

CS2100

Intro to graphs



Recap

- HW due Wed.
- Worksheet: coming (today)
- Review: 1 week from today
- Sample final coming tomorrow
- No lab - lecture instead
- Wed next week: 8am final
- No office hours today

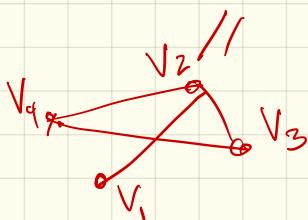
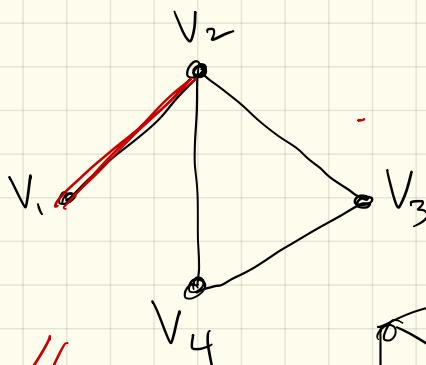
Graphs

A graph $G = (V, E)$ is an ordered pair of 2 sets:

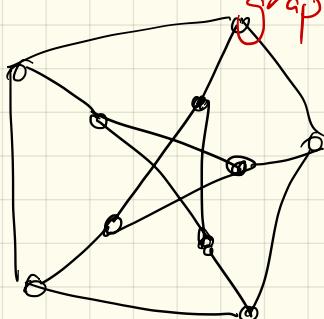
$$V = \text{vertices} = \{v_1, v_2, v_3, v_4\}$$

$$E = \text{edges} = \{\{v_1, v_2\}, \{v_2, v_3\}, \{v_3, v_4\}, \{v_2, v_4\}\}$$

View:



Peterson graph



Why?

They model everything!

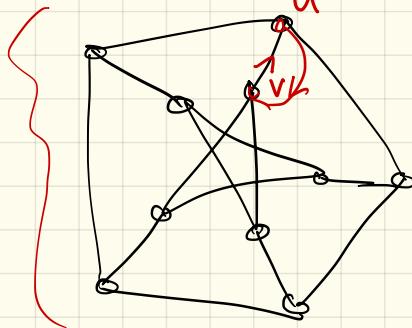
(non-hierarchical, non-linear)

Examples

- connections on social media
- road networks
- internet
- :
:

More defs:

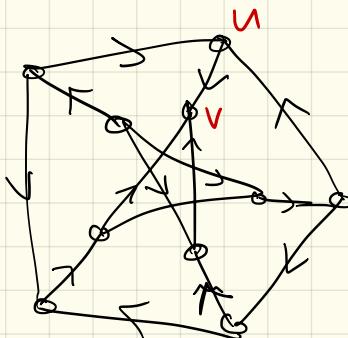
G is undirected if edges are unordered pairs
so $\{u, v\} = \{v, u\}$ \leftarrow endpoints



G is directed if edges are ordered pairs

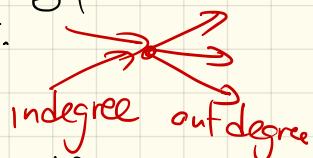
so $(u, v) \neq (v, u)$

(u, v)



Dfn's cont :

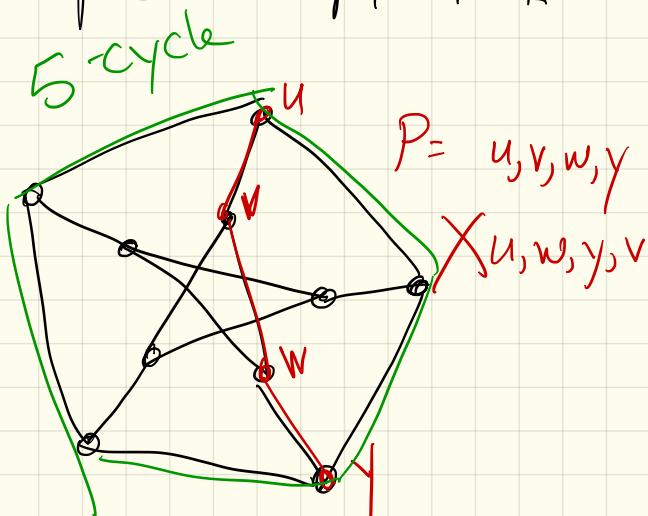
The degree of a vertex, $d(v)$, is the number of adjacent edges.



