Top sort DFS: making it more precise

```
TopologicalSort(G):
    for all vertices v
        v.status ← New
    clock ← V
    for all vertices v
        if v.status = New
            clock ← TopSortDFS(v, clock)
    return S[1..V]
```

```
TopSortDFS(v, clock):
    v.status ← Active
    for each edge v→w
        if w.status = New
            clock ← TopSortDFS(v, clock)
        else if w.status = Active
            fail gracefully
    v.status ← Finished
    S[clock] ← v
    clock ← clock − 1
    return clock
```

Figure 6.9. Explicit topological sort

Unpacking his figure:

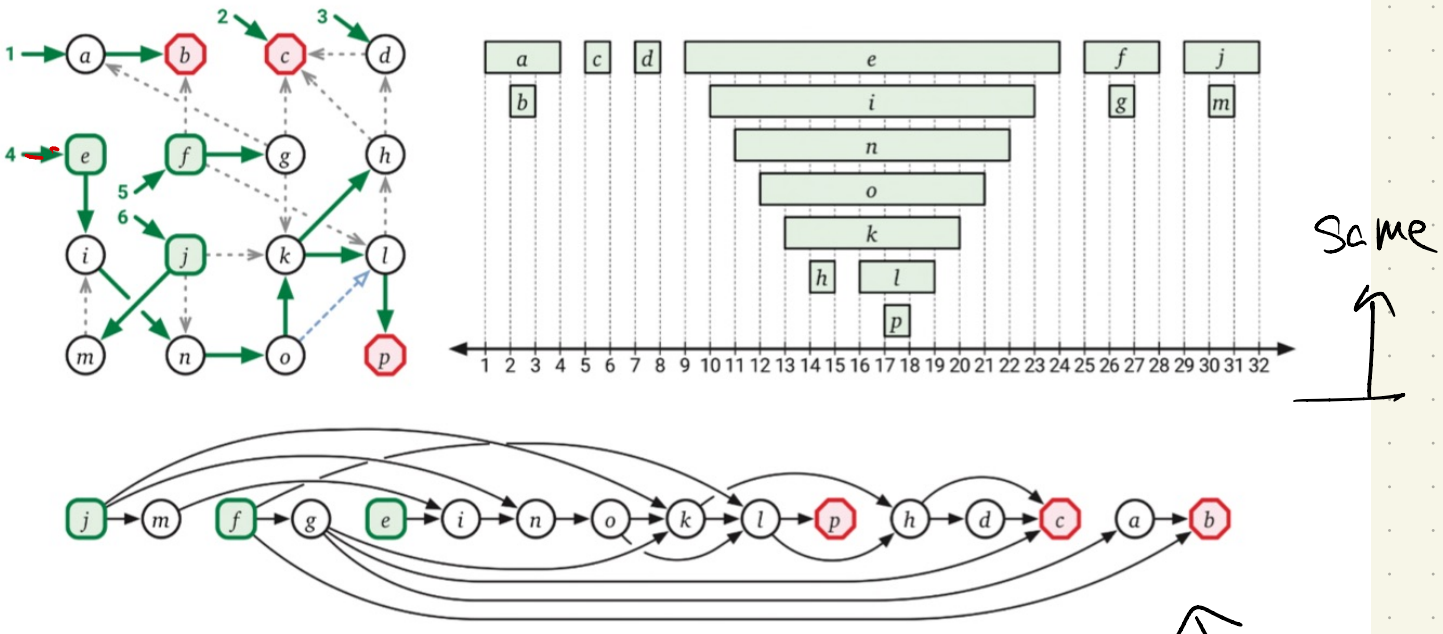


Figure 6.8. Reversed postordering of the dag from Figure 6.6.

Memoization + DP

Nice connection!

If the graph is a DAG, can do dynamic programming on it.

Why?

Think of the recurrences:

$$T(v) = \max_{\text{(predecessors or successors } u \text{ of } v)} \{ T(u) \text{ lookup} + \text{calculation} \}$$

When will the algorithm get stuck?

