

# Data Structures & Algorithms

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*Six ways to make people like you – Dale Carnegie*

- 1. Become genuinely interested in other people*
- 2. Smile*

# Recap

- What is sorting?
- Why learn about sorting?
- Properties of sorting algorithms
- Three simple sorting algorithms – Identifying their best and worst cases and time complexities

# Objectives

- What is a Tree (as a data structure)?
- Learn about different types of trees and the associated properties, definitions and terminologies
- Special emphasis on Binary Search Trees
  - ❖ How does a BST work?
  - ❖ How to traverse in a BST?
  - ❖ Time complexity of a BST

# Tree

- A tree combines the advantages of two other data structures:
  - ❖ An ordered array
  - ❖ A linked list

# Ordered Array

- Quick to search for a particular element, using binary search
- On the other hand, insertions are slow
  - ❖ First need to find where the object will go
  - ❖ Then move all the objects with greater keys up one space to make the room

# Linked List

- Insertions and deletions are quick
  - ❖ Simply requires changing a few constant number of references
- On the other hand, finding a particular element is slow
  - ❖ Must start at the beginning of the linked list
  - ❖ Visit each element until you find the one you're looking for
- What if we made the linked list ordered? Will it help?

# Trees to Rescue

- It would be nice to have a data structure
  - ❖ With quick insertions and deletions of a linked list
  - ❖ And, the quick searching of an ordered array

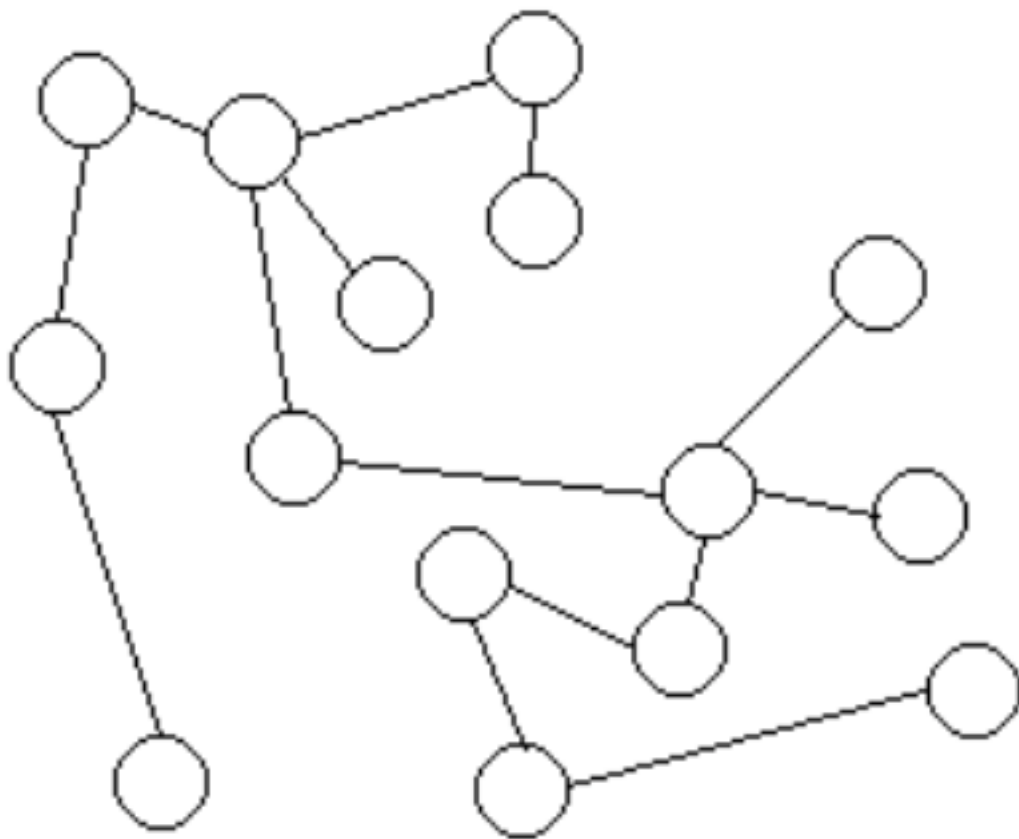
# Trees to Rescue

- Trees provide both these characteristics
- Our main focus will be a **binary tree**
- But let's first start discussing trees in general



# Tree

- Consists of nodes connected by edges



Node

(a.k.a. vertex) a data element in the tree

## Edge

(a.k.a. branch, or link) a connection between two nodes

Empty tree

has zero nodes

## Size

the size of a tree is the number of nodes

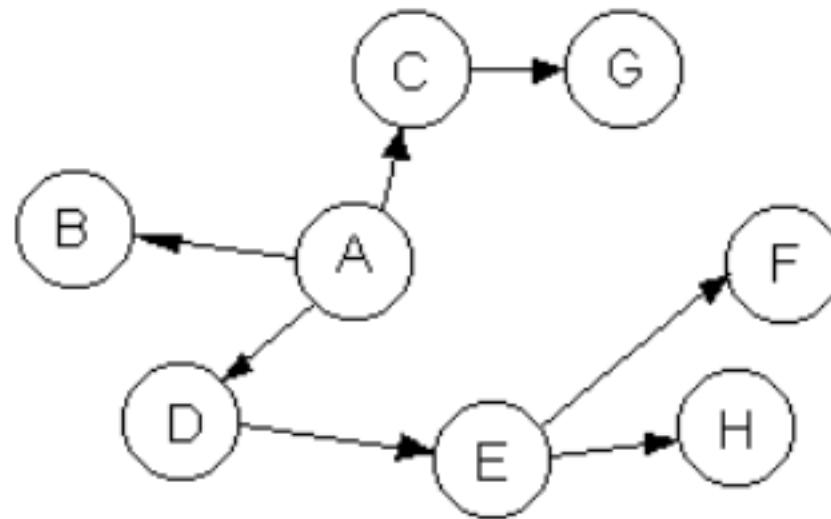
## Path

a sequence  $n_0 e_1 n_1 e_2 n_2 \dots e_k n_k$  where  $k \geq 0$  and  $e_i$  connects  $n_{i-1}$  and  $n_i$ .

# Oriented Trees

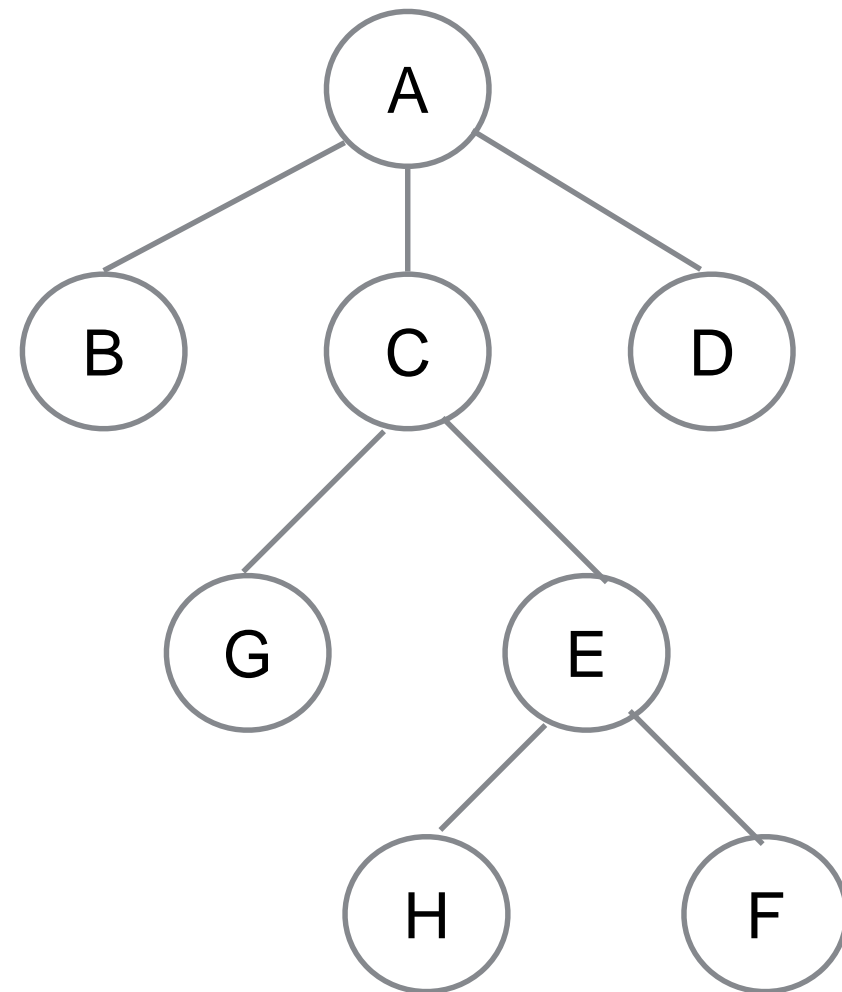
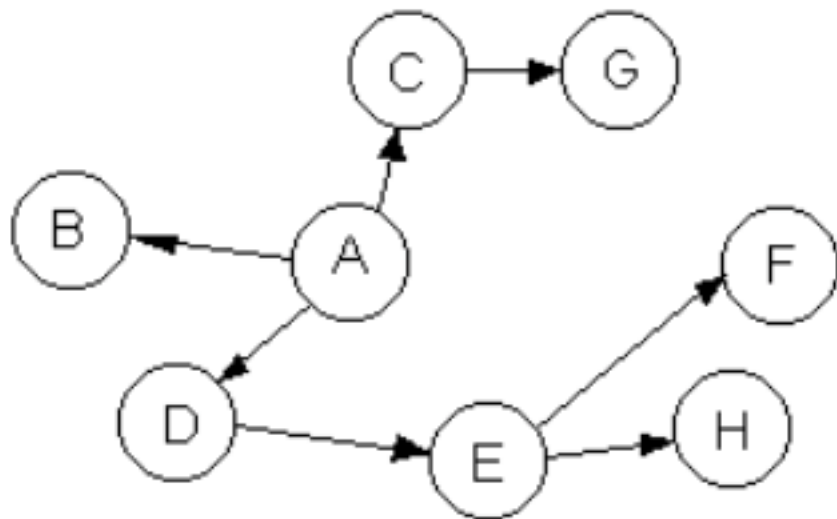
# Oriented Trees

- A tree used to represent a hierarchical data.
- All edges are directed outward from a distinguished node called the root node



# Oriented Trees

- Usually drawn with the root at the top, all edges pointing downward, the arrows are thus redundant and are often omitted.



# Definitions

## Parent

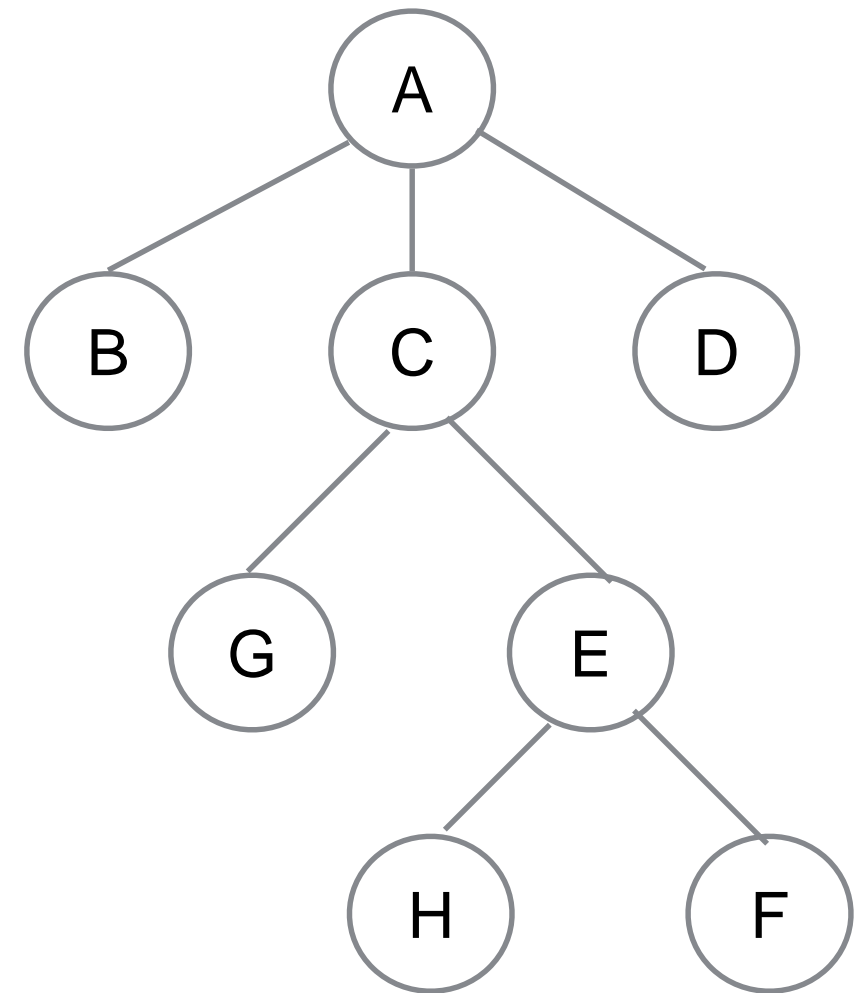
A is the parent of B and C and D

## Children

The children of A are B and C and D

## Siblings

B and C are siblings



# Definitions

## Root node

The only node without a parent

## Leaf node

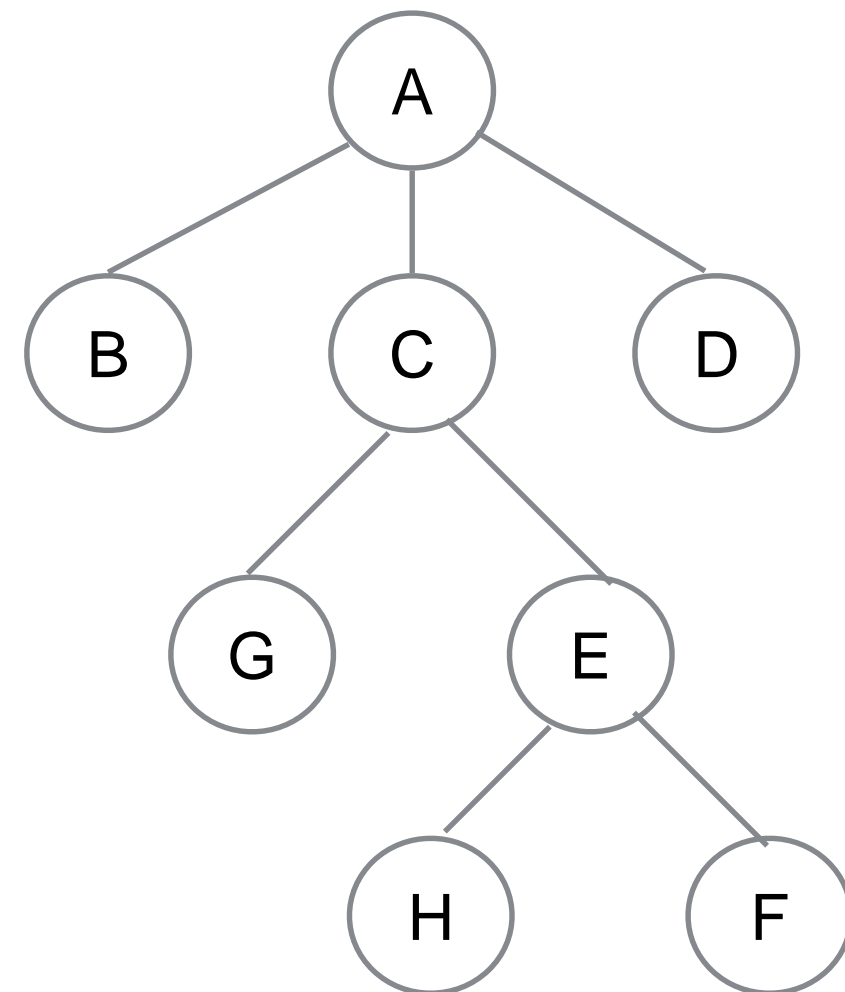
A node without children

## Degree(n)

The number of children of n

## Degree(t)

The greatest degree of the nodes in t



# Definitions

## **Level(n)**

$\text{Level}(n) = \text{if } n \text{ is the root then } 0 \text{ else } 1 + \text{Level}(\text{Parent}(n))$

## **Depth(n)**

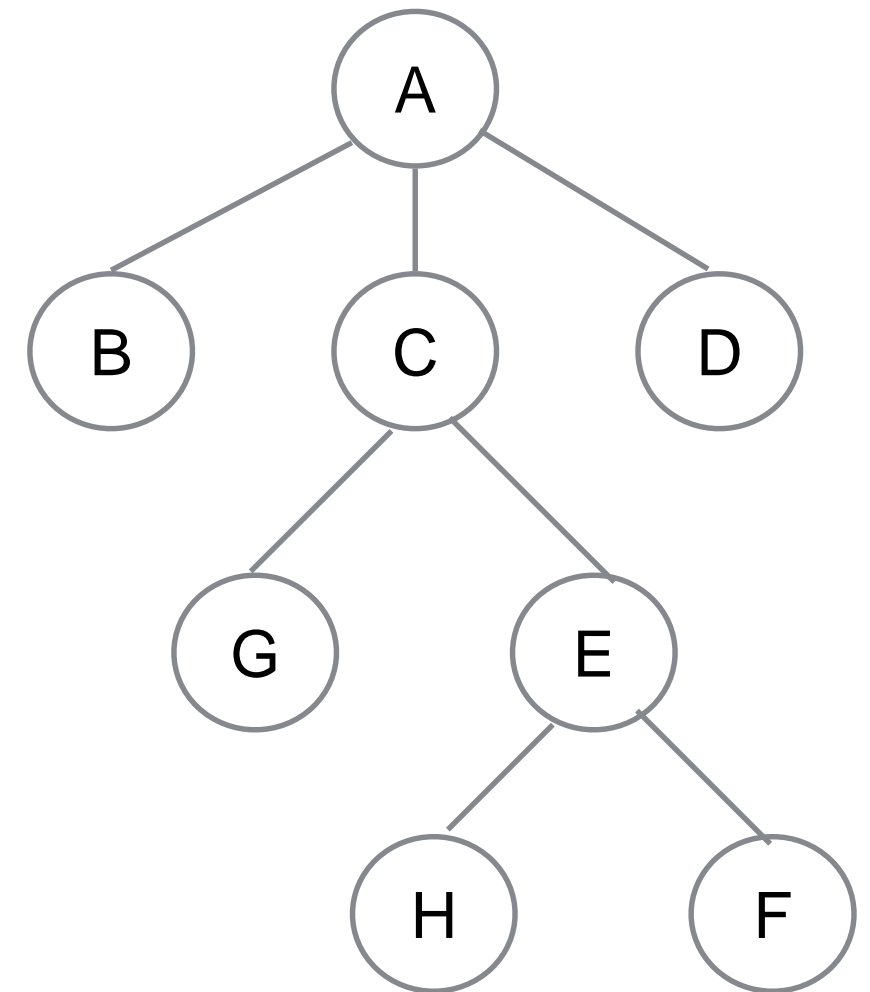
Same as  $\text{Level}(n)$

## **Height(n)**

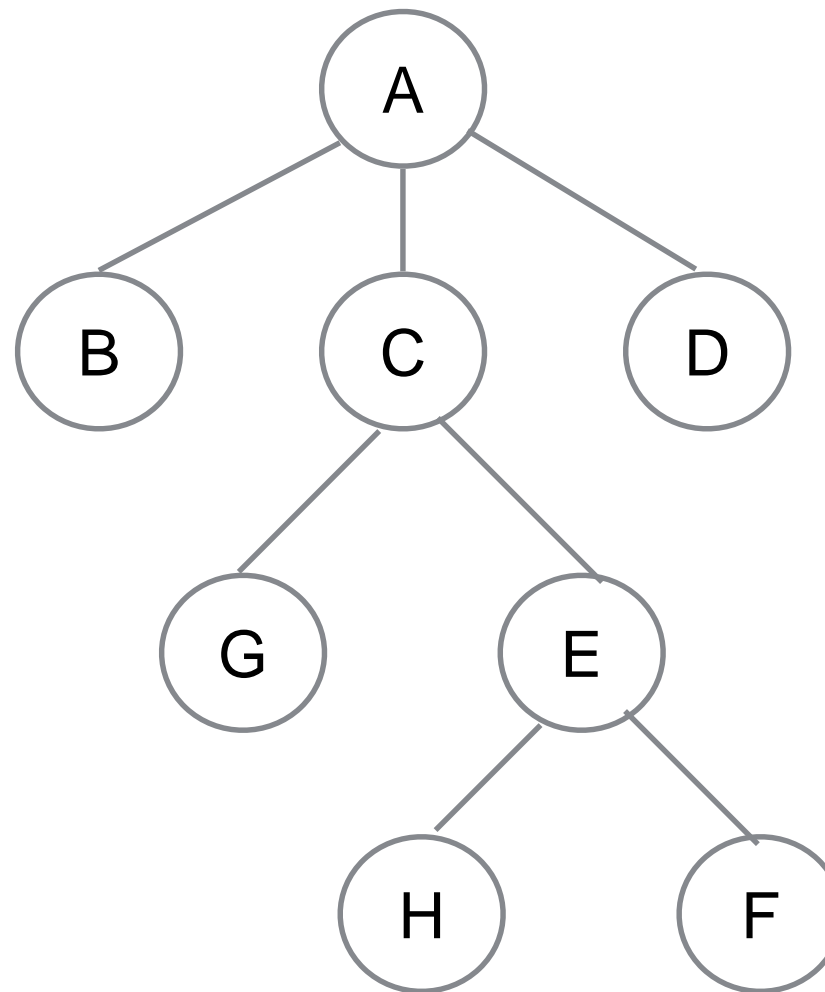
Maximum length over all paths from  $n$  to a leaf

