

Topological Data Analysis

Fall 2025

Syllabus
Top-Review



Course intro

- Syllabus & HW → main webpage
- HW submission → Canvas
(+ gradebook)
- Prereqs: some linear algebra
some programming background
- Slack?
- HW: Mix of pen/paper & Coding
↳ flexible, so see me if you
have any issues!

Textbook(s)

Main reference:

free pdf

1:51PM Fri Aug 15

rcs.purdue.edu

CSE 40113: Algorithms, Spring 2025

Topological Data Analysis Book

Book : Computational Topology for Data Analysis
(published by Cambridge University Press)

Tamal K Dey
Department of Computer Science, Purdue University, IN

Yusu Wang
Halicioglu Data Science Institute, UC San Diego, CA

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[MAA review](#) and [zbMath review](#)

[Errata](#) detected in the print are corrected in electronic version marked with red text

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• Contents

Chapter 1: Basic Topology

- a. Topological spaces, metric space topology
- b. Maps: homeomorphisms, homotopy equivalence, isotopy
- c. Manifolds
- d. Functions on smooth manifolds
- e. Notes and Exercises

Chapter 2 (i) . Complexes

- a. Simplicial complexes
- b. Nerves, Čech and Vietoris-Rips complexes
- c. Sparse complexes (Delaunay, Alpha, Witness)
- d. Graph induced complexes

Others:

Listed on Syllabus

Most are available in the library, or
Come visit my office!

Project:

Ideally, this will connect to your research.

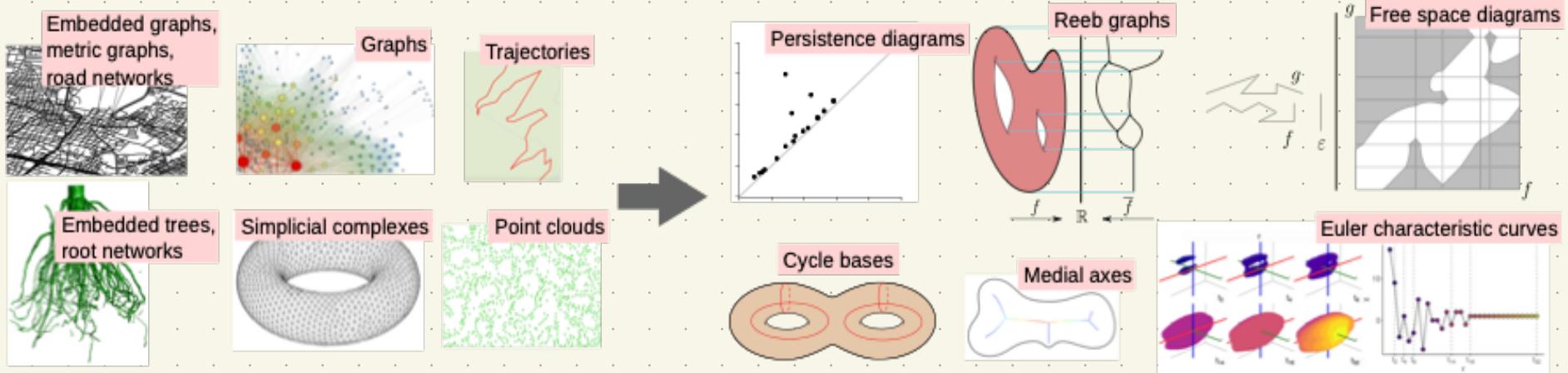
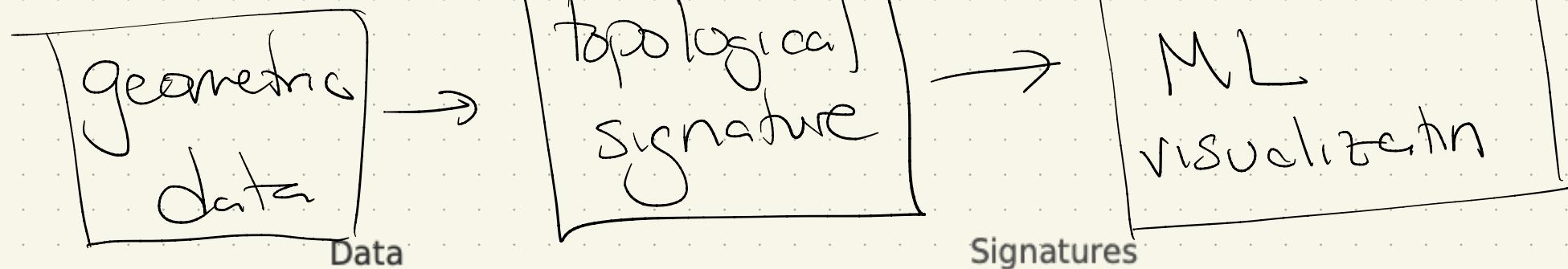
But - we'll have several assignments to help explore topics, if you're unsure of what direction to take.

