

## A Proofs of Propositions

**Proof of Proposition 1.** Before jumping into the details of the proposition, we first prove the posterior updating result (3.3). The definition indicates

$$f^\theta(x|s) \propto \left[ \frac{f(x|s)}{f(x)} \right]^\theta = \left( \frac{\alpha}{\alpha + \beta} \right)^{\frac{\theta}{2}} \quad (\text{A.1})$$

$$\times \exp \left( -\frac{\theta}{2} \left\{ (\alpha + \beta) \left( x - \frac{\alpha z + \beta s}{\alpha + \beta} \right)^2 - \alpha(x - z)^2 \right\} \right) \quad (\text{A.2})$$

where  $f(\cdot)$  denotes the density function. Since

$$(A.3) = \exp \left\{ -\frac{\alpha + \beta(1 + \theta)}{2} \left( x - \frac{\alpha z + \beta(1 + \theta)s}{\alpha + \beta(1 + \theta)} \right)^2 \right\}, \quad (\text{A.3})$$

we obtain the posterior distribution (3.3).

Substituting  $\hat{s} = \hat{x} + \frac{1}{\sqrt{\beta}}\Phi^{-1}(\hat{x})$  (3.2) into (3.4), we have

$$\begin{aligned} 1 - \Phi \left( \sqrt{\alpha + \beta(1 + \theta)} \cdot \frac{\sqrt{\beta}(1 + \theta)\Phi^{-1}(\hat{x}) + \alpha(z - \hat{x})}{\alpha + \beta(1 + \theta)} \right) &= c \\ \iff \Phi^{-1}(1 - c) &= \frac{\sqrt{\beta}(1 + \theta)\Phi^{-1}(\hat{x}) + \alpha(z - \hat{x})}{\sqrt{\alpha + \beta(1 + \theta)}} \\ \iff \sqrt{1 + \frac{\alpha}{\beta(1 + \theta)}} \cdot \frac{\Phi^{-1}(1 - c)}{\sqrt{1 + \theta}} + \frac{\alpha(\hat{x} - z)}{\sqrt{\beta}(1 + \theta)} &= \Phi^{-1}(\hat{x}) \end{aligned} \quad (\text{A.4})$$

Since  $\min_{x \in (0,1)} \frac{d}{dx} \Phi^{-1}(x) = \min_{x \in (0,1)} \frac{1}{\phi(\Phi^{-1}(x))} = \sqrt{2\pi}$ , the equilibrium is in monotone strategies and is unique if and only if

$$\begin{aligned} \frac{\alpha}{\sqrt{\beta}(1 + \theta)} &\leq \sqrt{2\pi} \\ \iff \alpha &\leq (1 + \theta)\sqrt{2\pi}\beta \\ \iff \theta &\geq \frac{\alpha}{\sqrt{2\pi}\beta} - 1. \end{aligned}$$

It only remains to show that the unique monotone equilibrium is the only equilibrium that survives iterated deletion of strictly dominated strategies. Let  $h(s)$  denote the threshold that an agent finds it optimal to follow when all other agents use a threshold  $s$ . Note that there is a 1-to-1 mapping between the thresholds  $\hat{x}$  that solve (3.2) and the fixed points of  $h$ . The monotone equilibria are defined by the fixed points of  $h$ . Construct two sequences  $\{\underline{s}_j\}_{j=0}^\infty$  and  $\{\bar{s}_j\}_{j=0}^\infty$  by  $\underline{s}_0 = -\infty, \underline{s}_j = h(\underline{s}_{j-1})$  and  $\bar{s}_0 = \infty, \bar{s}_j = h(\bar{s}_{j-1})$ . Each sequence is increasing or decreasing with upper or lower bound. Thus, they both converge to some  $\underline{s}$  and  $\bar{x}$ . By continuity of  $h$ , these points must be a fixed point of  $h$ , which is  $\hat{s}$ . Since the

only strategies that survives after  $j$  rounds of iterated deletion of dominated strategies are functions  $k$  such that  $k(s) = 1$  for all  $s \leq \underline{s}_j$  and  $k(s) = 0$  for all  $s > \bar{s}_j$ , the only strategy that survives in the limit is the unique monotone equilibrium.  $\square$

**Proof of Proposition 2.** As  $\beta \rightarrow \infty$  with  $\alpha < \infty$ , (LHS) of (A.4) with  $\theta = 0$  becomes  $\Phi^{-1}(1 - c)$  and (RHS) of (A.4) with  $\theta = 0$  remains the same. Thus, we obtain  $x_\infty = 1 - c$  since  $\Phi^{-1}$  is monotone. Similarly, (LHS) of (A.4) becomes  $\Phi^{-1}(1 - c)/\sqrt{1 + \theta}$  and (RHS) of (A.4) remains the same. Thus, we obtain  $x_\infty = \Phi\left(\frac{\Phi^{-1}(1 - c)}{\sqrt{1 + \theta}}\right)$ .  $\square$

**Proof of Corollary 1.** Since  $\Phi(\cdot)$  is an monotone increasing function and  $\Phi^{-1}(\cdot)$  undergoes a sign change at  $c = \frac{1}{2}$ , the order of the two equilibrium thresholds flips at  $c = \frac{1}{2}$ .  $\square$

## B Simulation Results

To investigate how effective the comparative statics analysis is for finite values of  $\beta$ , I perform numerical analysis on how the equilibrium threshold changes as I vary the value of  $c$ . Since the equilibrium thresholds do not have analytical solutions, I implement simulation exercises with  $\alpha = 0.3$  and  $\beta = 0.5$  so that they satisfy the uniqueness condition of Proposition 1 and 2. For the other parameters, let  $z = 0$  for computational convenience and  $\theta = 0.5$  following the estimation results using survey expectation data in [Bordalo et al. \(2020\)](#).

As expected by Proposition 2 and Corollary 1, equilibrium thresholds differ for Bayesian global games and diagnostic global games. As I change the value of  $c$  from 0 to 1, this difference in thresholds becomes narrower, at some point around  $c \in [0.5, 0.6]$  their order is reversed, and the gap becomes larger thereafter. Here, I present 3 cases where  $c = 0.1, 0.6, 0.9$  which illustrate this property well in Figure 2, 3, and 4, where equilibrium thresholds are the intersections of the inverse of the normal distribution and red lines. In addition, I also implement sensitivity analysis with respect to  $\alpha$  and  $\beta$  when  $c = 0.1, 0.6, 0.9$ .

Figure 1: Equilibrium thresholds when  $c = 0.1$

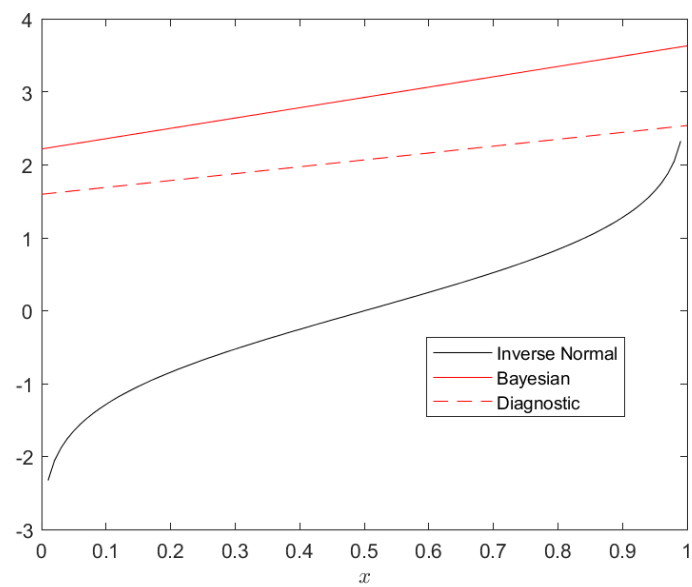


Figure 2: Equilibrium thresholds when  $c = 0.6$

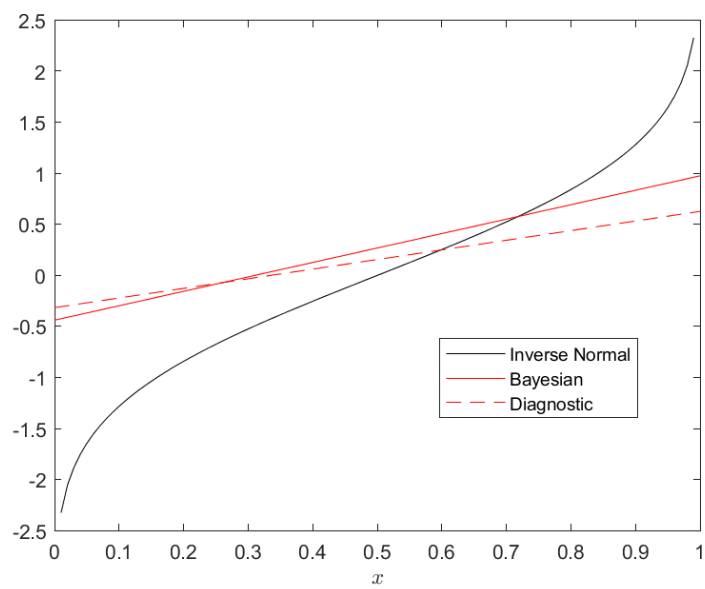


Figure 3: Equilibrium thresholds when  $c = 0.9$

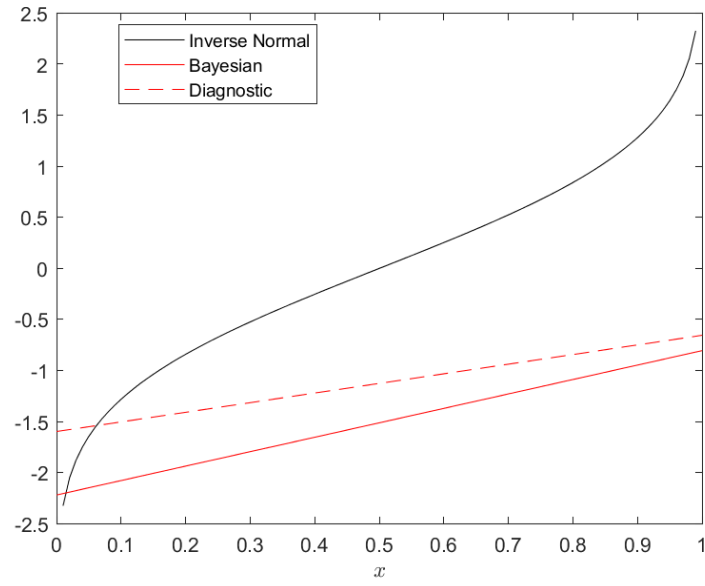
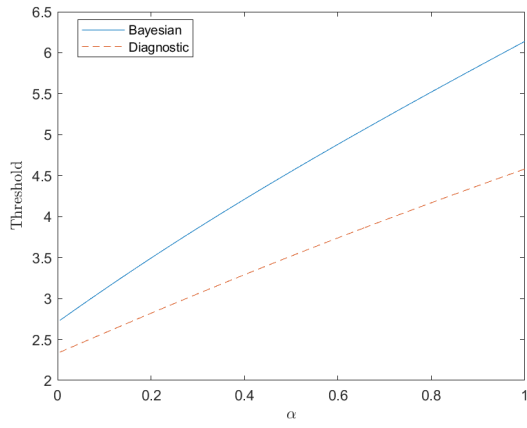
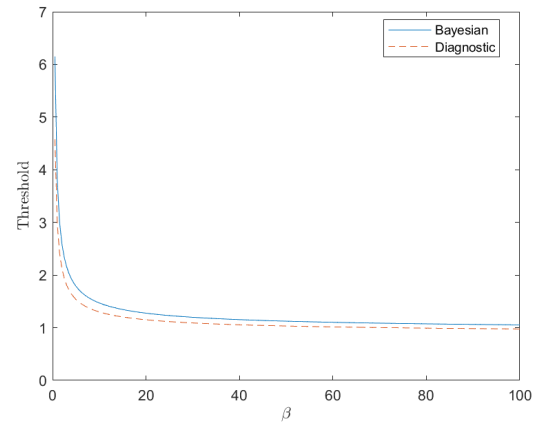


Figure 4: Sensitivity analysis when  $c = 0.1$



(a)  $\alpha$



(b)  $\beta$

Figure 5: Sensitivity analysis when  $c = 0.6$

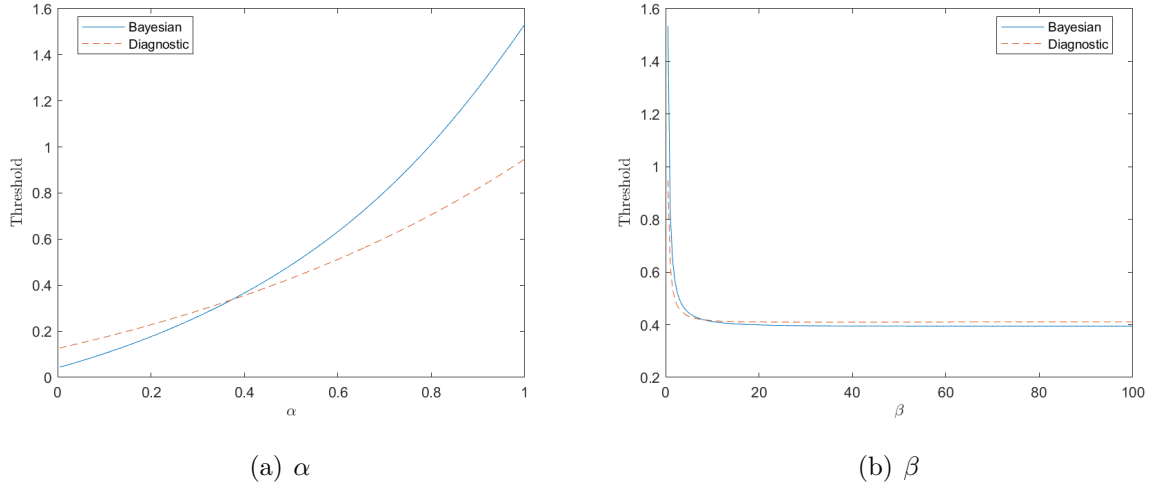
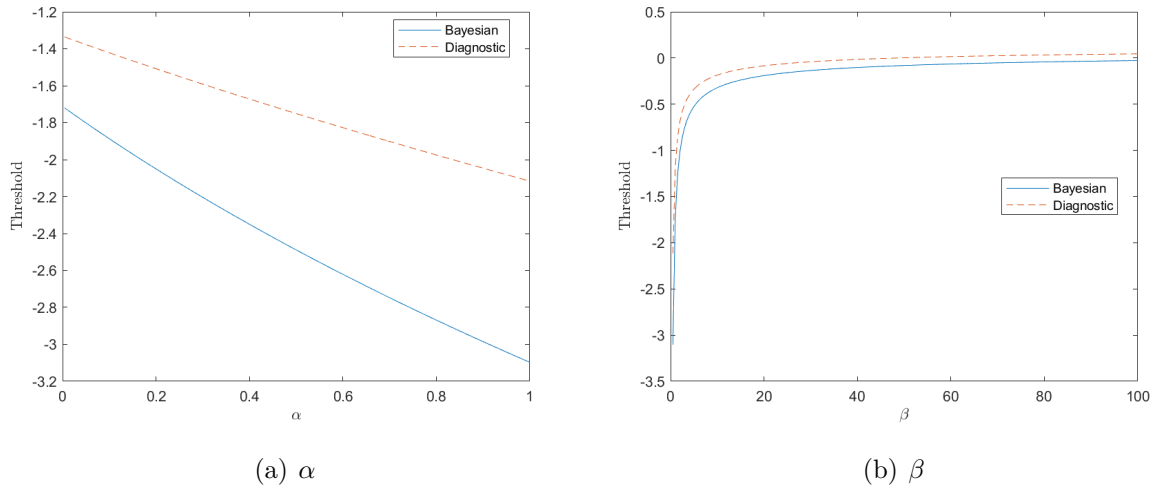


Figure 6: Sensitivity analysis when  $c = 0.9$



## References

- [1] Bordalo, P., Gennaioli, N., Ma, Y., and Shleifer, A. (2020). Overreaction in Macroeconomic Expectations. *American Economic Review*, 110(9), 2748-82.