

**Theorem 5.3** Suppose  $f(t, y)$  is defined on a convex set  $D \subset \mathbb{R}^2$ . If a constant  $L > 0$  exists with

Hausdorff (1832–1903)  
and many branches of  
including number  
series, differential

$$\left| \frac{\partial f}{\partial y}(t, y) \right| \leq L, \quad \text{for all } (t, y) \in D, \quad (5.1)$$

then  $f$  satisfies a Lipschitz condition on  $D$  in the variable  $y$  with Lipschitz constant  $L$ . ■

$\text{ex}) \quad y'(t) = \underbrace{y^2 e^t}_{f(t, y)} \quad (t, y) \in [0, 1] \times [0, 2]$

$f(t, y) = y^2 e^t \quad \leftarrow \text{Show } f \text{ satisfies Lip condition}$   
 in the var  $y$ .

$$\left| \frac{\partial f(t, y)}{\partial y} \right| = \left| 2y e^t \right| \leq 2 \cdot 2 e^1 = 4e = L$$

**Theorem 5.6** Suppose  $D = \{(t, y) \mid a \leq t \leq b \text{ and } -\infty < y < \infty\}$ . If  $f$  is continuous and satisfies a Lipschitz condition in the variable  $y$  on the set  $D$ , then the initial-value problem

$$\frac{dy}{dt} = f(t, y), \quad a \leq t \leq b, \quad y(a) = \alpha$$

is well-posed. ■

**Question 1:** Determine whether the following IVP's are well-posed.

(a)

$$\frac{dy}{dt} = \frac{1+y}{t}, \quad 1 \leq t \leq 2, \quad y(1) = 2$$

(b)

$$\frac{dy}{dt} = y \cos(t), \quad 0 \leq t \leq 1, \quad y(0) = 1$$

$$D = \{(t, y) : -1 \leq t \leq 2, y \in \mathbb{R}\}$$

$$f(t, y) = \frac{1+y}{t}$$

$$\left| \frac{\partial f(t, y)}{\partial y} \right| = \left| \frac{1}{t} \right| \leq 1 = L$$

$f$  is continuous in  $D$  and satisfies Lip condition on  $D$

in the variable  $y$ . By Thm 5.6, the IVP is well-posed.

$f$  is not continuous at  $t=0$ . Thus not well-posed.

$$\forall \epsilon > 0 \quad \exists s > 0 \quad \forall x, y \in \mathbb{X}, |x-y| < s \Rightarrow |f(x) - f(y)| < \epsilon.$$

$$|f(x) - f(y)| < L \underbrace{|x-y|}$$

$$|x-y| < \frac{\epsilon}{L}$$

**Question 2:** Consider the IVP

$$\frac{dy}{dt} = \frac{1+t}{1+y} = f(t, y)$$

with  $1 \leq t \leq 2$  and  $y(1) = 2$ .

- (a) By hand, compute an approximation to  $y(2)$  using Euler's method with  $h = 0.5$ .
- (b) Using code, approximate  $y(2)$  using Euler's method with  $h = 0.5, 0.2, 0.1, 0.01$  and record your results. (You do not have to submit your code).
- (c) The exact solution to the IVP is  $y(t) = \sqrt{t^2 + 2t + 6} - 1$ . Compare your approximations with the exact result  $y(2)$ , and interpret your results.

$$y(t+h) = y(t) + h y'(t) + \frac{h^2}{2!} y''(t) + \frac{h^3}{3!} y'''(t) + \dots$$

$$y(t+h) = y(t) + h \underbrace{y'(t)}_{\text{term}} + O(h^2)$$

$$y(t+h) = y(t) + h f(t, y) + \underbrace{O(h^2)}_{\text{term}}$$

$$w(t+h) = w(t) + h f(t, w)$$

$$y(1.5) = y(1) + 0.5 f(1, y(1))$$

$$= 2 + 0.5 \cdot \frac{2}{3} = 2 + \frac{1}{3} = \frac{7}{3}$$

$$y(2) = y(1.5) + 0.5 f(1.5, y(1.5))$$

$$= \frac{7}{3} + 0.5 f\left(1.5, \frac{7}{3}\right) = \frac{7}{3} + 0.5 \cdot \frac{1+1.5}{1+\frac{7}{3}} = \boxed{\frac{17}{9}}$$

**Question 3:** To derive Euler's method, we truncated the Taylor series expansion of  $y_{i+1}$  at the linear term. We could truncate at the quadratic term instead, giving the so-called Taylor method of order 2. This method approximates  $y_{i+1}$  by