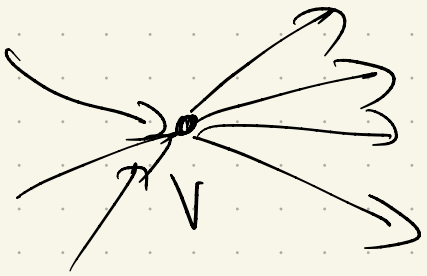
Example: longest path in a DAG.

Usually → very hard.

Think backtracking for a moment, & fix a "target" vertex t.

Let $LLP(v)$ = longest path from v to t

$$= \max \left\{ \right.$$



Using this recursion:

"memoize" the value LLP:

Add a field to the vertex & store it.

(Initially, =)

GetLongest(v):

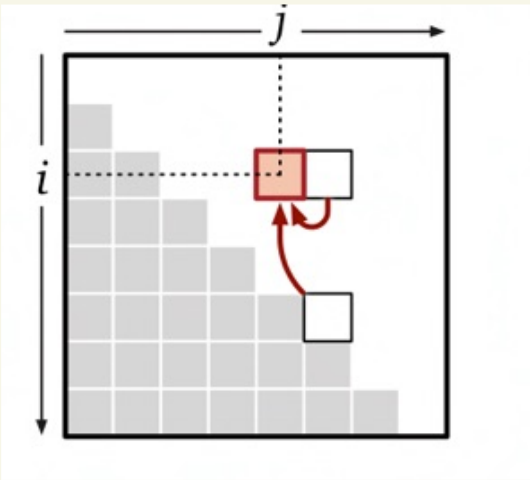
if v = t:

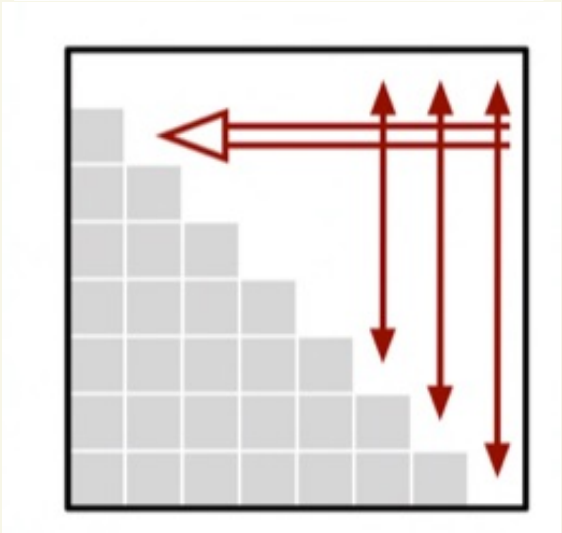
otherwise:

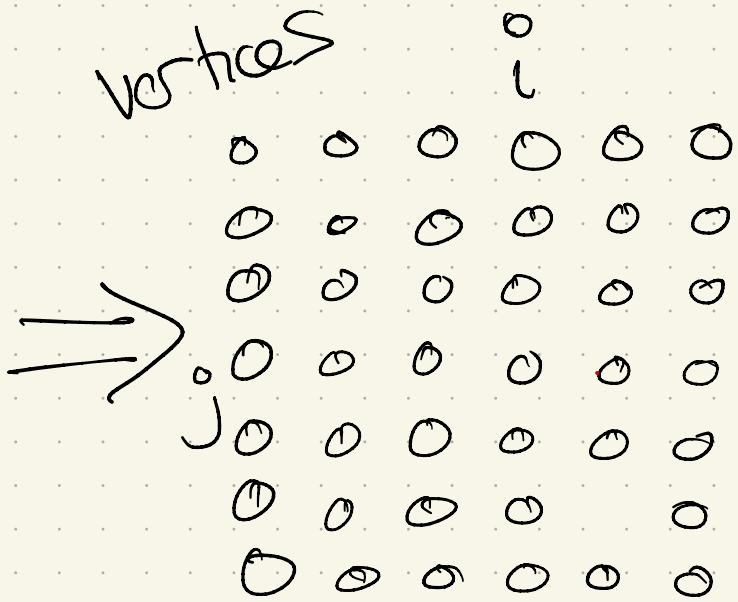
In principle, every DP we saw is working on a dependency graph of subproblems!

Recall: Longest Inc. Subsequence

$$LISbigger(i,j) = \begin{cases} 0 & \text{if } j > n \\ LISbigger(i, j+1) & \text{if } A[i] \geq A[j] \\ \max \begin{Bmatrix} LISbigger(i, j+1) \\ 1 + LISbigger(j, j+1) \end{Bmatrix} & \text{otherwise} \end{cases}$$







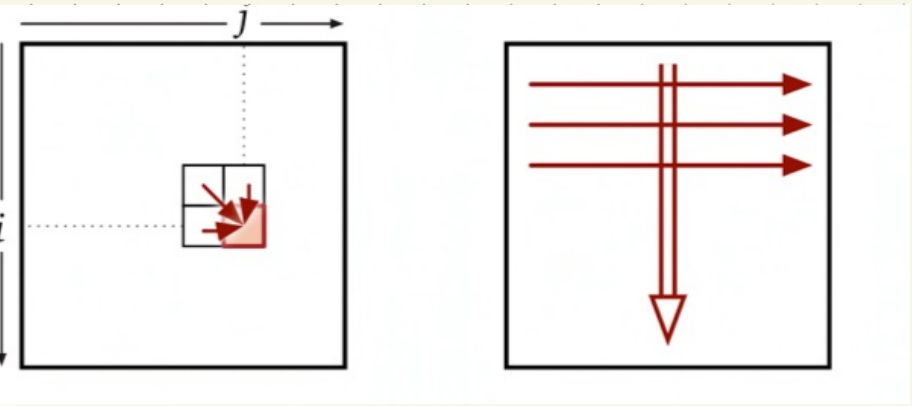
edges:

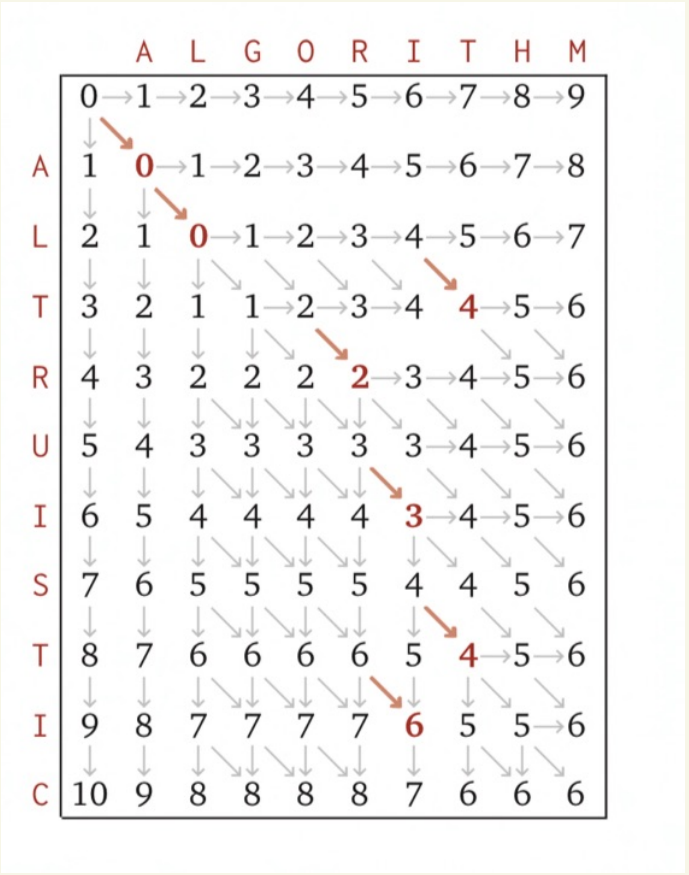
$(i,j) \rightarrow$

$(i,j) \rightarrow$

Edit distance: he actually (sort of) showed the graph!

$$Edit(i,j) = \begin{cases} i & \text{if } j = 0 \\ j & \text{if } i = 0 \\ \min \begin{cases} Edit(i, j-1) + 1 \\ Edit(i-1, j) + 1 \\ Edit(i-1, j-1) + [A[i] \neq B[j]] \end{cases} & \text{otherwise} \end{cases}$$



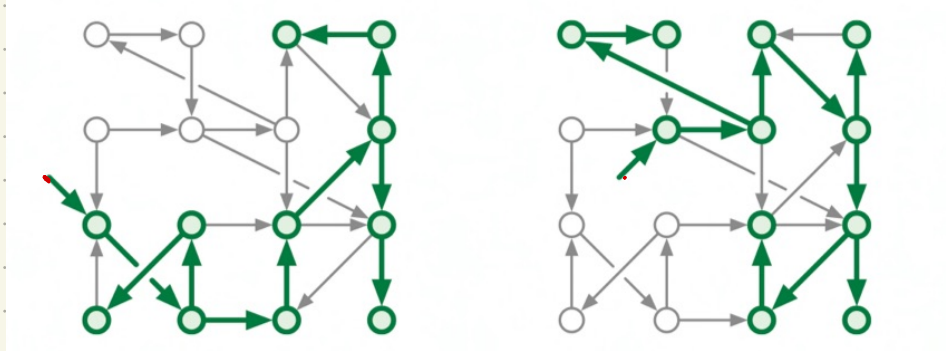


		A	L	G	O	R	I	T	H	M
	0	1	2	3	4	5	6	7	8	9
A	1	0	1	2	3	4	5	6	7	8
L	2	1	0	1	2	3	4	5	6	7
T	3	2	1	1	2	3	4	4	5	6
R	4	3	2	2	2	2	3	4	5	6
U	5	4	3	3	3	3	3	4	5	6
I	6	5	4	4	4	4	3	4	5	6
S	7	6	5	5	5	5	4	4	5	6
T	8	7	6	6	6	6	5	4	5	6
I	9	8	7	7	7	7	6	5	5	6
C	10	9	8	8	8	8	7	6	6	6

Strong connectivity

In an undirected graph, if $u \rightsquigarrow v$, then $v \rightsquigarrow u$.

Not true in directed case:



So 2 notions:

weak connectivity:

strong connectivity:

related: SCCs

Can actually order the strongly connected pieces of a graph:

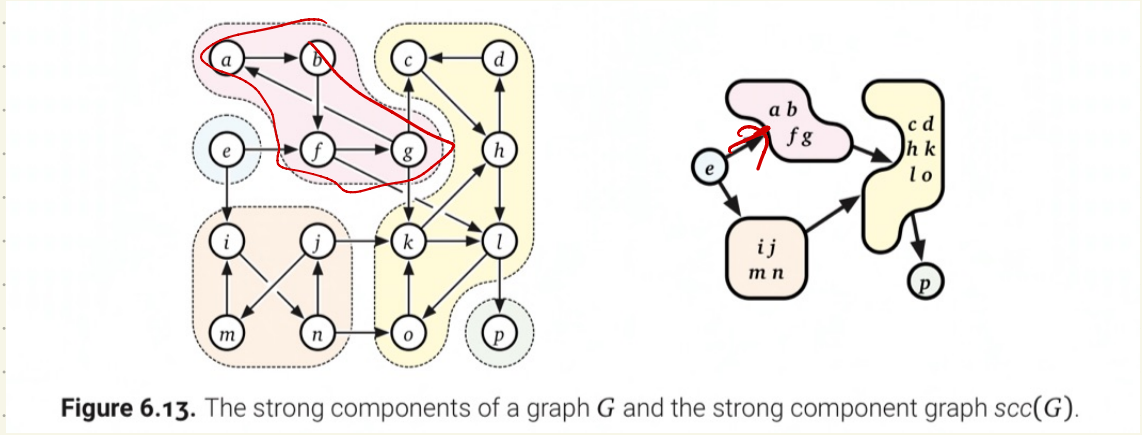


Figure 6.13. The strong components of a graph G and the strong component graph $scc(G)$.

How?

- Well, each component either isn't connected, or only has 1-way edges. Why?

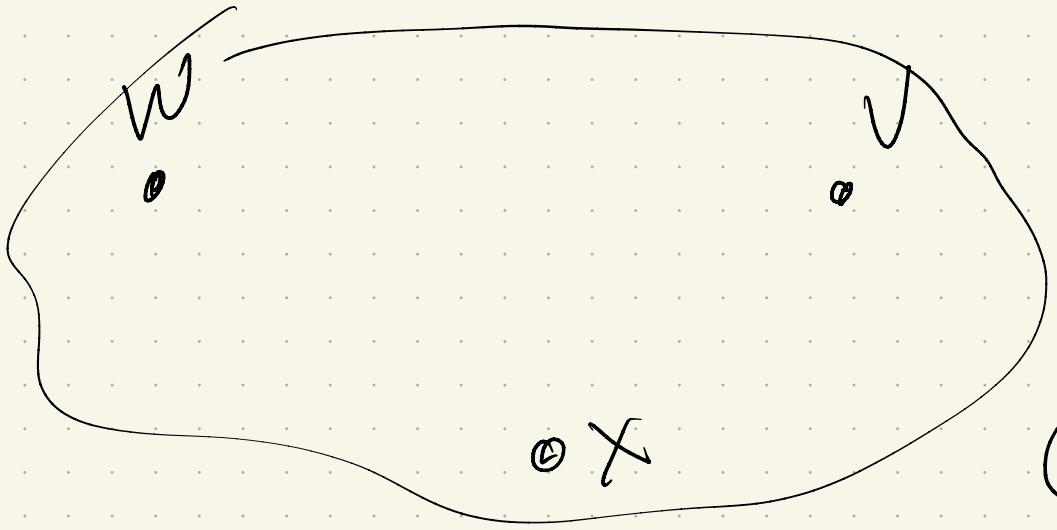
scc

scc

More formally:

Every strong cc must have at least one vertex with no parent.

Proof: Consider two vertices in component



Let x be first vertex in clock-order in sec:

Possible to compute SCCs in $O(V+E)$ time.

Need good sinks!

DFS (rev(G))

↳ find sinks

Then, reverse back to G & run DFS from them.

(See book for details)

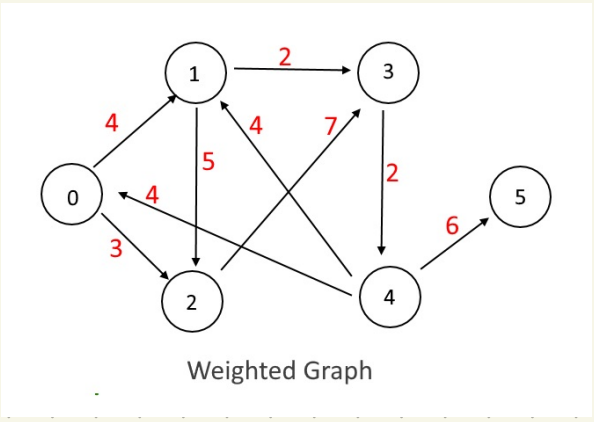
Next module:

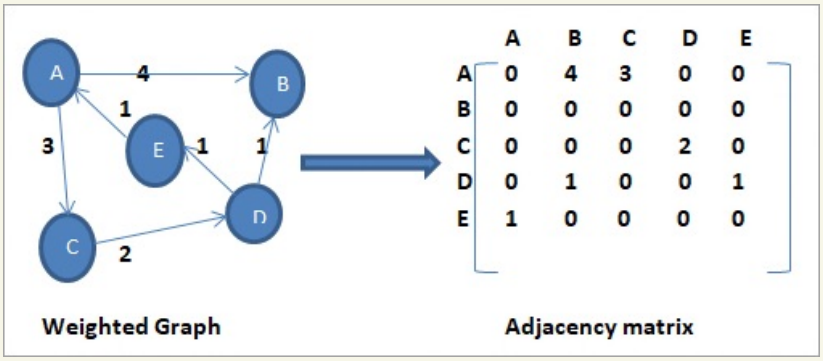
Minimum Spanning trees

& shortest paths.

Both are on weighted graphs - so $G = (V, E)$, plus $W: E \to \mathbb{R}$ (or $\mathbb{R}^+$)

picture:





Minimum Spanning Trees

Goal: Given a weighted Graph G, $w: E \to \mathbb{R}$ the weight function, find a spanning tree T of G that minimizes:

$$w(T) = \sum_{e \in T} w(e)$$

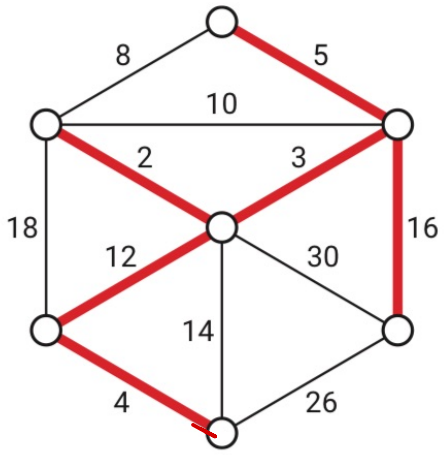


Figure 7.1. A weighted graph and its minimum spanning tree.

Motivation:

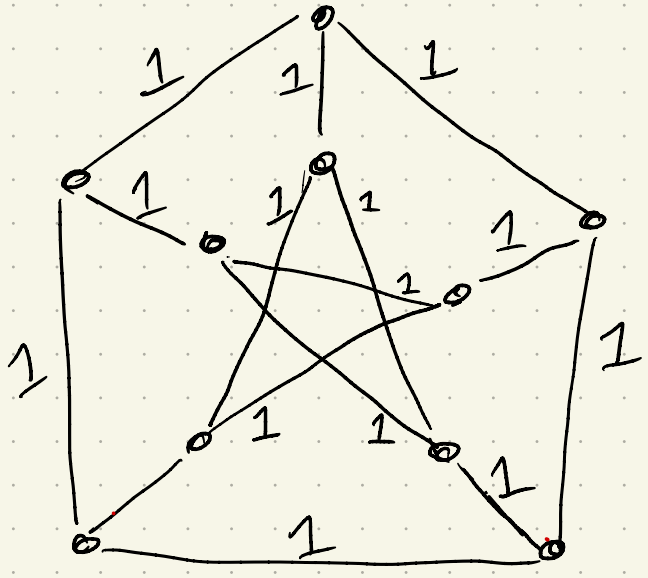
First:

Does it have to be a tree?

Second:

These are obviously not unique!

Ex:



tree?

Things will be cleaner if we have unique trees. So:

Lemma: Assuming all edge weights are distinct, then MST is unique.

Pf: By contradiction:

Suppose T & T' are both MSTs, with $T \neq T'$

- $T \cup T'$ contains a cycle
- That cycle must have 2 edges of equal weight

$\Rightarrow$ Contradiction!

Now, what if weights aren't unique?

Just need a way to consistently break ties.

```
ShorterEdge(i, j, k, l)
  if w(i, j) < w(k, l)          then return (i, j)
  if w(i, j) > w(k, l)          then return (k, l)
  if min(i, j) < min(k, l)      then return (i, j)
  if min(i, j) > min(k, l)      then return (k, l)
  if max(i, j) < max(k, l)      then return (i, j)
  ⟨⟨if max(i,j) > max(k,l)⟩⟩     return (k, l)
```

So, takeaway:

Can assume unique MST.

Next: an algorithm.

The magic truth of MSTs:

You can be SUPER greedy.

Almost any natural idea will work!

This is highly unusual, & there's a reason for it:

these are a (rare) example of something called a matroid.

(Way beyond this class...)