A path $P = v_1, \dots, v_k$ is a set of vertices with $\{v_i, v_{i+1}\} \in E$ (or $(v_i, v_{i+1}) \in E$ if directed).

A path is simple if all vertices are distinct.

A cycle is a path which is simple except $v_1 = v_k$.



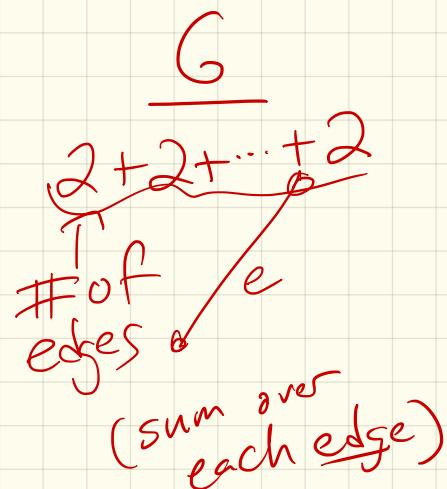
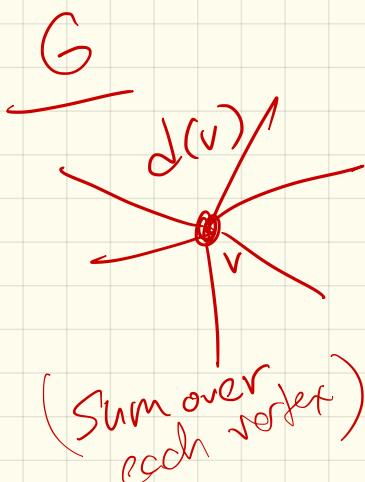
Lemma: (degree-sum formula)

$$\sum_{v \in V} d(v) = 2|E|$$

↓
PF:

Sum over all vertices of
deg of vertex =
 $d(v_1) + d(v_2) + \dots + d(v_n)$

↑
handshaking lemma



Size of G :
2 parameters:

$$|V| = n$$

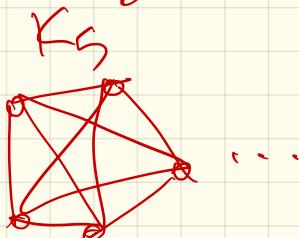
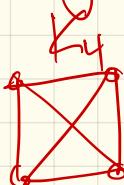
$$|E| = m \leftarrow$$

How big can m be in terms of n ?

$$m \leq \binom{n}{2} = \frac{n!}{2!(n-2)!} = \frac{n(n-1)}{2}$$
$$= O(n^2)$$

Worst case: K_n

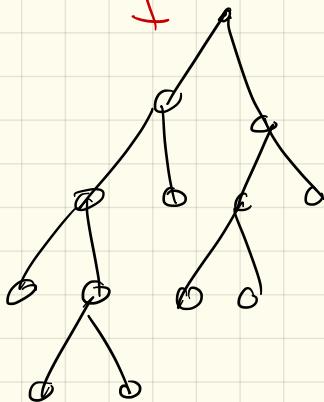
Complete graph



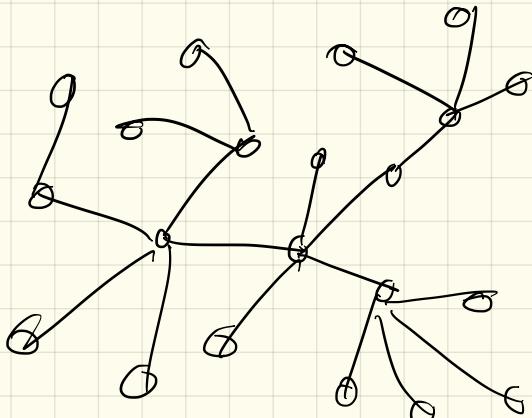
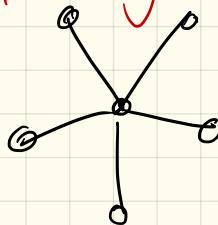
Tree :

A connected graph with
no cycles

(Note: no root here!)



$$\rightarrow n-1 \text{ edges} = m$$

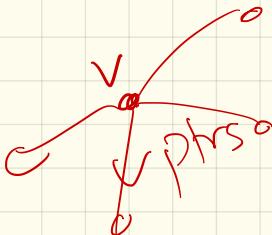


Representing graphs

How do we make this
data structure?

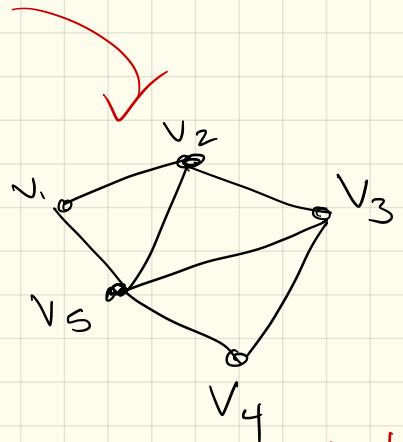
- pointers! ↴ :

↳ list-like



Adjacency (or vertex) lists :

$V_1 : V_2, V_5$
 $V_2 : V_1, V_5, V_3$
 $V_3 :$
 $V_4 :$
 $V_5 :$



upper bnd

SIZE: n "lists", each size $\leq n-1$

Lookup: Time to check if V_i & V_j are nbrs:

$O(n)$
(or $O(\log n)$)

Implementation:

We call these vertex lists,
but don't have to
use lists

Options:

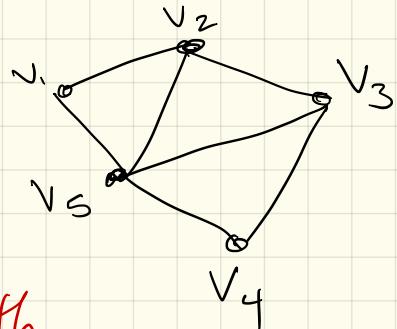
- lists
- vectors
- :

Trade-offs:

insert / vs. lookup
~~remove~~

Adjacency Matrix

| | v_1 | v_2 | v_3 | v_4 | v_5 |
|-------|-------|-------|-------|-------|-------|
| v_1 | X | 1 | 0 | 0 | 1 |
| v_2 | 1 | X | 1 | 0 | 1 |
| v_3 | 1 | 1 | X | 1 | 0 |
| v_4 | 1 | 1 | 1 | X | 1 |
| v_5 | 1 | 1 | 1 | 1 | X |



directed: need both
"halves" of matrix

space: $O(n^2)$

check nbr: $O(1)$

$A[i][j]$

Which is better?

Depends!

| | Adjacency matrix | Standard adjacency list (linked lists) | Adjacency list (hash tables) |
|---|------------------|---|--|
| Space | $\Theta(V^2)$ | $\Theta(V + E)$ | $\Theta(V + E)$ |
| Time to test if $uv \in E$ | $O(1)$ | $O(1 + \min\{\deg(u), \deg(v)\}) = O(V)$ | $O(1)$ |
| Time to test if $u \rightarrow v \in E$ | $O(1)$ | $O(1 + \deg(u)) = O(V)$ | $O(1)$ |
| Time to list the neighbors of v | $O(V)$ | $O(1 + \deg(v))$ | $O(1 + \deg(v))$ |
| Time to list all edges | $\Theta(V^2)$ | $\Theta(V + E)$ | $\Theta(V + E)$ |
| Time to add edge uv | $O(1)$ | $O(1)$ | $O(1)^*$ |
| Time to delete edge uv | $O(1)$ | $O(\deg(u) + \deg(v)) = O(V)$ | $O(1)$  |

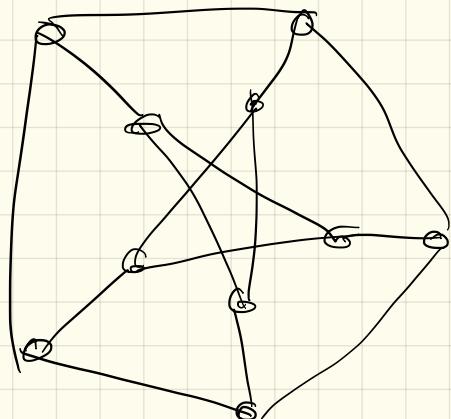
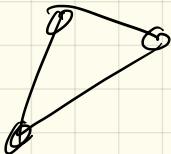
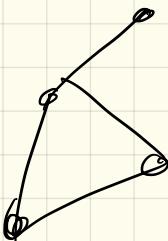
\uparrow
 $\mathcal{O}(n^2)$ space

\uparrow
 $\mathcal{O}(n+m)$

Dfn:

paths

- G is connected if $\forall u, v$,
there \exists path from u to v .
- The distance from u to v ,
 $d(u, v)$, is equal to the
 $\#$ of edges on the
minimum u, v -path



Algorithms on graphs

Basic 1st question:

Given any 2 vertices, are they connected?

Also: What is their distance?

How to solve?

Suggestion:

Suppose we're in a maze,
Searching for something.
What do you do?

Pseudocode : two versions

RECURSIVEDFS(v):

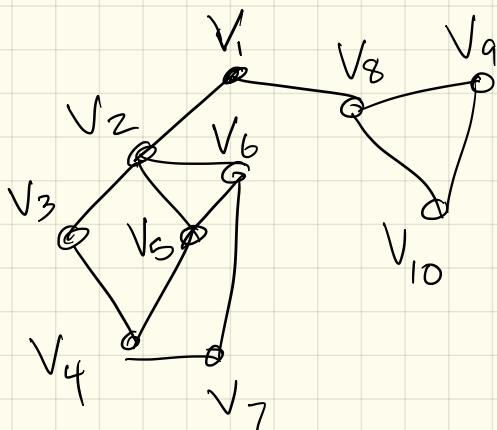
```
if  $v$  is unmarked  
    mark  $v$   
    for each edge  $vw$   
        RECURSIVEDFS( $w$ )
```

ITERATIVEDFS(s):

```
PUSH( $s$ )  
while the stack is not empty  
     $v \leftarrow \text{POP}$   
    if  $v$  is unmarked  
        mark  $v$   
        for each edge  $vw$   
            PUSH( $w$ )
```

Really, building a "tree":

DFS tree:



General traversal strategy's

TRAVERSE(s):

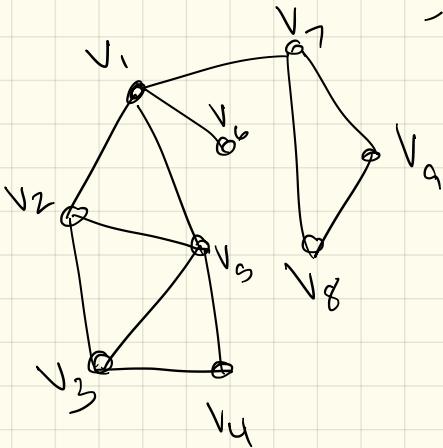
```
put  $s$  into the bag  
while the bag is not empty  
    take  $v$  from the bag  
    if  $v$  is unmarked  
        mark  $v$   
        for each edge  $vw$   
            put  $w$  into the bag
```

Q: Can we use a different "bag"?

BFS: use a queue

TRAVERSE(s):

put s into the bag
while the bag is not empty
 take v from the bag
 if v is unmarked
 mark v
 for each edge vw
 put w into the bag



BFS vs. DFS:

