

PROGRAM SEMANTIC



www.cs.uu.nl/docs/vakken/pv

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FORMAL SEMANTIC

- To provide a formal definition, or at least a model, of what a program is. There are several common styles to do this.
- **Natural operational semantic:** defining the meaning of a program in terms of the result of its execution.
- **Structural** (small steps) operational semantic: defining how the program is executed.
- **Denotational semantic:** defining what a program is.
- **Axiomatic semantic:** defining how to infer properties of a program.

RUNNING EXAMPLE : LASG

- *program* → *block*
block → { *identifier = expr* ; *statements* }
statements → one or more stmt seprated by “;”
stmt → *identifier := expr* | *block*

expr → 0 | 1 | 2 | ...
 | *identifier*
 | *expr* + *expr*

- A program produces/returns the final value of the (single) variable it declares at the root.

EXAMPLES

- A program that returns 11: $\{x=10; x:=x+1\}$
- A program with nested blocks, returning 21:

$\{x=10; \{y=x+10; \{x=y ; y:=x+1\} ; x:=y \}\}$

OPERATIONAL SEMANTIC

- Notation: $\langle e, s \rangle \rightarrow v$

“executing an expression e on the state s results in the value v ”

- How do you want to represent a “state” ?
- Let’s use list of “pairs” e.g. $s = [x \mapsto 0 , y \mapsto 9]$
- Duplicate mapping is allowed, e.g. $[x \mapsto 0 , x \mapsto 1 , y \mapsto 9]$
The first mapping of x in s is also called the “latest” or the “most recent”.

OPERATIONS ON STATE

- **query**, denoted by $s\ x$: querying the value of *the most recent mapping* of x in s . It is only defined if s contains x .
- **update** $s\ x\ v$: update x 's most recent mapping to v ; it assumes that x is defined in s .
- **remove** $x\ s$: remove the most recent mapping of x in s .

A NATURAL OPERATIONAL SEMANTIC OF EXPR

- “executing” an expr results in a value.
- $\langle c, s \rangle \rightarrow c$
- $\langle x, s \rangle \rightarrow s\ x$, assuming s contains x
- $\langle e_1 + e_2, s \rangle \rightarrow \langle e_1, s \rangle + \langle e_2, s \rangle$
- Example: $\langle x+1, s \rangle$ where $s = [x \mapsto 0, x \mapsto 1, y \mapsto 9]$

AND FOR STMT (ASSIGNMENT FIRST)

- Executing a statement on a state results in a new state.
- For assignment :

$$\frac{\langle e, s \rangle \rightarrow v}{\langle x := e, s \rangle \rightarrow \text{update } s \ x \ v}$$

OTHER STATEMENTS

- $S_1 ; S_2$, can you define a semantic for this ?
- Block is a bit more involved:

$$\frac{\langle e, s \rangle \rightarrow v \quad \langle S, x \mapsto v : s \rangle \rightarrow t}{\langle \{ x = e ; S \}, s \rangle \rightarrow \text{remove } x \ t}$$

FINALLY, THE SEMANTIC OF PROGRAM

- A program returns the final value of the variable it declares.
- Furthermore, any LAsg program starts from **the initial state**, which is [].
- Let $P = \{ x=e ; S \}$ be a **program**.

$$\frac{\begin{array}{l} \langle e, [] \rangle \rightarrow v \\ \langle S, [x \mapsto v] \rangle \rightarrow t \end{array}}{\langle P, [] \rangle \rightarrow tx}$$

STRUCTURAL OPERATIONAL SEMANTIC

- Structural, aka “small steps” semantic wants to describe the execution itself.
- Suppose we have an imaginary interpreter for LAsg, which “executes” an expr with the help of a stack. The following semantic describes how this works:
 - $\langle c, \sigma, s \rangle \Rightarrow \langle c : \sigma, s \rangle$
 - $\langle x, \sigma, s \rangle \Rightarrow \langle s\ x : \sigma, s \rangle$, assuming s contains x
 - $$\begin{array}{l} \langle e_1, \sigma, s \rangle \Rightarrow \langle v_1 : \sigma, s \rangle \\ \langle e_2, v_1 : \sigma, s \rangle \Rightarrow \langle v_2 : v_1 : \sigma, s \rangle \end{array}$$

$$\langle e_1 + e_2, \sigma, s \rangle \Rightarrow \langle v_1 + v_2 : \sigma, s \rangle$$

STMT (ASSIGNMENT FIRST)

- A statement may change the state.
- It does not change the stack (it may temporarily change the stack, but will restore it to what it was).
- For example, the semantic of assignment:

$$\frac{\langle e, \sigma, s \rangle \Rightarrow \langle v : \sigma, s \rangle}{\langle x := e, \sigma, s \rangle \Rightarrow \langle \sigma, \text{update } s \text{ x } v \rangle}$$

- How about seq and block ?
- How about the semantic of LAsg programs?

THE SEMANTIC OF A PROGRAM

- Let $P = \{ x=e ; S \}$ be a **program**.
- A program is executed on a fresh/empty stack and state.

- $$\begin{array}{l} \langle e, [], [] \rangle \Rightarrow \langle [v], [] \rangle \\ \langle S, [], [x \mapsto v] \rangle \Rightarrow \langle [], t \rangle \\ \hline \langle P, [], [] \rangle \Rightarrow t x \end{array}$$

PROPERTIES

- Having formal semantics allows us to more precisely discuss about properties of programs, or of the semantics themselves, and to prove them.
- Examples:
 - *After executing an expression e , the stack will grow with exactly one:*
 $\langle e, \sigma, s \rangle \Rightarrow \langle \tau, s \rangle$ implies $|\tau| = |\sigma| + 1$
 - *The stack after executing any statement S will be the same as it was at the start of the execution.*
 - *The natural and structural semantics of LAsg's expr are equivalent:*

For all $\sigma : \langle e, s \rangle \rightarrow v$ if and only if $\langle e, \sigma, s \rangle \Rightarrow \langle v: \sigma, s \rangle$

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DENOTATIONAL SEMANTIC

- What is a program? Or at least, define a (mathematical) model of what a program is.
- **Notation:** $\mathcal{E}[[e]]$ = the meaning of e
 - $\mathcal{E} : \text{expr} \rightarrow \text{some domain}$
 - is called *valuation function*.
- We will need :
 - \mathcal{E} for expr
 - \mathcal{S} for statements
 - \mathcal{P} for programs

DEFINING THE DOMAINS TO USE

- **State** = the domain of all possible states, each represented as a map as introduced before.
- **Int** = the domain of all integers.
- We will model an expr as a function of type **State** \rightarrow **Int**.
- and a statement as a function of type **State** \rightarrow **State**.

DENOTATIONAL SEM. OF EXPR

- $\mathcal{E} : \text{expr} \rightarrow (\text{State} \rightarrow \text{Int})$
- $\mathcal{E}[[c]] = (\lambda s. c)$
- $\mathcal{E}[[x]] = (\lambda s. s\ x)$ what if x is undefined in s ?
- $\mathcal{E}[[e_1 + e_2]] = (\lambda s. \mathcal{E}[[e_1]]s + \mathcal{E}[[e_2]]s)$

DENOTATIONAL SEM. OF STATEMENTS AND PROGRAMS

- $\mathcal{S} : \text{stmt} \rightarrow (\text{State} \rightarrow \text{State})$

- For example, assignment:

$$\mathcal{S}[\![x := e]\!] = (\lambda s. \text{update } s \ x \ (\mathcal{E}[\![e]\!]s))$$

- $\mathcal{P} : \text{program} \rightarrow \text{Int}$

$$\mathcal{P}[\![\{x=e; S\}]\!] = \text{let } t = \mathcal{S}[\![S]\!][x \mapsto \mathcal{E}[\![e]\!][\]] \text{ in } t \ x$$

AXIOMATIC SEMANTIC

- Defining the meaning of a program in terms of its properties of interest.
 - More precisely, in terms of which properties hold (and implicitly, which do not).
 - Commonly formulated in terms of inference rules.
- Example: property of interest is the functional correctness of a program, in terms of Hoare triples.

SPECIFYING STATES

- We need a slightly richer language than expr. Call it **Pred** (predicates) :
 - $e_1 = e_2$, $e_1 > e_2$
 - $\neg P$, $P_1 \wedge P_2$, $P_1 \Rightarrow P_2$
 - $\forall x. P$
- Examples (on which states they hold ?) :
 - $x > 0$
 - $\forall x. x > 0 \Rightarrow \neg(x = 0)$

HOARE TRIPLES

- **Note:** as before, we limit our discussion to LAsg.
- Let P and Q be predicates.
- For statement: $\{ * P * \} \text{ stmt } \{ * Q * \}$
- For LAsg program: $\{ * P * \} \text{ prog } \{ * Q * \}$
 - P contains no free variable ; effectively the only sensical P is the predicate *true*.
 - Q only has “return” as its free variable
- Examples:
 - $\{ * x > 0 * \} \text{ x:=x+1 } \{ * x > 1 * \}$
 - $\{ * \text{true} * \} \{ \text{x=10 ; x:=x+1} \} \{ * \text{return} > 10 * \}$

“AXIOMS” FOR STATEMENTS

- $P \Rightarrow Q[e/x]$ is valid

$$\{ *P* \} \ x:=e \ \{ *Q* \}$$

- $\{ *P* \} \ x' := e ; x_{old} := x ; x := x' ; S ; x := x_{old} \ \{ *Q* \}$

$$\{ *P* \} \ \{ x=e ; S \} \ \{ *Q* \}$$

x' , x'' , x_{old} are all fresh variables.

EXAMPLE

- $\{*\text{true}*\} \quad \{x:=2; y:=x-1\} \quad \{*\neg y < 0*\}$