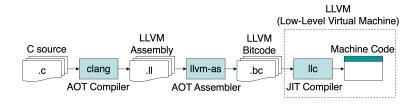
# **Code Generation**

# Multiple IRs in the Compiler

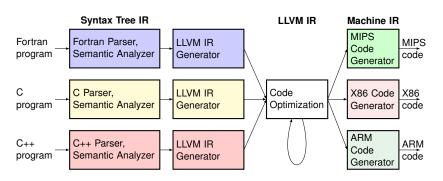
# Modern Compiler Framework (Clang/LLVM)

Remember this diagram from our first day?



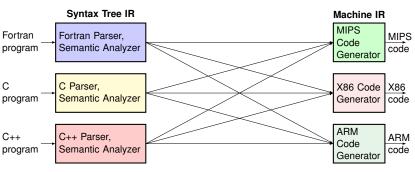
LLVM Bitcode is in LLVM IR (Intermediate Representation)

# Modern Compiler Framework (Clang/LLVM)



- Common LLVM IR for all languages and backends means:
  - Code optimizations need to be written only once
  - Implementation complexity if O(M + N) instead of O(M \* N) (where M = number of frontends, N = number of backends)

#### Why O(M \* N) when no common IR?



- Must translate M languages to N machine codes
  - Must also do optimizations during each of these translations

#### High-Level IRs

- Goal: Express the syntax and semantics of source code
- Examples: Abstract Syntax Tree, Parse Tree
- ☐ Differs on: Source code programming language
- Uses:
  - Generated by syntax analysis
  - Used by semantic analysis for binding and type checking
  - Language-specific optimizations (e.g. devirtualization)
  - Devirtualization: changing polymorphic calls to direct calls
    - Polymorphic method calls are indirect jumps using a vtable (A vtable is a table of function pointers for each class)
    - Sometimes the direct call is inlined into caller method

#### Low-Level IRs

- Goal: Express code in the ISA of an abstract machine
- Examples: Three address code, Static Single Assignment
- ☐ Differs on: Language and back-end machine agnostic
- Uses:
  - > A common IR that connects front-ends and back-ends
  - Language / machine independent optimizations
    - Common subexpression elimination
    - Constant propagation
    - Loop invariant code motion
    - ...
  - Optimizations done in this common IR unless reason not to

#### Machine IRs

- Goal: Generate code in the ISA of back-end machine
- Examples: x86 IR, ARM IR, MIPS IR
- ☐ Differs on: Back-end machine ISA
- Uses:
  - > Register allocation / machine code generation
  - > Machine-specific optimizations
    - Strength reduction (replacing op with cheaper op)
    - Vectorization (using CPU vector units if available)
    - ..

# Low-Level IRs

#### Three Address Code

Generic form is X = Y op Z

where X, Y, Z can be variables, constants, or compiler-generated temporaries holding intermediate values

- Characteristics
  - Assembly code for an 'abstract machine'
  - Long expressions are converted to multiple instructions
  - Control flow statements are converted to jumps
  - Machine independent
    - Operations are generic (not tailored to specific machine)
    - Function calls represented as generic call nodes
    - Uses symbolic names rather than register names (Actual locations of symbols are yet to be determined)
- Why this form?
  - Allows IR to be generated in a machine-agnostic way
  - Optimizations on IR can be done much more easily (Optimizations don't worry about syntactic structure)

#### Example

An example:

$$x * y + z / w$$
 is translated to

$$t1 = x * y$$
;  $t1$ ,  $t2$ ,  $t3$  are temporary variables

$$t2 = z / w$$

$$t3 = t1 + t2$$

- Sequential translation of an AST
- > Internal nodes in AST are translated to temporary variables
- > Can be generated through a depth-first traversal of AST

# Common Three-Address Statements (I)

Assignment statement:

$$x = y op z$$

where op is an arithmetic or logical operation (binary operation)

Assignment statement:

$$x = op y$$

where op is an unary operation such as -, not, shift)

Copy statement:

$$x = y$$

Unconditional jump statement:

goto L

where L is label

# Common Three-Address Statements (II)

```
Conditional jump statement:
          if (x relop y) goto L
    where relop is a relational operator such as =, \neq, >, <
 Procedural call statement:
          param x_1, ..., param x_n, call F_v, n
    As an example, foo(x1, x2, x3) is translated to
         param x<sub>1</sub>
         param x<sub>2</sub>
         param x<sub>3</sub>
         call foo. 3
 Procedural call return statement:
          return y
```

where y is the return value (if applicable)

# Common Three-Address Statements (III)

Indexed assignment statement:

y[i] = x

where x is an int and y is an array variable

Address and pointer operation statement:

x = & y; a pointer x is set to the address of y

; y is set to value contained in the location

$$^*y = x$$

; location addressed by y gets value x

#### Implementation of Three-Address Code

- ☐ There are three possible ways to store the code
  - quadruples
  - > triples
  - indirect triples
- Using quadruples op src1, src2, dest
  - There are four fields at maximum
  - Src1 and src2 are optional
  - Src1, src2, dest are variables (including temporaries)

#### **Examples:**

$$x = a + b$$
 => + a, b, x  
 $x = -y$  => -y, , x  
goto L => goto , , L

# **Using Triples**

- Tripes have only three fields. How?
  - Destination field of instruction is always a temporary (With the exception of assignments to variables)
  - Replace use of temporary wth pointer to that instruction
  - Instruction no longer needs a destination field!

Example: a = b \* (-c) + b \* (-c)

	Quadruples				Triple	S	
	ор	src1	src2	dest	ор	src1	src2
(0)	-	С		t1	-	С	
(1)	*	b	t1	t1	*	b	(0)
(2)	-	С		t2	-	С	
(3)	*	b	t2	t2	*	b	(2)
(4)	+	t1	t2	t1	+	(1)	(3)
(5)	=	t1		а	=	а	(4)

# More About Triples

Triples for array statements

$$x[i] = y$$

is translated to

- (0) [] x i
- (1) = (0) y
- That is, one statement is translated to two triples

# **Using Indirect Triples**

- Problem with triples
  - No code moving allowed because triple locations change (that would invalidate pointers to those locations, right?)

	Quadruples				Triple	S	
	ор	src1	src2	dest	ор	src1	src2
(0)	-	С		t1	-	С	
(1)	*	b	t1	t1	*	b	(0)
(2)	-	С		t2	-	С	
(3)	*	b	t2	t2	*	b	(2)
(4)	+	t1	t2	t1	+	(1)	(3)
(5)	=	t1		а	=	а	(4)

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	ор	src1	src2	dest	ор	src1	src2
(0)	-	С		t1	-	С	
(1)	*	b	t1	t1	*	b	(0)
(2)	+	t1	t1	t1	+	(1)	(1)
(3)	=	t1		а	=	а	(4)

# **Using Indirect Triples**

- ➤ IR is now a listing of pointers to triples
- > Triples are stored in a separate instruction storage (Typically triple objects are stored in program heap)
- Now code movement will not change locations of triples

	Indirect Triples					
	(ptr to triple storage)					
(0)	(0)					
(1)	(1)					
(2)	(2)					
(3)	(3)					
(4)	(4)					
(5)	(5)					

	Triple Storage				
	ор	src1	src2		
(0)	-	С			
(1)	*	b	(0)		
(2)	-	С			
(2)	*	b	(2)		
(4)	+	(1)	(3)		
(5)	=	а	(4)		

### After Optimization

	Indirect Triples					
	(ptr to triple database)					
(0)	(0)					
(1)	(1)					
(2)	(4)					
(3)	(5)					

	Triple Storage						
	ор						
(0)	-	С					
(1)	*	b	(0)				
(2)	-	С					
(3)	*	b	(2)				
(4)	+	(1)	(1)				
(5)	=	а	(4)				

- After optimization, triple objects sometimes can be freed
  - > Free space will get reused by heap management system

### After Optimization

	Indirect Triples					
	(ptr to triple database)					
(0)	(0)					
(1)	(1)					
(2)	(4)					
(3)	(5)					

	Triple Storage				
	ор	src1	src2		
(0)	-	С			
(1)	*	b	(0)		
(2)	(free	e space	∍)		
(3)	(free	e space	∍)		
(4)	+	(1)	(1)		
(5)	=	а	(4)		

After optimization, triple objects sometimes can be freed

> Free space will get reused by heap management system

### After Optimization

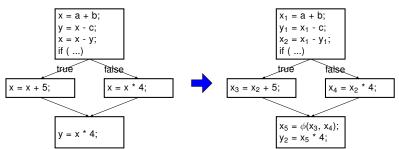
	Indirect Triples					
	(ptr to triple database)					
(0)	(0)					
(1)	(1)					
(2)	(4)					
(3)	(5)					

	Triple Storage				
	ор	src1	src2		
(0)	-	С			
(1)	*	b	(0)		
(2)	(free space)				
(3)	(free	e space	∍)		
(4)	+	(1)	(1)		
(5)	=	а	(4)		

- After optimization, triple objects sometimes can be freed
  - > Free space will get reused by heap management system
- LLVM IR is represented in memory in this way as well

# Static Single Assignment (SSA)

- Developed by R. Cytron, J. Ferrante, et al. in 1980s
  - Every variable is assigned exactly once i.e. one **DEF**
  - Convert original variable name to name  $_{version}$  e.g.  $x \rightarrow x_1, x_2$  in different places
  - ightharpoonup Use  $\phi$ -function to combine two DEFs of same original variable on a control flow merge



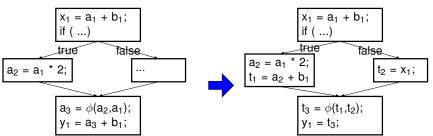
# SSA helps compiler optimizations

Dead Code Elimination (DCE):

$$x = a + b;$$
  
 $x = c - d;$   
 $y = x * b;$   
 $x_1 = a + b;$   
 $x_2 = c - d;$   
 $y_1 = x_2 * b;$ 

 $\dots$   $x_1$  is defined but never used, it is safe to remove

Partial Redundancy Elimination (PRE):



Redundant a + b computation on false branch is removed

# Why does SSA help optimizations?

- ☐ Data dependencies between instructions are made explicit
  - Variables with same name guaranteed to have same value
- Without SSA, same name does not mean same value
  - Must maintain data dependence graph to express this info
- We will discuss more in compiler optimization phase

# **Laying Out Memory**

- Local variables of a function are allocated on stack frame
  - Maintain offset from base of frame to allocate next variable
    - address(x) ← offset
    - offset += sizeof(x.type)

```
void foo() {
   int a;
   int b;
   long long c;
   int d;
}
```

- Local variables of a function are allocated on stack frame
  - Maintain offset from base of frame to allocate next variable
    - address(x) ← offset
    - offset += sizeof(x.type)

```
      void foo() {
      Address

      int a;
      0x0000

      int b;
      0x0004

      long long c;
      0x0008

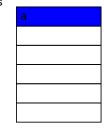
      int d;
      0x000c

      }
      0x0010
```

- Local variables of a function are allocated on stack frame
  - Maintain offset from base of frame to allocate next variable
    - address(x) ← offset
    - offset += sizeof(x.type)

```
void foo() {
  int a;
  int b;
  long long c;
  int d;
}
```

```
Address
0x0000
0x0004
0x0008
0x000c
0x0010
```

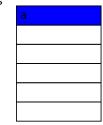


Offset=0 Addr(a) $\leftarrow$ 0

- Local variables of a function are allocated on stack frame
  - Maintain offset from base of frame to allocate next variable
    - address(x) ← offset
    - offset += sizeof(x.type)

```
void foo() {
  int a;
  int b;
  long long c;
  int d;
}
```

```
Address
0x0000
0x0004
0x0008
0x000c
0x0010
```

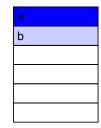


Offset=4 Addr(a) $\leftarrow$ 0

- Local variables of a function are allocated on stack frame
  - > Maintain offset from base of frame to allocate next variable
    - address(x) ← offset
    - offset += sizeof(x.type)

```
void foo() {
  int a;
  int b;
  long long c;
  int d;
}
```

```
Address
0x0000
0x0004
0x0008
0x000c
0x0010
```



Offset=8 Addr(a) $\leftarrow$ 0 Addr(b) $\leftarrow$ 4

- Local variables of a function are allocated on stack frame
  - > Maintain offset from base of frame to allocate next variable
    - address(x) ← offset
    - offset += sizeof(x.type)

```
void foo() {
    int a;
    int b;
    long long c;
    int d;
}
```

```
Address
0x0000
0x0004
0x0008
0x000c
0x0010
```

Offset=16 Addr(a) $\leftarrow$ Addr(b) $\leftarrow$ Addr(c) $\leftarrow$ 

- Local variables of a function are allocated on stack frame
  - > Maintain offset from base of frame to allocate next variable
    - $address(x) \leftarrow offset$
    - offset += sizeof(x.type)

```
void foo() {
    int a;
    int b;
    long long c;
    int d;
}

void foo() {
    0x00000
    0x0004
    0x00008
    int d;
}
```

```
Offset=20
Addr(a)\leftarrow0
Addr(b)\leftarrow4
Addr(c)\leftarrow8
Addr(d)\leftarrow16
```

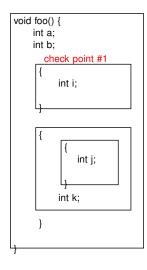
# What if function has nested scopes?

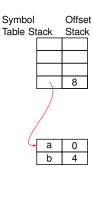
Let's take the below example code:

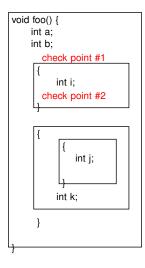
```
void foo() {
   int a:
   int b;
      int i;
         int j;
      int k;
```

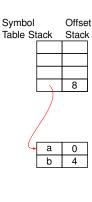
■ What is address(k)? 16?

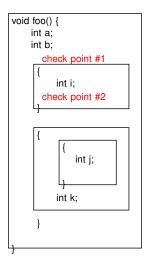
# Nested Scopes Example

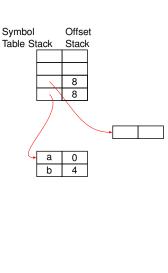


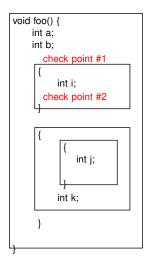


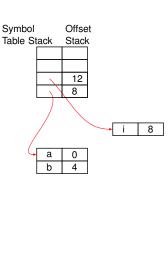


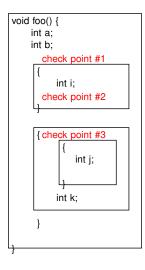


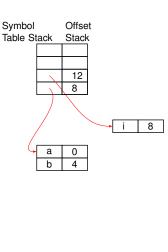


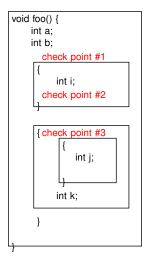


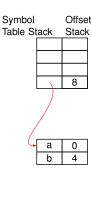


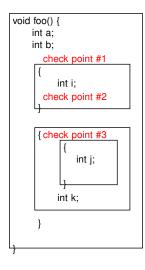


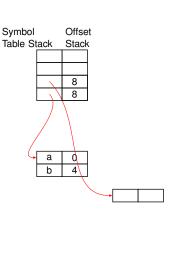


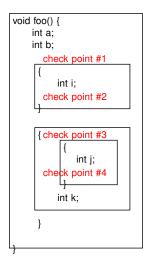


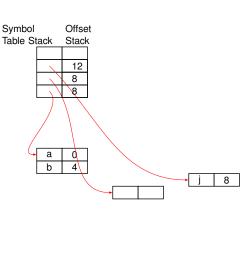


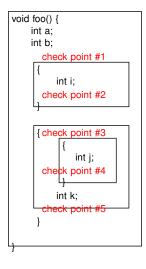


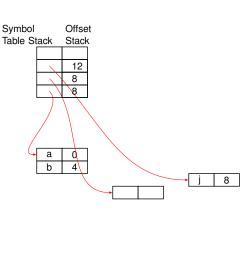


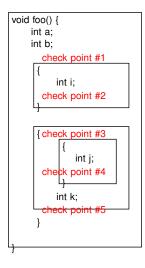


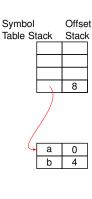


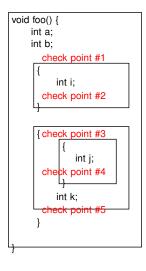


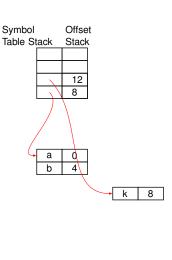












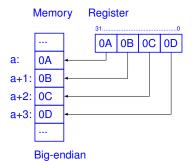
#### Consideration 1: Allocation Alignment

- Enforce addr(var) mod sizeof(memory word) == 0
  - Memory word: unit of memory access in given CPU
  - > If not, need to load two words and shift & concatenate

- This makes memory layout backend machine dependent
  - > Memory layout made explicit only in Machine IR
  - > Low-level IR needs to refers to locations in an abstract way

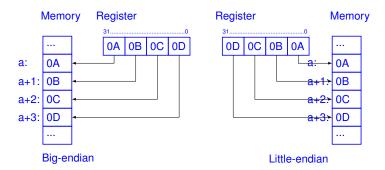
#### Consideration II: Endianness

- Endianness
  - > Big endian: MSB (most significant byte) in lowest address
  - > Little endian: LSB (least significant byte) in lowest address



#### Consideration II: Endianness

- Endianness
  - > Big endian: MSB (most significant byte) in lowest address
  - ➤ Little endian: LSB (least significant byte) in lowest address



#### How about other memory besides stack memory?

- Static Memory
  - > Where global variables and other static variables reside
  - Layout variables from base address in the same way
- Heap Memory
  - Where dynamically allocated memory using malloc reside
  - Handled by runtime memory management library
  - Compiler not much to do with how this memory is laid out

# Generating IR

#### Generating IR from Language Constructs

- Goal: translate language constructs in syntax tree to IR
  - Two ways to implement semantic rules for translation
    - > By depth-first traversal of syntax tree built by parser
      - This is what you are doing for Project 4
    - By a syntax directed translation scheme
      - This is what we will discuss now (based on LR parser)
      - But most concepts apply to both implementations

#### Generating IR from Language Constructs

- Goal: translate language constructs in syntax tree to IR
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      - This is what you are doing for Project 4
    - By a syntax directed translation scheme
      - This is what we will discuss now (based on LR parser)
      - But most concepts apply to both implementations
- What language structures do we need to translate?
  - Declarations
    - Variables, functions (parameters and return types), ...
  - Statements
    - Assignment statements
    - Function call statements
    - Control flow statements (if-then-else, for/while loops)
  - Expressions
    - X + Y, X Y, X < Y, X > Y, X == Y, ...

#### Attributes to Evaluate in Translation

- Variable declaration:
  - **T V** e.g. int a,b,c;
  - > Type information **T.type T.width**
  - > Variable information V.type, V.offset
- Statement **S** 
  - > S.code: synthesized attribute that holds IR code of S
- Expression E
  - > E.code: synthesized attribute that holds IR code for E
  - E.place: synthesized attribute for temporary variable name to store result of E (for SSA, virtual register name)

#### **Processing Declarations**

- ☐ Translating declarations in a single scope
  - > enter(name, type, offset): insert variable into symbol table

```
\begin{array}{lll} S \rightarrow M \ D \\ M \rightarrow \varepsilon & \{ \ offset=0; \} \ /^* \ reset \ offset \ before \ layout \ ^*/ \\ D \rightarrow D \ D \\ D \rightarrow T \ id; & \{ \ enter(id.name, \ T.type, \ offset); \ offset \ += \ T.width; \} \\ T \rightarrow integer & \{ \ T.type=integer; \ T.width=4; \} \\ T \rightarrow real & \{ \ T.type=real; \ T.width=8; \} \\ T \rightarrow T1[num] & \{ \ T.type=array(num.val, \ T1.type); \\ & T.width=num.val \ ^* \ T1.width; \} \\ T \rightarrow \ ^* \ T1 & \{ \ T.type=ptr(T1.type); \ T.width=4; \} \end{array}
```

### Processing Declarations in Nested Scopes

- Translating declarations in nested scopes
  - push(item, stack): Pushes item on to stack
  - > pop(stack): Pops item at the top of stack
  - > top(stack): Returns item at the top of stack

```
\begin{array}{lll} S \to M \ D & \{ \ pop(tblptr); \ pop(offset); \} \\ M \to \varepsilon & \{ \ t=mktable(nil); \ push(t, \ tblptr); \ push(0,offset); \} \\ D \to D \ D & \\ D \to \{ \ N \ D \ \} & \{ \ pop(tblptr); \ pop(offset); \} \\ N \to \varepsilon & \{ \ t=mktable(nil); \ push(t, \ tblptr); \ push(top(offset), \ offset); \\ D \to T \ id; & \{ \ enter(id.name, \ T.type, \ top(offset)); \\ & top(offset) = top(offset) + T.width; \} \end{array}
```

#### **Processing Statements**

- Statements rely on symbol table populated by declarations
  - > lookup (id): search id in symbol table, return nil if none
  - > emit(code): print three address IR for code
  - > newtemp(): get a new temporary variable (or register)
    - E.g., in SSA form, it returns the next virtual register number int newtemp() { return virtual\_register++; }

```
\begin{split} S &\rightarrow \mathsf{id} = \mathsf{E} \quad \{ \text{ P=lookup(id); if } (\mathsf{P==nil}) \text{ perror(...); else } \mathsf{emit}(\mathsf{P} \text{ '=' E.place}); \} \\ E &\rightarrow \mathsf{E1} + \mathsf{E2} \{ \text{ E.place = newtemp(); emit(E.place '=' E1.place '+' E2.place); } \} \\ E &\rightarrow \mathsf{E1} \quad \text{* E2 } \{ \text{ E.place = newtemp(); emit(E.place '=' E1.place '*' E2.place); } \} \\ E &\rightarrow \mathsf{-E1} \quad \text{$\{ \text{ E.place = newtemp(); emit(E.place '=' '-' E1.place); } \} } \\ E &\rightarrow \mathsf{(E1)} \quad \text{$\{ \text{ E.place = E1.place; } \} } \\ E &\rightarrow \mathsf{id} \quad \text{$\{ \text{ P=lookup(id); E.place=P; } \} } \end{split}
```

