hw1

September 13, 2024

0.0.1 Woodrow Reese

HW1

```
[1]: import numpy as np
import pandas as pd
import math
from collections import Counter
```

1 Question 4

1.1 (a)

- Fraud detection classification. Predictors: Purchase history, recipient's info, transaction suze
- Risk management classification. Predictors: credit score, debt, cash flow
- Image classification (medical) ## (b)
- My linear regression model in Question 9. Predicting MPG given car weight.
- Population change over time. Predictors: Rent, income, transportation, crime.
- Home valuation. Predictors: SqFt, land, garage, bathrooms, bedrooms. The response is the estimated value of the home given X ## (c)
- Netflix recommendation system. Recommendations are based on what other people who have watched/liked the same show as you.
- Ad targeting. An audience is targeted based on interests, age, search activity etc. Different ads can catch the eye better given a different audiences.
- Player efficiency rating based on points, points allowed, fouls, turnovers, etc. Players can be classified by their efficiency, allowing to balanced lineups throughout the game.

2 Question 6

A parametric approach relies on assumption about the population: - It follows a uniform distribution - The variance of the population is the same over each independent observation

An advantage is that the approach is simpler and generally will not overfit the training data. A disadvantage is that the model is sensitive to the assumptions made, making it inflexible and unfit to find relationships in nonlinear data.

A non-parametric approach doesn't make assumptions about the population. Random samples are used to make observations about the population.

An advantage is that the approach is not heavily affected by outliers, allowing for nonlinear data to be a good fit for these models. Variance decreases as the sample size increases and a drawback of this approach is the opposite; the variance of the model will be larger if the sample size is small.

3 Question 7

```
[2]: table = pd.read_csv('./q7Table.csv')
[2]:
        Х1
            X2
               ХЗ
                        Y
                 0
                      Red
     1
         2
             0
                 0
                      Red
     2
         0
                 3
            1
                      Red
     3
        0
                 2 Green
            1
       -1
             0
                 1 Green
     5
        1
             1
                 1
                      Red
    4 (a)
[3]: # if we were to compare to a non-origin point...
     # euclidean(p1, p2): array | object, array | object: {
       return math.sqrt((p1.x1-p2.x1)**2+(p1.x2-p2.x2)**2+(p1.x3-p2.x3)**2)
     # }
     def euclidean(x1, x2, x3):
         return math.sqrt(x1**2 + x2**2 + x3**2)
     arr = []
     for i in range(6):
         dist = euclidean(table['X1'][i], table['X2'][i], table['X3'][i])
         arr.append((i, dist))
         print(f'Obs: {i+1}, Dist: {dist}')
    Obs: 1, Dist: 3.0
    Obs: 2, Dist: 2.0
    Obs: 3, Dist: 3.1622776601683795
    Obs: 4, Dist: 2.23606797749979
    Obs: 5, Dist: 1.4142135623730951
    Obs: 6, Dist: 1.7320508075688772
[4]: prediction = []
     def knn(k):
         arr.sort(key=lambda x: x[1]) # Sort by minDist
         knn = arr[:k] # Add the k smallest distances to knn (obs: dist)
         # For each correspoinding point, add to prediction and return the points
         for i in range(len(knn)):
```

```
prediction.append(table.iloc[knn[i][0]])
return prediction

# My knn function adds duplicates to prediction before returning?
    # knn(3) is of len 4
    # knn(4) is of len 9
```

5 (b)

The prediction is (-1, 0, 1), Green because this is the point closest to the origin

6 (c)

```
[6]: knn(3)
[6]: [X1
                -1
      X2
                 0
      ХЗ
                 1
      Y
            Green
      Name: 4, dtype: object,
                -1
      Х1
      Х2
                 0
      ХЗ
                 1
            Green
      Name: 4, dtype: object,
      Х1
              1
      Х2
              1
      ХЗ
              1
      Y
            Red
      Name: 5, dtype: object,
      Х1
              2
      Х2
              0
      ХЗ
              0
      Y
            Red
      Name: 1, dtype: object]
```

The prediction is red because the majority (2/3) of neighbors are colored red.

7 (d)

Given the boundary is highly non-linear, we should expect a small K to be the best fit. Our model is not flexible given the small observation size.

8 Question 9

```
[7]: Auto = pd.read_csv('./Auto.csv')
     Auto.head()
[7]:
               cylinders
                           displacement horsepower
                                                       weight
                                                               {\tt acceleration}
                                                                              year
        18.0
                                   307.0
                                                 130
                                                         3504
                                                                        12.0
                                                                                 70
                        8
     1
       15.0
                        8
                                   350.0
                                                 165
                                                         3693
                                                                        11.5
                                                                                 70
     2 18.0
                        8
                                                 150
                                                                        11.0
                                                                                 70
                                   318.0
                                                         3436
     3 16.0
                        8
                                   304.0
                                                 150
                                                         3433
                                                                        12.0
                                                                                 70
     4 17.0
                        8
                                                                                 70
                                   302.0
                                                 140
                                                         3449
                                                                        10.5
        origin
     0
                 chevrolet chevelle malibu
              1
     1
              1
                          buick skylark 320
     2
              1
                         plymouth satellite
     3
              1
                              amc rebel sst
```

ford torino

[8]: Auto.info()

1

4

<class 'pandas.core.frame.DataFrame'>
RangeIndex: 397 entries, 0 to 396
Data columns (total 9 columns):

#	Column	Non-Null Count	Dtype
0	mpg	397 non-null	float64
1	cylinders	397 non-null	int64
2	displacement	397 non-null	float64
3	horsepower	397 non-null	object
4	weight	397 non-null	int64
5	acceleration	397 non-null	float64
6	year	397 non-null	int64
7	origin	397 non-null	int64
8	name	397 non-null	object
<pre>dtypes: float64(3), int64(4), object(2)</pre>			

memory usage: 28.0+ KB

9 (a)

Qualitative: year, origin, name, cylinders

Quantitative: mpg, displacement, hp, weight, acceleration

10 (b)

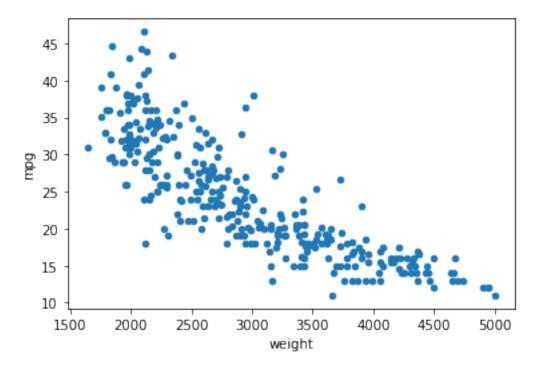
```
[9]: quantitative = []
      quantitative.append(Auto[['mpg']])
      quantitative.append(Auto[['displacement']])
      quantitative.append(Auto[['weight']])
      quantitative.append(Auto[['acceleration']])
[10]: def range(arr, s):
          print(f'Range of {s}: [{arr.min()}, {arr.max()}] => {arr.max() - arr.
       →min()}')
      _range(Auto['mpg'], 'mpg')
      _range(Auto['displacement'], 'displacement')
      _range(Auto['weight'], 'weight')
      _range(Auto['acceleration'], 'acceleration')
     Range of mpg: [9.0, 46.6] \Rightarrow 37.6
     Range of displacement: [68.0, 455.0] => 387.0
     Range of weight: [1613, 5140] => 3527
     Range of acceleration: [8.0, 24.8] \Rightarrow 16.8
     11
           (c)
[11]: def _compute(arr, s):
          print(f'\{s\} \Rightarrow Std:\{arr.std():.2f\}\tMean:\{arr.mean():.2f\}')
      _compute(Auto['mpg'], 'mpg')
      _compute(Auto['displacement'], 'displacement')
      _compute(Auto['weight'], 'weight')
      _compute(Auto['acceleration'], 'acceleration')
     mpg => Std:7.83 Mean:23.52
     displacement => Std:104.38
                                       Mean: 193.53
     weight => Std:847.90
                              Mean:2970.26
     acceleration => Std:2.75
                                       Mean:15.56
     12
           (d)
\lceil 12 \rceil: auto = Auto
      auto.drop(index=[i for i in range(10,86,1)], inplace=True)
      auto.info()
```

```
<class 'pandas.core.frame.DataFrame'>
     Int64Index: 321 entries, 0 to 396
     Data columns (total 9 columns):
          Column
                         Non-Null Count Dtype
          _____
                         -----
                                         float64
      0
                         321 non-null
          mpg
      1
          cylinders
                         321 non-null
                                         int64
          displacement 321 non-null
                                         float64
      3
          horsepower
                         321 non-null object
          weight
                         321 non-null
                                         int64
      4
      5
          acceleration 321 non-null
                                         float64
      6
          year
                         321 non-null
                                         int64
      7
                         321 non-null
          origin
                                         int64
          name
                         321 non-null
                                         object
     dtypes: float64(3), int64(4), object(2)
     memory usage: 25.1+ KB
[13]: def _range(arr, s):
          print(f'Range of \{s\}: [\{arr.min()\}, \{arr.max()\}] \Rightarrow \{arr.max() - arr.max()\}
       →min()}')
      _range(auto['mpg'], 'mpg')
      _range(auto['displacement'], 'displacement')
      _range(auto['weight'], 'weight')
      _range(auto['acceleration'], 'acceleration')
     Range of mpg: [11.0, 46.6] \Rightarrow 35.6
     Range of displacement: [68.0, 455.0] => 387.0
     Range of weight: [1649, 4997] \Rightarrow 3348
     Range of acceleration: [8.5, 24.8] \Rightarrow 16.3
[14]: def _compute(arr, s):
          print(f'{s} => Std:{arr.std():.2f}\tMean:{arr.mean():.2f}')
      compute(auto['mpg'], 'mpg')
      _compute(auto['displacement'], 'displacement')
      _compute(auto['weight'], 'weight')
      _compute(auto['acceleration'], 'acceleration')
     mpg => Std:7.90 Mean:24.44
     displacement => Std:99.86
                                      Mean: 187.17
     weight => Std:809.64
                              Mean:2933.18
     acceleration => Std:2.71
                                      Mean:15.71
```

13 (e)

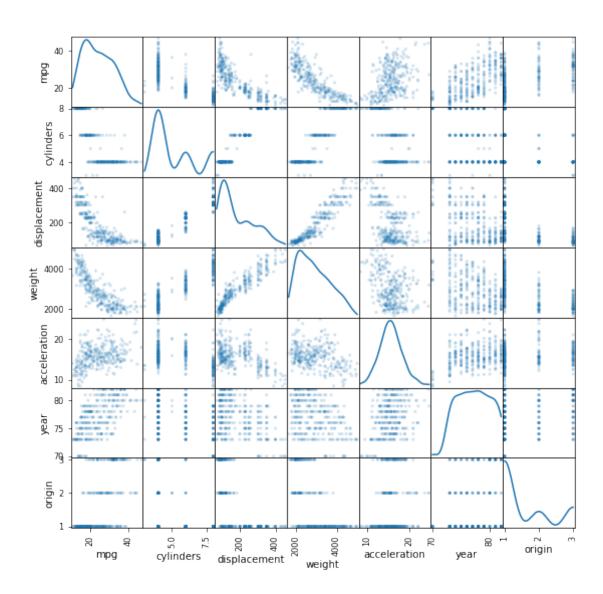
```
[15]: Auto.plot.scatter(x='weight',y='mpg')
```

[15]: <AxesSubplot:xlabel='weight', ylabel='mpg'>



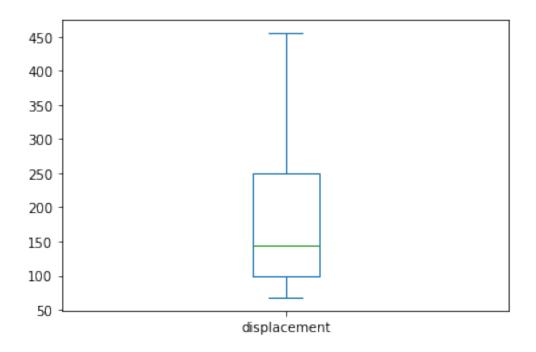
```
[16]: pd.plotting.scatter_matrix(Auto, alpha=0.2, figsize=(9,9), diagonal='kde')
[16]: array([[<AxesSubplot:xlabel='mpg', ylabel='mpg'>,
              <AxesSubplot:xlabel='cylinders', ylabel='mpg'>,
              <AxesSubplot:xlabel='displacement', ylabel='mpg'>,
              <AxesSubplot:xlabel='weight', ylabel='mpg'>,
              <AxesSubplot:xlabel='acceleration', ylabel='mpg'>,
              <AxesSubplot:xlabel='year', ylabel='mpg'>,
              <AxesSubplot:xlabel='origin', ylabel='mpg'>],
             [<AxesSubplot:xlabel='mpg', ylabel='cylinders'>,
              <AxesSubplot:xlabel='cylinders', ylabel='cylinders'>,
              <AxesSubplot:xlabel='displacement', ylabel='cylinders'>,
              <AxesSubplot:xlabel='weight', ylabel='cylinders'>,
              <AxesSubplot:xlabel='acceleration', ylabel='cylinders'>,
              <AxesSubplot:xlabel='year', ylabel='cylinders'>,
              <AxesSubplot:xlabel='origin', ylabel='cylinders'>],
             [<AxesSubplot:xlabel='mpg', ylabel='displacement'>,
              <AxesSubplot:xlabel='cylinders', ylabel='displacement'>,
              <AxesSubplot:xlabel='displacement', ylabel='displacement'>,
```

```
<AxesSubplot:xlabel='weight', ylabel='displacement'>,
<AxesSubplot:xlabel='acceleration', ylabel='displacement'>,
<AxesSubplot:xlabel='year', ylabel='displacement'>,
<AxesSubplot:xlabel='origin', ylabel='displacement'>],
[<AxesSubplot:xlabel='mpg', ylabel='weight'>,
<AxesSubplot:xlabel='cylinders', ylabel='weight'>,
<AxesSubplot:xlabel='displacement', ylabel='weight'>,
<AxesSubplot:xlabel='weight', ylabel='weight'>,
<AxesSubplot:xlabel='acceleration', ylabel='weight'>,
<AxesSubplot:xlabel='year', ylabel='weight'>,
<AxesSubplot:xlabel='origin', ylabel='weight'>],
[<AxesSubplot:xlabel='mpg', ylabel='acceleration'>,
<AxesSubplot:xlabel='cylinders', ylabel='acceleration'>,
<AxesSubplot:xlabel='displacement', ylabel='acceleration'>,
<AxesSubplot:xlabel='weight', ylabel='acceleration'>,
<AxesSubplot:xlabel='acceleration', ylabel='acceleration'>,
<AxesSubplot:xlabel='year', ylabel='acceleration'>,
<AxesSubplot:xlabel='origin', ylabel='acceleration'>],
[<AxesSubplot:xlabel='mpg', ylabel='year'>,
<AxesSubplot:xlabel='cylinders', ylabel='year'>,
<AxesSubplot:xlabel='displacement', ylabel='year'>,
<AxesSubplot:xlabel='weight', ylabel='year'>,
<AxesSubplot:xlabel='acceleration', ylabel='year'>,
<AxesSubplot:xlabel='year', ylabel='year'>,
<AxesSubplot:xlabel='origin', ylabel='year'>],
[<AxesSubplot:xlabel='mpg', ylabel='origin'>,
<AxesSubplot:xlabel='cylinders', ylabel='origin'>,
<AxesSubplot:xlabel='displacement', ylabel='origin'>,
<AxesSubplot:xlabel='weight', ylabel='origin'>,
<AxesSubplot:xlabel='acceleration', ylabel='origin'>,
<AxesSubplot:xlabel='year', ylabel='origin'>,
<AxesSubplot:xlabel='origin', ylabel='origin'>]], dtype=object)
```



