

Algorithms - Spring '25

LPs-Duality



Recap:

- Make sure to sign up for HW8 grading slot!
- Practice final is posted
- CIFs are live & feedback is appreciated

A moment of honesty to start
lecture:



To deal with a 14-dimensional space,
visualize a 3-D space and say
'fourteen' to yourself very loudly.
Everyone does it.

— Geoffrey Hinton —

AZ QUOTES

Linear optimizations: Example

n foods, m nutrients

Let a_{ij}^o = amount of nutrient i in food j

r_i^o = requirement of nutrient i

x_j = amount of food j purchased

c_j = cost of food j

Goal: Buy food so you satisfy nutrients
while minimizing cost

Can view as matrix 

$$A = \left[\begin{array}{c} j \\ i \end{array} \right] \rightarrow a_{ij} \quad]$$

$$\vec{r} = (r_1, r_2, \dots, r_m)$$
$$\vec{x} = (x_1, \dots, x_n)$$
$$\vec{c} = (c_1, \dots, c_n)$$

So: minimize

s.t.

In general, get systems like this:

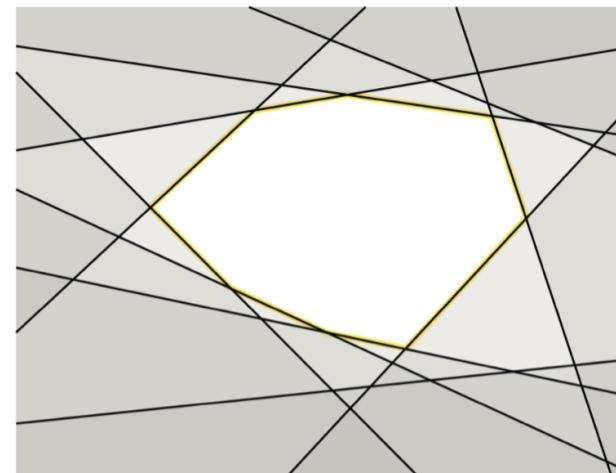
$$\text{maximize} \sum_{j=1}^d c_j x_j$$

$$\text{subject to } \sum_{j=1}^d a_{ij} x_j \leq b_i \quad \text{for each } i = 1..p$$

$$\sum_{j=1}^d a_{ij} x_j = b_i \quad \text{for each } i = p+1..p+q$$

$$\sum_{j=1}^d a_{ij} x_j \geq b_i \quad \text{for each } i = p+q+1..n$$

Geometric Picture:



A two-dimensional polyhedron (white) defined by 10 linear inequalities.

History

Dates back to 1800's where studied by Fourier.

By 1940's: serious study, due to business/optimization demand

- Not known to be NP-Hard
(Karp actually listed it as key open question in original paper on NP-Hardness)

Canonical form:

Avoid having both \leq and \geq .

Why?

So get something more like our first example:

$$\text{maximize } \sum_{j=1}^d c_j x_j$$

$$\text{subject to } \sum_{j=1}^d a_{ij} x_j \leq b_i \quad \text{for each } i = 1..n$$

$$x_j \geq 0 \quad \text{for each } j = 1..d$$

Or given a vector \vec{c} , matrix A + vector \vec{b} :

Anything can be put into
canonical forms.

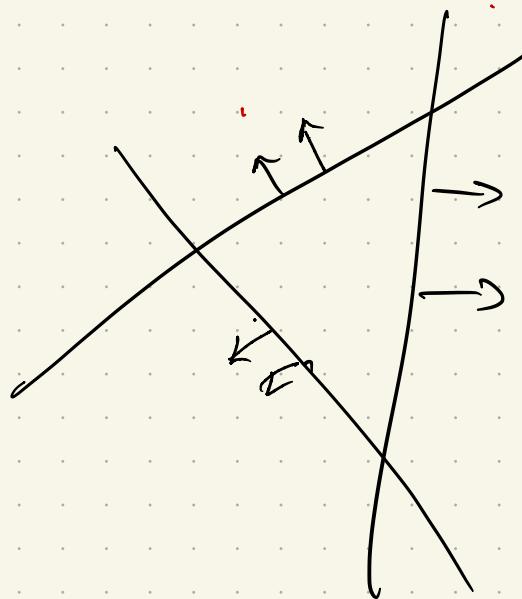
The reduction:

① Avoid = :

② Avoid \geq :

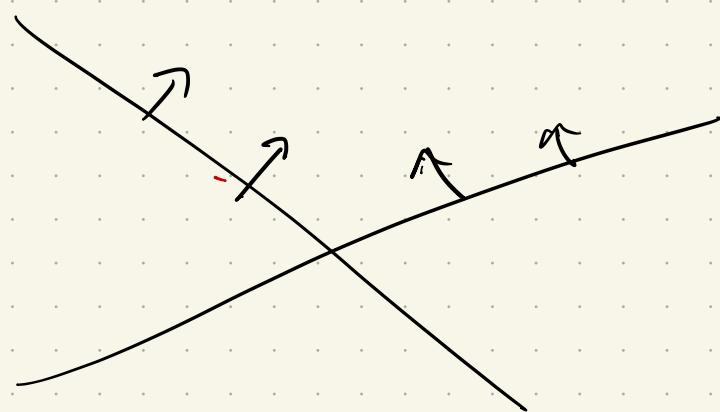
How could these not have a solution?

2 ways:



or

maximize $x_1 + x_2$
s.t.



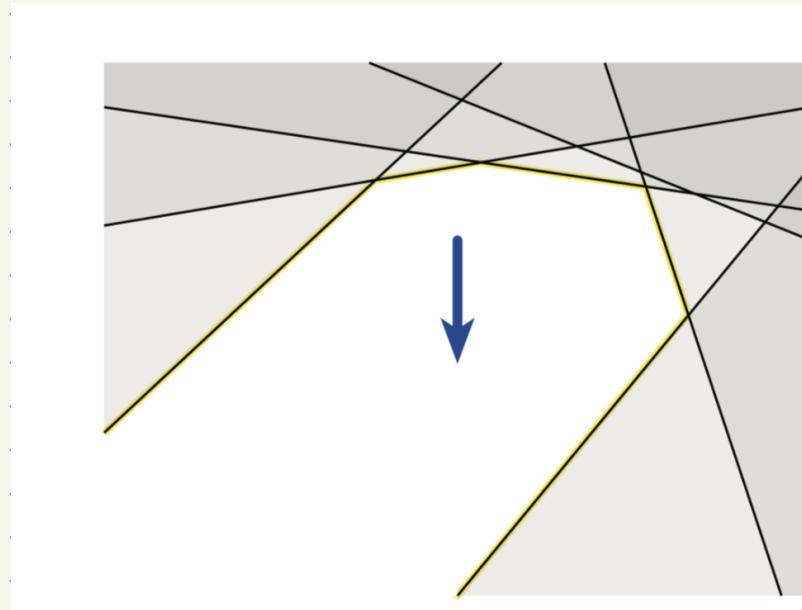
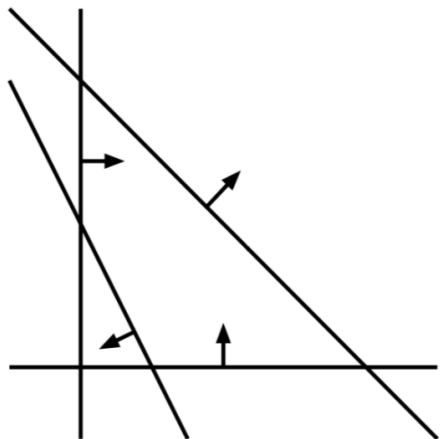
Better pictures (still 2d):

maximize $x - y$

subject to $2x + y \leq 1$

$x + y \geq 2$

$x, y \geq 0$



Note:

- ① Multiplying by -1 turns any maximization problem into a minimization one:

Why?

