## ECE586/AI586 Applied Matrix Analysis - Homework 3

Winter 2024 Instructor: Xiao Fu

School of Electrical Engineering and Computer Science Oregon State University

March 7, 2025

# Woonki Kim kimwoon@oregonstate.edu

Q1. (The Eckart-Young Theorem) Given a matrix  $\mathbf{A} \in \mathbb{R}^{m \times n}$  and the full SVD  $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$ . Define  $\mathbf{A}_k = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^T$ . Assume that  $k \leq \operatorname{rank}(\mathbf{A}) = r$ . Show that

$$\mathbf{A}_k = \arg\min_{\mathbf{B}: \operatorname{rank}(\mathbf{B}) \le k} \|\mathbf{A} - \mathbf{B}\|_F.$$

(Hint: Do not use Weyl's inequality directly; if you want to use it, prove it first.) (25%)

#### A1.

Any matrix  $\mathbf{M} \in \mathbb{R}^{m \times n}$  can be written as:

$$M = U\Sigma V^T$$

where  $\mathbf{U}$  and  $\mathbf{V}$  is orthogonal.

Let r be the number of nonzero singular values:

$$\sigma_1 > \dots \sigma_r > 0, \quad \sigma_{r+1} = \dots = 0$$

Then:

$$\mathbf{M} = \begin{bmatrix} \mathbf{U_1} & \mathbf{U_2} \end{bmatrix} \begin{bmatrix} \tilde{\boldsymbol{\Sigma}} & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \mathbf{V_1}^T \\ \mathbf{V_2}^T \end{bmatrix}$$

where

$$\tilde{\Sigma} = \mathrm{Diag}(\sigma_1, \cdots, \sigma_r)$$

$$\mathbf{U}_1 = \begin{bmatrix} \mathbf{u}_1, \dots, \mathbf{u}_r \end{bmatrix} \in \mathbb{R}^{m \times r}, \quad \mathbf{U}_2 = \begin{bmatrix} \mathbf{u}_{r+1}, \dots, \mathbf{u}_m \end{bmatrix} \in \mathbb{R}^{m \times (m-r)}$$

Thus:

$$\mathbf{M} = \mathbf{U}_1 \tilde{\boldsymbol{\Sigma}} \mathbf{V_1}^T$$

Writing in outerproduct form:

$$\mathbf{M} = \sum_{i}^{r} \sigma_{i} \mathbf{u_{i}} \mathbf{v_{i}}^{T}$$

$$\mathbf{V}_1 = \begin{bmatrix} \mathbf{v}_1, \dots, \mathbf{v}_r \end{bmatrix} \in \mathbb{R}^{n \times r}, \quad \mathbf{V}_2 = \begin{bmatrix} \mathbf{v}_{r+1}, \dots, \mathbf{v}_n \end{bmatrix} \in \mathbb{R}^{n \times (n-r)}$$

Since  $rank(\mathbf{B}) = (number of nonzero singular values)$ , any matrix  $\mathbf{B}$  with rank at most k can be written as:

$$\mathbf{B} = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^T,$$

To discriminate from the formula of **A**, let **B**:

$$\mathbf{B} = \sum_{i=1}^k \lambda_i \mathbf{x}_i \mathbf{y}_i^T$$

where,  $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_k \geq 0$  are singular values of **B**,  $\mathbf{x}_i$  and  $\mathbf{y}_i$  are orthonormal left and right singular vectors.

Using thin SVD form, the optimization problem can be reformulated as:

$$\arg\min_{\mathbf{B}: \operatorname{rank}(\mathbf{B}) \le k} \|\mathbf{A} - \mathbf{B}\|_F.$$

$$=\arg\min_{\sum_{i=1}^k \lambda_i \mathbf{x}_i \mathbf{y}_i^T} \| \left( \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T \right) - \left( \sum_{i=1}^k \lambda_i \mathbf{x}_i \mathbf{y}_i^T \right) \|_F$$

Optimization problem's solution is invariant to square, thus squaring:

$$\arg\min_{\sum_{i=1}^k \lambda_i \mathbf{x}_i \mathbf{y}_i^T} \| \left( \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T \right) - \left( \sum_{i=1}^k \lambda_i \mathbf{x}_i \mathbf{y}_i^T \right) \|_F^2$$

Looking at the objective function:

$$\| \left( \sum_{i=1}^{r} \sigma_{i} \mathbf{u}_{i} \mathbf{v}_{i}^{T} \right) - \left( \sum_{i=1}^{k} \lambda_{i} \mathbf{x}_{i} \mathbf{y}_{i}^{T} \right) \|_{F}^{2}$$

$$= \operatorname{Tr} \left( \left( \sum_{i=1}^{r} \sigma_{i} \mathbf{u}_{i} \mathbf{v}_{i}^{T} - \sum_{i=1}^{k} \lambda_{i} \mathbf{x}_{i} \mathbf{y}_{i}^{T} \right)^{T} \left( \sum_{i=1}^{r} \sigma_{i} \mathbf{u}_{i} \mathbf{v}_{i}^{T} - \sum_{i=1}^{k} \lambda_{i} \mathbf{x}_{i} \mathbf{y}_{i}^{T} \right) \right).$$

Expanding further:

$$= \operatorname{Tr}\left(\left(\sum_{i=1}^{r} \sigma_{i} \mathbf{u}_{i} \mathbf{v}_{i}^{T}\right)^{T} \left(\sum_{j=1}^{r} \sigma_{j} \mathbf{u}_{j} \mathbf{v}_{j}^{T}\right)\right)$$
$$-2 \operatorname{Tr}\left(\left(\sum_{i=1}^{r} \sigma_{i} \mathbf{u}_{i} \mathbf{v}_{i}^{T}\right)^{T} \left(\sum_{j=1}^{k} \lambda_{j} \mathbf{x}_{j} \mathbf{y}_{j}^{T}\right)\right)$$
$$+ \operatorname{Tr}\left(\left(\sum_{i=1}^{k} \lambda_{i} \mathbf{x}_{i} \mathbf{y}_{i}^{T}\right)^{T} \left(\sum_{j=1}^{k} \lambda_{j} \mathbf{x}_{j} \mathbf{y}_{j}^{T}\right)\right).$$

• First term:

$$\operatorname{Tr}\left(\sum_{i=1}^{r}\sum_{j=1}^{r}\sigma_{i}\sigma_{j}(\mathbf{u}_{i}\mathbf{v}_{i}^{T})^{T}(\mathbf{u}_{j}\mathbf{v}_{j}^{T})\right).$$

Since  $\mathbf{u}_i$  and  $\mathbf{v}_i$  are orthonormal vectors:

$$\sum_{i=1}^{r} \sigma_i^2.$$

• Second term:

$$-2\operatorname{Tr}\left(\sum_{i=1}^{r}\sum_{j=1}^{k}\sigma_{i}\lambda_{j}(\mathbf{u}_{i}\mathbf{v}_{i}^{T})^{T}(\mathbf{x}_{j}\mathbf{y}_{j}^{T})\right).$$

• Third term:

$$\operatorname{Tr}\left(\sum_{i=1}^k \sum_{j=1}^k \lambda_i \lambda_j (\mathbf{x}_i \mathbf{y}_i^T)^T (\mathbf{x}_j \mathbf{y}_j^T)\right).$$

Since  $\mathbf{x}_i$  and  $\mathbf{y}_i$  are orthonormal vectors:

$$\sum_{i=1}^{k} \lambda_i^2.$$

Thus:

$$\|\mathbf{A} - \mathbf{B}\|_F^2 = \sum_{i=1}^r \sigma_i^2 - 2\sum_{i=1}^k \sigma_i \lambda_i \langle \mathbf{x}_i, \mathbf{u}_i \rangle \langle \mathbf{y}_i, \mathbf{v}_i \rangle + \sum_{i=1}^k \lambda_i^2.$$

To minimize this expression, second term should be as large as possible. The second term in the equation,

$$-2\sum_{i=1}^k \sigma_i \lambda_i \langle \mathbf{x}_i, \mathbf{u}_i \rangle \langle \mathbf{y}_i, \mathbf{v}_i \rangle,$$

Since  $\mathbf{u}_i$  and  $\mathbf{v}_i, \mathbf{x}_i$  and  $\mathbf{y}_i$  are orthonormal, thus unit vectors. Thus by Cauchy-Schwarz inequality:

$$|\langle \mathbf{x}_i, \mathbf{u}_i \rangle| \leq 1.$$

$$|\langle \mathbf{y}_i, \mathbf{v}_i \rangle| \leq 1,$$

where equality holds when:

$$\mathbf{x}_i = \mathbf{u}_i, \quad \mathbf{y}_i = \mathbf{v}_i.$$

Substituting these into the equation:

$$\|\mathbf{A} - \mathbf{B}\|_F^2 = \sum_{i=1}^r \sigma_i^2 - 2\sum_{i=1}^k \sigma_i \lambda_i + \sum_{i=1}^k \lambda_i^2.$$

Dividing sigma term:

$$\sum_{i=k+1}^{r} \sigma_i^2 + \sum_{i=1}^{k} \sigma_i^2 - 2\sum_{i=1}^{k} \sigma_i \lambda_i + \sum_{i=1}^{k} \lambda_i^2.$$

Integrating summation over i to k:

$$\sum_{i=k+1}^{r} \sigma_i^2 + \sum_{i=1}^{k} (\sigma_i^2 - 2\sigma\lambda + \lambda_i^2)$$

Expressing in square form:

$$\sum_{i=k+1}^{r} \sigma_i^2 + \sum_{i=1}^{k} (\sigma_i - \lambda_i)^2$$

Square term's minimum is obviously 0, thus it is minimum when:

$$\lambda_i = \sigma_i$$
, for  $i = 1, \dots, k$ 

Substituting this choice,

$$\|\mathbf{A} - \mathbf{B}\|_F^2 = \sum_{i=1}^r \sigma_i^2 - 2\sum_{i=1}^k \sigma_i \lambda_i + \sum_{i=1}^k \lambda_i^2.$$
$$= \sum_{i=1}^r \sigma_i^2 - 2\sum_{i=1}^k \sigma_i^2 + \sum_{i=1}^k \sigma_i^2.$$

