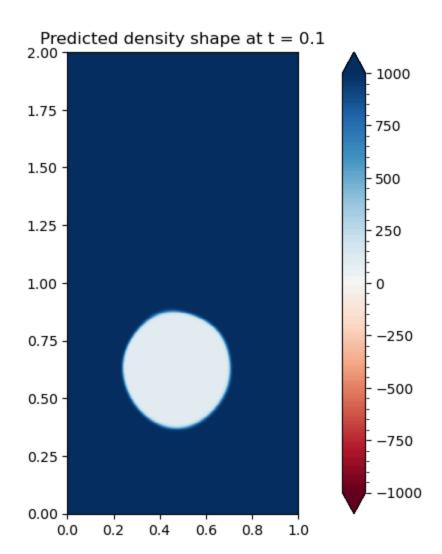
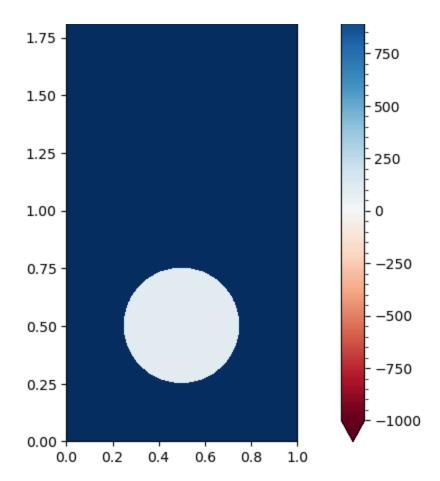
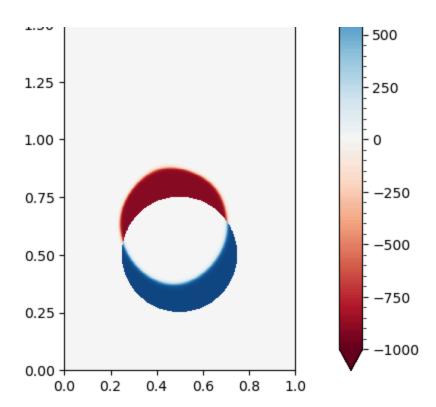
```
In [2]: import torch
        from torch import nn
       import numpy as np
       from torch.autograd import Variable
       import matplotlib.pyplot as plt
       from Forward with Layer Setting import Net
       from InitialConditionLoss import InitialCondition rho
        time plotted = 0.1
        device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")
        net = Net().to(device)
       net.load state dict(torch.load("BubbleLayers lr0.005 finaltime0.1.pt", map location=torch.device('cpu')))
        #Graph at various time slices
       spatial discretization = 1000
        #Define numpy arrays for inputs
       x1 = np.linspace(net.x1 l,net.x1 u,spatial discretization).reshape(spatial discretization)
       x2 = np.linspace(net.x2 l,net.x2 u,spatial discretization).reshape(spatial discretization)
       x1x2 = np.array(np.meshqrid(x1, x2)).reshape(2,spatial discretization**2)
       t = time plotted*np.ones((spatial discretization**2,1))
       x1 input = x1x2[0].reshape(spatial discretization**2, 1)
       x2 input = x1x2[1].reshape(spatial discretization**2, 1)
        x1x2 = [x1 input, x2 input]
        #convert to pytorch tensors
       pt x1 = Variable(torch.from numpy(x1 input).float(), requires grad=False).to(device)
       pt x2 = Variable(torch.from numpy(x2 input).float(), requires grad=False).to(device)
```

```
pt t = Variable(torch.from numpy(t).float(), requires grad=False).to(device)
#get network outputs
pt_u1, pt_u2, pt_p, pt_rho = net(pt_x1, pt_x2, pt_t)
#get actual initial condition
rho exact = InitialCondition rho(net, pt x1, pt x2)
#Convert back to numpy
u1, u2, p, rho = pt u1.data.cpu().numpy(), pt u2.data.cpu().numpy(), pt p.data.cpu().numpy(), pt rho.data.c
rho exact = rho exact.data.cpu().numpy()
error = rho-rho exact
X, Y = np.meshgrid(x1, x2)
fig, axs = plt.subplots(3 )
#fig.suptitle(f'Time = {time plotted}')
fig.tight layout()
axs[0].set title("Predicted density shape at t = %.1f" % time plotted)
axs[1].set title('Actual Initial Density where t=0 for comparing movement')
axs[2].set title('Error')
#axs[0].pcolor(X, Y, rho.reshape(X.shape))
#axs[1].pcolor(X, Y, rho exact.reshape(X.shape))
#axs[2].pcolor(X, Y, error.reshape(X.shape))
# Plot both positive and negative values between +/- 1.2
pos neg clipped = axs[0].imshow(rho.reshape(X.shape), cmap='RdBu', vmin=-1000, vmax=1000,
                             interpolation='none', extent = (net.x1_l,net.x1_u, net.x2_u, net.x2_l))
# Add minorticks on the colorbar to make it easy to read the
# values off the colorbar.
cbar = fig.colorbar(pos neg clipped, ax=axs[0].invert yaxis(), extend='both')
cbar.minorticks on()
# Plot both positive and negative values between +/- 1.2
pos neg clipped = axs[1].imshow(rho exact.reshape(X.shape), cmap='RdBu', vmin=-1000, vmax=1000,
                             interpolation='none', extent = (net.x1 l,net.x1 u, net.x2 u, net.x2 l))
# Add minorticks on the colorbar to make it easy to read the
# values off the colorbar.
```



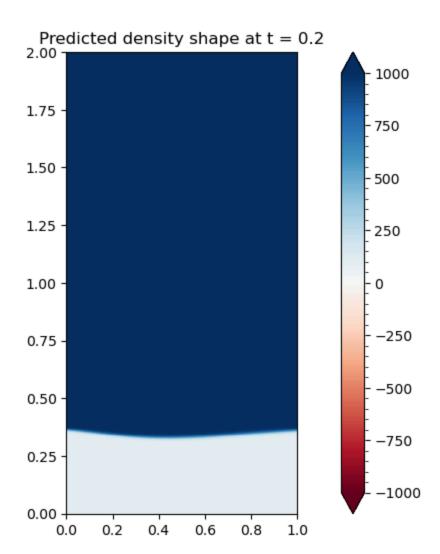


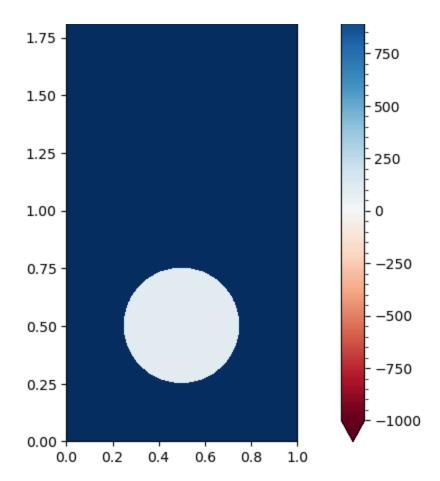




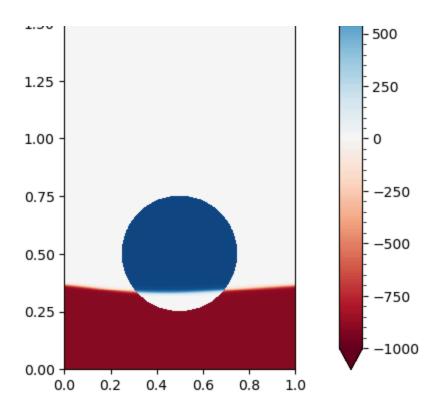
```
net.load state dict(torch.load("BubbleLayers lr0.005 finaltime0.2.pt", map location=torch.device('cpu')))
#Graph at various time slices
spatial discretization = 1000
#Define numpy arrays for inputs
x1 = np.linspace(net.x1_l,net.x1_u,spatial_discretization).reshape(spatial_discretization)
x2 = np.linspace(net.x2 l,net.x2 u,spatial discretization).reshape(spatial discretization)
x1x2 = np.array(np.meshqrid(x1, x2)).reshape(2,spatial discretization**2)
t = time plotted*np.ones((spatial discretization**2,1))
x1 input = x1x2[0].reshape(spatial discretization**2, 1)
x2 input = x1x2[1].reshape(spatial discretization**2, 1)
x1x2 = [x1 input, x2 input]
#convert to pytorch tensors
pt_x1 = Variable(torch.from_numpy(x1_input).float(), requires_grad=False).to(device)
pt x2 = Variable(torch.from numpy(x2 input).float(), requires grad=False).to(device)
pt t = Variable(torch.from numpy(t).float(), requires grad=False).to(device)
#get network outputs
pt_u1, pt_u2, pt_p, pt_rho = net(pt_x1, pt_x2, pt_t)
#get actual initial condition
rho exact = InitialCondition rho(net, pt x1, pt x2)
#Convert back to numpy
u1, u2, p, rho = pt u1.data.cpu().numpy(), pt u2.data.cpu().numpy(), pt p.data.cpu().numpy(), pt rho.data.c
rho exact = rho exact.data.cpu().numpy()
error = rho-rho exact
X, Y = np.meshgrid(x1, x2)
fig, axs = plt.subplots(3 )
#fig.suptitle(f'Time = {time plotted}')
```

```
fig.tight lavout()
axs[0].set title("Predicted density shape at t = %.1f" % time plotted)
axs[1].set title('Actual Initial Density where t=0 for comparing movement')
axs[2].set title('Error')
#axs[0].pcolor(X, Y, rho.reshape(X.shape))
#axs[1].pcolor(X, Y, rho exact.reshape(X.shape))
#axs[2].pcolor(X, Y, error.reshape(X.shape))
# Plot both positive and negative values between +/- 1.2
pos neg clipped = axs[0].imshow(rho.reshape(X.shape), cmap='RdBu', vmin=-1000, vmax=1000,
                             interpolation='none', extent = (net.x1 l,net.x1 u, net.x2 u, net.x2 l))
# Add minorticks on the colorbar to make it easy to read the
# values off the colorbar.
cbar = fig.colorbar(pos neg clipped, ax=axs[0].invert yaxis(), extend='both')
cbar.minorticks on()
# Plot both positive and negative values between +/- 1.2
pos neg clipped = axs[1].imshow(rho exact.reshape(X.shape), cmap='RdBu', vmin=-1000, vmax=1000,
                             interpolation='none', extent = (net.x1 l,net.x1 u, net.x2 u, net.x2 l))
# Add minorticks on the colorbar to make it easy to read the
# values off the colorbar.
cbar = fig.colorbar(pos neg clipped, ax=axs[1].invert yaxis(), extend='both')
cbar.minorticks on()
# Plot both positive and negative values between +/- 1000
pos neg clipped = axs[2].imshow(error.reshape(X.shape), cmap='RdBu', vmin=-1000, vmax=1000,
                             interpolation='none', extent = (net.x1 l,net.x1 u, net.x2 u, net.x2 l))
# Add minorticks on the colorbar to make it easy to read the
# values off the colorbar.
cbar = fig.colorbar(pos neg clipped, ax=axs[2].invert yaxis(), extend='both')
cbar.minorticks on()
#plt.xticks(np.arange(0, 1, step=.1))
#plt.yticks(np.arange(0, 2, step=.1))
#axs[2].legend()
fig.set figheight(20)
fig.set figwidth(10)
plt.show()
```