- ② Can turn inequalities into equalities via slack variables:

$$\sum_{i=0}^n a_i x_i \leq b \Rightarrow$$

③ Can change equalities into
inequalities, also!

$$\sum_{i=1}^n a_i x_i = b$$

↓

Modeling Problems: Flows + Cuts

Input: directed G w/edge capacities $c(e)$
+ $s, t \in V$

Goal: Compute flow $f: E \rightarrow \mathbb{R}$ s.t.

$$\textcircled{1} \quad 0 \leq f(e) \leq c(e)$$

$$\textcircled{2} \quad \forall v \neq s, t,$$

$$\sum_u f(u \rightarrow v) = \sum_w f(v \rightarrow w)$$

Make an LP: Maximize

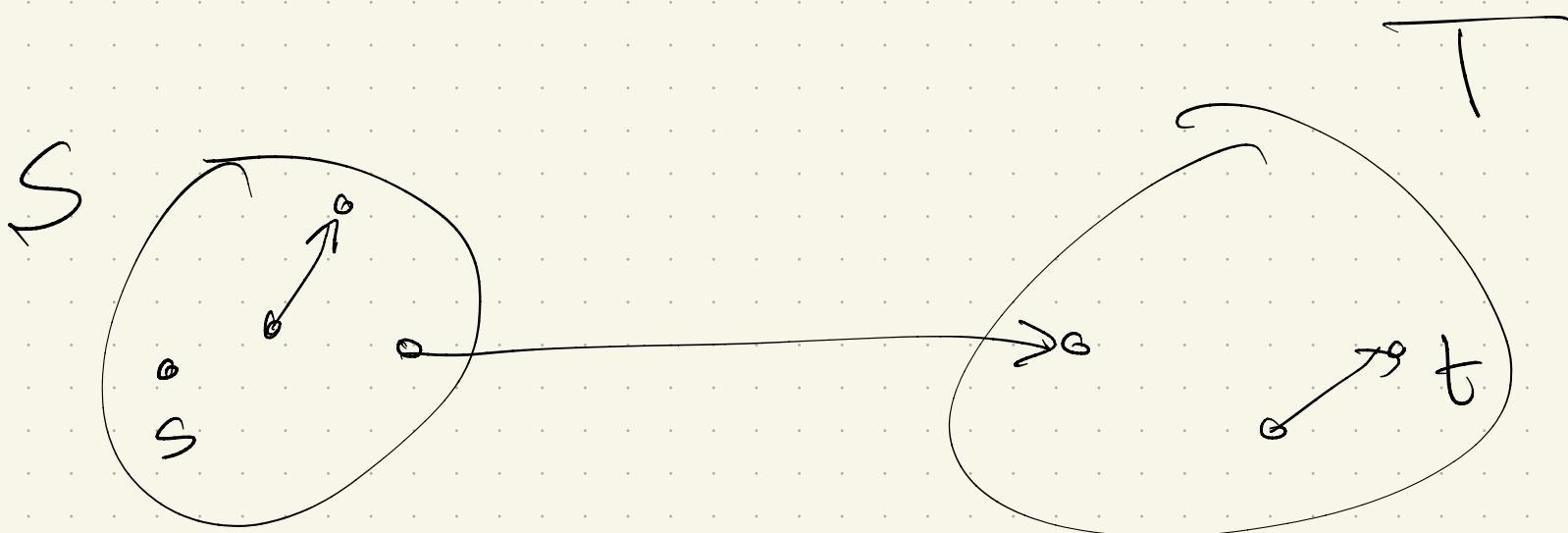
s.t.

Related : Min cuts (S,T)

Use indicator variables:

$$S_v = 0 \text{ or } 1$$

$$X_e = X_{(u \rightarrow v)} = 1 \text{ if } u \in S \text{ and } v \in T$$



The LP:

Minimize $\sum_{u \rightarrow v} c_{u \rightarrow v} \cdot x_{u \rightarrow v}$ ↗ want few edges

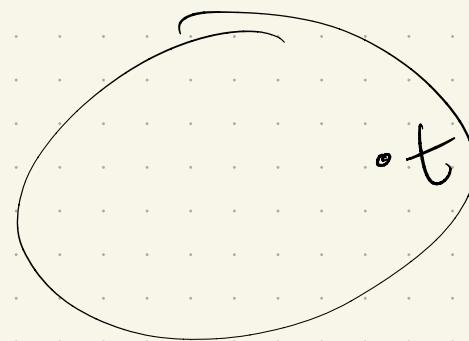
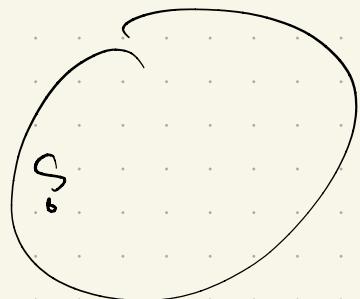
s.t.

$$x_{u \rightarrow v} + s_v - s_u \geq 0 \quad \forall u \rightarrow v$$

$$x_{u \rightarrow v} \geq 0 \quad \forall u, v$$
 ↗ which are forced?

$$s_s = 1$$

$$s_t = 0$$



Note:

For flow/cuts, a solution would yield
optimal LP solution.

The reverse is not obvious!

LP might have strange fractional
answer which
doesn't describe a cut.

If can be shown that this
won't happen
↳ but not obvious..

Duality:

Recall our chocolate:

$$LP: \max x_1 + 6x_2$$

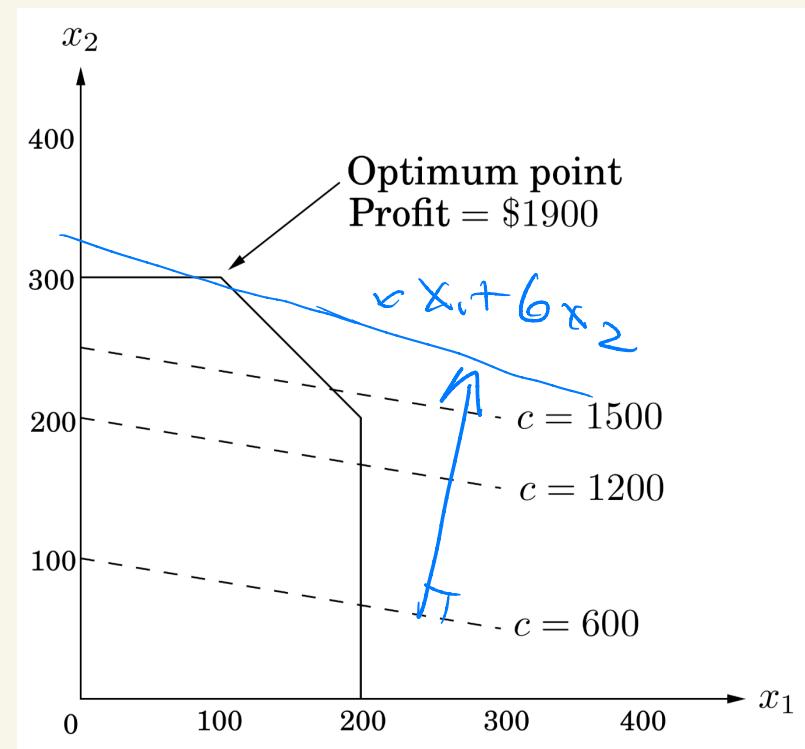
s.t.

$$x_1 \leq 200$$

$$x_2 \leq 300$$

$$x_1 + x_2 \leq 400$$

$$x_1, x_2 \geq 0$$



Can we check that this is best?

$$\text{s.t. } \max \quad x_1 + 6x_2$$

$$x_1 \leq 200$$

①

$$x_2 \leq 300$$

②

$$x_1 + x_2 \leq 400$$

$$x_1, x_2 \geq 0$$

Play w/ inequalities:

$$\textcircled{1} + 6 \cdot \textcircled{2} :$$

Interesting!

These 2 inequalities tell us that we
couldn't ever beat \$2000.

But recall soln was \$1900-

Can we get a better combo?

$$\max \quad x_1 + 6x_2$$

s.t.

$$x_1 \leq 200$$

①

$$x_2 \leq 300$$

②

$$x_1 + x_2 \leq 400$$

③

$$x_1, x_2 \geq 0$$

$$\text{Play} = 0 \cdot \textcircled{1} + 5 \cdot \textcircled{2} + 1 \cdot \textcircled{3}$$

These multipliers, $(0, 5, 1)$, ate a certificate of optimality.

↳ No valid solution can ever beat \$1900

But

How do we find these magic values??

In this, we had three " \leq " inequalities

↳ So goal is to find the right 3 multipliers: y_1 , y_2 , and y_3

Let's try to rewrite...

Multiplier

$$y_1 \times x$$

$$\cancel{y}_2 \times x$$

$$y_3 \times x_1 + x_2 \leq 400$$

Inequality

$$x_1 \leq 200$$

$$x_2 \leq 300$$

$$x_1 + x_2 \leq 400$$

Result

Rewrite: Make left side look like the original max/min goal, so right will be an upper bound

So here:

$$(y_1 + y_3)x_1 + (y_2 + y_3)x_2 \leq 200y_1 + 300y_2 + 400y_3$$

Means:

$$x_1 + 6x_2 \leq 200y_1 + 300y_2 + 400y_3$$

If: $\begin{cases} y_1, y_2, y_3 \geq 0 \\ y_1 + y_3 \geq 1 \\ y_2 + y_3 \geq 6 \end{cases}$

b/c if negative, inequalities flip!
b/c original eqn.

Any y_i 's would give an upper bound!

We want the best one

↳ ie minimize another LP!

Duality

$$\begin{array}{ll}
 \text{s.t.} & \max x_1 + 6x_2 \\
 & x_1 \leq 200 \\
 & x_2 \leq 300 \\
 & x_1 + x_2 \leq 400 \\
 & x_1, x_2 \geq 0
 \end{array}
 \quad \text{dual} \quad
 \begin{array}{l}
 \min 200y_1 + 300y_2 \\
 + 400y_3 \\
 \text{s.t.} \\
 y_1 + y_3 \geq 1 \\
 y_2 + y_3 \leq 6 \\
 y_1, y_2, y_3 \geq 0
 \end{array}$$

Any solution to bottom is upper bound to top LP.

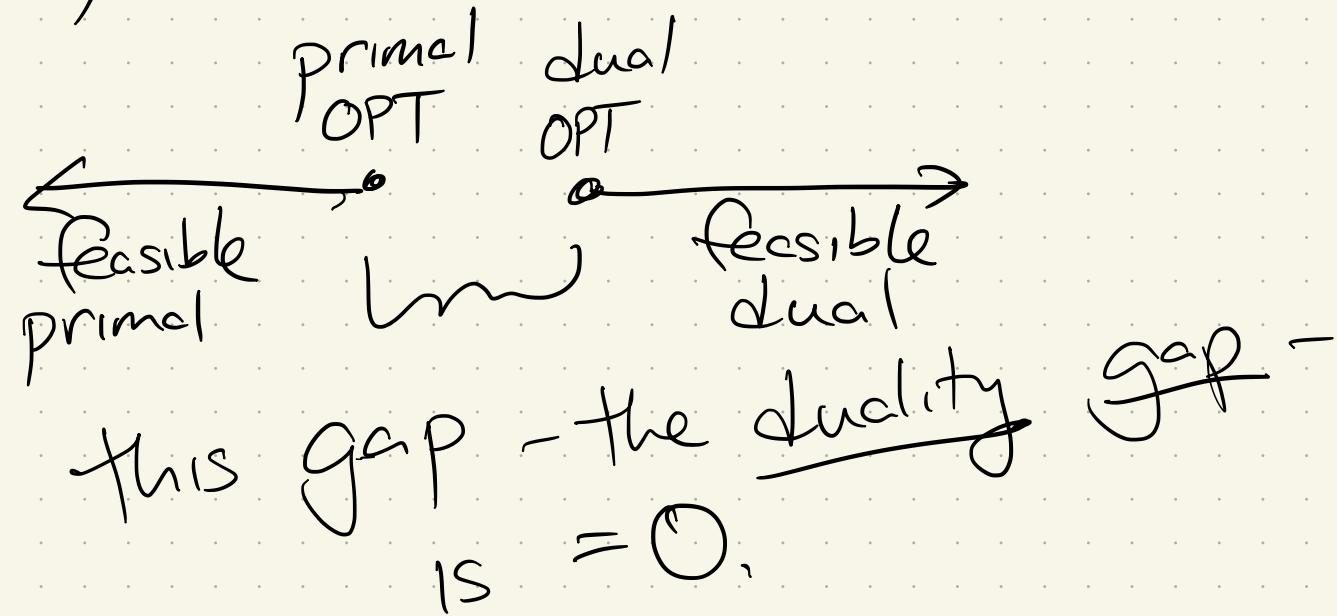
⇒ If we can find primal/duals that are equal, both are OPT

Here, 1900: primal $(x_1, x_2) = (100, 300)$

Dual: $(y_1, y_2, y_3) = (0, 5, 1)$

This is just like max flow / min cut duality, in a way.

