# Sequential Bayesian Approach and Prediction

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READING: [Gelman et al. 2014, §1.3, 2.1, 2.5].

## Sequential Bayesian Approach

Suppose that we have observed  $x_1$  and  $x_2$ , where  $x_1$  comes first. We wish to infer about  $\theta$ . Conditioning on  $X_1 = x_1$  yields

$$f_{X_2,\Theta|X_1}(x_2,\theta \mid x_1) = f_{X_2|\Theta,X_1}(x_2 \mid \theta, x_1) f_{\Theta|X_1}(\theta \mid x_1)$$
 (1)

where

- $f_{X_2|X_1,\Theta}(x_2|x_1,\theta)$  is the new, updated likelihood function of  $\theta$ based on  $x_2$  and
- $f_{\Theta|X_1}(\theta \mid x_1)$  is the new, updated prior for  $\theta$ .

Now, (1) implies

$$f_{\Theta|X_1,X_2}(\theta \mid x_1,x_2) \propto f_{X_2|\Theta,X_1}(x_2 \mid \theta,x_1) f_{\Theta|X_1}(\theta \mid x_1)$$
 (2)

which is simply the Bayes' rule with an extra conditioning on  $X_1$ .<sup>2</sup>

<sup>2</sup> We obtain the ordinary Bayes' rule by

<sup>1</sup> For example, the subscript denotes a

Put the quantities we know on the right

and the quantities we do not know on

time index.

the left.

# Prediction

Suppose that we have observed  $X_1 = x_1$  and wish to predict  $X_2$ . For this purpose, we use the *predictive distribution*<sup>3</sup>  $f_{X_2|X_1}(x_2|x_1)$ . We derive this pdf as follows. Recall (1):

$$f_{X_2,\Theta|X_1}(x_2,\theta \mid x_1) = f_{X_2|\Theta,X_1}(x_2 \mid \theta, x_1) f_{\Theta|X_1}(\theta \mid x_1).$$
 (3)

removing  $|X_1|$  from all terms in (2).

<sup>3</sup> say a probability density function (pdf), for simplicity of exposition

Now, marginalize the joint pdf of  $X_2$  and  $\Theta$  in (3) with respect to the unknown parameter  $\Theta$ , i.e., integrate  $\Theta$  out:

$$f_{X_{2}|X_{1}}(x_{2} | x_{1}) = \int f_{X_{2},\Theta|X_{1}}(x_{2}, \theta | x_{1}) d\theta$$

$$= \int f_{X_{2}|\Theta,X_{1}}(x_{2} | \theta, x_{1}) f_{\Theta|X_{1}}(\theta | x_{1}) d\theta.$$
(4)

Conditionally independent observations

Consider conditionally independent  $X_1$  and  $X_2$  given  $\Theta = \theta$ , i.e.,

$$f_{X_1,X_2|\Theta}(x_1,x_2 \mid \theta) = f_{X_1|\Theta}(x_1 \mid \theta) f_{X_2|\Theta}(x_2 \mid \theta)$$
 (5)

or, equivalently,

$$f_{X_2|X_1,\Theta}(x_2 \mid x_1, \theta) = f_{X_2|\Theta}(x_2 \mid \theta).$$
 (6)

Now, (4) simplifies to

$$f_{X_2|X_1}(x_2 \mid x_1) = \int f_{X_2|\Theta}(x_2 \mid \theta) f_{\Theta|X_1}(\theta \mid x_1) d\theta.$$
 (7)

Suppose that  $X_1$  and  $X_2$  are independent given  $\Theta = \theta$ , coming from

$$\{X_i \mid \Theta = \theta\}_{i=1}^2 \sim \text{Bin}(N_i, \theta)$$

i.e., the joint likelihood for measurements  $x_1$  and  $x_2$  is

$$\begin{aligned} p_{X_1,X_2|\Theta}(x_1,x_2 \mid \theta) &= p_{X_1|\Theta}(x_1 \mid \theta) p_{X_2|\Theta}(x_2 \mid \theta) \\ &= \binom{N_1}{x_1} \theta^{x_1} (1-\theta)^{N_1-x_1} \binom{N_2}{x_2} \theta^{x_2} (1-\theta)^{N_2-x_2} \mathbb{1}_{(0,1)}(\theta). \end{aligned}$$

As we have seen earlier in handout introBayes, the class of conjugate prior pdfs for  $\Theta$  under this data model is

$$f_{\Theta}(\theta) = \text{Beta}(\theta \mid \alpha, \beta)$$
$$\propto \theta^{\alpha - 1} (1 - \theta)^{\beta - 1} \mathbb{1}_{(0, 1)}(\theta).$$

\*The posterior pdf of  $\theta$  is

$$f_{\Theta|X_1,X_2}(\theta \mid x_1,x_2) \propto p_{X_1,X_2|\Theta}(x_1,x_2 \mid \theta) f_{\Theta}(\theta)$$
$$\propto \theta^{x_1+x_2+\alpha-1} (1-\theta)^{N_1+N_2-x_1-x_2+\beta-1} \mathbb{1}_{(0,1)}(\theta)$$

which is the kernel of the Beta $(x_1 + x_2 + \alpha, \beta + N_1 - x_1 + N_2 - x_2)$  pdf, see the table of distributions. Hence,

$$f_{\Theta|X_1,X_2}(\theta \mid x_1,x_2) = \text{Beta}(\theta \mid x_1 + x_2 + \alpha, \beta + N_1 - x_1 + N_2 - x_2).$$

The posterior pdf  $f_{\Theta|X_1}(\theta \mid x_1)$  given only  $X_1 = x_1$ . Now,

$$f_{\Theta|X_1}(\theta \mid x_1) \propto p_{X_1|\Theta}(x_1 \mid \theta) f_{\Theta}(\theta)$$
$$\propto \theta^{x_1 + \alpha - 1} (1 - \theta)^{N_1 - x_1 + \beta - 1} \mathbb{1}_{(0,1)}(\theta)$$

which is the kernel of the Beta( $x_1 + \alpha, \beta + N_1 - x_1$ ) pdf; therefore,

$$f_{\Theta|X_1}(\theta \mid x_1) = \text{Beta}(\theta \mid x_1 + \alpha, \beta + N_1 - x_1).$$

\*Predicting  $X_2$  after observing  $X_1 = x_1$ . Since  $X_1$  and  $X_2$  are independent dent given  $\Theta = \theta$ , we apply (7):

$$p_{X_{2}|X_{1}}(x_{2}|x_{1}) = \int_{0}^{1} p_{X_{2}|\Theta}(x_{2}|\theta) f_{\Theta|X_{1}}(\theta|x_{1}) d\theta$$

$$= \binom{N_{2}}{x_{2}} \frac{\Gamma(\alpha + \beta + N_{1})}{\Gamma(x_{1} + \alpha)\Gamma(\beta + N_{1} - x_{1})} \qquad c = \frac{\Gamma(x_{1} + x_{2} + \alpha)\Gamma(\beta + N_{1} - x_{1} + N_{2} - x_{2})}{\Gamma(\alpha + \beta + N_{1} + N_{2})}$$

$$\cdot \underbrace{\int_{0}^{1} \theta^{x_{1} + x_{2} + \alpha - 1} (1 - \theta)^{\beta + N_{1} - x_{1} + N_{2} - x_{2} - 1} d\theta}_{c}$$

$$= \binom{N_{2}}{x_{2}} \frac{\Gamma(\alpha + \beta + N_{1})}{\Gamma(x_{1} + \alpha)\Gamma(\beta + N_{1} - x_{1})} \frac{\Gamma(x_{1} + x_{2} + \alpha)\Gamma(\beta + N_{1} - x_{1} + N_{2} - x_{2})}{\Gamma(\alpha + \beta + N_{1} + N_{2})}$$

which is the predictive probability mass function (pmf) of  $X_2$  given  $X_1 = x_1$ .

- **\*** Comments:
  - Here, we have used the fact that Beta( $\alpha$ ,  $\beta$ ) pdf of a random variable  $\Theta$  has the following form (see the distribution table):

$$f_{\Theta}(\theta) = \underbrace{\frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)}}_{\theta} \quad \theta^{\alpha - 1}(1 - \theta)^{\beta - 1}$$

normalizing constant

which implies

$$\int_0^1 \theta^{\alpha-1} (1-\theta)^{\beta-1} d\theta = \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha+\beta)}.$$

DC Level Estimation in AWGN with Known Variance: Predictive Distribution

Suppose that we have collected *N* independent, identically distributed (i.i.d.) observations  $(X[n])_{n=0}^{N-1}$  given  $\theta$  and that they follow

$$\{X[n] \mid \Theta = \theta\} \sim \mathcal{N}(\theta, \sigma^2).$$

We wish to predict the next observation, denoted by  $X_{\star}$ , which is independent of  $(X[n])_{n=0}^{N-1}$  given  $\Theta = \theta$ , and follows

$$\{X_{\star} \mid \Theta = \theta\} \sim \mathcal{N}(\theta, \sigma^2).$$
 (8)

Then,  $X_{\star}$  and

$$\bar{X} = \frac{1}{N} \sum_{n=0}^{N-1} X[n]$$

are also independent given  $\Theta = \theta$ ; consequently,

$$f_{X_{\star},\Theta|\bar{X}}(x_{\star},\theta\,|\,\bar{x}) = f_{X_{\star}|\Theta}(x_{\star}\,|\,\theta) f_{\Theta|\bar{X}}(\theta\,|\,\bar{x}). \tag{9}$$

Based on (9), we have

$$\mathbf{E}_{X_{\star},\Theta|\bar{X}}(\cdot\,|\,\bar{x}) = \mathbf{E}_{\Theta|\bar{X}}\big[\mathbf{E}_{X_{\star}|\Theta}(\cdot\,|\,\Theta)\,|\,\bar{x}\big]. \tag{10}$$

Recall that  $\bar{x}$  is a sufficient statistic for  $\theta$  based on  $x = (x[n])_{n=0}^{N-1}$ ; then, by sufficiency,

$$f_{\Theta|X}(\theta \mid x) = f_{\Theta|\overline{X}}(\theta \mid \overline{x}).$$

Our predictive distribution is

$$f_{X_{\star}|X}(x_{\star} \mid \mathbf{x}) = f_{X_{\star}|\overline{X}}(x_{\star} \mid \overline{x})$$

$$= \int \underbrace{f_{X_{\star}|\Theta}(x_{\star} \mid \vartheta) f_{\Theta|\overline{X}}(\vartheta \mid \overline{x})}_{f_{X_{\star},\Theta|\overline{X}}(x_{\star},\vartheta \mid \overline{x})} d\vartheta. \tag{11}$$

Focus on (9):

$$f_{X_{\star},\Theta|\bar{X}}(x_{\star},\theta\mid\bar{x}) = \underbrace{f_{X_{\star}|\Theta}(x_{\star}\mid\theta)}_{\mathcal{N}(x_{\star}\mid\theta,\sigma^{2})} \underbrace{f_{\Theta|\bar{X}}(\theta\mid\bar{x})}_{\mathcal{N}(\theta\mid\mu_{N},\tau_{N}^{2})}$$

and, therefore,

$$f_{X_{\star},\Theta|\overline{X}}(x_{\star},\theta\mid\overline{x}) \propto \exp\left[-\frac{1}{2\sigma^{2}}(x_{\star}-\theta)^{2}\right] \exp\left\{-\frac{1}{2\tau_{N}^{2}}\left[\theta-\mu_{N}(\overline{x})\right]^{2}\right\}$$

which is the kernel of a bivariate Gaussian pdf. Hence,  $f_{X_{\bullet},\Theta|\bar{X}}(x_{\star},\theta|\bar{x})$ is a bivariate Gaussian pdf.

WE wish to find the predictive pdf  $f_{X_{\star}|\bar{X}}(x_{\star}|\bar{x})$ .

Integrating  $\theta$  out<sup>4</sup> in (11) is easy, see handout revprob. Since we know that the predictive pdf  $f_{X_{\star}|\bar{X}}(x_{\star}|\bar{x})$  must be Gaussian, we just need to find its mean:

$$\begin{array}{rcl} \mathbf{E}_{X_{\star}|\bar{X}}(X_{\star}\,|\,\bar{x}) & = & \mathbf{E}_{X_{\star},\Theta|\bar{X}}(X_{\star}\,|\,\bar{x}) \\ & \stackrel{\text{iter. exp.}}{=} & \mathbf{E}_{\Theta|\bar{X}}\big[\mathbf{E}_{X_{\star}|\Theta}(X_{\star}\,|\,\Theta)\,|\,\bar{x}\big] \\ & \stackrel{\text{see (8)}}{=} & \mathbf{E}_{\Theta|\bar{X}}(\Theta\,|\,\bar{x}) \\ & = & \mu_{N}(\bar{x}) \end{array}$$

see handout introBayes where we

$$f_{\Theta|\bar{X}}(\theta \mid \bar{x}) = \mathcal{N}(\theta \mid \mu_N(\bar{x}), \tau_N^2)$$

$$\mu_N(\bar{x}) = \frac{(N/\sigma^2)\bar{x} + (1/\tau_0^2)\mu_0}{N/\sigma^2 + 1/\tau_0^2}$$
$$\frac{1}{\tau_N^2} = \frac{N}{\sigma^2} + \frac{1}{\tau_0^2}.$$

 $^4$  i.e., marginalizing with respect to heta

and variance

$$\begin{aligned} \operatorname{var}_{X_{\star}|\overline{X}}(X_{\star} \mid \overline{x}) &= \operatorname{E}_{\Theta|\overline{X}} \left[ \underbrace{\operatorname{var}_{X_{\star}|\Theta}(X_{\star} \mid \Theta)}_{\sigma^{2}, \operatorname{see}(8)} \mid \overline{x} \right] \\ &+ \operatorname{var}_{\Theta|\overline{X}} \left[ \underbrace{\operatorname{E}_{X_{\star}|\Theta}(X_{\star} \mid \Theta)}_{\Theta, \operatorname{see}(8)} \mid \overline{x} \right] \\ &= \sigma^{2} + \tau_{N}^{2}. \end{aligned}$$

use the law of conditional variances based on (10)

Hence,

$$f_{X_{\star}|\overline{X}}(x_{\star}|\overline{x}) = \mathcal{N}(x_{\star}|\mu_{N}(\overline{x}), \sigma^{2} + \tau_{N}^{2}).$$

## Acronyms

i.i.d. independent, identically distributed. 3 pdf probability density function. 1-4 pmf probability mass function. 3

### References

Gelman, A., J. B. Carlin, H. S. Stern, David B. Dunson, Aki Vehtari, and D. B. Rubin (2014). Bayesian Data Analysis. 3rd ed. Boca Raton, FL: Taylor & Francis (cit. on p. 1).