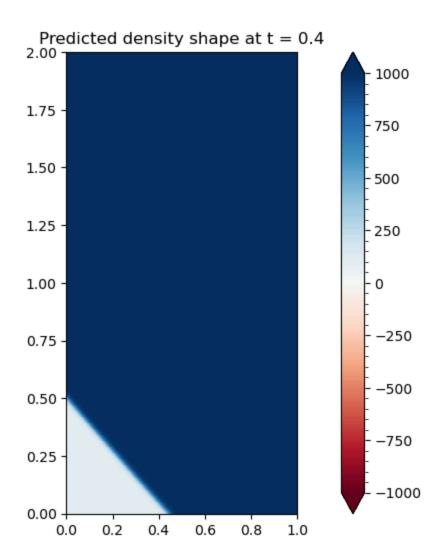


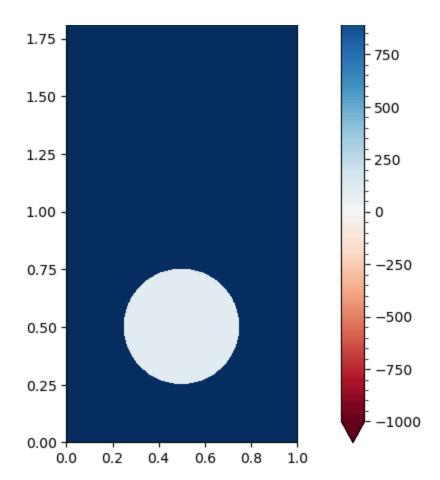




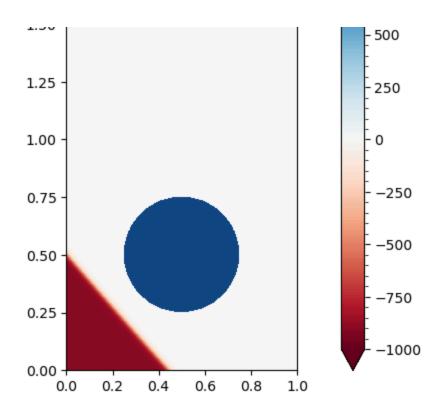
```
net.load state dict(torch.load("BubbleLayers lr0.005 finaltime0.4.pt", map location=torch.device('cpu')))
#Graph at various time slices
spatial discretization = 1000
#Define numpy arrays for inputs
x1 = np.linspace(net.x1_l,net.x1_u,spatial_discretization).reshape(spatial_discretization)
x2 = np.linspace(net.x2 l,net.x2 u,spatial discretization).reshape(spatial discretization)
x1x2 = np.array(np.meshqrid(x1, x2)).reshape(2,spatial discretization**2)
t = time plotted*np.ones((spatial discretization**2,1))
x1 input = x1x2[0].reshape(spatial discretization**2, 1)
x2 input = x1x2[1].reshape(spatial discretization**2, 1)
x1x2 = [x1 input, x2 input]
#convert to pytorch tensors
pt_x1 = Variable(torch.from_numpy(x1_input).float(), requires_grad=False).to(device)
pt x2 = Variable(torch.from numpy(x2 input).float(), requires grad=False).to(device)
pt t = Variable(torch.from numpy(t).float(), requires grad=False).to(device)
#get network outputs
pt_u1, pt_u2, pt_p, pt_rho = net(pt_x1, pt_x2, pt_t)
#get actual initial condition
rho exact = InitialCondition rho(net, pt x1, pt x2)
#Convert back to numpy
u1, u2, p, rho = pt u1.data.cpu().numpy(), pt u2.data.cpu().numpy(), pt p.data.cpu().numpy(), pt rho.data.c
rho exact = rho exact.data.cpu().numpy()
error = rho-rho exact
X, Y = np.meshgrid(x1, x2)
fig, axs = plt.subplots(3 )
#fig.suptitle(f'Time = {time plotted}')
```

```
fig.tight lavout()
axs[0].set title("Predicted density shape at t = %.1f" % time plotted)
axs[1].set title('Actual Initial Density where t=0 for comparing movement')
axs[2].set title('Error')
#axs[0].pcolor(X, Y, rho.reshape(X.shape))
#axs[1].pcolor(X, Y, rho exact.reshape(X.shape))
#axs[2].pcolor(X, Y, error.reshape(X.shape))
# Plot both positive and negative values between +/- 1.2
pos neg clipped = axs[0].imshow(rho.reshape(X.shape), cmap='RdBu', vmin=-1000, vmax=1000,
                             interpolation='none', extent = (net.x1 l,net.x1 u, net.x2 u, net.x2 l))
# Add minorticks on the colorbar to make it easy to read the
# values off the colorbar.
cbar = fig.colorbar(pos neg clipped, ax=axs[0].invert yaxis(), extend='both')
cbar.minorticks on()
# Plot both positive and negative values between +/- 1.2
pos neg clipped = axs[1].imshow(rho exact.reshape(X.shape), cmap='RdBu', vmin=-1000, vmax=1000,
                             interpolation='none', extent = (net.x1 l,net.x1 u, net.x2 u, net.x2 l))
# Add minorticks on the colorbar to make it easy to read the
# values off the colorbar.
cbar = fig.colorbar(pos neg clipped, ax=axs[1].invert yaxis(), extend='both')
cbar.minorticks on()
# Plot both positive and negative values between +/- 1000
pos neg clipped = axs[2].imshow(error.reshape(X.shape), cmap='RdBu', vmin=-1000, vmax=1000,
                             interpolation='none', extent = (net.x1 l,net.x1 u, net.x2 u, net.x2 l))
# Add minorticks on the colorbar to make it easy to read the
# values off the colorbar.
cbar = fig.colorbar(pos neg clipped, ax=axs[2].invert yaxis(), extend='both')
cbar.minorticks on()
#plt.xticks(np.arange(0, 1, step=.1))
#plt.yticks(np.arange(0, 2, step=.1))
#axs[2].legend()
fig.set figheight(20)
fig.set figwidth(10)
plt.show()
```









In [ ]: