마이크로프로세서응용 <16조, preliminary>

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1. LDPC

1) 동작사진

```
kLDPC decoder>
Measured Accuracy : MSR(dB) = -inf
     -Benchmarking Start-
Case O: LDPC Reference
                                                 Fltr Avg, Fltr Avg(Hs)
41791519, 125.375
             Мах,
                          Hin,
                                    Average,
       41797121,
                     41785203,
                                   41791376,
 ase 1: LDPC Optimization
                                                 Fltr Avg, Fltr_Avg(ms)
                                    Average,
                           Hin,
             Мах,
                     18784948,
                                   18791062,
                                                 18790792,
       18797985,
   -Benchmarking Complete-
Optimized LDPC Decoder is x2.22 faster than Reference
```

2) 적용 아이디어 설명

Loop Optimization 적용

- For loop 합쳐서 For loop 최소한으로 동작하도록 유도
- For loop 순서 바꿔서 여러 개 For loop 한번에 동작하도록 유도

Cache Optimize 적용

- 동일한 matrix 연속해서 접근 가능하도록 코드의 순서 변경

3) 보완방향

Tiling 적용

H matrix 접근을 한번에 통일하여 동작하도록 유도

최소합 알고리즘, LLR-SPA 알고리즘 적용

2. QRD

1) 동작사진

```
COM6 - Tera Term VT
                                                                                                              X
                                                                                                 메뉴(F) 수정(E) 설정(S) 제어(O) 창(W) 도움말(H)
Measured Accuracy : MSR(dB) = -57.682
     --Benchmarking Start-----
Case D: QRD Reference
       Hax,
19749149,
                                               Average,
19747104,
                                                                 Fltr Avg, Fltr_Avg(ms)
19747080, 59.241
                                   Hin,
                            19745246,
 Case 1: QRD Optimization
                                                                 Fltr Avg, Fltr_Avg(ms)
14441123, 43.323
Nr, Hax, Mir
10, 14443394, 14439117
----Benchmarking Complete---
                                               Average,
14441149,
                            14439117,
Optimized FFT is x1.37 faster than Reference
 <QR-Decomposition>
No. of Tx Antennas: 8
No. of Rx Antennas: 8
No. of subcarriers : 1960
Measured Accuracy : NSR(dB) = -57.682
----Benchmarking Start----
Case O: QRD Reference
Nr, Hax, Hin
10, 19747862, 19742055
Case 1: QRD Optimization
                                               Average,
19746014,
Nr,
10,
                                                                 Fltr Avg, Fltr_Avg(ms)
19746278, 59.239
                            19742055,
                                                                 Fltr Avg, Fltr_Avg(ms)
14435830, 43.307
Mr, Мах, Міл
10, 14437062, 14433660
----Benchmarking Сомрlete---
                                               Average,
14435736,
                           14433660,
Optimized FFT is <u>x1.37</u> faster than Reference
```

2) 적용 아이디어 설명

> Loop Unrolling

> Dave Eberly's fast inverse square root algorithm

```
// invert sqrt
// Dave Eberly's FastinverseSqrt Algorithm

tmp_i = sq;
fHalf = 0.5f * sq;
t = *(int*)&sq;
t = 0x5f3759df - (t >> 1);
sq = *(float*)&t;
sq = sq*(1.5f - fHalf*sq*sq);

tmp_r = sq * tmp_i; // tmp_r = fastSqrt(sq);
```

- 기존의 <math.h> 의 sqrt 함수보다 더 빠른 fast inverse square root 알고리즘을 적용시켰다.

> Frequency reduction(Temporary Variables)

```
// Normalization Column - Temporary variable
R[i * NTX * NTX + j * NTX + j].real = tmp_r;
for(k = 0; k < NRX; k++)
{
    Q[i * NTX * NRX + k * NTX + j].real /= tmp_r;
    Q[i * NTX * NRX + k * NTX + j].img /= tmp_r;
}</pre>
```

- 루프 내에서 변수화 시킬 수 있는 것을 찾아, 변수화 시켜주었다.

> Frequency Reduction(Temporary Variables), Loop unrolling, Loop order change

```
Update Column - Temporary variable & loop order change
for(l = 0; l < NRX; l++)</pre>
   tmp_r = Q[i * NTX * NRX + l * NTX + j].real;
                                                // Frequency Reduction
   tmp_i = Q[i * NTX * NRX + l * NTX + j].img;
   for(k = (j + 1); k < 7; k+=2)
                                      // loop unrolling
       Q[i * NTX * NRX + l * NTX + k].real = Q[i * NTX * NRX + l * NTX + k].real
                                             -(R[i*NTX*NTX+j*NTX+k].real*tmp_r
                                             - R[i * NTX * NTX + j * NTX + k].img * tmp_i);
       Q[i * NTX * NRX + l * NTX + k].img = Q[i * NTX * NRX + l * NTX + k].img
                          - (R[i * NTX * NTX + j * NTX + k].real * tmp_i
                                  + R[i * NTX * NTX + j * NTX + k].img * tmp_r);
       Q[i * NTX * NRX + l * NTX + (k+1)].real = Q[i * NTX * NRX + l * NTX + (k+1)].real
                          -(R[i*NTX*NTX+j*NTX+(k+1)].real*tmp_r
                                  -R[i*NTX*NTX+j*NTX+(k+1)].img*tmp_i);
       Q[i*NTX*NRX+l*NTX+(k+1)].img = Q[i*NTX*NRX+l*NTX+(k+1)].img
                          - (R[i * NTX * NTX + j * NTX + (k+1)].real * tmp_i
                                  + R[i * NTX * NTX + j * NTX + (k+1)].img * tmp_r);
   if(i % 2 == 0){
                           // if((8-(j+1)) % 2 == 1)
       Q[i * NTX * NRX + l * NTX + 7].real = Q[i * NTX * NRX + l * NTX + 7].real
                                          - (R[i * NTX * NTX + j * NTX + 7].real * tmp_r
                                         - R[i * NTX * NTX + j * NTX + 7].img * tmp_i);
       Q[i * NTX * NRX + l * NTX + 7].img = Q[i * NTX * NRX + l * NTX + 7].img
                                         - (R[i * NTX * NTX + j * NTX + 7].real * tmp_i
                                          + R[i * NTX * NTX + j * NTX + 7].img * tmp_r);
```

- 여러가지 loop optimization을 적용시켰다.

> Loop Tiling

```
#ifndef min

#define min(a,b) (((a) < (b)) ? (a) : (b))

#endif
```

- loop tiling을 위해, min(a,b)를 define 해주었다.
- tile size는 8로 설정하여 loop tiling을 진행했다.