

Algorithms - Spring '23

MSSR



Recap

- HW posted, due next Wed
 - ↳ MST & Shortest Paths
- Next week's readings are up
- Algorithms visualizer:
 - demo]
- End time note: please stop me if I go over!

Shortest paths so far

Key: relaxing tense edges $d(v) > d(u) + w(u \rightarrow v)$

Time to compute shortest path tree rooted at any $s \in V$.

- If your graph is unweighted:

BFS: $O(V + E)$

- If your graph is a DAG:

Top sort + DP: $O(V + E)$

- If no negative edges:

Dijkstra: $O(E \log V)$

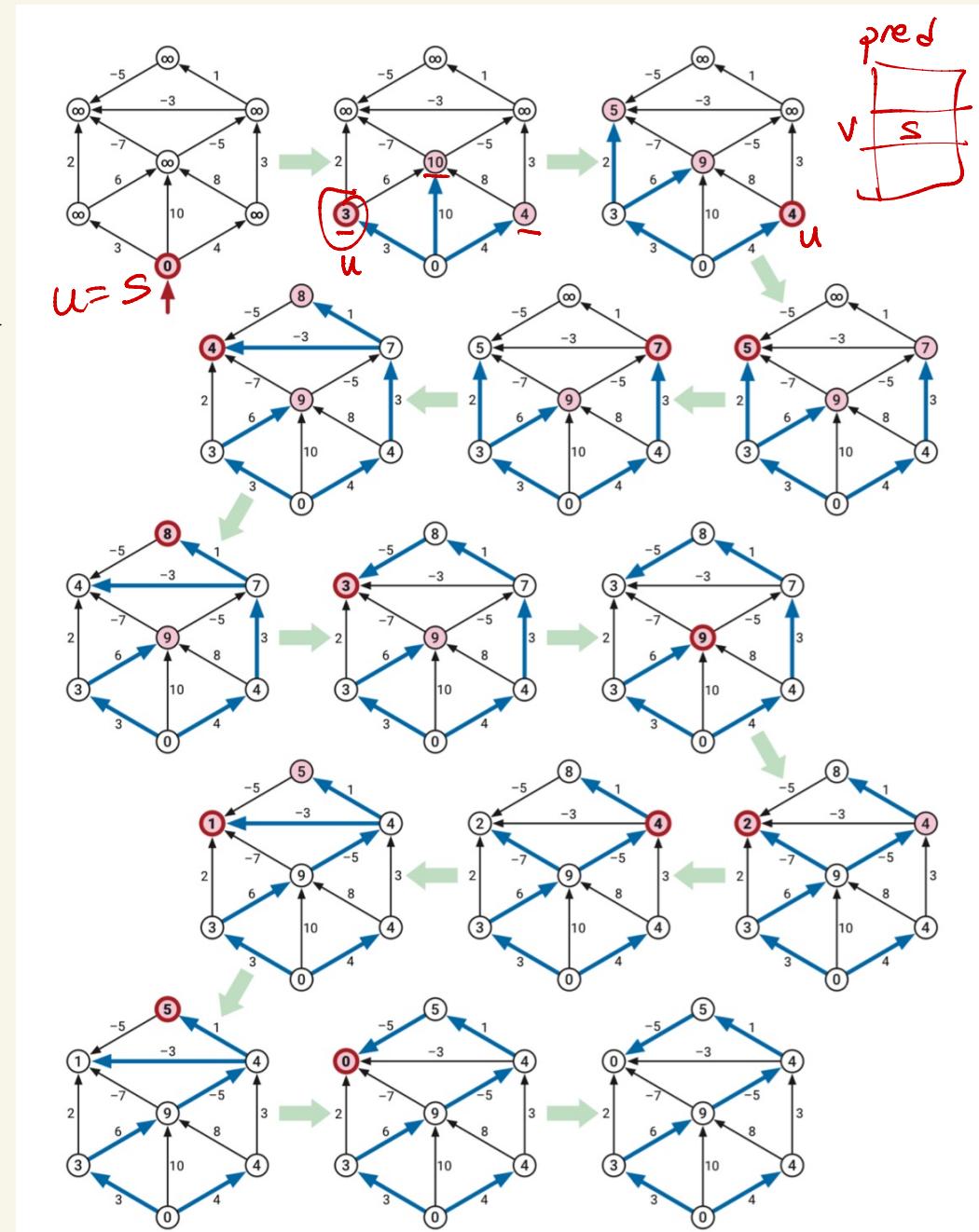
Dijkstra: Saw 2 versions

One of them
works on negative
edges
(no cycles)

```
DIJKSTRA( $s$ ):  
    INITSSSP( $s$ )  
    INSERT( $s, 0$ )  
    while the priority queue is not empty  
         $u \leftarrow \text{EXTRACTMIN}()$   
        for all edges  $u \rightarrow v$   
            if  $u \rightarrow v$  is tense  
                RELAX( $u \rightarrow v$ )  