Outline:

- talk summary → in Sept
- paper "chase" { in October
- project proposal
- final presentation + submission

What is topological data analysis?

Traditional pipeline:



Goals:

Some history:

Recognizing exact topology can be hard.
How so?

- Deciding if 2 4-manifolds are homeomorphic is undecidable
[Markov 1960, van Meter 2005]
- Deciding if you can "unknot" a curve using a fixed number of moves is NP-Hard
[de Mesmay, Sedgwick, & Tancer 2021]



An approach

Since we can't solve the problem exactly, focus on invariants and ways to simplify the data.

This is not new:

Examples:

- Knot invariants
- Curve skeletons
- Manifold approximations
 - ↳ ie meshes

A first example: Euler characteristic

Introduced first by Maurolico in 1537.
(This is known as

Then published by Euler in 1758:

Name	Image	Vertices	Edges	Faces	Euler characteristic:
		V	E	F	$\chi = V - E + F$
Tetrahedron		4	6	4	2
Hexahedron or cube		8	12	6	2
Octahedron		6	12	8	2
Dodecahedron		20	30	12	2
Icosahedron		12	30	20	2

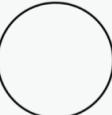
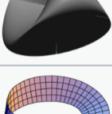
For any embedded planar graph
 $G = (V, E)$ with F faces

$$V - E + F = 2$$

Note: planar \Rightarrow

More generally:

Euler characteristic: $V - E + F = \chi$

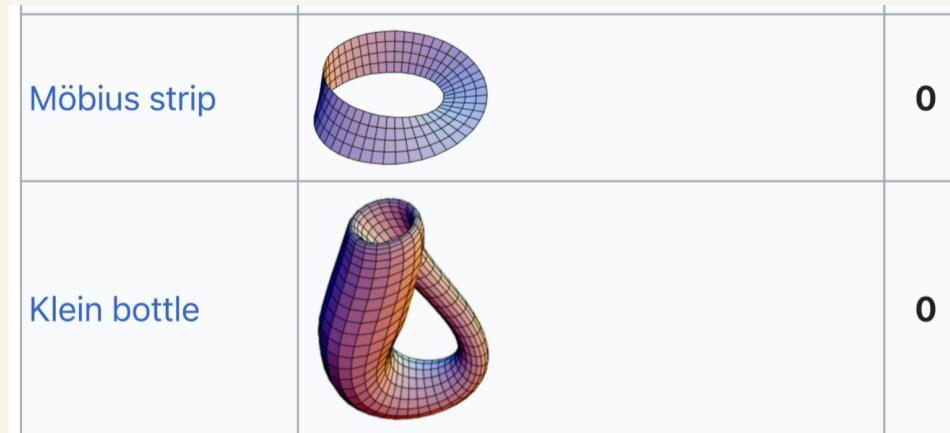
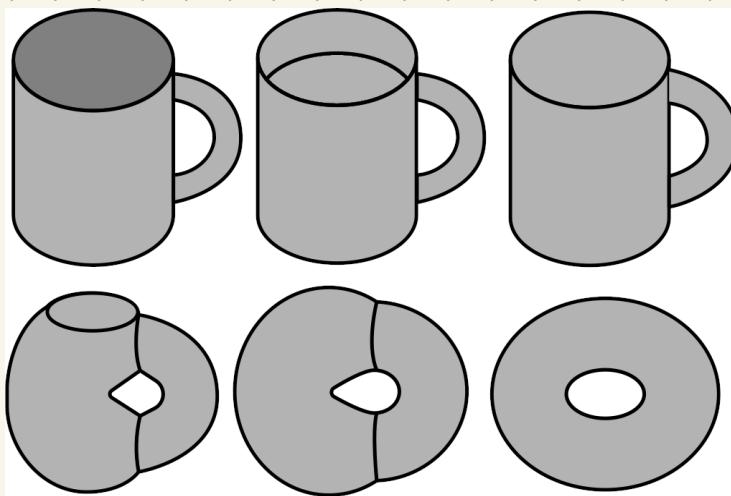
Name	Image	χ
Interval		1
Circle		0
Disk		1
Sphere		2
Torus (Product of two circles)		0
Double torus		-2
Triple torus		-4
Real projective plane		1
Möbius strip		0