## **Height(t)**

The height of  $t$ 's root node



# Definitions



## **Ancestors(n)**

$\text{Ancestors}(n) = \text{if } n \text{ is the root then } \{ \} \text{ else } \{ \text{Parent}(n) \} \text{ union } \text{Ancestors}(\text{Parent}(n))$

## **Descendants(n)**

The set of all nodes reachable from  $n$  following the edges leaving it in the direction of the arrows



# Definitions

## **PathLength(t)**

The sum of all the depths of all the nodes in t

## **Empty Tree**

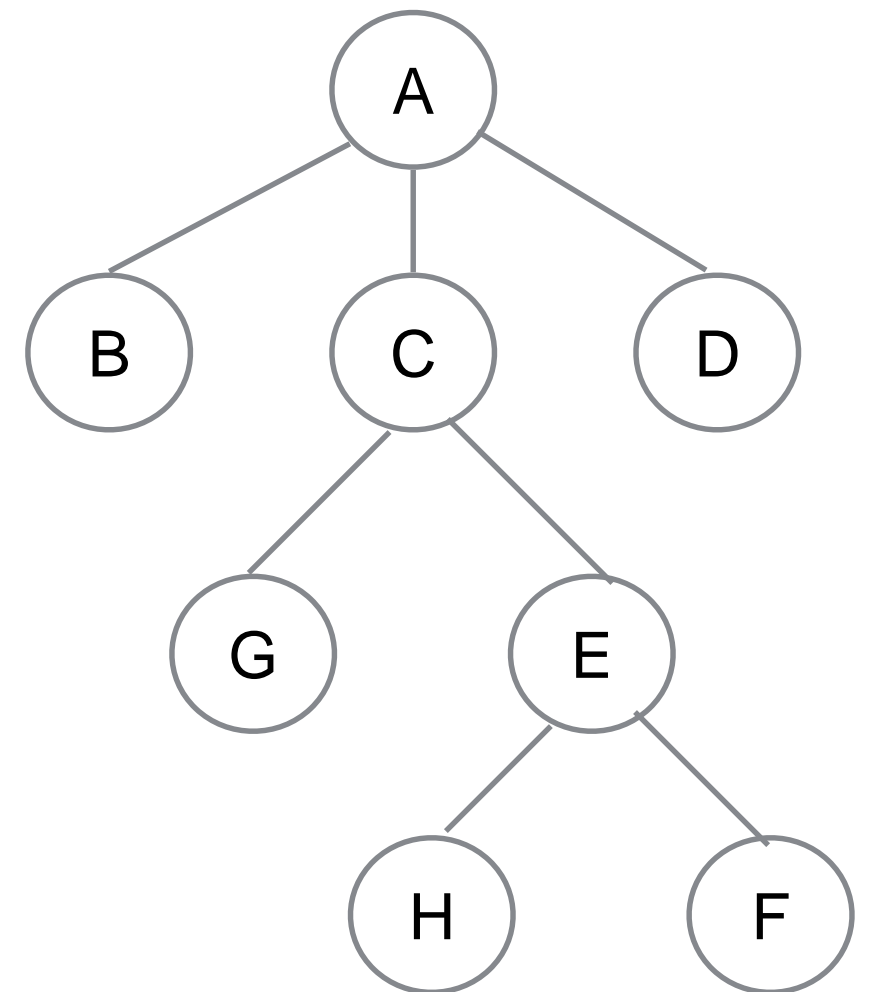
A tree with zero nodes

## **Singleton Tree**

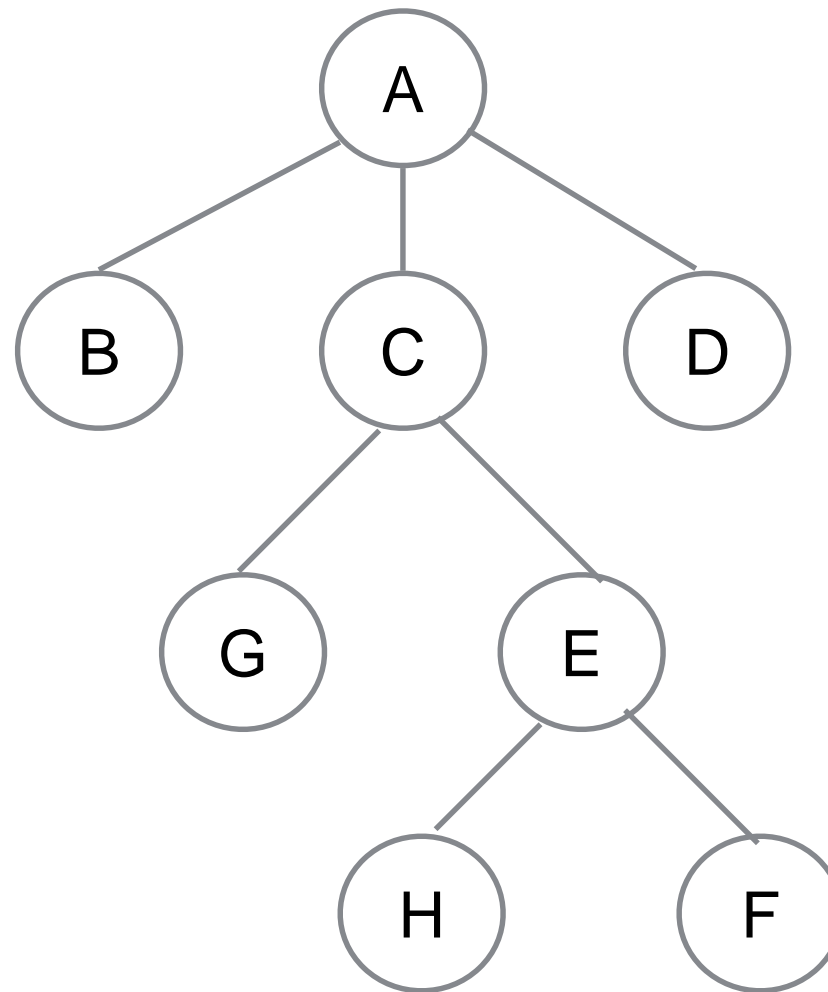
A tree with only one node

## **Subtree(n)**

The subtree rooted at n



# Definitions



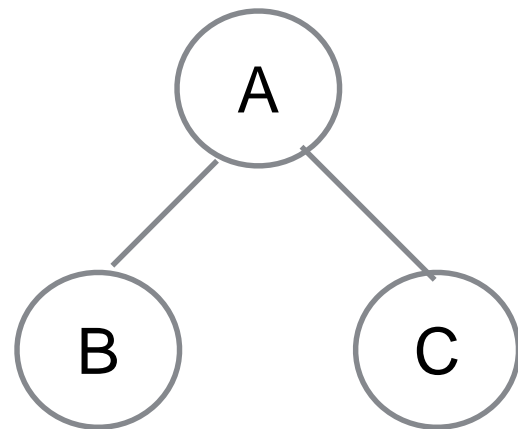
## **k-node**

A node with  $k$  children. A 0-node is a leaf. A 1-node has exactly one child. A 2-node has exactly two children. Etc.

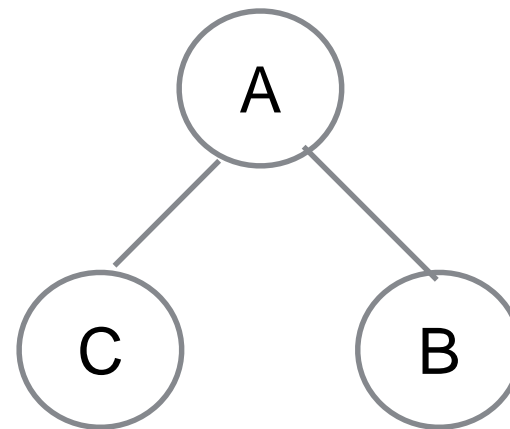
# Ordered Trees

# Ordered Trees

- An oriented tree in which the children of a node are somehow **ordered**.



T1



T2

If T1 and T2 are ordered trees then  $T1 \neq T2$ ,  
otherwise  $T1 = T2$

# Types of Ordered Trees

- Fibonacci Tree
- Binomial tree
- k-ary Tree

# k-ary Trees

- A tree in which the children of a node appear at distinct index positions in  $0..k - 1$
- Maximum number of children for a node is  $k$

# Types of k-ary Trees

- 2-ary Trees, known as **Binary Trees**
- 3-ary Trees, known as **Ternary Trees**
- 1-ary Trees, known as **Lists**

# k-ary Tree Representation

```
class Node {
```

```
    private Object data;
```

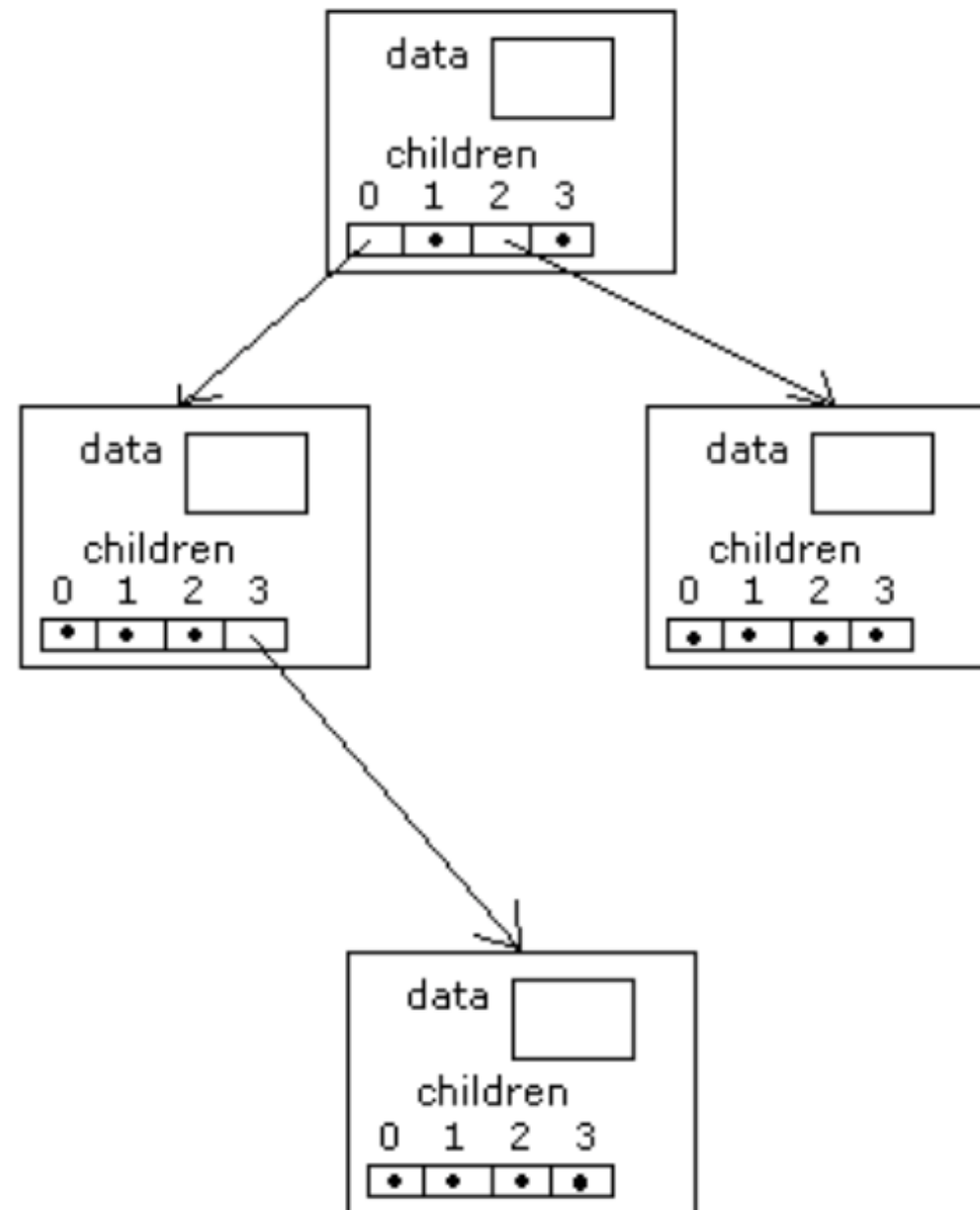
```
    private Node[] children;
```

```
    .
```

```
    .
```

```
    .
```

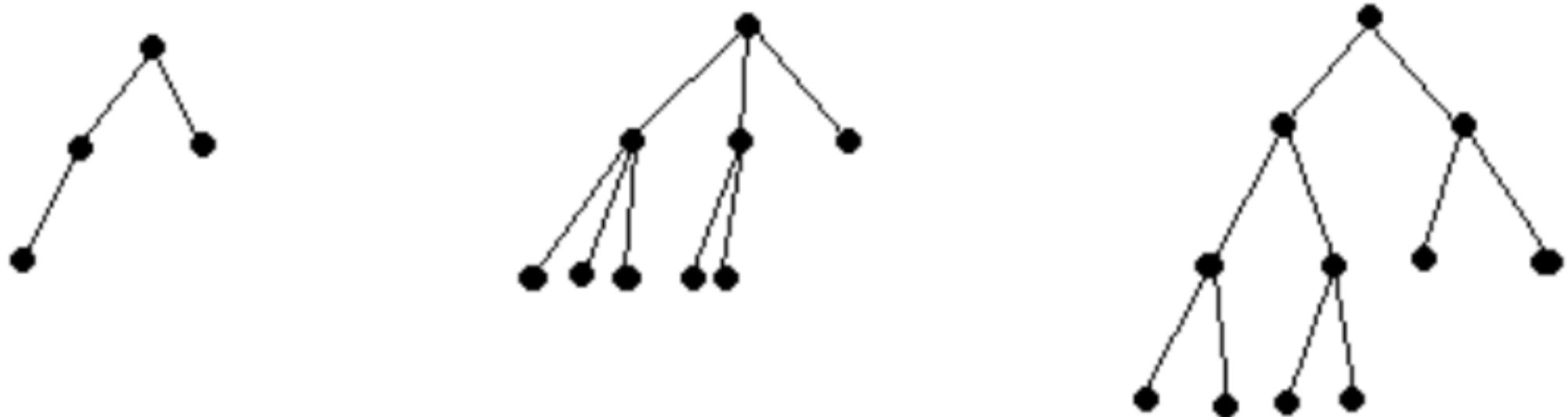
```
}
```





# Complete k-ary Trees

- ❖ Filled out on every level, except perhaps on the last one
- ❖ All nodes on the last level, should be as far to left as possible



*Complete trees can be packed into an array with no wasted space*

# Binary Tree

# Binary Tree

- A **binary tree**  $T$  of  $n$  nodes,  $n \geq 0$ ,
  - ❖ is either empty, if  $n = 0$
  - ❖ or consists of a root node  $u$  and two binary trees  $u(1)$  and  $u(2)$  of  $n_1$  and  $n_2$  nodes, respectively, such that  $n = 1 + n_1 + n_2$
- We say that  $u(1)$  is the **first or left subtree** of  $T$ , and  $u(2)$  is the **second or right subtree** of  $T$

# Binary Tree



External nodes - have no subtrees (referred to as leaf nodes)



Internal nodes - always have two subtrees

Figures mostly used for internal and external  
nodes

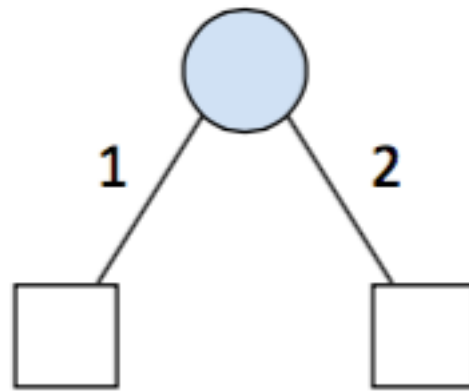
External nodes are usually omitted

# Binary Tree



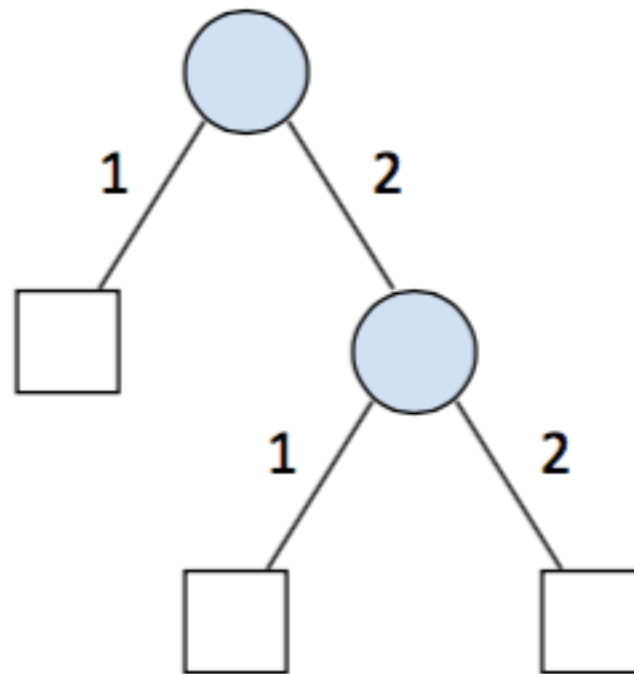
Binary Tree of zero nodes

# Binary Tree



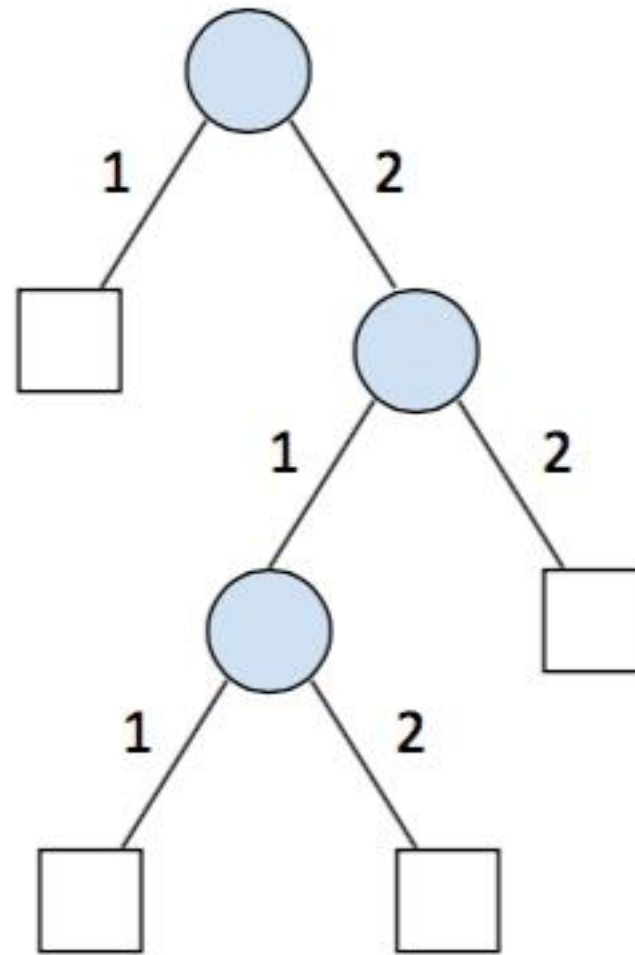
Binary Tree of 1 nodes

# Binary Tree



Binary Tree of 2 nodes

# Binary Tree



Binary Tree of 3 nodes

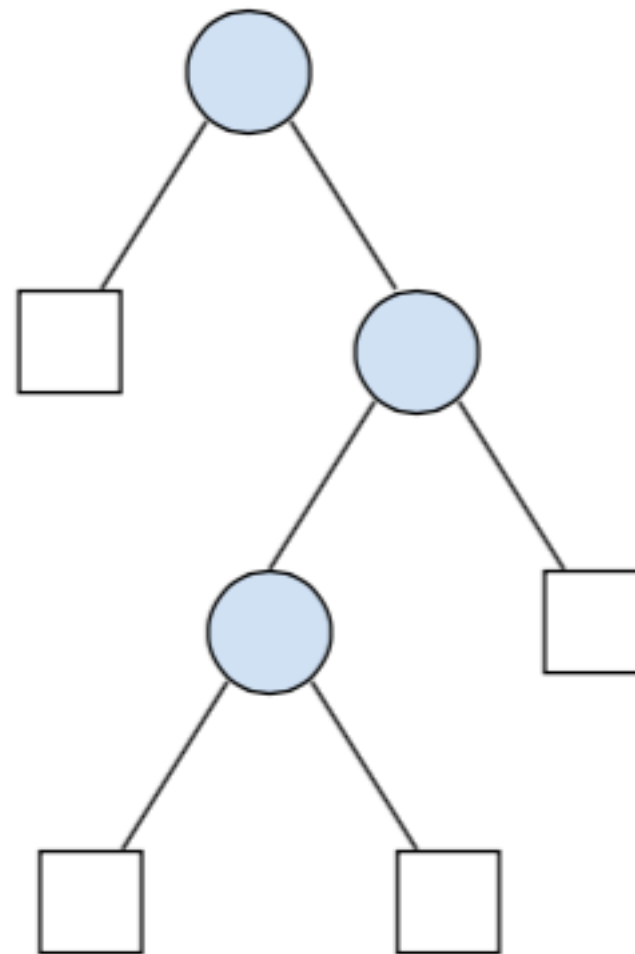


# Why Binary Trees

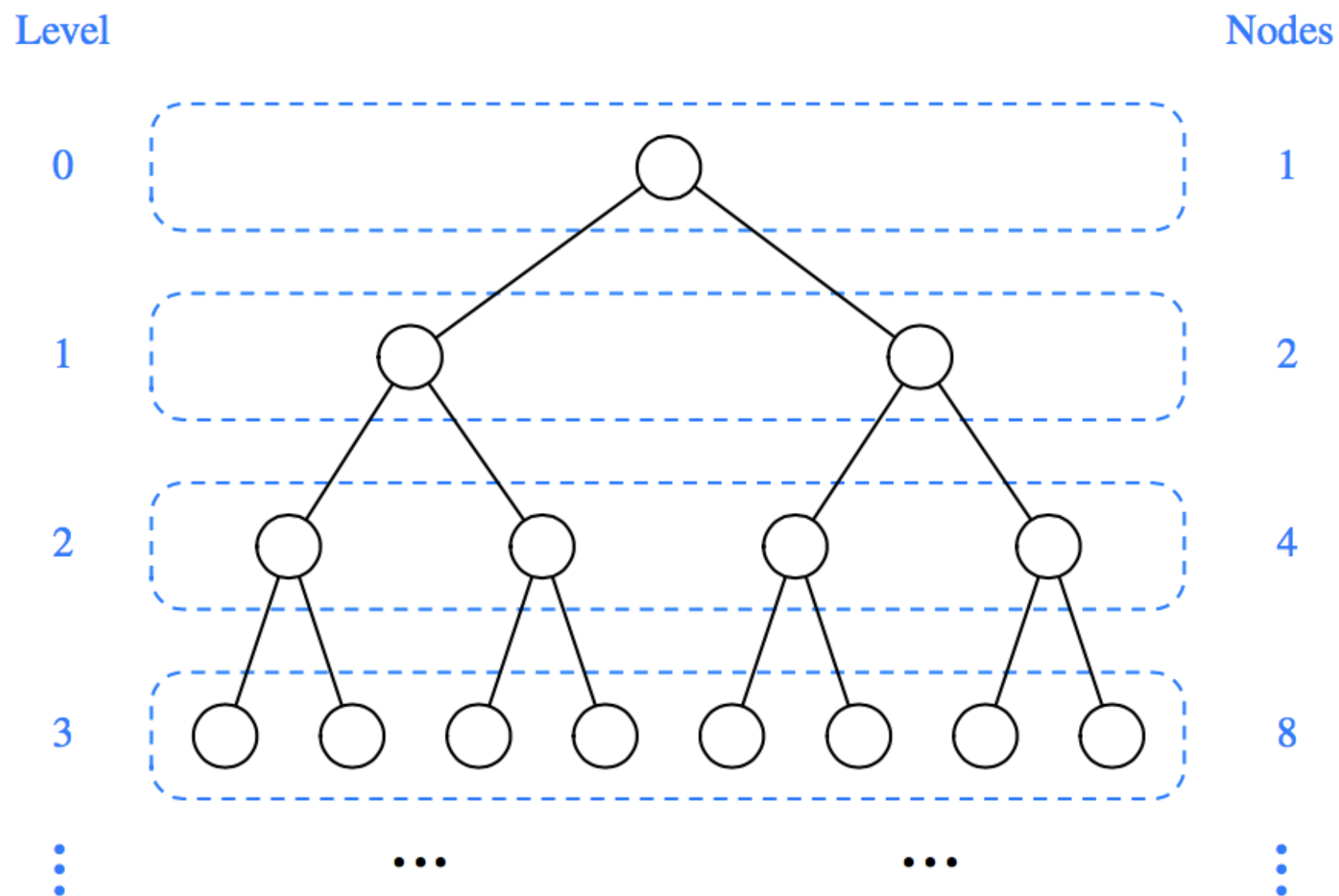
- Binary trees are a bit simpler and easier to understand than trees with a large or unbounded number of children
- Binary tree nodes have an elegant linked representation with "left" and "right" subtrees
- Binary trees form the basis for efficient representations of sets, dictionaries, and priority queues

# Binary Tree Properties

- Let  $T$  be a binary tree with  $n$  internal nodes,  $n \geq 0$ ,
- Then, the number of external nodes of  $T$  is  $n + 1$



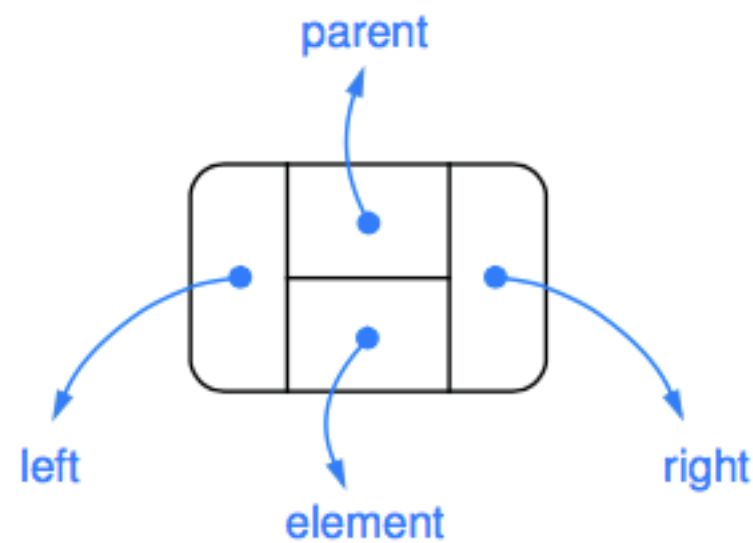
# Binary Tree Properties



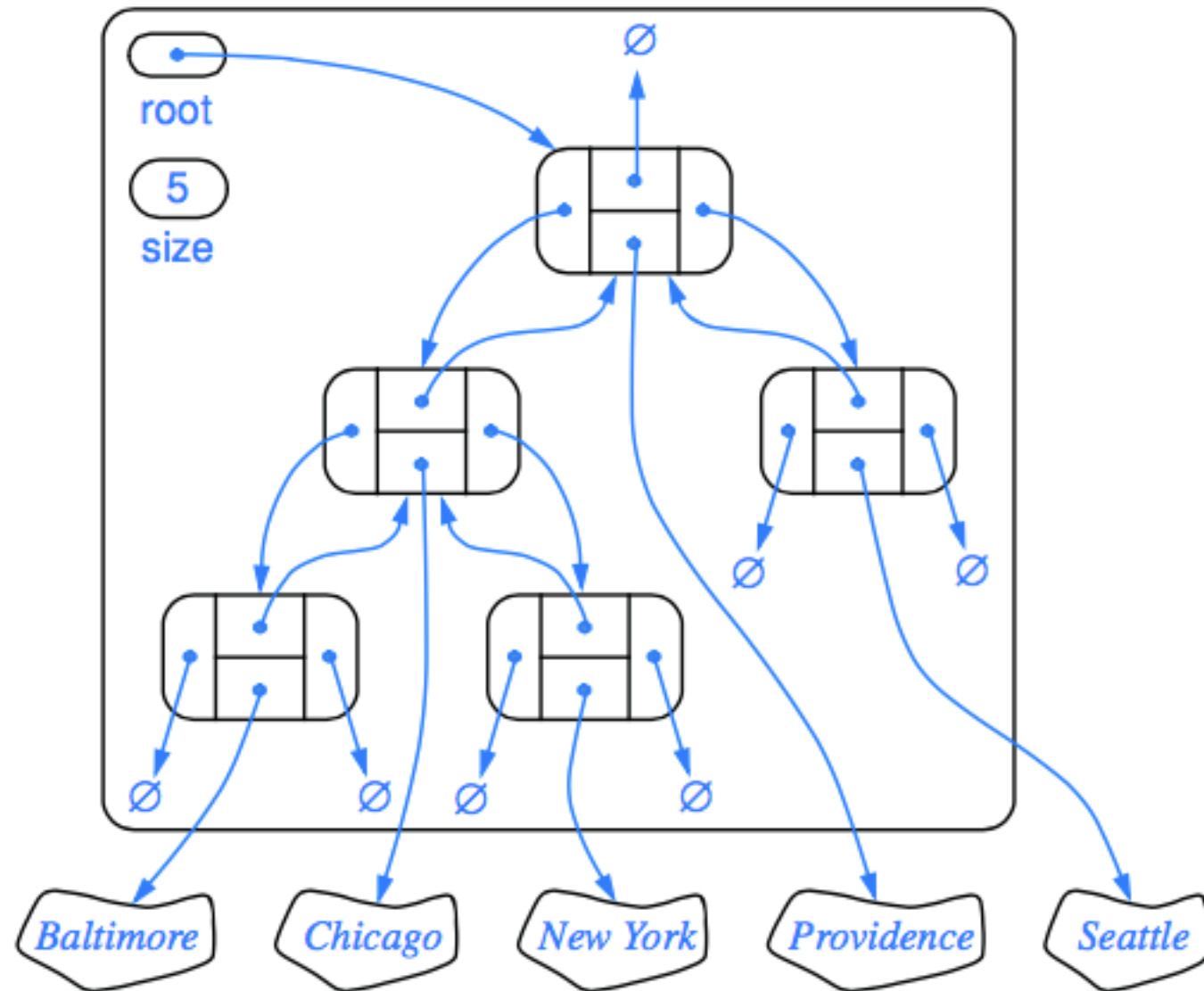
Maximum number of nodes in the levels of a binary tree

# Binary Tree Representations

- Linked Structure



(a)



(b)

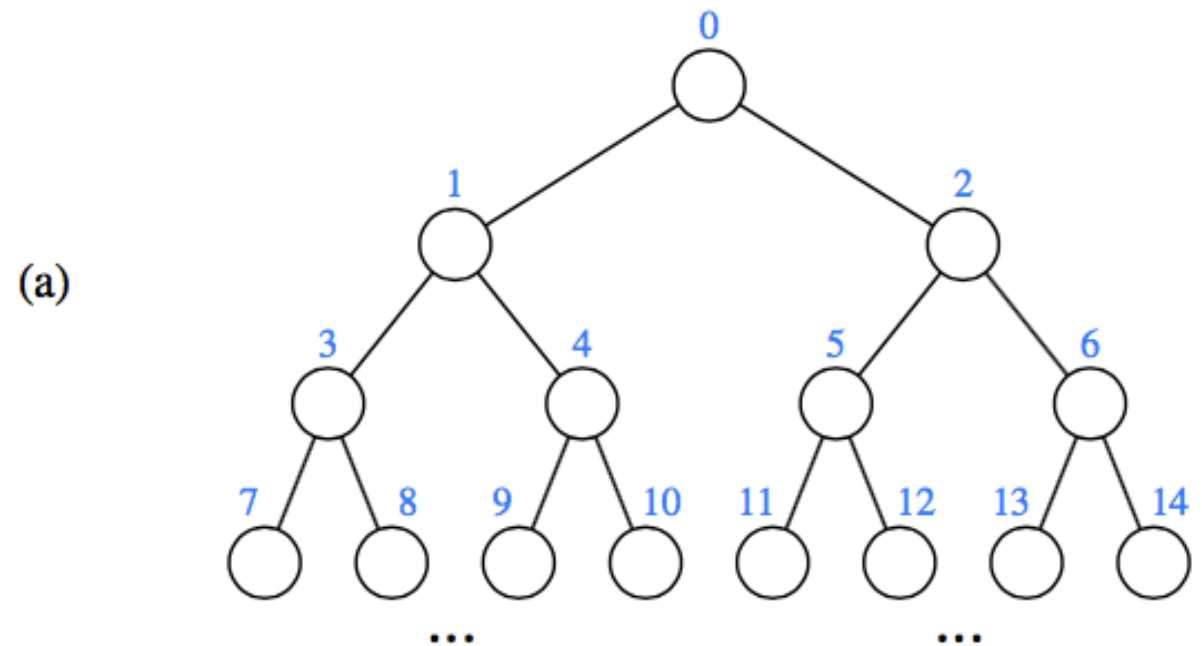
# Binary Tree Representations

- Array Based Structure
  - Requires a mechanism for numbering the positions of T
  - For every position  $p$  of T , let  $f(p)$  be the integer defined as follows
    - If  $p$  is the root of T, then  $f(p) = 0$
    - If  $p$  is the left child of position  $q$ , then  $f(p) = 2f(q) + 1$ .
    - If  $p$  is the right child of position  $q$ , then  $f(p) = 2f(q) + 2$ .

# Binary Tree Representations

- Array Based Structure

(a) general scheme



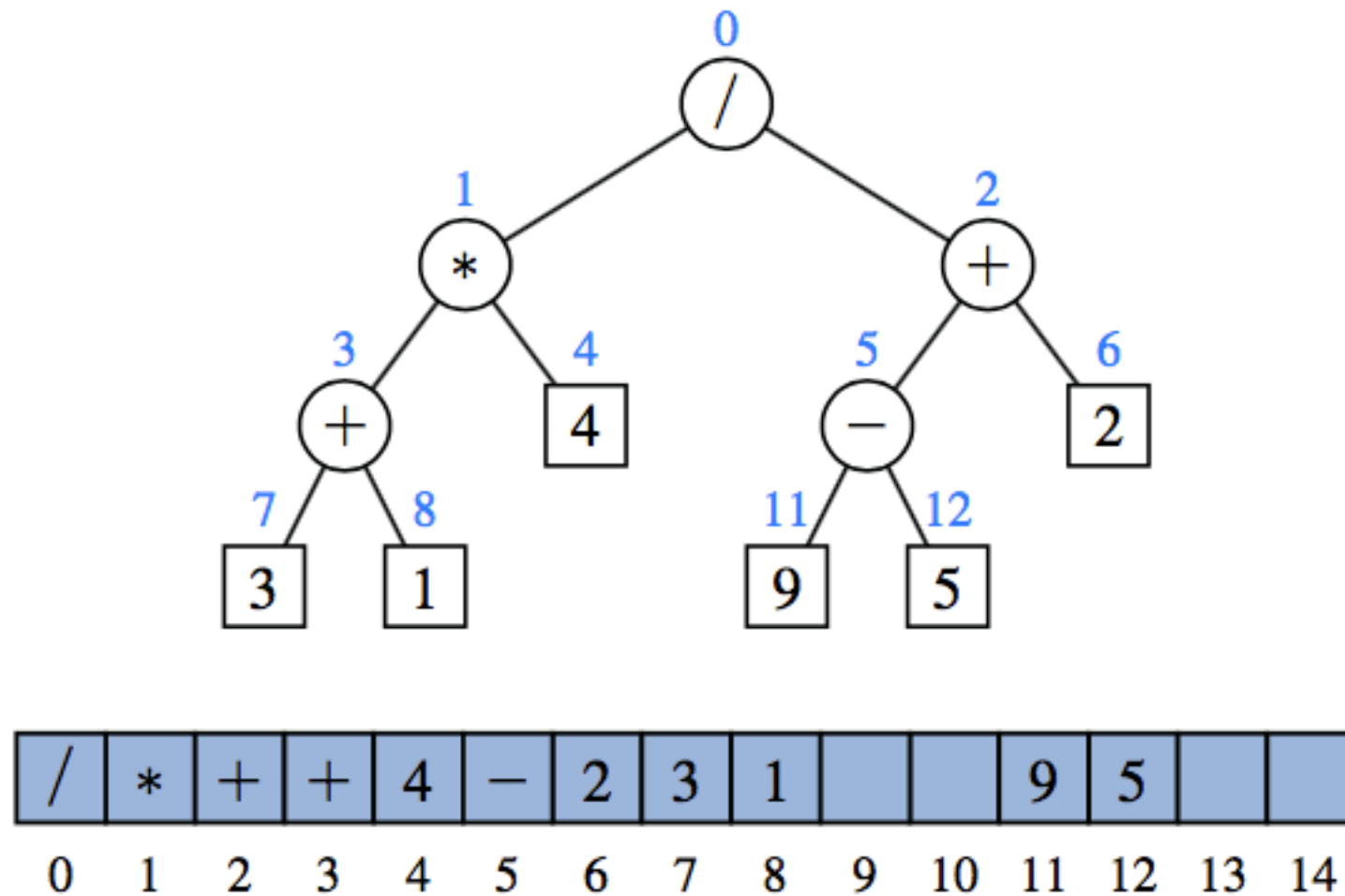
If  $p$  is the **root** of  $T$ , then  $f(p) = 0$

If  $p$  is the **left child** of position  $q$ , then  $f(p) = 2f(q) + 1$ .

If  $p$  is the **right child** of position  $q$ , then  $f(p) = 2f(q) + 2$ .

# Binary Tree Representations

- Array Based Structure



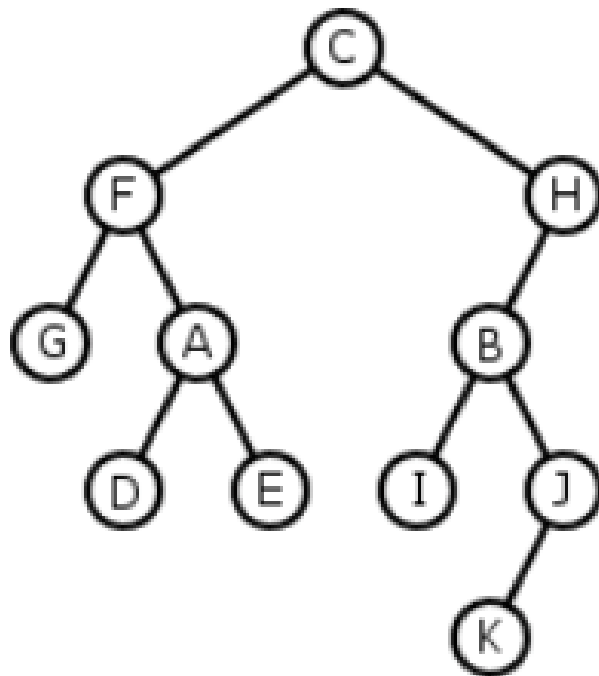
# Tree Traversal Algorithms



# Tree Traversal Algorithms

- A way of **accessing** or **visiting** all the nodes of T
- Preorder Traversal –
  - Visit the node, Preorder Left, Preorder Right
- Postorder Traversal
  - Postorder Left, Postorder Right, Visit the node
- Inorder Traversal
  - Inorder Left, Visit the node, Inorder Right

# Tree Traversals



- **Preorder:** C F G A D E H B I J K
- **Inorder:** G F D A E C I B K J H
- **Postorder:** G D E A F I K J B H C

# Preorder Traversal

**Algorithm** preorder( $p$ ):

```
perform the “visit” action for position  $p$     { this happens before any recursion }  
for each child  $c$  in children( $p$ ) do  
    preorder( $c$ )                                { recursively traverse the subtree rooted at  $c$  }
```

**Code Fragment 8.12:** Algorithm preorder for performing the preorder traversal of a subtree rooted at position  $p$  of a tree.

# Postorder Traversal

**Algorithm** postorder( $p$ ):

**for each child  $c$  in  $\text{children}(p)$  do**

```
postorder(c) { recursively traverse the subtree rooted at c }
```

perform the “visit” action for position  $p$       { this happens after any recursion }

**Code Fragment 8.13:** Algorithm `postorder` for performing the postorder traversal of a subtree rooted at position  $p$  of a tree.

# Inorder Traversal

**Algorithm** inorder( $p$ ):

**if  $p$  has a left child  $lc$  then**

$$\text{inorder}(lc)$$

{ recursively traverse the left subtree of  $p$  }

perform the “visit” action for position  $p$

**if  $p$  has a right child  $rc$  then**

$$\text{inorder}(rc)$$

{ recursively traverse the right subtree of  $p$  }

**Code Fragment 8.15:** Algorithm inorder for performing an inorder traversal of a subtree rooted at position  $p$  of a binary tree.

# Binary Search Trees

# Binary Search Trees

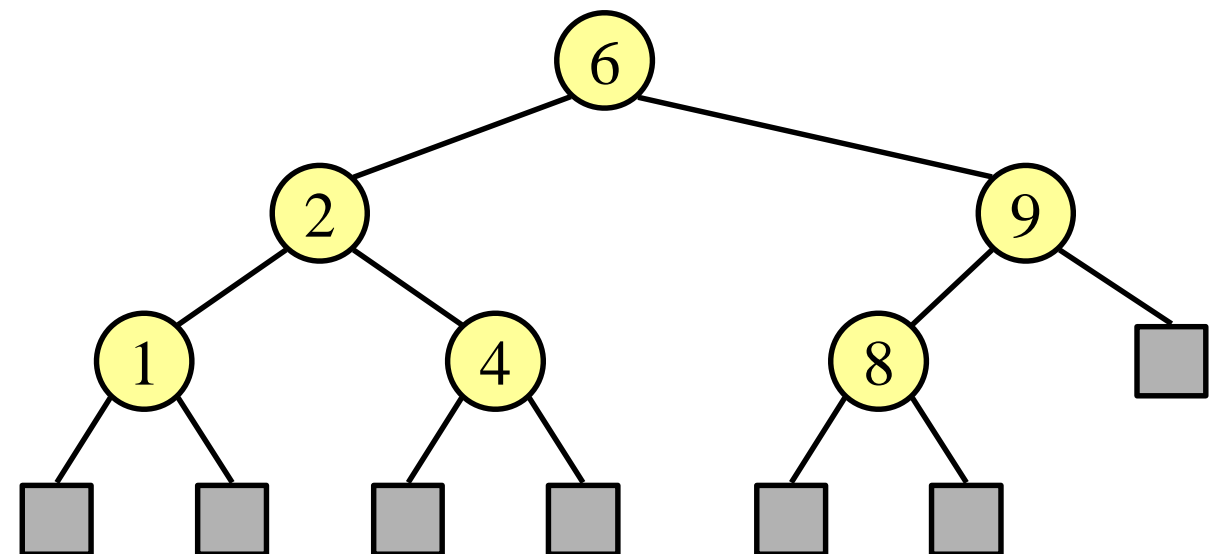
- A special type of binary tree
  - it represents information in an ordered format
  - A binary search tree is a binary tree in which every node holds a value  $>$  every value in its left subtree and  $<$  every value in its right subtree

Assuming no duplicates are allowed

# Binary Search Trees

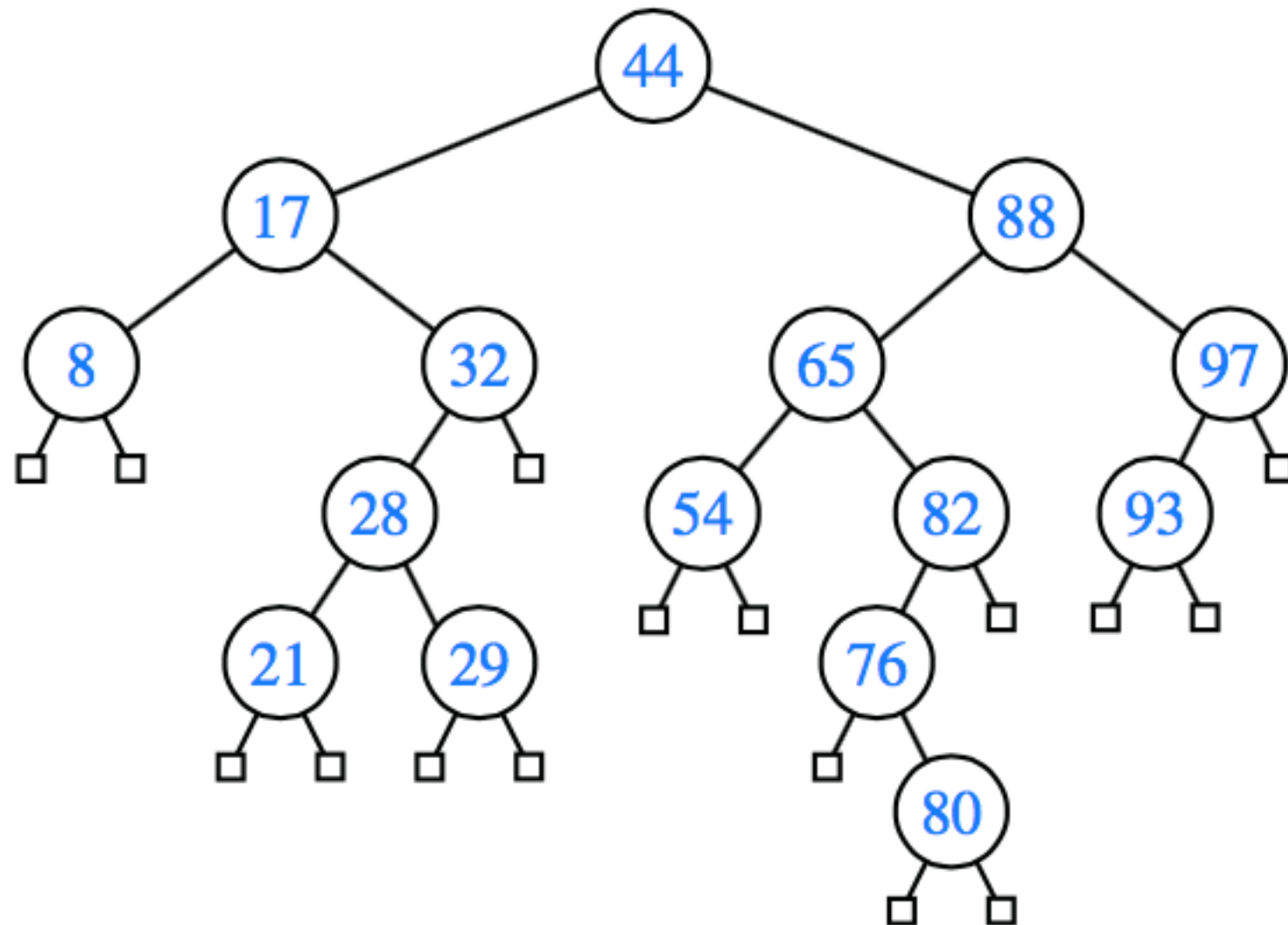
- Let  $u$ ,  $v$ , and  $w$  be three nodes such that  $u$  is in the left subtree of  $v$  and  $w$  is in the right subtree of  $v$ . We have
- An inorder traversal of a binary search tree visits the keys in increasing order

$$key(u) < key(v) < key(w)$$





# Example



- What is in the leftmost node?
- What is in the rightmost node?

# BST Operations

- A binary search tree is a special case of a binary tree
  - So, it has all the operations of a binary tree
- It also has **operations specific to a BST**:
  - **add** an element (requires that the BST property be maintained)
  - **remove** an element (requires that the BST property be maintained)
  - **Remove/find the maximum** element
  - **Remove/find the minimum** element

# Searching in a BST

- Why is it called a binary **search** tree?
- Data is stored in such a way, that it can be more **efficiently** found than in an ordinary binary tree

# Searching in a BST

- Algorithm to search for an item in a BST
  - Compare data item to the root of the (sub)tree
  - If data item = data at root, found
  - If data item < data at root, go to the left; if there is no left child, data item is not in tree
  - If data item > data at root, go to the right; if there is no right child, data item is not in tree

# Searching in a BST

**Algorithm** TreeSearch( $p$ ,  $k$ ):

**if**  $p$  is external **then**

**return**  $p$

{unsuccessful search}

**else if**  $k == \text{key}(p)$  **then**

**return**  $p$

{successful search}

**else if**  $k < \text{key}(p)$  **then**

**return** TreeSearch(left( $p$ ),  $k$ )

{recur on left subtree}

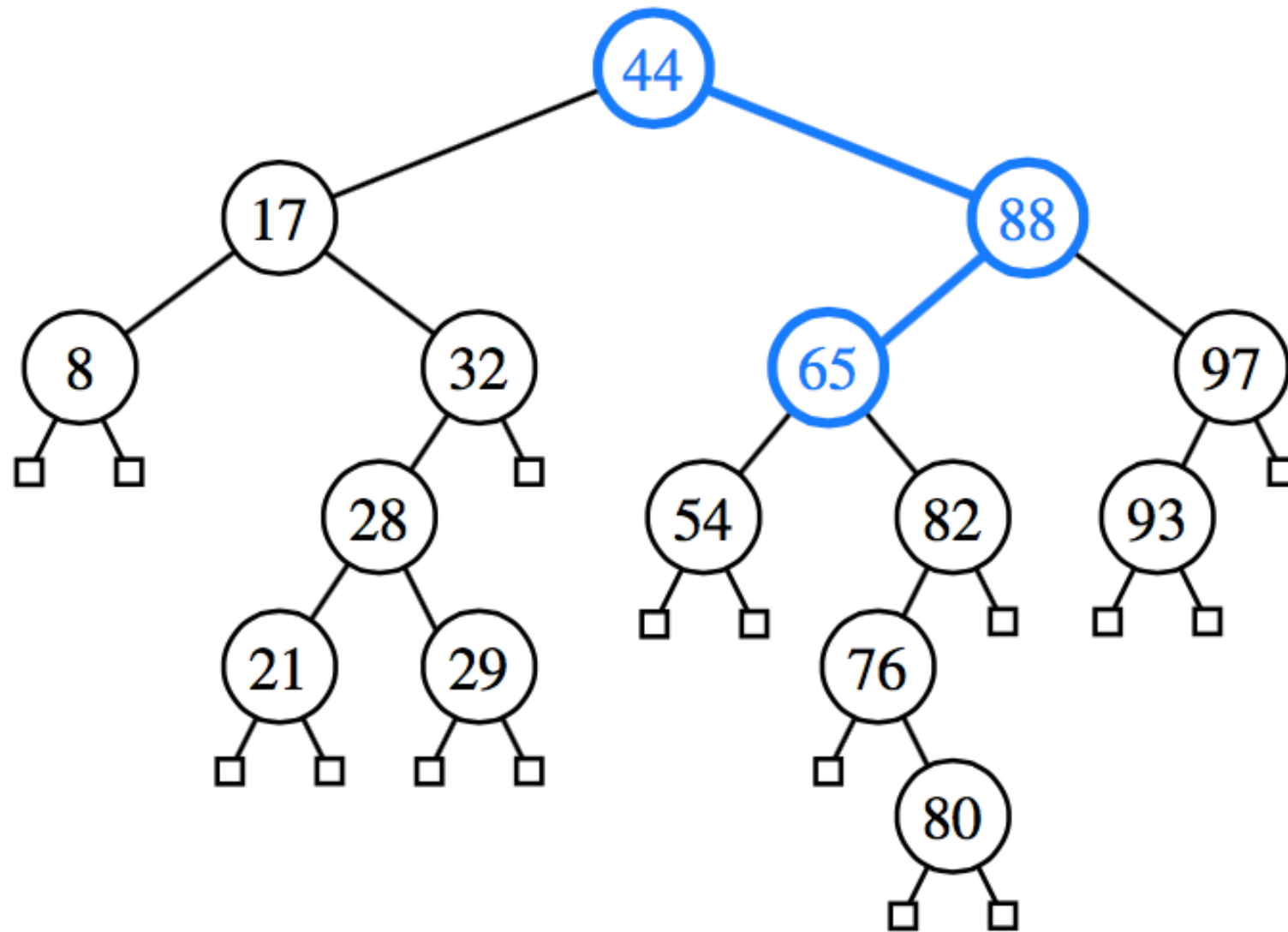
**else** {we know that  $k > \text{key}(p)$ }

**return** TreeSearch(right( $p$ ),  $k$ )

{recur on right subtree}

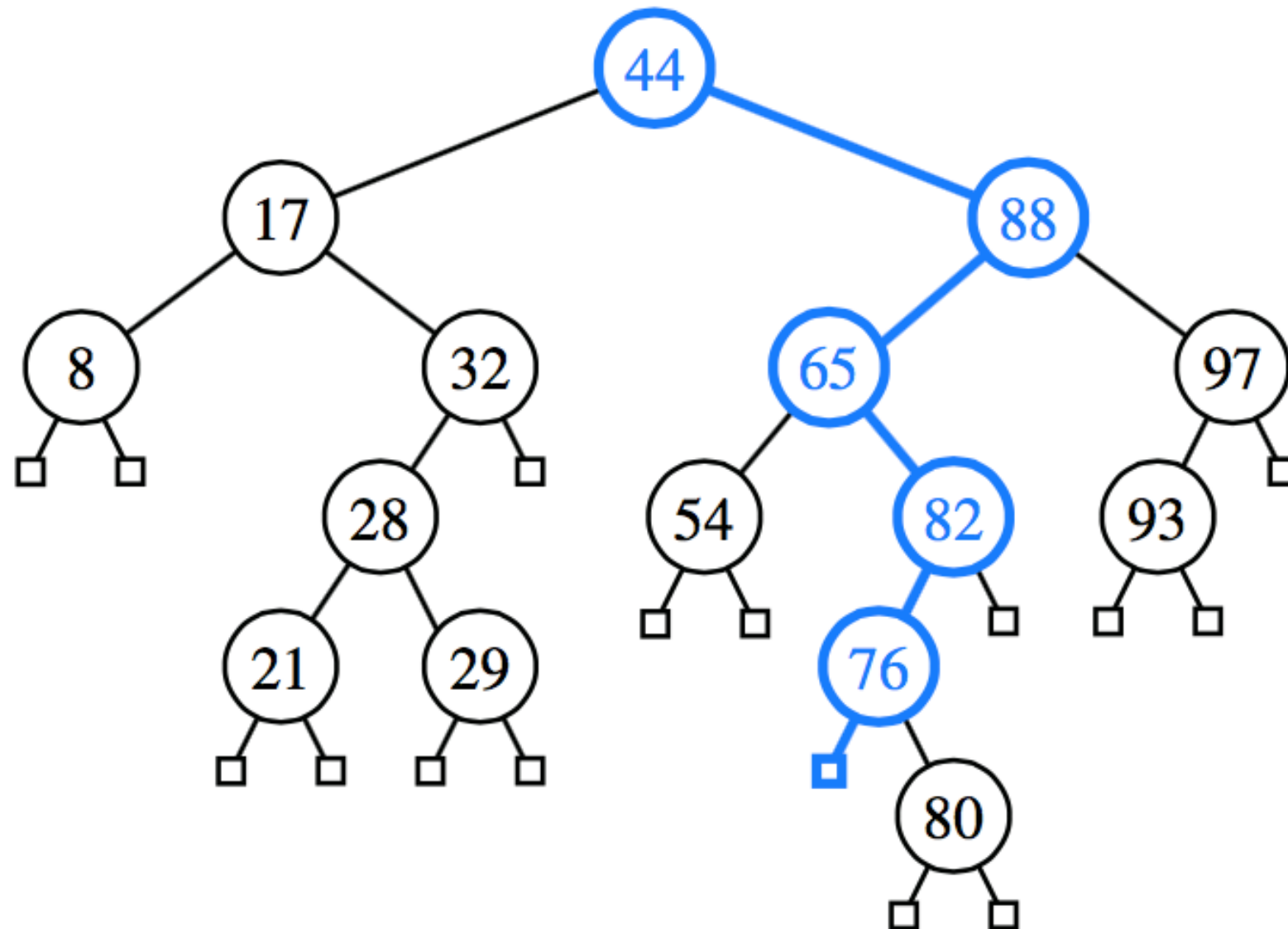
**Code Fragment 11.1:** Recursive search in a binary search tree.

# Searching in a BST



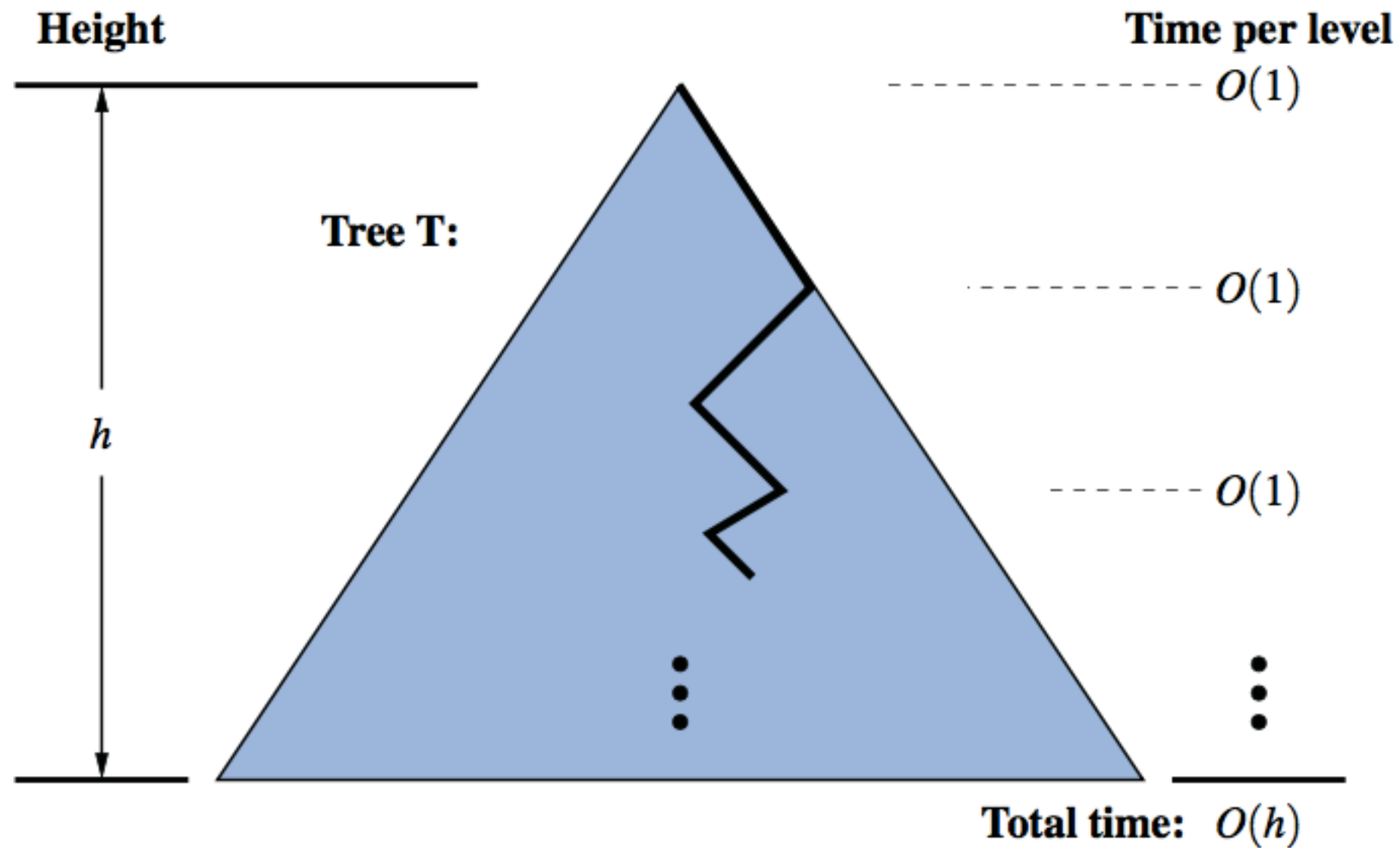
A **successful** search for key 65 in a binary search tree

# Searching in a BST



A **unsuccessful** search for key 68 that terminates at the leaf to the left of key 76

# Analysis of BST Searching





# Insertions in a BST

- To **add** an item to a BST:
  - Follow the algorithm for searching, until there is no child
  - Insert at that point
- So, new node will be added as a leaf
- (We are assuming no duplicates allowed)

# Insertions in a BST

**Algorithm** TreeInsert( $k, v$ ):

*Input:* A search key  $k$  to be associated with value  $v$

$p = \text{TreeSearch}(\text{root}(), k)$

**if**  $k == \text{key}(p)$  **then**

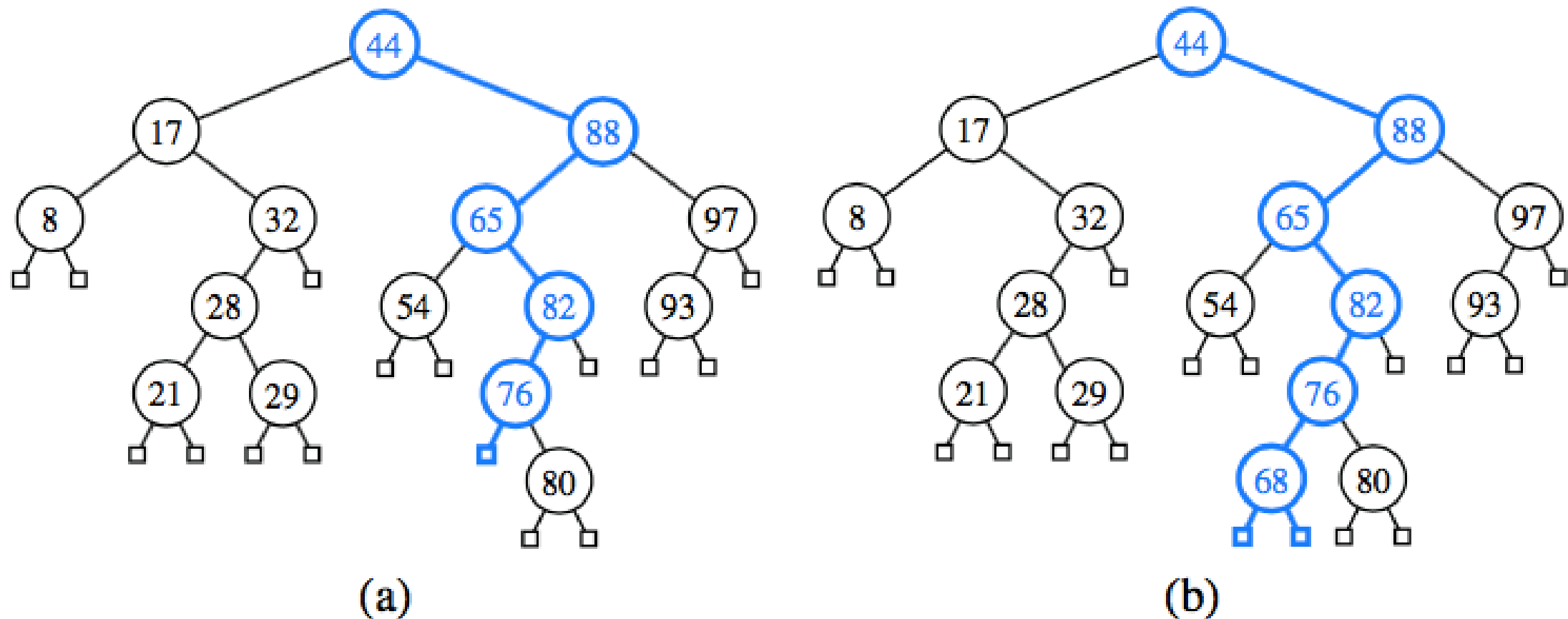
    Change  $p$ 's value to  $(v)$

**else**

    expandExternal( $p, (k, v)$ )

**Code Fragment 11.2:** Algorithm for inserting a key-value pair into a map that is represented as a binary search tree.

# Insertions in a BST



**Figure 11.4:** Insertion of an entry with key 68 into the search tree of Figure 11.2. Finding the position to insert is shown in (a), and the resulting tree is shown in (b).

# Deletions in a BST

method remove (key)

1. if the tree is empty return false
2. Attempt to locate the node containing the target using the binary search algorithm  
if the target is not found return false  
else the target is found, so remove its node:

// Now there can be 4 cases

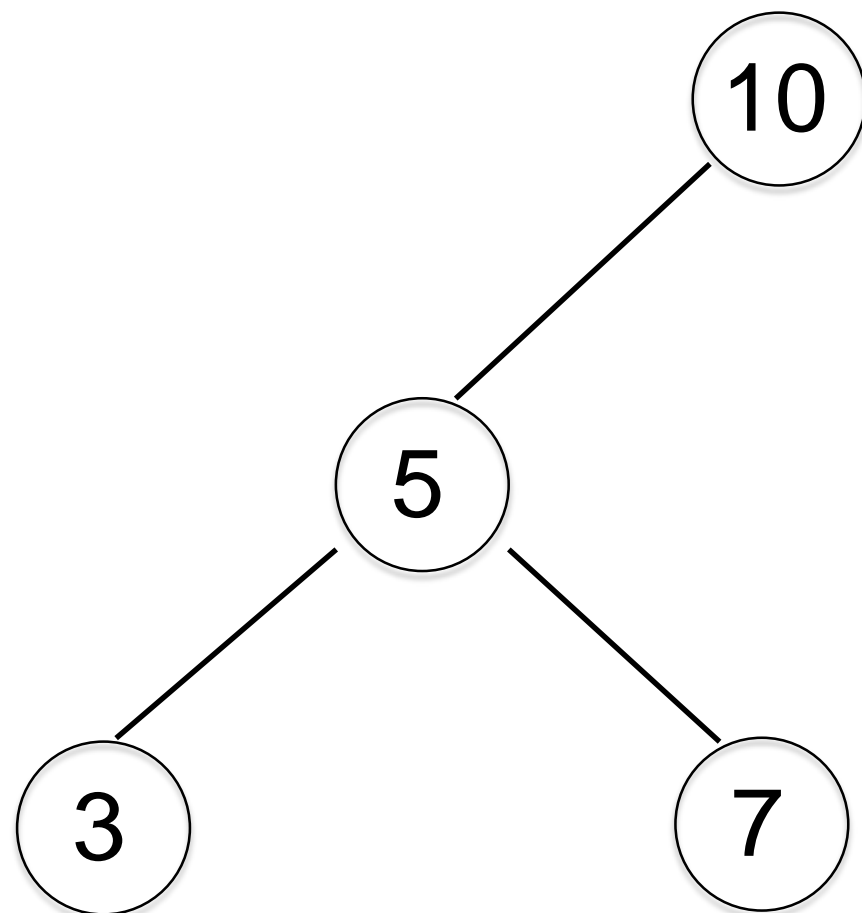
// The easiest case, the node has no children – is a leaf

Case 1: if the node has 2 empty subtrees  
replace the link in the parent with null

# Deletions in a BST

// The easiest case, the node has no children – is a leaf

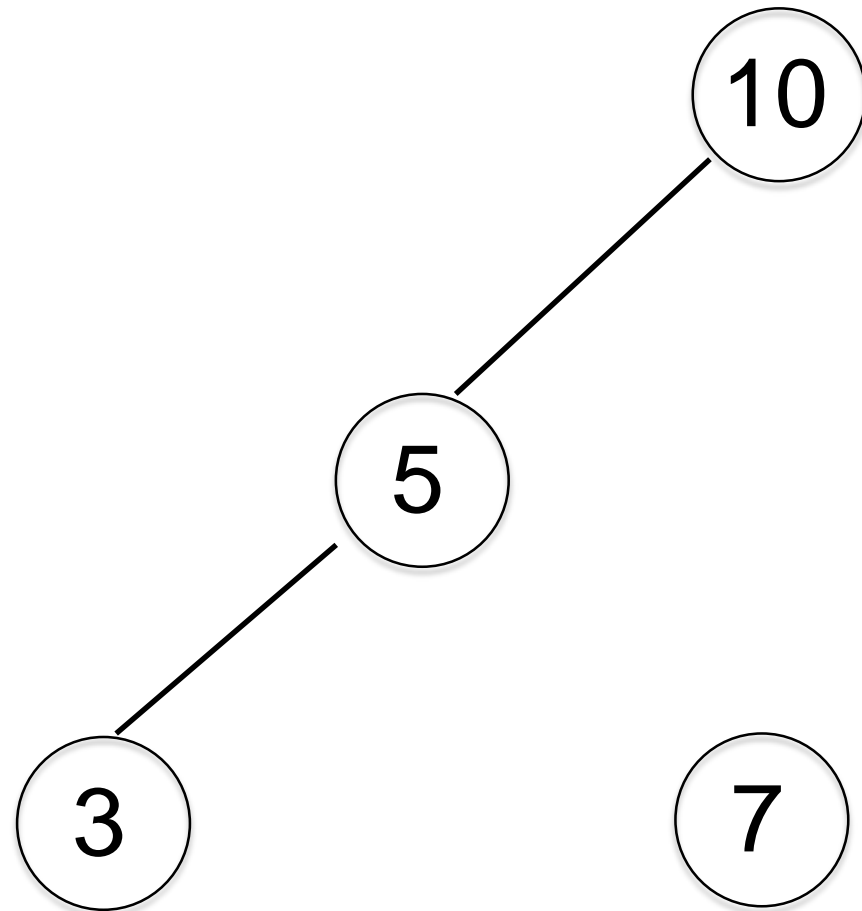
**Case 1:** the node has no children



Let's delete the node with key 7

# Deletions in a BST

// **Case 1:** the node has no children



Replace the link in the parent with null!

Awaiting garbage  
collection

# Deletions in a BST

// Next are the cases with one child

**Case 2:** if the node has no left child

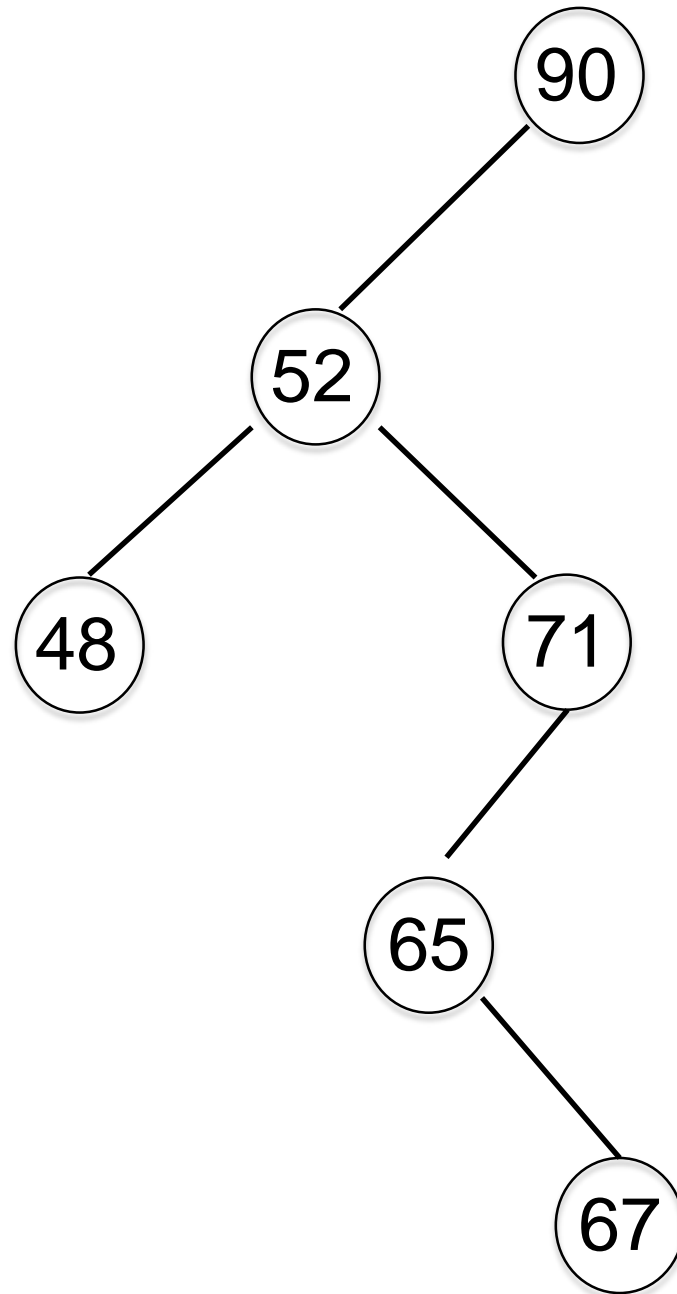
- link the parent of the node
- to the right (non-empty) subtree

**Case 3:** if the node has no right child

- link the parent of the target
- to the left (non-empty) subtree

# Deletions in a BST

**Case 2:** the node has only a left child

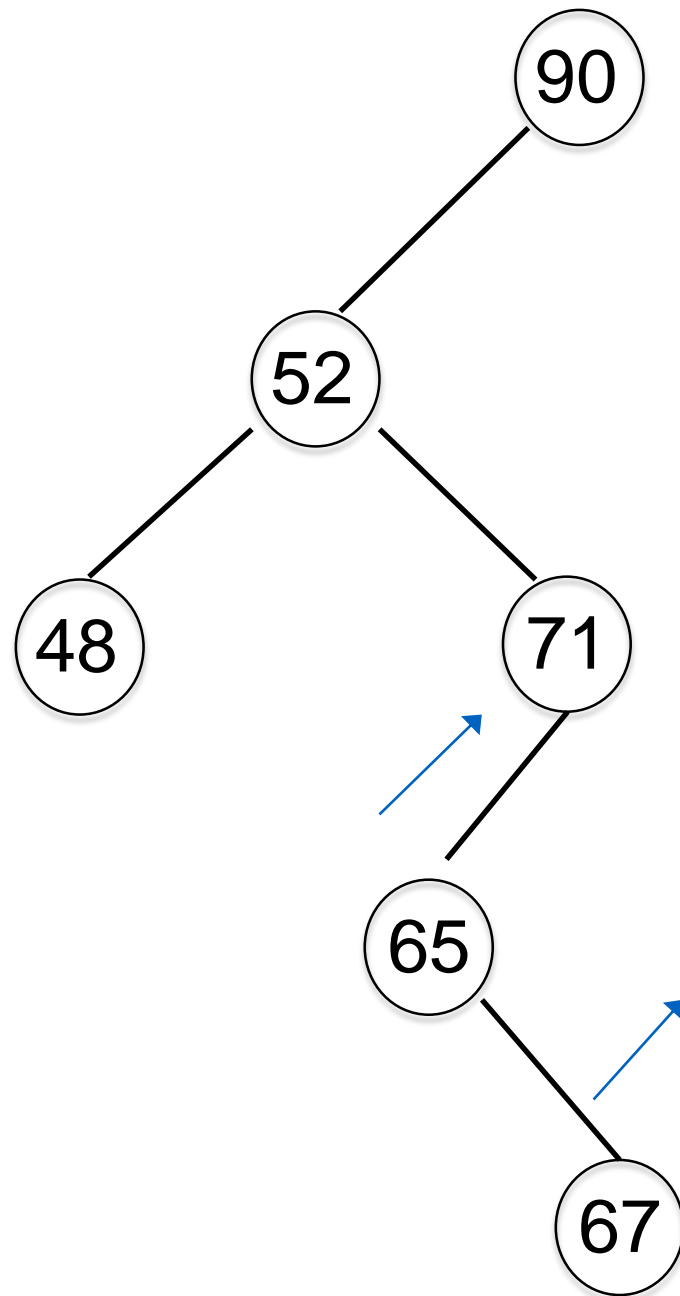


Let's delete the node with key 71



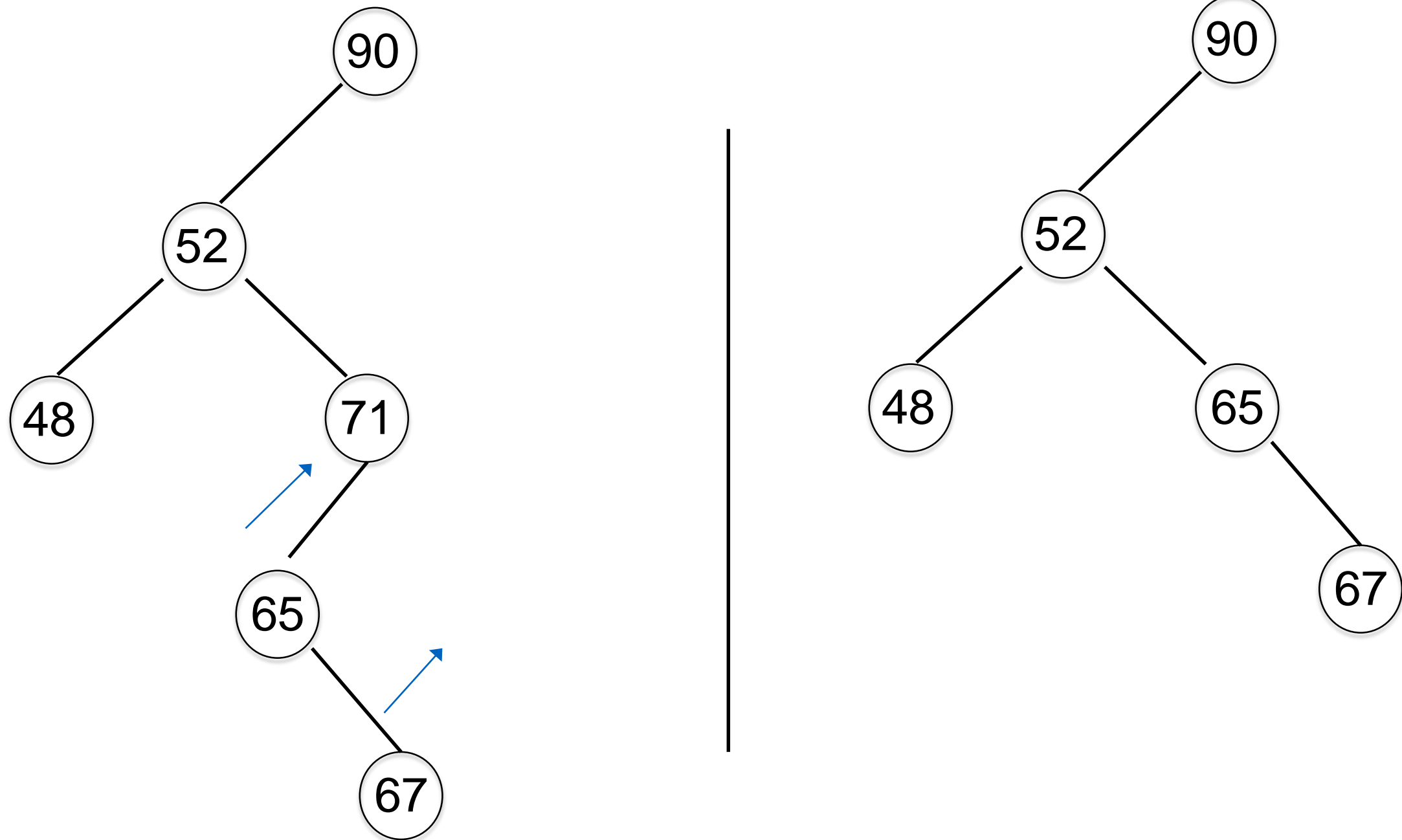
# Deletions in a BST

**Case 2:** the node has only a left child



# Deletions in a BST

**Case 2:** the node has only a left child



# Deletions in a BST

// The most difficult case, the node has two children  
// deleting this node will leave two children in trouble

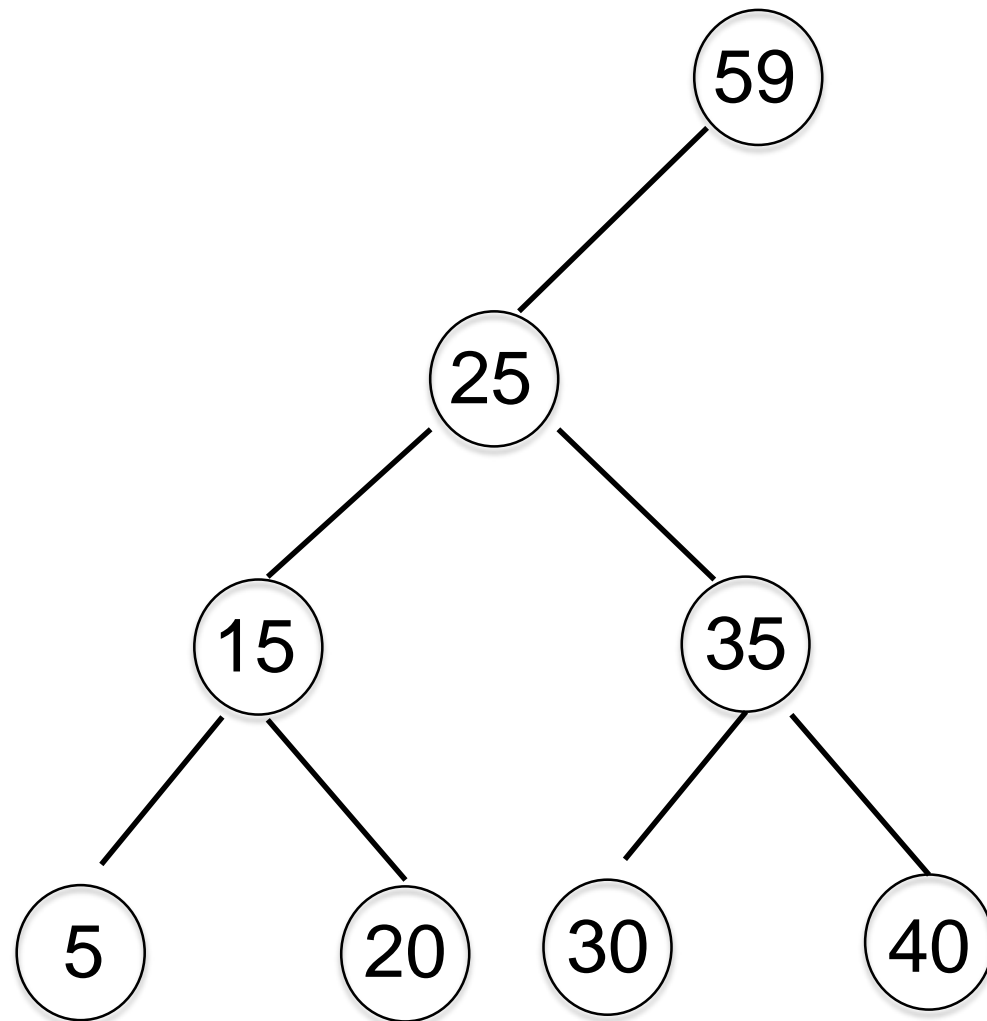
Case 4: if the node has a two children

# Deletions in a BST

// Why is this a difficult case

**Case 4:** if the node has a two children

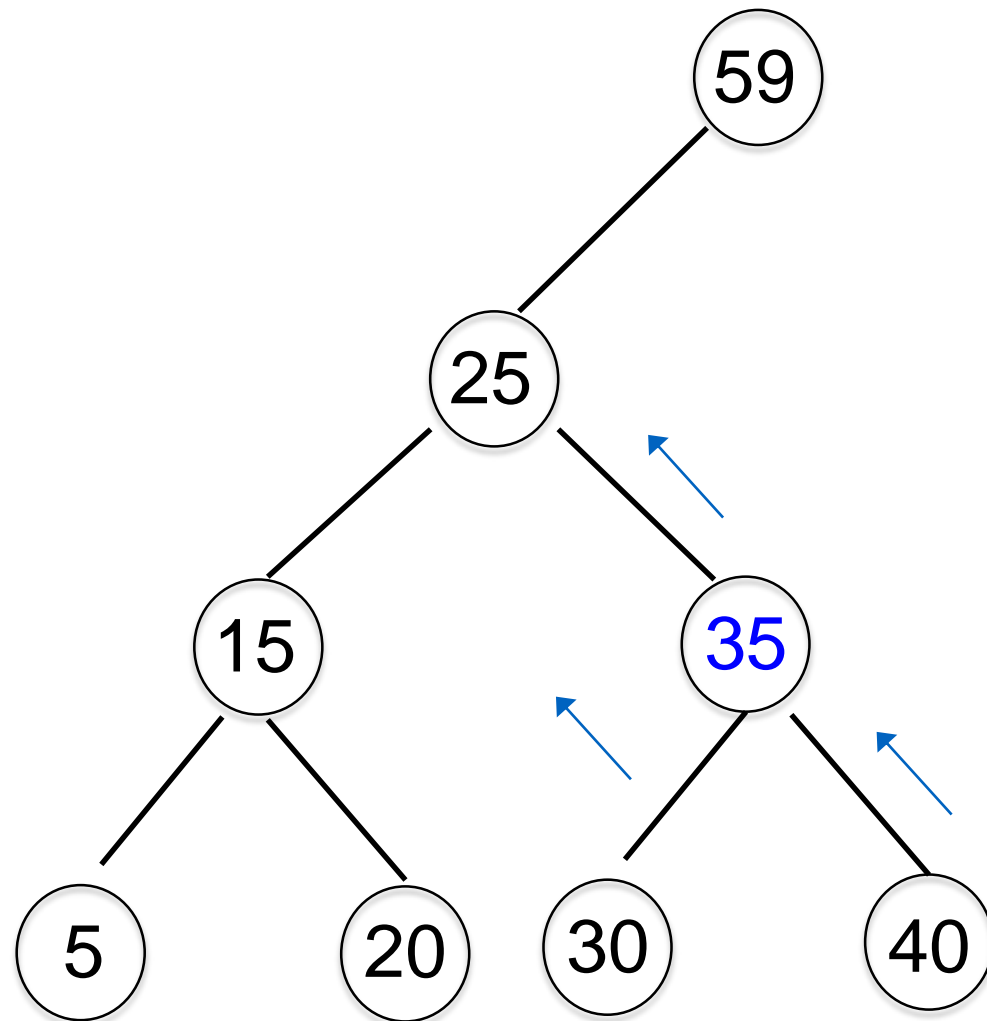
Let's delete 25 – Two choices



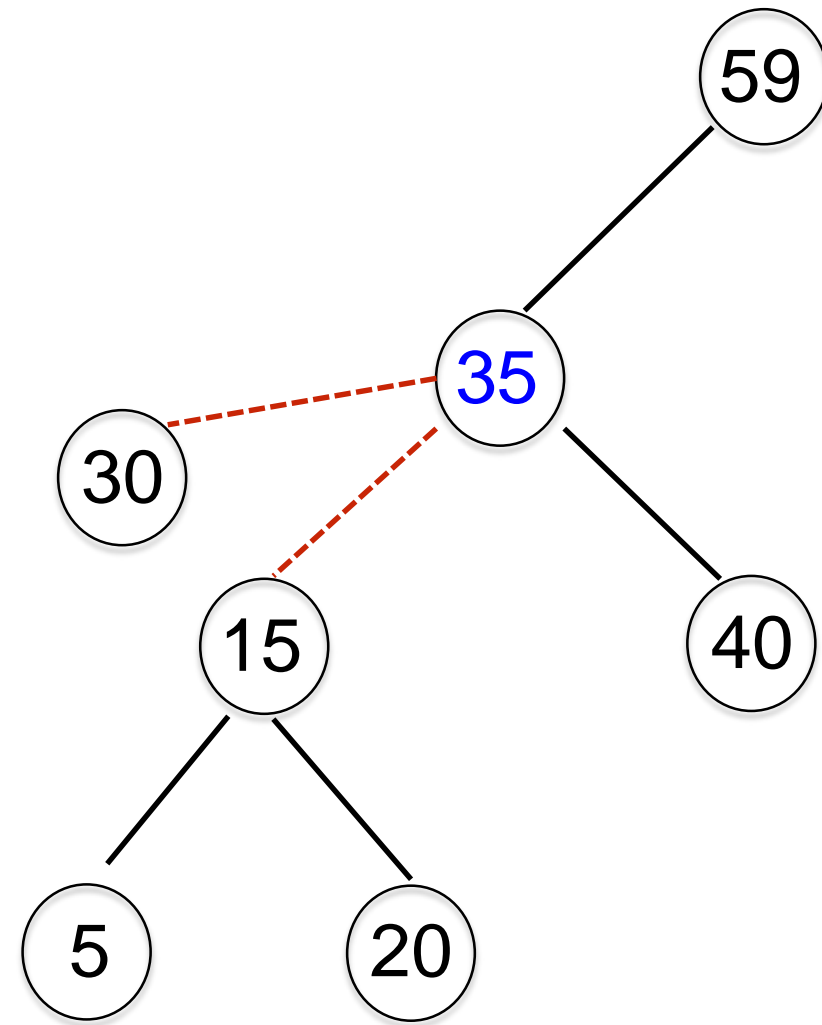
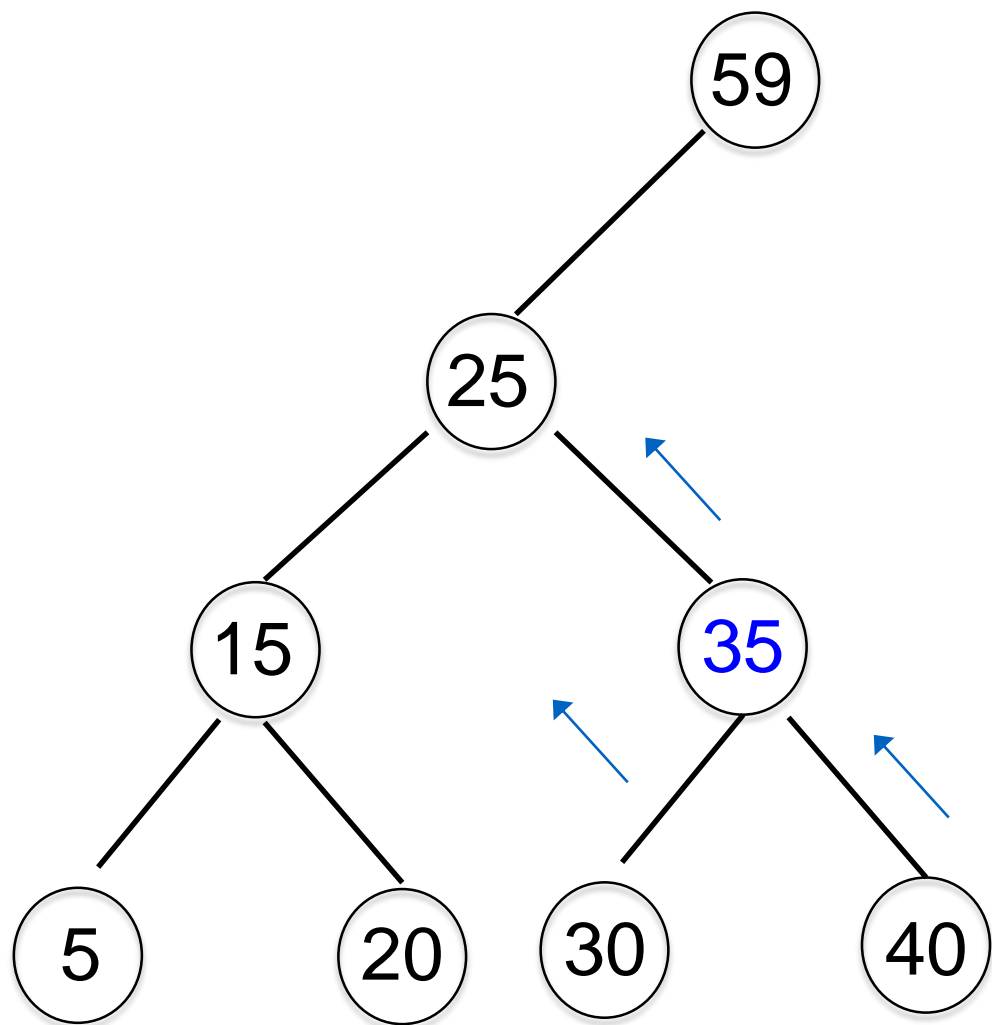
- Replace with root of left sub-tree, **OR**
- Replace with the root of right sub-tree

# Deletions in a BST

- Replace with the root of right sub-tree



# Deletions in a BST



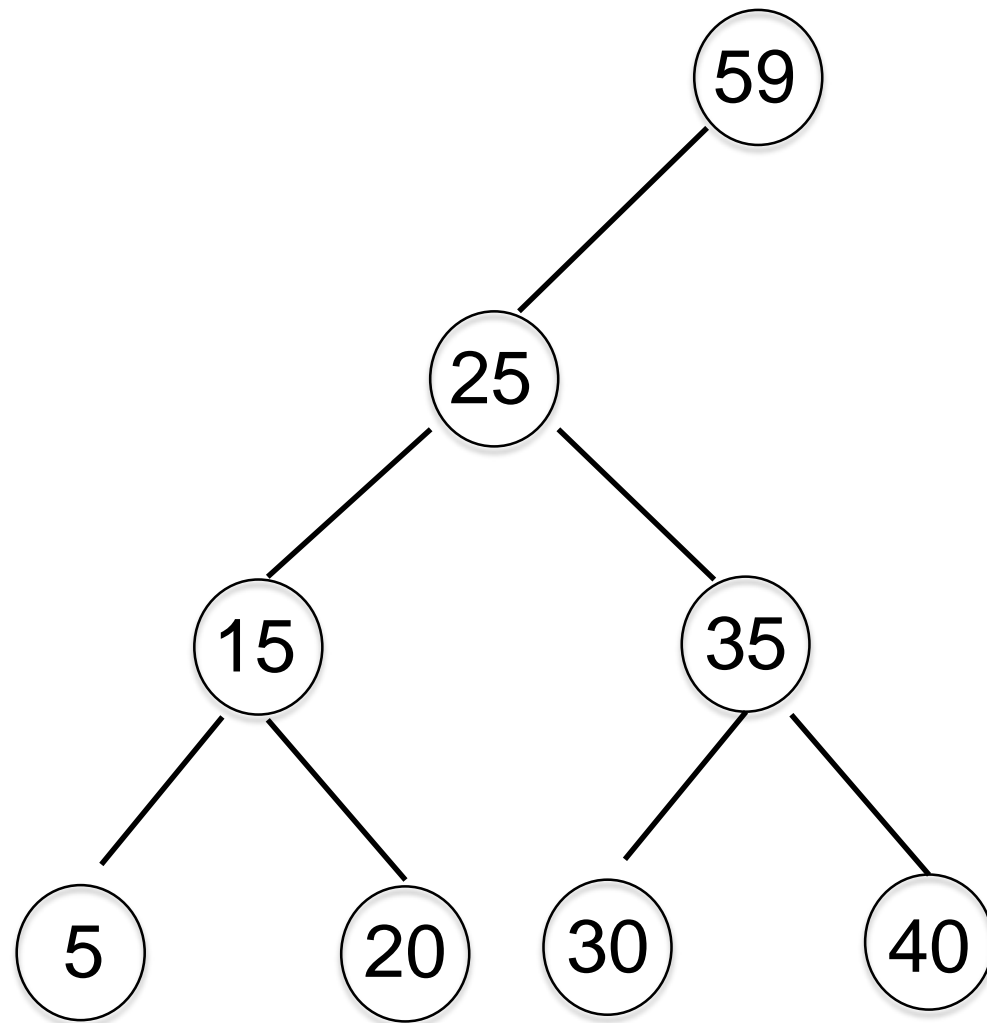
# Deletions in a BST

// Thus a trick is needed

Case 4: if the node has a two children

Replace the node with its predecessor or successor from the inorder traversal of the tree, and delete that node instead.

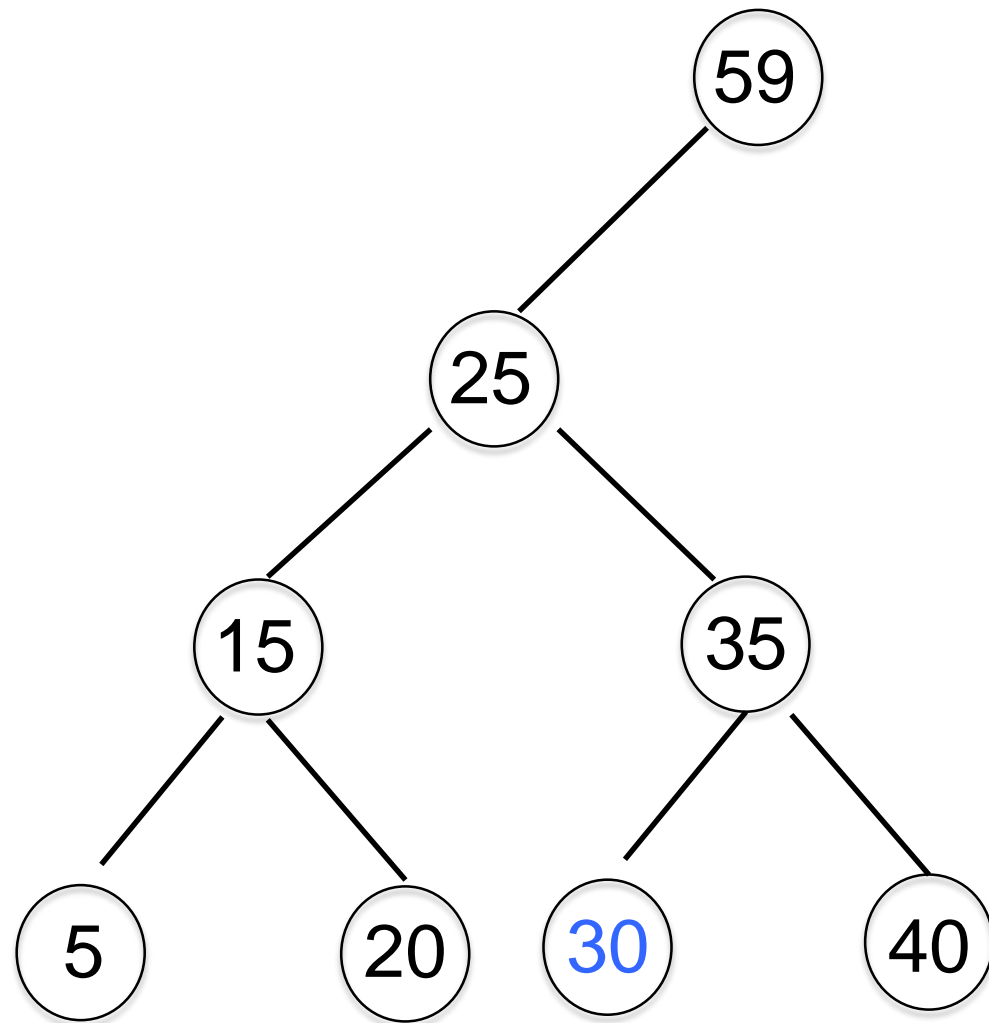
# Inorder Successor



What is the in-order successor of node 25?

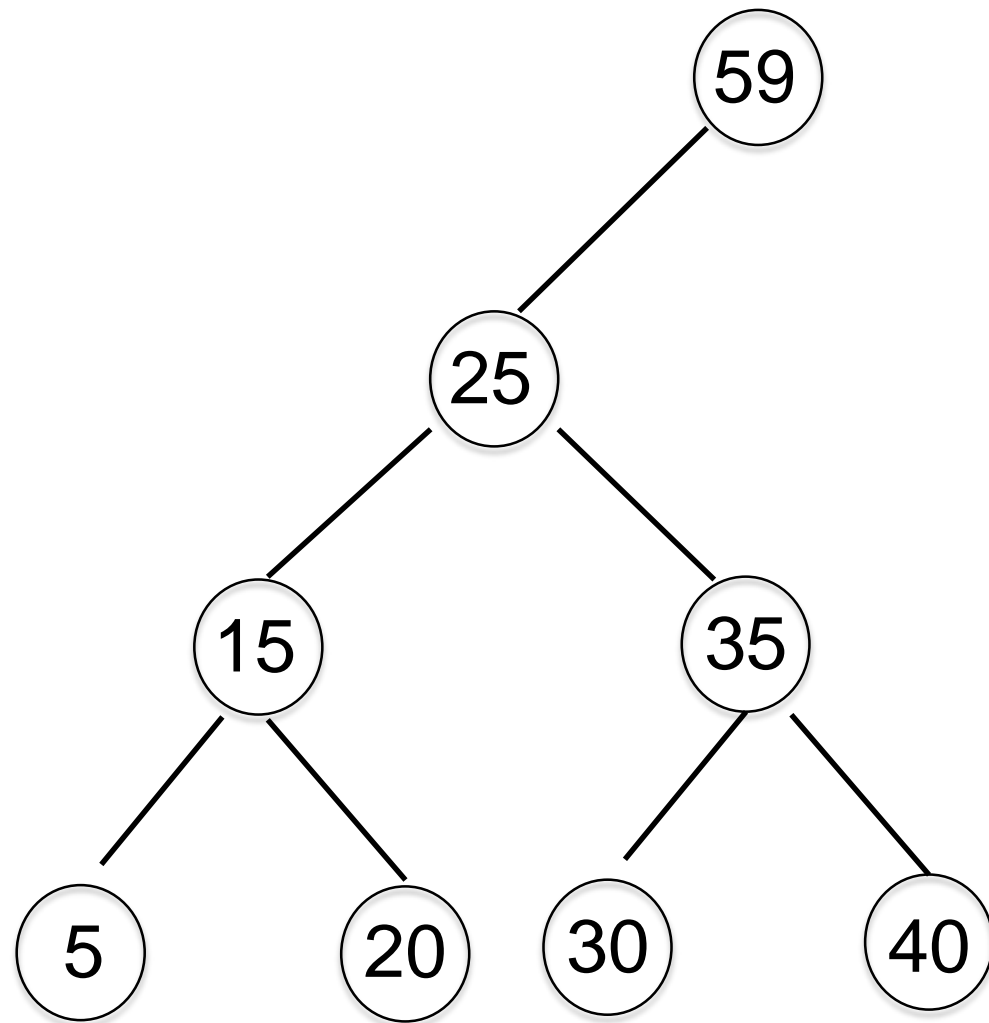


# Inorder Successor



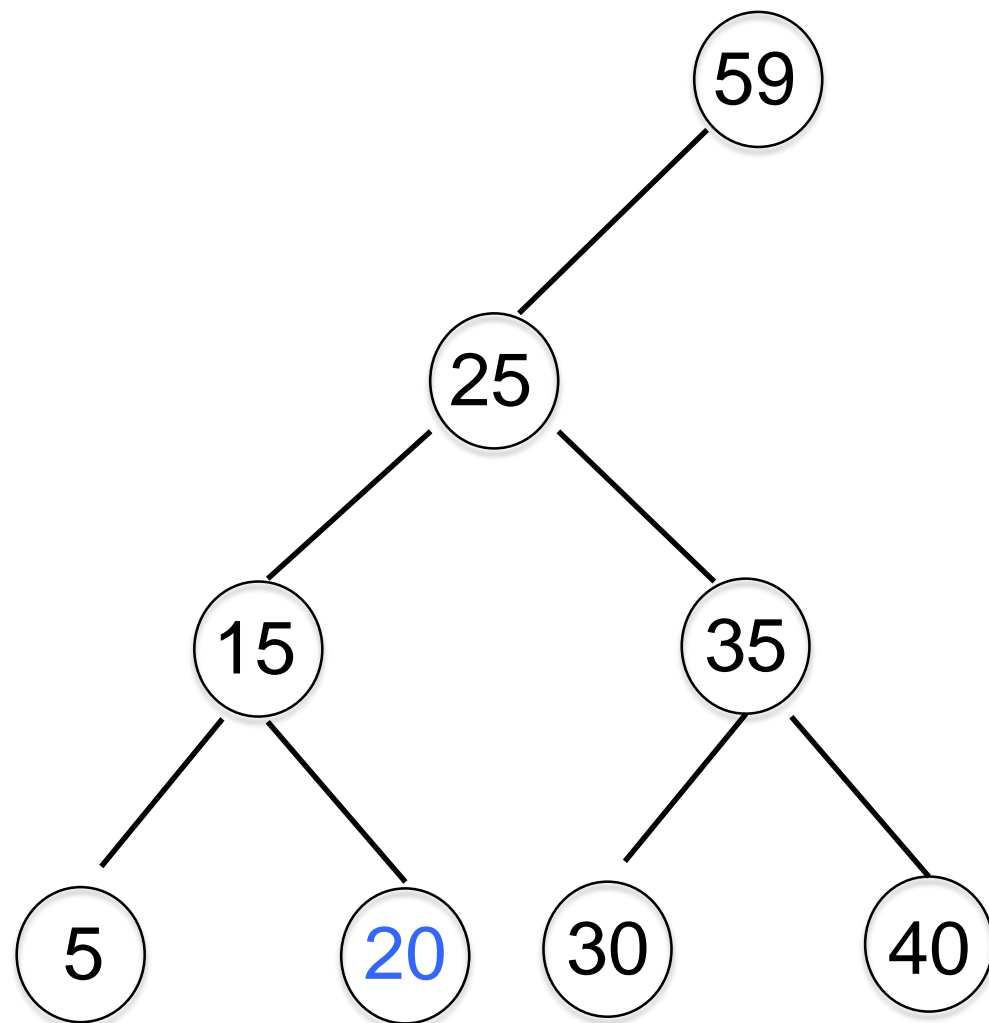
How to find it?

# Inorder Predecessor



What is the in-order predecessor of node 25?

# Inorder Predecessor



How to find it?

# Deletions in a BST

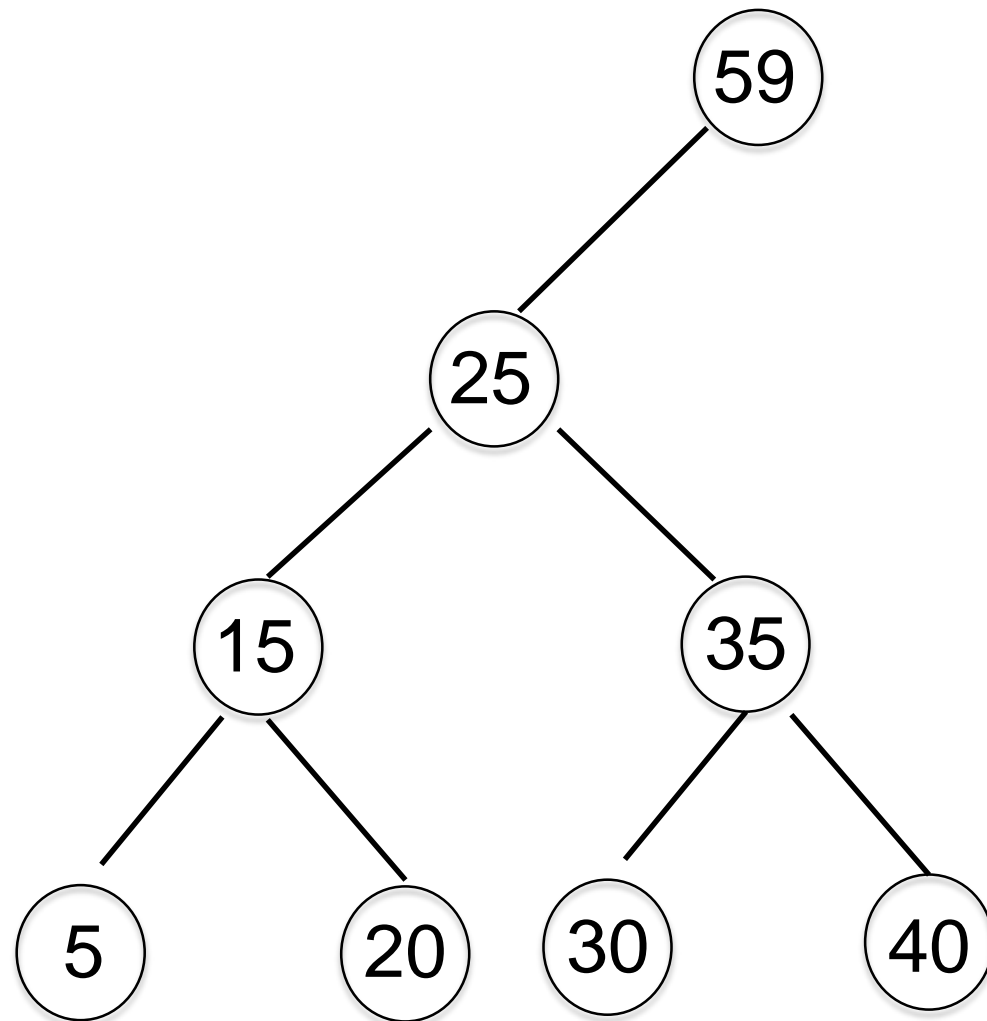
// Thus a trick is needed

Case 4: if the node has a two children

Replace the node with its predecessor or successor from the inorder traversal of the tree. and delete that node instead.

# Deletions in a BST

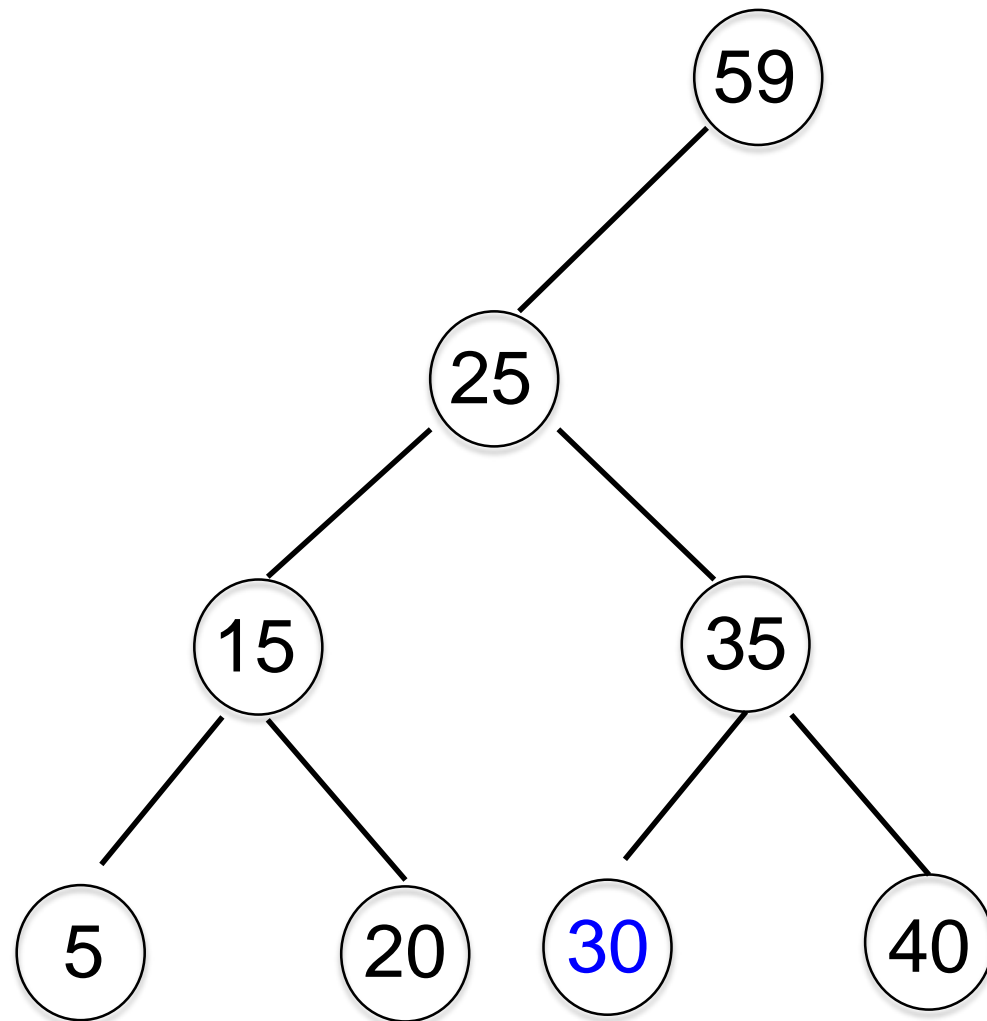
Let's delete 25



# Deletions in a BST

Let's delete 25

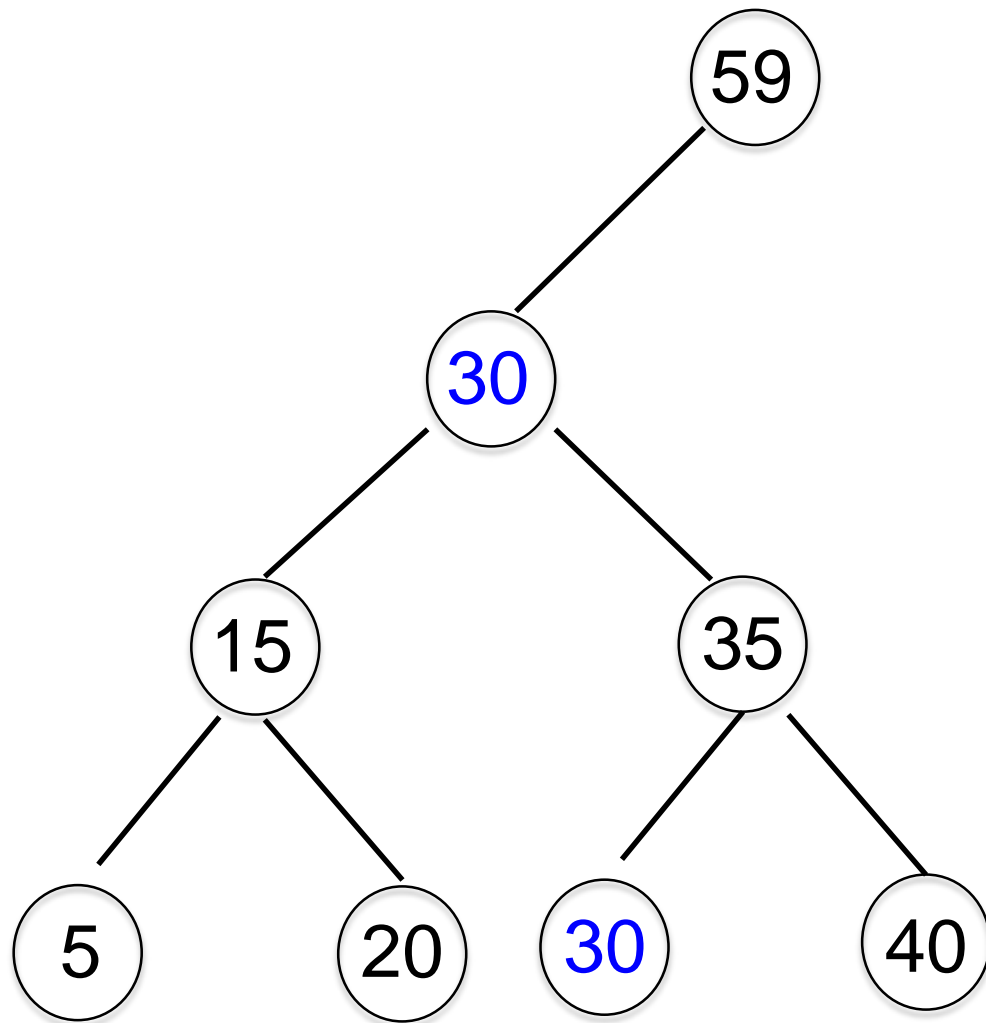
- Identify its successor



# Deletions in a BST

Let's delete 25

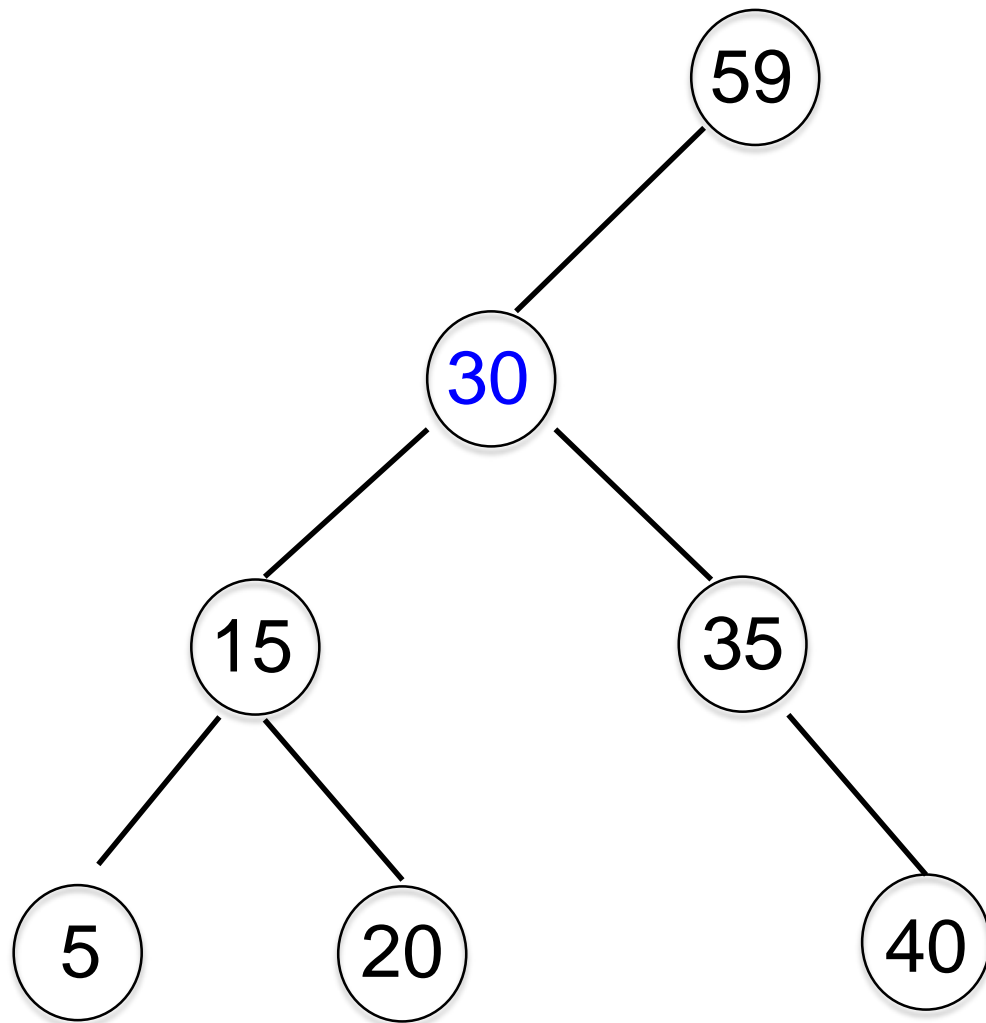
- Replace it with its successor



# Deletions in a BST

Let's delete 25

- Delete the successor

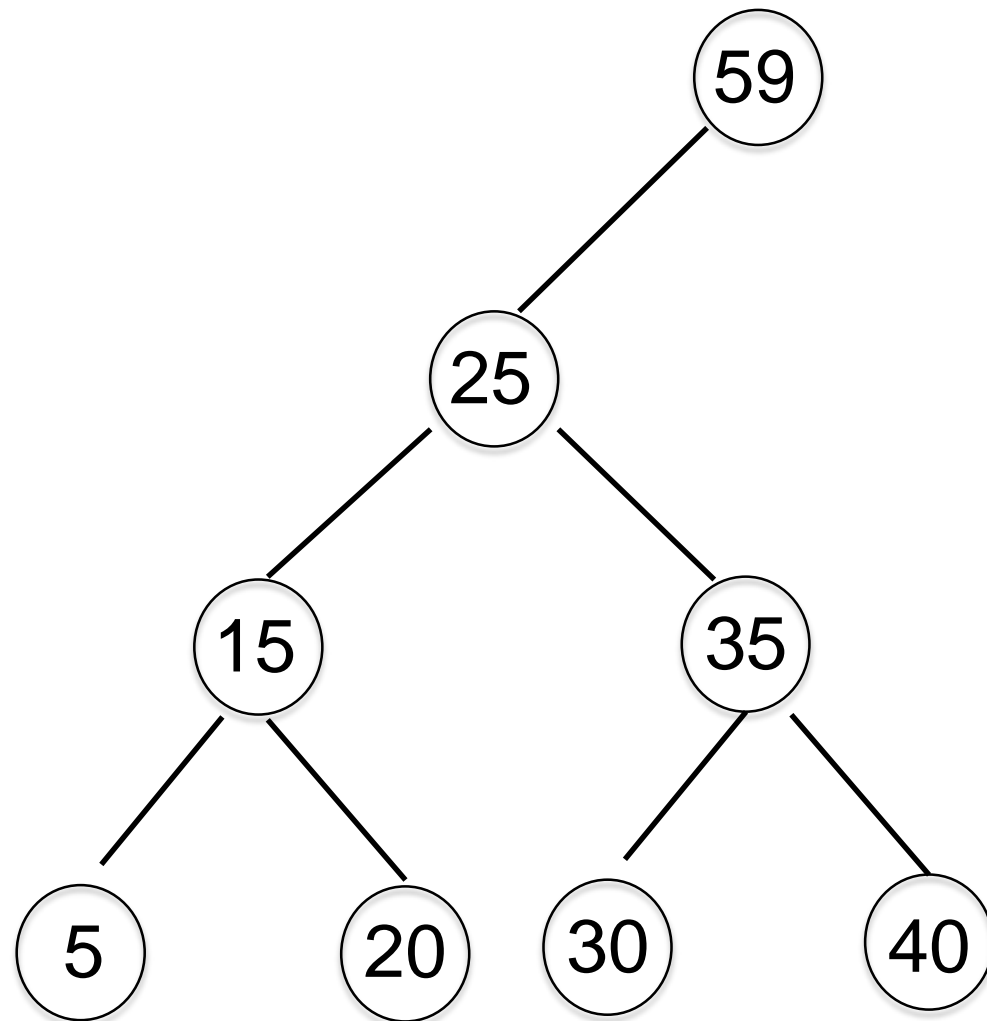




OR

# Deletions in a BST

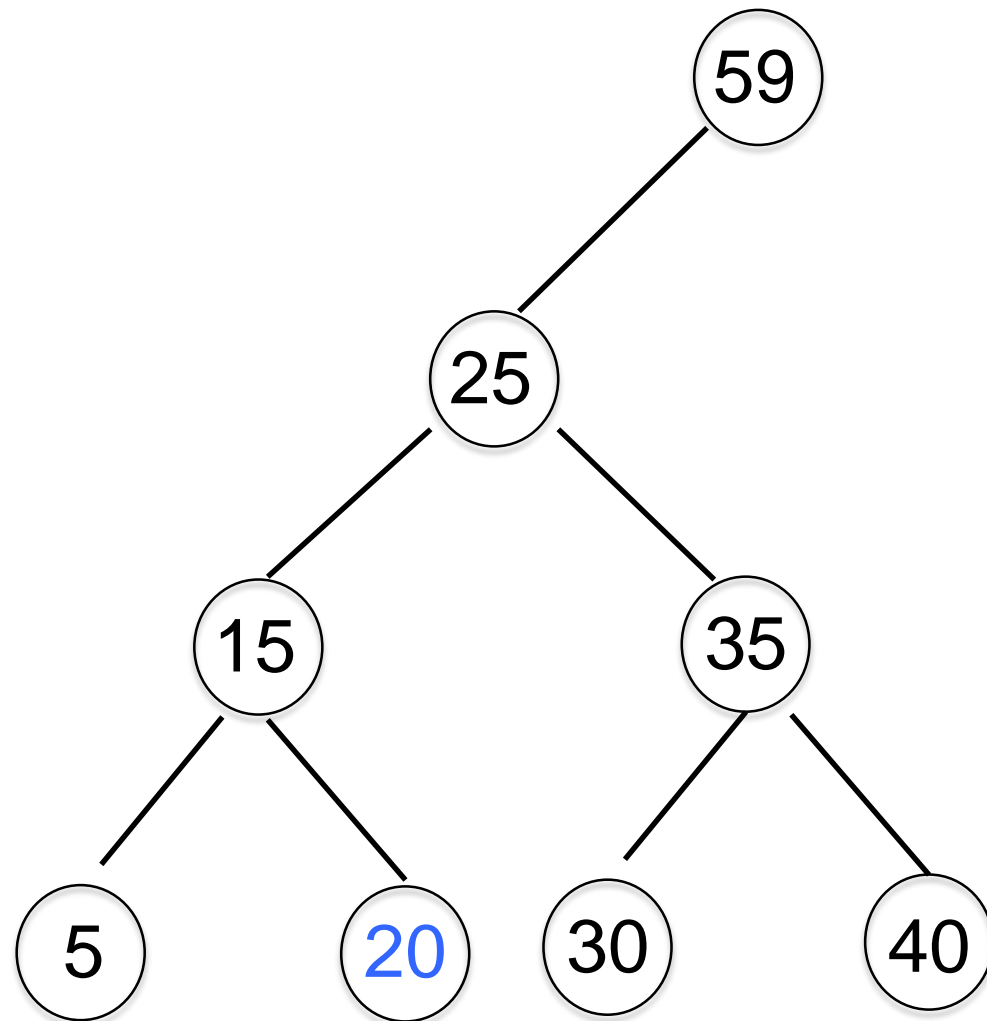
Let's delete 25



# Deletions in a BST

Let's delete 25

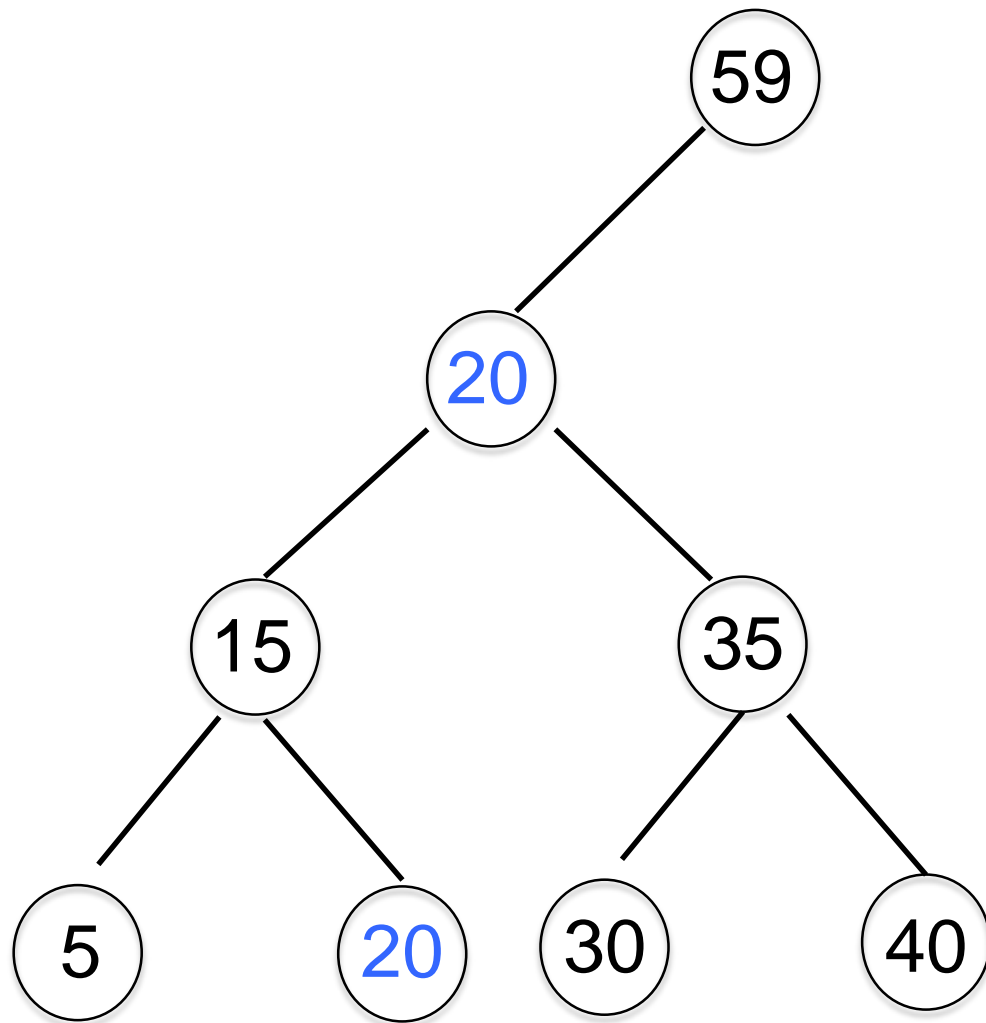
- Identify its predecessor



# Deletions in a BST

Let's delete 25

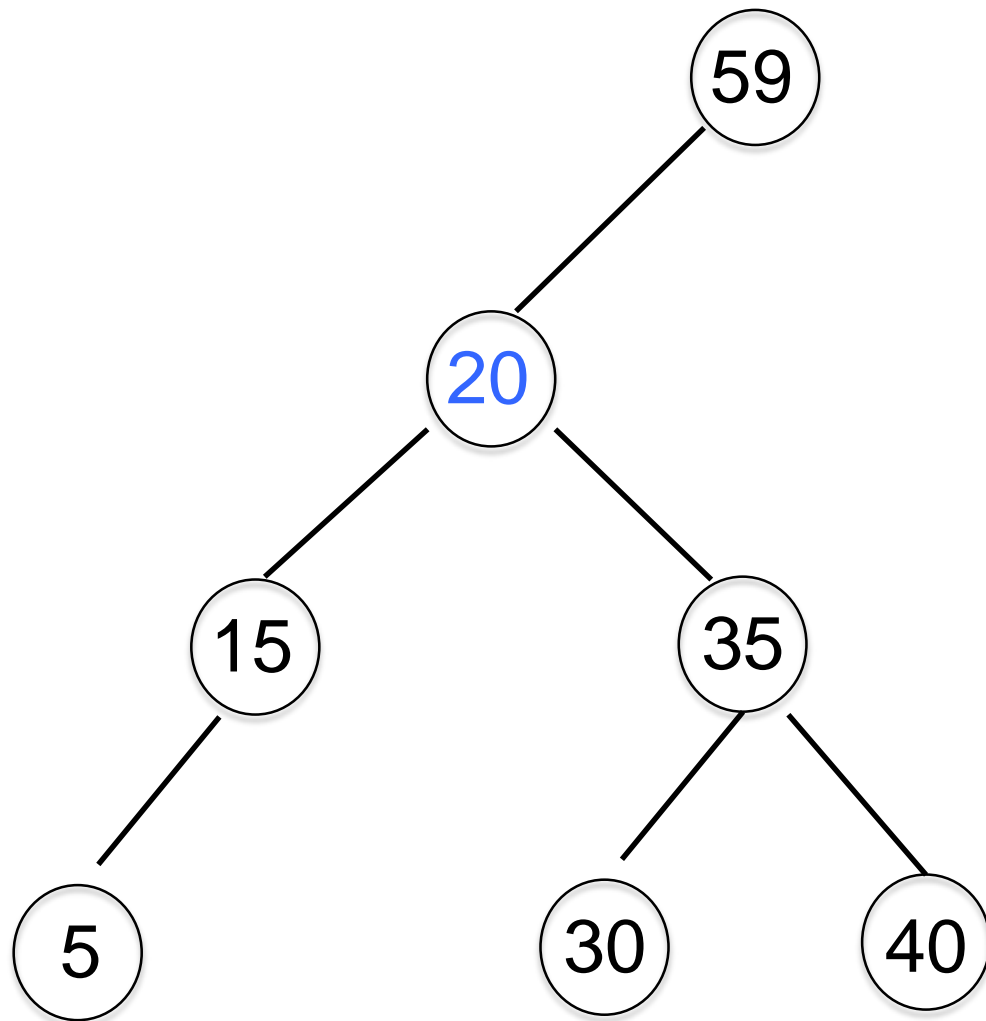
- Replace the node with predecessor



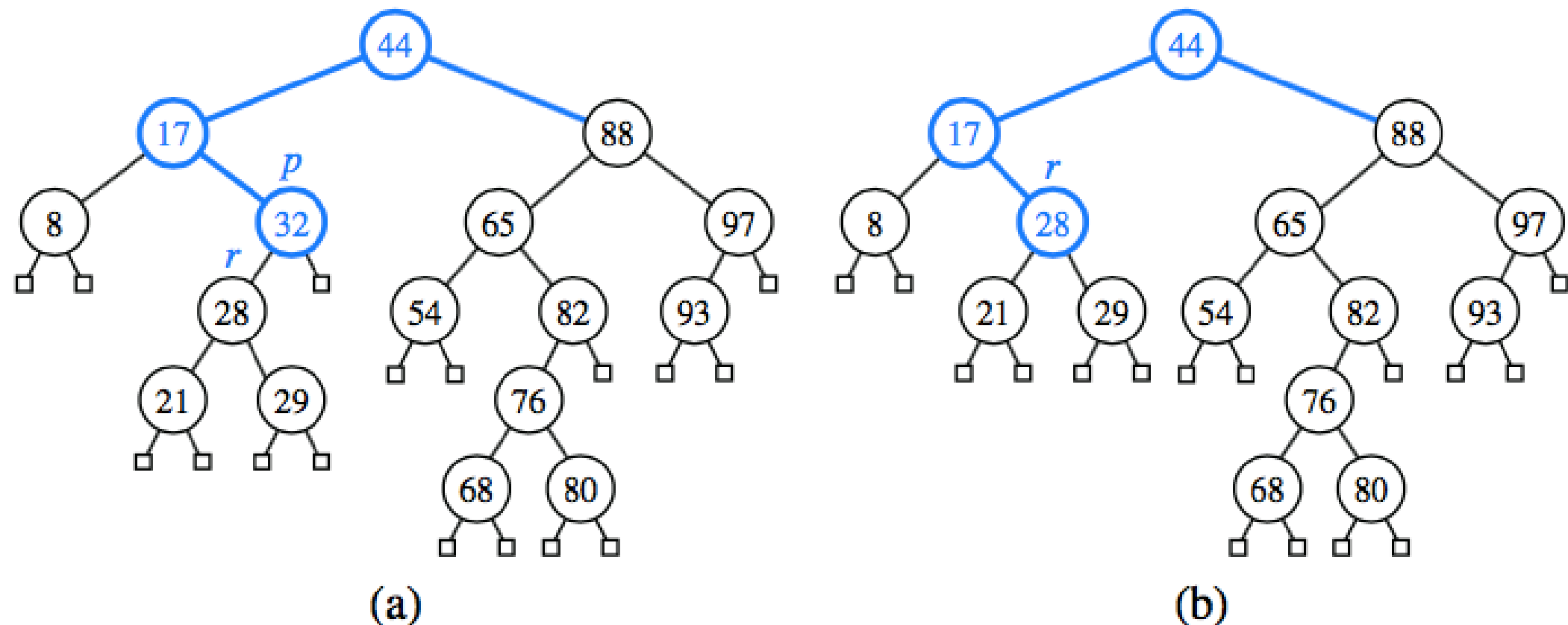
# Deletions in a BST

Let's delete 25

- Delete the predecessor

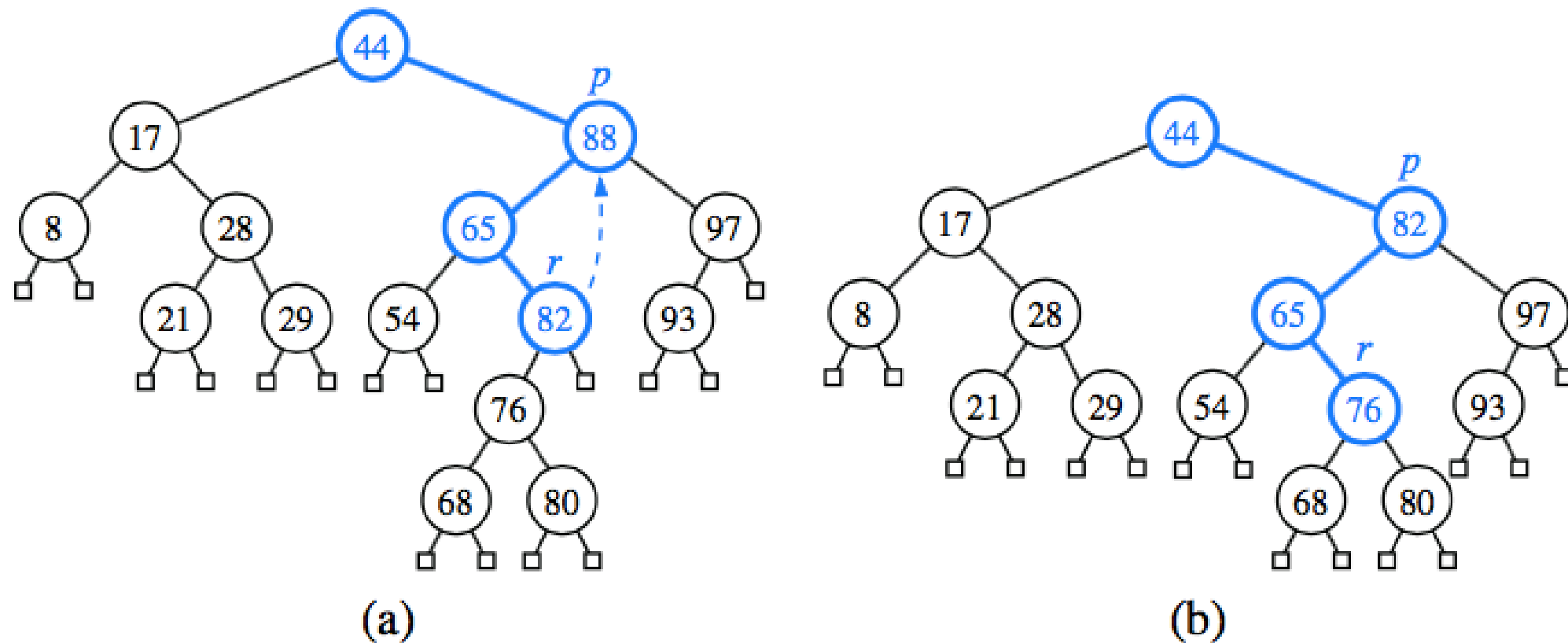


# Deletions in a BST



**Figure 11.5:** Deletion from the binary search tree of Figure 11.4b, where the entry to delete (with key 32) is stored at a position  $p$  with one child  $r$ : (a) before the deletion; (b) after the deletion.

# Deletions in a BST



**Figure 11.6:** Deletion from the binary search tree of Figure 11.5b, where the entry to delete (with key 88) is stored at a position  $p$  with two children, and replaced by its predecessor  $r$ : (a) before the deletion; (b) after the deletion.

# BST Analysis

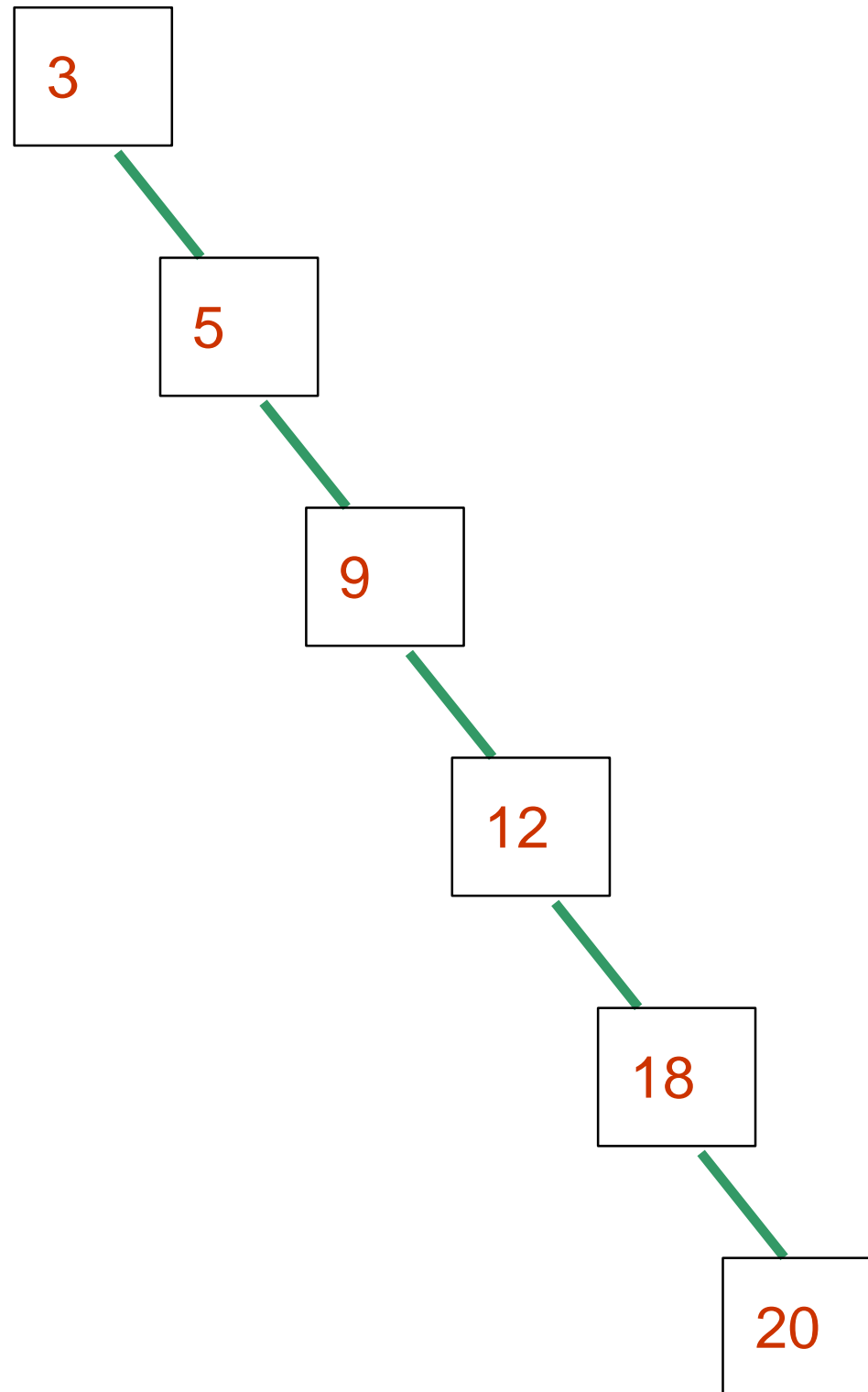
- All the important operations of BST are  $O(h)$
- So the question now is:  $h = O(?)$



# Discussion

- Look at what happens if we insert the following numbers in this order:

**3 5 9 12 18 20**



# Degenerate Binary Trees

- The resulting tree is called a *degenerate* binary tree
- Note that it looks more like a linked list than a tree!
- Thus,  $h = O(n)$

# Degenerate Binary Trees

- How to avoid *degenerate* binary tree?
  - Random Binary Search Trees
  - Balanced Binary Search Trees

# Random BST

- A tree that arises from inserting the keys in *random* order into an initially empty tree
- Theorem
  - ❖ The *expected* height of a randomly built binary search tree is  $O(\lg n)$

# Random BST

- ❖ The *expected* height of a randomly built binary search tree is  $O(\log n)$
- You can see the complete proof in “Introduction to Algorithms,” by Cormen, Chapter 12, Theorem 12.4
- But to make it easy for you to understand the proof, I will explain the **PROOF OUTLINE** on the board.

# Questions as Homework

- How to proof through “Proof via Induction” that the **number of external nodes** in a binary tree having  $n$  internal nodes is  $n + 1$ ?
- Why is the **expected height** of a randomly built BST of  $n$  nodes is  $O(\log n)$ ?

# Did we achieve today's objectives?

- What is a Tree (as a data structure)?
- Learn about different types of trees and the associated properties, definitions and terminologies
- Special emphasis on Binary Search Trees
  - ❖ How does a BST work?
  - ❖ How to traverse in a BST?
  - ❖ Time complexity of a BST