            if  $v$  is in the priority queue  
                DECREASEKEY( $v, \text{dist}(v)$ )  
            else  
                INSERT( $v, \text{dist}(v)$ )
```

Figure 8.11. Dijkstra's algorithm.

worst case
exp time



If negative edges and (potentially) negative cycles:

Bellman-Ford

Runtime:

ONE

BELLMANFORD(s)

INITSSSP(s)

repeat $V - 1$ times

for every edge $u \rightarrow v$

if $u \rightarrow v$ is tense

RELAX($u \rightarrow v$)

for every edge $u \rightarrow v$

if $u \rightarrow v$ is tense

return "Negative cycle!"

- OR -

BELLMANFORDFINAL(s)

$dist[s] \leftarrow 0$

for every vertex $v \neq s$

$dist[v] \leftarrow \infty$

for $i \leftarrow 1$ to $V - 1$

for every edge $u \rightarrow v$

if $dist[v] > dist[u] + w(u \rightarrow v)$

$dist[v] \leftarrow dist[u] + w(u \rightarrow v)$

Multiple-Source Shortest Paths (MSSP)

MSSP(6):

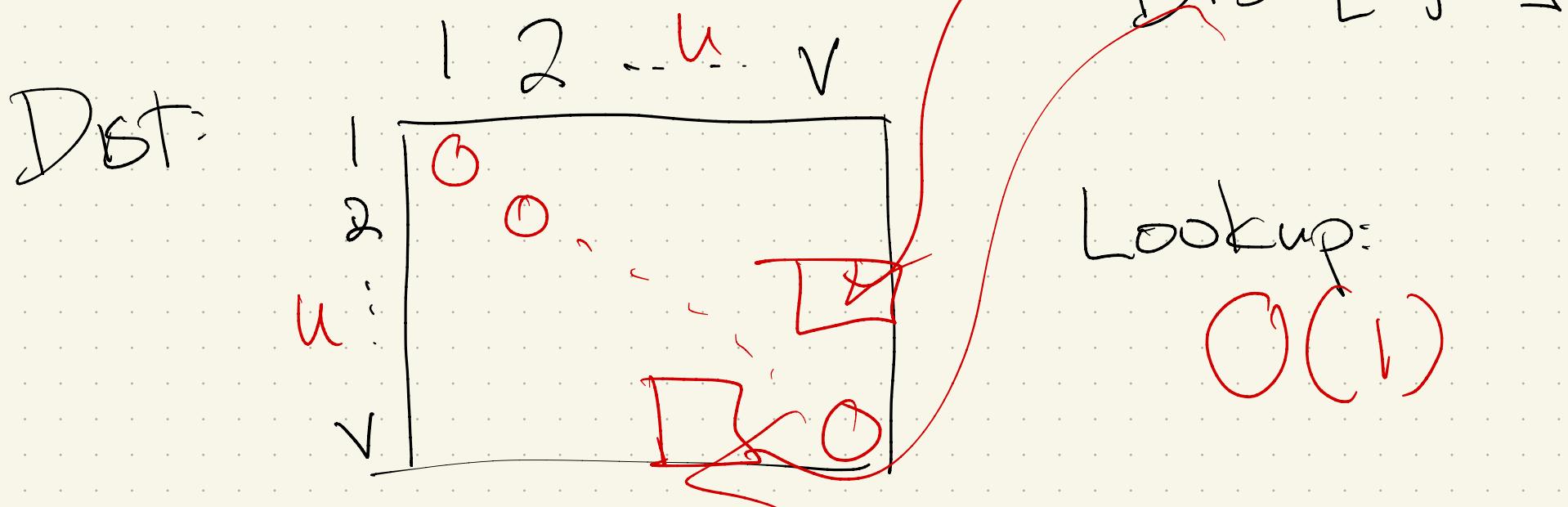
for each pair $u, v \in G$:

Compute shortest $u \rightsquigarrow v$

Compute shortest $v \rightsquigarrow u$

Store in $DIST[u, v]$ +

$DIST[v, u]$



Computing MSSPs:

First attempt: [for each vertex v
Run SSSP(v)]

Runtime: $O(V \times (\text{SSSP}_{alg}))$

- if unweighted or a DAG, SSSP was
 $O(V+E) \Rightarrow O(V(V+E))$
- no negative edge weights, Dijkstra was
 $O(E \log V) \Rightarrow O(VE \log V) = O(V^3 \log V)$
- Bellman-Ford was $O(NE)$

$$\Rightarrow O(V^2 E) = O(V^4)$$

Side question:

Since negative edges are bad, why can't we just re-weight?

Idea: Increase all edge weights by some amount, so all positive.

Doesn't work:

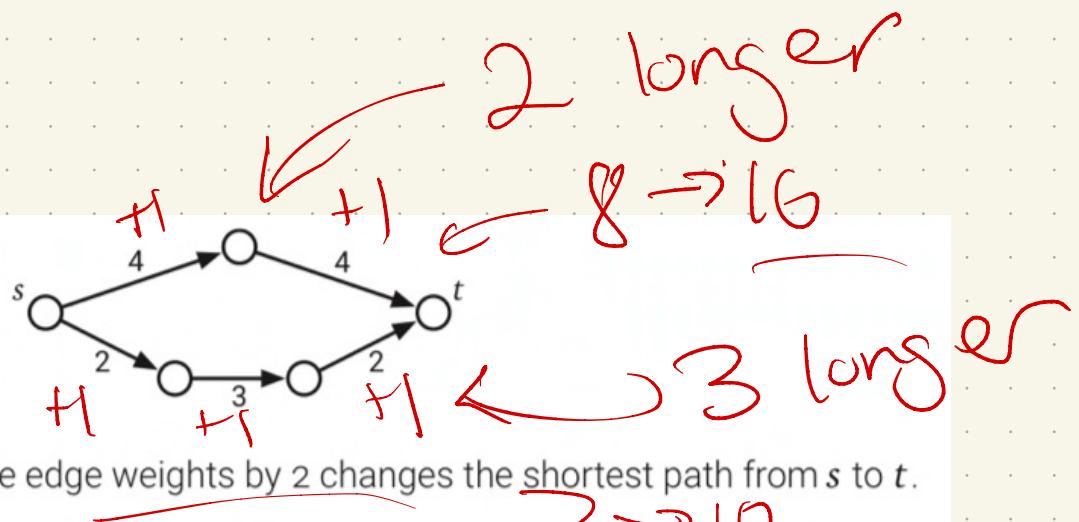


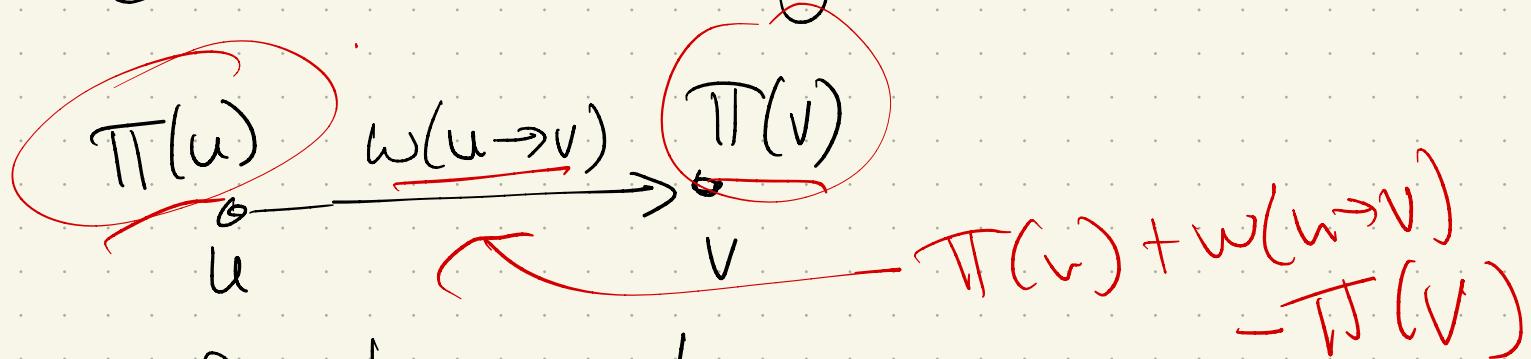
Figure 9.1. Increasing all the edge weights by 2 changes the shortest path from s to t .

Why? not reweighting ~~paths~~ the same amount

Another idea (that works):

Suppose each v has a price attached,
 $\pi(v)$.

(Still have edge weights.)



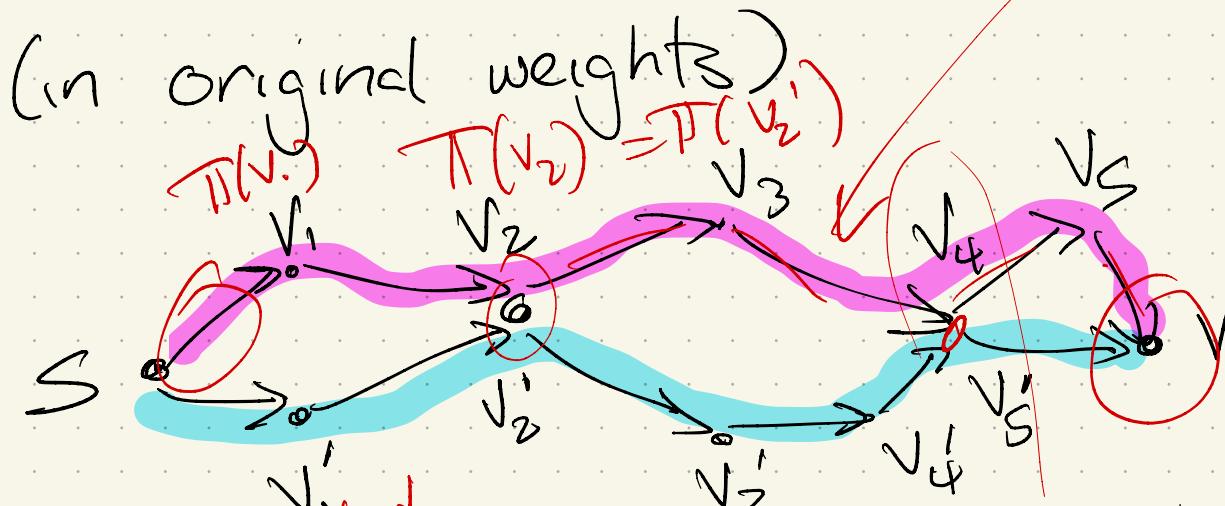
Define a new function w' :

$$w'(u \rightarrow v) = \pi(u) + \underline{w(u \rightarrow v)} \boxed{-\pi(v)}$$

Claim: Shortest path is unchanged!
all paths stay in some "order"

Claim: under w' , shortest paths are the same as under w .