### **Processing Array References**

Recall generalized row/column major addressing

For example:

1-dimension: int x[100]; ..... x[i<sub>1</sub>]

2-dimension: int x[100][200]; ..... x[i<sub>1</sub>][i<sub>2</sub>]

3-dimension: int x[100][200][300]; .....  $x[i_1][i_2][i_3]$ 

Row major: offset of a k-dimension array item

1-dimension:  $A_1 = a_1^*$  width

2-dimension:  $A_2 = a_2^*$ width  $a_2 = a_1^* N_2 + i_2$ 

 $a_1 = i_1$ 

3-dimension:  $A_3 = a_3^*$  width  $a_3 = a_2^* N_3 + i_3$ 

...

k-dimension:  $A_k = a_k^*$ width  $a_k = a_{k-1}^* N_k + i_k$ 

#### **Processing Array References**

```
Processing an array assignment (e.g. A[i] = B[i];)
S \rightarrow L = E { t = newtemp(); emit( t '=' L.place '*' L.width);
                 emit(t '=' L.base '+' t); emit ('*'t '=' E.place); }
E \rightarrow L { E.place = newtemp(); t= newtemp();
                 emit( t '=' L.place '*' L.width); emit ( E.place '=' (L.base '+' t) ); }
L → id [E] { L.base = lookup(id).base; L.width = lookup(id).width; L.dim=1;
                 L.place = E.place; }
L \rightarrow L1 [E] \{L.base = L1.base; L.width = L1.width; L.dim = L1.dim + 1;
                 L.place = newtemp();
                 emit( L.place '=' L1.place '*' L.max[L.dim]);
                 emit( L.place '=' L.place '+' E.place); }
```

### **Processing Boolean Expressions**

- Boolean expression: a op b
  - ➤ where op can be <, >, >=, &&, ||, ...
  - 1. Without short circuiting
    - > Short circuiting:
      - In expression A && B, not evaluating B when A is false
      - In expression A || B, not evaluating B when A is true
    - Without short circuiting, entire expression is evaluated:

```
\begin{array}{ll} S \rightarrow \text{id} = E & \equiv & \text{lookup(id)} = \text{E.place} \\ E \rightarrow (a < b) \text{ or } (c < d \text{ and } e < f) \equiv & t1 = a < b \\ & t2 = c < d \\ & t3 = e < f \\ & t4 = t2 \text{ \&\& } t3 \\ & \text{E.place} = t1 \text{ || } t4 \end{array}
```

#### **Processing Boolean Expressions**

- 2. With short circuiting (e.g. C/C++/Java)
  - Processing simple boolean expressions:

```
S \rightarrow if E then S1

E \rightarrow a < b \equiv E.true = code for S1;

E.false = S.next;

emit( if E goto E.true );

emit( goto E.false );
```

S.next: address of code after S

E.true: address of code to execute on 'true'

E.false: address of code to execute on 'false'

- Processing compound boolean expressions:
  - Chain together multiple of above by updating E.true/E.false
  - E→ E1 && E2: E1.true = code for E2, E1.false = S.next
  - E $\rightarrow$  E1 || E2: E1.false = code for E2, E1.true = code for S1

### Processing Boolean Expressions

- 2. With short circuiting (cont'd)
  - ➤ A short circuited compound boolean expression

```
\begin{array}{ll} S \! \to \text{if E then S1} \\ E \! \to \text{(a < b) or (c < d and e < f)} \equiv & E.true = \text{code for S1}; \\ E.false = S.next; \\ emit( & \text{if (a < b) goto E.true} \\ \text{goto L1} \\ \text{L1: if (c < d) goto L2} \\ \text{goto E.false} \\ \text{L2: if (e < f) goto E.true} \\ \text{goto E.false} \\ \text{\text{\text{.}}} \end{array}
```

- Problem: E.true, E.false, S.next are non-L-attributes
  - Depend on code that has not been generated yet
     E.true: Only available when S1 is generated
     E.false: Only available when code after S is generated
  - Emitting any forward jump poses this problem

#### **Syntax Directed Translation**

- Non-L-attributs preclude syntax directed translation
  - > Even with parse tree, preclude simple left-to-right traversal
- Solutions: two methods
  - > Two pass approach process the code twice
    - Generate labels in the first pass
    - Replace labels with addresses in the second pass
  - One pass approach
    - Generate holes when address is needed but unknown
    - Backpatch holes when address is known later on
- We will discuss the more efficient one pass approach
  - It is also the method you will use in project 4.

