

Algorithms - Spring 2025

Flows + Cuts



Recap

- No class next Monday, and office hours will be Wed: 1-3
- HW - due tonight
- Next HW: flows

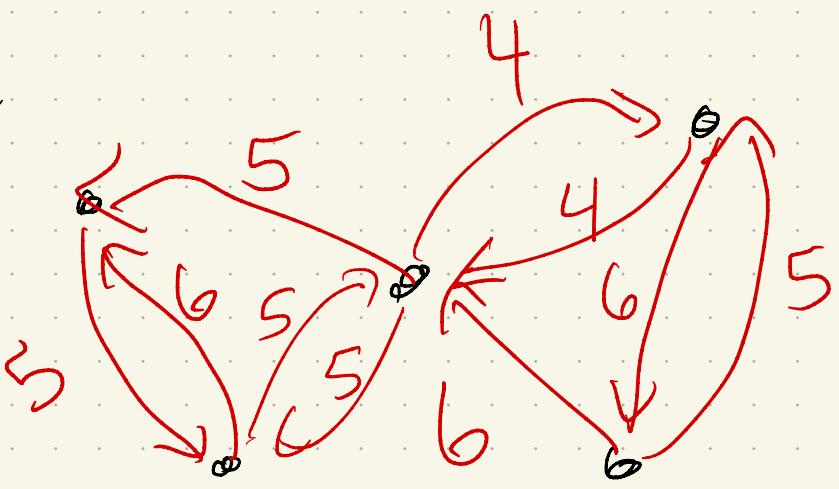
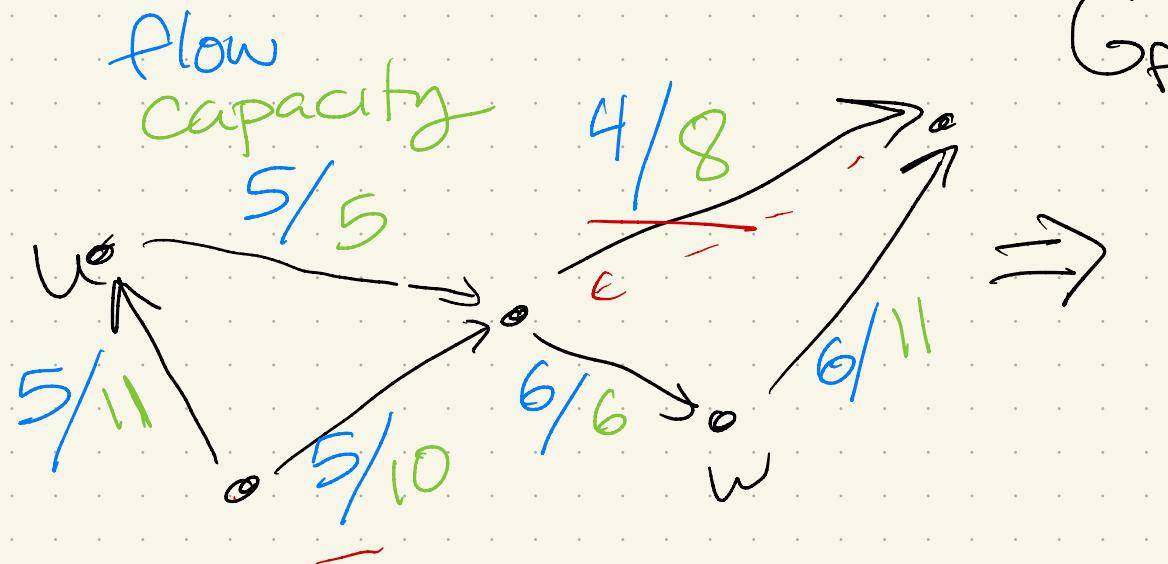
More formally: Residual network G_f :

Given G & f :

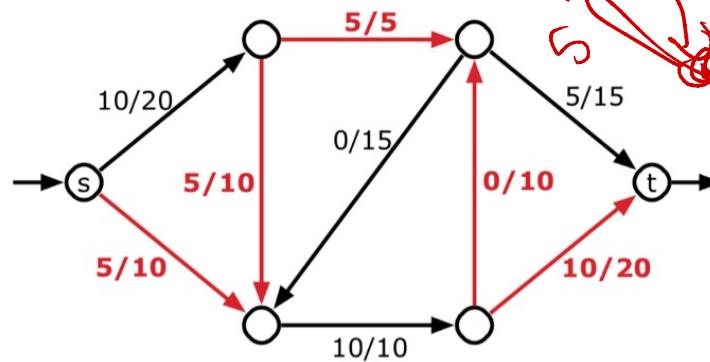
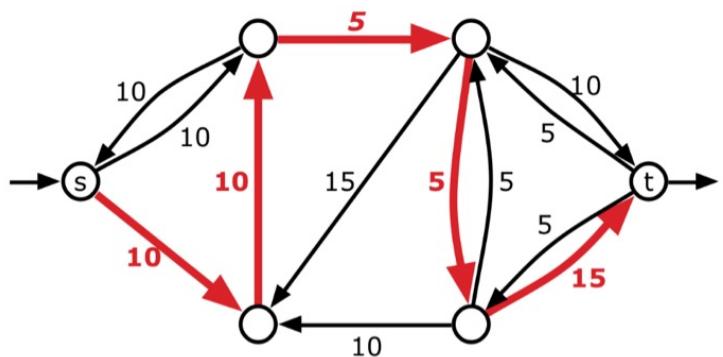
$$C_f(u \rightarrow v) = \begin{cases} c(u \rightarrow v) - f(u \rightarrow v) & \text{if } u \rightarrow v \\ f(u \rightarrow v) & \text{if } v \rightarrow u \text{ is in } E \\ \text{no edge (or } 0\text{)} & \text{otherwise} \end{cases}$$

*if $u \rightarrow v$
is in E*
*~~if reverse
edge~~*

Ex: G, f



Augmenting a path: send more!

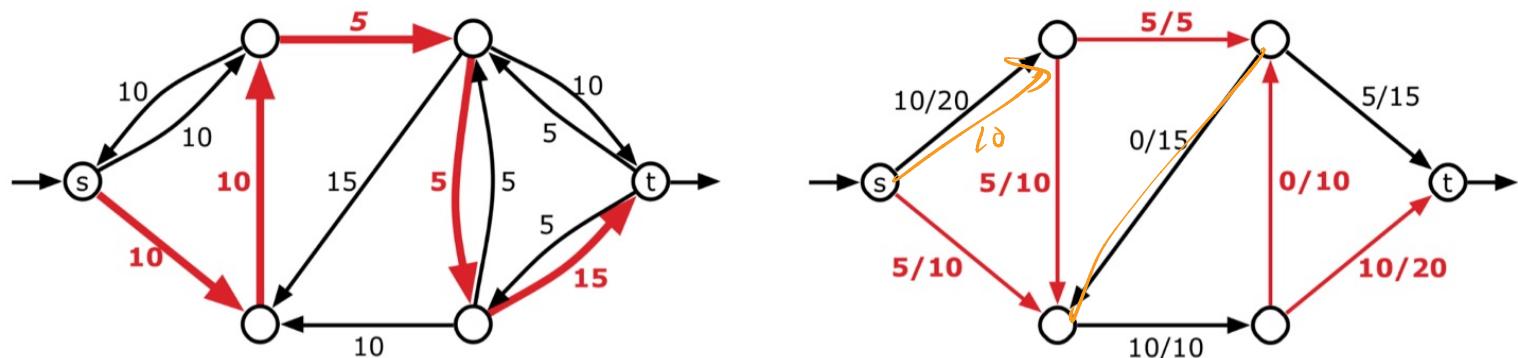


An augmenting path in G_f with value $F = 5$ and the augmented flow f' .

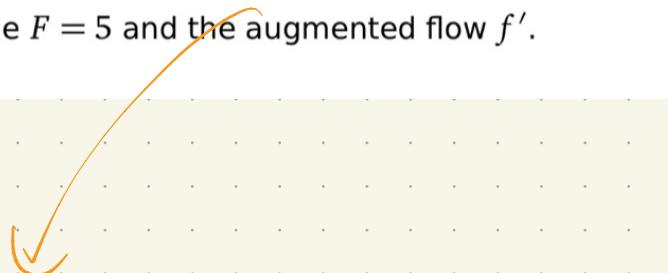
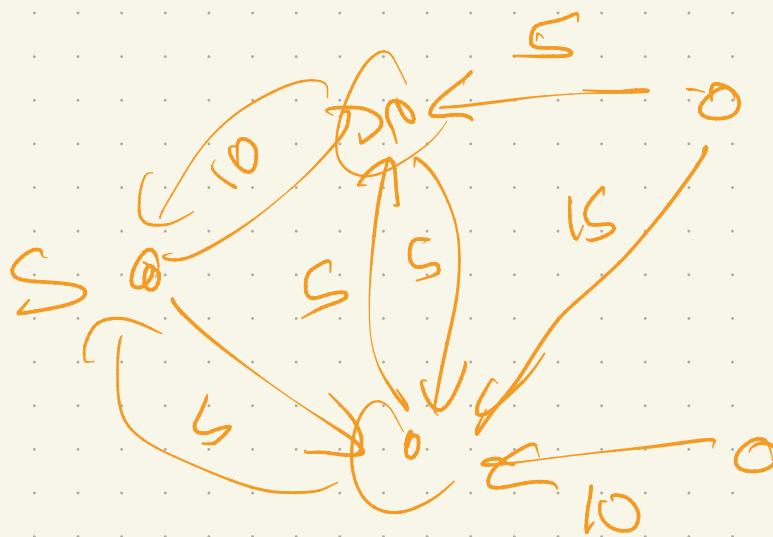
This is just an s - t path in G_f .

Then, find min capacity edge on that path

Claim: I can build a new flow whose value is bigger than f 's



An augmenting path in G_f with value $F = 5$ and the augmented flow f' .



Claim: If f is a maximum flow,
then G_f has no augmenting path

Proof: by contradiction

Assume f is maximum.

Build G_f & find path.

Use this path a bigger flow

bottle
neck
age

f' .

→ Then f was not
maximum

So: f wasn't a max flow, since f' is larger.

On other hand:

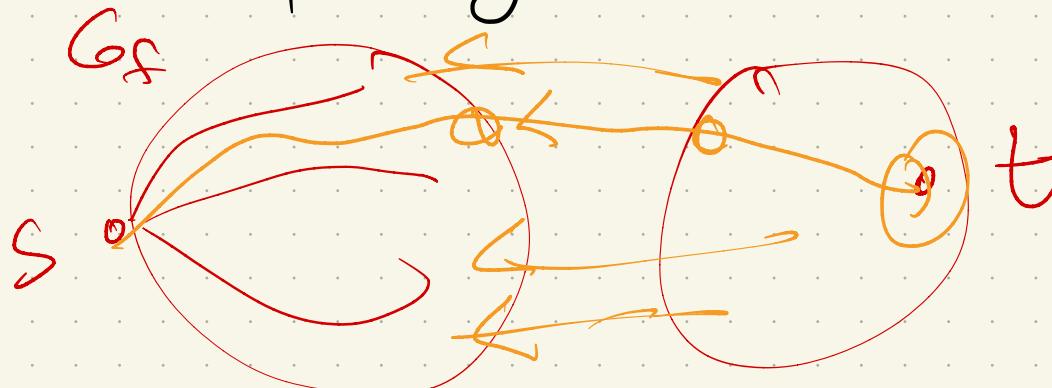
If G_f has no $s \rightarrow t$ path, find

$|S| =$ set of vertices that s can reach

Claim: $(S, V-S)$ is a cut.

(+ f uses every $S \rightarrow V-S$ edge to its max capacity)

Why?



Immediate Algorithm: $(V+E) \cdot f^*$

Start with $f = 0$.

Build G_f

$\text{WFS}(G_f, s)$

While $t + s$ in same component:

find $s \rightarrow t$ path via WFS

Augement along the path to get f'

$f \leftarrow f'$

Build G_f

$\text{WFS}(G_f, s)$

$\sim V+E$

$V+E \geq O(B)$

t and s are ~~set~~ connected

~~✓~~

every

time, flow increases

$V+E$

$O(N)$

Runtime?

loop repeats $\leq f^*$ times

Why all this integrality stuff?

We are assuming each path pushes at least 1 more unit of flow!

Can it be that bad?

Yes:

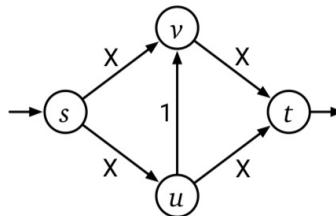


Figure 10.7. Edmonds and Karp's bad example for the Ford-Fulkerson algorithm.

+1 each round if bottleneck is not cap = 1 edge

How "big" is f^* ?

(Remember, not part of input!)

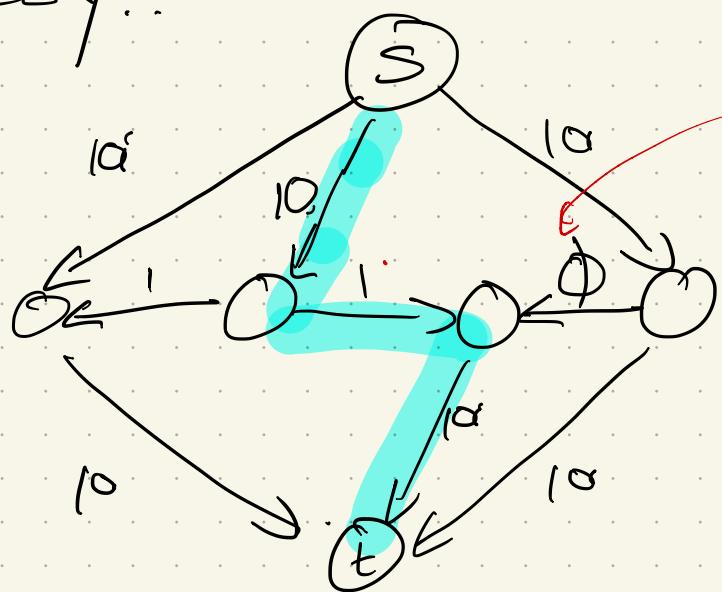
$f^* \leq$ (at edges w/)

~~s~~

~~t~~ +

What if it's not integers?

Messy!!



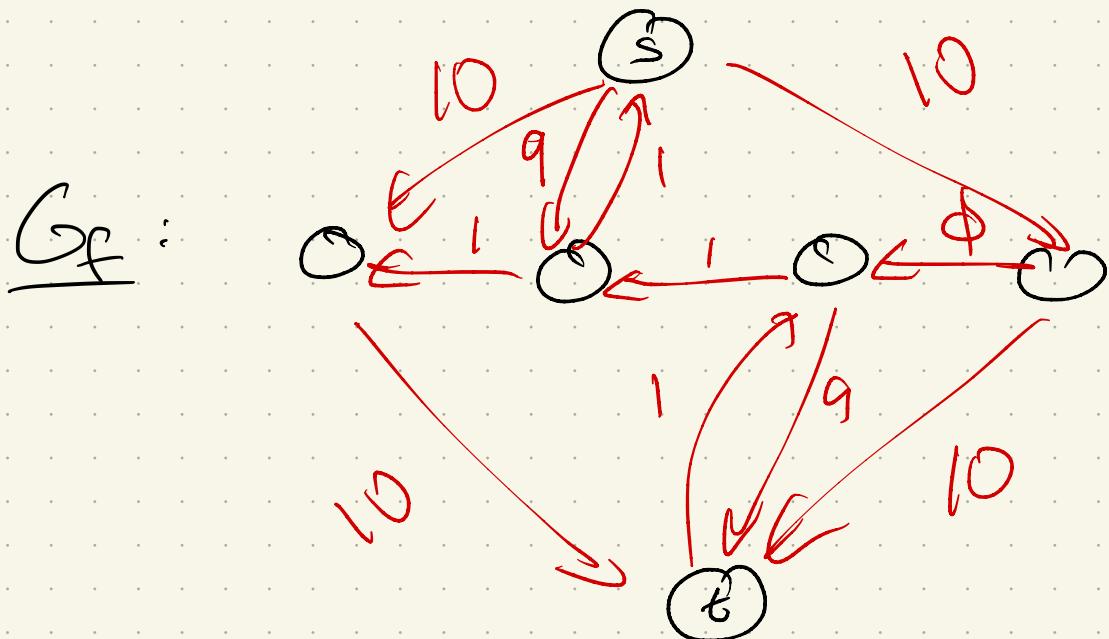
The key:

$$\phi = \frac{1 + \sqrt{5}}{2}$$

WHY??

Simple:

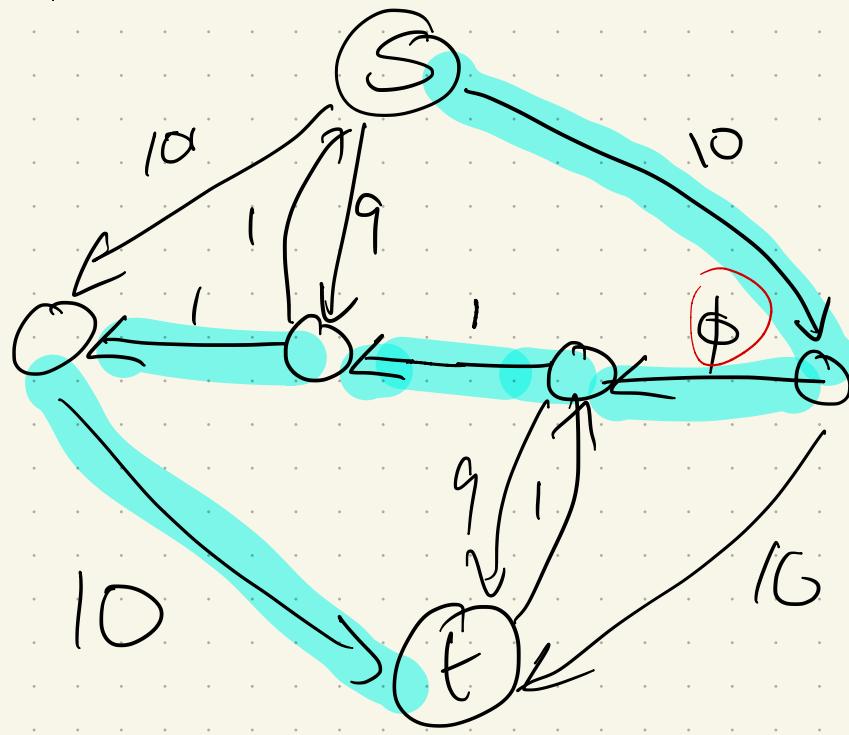
$$1 - \phi = \phi^2$$



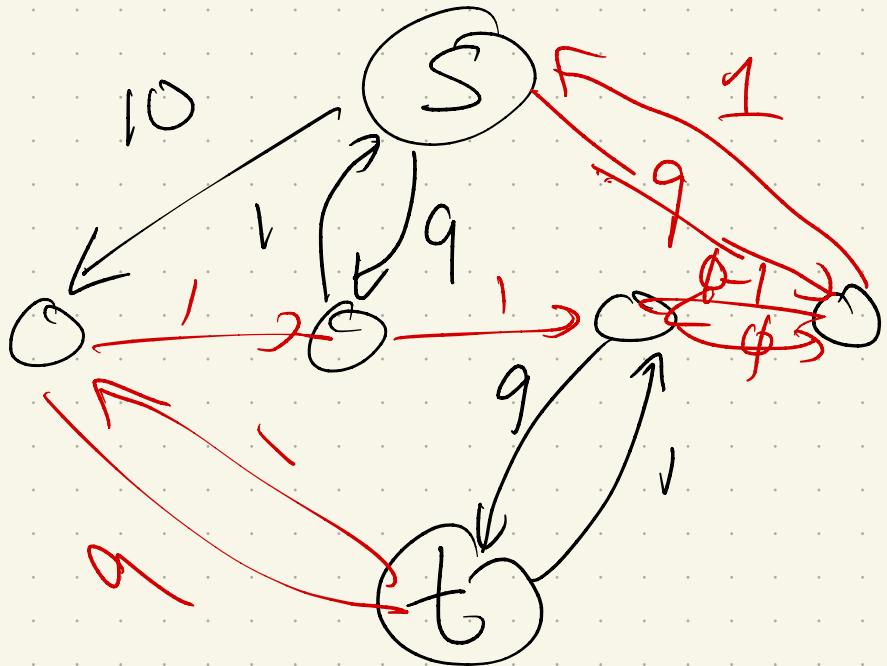
Gf:

flow of
val = 1

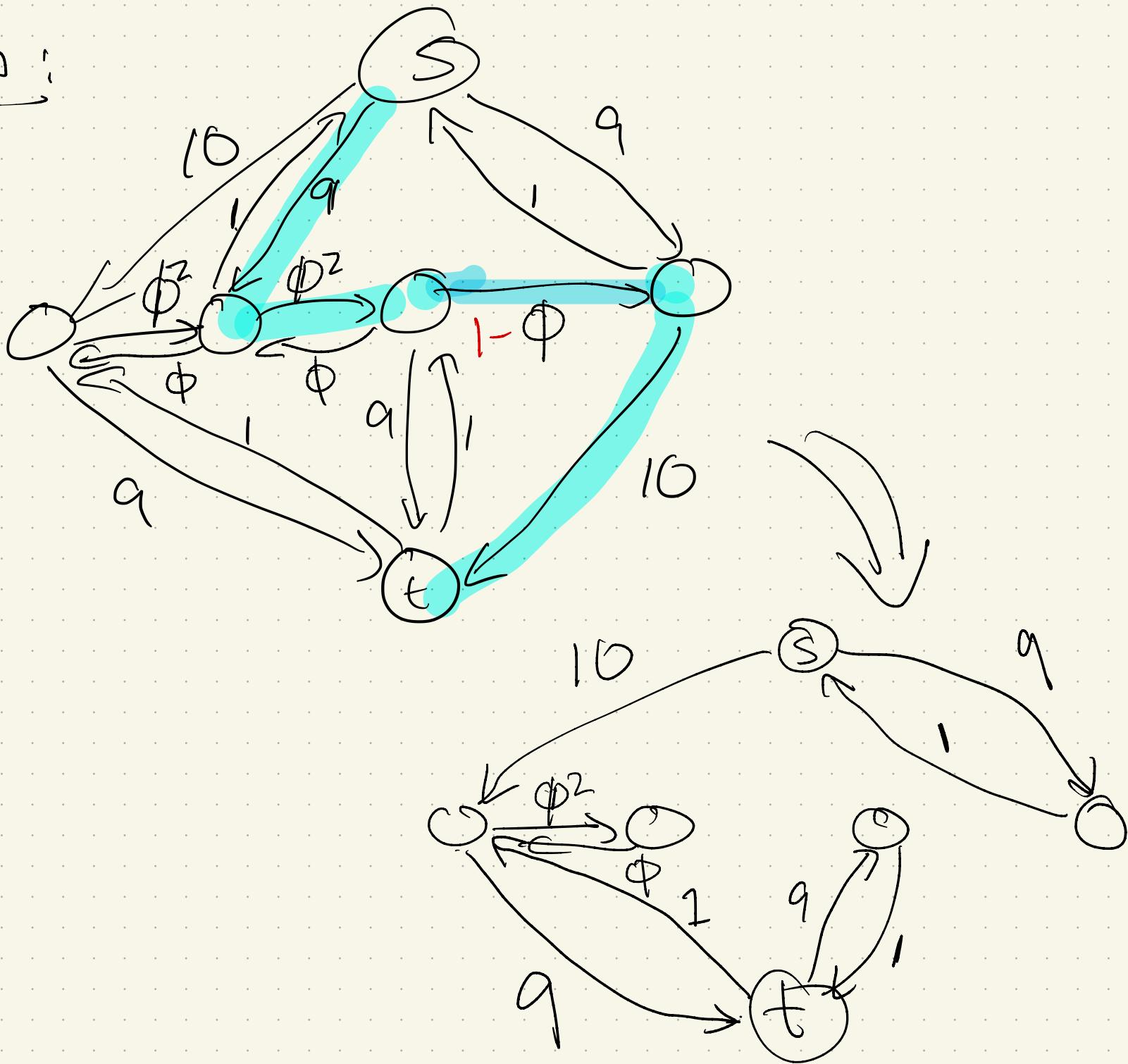
Next path:



↙
New G_F :



Then:



Continue to push:

assume
integers!

Ends with:

ϕ , 0, and

$$1-\phi = \phi^2$$

Repeat:

• ϕ^2 , 0, ϕ^3

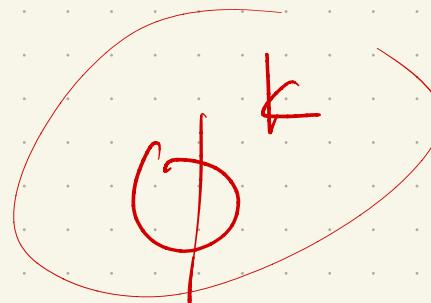
$$(1-\phi)\phi$$

then

•

etc

•

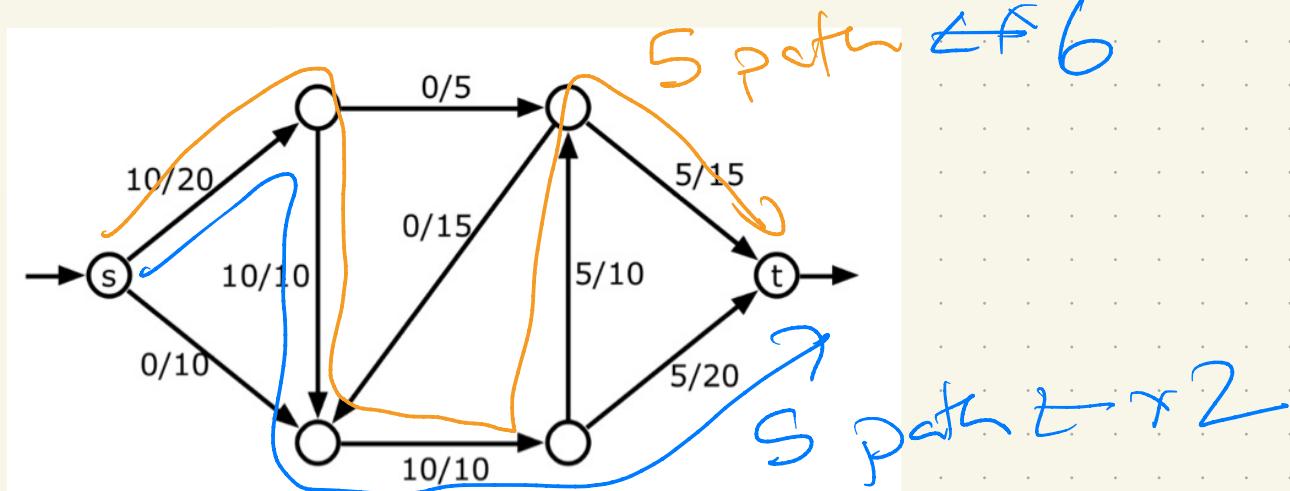


But, max flow = 21

General framework: Decomposing flows

Given a valid flow, we have an intuition that it "follows" paths:

But: it's a function! (no paths.)



That said, this intuition does hold in some sense!

Formalizing:
 Linear combinations of flows
 result in flows:
 (ignoring capacities)

$$h(u \rightarrow v) = \alpha \cdot f(u \rightarrow v) + \beta g(u \rightarrow v)$$

$$f(u \rightarrow v) = 5$$

$$g(u \rightarrow v) = 1$$

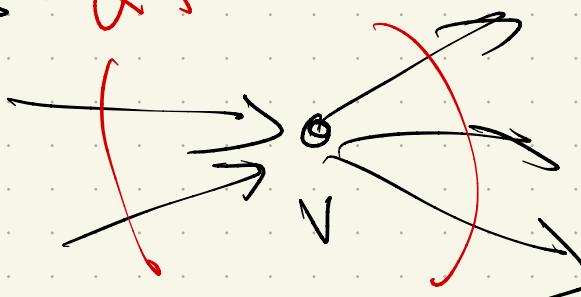
$$h = 2 \cdot 5 + 3 \cdot 1$$

$$= 13$$

$$\text{vertex constraints: } \alpha f + \beta g \leq h$$

vertex constraints:

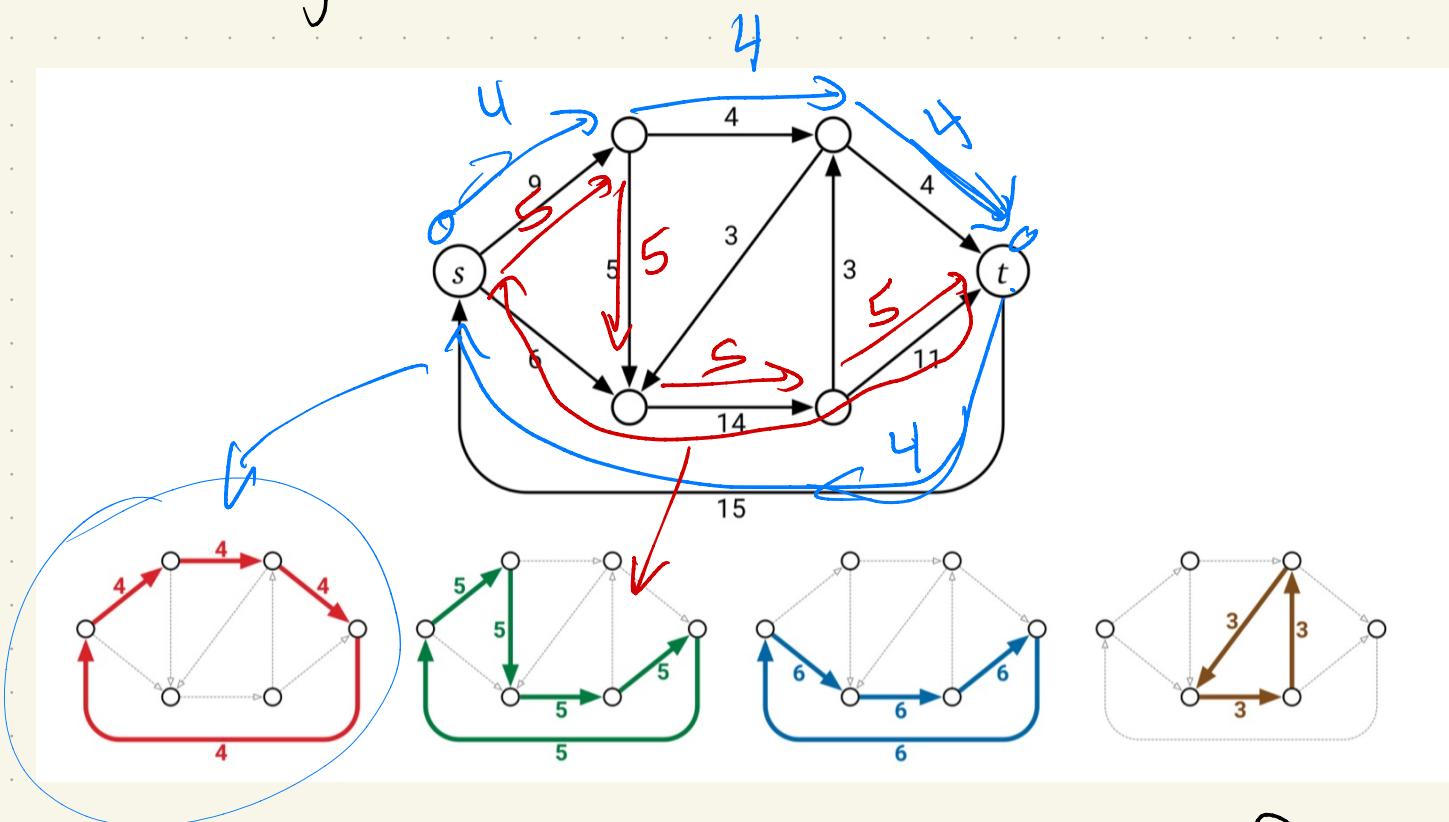
all OK



Flow decomposition:

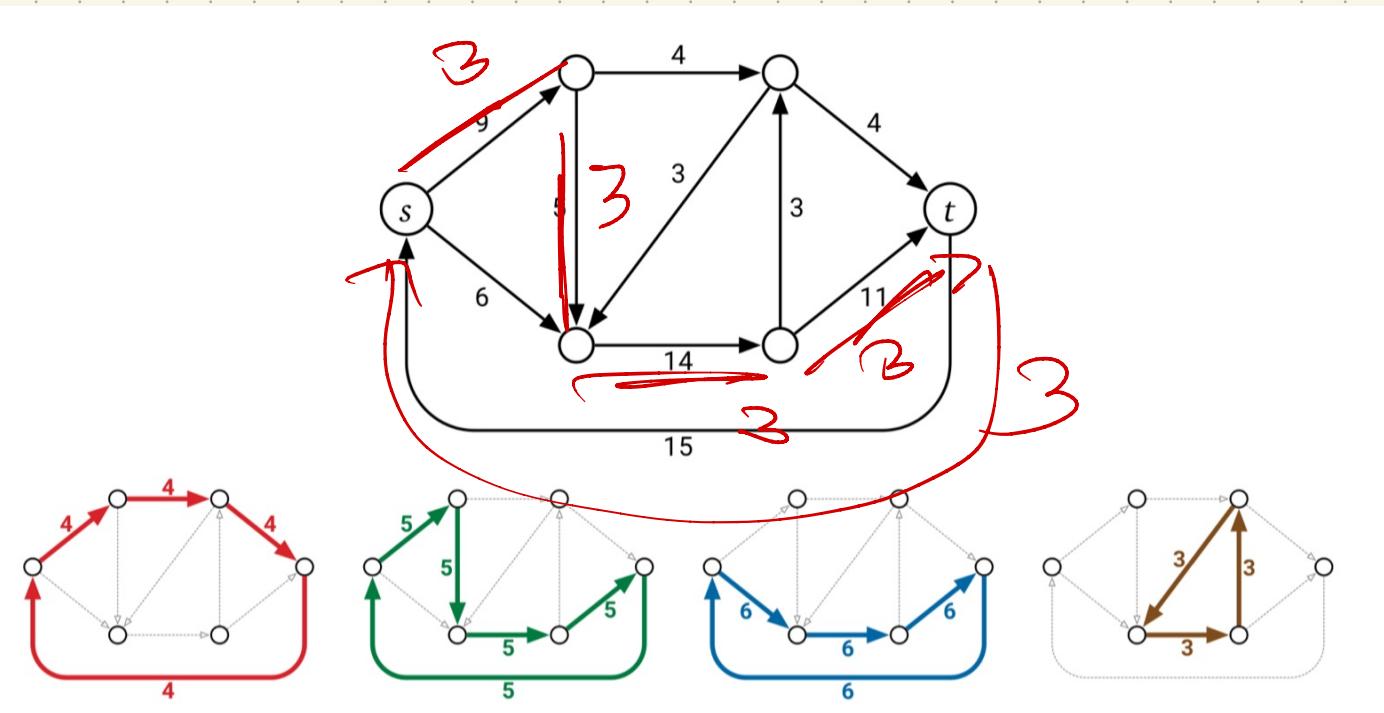
flow in flow out

Add an edge $t \rightarrow s$, + can decompose a flow into cycles:



S.t. "Sum" of cycles = flow.

Not unique:



Why care?

Suggests general strategy in FF

of "find a path & push" will
always get you to best flow
(if integer capacity).

Let's see how it works...

Faster versions

This is an active area of research!
We'll see two faster examples,
both (relatively) simple variations
on the Ford-Fulkerson algorithm:

- ① Edmonds - Karp: choose largest bottleneck edge

$$\hookrightarrow O(E^2 \log E \log f^*)$$

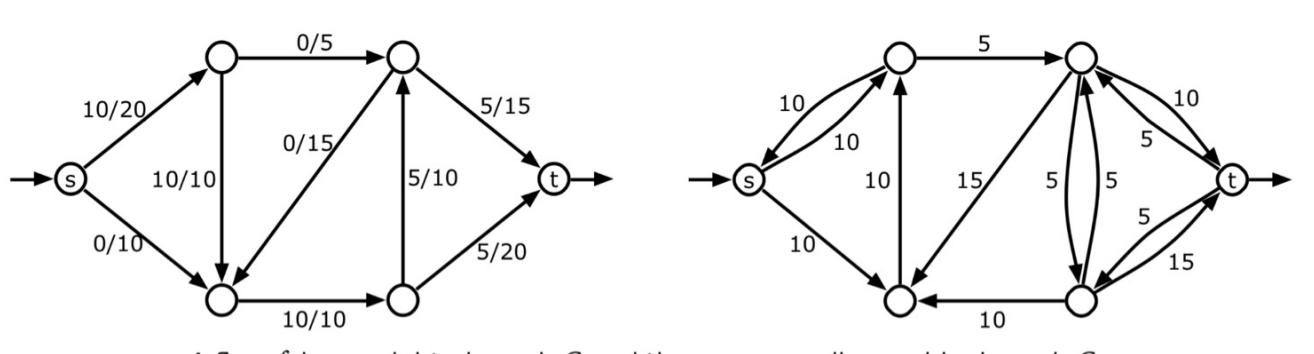
- ② shortest augmenting path (fewest edges)

$$\hookrightarrow O(VE^2)$$

Edmonds-Karp:

Largest bottleneck: how?

Take G_f :



Grow a tree from s , adding largest edge out each time' ↳ Similar to HW!

Runtime:

variant of MST: $E \log V$

E-K

~~MAXFLOW(G)~~:

Let $f(e) = 0$ initially $\forall e$
Construct G_f

While there is $s-t$ path in G_f :

~~Let p be a simple augmenting path~~

$f' \leftarrow \text{augment}(f, p)$

~~path~~

V+E
s(t)
update G_f

return f

Replace:

~~Flog~~ ✓

Let p be the largest bottleneck path

of repetitions in loop?

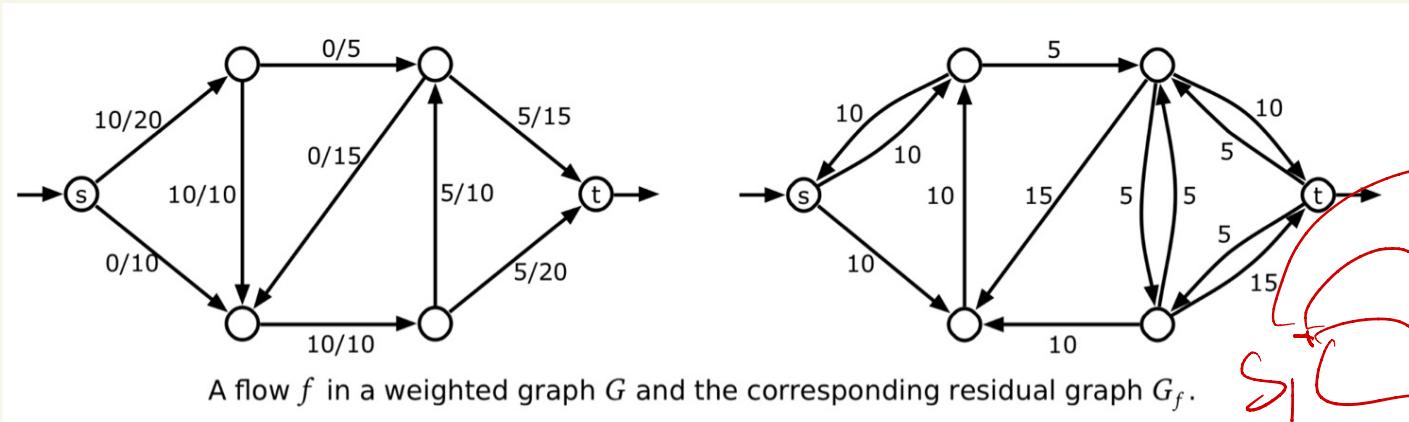
In FF, went down by ≥ 1 .

Here? Hopefully better!

Key: look at current flow

loop repetitions:

Consider current flow:

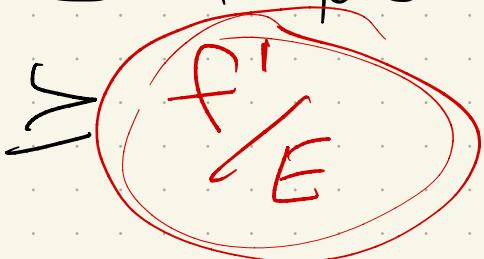


Residual graph: Also a flow graph.

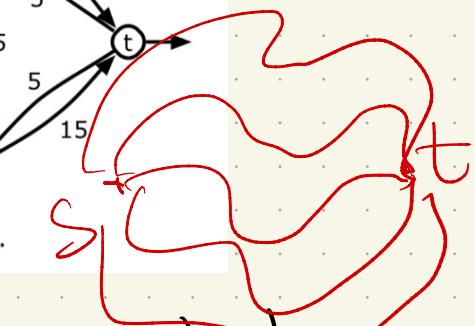
Let f' be max flow in G_f .

G_f has f' flow, & at most E paths from s to t

\Rightarrow One of them is big:



total is f'



$\leq E$

So: adds $\geq \frac{f'}{E}$ to flow $f' - \frac{f'}{E}$ next time

\Rightarrow next residual graph will have $\geq (1 - \frac{1}{E}) f'$ in it.

\hookrightarrow $(1 - \frac{1}{|E|})^l f^*$ repetitions

What is l ?

Well, $l = E \cdot \ln f^*$ repetitions,

$$(1 - \frac{1}{|E|})^l f^* < 1$$

Wait: < 1 ??

\hookrightarrow must hit integer since valued

$$f' \rightarrow \left(1 - \frac{1}{E}\right) f'$$

\downarrow

$$\left(1 - \frac{1}{E}\right)^2 f'$$

$$\left(1 - \frac{1}{E}\right)^3 f'$$

\vdots smaller

E-K

~~MAXFLOW(G)~~:

Let $f(e) = 0$ initially $\forall e$
Construct G_f

While there is s-t path in G_f :

~~let p be a simple augmenting
path~~
 $f' \leftarrow \text{augment}(f, p)$

update G_f

return f

Replace:

Let p be the
largest bottleneck
path

Inside of
loop: find bottleneck:

$$E \log V + (V+E)$$

+ # iterations: $E \ln f$

$$\Rightarrow O(E^2 \log V \ln f)$$

Shortest paths \leftarrow min # of edges

Let $P = \text{shortest}$

~~MAX FLOW (G)~~:

Let $f(e) = 0$ initially $\forall e$
Construct G_f

while there is s-t path in G_f

~~let P be a simple s-t path~~

$f' \leftarrow \text{augment}(f, P)$

$f \leftarrow f'$
update G_f

return f

s-t path

(# edges, not
capacities)

$V+E$

$V+E$

Which traversal?

BFS

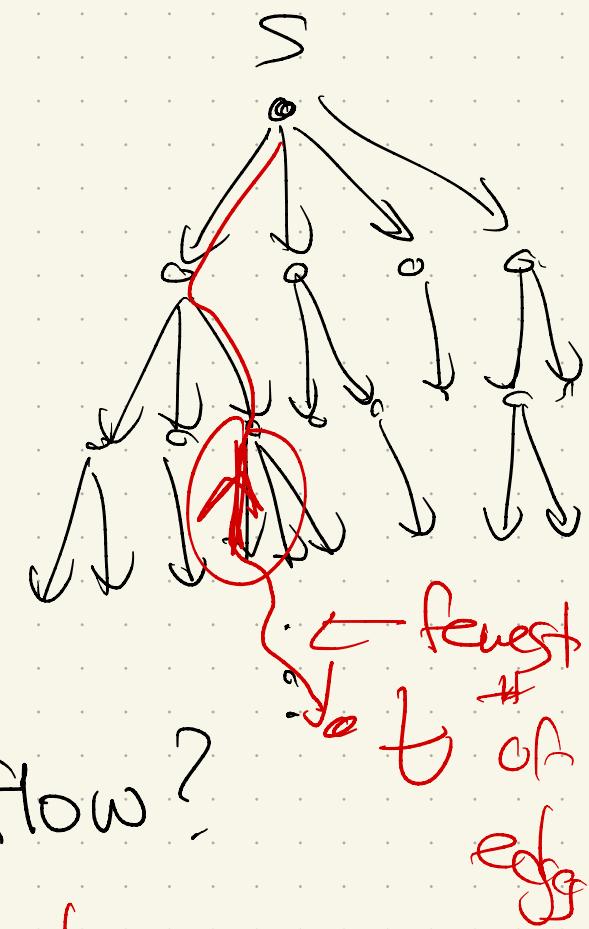
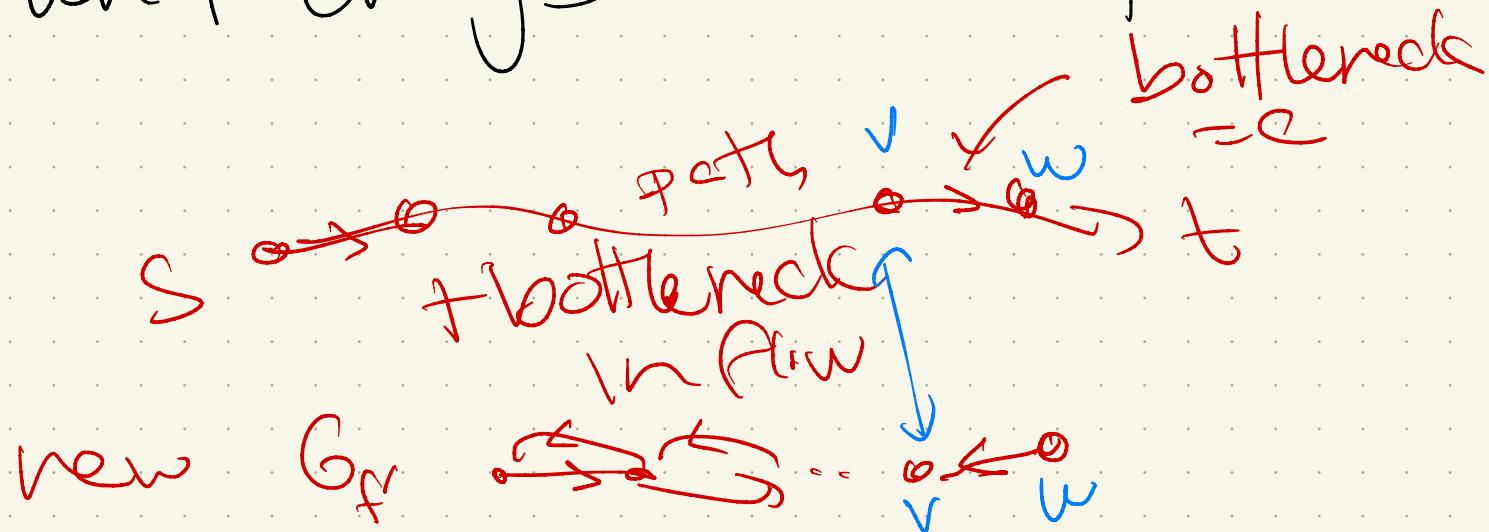
So inside of loop = $O(V+E)$

Q: How many times do we need a path?

(ie: how many repetitions of the while loop?)

Think of G_f + the BFS tree rooted at s_0 .

What changes after we push flow?



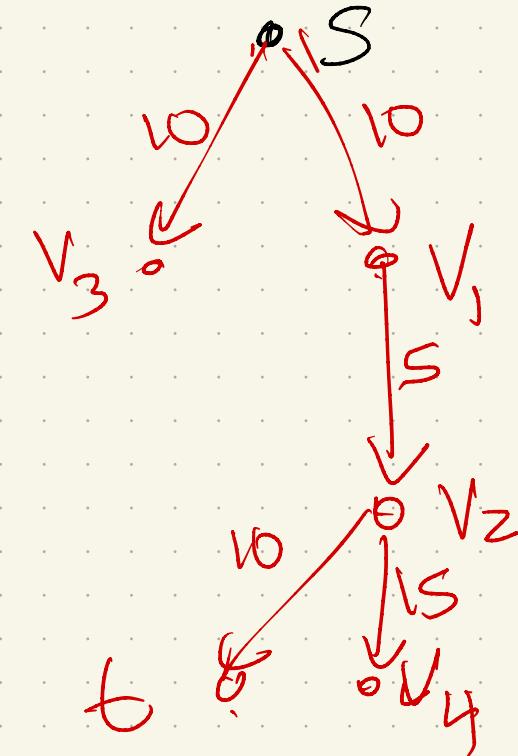
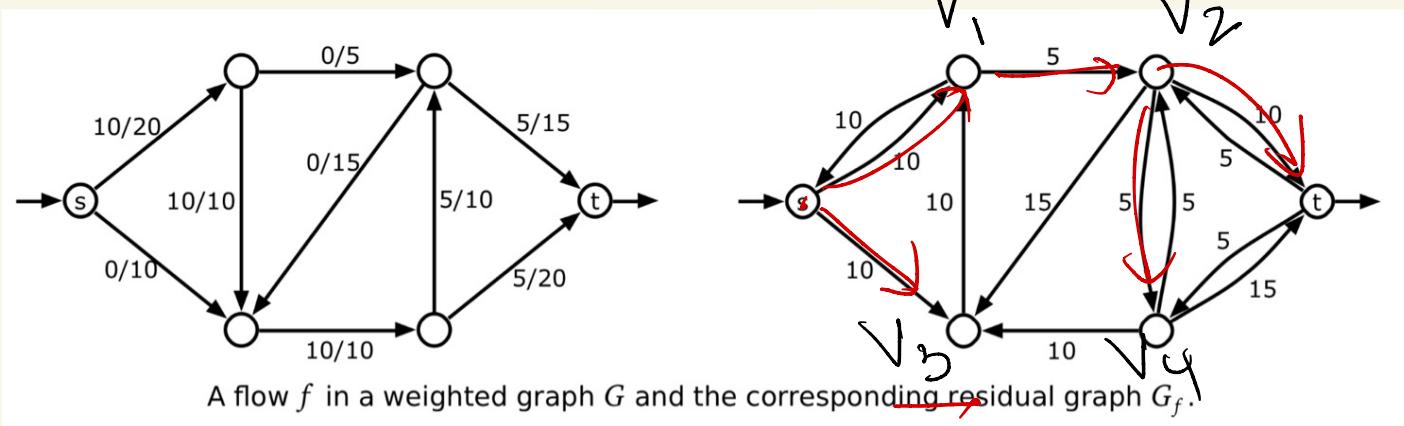
Let G_0 = initial G_f

+ G_i^o = residual graph after i repetitions of the loop.

G_i^o has a BFS tree T_i^o , so let

$$\text{level}_i^o(v) = \text{depth in tree}$$

(Note: once S can't reach t , BFS tree:
then $\text{level}(t) = \infty$)



Claim: levels only get bigger
in each round.

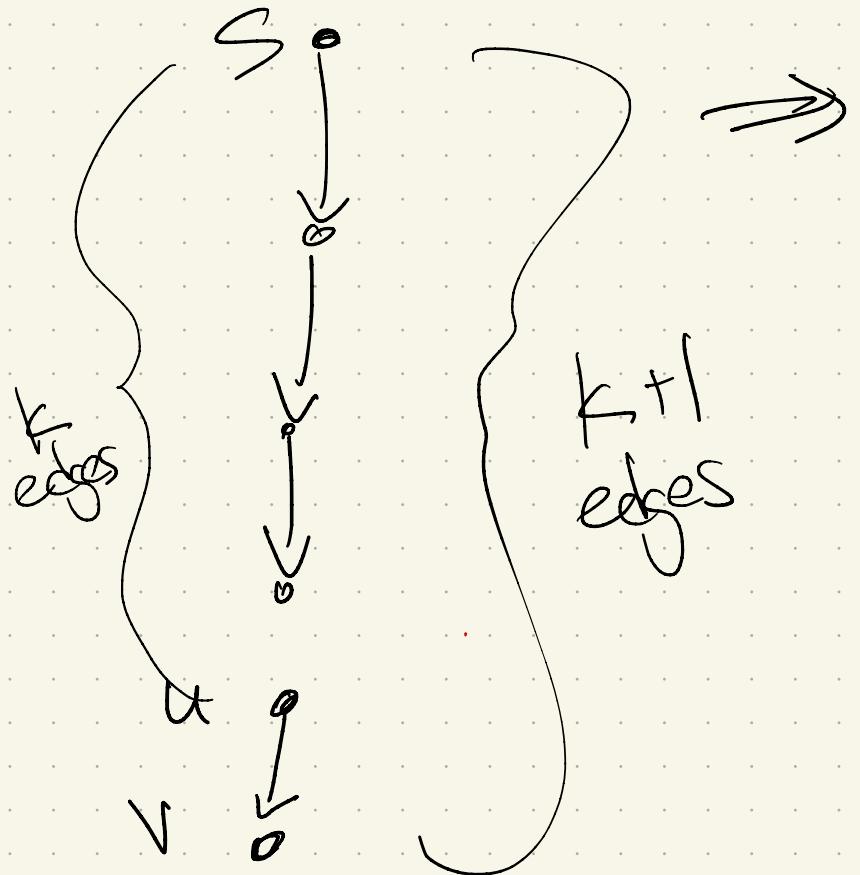
Proof: induction on level. (fix i)

base case: S (level 0), always stays ≥ 0

IH: consider levels $\leq k$ in G_i .
for any such u on level $\leq k$,
 $\text{level}_{i-1}(u) \leq \text{level}_i(u)$

IS: now take v on level $k+1$ of G_i :

Must be a path $s \rightsquigarrow v$



take u just before
 v on path

Now: how did we get this
path in G_i ?

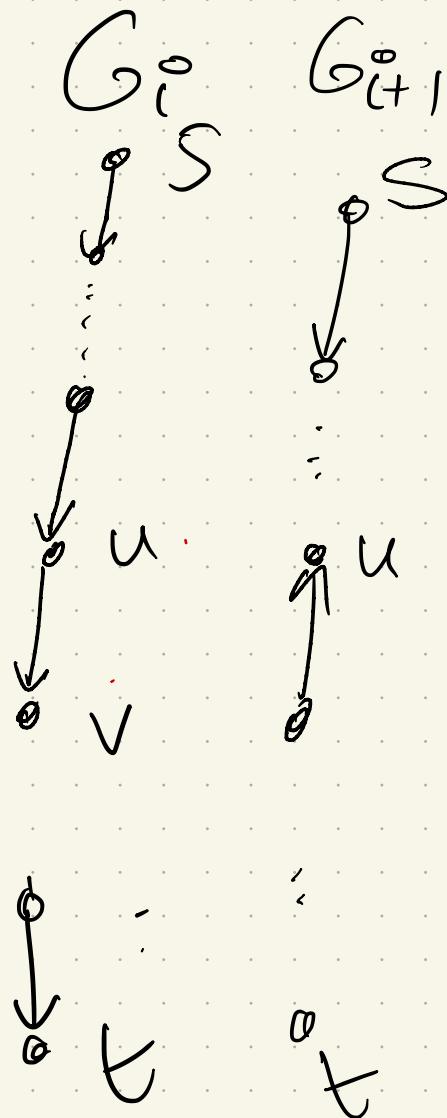
Cont:

- $u \rightarrow v$ is an edge in G_{i-1}°
 $\text{level}_{i-1}(v) \leq \text{level}_{i-1}(u) + 1$

- might have come from pushing in G_i :
here, it came from pushing a shortest path in the last round.
so $v \rightarrow u$ was used last round.

Then: Edges can disappear & reappear.

How many times?



level (v)

got

bigger!

level (v)
got bigger

G_j^o

If level
goes up
+2, after
 $\frac{V}{2}$ rounds



In each iteration of the loop —
some edge disappears!

⇒ $\frac{V}{2} \cdot E$ repetitions

Total:

MAXFlow (G):

Let $f(e) = 0$ initially $\forall e$
Construct G_f

while there is $s-t$ path in G_f

~~let P be a simple $s-t$ path~~

$f' \leftarrow \text{augment}(f, P)$

$f \leftarrow f'$

update G_f

return f

Let $P = \text{shortest}$

$s-t$ path

(# edges, not
capacities)

$$V \cdot E \cdot (V + E)$$

$$= VE^2$$

And... not done!

Technique	Direct	With dynamic trees	Source(s)
Blocking flow	$O(V^2E)$	$O(VE \log V)$	[Dinitz; Karzanov; Even and Itai; Sleator and Tarjan]
Network simplex	$O(V^2E)$	$O(VE \log V)$	[Dantzig; Goldfarb and Hao; Goldberg, Grigoriadis, and Tarjan]
Push-relabel (generic)	$O(V^2E)$	—	[Goldberg and Tarjan]
Push-relabel (FIFO)	$O(V^3)$	$O(VE \log(V^2/E))$	[Goldberg and Tarjan]
Push-relabel (highest label)	$O(V^2\sqrt{E})$	—	[Cheriyan and Maheshwari; Tunçel]
Push-relabel-add games	—	$O(VE \log_{E/(V \log V)} V)$	[Cheriyan and Hagerup; King, Rao, and Tarjan]
Pseudoflow	$O(V^2E)$	$O(VE \log V)$	[Hochbaum]
Pseudoflow (highest label)	$O(V^3)$	$O(VE \log(V^2/E))$	[Hochbaum and Orlin]
Incremental BFS	$O(V^2E)$	$O(VE \log(V^2/E))$	[Goldberg, Held, Kaplan, Tarjan, and Werneck]
Compact networks	—	$O(VE)$	[Orlin]

Figure 10.10. Several purely combinatorial maximum-flow algorithms and their running times.

Many use
very different
techniques

- linear programming
- complex data structures
- not residual graphs

Still active :

Showing 1–50 of 368 results for all: maximum flow in graphs

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maximum flow in graphs

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1 2 3 4 5 ... Next

1. arXiv:2503.20985 [pdf, ps, other] cs.DS
Deterministic Vertex Connectivity via Common-Neighborhood Clustering and Pseudorandomness
Authors: Yonggang Jiang, Chaitanya Nalam, Thatchaphol Saranurak, Sorrachai Yingchareonthawornchai
Abstract: We give a deterministic algorithm for computing a global minimum vertex cut in a vertex-weighted graph n vertices and m edges in $\tilde{O}(mn)$ time. This breaks the long-standing $\tilde{\Omega}(n^4)$ -time barrier in dense... ▾ More
Submitted 26 March, 2025; originally announced March 2025.

2. arXiv:2503.13274 [pdf, ps, other] cs.DS
Parallel Minimum Cost Flow in Near-Linear Work and Square Root Depth for Dense Instances
Authors: Jan van den Brand, Hossein Gholizadeh, Yonggang Jiang, Tijn de Vos
Abstract: ...edge graphs with integer polynomially-bounded costs and capacities, we provide a randomized parallel algorithm for the minimum cost flow problem with $\tilde{O}(m + n^{1.5})$ work and $\tilde{O}(\sqrt{n})$ depth. On moderately dense graphs ($m > n^{1.5}$), our algorithm is the first... ▾ More
Submitted 17 March, 2025; originally announced March 2025.

3. arXiv:2502.09105 [pdf, other] cs.DS
Incremental Approximate Maximum Flow via Residual Graph Sparsification
Authors: Gramoz Goranci, Monika Henzinger, Harald Räcke, A. R. Sricharan
Abstract: ...maximum flow in undirected, uncapacitated n -vertex graphs undergoing m edge insertions in $\tilde{O}(m + nF^*/\epsilon)$ total update time, where F^* is the... ▾ More
Submitted 13 February, 2025; originally announced February 2025.

Plus work for special classes of graphs:
planar, sparse, etc.