Why? Consider 2 $s \rightarrow v$ paths:



weights: $\pi(v_i)$
 purple: $w(s \rightarrow v_1)$
 $+ w(v_1 \rightarrow v_2)$
 $+ \dots w(v_5 \rightarrow v)$

Purple path after reweighting:

$$\{ \pi(s) + w(s \rightarrow v_1) - \pi(v_1) \} + \{ \pi(v_1) + w(v_1 \rightarrow v_2) - \pi(v_2) \} + \dots$$

\Rightarrow Blue path: $= \pi(s) + \cancel{\text{original path}} - \pi(v)$

$$\pi(s) + \text{original blue} - \pi(v)$$

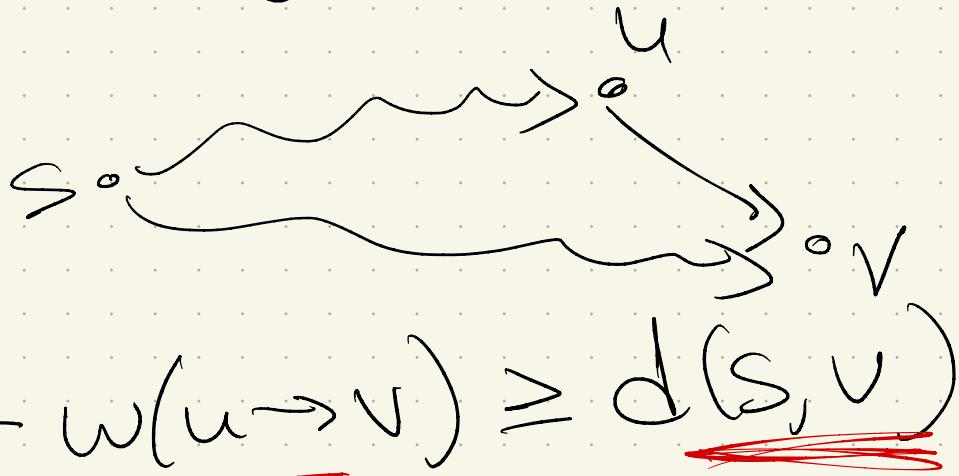
Johnson's algorithm for MSSP:
use this new kind of weight
function!

$O(V \cdot E)$

- Run Bellman-Ford once from some $s \in V$
no false edges \hookrightarrow no negative cycles or give up.
- Reweight (if it works): let $\pi(v) = d(s, v)$
 $d(s, u)$ $w(u \rightarrow v)$ $d(s, v)$
 $d(s, u) + w(u \rightarrow v) = d(s, v)$
 $d(s, u) + w(u \rightarrow v) \geq d(s, v)$
- Now all paths are positive, so can use faster algorithm for other SSSPs!

Aside: Why positive?

After SSSP, no edges are
tense:



$$\text{So } \underline{d(s, u) + w(u \rightarrow v)} \geq d(s, v)$$

rearrange:

$$\begin{aligned} & \rightarrow d(s, u) + w(u \rightarrow v) - d(s, v) \\ & = w'(u \rightarrow v) \geq 0 \end{aligned}$$

So - Algorithm:

Runtime:

$$\mathcal{O}(V^2 \log V)$$

$P = \text{D}(S) + (\text{path}) - \text{D}(V)$

MIN \Rightarrow

JOHNSONAPSP(V, E, w) :

$\langle\langle$ Add an artificial source $\rangle\rangle$

add a new vertex s

for every vertex v

add a new edge $s \rightarrow v$

$w(s \rightarrow v) \leftarrow 0$

$\langle\langle$ Compute vertex prices $\rangle\rangle$

$dist[s, \cdot] \leftarrow \text{BELLMANFORD}(V, E, w, s)$

if BELLMANFORD found a negative cycle

fail gracefully

$\langle\langle$ Reweight the edges $\rangle\rangle$

for every edge $u \rightarrow v \in E$

$w'(u \rightarrow v) \leftarrow dist[s, u] + w(u \rightarrow v) - dist[s, v]$

$\langle\langle$ Compute reweighted shortest path distances $\rangle\rangle$

for every vertex u

$dist'[u, \cdot] \leftarrow \text{DIJKSTRA}(V, E, w', u)$

$\langle\langle$ Compute original shortest-path distances $\rangle\rangle$

for every vertex u

for every vertex v

$dist[u, v] \leftarrow dist'[u, v] - dist[s, u] + dist[s, v]$

directed graph

$\mathcal{O}(VE)$

Reweight

$V \cdot E \log V$

Figure 9.2. Johnson's all-pairs shortest paths algorithm

Compare to naive: $\mathcal{O}(V^2 E) = \mathcal{O}(V^4)$

V vs $\log V$

More Improvements

Set up recursive approach:

Let $\text{dist}(u, v, l)$ = best $u \rightsquigarrow v$ path using at most l edges.

Then, back to "keep reflexing edges" approach:

$$\text{dist}(u, v, l) = \begin{cases} 0 & \text{if } l = 0 \text{ and } u = v \\ \infty & \text{if } l = 0 \text{ and } u \neq v \\ \min \left\{ \begin{array}{l} \text{min}_{x \rightarrow v} (\text{dist}(u, x, l-1) + w(x \rightarrow v)) \\ \text{don't use another edge} \end{array} \right\} & \text{otherwise} \end{cases}$$

build length l via length $l-1$
do we another

Code:

SHIMBELAPSP(V, E, w):

```
for all vertices  $u$ 
  for all vertices  $v$ 
    if  $u = v$ 
       $dist[u, v, 0] \leftarrow 0$ 
    else
       $dist[u, v, 0] \leftarrow \infty$ 
```

```
for  $\ell \leftarrow 1$  to  $V - 1$ 
  for all vertices  $u$ 
    for all vertices  $v \neq u$ 
       $dist[u, v, \ell] \leftarrow dist[u, v, \ell - 1]$ 
    for all edges  $x \rightarrow v$ 
      if  $dist[u, v, \ell] > dist[u, x, \ell - 1] + w(x \rightarrow v)$ 
         $dist[u, v, \ell] \leftarrow dist[u, x, \ell - 1] + w(x \rightarrow v)$ 
```

} paths of length 0
might need $V-1$ edges

Can improve

ALLPAIRSBELLMANFORD(V, E, w):

```
for all vertices  $u$ 
  for all vertices  $v$ 
    if  $u = v$ 
       $dist[u, v] \leftarrow 0$ 
    else
       $dist[u, v] \leftarrow \infty$ 
```

```
for  $\ell \leftarrow 1$  to  $V - 1$ 
  for all vertices  $u$ 
    for all edges  $x \rightarrow v$ 
      if  $dist[u, v] > dist[u, x] + w(x \rightarrow v)$ 
         $dist[u, v] \leftarrow dist[u, x] + w(x \rightarrow v)$ 
```

Runtime:

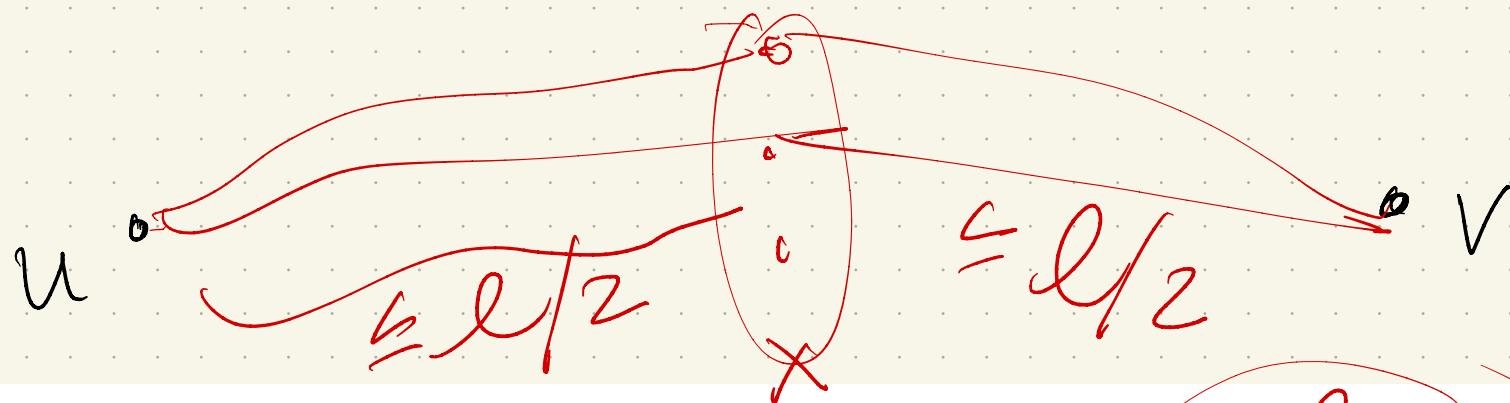
$V^2 E$

$V^3 N^4$

Wait \rightarrow that's worse!

But, let's try a more balanced
divide & conquer!

Instead of going $n-1 \rightarrow n$,
can we add longer paths?



$$dist(u, v, \underline{\ell}) = \begin{cases} w(u \rightarrow v) & \text{if } \underline{\ell} = 1 \\ \min_x (dist(u, x, \underline{\ell}/2) + dist(x, v, \underline{\ell}/2)) & \text{otherwise} \end{cases}$$

best $u \rightarrow v$ path of
length $\leq \underline{\ell}$

Code:

FISCHERMEYERAPSP(V, E, w):

for all vertices u
 for all vertices v
 $dist[u, v, 0] \leftarrow w(u \rightarrow v)$

for $i \leftarrow 1$ to $\lceil \lg V \rceil$ $\langle\langle \ell = 2^i \rangle\rangle$

 for all vertices u

 for all vertices v

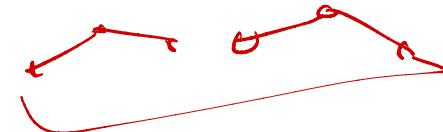
$dist[u, v, i] \leftarrow \infty$

 for all vertices x

 if $dist[u, v, i] > dist[u, x, i-1] + dist[x, v, i-1]$

$dist[u, v, i] \leftarrow dist[u, x, i-1] + dist[x, v, i-1]$

$\checkmark 2$



all pairs

u

x

v

Can also save space

LEYZOREKAPSP(V, E, w):

for all vertices u

 for all vertices v

$dist[u, v] \leftarrow w(u \rightarrow v)$

for $i \leftarrow 1$ to $\lceil \lg V \rceil$ $\langle\langle \ell = 2^i \rangle\rangle$