#### One-Pass Based Syntax Directed Translation

- Non-L-attributes during code generation are unavoidable
  - Due to forward jumps to code on the right hand side
  - > Example: E.true, E.false, S.next for boolean expressions
  - Is there a one-pass solution to the problem?

#### Idea:

- Leave holes for non-L-attribute values we don't know
- 2. Fill the holes in when we know the values later on
  - > holelist: synthesized attribute of 'holes' for one value
  - > Holes are filled in by traversing list when value is known
  - All holes will be patched by the end of code generation (Since all forward jumps would be resolved by then)

#### One-Pass Based Syntax Directed Translation

- Attributes for two pass based approach
  - Expression E
    - Synthesized attributes: E.codeE.holes\_truelist, and E.holes\_falselist
  - > Statement S
    - Synthesized attributes: S.code and S.holes\_nextlist
- 3 functions for implementing backpatching
  - > makelist(i): create a holelist with statement index i
  - merge(p1, p2): concatenate list p1 and list p2
  - > backpatch(p, i): insert index i in every hole in holelist p

#### Backpatching for if-then

- $\square$  Given rule  $S \rightarrow if E then S1, below is done in one-pass:$ 
  - (1). Gen E.code, making E.holes\_truelist, E.holes\_falselist
  - (2). Gen S1.code, filling in E.holes\_truelist and merging S1.holes\_nextlist with E.holes\_falselist
  - (3). Pass on merged list to **S.holes\_nextlist**

```
S \rightarrow \text{if E then M S1} \\ \{ \\ \text{backpatch(E.holes\_truelist, M.index);} \\ \text{S.holes\_nextlist} = \text{merge(S1.holes\_nextlist, E.holes\_falselist);} \\ \text{M} \rightarrow \varepsilon \\ \{ \text{M.index} = \text{curIndex;} \} \\ \\ \text{E.true:} \\ \text{E.code} \\ \text{S1.code} \\ \text{Snextlist} \\ \text{S
```

#### Backpatching for if-then-else

- $\square$  Given rule S  $\rightarrow$  if E then S1 else S2:
  - (1). Gen E.code, making E.holes\_truelist, E.holes\_falselist
  - (2). Gen S1.code, filling in E.holes\_truelist
  - (3). Emit goto to S.next before S2, to skip over S2
  - (4). Gen S2.code, filling in E.holes\_falselist
  - (5). Merge relevant holes into S.holes\_nextlist

```
\begin{split} S &\rightarrow \text{if E then M1 S1 N else M2 S2} \\ \{ \\ \text{backpatch(E.holes\_truelist, M1.index);} \\ \text{backpatch(E.holes\_falselist, M2.index);} \\ \text{templist} &= \text{merge}(\text{S1.holes\_nextlist}, \text{N.holes\_nextlist});} \\ \text{S.holes\_nextlist} &= \text{merge}(\text{templist, S2.holes\_nextlist});} \\ \text{N} &\rightarrow \varepsilon \\ \{ \\ \text{N.holes\_nextlist} &= \text{makelist}(\text{curIndex});} \\ \text{emit('goto } &\_\_\_');} \\ \} \end{split}
```

```
E.true:

E.code

S1.code

E.false:

S2.code

...
```

### Backpatching for S.holes\_nextlist

- ☐ When does the holes in S.holes\_nextlist get patched?
- When the instruction after S is generated of course!
- $\square$  Given rule  $S \rightarrow S1 S2$ :
  - (1). Gen S1.code making S1.holes\_nextlist
  - (2). Gen S2.code filling in S1.holes\_nextlist and making S2.holes\_nextlist
  - (3). Pass on S2.holes\_nextlist to S.holes\_nextlist

#### Backpatching for Boolean Expressions

```
\label{eq:energy} \begin{array}{ll} E \rightarrow \text{E1 or M E2} & \{ \text{ backpatch}(\text{E1.holes\_falselist}, \text{ M.index}); \\ & \text{ E.holes\_truelist} = \text{merge}(\text{E1.holes\_truelist}, \text{ E2.holes\_truelist}); \\ & \text{ E.holes\_falselist} = \text{E2.holes\_falselist}; \, \} \\ \\ E \rightarrow \text{E1 and M E2} & \{ \text{ backpatch}(\text{E1.holes\_truelist}, \text{ M.index}); \\ & \text{ E.holes\_falselist} = \text{merge}(\text{E1.holes\_falselist}, \text{ E2.holes\_falselist}); \\ & \text{ E.holes\_truelist} = \text{E2.holes\_truelist}; \, \} \\ \\ M \rightarrow \varepsilon & \{ \text{ M.index} = \text{curIndex}; \, \} \\ \\ \end{array}
```

#### Backpatching for Boolean Expressions

```
E \rightarrow not E1
                           { E.holes truelist = E1.holes falselist;
                              E.holes falselist = E1.holes truelist; }
E \rightarrow (E1)
                           { E.holes truelist = E1.holes truelist:
                              E.holes falselist = E1.holes falselist: }
E \rightarrow id1 \text{ relop id2}
                           { E.holes truelist = makelist(curIndex):
                              E.holes falselist = makelist(curlndex+1);
                              emit('if' id1.place 'relop' id2.place 'goto ____');
                              emit('goto '); }
\mathsf{E} \to \mathsf{true}
                           { E.holes truelist = makelist(curlndex);
                              emit('goto '); }
E \rightarrow false
                           { E.holes falselist = makelist(curIndex);
                              emit('goto '); }
```

## Backpatching Example

$$lacksquare$$
 E  $ightarrow$  (a

When reducing (a<b) to E1, we have 100: if(a<b) goto

101: goto \_\_\_\_

igspace When reducing  $\varepsilon$  to M1, we have

■ When reducing (c<d) to E2, we have</p>

102: if(c<d) goto

103: goto

 $ldsymbol{\bot}$  When reducing  $\varepsilon$  to M2, we have

■ When reducing (e<f) to E3, we have</p>

104: if(e<f) goto \_\_\_\_

105: goto

E1.hole truelist=(100)

E1.hole falselist=(101)

M1.index = 102

E2.hole truelist=(102)

E2.hole falselist=(103)

M2.index = 104

E3.hole truelist=(104)

E3.hole falselist=(105)

#### Backpatching Example (cont.)

```
When reducing (E2 and M2 E3) to E4, we backpatch((102), 104);
       100: if(a<b) goto
                                    E4.hole truelist=(104)
       101: goto
                                   E4.hole falselist=(103,105)
       102: if(c<d) goto 104
       103: goto
       104: if(e<f) goto ____
       105: goto
When reducing (E1 or M1 E4) to E5, we backpatch((101), 102);
       100: if(a<b) goto
                                   E5.hole truelist=(100, 104)
       101: goto 102
                                   E5.hole falselist=(103,105)
       102: if(c<d) goto 104
       103: goto
       104: if(e<f) goto
       105: goto
```

### Backpatching Example (cont.)

```
When reducing (E2 and M2 E3) to E4, we backpatch((102), 104);
        100: if(a<b) goto
                                     E4.hole truelist=(104)
        101: goto
                                    E4.hole falselist=(103,105)
        102: if(c<d) goto 104
        103: goto
        104: if(e<f) goto
        105: goto
When reducing (E1 or M1 E4) to E5, we backpatch((101), 102);
        100: if(a<b) goto
                                    E5.hole truelist=(100, 104)
        101: goto 102
                                    E5.hole falselist=(103,105)
        102: if(c<d) goto 104
        103: goto
        104: if(e<f) goto
        105: goto ____
  Are we done?
```

### Backpatching Example (cont.)

Yes for this expression

```
When reducing (E2 and M2 E3) to E4, we backpatch((102), 104);
          100: if(a<b) goto
                                       E4.hole truelist=(104)
          101: goto
                                      E4.hole falselist=(103,105)
          102: if(c<d) goto 104
          103: goto
          104: if(e<f) goto ____
          105: goto
 When reducing (E1 or M1 E4) to E5, we backpatch((101), 102);
          100: if(a<b) goto
                                      E5.hole truelist=(100, 104)
          101: goto 102
                                      E5.hole falselist=(103,105)
          102: if(c<d) goto 104
          103: goto
          104: if(e<f) goto
          105: goto ____
Are we done?
```

