CS314 - Union-Find

2/22/2010

Announcements

- HW due Friday

- Next neek's homework won't be due until after break (but don't leave it all for after break!) Minimum Spanning Tree

Idea: Have a set of nodes of want to
build communications network on them.

Have distances (or costs) for each

Possible connection

Goal: Build cheapest network which

connects each pair

Called MST - minimum spanning tree

What we Showed:

Lemma: Let T be a min cost set of edges

Connecting the vertices. Then (V,T) Vis a

Tree.

Let S be any subset of V and let

Cut Prop: Let S be any subset of V and let e be min-cost edge from S to V-S. Every MST must contain e.

Lyde Prop: Let C be a cycle in 6 and let e be the most expansive edge on C. Then e is not in any MST. - Kruskal's: Sort edges, min to max Add edge If it doesn't create a Beckurerds Koruskalis: Sort edges, max to min.

Detete edge if it doesn't dosconnect G. Primis: Take vortex + expand via cheapest Kunning times: Maintain q min-heap which holds every edge leaving S. How many times will I extract Min,? Frims! log m = log n2 - O(log n) How many times might I insert into
(Changekey)
at most once per edge $=) O(m \log n + n \log n) = O(m \log n)$

m things log m = log n = 2 logn m = N og m = O(log n) Kruskals: e.

edges a go in increasi

(m logum) = Q(m logn)

(

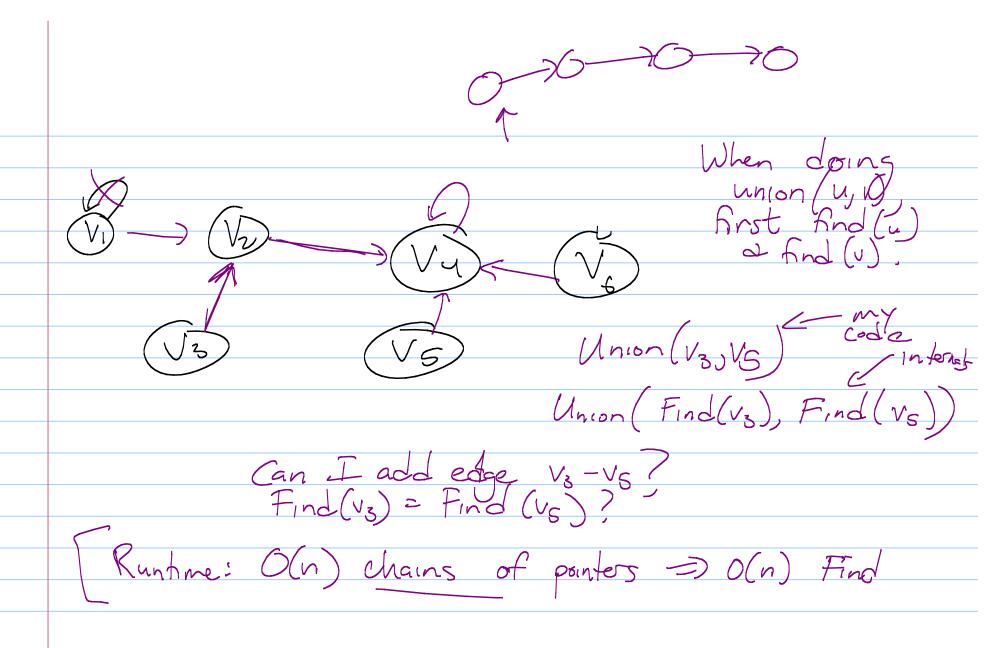
T, f it doesn't create from HW, O(m+n) using BPS/ $O(m \log n + m(m+n))$

Data Structure: Union-Find Suppose we want to maintain connected components in a graph as edges are added. (Want to avoid O(n) search each time!) gi component

) peradons: Find (u): returns name of connected component that vortex u is in Make Unworfind (S): make UF datastructure where each element in S is its Union (u,v): merge the component containing v. Array based implementation: Vivzus vu S6...

Keep an array entry for each element
which stores that set it is in. Find (a): O(1) array lookup A(Union (u,v): O(n)-ick Make UF (S): O(n) Morion (V, Vz Union (Vz) Vo Union (VI) V3

Pointer Based Each node 15 initially alone. Make UF (S) $Find(v_i) = v_i$ Union (V4, V6): repoint at V6 Union (V3, V2) Find (V4) = V6 Union (V6, V6) Find (V4) = V5



To improve:
When Union (vi, vj) is called:

Find(vi)

Find(vj)

Then point smaller set to larger

set. (so Store size

Runtine: Time to Find(v) is now the number of times that the leader of v's component changes Every time leader changes the set must have at least doubled in size, since v was in the smaller part of the uncon. If there are n elements in vs set, how many times could it have doubled? Ollogn

Find (u): O(log n) Union (u,v): O(logn) -> does 2 finds MakeUF(S): O(n) Kruskalis: -Sort edges O(mlogn)
- Create let O(n)

For T- Test of new edge will cr
each 2 Finds: O(logn)

edge Union O(logn)

O(mlogn) + O(mlogn) este a cycle. An improvement (not necessary for Kruskal's but shithice):

What is worst case for find?

(ie when does it happen?)

Find (v) (og n

ind (v) (og n

on Py to root Path-Compression: repoint every one at representative Find (v)

By shortening path from v to x we make later Find calls quicker. We won't do defailed analysis
but in Find/Union operations gives
O(n d(n)) time, almost O(1) per
d(n) = inverse Ackermann function opa essentially, this is O(n) time