 for all vertices u

 for all vertices v

for all vertices x

 if $dist[u, v] > dist[u, x] + dist[x, v]$

$dist[u, v] \leftarrow dist[u, x] + dist[x, v]$

$\sqrt{3} \log V$

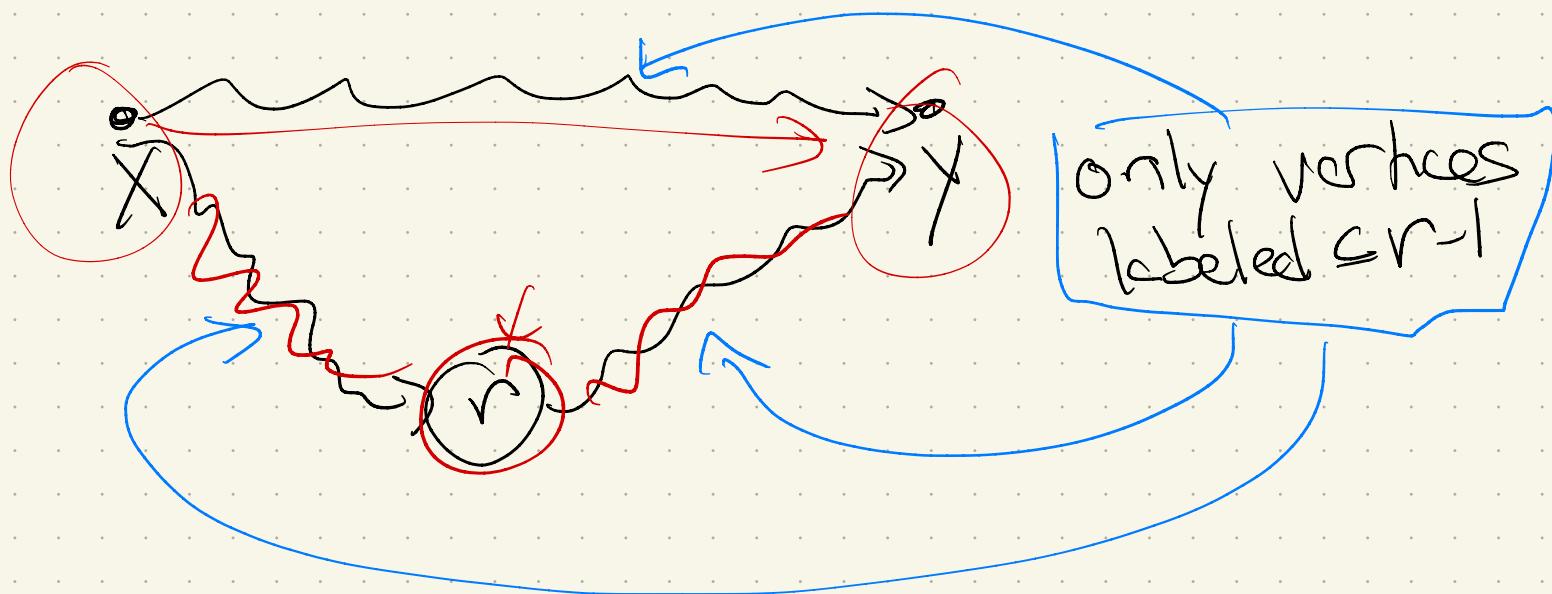
Can we get better?

Floyd-Warshall: instead of path length
order vertices $1, \dots, V$ does vertex order

Let $d(x, y, r) =$

best length path via
vertices labeled $1 \dots r$

Then:



Recursion:

$$dist(u, v, r) = \begin{cases} w(u \rightarrow v) & \text{if } r = 0 \\ \min \left\{ \begin{array}{l} dist(u, v, r - 1) \\ dist(u, r, r - 1) + dist(r, v, r - 1) \end{array} \right\} & \text{otherwise} \end{cases}$$

don't use
vertex r

use vertex r

code ↗

KLEENEAPSP(V, E, w):

```
for all vertices  $u$ 
    for all vertices  $v$ 
         $dist[u, v, 0] \leftarrow w(u \rightarrow v)$ 

    for  $r \leftarrow 1$  to  $V$ 
        for all vertices  $u$ 
            for all vertices  $v$ 
                if  $dist[u, v, r - 1] < dist[u, r, r - 1] + dist[r, v, r - 1]$ 
                     $dist[u, v, r] \leftarrow dist[u, v, r - 1]$ 
                else
                     $dist[u, v, r] \leftarrow dist[u, r, r - 1] + dist[r, v, r - 1]$ 
```

Save
Space

Runtime:

FLOYDWARSHALL(V, E, w):

```
for all vertices  $u$ 
    for all vertices  $v$ 
         $dist[u, v] \leftarrow w(u \rightarrow v)$ 

for all vertices  $r$ 
    for all vertices  $u$ 
        for all vertices  $v$ 
            if  $dist[u, v] > dist[u, r] + dist[r, v]$ 
                 $dist[u, v] \leftarrow dist[u, r] + dist[r, v]$ 
```

Next topic: Flows & cuts