Works for any LP:



In general:

Primal LP

$$\max \vec{C}^T \vec{x}$$

s.t.

$$A\vec{x} \leq \vec{b}$$

$$\vec{x} \geq 0$$

$\vec{c}, \vec{x}, \vec{b}$ vectors

Dual LP

$$\min \vec{y}^T \vec{b}$$

s.t.

$$\vec{y}^T A = \vec{c}^T$$

$$\vec{y} \geq 0$$

$\vec{c}, \vec{b}, \vec{y}$, vectors

Limits of LP:

Many things are not LPs!

Ex: Integer solutions

Ex: Quadratic or more complex
constraints

Often other approaches could give a better runtime!

Ex: Flows + cuts!

Ordn: $O(VE)$ via a combinatorial approach

LP:
E variables,
 $V+E$ equations



- LP w/simplex alg. is exponential
- with "better" algorithm matrix multiply time (so $\sim E^3$)

The algorithm: Simplex (Dantzig 1947)

Assumes canonical form:

So:

- no min
- only \leq
- $+ \geq 0$ for all variables
- fast in practice, but exponential in worst case

$$\begin{aligned} & \text{maximize } \sum_{j=1}^d c_j x_j \\ & \text{subject to } \sum_{j=1}^d a_{ij} x_j \leq b_i \quad \text{for each } i = 1..n \\ & \quad x_j \geq 0 \quad \text{for each } j = 1..d \end{aligned}$$

Klee-Minty, 1973: some feasible polytopes have $O(n^{d/2})$ vertices

Algorithm (Simplex):

Take any vertex v in feasible region
while some neighbor v' is better

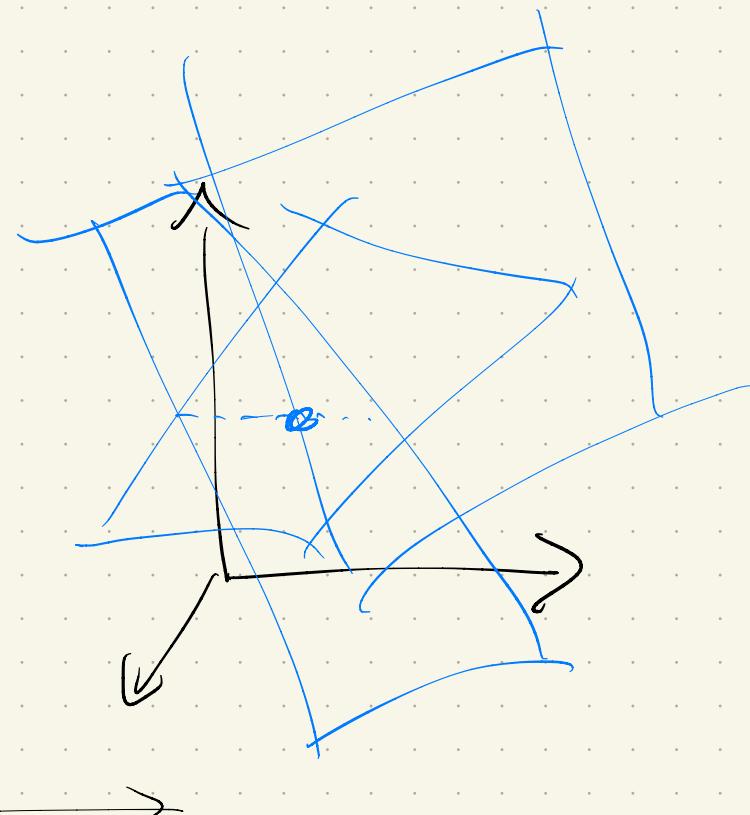
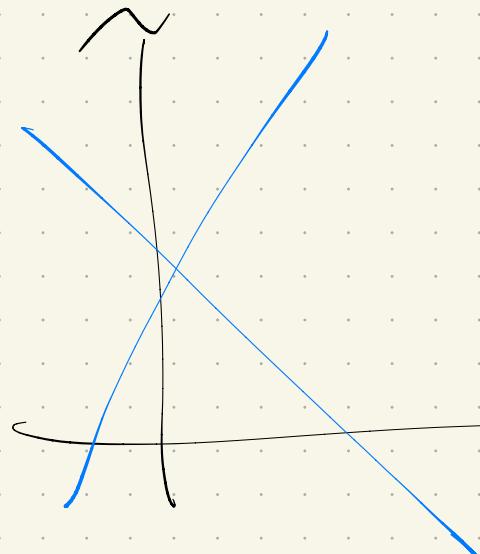
$$v \leftarrow v'$$

