

Imię i nazwisko: Paweł Skrzypczyński

Główna afiliacja: Narodowy Bank Polski, Warszawa

Liczba cytowań: 121.0. Liczba autocytowań: 4 (3.2 %). H-index: 3.0

Liczba artykułów: 4.0. Liczba książek: nan. Rozdziały: nan. Papers: 6.0

Rok rozpoczęcia działalności naukowej: 2007. Ostatni aktywny rok: 2012.

Wybrane artykuły lub inne prace z usługi Cross-Ref:

Can a Simple DSGE Model Outperform Professional Forecasters?, DOI: 10.2139/ssrn.1118767
Forecasting the Polish Zloty with Non-Linear Models, DOI: 10.2139/ssrn.1804011
Are Business Cycles in the US and Emerging Economies Synchronized?, DOI: 10.2139/ssrn.2039264
Can We Beat the Random Walk in Forecasting CEE Exchange Rates?, DOI: 10.2139/ssrn.2163518
Putting the New Keynesian DSGE Model to the Real-Time Forecasting Test, DOI: 10.2139/ssrn.1499084
Failure transparency in CORBA systems, DOI: 10.1109/pcee.2002.1115249
Spatial Uncertainty Management for Simultaneous Localization and Mapping, DOI: 10.1109/robot.2007.364101
Map-based adaptive foothold planning for unstructured terrain walking, DOI: 10.1109/robot.2010.5509670
A probabilistic framework for global localization with segmented planes, DOI: 10.1109/ecmr.2017.8098672
Estimating terrain elevation maps from sparse and uncertain multi-sensor data, DOI: 10.1109/robio.2012.6491052
Uncertain Spatial Knowledge Management in a Mobile Robot Architecture, DOI: 10.1109/mfi.2006.265600
Performance comparison of point feature detectors and descriptors for visual navigation on Android platform, DOI: 10.1109/iwcmc.2014.6906342
Rough terrain mapping and classification for foothold selection in a walking robot, DOI: 10.1109/ssrr.2010.5981552
Hybrid field of view vision: From biological inspirations to integrated sensor design, DOI: 10.1109/mfi.2016.7849557
Environment modelling in a multi-agent mobile system, DOI: 10.1109/eurbot.1999.827620
Posture optimization strategy for a statically stable robot traversing rough terrain, DOI: 10.1109/iros.2012.6385548
Interactive programming of a mechatronic system: A small humanoid robot example, DOI: 10.1109/aim.2013.6584134
Experimental evaluation of visual place recognition algorithms for personal indoor localization, DOI: 10.1109/ipin.2016.7743649
The importance of measurement uncertainty modelling in the feature-based RGB-D SLAM, DOI: 10.1109/romoco.2015.7219752
Indoor navigation using QR codes and WiFi signals with an implementation on mobile platform, DOI: 10.1109/spa.2016.7763605

Dominujący współpracownicy: