

Software Testing

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Content

- Chapter 2 of LN. Here I will just give you a summary of the chapter:
 - Coverage
 - White box testing
 - Black box testing
- Some addition: symbolic testing

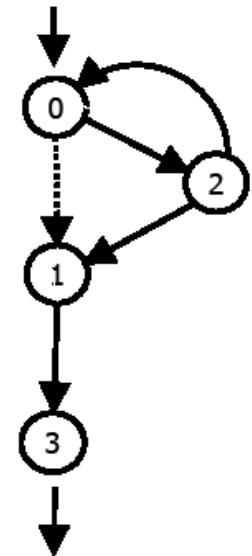
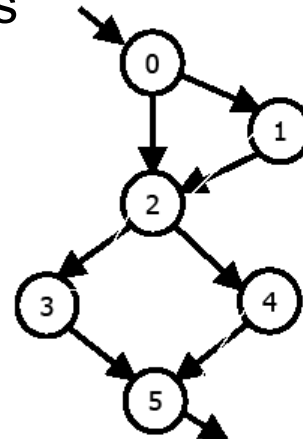
Testing vs Verification

```
tax(income | tx) {  
    tx = 0 ;  
    if (income > 20000) then  
        { tx := 0.2 * (income - 20000) ; income := 20000 }  
    if (income ≤ 10000) then tx := 0 ;  
    else tx := tx + 0.1 * (income - 10000)  
}
```

- *Verification* : show that *all possible executions* satisfy the given specification (very hard).
- *Testing* : show that at least few executions satisfy the specification.
 - not trivial to determine which executions to choose
 - not trivial to figure out how to trigger those executions (undecidable)

Coverage

- Introduce a “reasonable” *equivalence relation* over the executions, then try to “cover” all induced equivalence classes (an EC is covered if there is at least one test case’s whose execution belongs to it).
- Popular: CFG-based coverage:
 - Try to cover all nodes, or all edges
 - Try to cover all paths, or all prime paths, or all linearly independent paths



Automated testing

- Consider a program $f(x|y)$, specified by $\{P\} f(x,y) \{Q\}$
- A test-case for f is an instance of x , satisfying P . The result y is checked if it satisfies Q .
- While inputs (instances of x) can be generated, no algorithm can guess what's in your mind. So, there is no way to “generate” P and Q .
- **Coverage problem:** come up with an instance of x , such that the resulting execution covers some target c , e.g. a certain branch.
(recall that such a problem is undecidable)

From Unit Testing Tool Competition 2015

- Benchmarking of automated unit testing tools for Java; “unit testing” at the class level.
- 63 classes from various open source projects
- Base lines: randoop (random testing tool), human testers.
- Tools → all exploit reflection
 - T3 (random + pair-wise)
 - GRT (guided random + light static analysis)
 - JTexpert (guided random + light static analysis)
 - Mosa (evolutionary algorithm + light static analysis)
 - Evosuite (evolutionary algorithm + light static analysis + memetic)
 - Commercial (secret)

From Unit Testing Tool Competition 2015

	Rando op	Human	T3	GRT	JTexpe rt	Mosa	Evosuit e	CT
cov_b	32	68	57	61	55	56	55	26
cov_m	20	50	41	45	31	39	41	12
Tgen	1.77h	23h	0.85h	4.6h	1.55h	1.48h	6.5h	1.01h

	tools	tools+humans
Average cov_i	78.0 %	84.9 %
Average cov_b	64.7 %	70.1 %
Average cov_m	60.3 %	69.4 %
# CUTs with $cov_b = 100\%$	6	7
# CUTs with $cov_b \geq 80\%$	31	34
CUTs with $cov_i \leq 10\%$	{ 43,45,49,61 }	{ 45 }
CUTs with $cov_i \leq 5\%$	{ 45,61 }	{ 45 }
SCORE	266.7	277.8

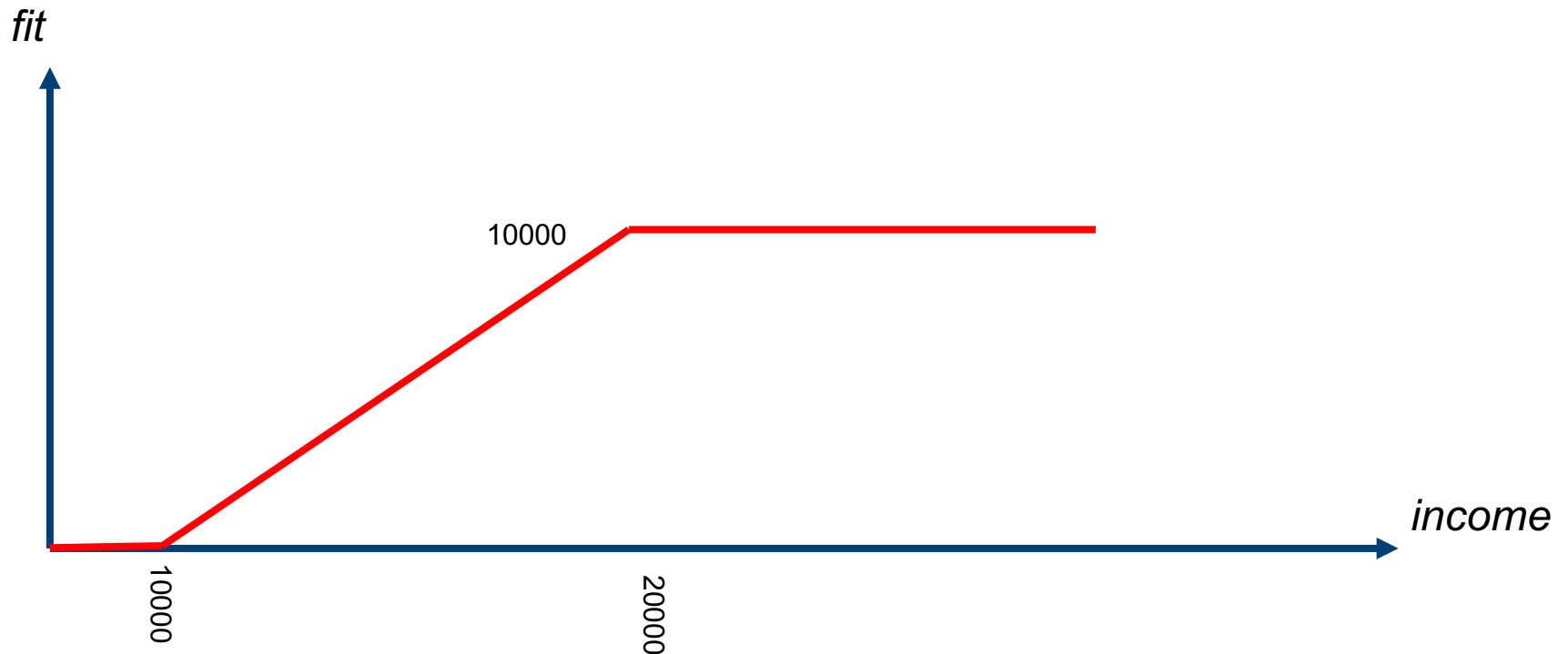
TABLE IV
COMBINED STRENGTH OF THE CONTESTING TOOLS

Cov. problem as a search problem

- Consider again the example program; ■ is the target to cover. The program is extended with “instrumentation” ; for simplicity, fit is a global-var.
- The problem can be re-expressed to searching an input for tax, such that the value of “fit” is minimized.

```
tax(income | tx) {  
    tx := 0 ;  
    if (income > 20000) then  
        { tx := 0.2 * (income - 20000) ; income := 20000 }  
    fit := max(0, income - 10000)  
    if (income ≤ 10000) then ■ tx := 0 ;  
    else tx := tx + 0.1 * (income - 10000)  
}
```


Hill climbing



- (actually hill descent here)
 - start with some input vector i
 - adjust i , if this improves fit, repeat the process.
 - stop if no improvement is obtained.
- you can get stuck in a local-minimum
- other search-algorithms, e.g. genetic

Using “symbolic execution”

- Consider $\{P\} f(x|y) \{Q\}$
- Consider a “progran path” ρ in $f(x)$
 - full: from start to end
 - you may require it to pass a certain “target branch” b
 - we convert all branching conditions along ρ to the corresponding **assert**, and in the “right orientation”.
 - let’s ignore loop and exception for now.
- Testing-1: any instance of x satisfying $P \wedge \text{wlp } \rho \text{ true}$ will trigger an execution that covers b and $\rho \rightarrow$ solving the coverage problem.
- Testing-2: we can also use testing to check the validity of $P \Rightarrow \text{wlp } \rho Q$. But we need to convert conditions to **assume** rather than **assert**.

Example

```
tax(income | tx) {  
  tx := 0 ;  
  if (income > 20000) then  
    { tx := 0.2 * (income - 20000) ; income := 20000 }  
  if (income ≤ 10000) then ■ tx := 0 ;  
  else tx := tx + 0.1 * (income - 10000)  
}
```

- Suppose pre-cond is “ $\text{income} \geq 0$ ”, and post-cond “ $\text{tx} < \text{income}$ ”
- A program path ρ covering ■
 tx := 0 ;
 assert income ≤ 20000 ;
 assert income ≤ 10000 ;
 tx := 0
- **wlp** ρ true = $\text{income} \leq 10000 \wedge \text{income} \leq 20000$
- Testing-1 mode: find a **solution** of $\text{income} \geq 0 \wedge \text{income} \leq 10000 \wedge$
 $\text{income} \leq 20000$; it triggers an execution that will cover the entire ρ ,
 thus also ■

Example

- If we use **assume** to encode ρ we get:
tx := 0 ;
assume income \leq 20000 ;
assume income \leq 10000 ;
tx := 0
- calculating $P \Rightarrow \text{wlp } Q$ we obtain :
income $\geq 0 \Rightarrow$ income $\leq 10000 \Rightarrow$ income $\leq 20000 \Rightarrow 0 < \text{income}$
- The path ρ is **correct** if the above implication is **valid**. In Testing-2 mode we use testing to check this validity.
- The predicate it is not valid. Counter example: income = 0.

Issues with the wlp-based approach

- Such a path-based wlp approach can be expensive (a program may have exponentially many paths, even if we have no loop) → mitigation by merging some paths.
- Some paths may turn out to be infeasible (thus wasting our testing effort)
- What if the program contains loops?
 - you can do $[\text{loop}]^k$ or $\langle \text{loop} \rangle^k$ unrolling depending on your purpose.
 - For Testing-1 mode use $[\text{loop}]^k$
 - For Testing-2 mode use $\langle \text{loop} \rangle^k$
- What if the program contains calls to methods whose source code is unknown?

Single-assignment approach

- Given the following program path, we can convert it to a set of single-assignment-based constraints :

```
assert x > 10  
tx := 0.2 * (x - 10)  
x := 10  
assert xy > 10  
tx := tx + 0.1 * (xy - 10)
```



```
assert x > 10  
 $\wedge tx_1 = 0.2 * (x - 10)$   
 $\wedge x_1 = 10$   
 $\wedge$  assert  $x_1 y > 10$   
 $\wedge tx_2 = tx_1 + 0.1 * (x_1 y - 10)$ 
```

Only the yellow part form the condition for fully traversing the path.

- The end product is equivalent to what you get through **wlp**.
- Solving the constraints gives you an input (x,y) such that the resulting execution fully traverses the path.

Combined concrete-symbolic testing

- A program path containing “back-box” method call.

```
assert x > 10  
tx := 0.2 * (x - 10)  
x := f()  
assert xy > 10  
tx := tx + 0.1 * (xy - 10)
```



```
assert x > 10  
 $\wedge tx_1 = 0.2 * (x - 10)$   
 $\wedge x_1 = ??$   
 $\wedge$  assert  $x_1 y > 10$   
 $\wedge tx_2 = tx_1 + 0.1 * (x_1 y - 10)$ 
```

- It is not possible to solve the constraints because the assignment to x_1 is unknown.
- We can however combine this with concrete executions. If you manage to get an execution with an x that passes the first assert, the resulting x_1 can be instrumented, and we can solve the remaining constraints to get the needed value of y .