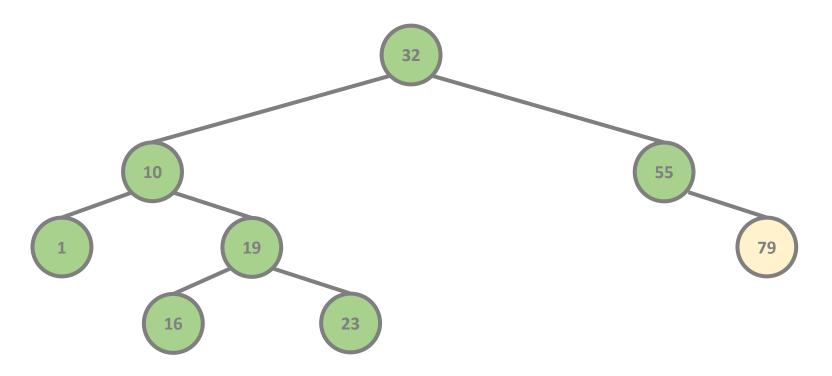
IN-ORDER TRAVERSAL (SORTED ORDER)



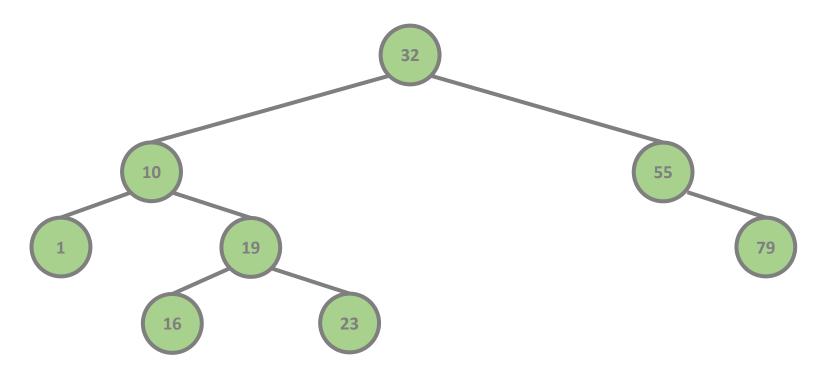
IN-ORDER TRAVERSAL (SORTED ORDER)



IN-ORDER TRAVERSAL (SORTED ORDER)



IN-ORDER TRAVERSAL (SORTED ORDER)



Binary Search Trees (Algorithms and Data Structures)

	AVERAGE-CASE	WORST-CASE
space complexity	O(N)	O(N)
insertion	O(logN)	O(N)
deletion (removal)	O(logN)	O(N)
search	O(logN)	O(N)





INSERT(4)



INSERT(4)



INSERT(4)

