

A Proofs of Propositions

Proof of Proposition 1. Before jumping into the details of the proposition, we first prove the posterior updating result (3.3). The definition indicates

$$f^\theta(x|s) \propto \left[\frac{f(x|s)}{f(x)} \right]^\theta = \left(\frac{\alpha}{\alpha + \beta} \right)^{\frac{\theta}{2}} \quad (\text{A.1})$$

$$\times \exp \left(-\frac{\theta}{2} \left\{ (\alpha + \beta) \left(x - \frac{\alpha z + \beta s}{\alpha + \beta} \right)^2 - \alpha(x - z)^2 \right\} \right) \quad (\text{A.2})$$

where $f(\cdot)$ denotes the density function. Since

$$(A.3) = \exp \left\{ -\frac{\alpha + \beta(1 + \theta)}{2} \left(x - \frac{\alpha z + \beta(1 + \theta)s}{\alpha + \beta(1 + \theta)} \right)^2 \right\}, \quad (\text{A.3})$$

we obtain the posterior distribution (3.3).

Substituting $\hat{s} = \hat{x} + \frac{1}{\sqrt{\beta}}\Phi^{-1}(\hat{x})$ (3.2) into (3.4), we have

$$\begin{aligned} 1 - \Phi \left(\sqrt{\alpha + \beta(1 + \theta)} \cdot \frac{\sqrt{\beta}(1 + \theta)\Phi^{-1}(\hat{x}) + \alpha(z - \hat{x})}{\alpha + \beta(1 + \theta)} \right) &= c \\ \iff \Phi^{-1}(1 - c) &= \frac{\sqrt{\beta}(1 + \theta)\Phi^{-1}(\hat{x}) + \alpha(z - \hat{x})}{\sqrt{\alpha + \beta(1 + \theta)}} \\ \iff \sqrt{1 + \frac{\alpha}{\beta(1 + \theta)}} \cdot \frac{\Phi^{-1}(1 - c)}{\sqrt{1 + \theta}} + \frac{\alpha(\hat{x} - z)}{\sqrt{\beta}(1 + \theta)} &= \Phi^{-1}(\hat{x}) \end{aligned} \quad (\text{A.4})$$

Since $\min_{x \in (0,1)} \frac{d}{dx} \Phi^{-1}(x) = \min_{x \in (0,1)} \frac{1}{\phi(\Phi^{-1}(x))} = \sqrt{2\pi}$, the equilibrium is in monotone strategies and is unique if and only if

$$\begin{aligned} \frac{\alpha}{\sqrt{\beta}(1 + \theta)} &\leq \sqrt{2\pi} \\ \iff \alpha &\leq (1 + \theta)\sqrt{2\pi}\beta \\ \iff \theta &\geq \frac{\alpha}{\sqrt{2\pi}\beta} - 1. \end{aligned}$$

It only remains to show that the unique monotone equilibrium is the only equilibrium that survives iterated deletion of strictly dominated strategies. Let $h(s)$ denote the threshold that an agent finds it optimal to follow when all other agents use a threshold s . Note that there is a 1-to-1 mapping between the thresholds \hat{x} that solve (3.2) and the fixed points of h . The monotone equilibria are defined by the fixed points of h . Construct two sequences $\{\underline{s}_j\}_{j=0}^\infty$ and $\{\bar{s}_j\}_{j=0}^\infty$ by $\underline{s}_0 = -\infty, \underline{s}_j = h(\underline{s}_{j-1})$ and $\bar{s}_0 = \infty, \bar{s}_j = h(\bar{s}_{j-1})$. Each sequence is increasing or decreasing with upper or lower bound. Thus, they both converge to some \underline{s} and \bar{x} . By continuity of h , these points must be a fixed point of h , which is \hat{s} . Since the

only strategies that survives after j rounds of iterated deletion of dominated strategies are functions k such that $k(s) = 1$ for all $s \leq \underline{s}_j$ and $k(s) = 0$ for all $s > \bar{s}_j$, the only strategy that survives in the limit is the unique monotone equilibrium. \square

Proof of Proposition 2. As $\beta \rightarrow \infty$ with $\alpha < \infty$, (LHS) of (A.4) with $\theta = 0$ becomes $\Phi^{-1}(1 - c)$ and (RHS) of (A.4) with $\theta = 0$ remains the same. Thus, we obtain $x_\infty = 1 - c$ since Φ^{-1} is monotone. Similarly, (LHS) of (A.4) becomes $\Phi^{-1}(1 - c)/\sqrt{1 + \theta}$ and (RHS) of (A.4) remains the same. Thus, we obtain $x_\infty = \Phi\left(\frac{\Phi^{-1}(1 - c)}{\sqrt{1 + \theta}}\right)$. \square

Proof of Corollary 1. Since $\Phi(\cdot)$ is an monotone increasing function and $\Phi^{-1}(\cdot)$ undergoes a sign change at $c = \frac{1}{2}$, the order of the two equilibrium thresholds flips at $c = \frac{1}{2}$. \square

B Simulation Results

To investigate how effective the comparative statics analysis is for finite values of β , I perform numerical analysis on how the equilibrium threshold changes as I vary the value of c . Since the equilibrium thresholds do not have analytical solutions, I implement simulation exercises with $\alpha = 0.3$ and $\beta = 0.5$ so that they satisfy the uniqueness condition of Proposition 1 and 2. For the other parameters, let $z = 0$ for computational convenience and $\theta = 0.5$ following the estimation results using survey expectation data in [Bordalo et al. \(2020\)](#).

As expected by Proposition 2 and Corollary 1, equilibrium thresholds differ for Bayesian global games and diagnostic global games. As I change the value of c from 0 to 1, this difference in thresholds becomes narrower, at some point around $c \in [0.5, 0.6]$ their order is reversed, and the gap becomes larger thereafter. Here, I present 3 cases where $c = 0.1, 0.6, 0.9$ which illustrate this property well in Figure 2, 3, and 4, where equilibrium thresholds are the intersections of the inverse of the normal distribution and red lines. In addition, I also implement sensitivity analysis with respect to α and β when $c = 0.1, 0.6, 0.9$.

Figure 1: Equilibrium thresholds when $c = 0.1$

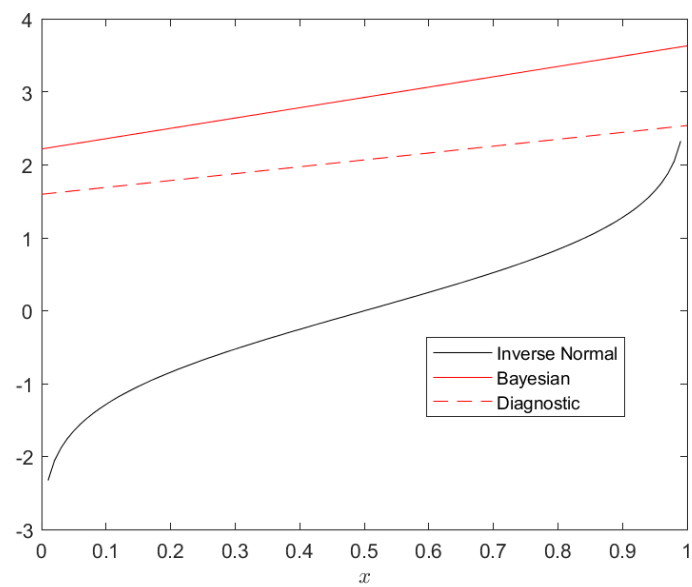


Figure 2: Equilibrium thresholds when $c = 0.6$

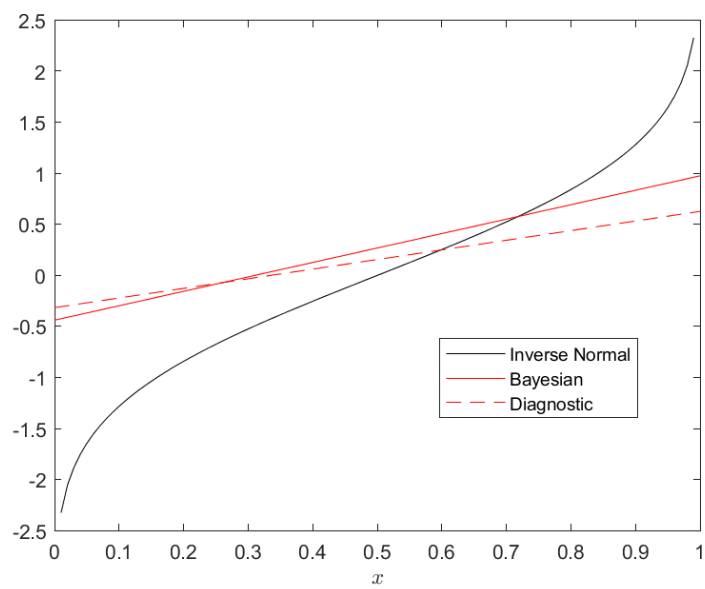


Figure 3: Equilibrium thresholds when $c = 0.9$

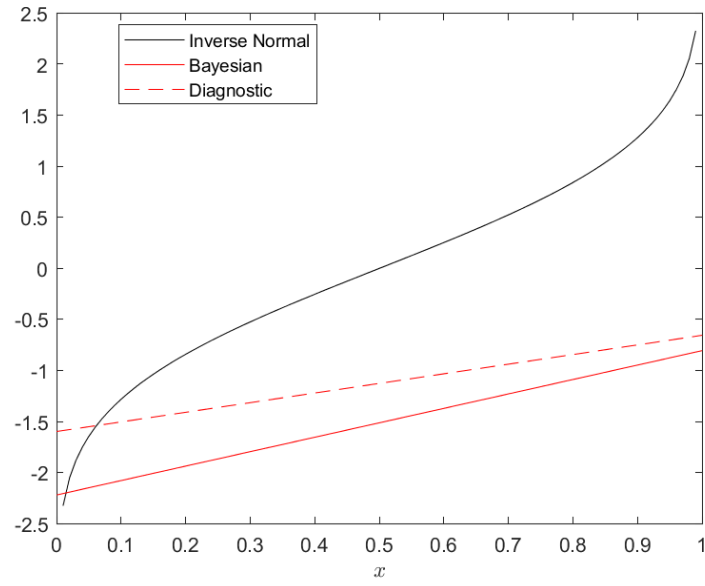
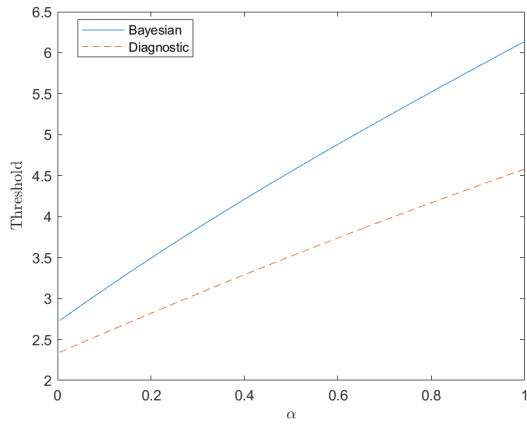
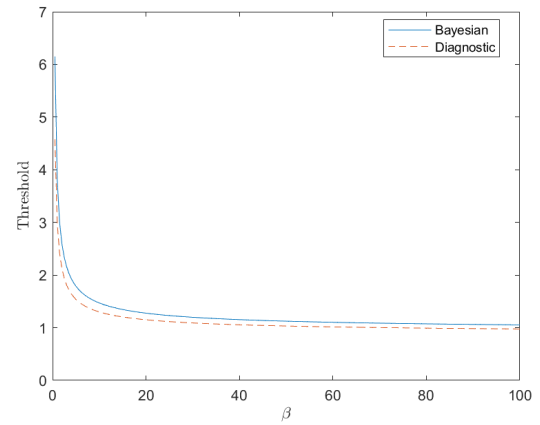


Figure 4: Sensitivity analysis when $c = 0.1$



(a) α



(b) β

Figure 5: Sensitivity analysis when $c = 0.6$

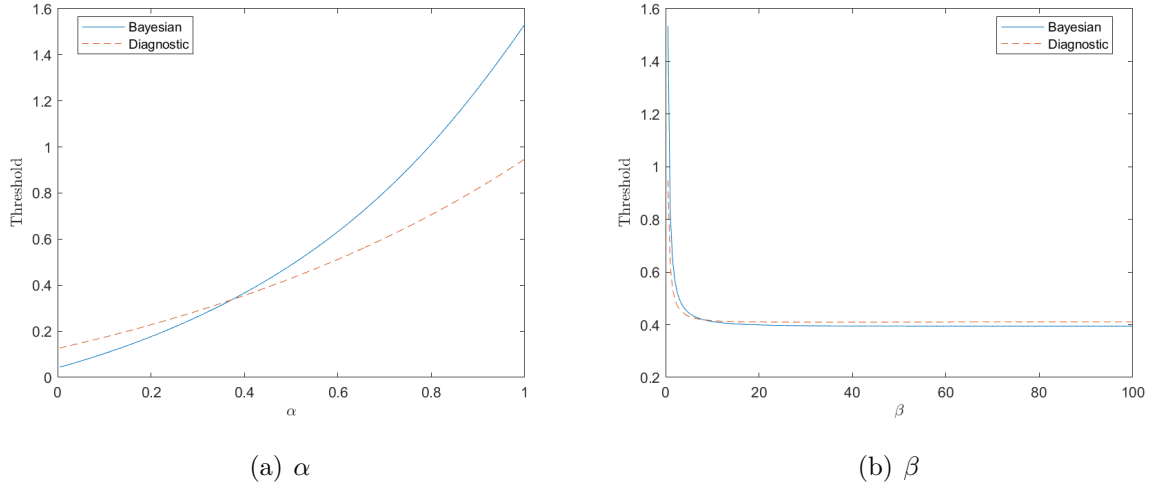
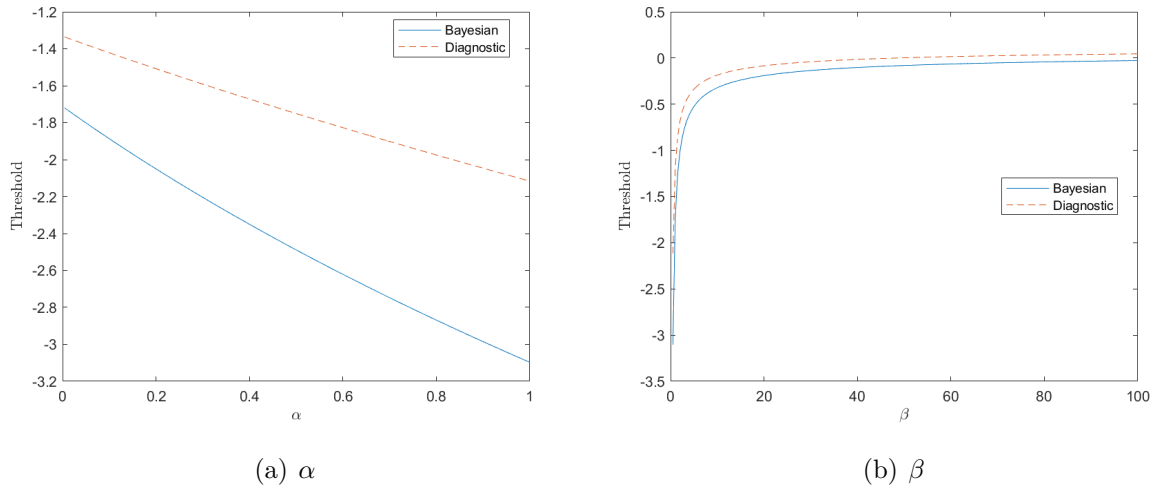


Figure 6: Sensitivity analysis when $c = 0.9$



References

- [1] Bordalo, P., Gennaioli, N., Ma, Y., and Shleifer, A. (2020). Overreaction in macroeconomic expectations. *American Economic Review*, 110(9), 2748-82.