Details lacking!

Step 1: find a vertex

take d

hyperplanes?



Any d hyperplanes give a vertex:
Loop through m-d others!

Either feasible for each

Or Not

→ use the new hyperplane

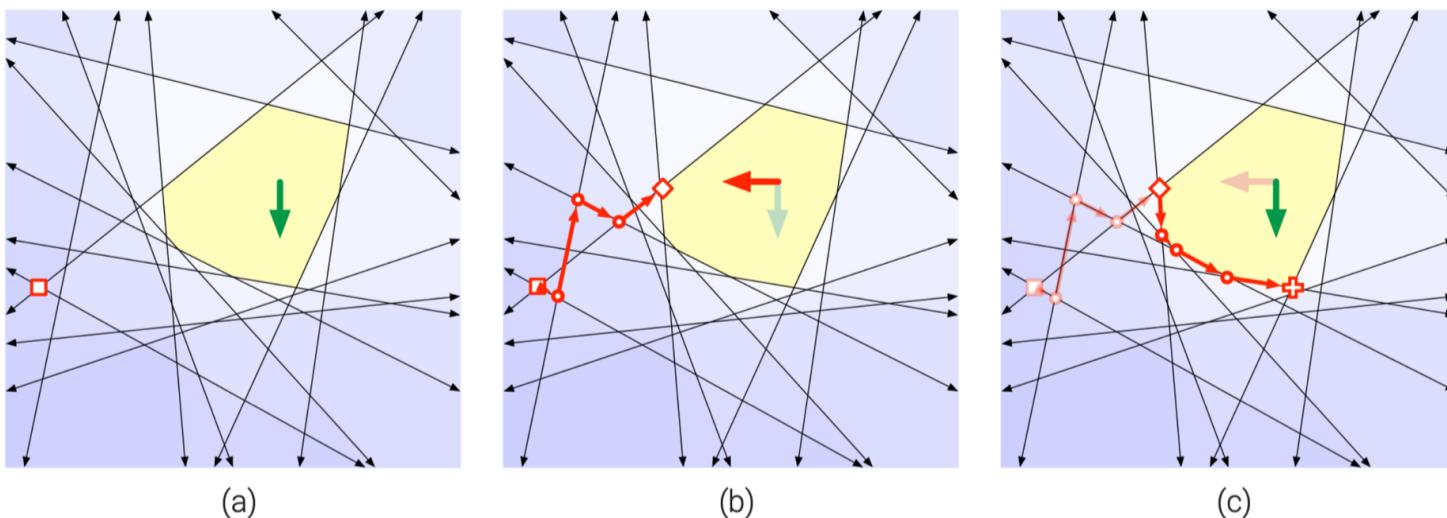


Figure I.2. Primal simplex with dual initialization: (a) Choose any basis. (b) Rotate the objective to make the basis locally optimal, and pivot "up" to a feasible basis. (c) Pivot down to the optimum basis for the original objective.

How to pick where to move?

No ideal way!

Many proposed, but for almost
every one there is some input
polyhedron that needs an
exponential number of pivots.

Ellipsoid algorithm, Khachiyan 1979

- (weakly) polynomial time

↳ dependent of precision

- high level idea: compute smaller & smaller ellipses which contain solution

Interior point Methods, Karmarkar 1984

- Move through polytope's interior!

- Still weakly polynomial

- But - practical