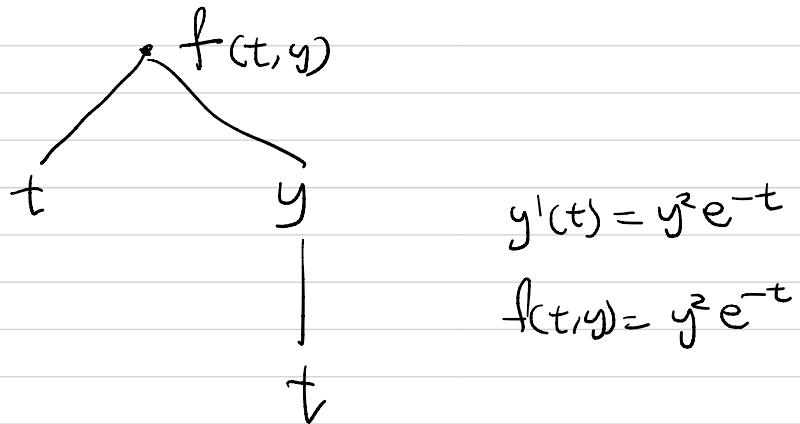
$$w_{i+1} = w_i + hf(t_i, w_i) + \frac{h^2}{2} \frac{df}{dt} \Big|_{(t_i, w_i)}.$$

- (a) For the IVP  $y'(t) = y^2 e^{-t}$ ,  $0 \leq t \leq 1$ ,  $y(0) = 1$ , calculate  $\frac{df}{dt}$ . (Remember  $\frac{df}{dt}$  is different to  $\frac{\partial f}{\partial t}$  since  $y$  is a function of  $t$ !)
- (b) By hand, use both Euler's method and the Taylor method of order 2 to approximate  $y(1)$  with  $h = 0.5$ .
- (c) Modify your code from 2(b) to implement the Taylor method of order 2 to approximate  $y(1)$  using  $h = 0.5, 0.1, 0.01$ . Also use Euler's method to calculate the same approximations. Provide the code you wrote for this question.
- (d) The exact solution to the IVP is  $y(t) = e^t$ . Use this to calculate the errors (where error  $e = |w_n - y(1)|$ ) in your approximations from part (c). Summarise your results, comparing Euler's method to the Taylor method of order 2.

$$y(t+h) = y(t) + h y'(t) + \frac{h^2}{2} y''(t) + \frac{h^3}{6} y'''(t) + \dots$$

$$w(t+h) = w(t) + h w'(t)$$

$$w(t+h) = w(t) + h w'(t) + \frac{h^2}{2} w''(t)$$



$$\frac{df}{dt} f(t, y) = \frac{\partial}{\partial t} f(t, y) + \frac{\partial f(t, y)}{\partial y} \frac{dy}{dt}$$

$$= -y^2 e^{-t} + (2y e^{-t})(y^2 e^{-t})$$

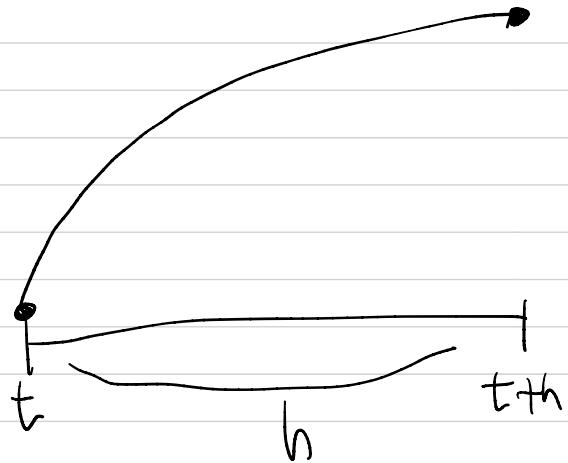
$$= -y^2 e^{-t} + 2y^3 e^{-2t}$$

Euler method

$$w(t+h) = w(t) + h f(t, w(t))$$
$$= w(t) + h (w(t))^2 e^{-t}$$

$$\text{Taylor's method} \geq w(t+h) = w(t) + h f(t, w(t)) + \frac{h^2}{2} \frac{df}{dt}(t, w(t))$$

$$= w(t) + h (w(t))^2 e^{-t} + \frac{h^2}{2} \left( - (w(t))^2 e^{-t} + 2(w(t))^3 e^{-2t} \right)$$



$$w_{i+1} = w_i + w_{i-1} + w_{i-2} + h \phi(t_i, t_{i-1}, w_i, w_{i-1})$$

**Definition 5.11** The difference method

$$w_0 = \alpha$$

$$w_{i+1} = w_i + h\phi(t_i, w_i), \quad \text{for each } i = 0, 1, \dots, N-1,$$

has **local truncation error**

$$\tau_{i+1}(h) = \frac{y_{i+1} - (y_i + h\phi(t_i, y_i))}{h} = \frac{y_{i+1} - y_i}{h} - \phi(t_i, y_i),$$

for each  $i = 0, 1, \dots, N-1$ , where  $y_i$  and  $y_{i+1}$  denote the solution at  $t_i$  and  $t_{i+1}$ , respectively. ■

**Definition 5.18** A one-step difference-equation method with local truncation error  $\tau_i(h)$  at the  $i$ th step is said to be **consistent** with the differential equation it approximates if

$$\lim_{h \rightarrow 0} \max_{1 \leq i \leq N} |\tau_i(h)| = 0.$$

**Definition 5.19** A one-step difference-equation method is said to be **convergent** with respect to the differential equation it approximates if

$$\lim_{h \rightarrow 0} \max_{1 \leq i \leq N} |w_i - y(t_i)| = 0,$$

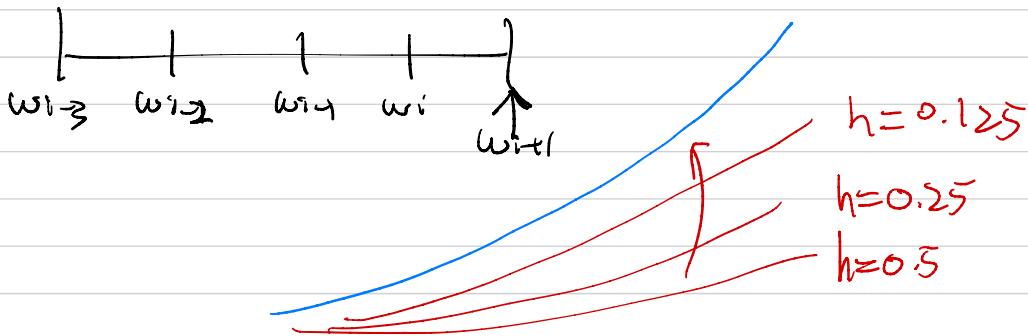
where  $y(t_i)$  denotes the exact value of the solution of the differential equation and  $w_i$  is the approximation obtained from the difference method at the  $i$ th step. ■

## Definition of stable

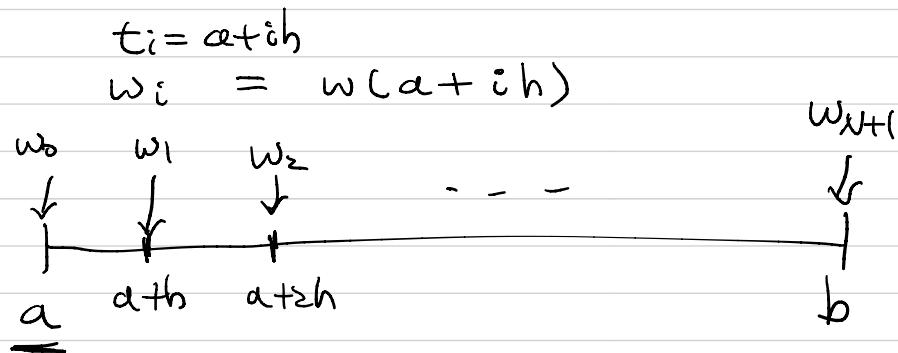
A method is convergent if the solution to the difference equation approaches the solution to the differential equation as the step size goes to zero.

To analyze this situation, at least partially, we will try to determine which methods are **stable**, in the sense that small changes or perturbations in the initial conditions produce correspondingly small changes in the subsequent approximations.

The concept of stability of a one-step difference equation is somewhat analogous to the condition of a differential equation being well-posed, so it is not surprising that the Lipschitz condition appears here, as it did in the corresponding theorem for differential equations, Theorem 5.6 in Section 5.1.



Q: Find the local truncation error of Euler's method.



$$N = \frac{(b-a)}{h}$$

$$w_{i+1} = w_i + h f(t_i, w_i)$$

$$y(t+h) = y(t) + h y'(t) + \sum \frac{h^2}{2} y''(t) + \underbrace{\frac{h^3}{6} y'''(t) + \frac{h^4}{24} y^{(4)}(t) + \dots}_{O(h^3)}$$

$$y(t+h) = y(t) + h y'(t) + \frac{h^2}{2} y''(t) + O(h^3)$$

$$y(t+h) - y(t) - h y'(t) = \frac{h^2}{2} y''(t) + O(h^3)$$

$$\frac{y(t+h) - y(t)}{h} - y'(t) = \frac{h}{2} y''(t) + O(h^2) = O(h)$$

$$\left| \frac{h}{2} y''(t) + O(h^2) \right| = \text{local truncation error.}$$

$$\left| \frac{h}{2} \frac{d}{dt} f(t, y) + O(h^2) \right| = O(h)$$

**Example 1** Show that Euler's method is convergent.

$$y(t_{N+1}) = y(t_N) + h f(t_N, y(t_N)) + \frac{h^2}{2} \underbrace{\frac{d}{dt} f(t_N, y(t_N))}_{\text{local linearization}} + O(h^3)$$

