

# **SEM1000 ULTRASONIC WEATHER STATION**



# **Instruction Manual**

V.220701R



## 1.Product description

SEM1000 small integrated weather station can be widely used in environmental detection, integrating wind speed, wind direction, temperature and humidity, noise collection, PM2.5 and PM10, atmospheric pressure, light or rainfall. The equipment adopts standard MODBUS-RTU communication protocol and RS485 signal. Output, the communication distance is up to 2000 meters, and the data can be uploaded to the customer's monitoring software or PLC configuration screen through 485 communication, and it also supports secondary development.

With the built-in electronic compass selection device, there is no longer a position requirement during installation, just ensure that it is installed horizontally. It is suitable for use in mobile occasions such as marine ships, automobile transportation, etc., and there is no direction requirement during installation.

This product is widely used in various occasions that need to measure environmental temperature and humidity, noise, air quality, atmospheric pressure, light or rainfall, etc. It is safe and reliable, beautiful in appearance, easy to install, and durable.

#### 2. Features

SEM1000is small in size, light in weight, made of high-quality anti-ultraviolet materials, long service life, high-sensitivity probe, stable signal and high precision. The key components adopt imported components, which are stable and reliable, and have the characteristics of wide measurement range, good linearity, good waterproof performance, convenient use, easy installation, and long transmission distance.

- It adopts the integrated design of multiple collection devices and is easy to install.
- The wind speed and direction are measured by the principle of ultrasonic wave, and there is no angle limit, 360° omni-directional, and the data of wind speed and wind direction can be obtained at the same time.
- Noise collection, accurate measurement, the range is as high as 30dB~120dB.
- PM2.5 and PM10 are collected at the same time, range: 0-1000ug/m3, resolution 1ug/m3, unique dual-frequency data collection and automatic calibration technology, the consistency can reach ±10%.
- Measure the environmental temperature and humidity, the measuring unit is imported from Switzerland, and the measurement is accurate.
- Wide range of 0-120Kpa air pressure range, applicable to various altitudes.
- Using dedicated 485 circuit, stable communication
- For devices with built-in electronic compass, there is no direction requirement during installation, and it can be installed horizontally.

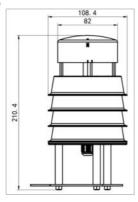
# 3. The main parameters

DC power supply (default)	10-30VDC	
Maximum power consumption	RS485 output	0.7W
	Wind speed	±0.5+2%FS
	Wind direction	±3°
	Humidity	±3%RH(60%RH,25°C)
Precision	Temperature	±0.5°C (25°C)
	Atmospheric pressure	±0.15Kpa@25°C 75Kpa
	noise	±3db
	PM10 PM2.5	±10% (25°C)



	Light intensity	±7%(25℃)	
	Wind speed	0~40m/s, starting wind speed 0.5m/s	
	Wind direction	0~359°	
	Humidity	0%RH~99%RH	
Dongo	Temperature	-40℃~+80℃	
Range	Atmospheric pressure	0-120Kpa	
	Noise	30dB~120dB	
	PM10 PM2.5	0-1000ug/m3	
	Light intensity	0~200,000 Lux	
	Temperature	≤0.1°C/y	
	Humidity	≤1%/y	
Long-term stability	Atmospheric pressure	-0.1Kpa/y	
Long-term stability	Noise	≤3db/y	
	PM10 PM2.5	≤1%/y	
	Light intensity	≤5%/y	
	Wind speed	1S	
	Wind direction	1S	
	Temperature and humidity	≤1s	
Response time	Atmospheric pressure	≤1s	
	Noise	≤1s	
	PM10 PM2.5	≤90S	
	Light intensity	≤0.1s	
	Precision	±5%	
Outing I waitefull to a warm at a wa	Resolution	0.1mm	
Optical rainfall parameters	Max. instantaneous rainfall	24mm/min	
	Sense of rain diameter	6cm	
Protection level	IP54		
Output signal	RS485 (standard Modbus communication protocol)		

# 4. Shell size

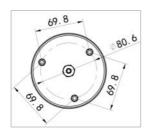


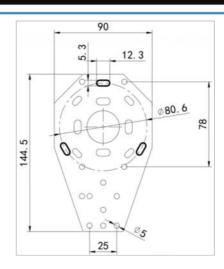
253. 10 Ø108

Equipment size drawing (unit: mm)

Dimensional drawing with optical rainfall element (unit: mm)







Dimensional drawing of equipment bottom shell and mounting bracket (unit: mm)

# 5. Equipment installation instructions

## 5.1. Inspection before equipment installation

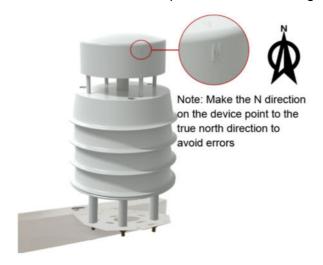
**Equipment List:** 

- One integrated weather station equipment
- Certificate of conformity
- 1 70cm waterproof plug-in male head, 1 white holder, 2 M4\*10 screws and nuts, 3 M5 nuts

#### 5.2. Installation method

# Beam installation (optional):

The installation of devices without electronic compass is shown in the figure below:



# 5.3. Sensor wiring

DC power supply 10-30V power supply. When wiring the 485 signal line, pay attention to the two lines A/B not to be reversed, and the addresses of multiple devices on the bus must not conflict.

	Thread color	Description
Power cupply	Brown	Positive power supply (10-30V DC)
Power supply	Black	Power negative
Communication	Green	485-A
Communication	Blue	485-B



#### 5.4. 485 field wiring instructions

When multiple 485 devices are connected to the same bus, there are certain requirements for field wiring. For details, please refer to the "485 Device Field Wiring Manual" in the information package.

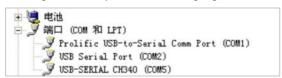
#### 6. Configuration software installation and use

#### 6.1. Software selection

Open the data package, select "Debugging Software" --- "485 Parameter Configuration Software", find "485 Parameter Configuration Tool" and open it.

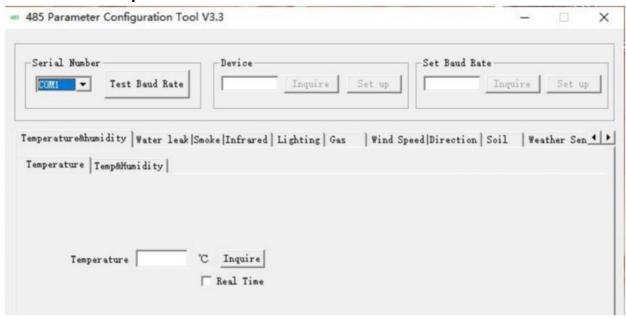
#### 6.2. Parameter setting

①. Select the correct COM port (check the COM port in "My Computer—Properties—Device Manager—Port"). The following figure lists the driver names of several different 485 converters.



- 2 Connect only one device alone and power it on, click the test baud rate of the software, the software will test the baud rate and address of the current device, the default baud rate is 4800bit/s, and the default address is 0x01.
- ③. Modify the address and baud rate according to the needs of use, and at the same time, you can query the current function status of the device.
- 4. If the test is unsuccessful, please recheck the equipment wiring and 485 driver installation.

## 7. Communication protocol



#### 7.1. Basic communication parameters

Code	8-bit binary
Data bit	8-bit
Parity bit	no
Stop bit	1 bit
Error checking	CRC (Redundant Cyclic Code)
Baud rate	2400bit/s, 4800bit/s, 9600 bit/s can be set, the factory default is 4800bit/s



#### 7.2. Data frame format definition

Using Modbus-RTU communication protocol, the format is as follows:

Initial structure ≥ 4 bytes of time

Address code = 1 byte

Function code = 1 byte

Data area = N bytes

Error check = 16-bit CRC code

Time to end structure ≥ 4 bytes

Address code: the address of the transmitter, which is unique in the communication network

(factory default 0x01).

Function code: The command function instruction issued by the host, this transmitter only

uses function code 0x03 (read register data).

Data area: The data area is the specific communication data, pay attention to the high byte

of the 16bits data first!

CRC code: two-byte check code.

Host query frame structure:

Address code	Function code	Register start address	Register length	Check code low	Check code high
1 byte	1 byte	2 byte	2 byte	1 byte	1 byte

## Slave machine response frame structure:

Address	Function	Number of	Data	Data	N data	Check	Check
code	code	valid bytes	area 1	area 2	area	code low	code high
1 byte	1 byte	1 byte	2 byte	2 byte	2 byte	1 byte	1 byte

## 7.3. Register address

The contents of the register are shown in the following table (support 03/04 function code):

Register address	PLC or configurati on address	Content	Operating	Definition description		
500	40501	Wind speed value	Read only	100 times the actual value		
				Actual value		
501	1 40502	Wind force	Read only	(The wind level value corresponding to		
				the current wind speed)		
		Wind direction (0-7 files)	40503   ` Read only		Actual value (the direction of true north	
502	40503			40503   ` Read only	Read only	is 0, the value is increased clockwise,
					and the value of true east is 2)	
				Actual value (the direction of true north		
503	40504	Wind direction	Read only	is 0° and the degree increases		
303	40304	(0-360°)	Tread Offig	clockwise, and the direction of true east		
				is 90°)		
504	40505	Humidity value	Read only	10 times the actual value		
505	40506	Temperature value	Read only	10 times the actual value		
506	40507	Noise value	Read only	10 times the actual value		



			_	
507	40508	PM2.5 value (if CO2 type device is selected, this register is CO2 value)	Read only	Actual value
508	40509	PM10 value (if CO2 type equipment is selected, this register is empty)	Read only	Actual value
509	40510	Atmospheric pressure value (unit Kpa,)	value (unit Read only 10 times the actu	
510	40511	High 16-bit value of Lux value of 20W	Read only	Actual value
511	40512	Low 16-bit value of Lux value of 20W	Read only	Actual value
512	40513	20W light value (unit: hundred lux)	Read only	Actual value
513	40514	Optical rainfall rainfall value (unit: mm)	Read only	10 times the actual value

Calibration register

Register address	Content	Definition description	
6000 H	Small ultrasonic wind direction	0 means normal direction	
6000 П	offset register	1 means the direction is offset by 180°	
6001 H	Small ultrasonic wind speed	Write 0xAA, wait for 10s, and set the device to	
6001 H	zero register	zero	
6002 H	Optical Rainfall Zeroing	Write 0x5A, set the rainfall value to zero	
0002 H	Register		

# 7.4. Communication protocol example and explanation

# 7.4.1.Example: Read the real-time wind speed value of the transmitter device (address 0x01)

Interrogation frame

Address	Function code	Initial	Data longth	Check code	Check code
code		address	Data length	low byte	high byte
0x01	0x03	0x01 0xF4	0x00 0x01	0x C4	0x04

# Reply frame

Address code	Address code	Function	Returns the number	Wind speed	Check code	Check code
	code	of valid bytes	value	low byte	high byte	
	0x01	0x03	0x02	0x00 0x7D	0x78	0x65

Real-time wind speed calculation:

Wind speed: 007D (hexadecimal) = 125 => wind speed = 1.25 m/s



# 7.4.2. Example: Read the wind direction value of the transmitter device (address 0x01)

#### Interrogation frame

Address code	Function	Initial	Data length	Check code low	Check code
Address code	code	address	Data length	byte	high byte
0x01	0x03	0x01 0xF6	0x00 0x01	0x65	0xC4

#### Reply frame

Address	Function Returns the number		Wind direction	Check code	Check code
code	code	of valid bytes	value	low byte	high byte
0x01	0x03	0x02	0x00 0x02	0x39	0x85

Wind direction calculation:

Wind direction: 0002 (hexadecimal) = 2 => wind direction = east wind

# 7.4.3. Example: Read the temperature and humidity value of the transmitter device (address 0x01) Interrogation frame

Address	Function code	Initial address	Data length	Check code	Check code h
code	Function code	ililiai address		low byte	igh byte
0x01	0x03	0x01 0xF8	0x00 0x02	0x44	0x06

Response frame (for example, the temperature is -10.1 °C and the humidity is 65.8%RH)

Address	Function	Number of	Humidity	Temperature	Check code	Check code
code	code	valid bytes	value	value	low byte	high byte
0x01	0x03	0x04	0x02 0x92	0xFF 0x9B	0x5A	0x3D

Temperature: upload in the form of complement code when the temperature is lower than 0°C

0xFF9B (hexadecimal) = -101 => temperature = -10.1°C

**Humidity:** 

0x0292 (hexadecimal) = 658 => humidity = 65.8%RH

## 8. Common problems and solutions

The device cannot connect to the PLC or computer

Possible reasons:

- 1) The computer has multiple COM ports, and the selected port is incorrect.
- 2) The device address is wrong, or there are devices with duplicate addresses (the factory defaults are all 1).
- 3) The baud rate, check method, data bit, stop bit are wrong.
- 4) The host polling interval and waiting response time are too short, and both need to be set above 200ms.
- 5) The 485 bus is disconnected, or the A and B wires are connected reversely.
- 6) If the number of equipment is too much or the wiring is too long, power supply should be nearby, add 485 booster, and add  $120\Omega$  terminal resistance at the same time.
- 7) The USB to 485 driver is not installed or damaged.
- 8) The equipment is damaged.