Ideal for computers:

- requires a discrete representation
- Given a data structure encoding V, E, F
easy to calculate

Topological signatures: invariants

Different Euler characteristic
⇒ different space

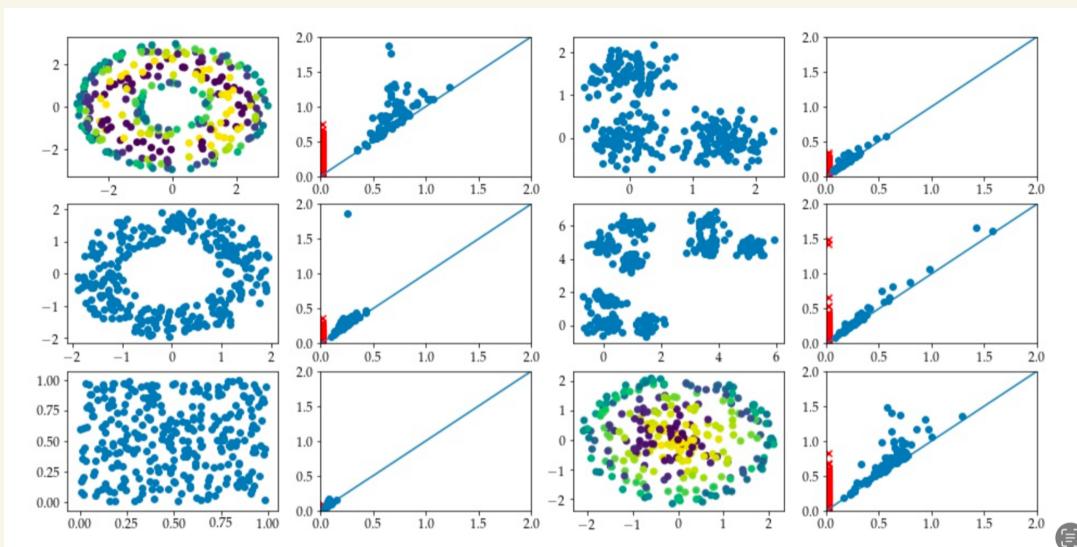


But different spaces might have the same Euler characteristic
(as well as very different geometry)