$$\omega_{N+1} = \omega_N + h f(t_N, \omega_N)$$

$$\begin{aligned} |y(t_{N+1}) - \omega_{N+1}| &= \left| (y(t_N) - \omega_N) + h (f(t_N, y(t_N)) - f(t_N, \omega_N)) + \frac{h^2}{2} \frac{d}{dt} f \right| \\ &\leq |y(t_N) - \omega_N| + h |f(t_N, y(t_N)) - f(t_N, \omega_N)| + \left| \frac{h^2}{2} \frac{d}{dt} f \right| \end{aligned}$$

Assumption : ①  $f$  is Lip in the var  $y$ .

②  $\left| \frac{d}{dt} f \right| \leq M$ . for some positive constant  $M$

$$\leq |y(t_N) - \omega_N| + h L |y(t_N) - \omega_N| + \frac{h^2 M}{2}$$

$$|y(t_{N+1}) - \omega_{N+1}| \leq (1 + hL) |y(t_N) - \omega_N| + \frac{h^2 M}{2}$$

$$\leq (1 + hL) \left( (1 + hL) |y(t_{N-1}) - \omega_{N-1}| + \frac{h^2 M}{2} \right) + \frac{h^2 M}{2}$$

$$= (1 + hL)^2 |y(t_{N-1}) - \omega_{N-1}| + \frac{h^2 M}{2} (1 + hL + 1)$$

$$\leq (1 + hL)^{N+1} |y(t_0) - \omega_0| + \frac{h^2 M}{2} \left( (1 + hL)^N + (1 + hL)^{N-1} + \dots + 1 \right)$$

$$= \frac{h^2 M}{2} \left( (1 + hL)^N + (1 + hL)^{N-1} + \dots + 1 \right)$$

$$r^N + r^{N-1} + \dots + 1 = \frac{1 - r^{N+1}}{1 - r}$$

$$= \frac{h^2 N}{2} \frac{1 - (1+hL)^{N+1}}{1 - (1+hL)}$$

$$= \frac{h^2 N}{2} \frac{1 - (1+hL)^{N+1}}{-hL}$$

$$= \frac{h^2 N}{2} \frac{(1+hL)^{N+1} - 1}{hL}$$

$$= \frac{hM}{2L} \left( (1+hL)^{N+1} - 1 \right) \quad (1+x)^m \approx e^{xm}$$

$$\approx \frac{hM}{2L} \left( e^{\downarrow hL(N+1)} - 1 \right)$$

↓

**Theorem 5.20** Suppose the initial-value problem

$$y' = f(t, y), \quad a \leq t \leq b, \quad y(a) = \alpha,$$

is approximated by a one-step difference method in the form

$$w_0 = \alpha,$$

$$w_{i+1} = w_i + h\phi(t_i, w_i, h).$$

Suppose also that a number  $h_0 > 0$  exists and that  $\phi(t, w, h)$  is continuous and satisfies a Lipschitz condition in the variable  $w$  with Lipschitz constant  $L$  on the set

$$D = \{(t, w, h) \mid a \leq t \leq b \text{ and } -\infty < w < \infty, 0 \leq h \leq h_0\}.$$

Then

- (i) The method is stable;
- (ii) The difference method is convergent if and only if it is consistent, which is equivalent to

$$\phi(t, y, 0) = f(t, y), \quad \text{for all } a \leq t \leq b;$$

- (iii) If a function  $\tau$  exists and, for each  $i = 1, 2, \dots, N$ , the local truncation error  $\tau_i(h)$  satisfies  $|\tau_i(h)| \leq \tau(h)$  whenever  $0 \leq h \leq h_0$ , then

$$|y(t_i) - w_i| \leq \frac{\tau(h)}{L} e^{L(t_i-a)}. \quad \blacksquare$$

**Example 2** The Modified Euler method is given by  $w_0 = \alpha$ ,

$$w_{i+1} = w_i + \frac{h}{2} [f(t_i, w_i) + f(t_{i+1}, w_i + hf(t_i, w_i))], \quad \text{for } i = 0, 1, \dots, N-1.$$

Verify that this method is stable by showing that it satisfies the hypothesis of Theorem 5.20.

→ Suppose  $f$  is continuous and satisfies Lipschitz condition  
in the variable  $w$ .