

ver! list: spece or hecking adjacency:
ncy matrix
, pace: O(n²)
ecking adjacency: (m+n)Adjac

oxtra O(n) Space Rearsive DFS (u): If u is unmarked:

mark u

for each eage Su, v 3 & E

Recursive DFS (v) (depth-first search) lo check if sat are connected, Call DFS(s). At end, if t is marked, return true

> "tree":

er version of DFS: not recursive while S is not empty:

V = S. pop

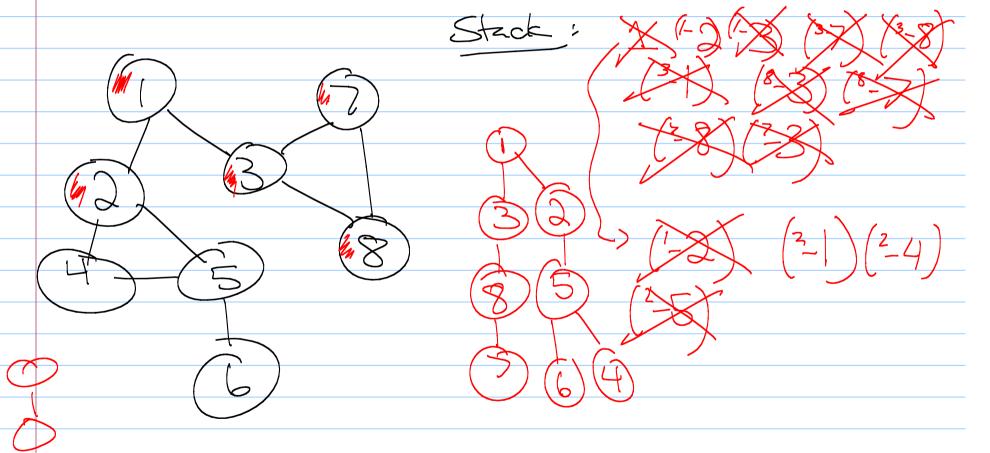
If v is not marked

mark (v)

for each edge vw

S. push (w)

Iterative DFS (1):



Idea: replace stack with a queue! ha ppe a) - Q. push (u) while Q is not empty:

o(i) -> V = Q. pop

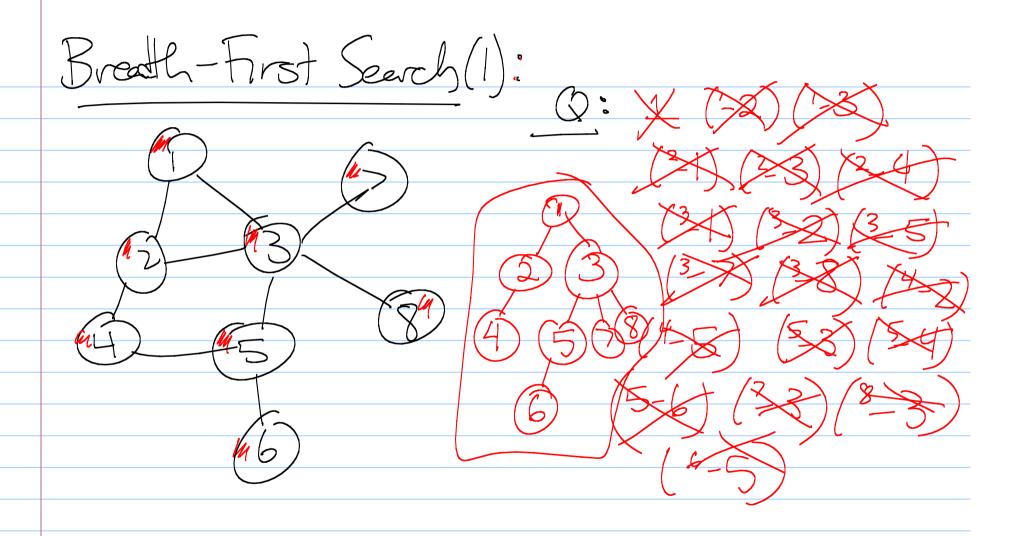
o(i) -> Marked

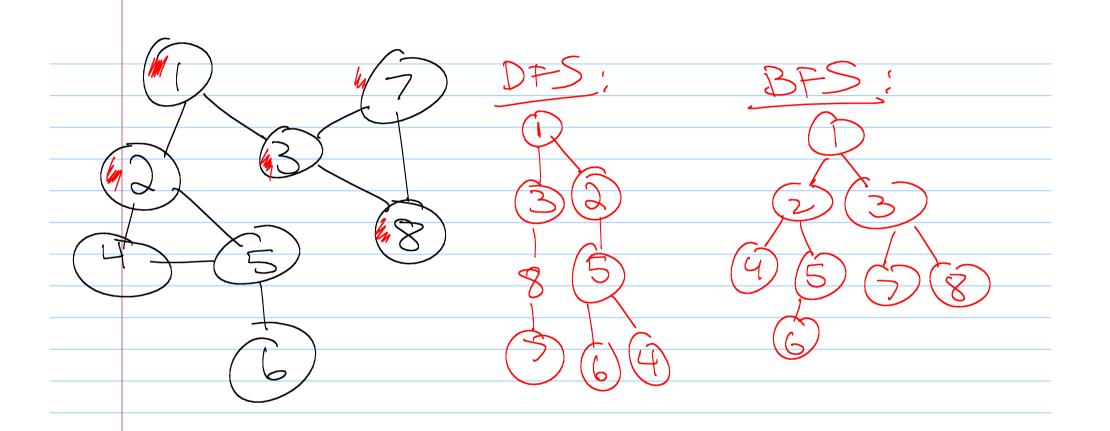
o(i) -> mark (v)

o(d(v)) (for each edge vw

o(d(v)) (for each edge vw

o(d(v)) (for each edge vw)





BFS versus DFS

-Both can tell if 2 vertices are

-Both can be used to detect cycles.

How?

Any edge in addition to the will create a cycle.

- Difference is structure of trees

Each edge is put on stack/queue First time vertex is visited, spend (next time(s) are O(1)) 5 d(v) = 2m = 0(m)

Other graph algorithms
- BFS returns a "short" S-t path,
in some sense. But won't work if graph has weights on the edges. Which s-t path will be in BFS tre? Shortest path trees

Given a weighted graph, find shortest path from s to t.

Uses?

Algorithms to solve this actually solve
I a more general problem:
Find Shortest path from s to
every other vertex.

Called the shortest path tree
rooted at s.

Can be computed in polynomial time.

Another question:

Given G, find a tree containing every vertex with minimum total weight.

Uses?

