

Chernoff Bound on Average Error Probability

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READING: [Fukunaga 1990], [Johnson 2013, §5.1.6], [Van Trees et al. 2013, §2.4], [Cover and Thomas 2006, §11.9], [Poor 1994].

Consider testing

$$\mathbb{H}_0 : \Theta \in \text{sp}_{\Theta}(0) \quad \text{versus}$$

$$\mathbb{H}_1 : \Theta \in \text{sp}_{\Theta}(1)$$

For the 0–1 loss, the Bayes' rule that minimizes the average error probability

$$\begin{aligned} \text{av. error probability} &= \Pr(\mathbb{H}_0) \int_{\mathcal{X}_1} f_{\mathbf{X}|\Theta}(\mathbf{x} | \mathbb{H}_0) d\mathbf{x} \\ &\quad + \Pr(\mathbb{H}_1) \int_{\mathcal{X}_0} f_{\mathbf{X}|\Theta}(\mathbf{x} | \mathbb{H}_1) d\mathbf{x} \end{aligned} \quad (1)$$

is the maximum *a posteriori* (MAP) decision rule:

$$\mathcal{X}_1^* = \{\mathbf{x} \mid f(\mathbf{x} | \mathbb{H}_0) \Pr(\mathbb{H}_0) - f(\mathbf{x} | \mathbb{H}_1) \Pr(\mathbb{H}_1) < 0\}. \quad (2)$$

see (7b) in handout Bayesdet

In many applications, we *may not be able to obtain* a simple closed-form expression for the minimum average error probability, but we *can find an upper bound for it* as follows:

$$\begin{aligned} \min \text{av. error prob.} &= \Pr(\mathbb{H}_0) \int_{\mathcal{X}_1^*} f_{\mathbf{X}|\Theta}(\mathbf{x} | \mathbb{H}_0) d\mathbf{x} \\ &\quad + \Pr(\mathbb{H}_1) \int_{\mathcal{X}_0^*} f_{\mathbf{X}|\Theta}(\mathbf{x} | \mathbb{H}_1) d\mathbf{x} \\ &= \int_{\mathcal{X}} \min\{f(\mathbf{x} | \mathbb{H}_0) \Pr(\mathbb{H}_0), f(\mathbf{x} | \mathbb{H}_1) \Pr(\mathbb{H}_1)\} d\mathbf{x} \\ &\leq \int_{\mathcal{X}} [f(\mathbf{x} | \mathbb{H}_0) \Pr(\mathbb{H}_0)]^{\lambda} [f(\mathbf{x} | \mathbb{H}_1) \Pr(\mathbb{H}_1)]^{1-\lambda} d\mathbf{x} \end{aligned}$$

plug the definition of \mathcal{X}_1^* into (2)

$0 \leq \lambda \leq 1$

which is the *Chernoff bound on the minimum average error probability*.

Here, we have used the fact that

$$\min\{a, b\} \leq a^{\lambda} b^{1-\lambda}, \quad \text{for } 0 \leq \lambda \leq 1, \quad a, b \geq 0.$$

Conditionally I.I.D. Measurements

SUPPOSE that $(X[n])_{n=0}^{N-1}$ are conditionally independent, identically distributed (i.i.d.) given $\Theta = \theta$, following $f_{X|\Theta}(x[n] | \theta)$. Then, the Chernoff bound becomes

$$\begin{aligned} \text{Chernoff bound} &= \int_{\mathcal{X}} \left[\Pr(\mathbb{H}_0) \prod_{n=0}^{N-1} f(x | \mathbb{H}_0) \right]^\lambda \left[\Pr(\mathbb{H}_1) \prod_{n=0}^{N-1} f(x | \mathbb{H}_1) \right]^{1-\lambda} dx \\ &= [\Pr(\mathbb{H}_0)]^\lambda [\Pr(\mathbb{H}_1)]^{1-\lambda} \prod_{n=0}^{N-1} \left\{ \int_{\mathcal{X}} [f(x | \mathbb{H}_0)]^\lambda [f(x | \mathbb{H}_1)]^{1-\lambda} dx \right\} \\ &= [\Pr(\mathbb{H}_0)]^\lambda [\Pr(\mathbb{H}_1)]^{1-\lambda} \left\{ \int_{\mathcal{X}} [f(x | \mathbb{H}_0)]^\lambda [f(x | \mathbb{H}_1)]^{1-\lambda} dx \right\}^N \end{aligned}$$

and, therefore,

$$\begin{aligned} \frac{1}{N} \ln(\text{min av. error prob.}) &\leq \frac{1}{N} \ln \left\{ [\Pr(\mathbb{H}_0)]^\lambda [\Pr(\mathbb{H}_1)]^{1-\lambda} \right\} \\ &\quad + \ln \int_{\mathcal{X}} [f(x | \mathbb{H}_0)]^\lambda [f(x | \mathbb{H}_1)]^{1-\lambda} dx. \quad \forall \lambda \in [0, 1] \end{aligned}$$

If $\Pr(\mathbb{H}_0) = \Pr(\mathbb{H}_1) = 1/2$ (which is often of interest when evaluating average error probabilities), we can state that for N conditionally i.i.d. measurements given $\Theta = \theta$ and simple hypotheses

$$\text{min av. error probability} \rightarrow w(N) \exp \left(-N \underbrace{\left\{ - \min_{\lambda \in [0,1]} \int_{\mathcal{X}} [f(x | \mathbb{H}_0)]^\lambda [f(x | \mathbb{H}_1)]^{1-\lambda} dx \right\}}_{\text{Chernoff information for a single observation}} \right)$$

as $N \nearrow +\infty$, where $w(N)$ is a slowly-varying function compared with the exponential term:

$$\lim_{N \nearrow +\infty} \frac{\ln w(N)}{N} = 0.$$

Note that the Chernoff information in the exponent term of the above minimum error-probability expression quantifies the asymptotic behavior of the minimum average error probability.

We now give a useful result for evaluating a class of Chernoff bounds, taken from [Fukunaga 1990].

Lemma 1. Consider $f_1(\mathbf{x}) = \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_1, \Sigma_1)$ and $f_2(\mathbf{x}) = \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_2, \Sigma_2)$. Then

$$\int [f_1(\mathbf{x})]^\lambda [f_2(\mathbf{x})]^{1-\lambda} d\mathbf{x} = \exp[-g(\lambda)]$$

where

$$\begin{aligned} g(\lambda) &= \frac{\lambda(1-\lambda)}{2} (\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1)^T [\lambda \Sigma_1 + (1-\lambda) \Sigma_2]^{-1} (\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1) \\ &\quad + 0.5 \ln \left[\frac{\det[\lambda \Sigma_1 + (1-\lambda) \Sigma_2]}{\det(\Sigma_1)^\lambda \det(\Sigma_2)^{1-\lambda}} \right]. \end{aligned}$$

☞ HERE, we bound average error probability, whereas [Poor 1994; Van Trees et al. 2013] bound conditional error probabilities using similar tools.

References

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