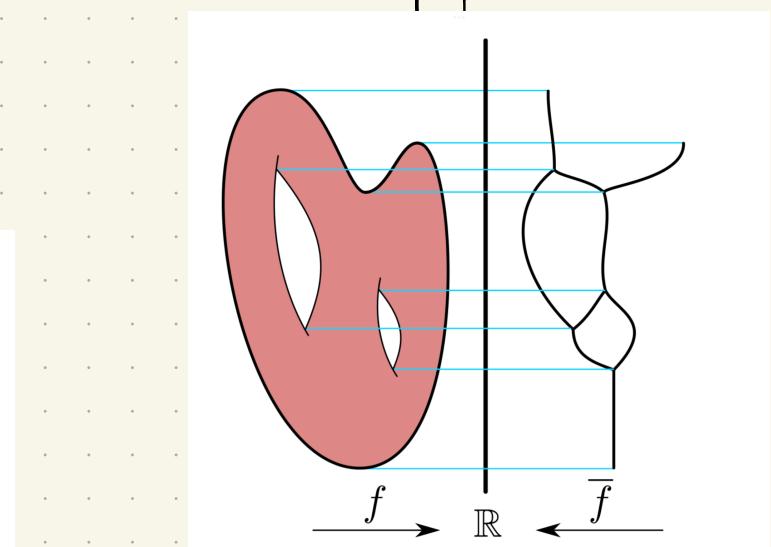
Back to signatures

We'll cover a range of possible choices, on a sliding scale of complexity + discriminativity.

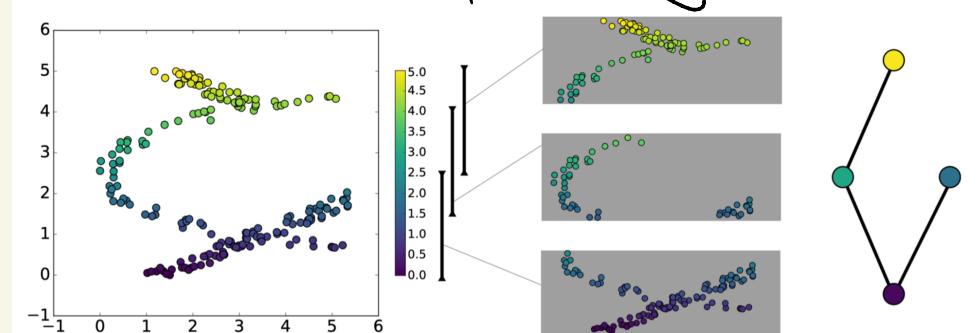
Examples:



Persistent homology



Reeb & Mapper graphs



Active research directions

This is a fairly young & vibrant area.

Emerging directions:

- Machine Learning with TDA
- Time series & dynamic systems
- Parallelization
- Visualization
- Algebraic methods & multi-dimensional persistence
- Many applications: atmospheric data, image processing, biomedical, neuroscience, vision, etc.

Our goals

Understand the computation + interpretation
of several commonly used tools in TDA:

- Euler curves
- Persistent homology
- Mapper & Reeb graphs
- Morse-Smale Complexes

In the end, understand what types of
signatures are likely to be both
useful & practical on data sets
(as well as which open source tools exist).

But first - topology!

Chapter 1 covers an intro to topology.

Depending on math, might seem
obvious, or might seem very hard!

Either is ok.

Worth reading textbook to be sure
you get main definitions in context,
& come see me if you have questions.

Topology

Topological space: a set T with elements (called points) + a set of subsets τ , such that

- $\emptyset, T \in \tau$

- $\forall U \subseteq T$, union of sets in U is in τ

- \forall finite $U \subseteq T$, intersection of sets in U is also in τ

Ex: $T = \{a, b, c\}$, $\tau = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}\}$

Check:

- b

- a

- c

Metric Space:

a pair (\mathbb{T}, d) , where \mathbb{T} is a set and
 $d: \mathbb{T} \times \mathbb{T} \rightarrow \mathbb{R}$ satisfies

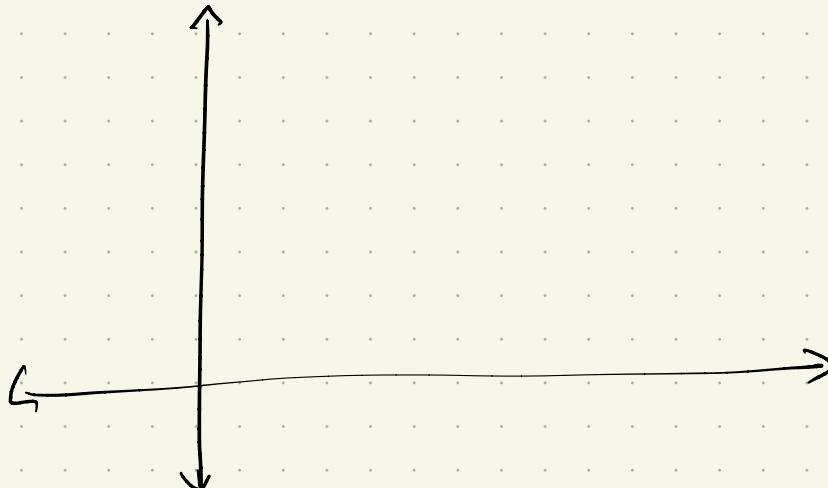
$$\bullet d(p, q) = 0 \Leftrightarrow p = q$$

$$\bullet d(p, q) = d(q, p) \quad \forall p, q \in \mathbb{T}$$

$$\bullet d(p, q) \leq d(p, r) + d(r, q) \quad \forall p, q, r \in \mathbb{T}$$

Example: $\mathbb{T} = \mathbb{R}^2$, $d((u_1, u_2), (v_1, v_2)) =$

$$\sqrt{(u_1 - v_1)^2 + (u_2 - v_2)^2}$$



Metric topology

Given a metric space (\mathbb{H}, d) , an open metric ball is

$$B_o(c, r) = \{ p \in \mathbb{H} \mid d(p, c) < r \}$$

The metric topology is the set of all metric balls.

Ex: \mathbb{R}^2 again:

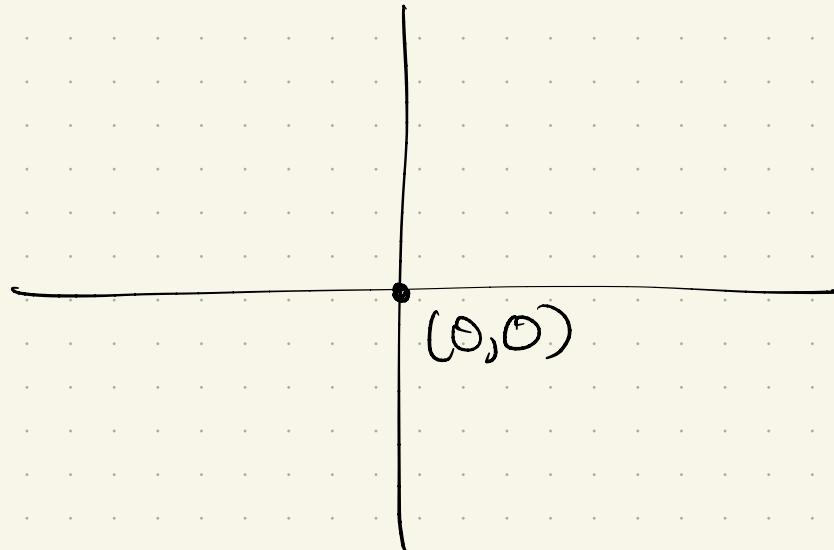
Many different metric topologies!

Fix \mathbb{R}^2 , & let's try $B_0(0, 1)$ for:

$$\bullet \|u-v\|_1 = |u_1 - v_1| + |u_2 - v_2|$$

$$\bullet \|u-v\|_2 = \sqrt{(u_1 - v_1)^2 + (u_2 - v_2)^2}$$

$$\bullet \|u-v\|_\infty = \max \{ |u_1 - v_1|, |u_2 - v_2| \}$$



Open & closed sets

Fixing a topology T , U is open if $U \in T$.
We say U is closed if $T \setminus U$ is open.

Back to first example:

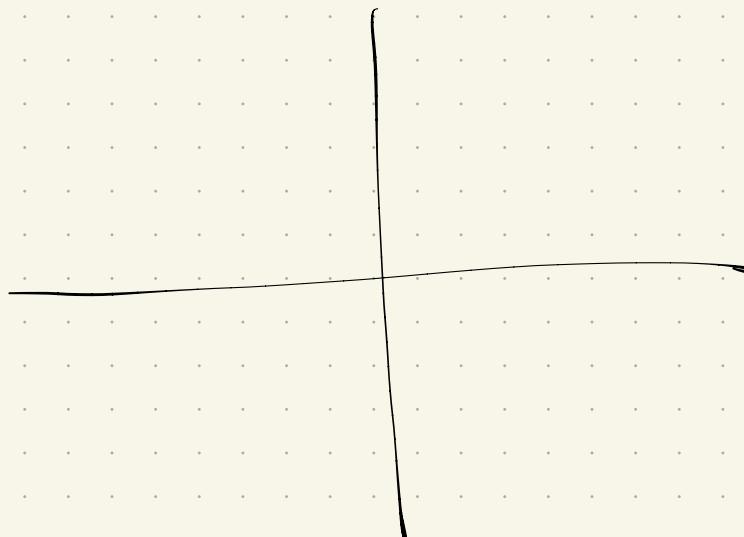
$$\Pi = \{a, b, c\}, T = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}\}$$

Closed sets:

In a metric space, can get some alternate definitions:

Consider $Q \subseteq \mathbb{T}$. A point $p \in \mathbb{T}$ is a **limit point** of Q if $\forall \varepsilon > 0$, Q contains some point $q \neq p$ with $d(p, q) < \varepsilon$

Example: \mathbb{R}^2 + $B_0(p, 1)$:

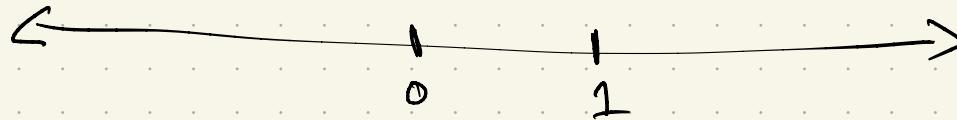


The **closure** of a point set $Q \subseteq \mathbb{T}$
is the set containing Q and all
of its limit points.

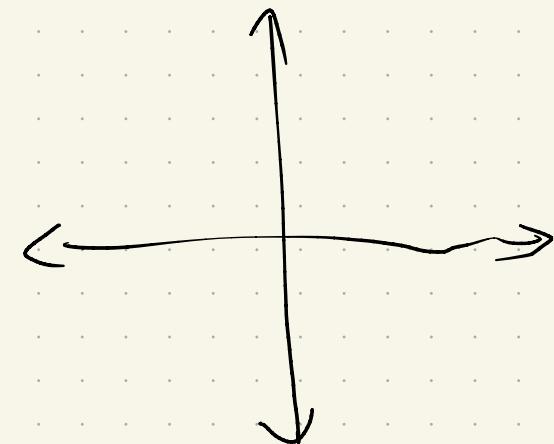
↳ written $C(Q)$, or \overline{Q}

We say Q is **closed** if $Q = C(Q)$.

Example: $(0, 1) \subseteq \mathbb{R}$ is an open ball



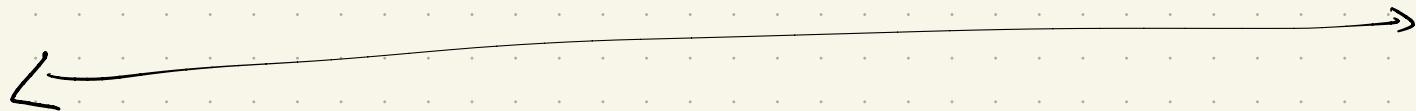
Example: $\mathbb{R}^2 + B_0(0, 1)$



A **open** (resp, closed) **cover** of a topological space (\mathbb{T}, τ) is a collection C of open (resp. closed) sets st.

$$\mathbb{T} = \bigcup_{c \in C} c$$

Example: \mathbb{R} , $C = \{(n-1, n+1) | n \in \mathbb{Z}\}$



A topological space is **disconnected**
if \exists 2 disjoint nonempty open sets
 $U, V \in T$ s.t. $T = U \cup V$.

(The space is **connected** if it is
not disconnected.)

Ex: $A = (1, 2) \cup (3, 4) \subset \mathbb{R}$

Note: **Subspace topology**: Given $U \subseteq T$,
 U can inherit topology from T via
 $\{x \cap U \mid x \in T\}$

Next time:

Maps, homeomorphisms, & homotopies!

(See remainder of Chapter 1)

Overall goal: understand enough about
maps to get to "nice" functions,
& start Morse theory