Simplifying,

$$\|\mathbf{A} - \mathbf{B}\|_F^2 = \sum_{i=1}^r \sigma_i^2 - \sum_{i=1}^k \sigma_i^2 = \sum_{i=k+1}^r \sigma_i^2$$

Thus the optimal value for the optimization problem is:

$$\|\mathbf{A} - \mathbf{B}\|_F^2 = \sum_{i=k+1}^r \sigma_i^2.$$

Recall that frobenius norm could be expressed in summation form of  $\sigma$ :

$$||\mathbf{X}||_F^2 = ||\mathbf{U}\mathbf{\Sigma}\mathbf{V}^T||_F^2$$

Since frobenius norm is invariant in orthogonal transformation(It just rotates):

$$||\mathbf{X}||_F^2 = ||\mathbf{U}\mathbf{\Sigma}\mathbf{V}^T||_F^2 = ||\mathbf{\Sigma}||_F^2 = \sum_i \sigma_i^2$$

And since:

$$\mathbf{A} - \mathbf{A}_k = \sum_{i=k+1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T.$$

Thus:

$$\|\mathbf{A} - \mathbf{A}_k\|_F^2 = \sum_{i=k+1}^r \sigma_i^2$$

Thus optimal value holds when:

$$\mathbf{B} = \mathbf{A}_k$$

Thus:

$$\mathbf{A}_k = \arg\min_{\mathbf{B}: \operatorname{rank}(\mathbf{B}) \le k} \|\mathbf{A} - \mathbf{B}\|_F.$$

**Q2.** (The Eckart-Young Theorem) Given a matrix  $\mathbf{A} \in \mathbb{R}^{m \times n}$  and the full SVD  $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$ . Define  $\mathbf{A}_k = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^T$ . Assume that  $k \leq \operatorname{rank}(\mathbf{A}) = r$ . Show that

$$\mathbf{A}_k = \arg\min_{\mathbf{B}: \operatorname{rank}(\mathbf{B}) \le k} \|\mathbf{A} - \mathbf{B}\|_2.$$

Note: This is different from Q1, since the distance is measured using the matrix 2-norm here. (25%)

#### **A2**.

Since:

$$\|\mathbf{A} - \mathbf{A}_k\|_2 \le \|\mathbf{A} - \mathbf{B}\|_2$$
,  $\forall \text{ rank-}k \text{ matrices } \mathbf{B}$ .

Let  $\mathbf{B} \in \mathbb{R}^{m \times n}$  and rank $(\mathbf{B}) = k$ .

And we have proven in Homework1 that the null space  $\mathcal{N}(\mathbf{B}) \subset \mathbb{R}^n$  dimension:

$$\dim \mathcal{N}(\mathbf{B}) = n - k$$

Now, considering the  $n \times (k+1)$  matrix  $\mathbf{V}_{k+1}$ :

$$\mathbf{V}_{k+1} = [\mathbf{v}_1 \, \mathbf{v}_2 \, \dots \, \mathbf{v}_{k+1}],$$

since it has (k+1) orthonormal vectors:

$$rank(\mathbf{V_{k+1}}) = k + 1$$

While  $\mathcal{R}(\mathbf{V}_{k+1})$ , is the subspace spanned by these k+1 column vectors:

$$\mathcal{R}(\mathbf{V}_{k+1}) = \operatorname{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_{k+1}\}.$$

Since each  $\mathbf{v}_i$  is a vector in  $\mathbb{R}^n$ , their span is a subspace of  $\mathbb{R}^n$ , meaning:

$$\mathcal{R}(\mathbf{V}_{k+1}) \subset \mathbb{R}^n$$
.

Since by the property of dimension:

$$\dim S + \dim T = \dim(S + T) + \dim(S \cap T).$$

Applying this to this case:

$$\dim(\mathcal{N}(\mathbf{B}) + \mathcal{R}(\mathbf{V}_{k+1})) = \dim\mathcal{N}(\mathbf{B}) + \dim\mathcal{R}(\mathbf{V}_{k+1}) - \dim(\mathcal{N}(\mathbf{B}) \cap \mathcal{R}(\mathbf{V}_{k+1}))$$

Substituting in actual dimension:

$$\dim(\mathcal{N}(\mathbf{B}) + \mathcal{R}(\mathbf{V}_{k+1})) = (n-k) + (k+1) - \dim(\mathcal{N}(\mathbf{B}) \cap \mathcal{R}(\mathbf{V}_{k+1}))$$
$$= (n+1) - \dim(\mathcal{N}(\mathbf{B}) \cap \mathcal{R}(\mathbf{V}_{k+1}))$$

Moving all to left side:

$$\dim(\mathcal{N}(\mathbf{B}) + \mathcal{R}(\mathbf{V}_{k+1})) - (n+1) + \dim(\mathcal{N}(\mathbf{B}) \cap \mathcal{R}(\mathbf{V}_{k+1})) = 0$$

Since  $\mathcal{N}(\mathbf{B}) + \mathcal{R}(\mathbf{V}_{k+1})$  is at most *n*-dimensional (both are a subspace of  $\mathbb{R}^n$ ):

$$\dim(\mathcal{N}(\mathbf{B}) + \mathcal{R}(\mathbf{V}_{k+1})) \le n$$

Substitute in the inequality to equality:

$$n - (n+1) + \dim(\mathcal{N}(\mathbf{B}) \cap \mathcal{R}(\mathbf{V}_{k+1})) \ge 0$$

Thus:

$$\dim(\mathcal{N}(\mathbf{B}) \cap \mathcal{R}(\mathbf{V}_{k+1})) \ge 1$$

Which means that  $\mathcal{N}(\mathbf{B})$  and  $\mathcal{R}(\mathbf{V}_{k+1})$  must have a nontrivial intersection:

$$\mathcal{N}(\mathbf{B}) \cap \mathcal{R}(\mathbf{V}_{k+1}) \neq \{0\}.$$

Since the intersection  $\mathcal{N}(\mathbf{B}) \cap \mathcal{R}(\mathbf{V}_{k+1})$  is nontrivial, there exists at least one nonzero vector  $\mathbf{w}$  in this intersection:

$$\mathbf{w} \in \mathcal{N}(\mathbf{B}) \cap \mathcal{R}(\mathbf{V}_{k+1}),$$

which means:

- $\mathbf{w}$  is in the null space of  $\mathbf{B}$  thus,  $\mathbf{B}\mathbf{w} = \mathbf{0}$
- w is also in the range space of  $V_{k+1}$ , so it can be written as a linear combination of the columns of  $V_{k+1}$

Since this subspace contains nonzero vectors, we can always normalize  $\mathbf{w}$  so that  $\|\mathbf{w}\|_2 = 1$ , meaning there exists a unit vector in this intersection. Since  $\mathbf{w} \in \mathcal{R}(\mathbf{V}_{k+1})$ :

$$\mathbf{w} = \sum_{i=1}^{k+1} w_i \mathbf{v}_i,$$

where the  $\mathbf{w}$ :

$$\sum_{i=1}^{k+1} w_i^2 = 1.$$

By the definition of the matrix norm:

$$\|\mathbf{M}\|_p = \max_{\|\mathbf{x}\|_p \le 1} \|\mathbf{M}\mathbf{x}\|_p$$

Thus 2-norm satisfies:

$$\|\mathbf{M}\|_2 = \max_{\|\mathbf{x}\|_2 \le 1} \|\mathbf{M}\mathbf{x}\|_2$$

expressing with inequality:

$$\|\mathbf{M}\|_2 \ge \|\mathbf{M}\mathbf{x}\|_2$$

Since squaring does not change inequality:

$$\|\mathbf{M}\|_{2}^{2} \geq \|\mathbf{M}\mathbf{x}\|_{2}^{2}$$

Substituting in A - B and w(since w is unit vector):

$$\|\mathbf{A} - \mathbf{B}\|_{2}^{2} \ge \|(\mathbf{A} - \mathbf{B})\mathbf{w}\|_{2}^{2}$$

Since  $\mathbf{w} \in N(\mathbf{B})$ , we have  $\mathbf{B}\mathbf{w} = \mathbf{0}$ , thus:

$$\|\mathbf{A} - \mathbf{B}\|_{2}^{2} \ge \|(\mathbf{A} - \mathbf{B})\mathbf{w}\|_{2}^{2} = \|\mathbf{A}\mathbf{w}\|_{2}^{2}.$$

Using the singular value decomposition  $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$ :

$$\|\mathbf{A}\mathbf{w}\|_2^2 = (\mathbf{U}\mathbf{\Sigma}\mathbf{V}^T\mathbf{w})^T(\mathbf{U}\mathbf{\Sigma}\mathbf{V}^T\mathbf{w})$$

$$= \mathbf{w}^T \mathbf{V} \mathbf{\Sigma}^2 \mathbf{V}^T \mathbf{w} = \sum_{i=1}^{k+1} w_i v_i \sigma_i^2 v_i w_i$$

Substituting  $\mathbf{w} = \sum_{i=1}^{k+1} w_i \mathbf{v}_i$ :

$$\|\mathbf{A} - \mathbf{B}\|_{2}^{2} \ge \|\mathbf{A}\mathbf{w}\|_{2}^{2} = \sum_{i=1}^{k+1} \sigma_{i}^{2} w_{i}^{2}$$

Since  $\sigma_1 \geq \sigma_2 \geq \ldots$ :

$$\sum_{i=1}^{k+1} \sigma_i^2 w_i^2 \ge \sigma_{k+1}^2 \sum_{i=1}^{k+1} w_i^2.$$

Since  $\sum_{i=1}^{k+1} w_i^2 = 1$ :

$$\|\mathbf{A} - \mathbf{B}\|_{2}^{2} \ge \|\mathbf{A}\mathbf{w}\|_{2}^{2} \ge \sigma_{k+1}^{2}.$$

Thus:

$$\|\mathbf{A} - \mathbf{B}\|_{2}^{2} \ge \sigma_{k+1}^{2}$$
.

Finally, equality holds when  $\mathbf{B} = \mathbf{A_k}$ 

$$\|\mathbf{A} - \mathbf{A}_k\|_2^2 = \sigma_{k+1}^2.$$

Thus:

$$\mathbf{A}_k = \arg\min_{\mathbf{B}: \operatorname{rank}(\mathbf{B}) \le k} \|\mathbf{A} - \mathbf{B}\|_2$$

Q3. Consider the nonnegative matrix factorization problem:

$$X = WH^T$$
,

where  $\mathbf{W} \in \mathbb{R}^{M \times R}$  and  $\mathbf{H} \in \mathbb{R}^{N \times R}$ , with rank $(\mathbf{W}) = \operatorname{rank}(\mathbf{H}) = R$ . Assume that  $\mathbf{H} \geq 0$  and the separability condition holds for  $\mathbf{H}$ . Denote  $\mathbf{\Lambda} = \{\ell_1, \dots, \ell_R\}$  such that

$$\mathbf{H}(\mathbf{\Lambda},:) = \mathbf{I}_R.$$

(a) Assume H1 = 1 and  $H \ge 0$ . Consider the following problem:

$$\min_{\mathbf{C} \in \mathbb{R}^{N \times N}} \|\mathbf{C}\|_{\text{row} - 0}$$

s.t. 
$$\mathbf{X} = \mathbf{XC}, \quad \mathbf{C} > 0, \quad \mathbf{1}^T \mathbf{C} = \mathbf{1}^T,$$

where  $\|\mathbf{C}\|_{\text{row}=0}$  counts the number of nonzero rows of  $\mathbf{C}$ . Assume the separability condition holds for  $\mathbf{H}$ . Denote  $\mathbf{\Lambda} = \{\ell_1, \dots, \ell_R\}$  such that

$$\mathbf{H}(\mathbf{\Lambda},:) = \mathbf{I}_R$$

Denote  $C^*$  as the solution of (1) and

$$\hat{\mathbf{\Lambda}} = \operatorname{supp}(\mathbf{C}^{\star}),$$

where  $supp(\mathbf{C}^*)$  extracts the indices of the nonzero rows of  $\mathbf{C}^*$ . Show that:

$$\hat{\mathbf{W}} = \mathbf{X}(:, \hat{\boldsymbol{\Lambda}}) = \mathbf{W}\boldsymbol{\Pi},$$

(25%)

where  $\Pi$  is a permutation matrix.

(b) Assume H1 = 1 and  $H \ge 0$ . Consider the following problem:

$$\min_{\mathbf{C}} \|\mathbf{C}\|_{\infty,1}$$

subject to:

$$\mathbf{X} = \mathbf{XC}, \quad \mathbf{C} \ge 0, \quad \mathbf{1}^T \mathbf{C} = \mathbf{1}^T,$$

where,  $\|\mathbf{C}\|_{\infty,1} = \sum_{\ell=1}^{N} \|\mathbf{C}(\ell,:)\|_{\infty}$  Denote  $\mathbf{C}^{\star}$  as the solution of (2). Also assume that all the rows of  $\mathbf{H}$  are different, i.e.,  $\mathbf{H}(\ell,:) \neq \mathbf{H}(k,:)$  for all  $k \neq \ell$ . Show that:

$$\operatorname{supp}(\mathbf{C}^{\star}) = \mathbf{\Lambda},$$

where supp( $\mathbf{C}^*$ ) extracts the indices of the nonzero rows of  $\mathbf{C}^*$ . (25%)

**Remark:** The formulations in (1) and (2) offer alternative approaches for handling the separable NMF problem. Particularly, (2) is a convex optimization-based formulation, which automatically implies that there exists a polynomial-time algorithm for solving the separable NMF problem.

#### A3.

(a) Before getting into the problem check X, W and H is all non-negative:

We have

$$C \ge 0$$
,  $H \ge 0$ 

By constraint:

$$X = XC$$

we can say that X is non-negative, since C is non-negative and if X holds negative elements the equation cannot hold.

With the equation:

$$X = WH^T$$

W is also non-negative, since both X and H is non-negative.

1. First consider separability condition:

$$\mathbf{H}(\mathbf{\Lambda},:) = \mathbf{I}_R.$$

where  $\mathbf{H}(\boldsymbol{\Lambda},:) \in \mathbb{R}^{R \times R}$ 

Since we assume  $\mathbf{H} \geq 0$  and rank $(\mathbf{H}) = R$  implying N > R, we can express  $\mathbf{H}$  as:

$$\mathbf{H} = \begin{bmatrix} 1 & 0 & 0 & \cdots & * & * & * \\ 0 & 1 & 0 & \cdots & * & * & * \\ 0 & 0 & 1 & \cdots & * & * & * \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & * & * & * \end{bmatrix}$$

where  $\mathbf{H} \in \mathbb{R}^{N \times R}$  with the first R rows form the identity matrix, and the remaining rows contain nonnegative values expressed as \*.

Now consider:

$$X = WH^T$$

if we select a single column at index  $\ell_r$  from **X**, we get:

$$\mathbf{X}(:,\ell_r)$$

Which can be expressed as:

$$\mathbf{X}(:,\ell_r) = \mathbf{W}\mathbf{H}(\ell_r,:)^T.$$

where  $\mathbf{H}(\ell_r,:)^T$  represents the  $\ell_r$ -th row of  $\mathbf{H}^T$ .

Since we know that  $\mathbf{H}(\Lambda,:) = \mathbf{I}_R$ , the row at index  $\ell_r$  must be the r-th standard basis vector:

$$\mathbf{H}(\ell_r,:) = \mathbf{e}_r^T = [0, 0, \dots, 1, \dots, 0].$$

where the 1 is in the r-th position.

Thus:

$$\mathbf{H}(\ell_r,:)^T = \mathbf{e}_r \in \mathbb{R}^R.$$

And this standard basis vector  $\mathbf{e}_r$  selects the r-th column of  $\mathbf{W}$ :

$$\mathbf{We}_r = \mathbf{w}_r$$
.

where  $\mathbf{w}_r$  is the r-th column of  $\mathbf{W}$ .

Thus:

$$\mathbf{X}(:,\ell_r) = \mathbf{w}_r.$$

Thus, if we select exactly the columns indexed by  $\Lambda$ :

$$\mathbf{X}(:, \mathbf{\Lambda}) = \mathbf{W}.$$

### 2. Now consider the constraint X = XC

Substituting  $\mathbf{X} = \mathbf{W}\mathbf{H}^T$ :

$$\mathbf{W}\mathbf{H}^T = (\mathbf{W}\mathbf{H}^T)\mathbf{C}.$$

Since W is a full column rank:

$$\mathbf{W}^{\dagger}\mathbf{W}\mathbf{H}^{T} = \mathbf{W}^{\dagger}(\mathbf{W}\mathbf{H}^{T})\mathbf{C}.$$

Thus:

$$\mathbf{H}^T = \mathbf{H}^T \mathbf{C}.$$

Here by assumption:

$$\mathbf{H}(\mathbf{\Lambda},:) = \mathbf{I}_R.$$

Thus, we can write  $\mathbf{H}^T$  in block form:

$$\mathbf{H}^T = egin{bmatrix} \mathbf{I}_R \ \mathbf{H}_{ ext{other}}^T \end{bmatrix}.$$

Substitute in block form into the equation:

$$\begin{bmatrix} \mathbf{I}_R \\ \mathbf{H}_{\text{other}}^T \end{bmatrix} (\mathbf{I} - \mathbf{C}) = 0.$$

• For the First R Rows (Corresponding to  $\Lambda$ ):

$$\mathbf{I}_R(\mathbf{I} - \mathbf{C}) = 0.$$

Since  $I_R$  is an identity matrix, this forces:

$$(\mathbf{I} - \mathbf{C})(\ell, :) = 0, \quad \forall \ell \in \mathbf{\Lambda}.$$

This means that for rows indexed by  $\Lambda$ , we must have:

$$\mathbf{I} - \mathbf{C} = 0 \quad (\mathbf{C}(\ell, :) = \mathbf{I}(\ell, :)).$$

Thus, the rows indexed by  $\Lambda$  in C form an identity matrix.

• For the Other Rows:

$$\mathbf{H}_{\text{other}}^T(\mathbf{I} - \mathbf{C}) = 0.$$

which implies each row of  $\mathbf{I} - \mathbf{C} \in \mathcal{N}(\mathbf{H}_{\text{other}}^T)$ .

Since  $\mathbf{H}^T$  is full column rank R, the rows indexed by  $\Lambda$  (which form  $\mathbf{I}_R$ ) already span the row space. This means that the remaining rows in  $\mathbf{H}_{\text{other}}^T$  do not contribute to a larger row space Thus, the null space of  $\mathbf{H}_{\text{other}}^T$  is exactly the subspace spanned by the identity rows indexed by  $\Lambda$ .

Thus:

$$\mathcal{N}(\mathbf{H}_{\text{other}}^T) = \text{span}\{\text{rows of } \mathbf{I}_R\}.$$

Since the rows of  $I_R$  are already a basis, this means the basis of  $\mathcal{N}(\mathbf{H}_{\text{other}}^T)$  is given by the rows of  $I_R$ 

Since each row of  $\mathbf{I} - \mathbf{C}$  must lie in  $\mathcal{N}(\mathbf{H}_{\text{other}}^T)$ , and we just showed that  $\mathcal{N}(\mathbf{H}_{\text{other}}^T)$  is spanned by the rows of  $\mathbf{I}_R$ :

$$\mathbf{C}(k,:) = \sum_{\ell \in \Lambda} \alpha_{k\ell} \mathbf{C}(\ell,:).$$

Since  $\mathbf{C}(\ell,:) = \mathbf{I}_R$  for  $\ell \in \Lambda$ :

$$\mathbf{C}(k,:) = \sum_{\ell \in \mathbf{\Lambda}} \alpha_{k\ell} \mathbf{I}_R.$$

Thus, every remaining row of C is a linear combination of the identity rows. Since  $C(\ell,:) = I_R$  for  $\ell \in \Lambda$ :

$$\mathbf{C}(k,:) = \sum_{\ell \in \mathbf{\Lambda}} \alpha_{k\ell} \mathbf{I}_R.$$

## 3. Now showing the relationship between $\Lambda$ and $\hat{\Lambda}$

Recall  $\mathbf{C}^*$  is the solution for optimization problem and the set  $\hat{\mathbf{\Lambda}}$  is the set of indices corresponding to the nonzero rows of  $\mathbf{C}^*$ :

$$\hat{\mathbf{\Lambda}} = \operatorname{supp}(\mathbf{C}^{\star}),$$

- $\|\mathbf{C}\|_{\text{row}-0}$  counts the number of non-zero rows in  $\mathbf{C}$ . Thus minimizing this ensures that only a minimal number of rows in  $\mathbf{C}$  remain nonzero.
- And by constraint, for rows indexed by  $\Lambda$ , we must have:

$$I - C = 0$$
  $(C(\ell, :) = I(\ell, :)).$ 

which means the rows indexed by  $\Lambda$  in C form an identity matrix.

• And also by constraint, each remaining row of C (rows not in  $\Lambda$ ):

$$\mathbf{C}(k,:) = \sum_{\ell \in \Lambda} \alpha_{k\ell} \mathbf{C}(\ell,:),$$

where  $\alpha_{k\ell}$  are some coefficients.

All this conditions can be achieved by letting **C** to have the rows indexed by  $\Lambda$  in **C** to form an identity matrix, and setting all coefficient  $\alpha_{k\ell} = 0$ , making other remaining row of **C**'s element to zero.

Thus the optimal C looks like:

$$\mathbf{C}^* = \begin{bmatrix} \mathbf{H}^T \\ 0 \end{bmatrix}$$

Thus the nonzero rows of  $C^*$  are exactly  $\Lambda$ :

$$\operatorname{supp}(\mathbf{C}^{\star}) = \hat{\boldsymbol{\Lambda}} = \boldsymbol{\Lambda}.$$

#### 4.Now consider $\hat{\mathbf{W}}$

By definition,  $\hat{\mathbf{W}}$  is the matrix obtained by selecting the columns of  $\mathbf{X}$  indexed by  $\hat{\mathbf{\Lambda}}$ :

$$\hat{\mathbf{W}} = \mathbf{X}(:, \hat{\boldsymbol{\Lambda}}).$$

From 3. we proved that:

$$\hat{\mathbf{\Lambda}} = \mathbf{\Lambda}$$
.

Thus:

$$\hat{\mathbf{W}} = \mathbf{X}(:, \boldsymbol{\Lambda}).$$

From 1. we proved that:

$$\mathbf{X}(:, \mathbf{\Lambda}) = \mathbf{W}$$

Finally:

$$\hat{\mathbf{W}} = \mathbf{X}(:, \mathbf{\Lambda}) = \mathbf{W}$$

But here:

- $-\Lambda$  is a fixed set of R indices.
- $-\hat{\Lambda}$  is also a set of R indices, but they may be selected in a different order by the optimization process.

Thus even though we have identified the correct indices in  $\Lambda$ , we cannot guarantee that they appear in the same order in  $\hat{\Lambda}$ .

So we use permutation:

$$\hat{\mathbf{W}} = \mathbf{W}\mathbf{\Pi}$$
.

where  $\Pi$  is an  $R \times R$  permutation matrix, meaning it only reorders the columns of  $\mathbf{W}$ . Thus:

$$\hat{\mathbf{W}} = \mathbf{W}\mathbf{\Pi}.$$

## (b) 1. First consider the objective function

We want to minimize:

$$\|\mathbf{C}\|_{\infty,1} = \sum_{\ell=1}^{N} \|\mathbf{C}(\ell,:)\|_{\infty}.$$

Mixed norm  $\|\mathbf{C}\|_{\infty,1}$ :

$$\|\mathbf{C}\|_{\infty,1} = \sum_{\ell=1}^{N} \|\mathbf{C}(\ell,:)\|_{\infty}.$$

where:

$$\|\mathbf{C}(\ell,:)\|_{\infty} = \max_{j} \sum_{j=1}^{n} |C(\ell,j)|$$

Here:

•  $\|\mathbf{C}(\ell,:)\|_{\infty}$  takes the maximum absolute value in row  $\ell$ .

- And summing over all rows means the objective function gathers row-wise large values in **C**.
- And by minimizing this objective function, it ensures row sparsity in C, meaning that C should have as few nonzero rows as possible.

2.Now consider the constraint  $\mathbf{X} = \mathbf{XC}$  (Same as problem (a)) Substituting  $\mathbf{X} = \mathbf{W}\mathbf{H}^T$ :

$$\mathbf{W}\mathbf{H}^T = (\mathbf{W}\mathbf{H}^T)\mathbf{C}.$$

Since W is a full column rank:

$$\mathbf{W}^{\dagger}\mathbf{W}\mathbf{H}^{T} = \mathbf{W}^{\dagger}(\mathbf{W}\mathbf{H}^{T})\mathbf{C}.$$

Thus:

$$\mathbf{H}^T = \mathbf{H}^T \mathbf{C}.$$

Here by assumption, **H** satisfies the separability condition, meaning there exists an index set  $\Lambda = \{\ell_1, \dots, \ell_R\}$  such that:

$$\mathbf{H}(\mathbf{\Lambda},:) = \mathbf{I}_R.$$

Thus, we can write  $\mathbf{H}^T$  in block form as:

$$\mathbf{H}^T = egin{bmatrix} \mathbf{I}_R \ \mathbf{H}_{ ext{other}}^T \end{bmatrix}.$$

Substitute in block form into the equation:

$$\begin{bmatrix} \mathbf{I}_R \\ \mathbf{H}_{\text{other}}^T \end{bmatrix} (\mathbf{I} - \mathbf{C}) = 0.$$

• For the First R Rows (Corresponding to  $\Lambda$ ):

$$\mathbf{I}_R(\mathbf{I} - \mathbf{C}) = 0.$$

Since  $I_R$  is an identity matrix thus:

$$(\mathbf{I} - \mathbf{C})(\ell, :) = 0, \quad \forall \ell \in \Lambda.$$

This means that for rows indexed by  $\Lambda$ :

$$\mathbf{I} - \mathbf{C} = 0 \quad (\mathbf{C}(\ell, :) = \mathbf{I}(\ell, :)).$$

Thus, the rows indexed by  $\Lambda$  in C form an identity matrix.

• For the Other Rows:

$$\mathbf{H}_{\text{other}}^T(\mathbf{I} - \mathbf{C}) = 0.$$

which implies each row of  $\mathbf{I} - \mathbf{C} \in \mathcal{N}(\mathbf{H}_{\text{other}}^T)$ .

Since  $\mathbf{H}^T$  is full column rank R, the rows indexed by  $\Lambda$  (which form  $\mathbf{I}_R$ ) already span the row space. This means that the remaining rows in  $\mathbf{H}_{\text{other}}^T$  do not contribute to a larger row space Thus, the null space of  $\mathbf{H}_{\text{other}}^T$  is exactly the subspace spanned by the identity rows indexed by  $\Lambda$ .

Thus:

$$\mathcal{N}(\mathbf{H}_{\text{other}}^T) = \text{span}\{\text{rows of } \mathbf{I}_R\}.$$

Since the rows of  $I_R$  are already a basis, this means the basis of  $\mathcal{N}(\mathbf{H}_{\text{other}}^T)$  is given by the rows of  $I_R$ 

Since each row of  $\mathbf{I} - \mathbf{C}$  must lie in  $\mathcal{N}(\mathbf{H}_{\text{other}}^T)$ , and we just showed that  $\mathcal{N}(\mathbf{H}_{\text{other}}^T)$  is spanned by the rows of  $\mathbf{I}_R$ :

$$\mathbf{C}(k,:) = \sum_{\ell \in \mathbf{\Lambda}} \alpha_{k\ell} \mathbf{C}(\ell,:).$$

Since  $\mathbf{C}(\ell,:) = \mathbf{I}_R$  for  $\ell \in \Lambda$ :

$$\mathbf{C}(k,:) = \sum_{\ell \in \mathbf{\Lambda}} \alpha_{k\ell} \mathbf{I}_R.$$

Thus, every remaining row of C is a linear combination of the identity rows.

Since  $\mathbf{C}(\ell,:) = \mathbf{I}_R$  for  $\ell \in \Lambda$ :

$$\mathbf{C}(k,:) = \sum_{\ell \in \mathbf{\Lambda}} \alpha_{k\ell} \mathbf{I}_R.$$

#### 3. Now the summing up objective function and constraints

- By minimizing  $\|\mathbf{C}\|_{\infty,1}$  ensures that only a minimal number of rows in  $\mathbf{C}$  remain nonzero.
- And by constraint, for rows indexed by  $\Lambda$ :

$$\mathbf{I} - \mathbf{C} = 0 \quad (\mathbf{C}(\ell, :) = \mathbf{I}(\ell, :)).$$

which means the rows indexed by  $\Lambda$  in C form an identity matrix.

• And also by constraint, each remaining row of C (rows not in  $\Lambda$ ):

$$\mathbf{C}(k,:) = \sum_{\ell \in \mathbf{\Lambda}} \alpha_{k\ell} \mathbf{C}(\ell,:),$$

where  $\alpha_{k\ell}$  are coefficients.

This can be achieved by letting C to have the rows indexed by  $\Lambda$  in C to form an identity matrix, and setting all coefficient  $\alpha_{k\ell} = 0$ , making other remaining row of C's element to zero.

Thus the optimal  ${\bf C}$  looks like:

$$\mathbf{C}^* = \begin{bmatrix} \mathbf{H}^T \\ 0 \end{bmatrix}$$

So the nonzero rows of  $\mathbf{C}^{\star}$  are exactly  $\boldsymbol{\Lambda}$ , thus:

$$\operatorname{supp}(\mathbf{C}^{\star}) = \mathbf{\Lambda}.$$