[17]: Auto['displacement'].plot.box()

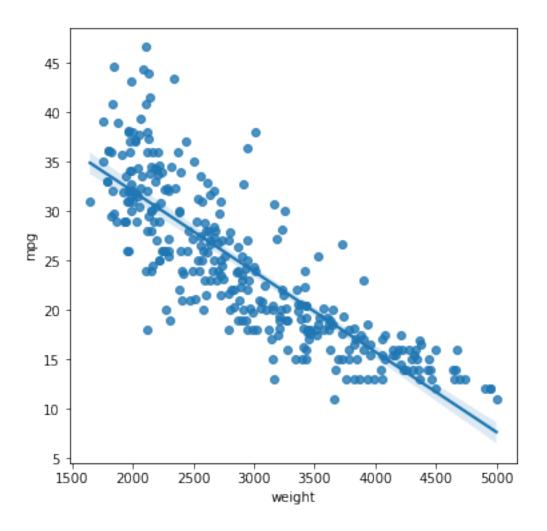
[17]: <AxesSubplot:>



```
[18]: # Linear regression model: train weight v mpg
# Intercept: 48.306516:.06f Coefficient: -0.008315:.06f
from sklearn.linear_model import LinearRegression
import seaborn as sns
import matplotlib.pyplot as plt

X = Auto['weight'].values.reshape(-1,1)
y = Auto['mpg']
model = LinearRegression()
model.fit(X, y)

plt.figure(figsize=(6,6))
sns.regplot(data=Auto, x='weight', y='mpg')
plt.show()
```



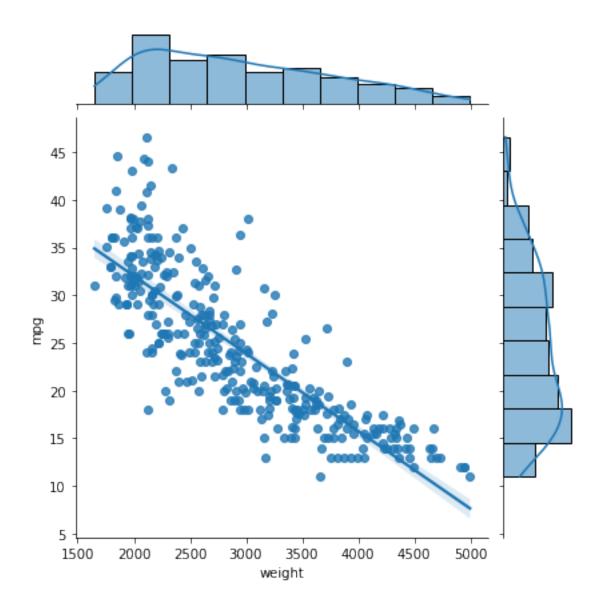
```
[19]: ## Prediction: 4000lb car gets ~15.8mpg
model.predict(np.array([2000]).reshape(1,-1))

## Prediction: 2000lb car gets ~32mpg
model.predict(np.array([2000]).reshape(1,-1))

[19]: array([32.03637571])

[150]: sns.jointplot(data=Auto, x='weight', y='mpg', kind='reg', height=6)
plt.show()
```

[150]: <seaborn.axisgrid.JointGrid at 0x1aa0f7ad310>



[]: