

Probability Theory & Statistics

Innopolis University, BS-I,II

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Part I

MEAN, AVERAGE, EXPECTATION, THE FIRST MOMENT

Definition

- Let $X:\Omega\rightarrow\mathbb{R}$ be a random variable and P_X be its probability distribution.
- *Mean, average, expectation, the first moment* of X is defined as

$$M(X) = E(X) = \sum_{x\in\mathbb{R}} x * P_X(x).$$

- Is this definition correct?

Examples

- Rolling the dice: since $P_X(x)=1/6$ for all x in $\{1, 2, 3, 4, 5, 6\}$, then $M(X)= 1*1/6 + 2*1/6 + 3*1/6 + 4*1/6 + 5*1/6 + 6*1/6 = 7/2$.
- Lottery prize (ref. week 5): since

Prize	1000	100	1	0
Probability	0.0001	0.001	0.01	0.9889

$$M(X)= 1000*0.0001 + 100*0.001 + 1*0.01 + 0*0.9889 = 0.1 + 0.1 + 0.01 = 0.21.$$

Two exercises

- What is the average sum of pips
 - on an domino tile?
 - on pair of dices?

Linearity of the expectation

- Prove: if $a \in \mathbb{R}$ is a constant then
 - $M(a) = a$;
 - $M(a * X) = a * M(X)$;
- Discuss: if X and Y have the same outcomes then $M(X + Y) = M(X) + M(Y)$;
- Prove: if $a, b \in \mathbb{R}$ are constants and X and Y have the same outcomes then
$$M(a * X + b * Y) = a * M(X) + b * M(Y).$$

Expectation of a function

- Let $X:\Omega\rightarrow\mathbb{R}$ be a random variable and $g:\mathbb{R}\rightarrow\mathbb{R}$ be function (that is defined on the range of X at least).
- Prove: if $Y=g(X)$ then $M(Y)=\sum_{x\in\mathbb{R}}g(x)*P_X(x)$.

Independent Random Variables

- Random variables $X, Y: \Omega \rightarrow \mathbb{R}$ are said to be *independent* if $(X=x)$ and $(Y=y)$ are independent events for all $x, y \in \mathbb{R}$.
- Prove: random variables $X, Y: \Omega \rightarrow \mathbb{R}$ are independent iff $P(X=x \cap Y=y) = P(X=x) * P(Y=y)$ for all $x, y \in \mathbb{R}$.
- Question: what the probability space is used in the definition and property?

Expectation of Product of Two Independent Random Variables

- Prove: if random variables $X, Y: \Omega \rightarrow \mathbb{R}$ are independent then $M(X*Y) = M(X)*M(Y)$.
- Question: is equality $M(X*Y) = M(X)*M(Y)$ valid for all random variables $X, Y: \Omega \rightarrow \mathbb{R}$? (Either prove or provide a counterexample.)

Part II

SELECTED DISCRETE DISTRIBUTIONS

Discrete Uniform Distribution

- Discrete uniform distribution corresponds to a random variable X that get exactly n values $\{x_1, \dots, x_n\}$ with a flat probability:

$$P_X(x_k) = 1/n \text{ for all } k \in [1..n].$$

- Expectation $M(X) = (x_1 + \dots + x_n)/n$ is the (arithmetic) mean of X values.
- Example: tossing a dice.

Bernoulli Trial and Distribution

- $X = \text{Bernoulli}(p)$, where $p \in [0, 1]$, gets just 2 conventional values 0 (fail) and 1 (success).
- Bernoulli distribution:
 - $P(\text{Bernoulli}(p)=1) = p$ and
 - $P(\text{Bernoulli}(p)=0) = 1-p$.
- $M(\text{Bernoulli}(p)) = 0 \cdot (1-p) + 1 \cdot p = p$.

Bernoulli Trials and Binomial Distribution

- Bernoulli trials (or binomial experiment) consist of some fixed number n of independent Bernoulli trials, each with a probability of success p , and counts the number of successes.
- A corresponding random variable is denoted by $B(n,p)$ or by $\text{binomial}(n,p)$, and is said to have a binomial distribution:

$$P_{B(n,p)}(k) = P(B(n,p)=k) = C_n^k p^k (1-p)^{(n-k)}.$$

Mean for Binomial Distribution

- Let $X=B(n,p)$.
- By expectation definition:

$$M(X)= \sum_{k \in [0..n]} k * C_n^k p^k (1-p)^{(n-k)}.$$

- By definition of $B(n,p)$: $X = X_1 + \dots + X_n$ where all $X_1, \dots, X_n = \text{Bernoulli}(p)$.
- By expectation linearity: $M(X) = n * p$.
- Intuitively: number of success in n trials should be $n * p$.

Random Variable with Geometric Distribution

- The probability distribution of the number k in $\{1, 2, 3, \dots\}$ of Bernoulli(p) trials needed to get the first success:

$$P(X=k) = (1-p)^{(k-1)} * p.$$

- Attention: for the first time the range of *possible* (i.e. not impossible) values is *infinite*; so the set of outcomes Ω must be infinite too.

Example: Beauty and the Beast

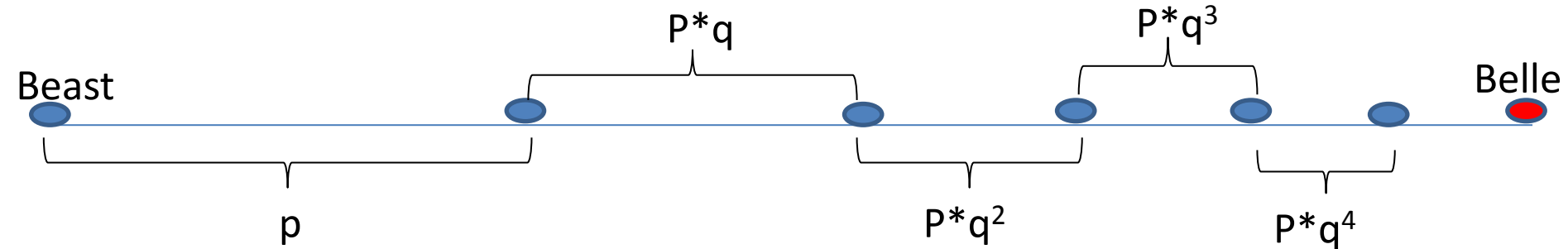
The Beast is a shy guy:
he stays just 1 meter
behind Belle ... but
can't dare to call her.



<http://kinoprofi.org/7041-krasavica-i-chudovische-chudesnoe-rozhdestvo-1997.html>

Example: Beauty and the Beast (cont.)

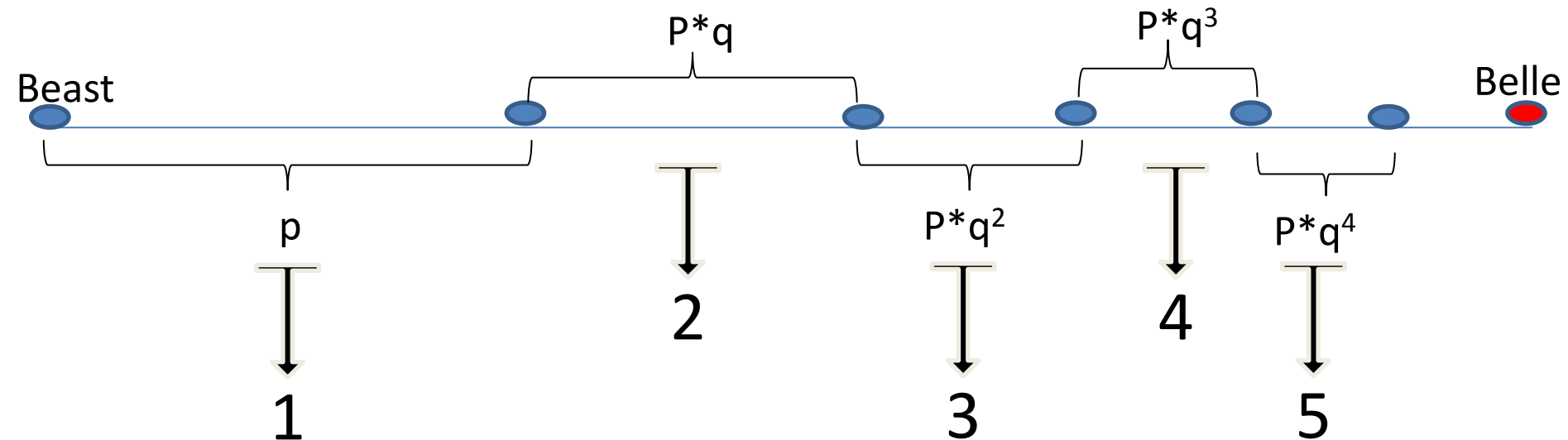
- So he makes the first step to her of p cm length and (maybe) some more steps so that each next step is $q=(1-p/100\text{cm})$ smaller then the previous one.



- After that the Beast calls Belle. What is probability that he calls after (exactly) k steps?

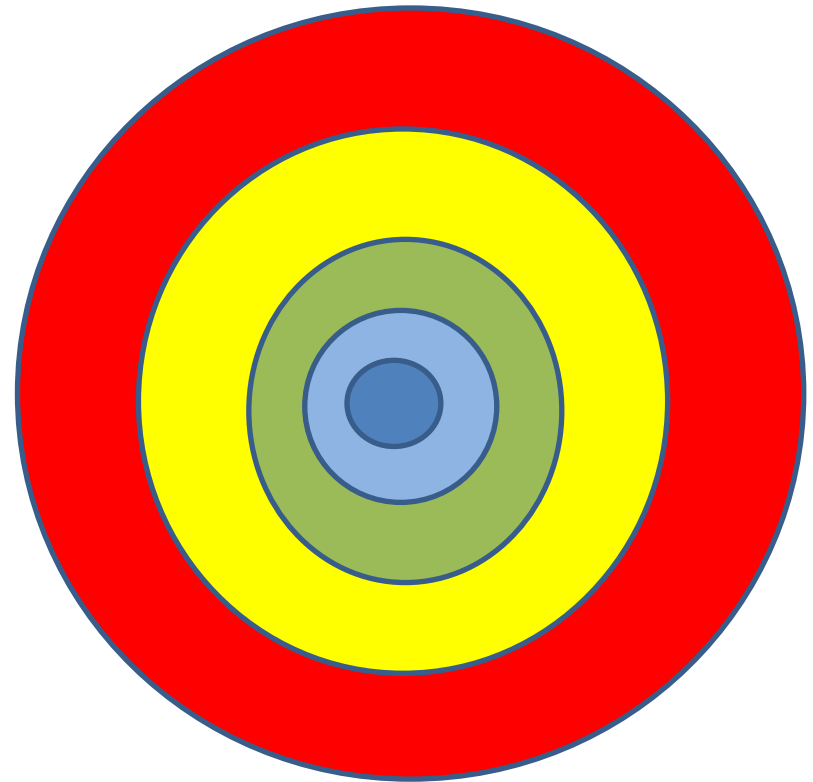
Example: Beauty and the Beast (cont.)

- Let $X:[0, 1) \rightarrow \mathbb{R}$ be the following staircase function: $X(t)=k$ on interval $[(1-q^{(k-1)}), (1-q^k))$.
- $\Omega=[0,1)$ and $X = \text{Geom}(p)$:



Build another example of $X = \text{Geom}(p)$

Find radiuses of rings
such that areas of
concentric rings
 $X = \text{Geom}(p)$:



Mean for Geometric Distribution

- If $X = \text{Geom}(p)$ then

$$M(X) = \sum_{k>0} k \cdot p \cdot (1-p)^{(k-1)} = 1/p$$

(refer the next part for a proof).

Part III

CONDITIONAL AND TOTAL EXPECTATION

Recall from Lecture for week 6

- Discrete random variable is any (total) real function on finite domain $X:\Omega\rightarrow\mathbb{R}$.
- (Discrete) probability distribution is a table/function that assigns probability (

$$P_X(x) = P(X=x) = \frac{|X^{-1}(x)|}{|\Omega|}$$

of the corresponding outcomes to each value x in the range of the variable X .

Recall from Lecture for week 6 (cont.)

- There are several ways how to affiliate a probability space with random variable $X:\Omega\rightarrow\mathbb{R}$.
- One particular way:
 - $\Omega' = \{ S \subseteq \Omega : S = X^{-1}(x), x \in \mathbb{R} \};$
 - $\mathcal{F} = 2^{\Omega'};$
 - $P:\mathcal{F}\rightarrow[0,1]$ is the additive continuation on \mathcal{F} of a function defined as $P(X^{-1}(x)) = P_X(x)$ for every $x \in \mathbb{R}$.

Other way to Probability Space

- Adopt the set of outputs Ω as the sample space,
- use the standard event space $\mathcal{F} = 2^\Omega$;
- expand (in additive way) onto \mathcal{F} the standard probability function $P(\omega) = 1/|\Omega|$ for $\omega \in \Omega$.

Conditional (Discrete) Random Variable (simple case)

- Assume $A \subseteq \Omega$ is an “event” in 2^Ω . Then *conditional random variable* $X|A$ is the restriction of the function X on the domain A .
- It defines *conditional distribution*

$$\begin{aligned} P_{X|A}(x) &= P((X|A)=x) = \\ &= |(X=x) \cap A|/|A| = |X^{-1}(x) \cap A|/|A| = \\ &= P((X=x) | A). \end{aligned}$$

- Corollary: $P((X=x) \cap A) = P_{X|A}(x) * P(A)$

Conditional Expectation

- Conditional expectation – expectation of conditional random variable:

$$M(X|A) = \sum_{x \in R} x * P_{X|A}(x) .$$

- If H_1, \dots, H_n is a partition then

$$P(A) = \sum_{k \in [1..n]} P(A|H_k) * P(H_k)$$

and hence

$$P_X(x) = \sum_{k \in [1..n]} P_{X|H_k}(x) * P(H_k).$$

Total Expectation Formula

$$\begin{aligned} M(X) &= \sum_{x \in R} x * P_X(x) = \\ &= \sum_{x \in R} x * \left(\sum_{k \in [1..n]} P_{X|H_k}(x) * P(H_k) \right) = \\ &= \sum_{x \in R} \sum_{k \in [1..n]} x * P_{X|H_k}(x) * P(H_k) = \\ &= \sum_{k \in [1..n]} \sum_{x \in R} x * P_{X|H_k}(x) * P(H_k) = \\ &= \sum_{k \in [1..n]} \left(\sum_{x \in R} x * P_{X|H_k}(x) \right) * P(H_k) = \\ &= \sum_{k \in [1..n]} M(X|H_k) * P(H_k) \end{aligned}$$

Part IV

EXAMPLES OF CONDITIONAL AND TOTAL EXPECTATION

Back to Lottery (week 5)

Prize	1000	100	1	0
Probability	0.0001	0.001	0.01	0.9889

- If all tickets are sold out then $M(X) = 1000 * 0.0001 + 100 * 0.001 + 1 * 0.01 + 0 * 0.9889 = 0.1 + 0.1 + 0.01 = 0.21$.
- The minimal circulation consists of 10000 tickets including 1 with prize 1000, 10 - with prize 100 each, and 100 – with prize 1 each.

Back to Lottery (cont.)

- Event A: just 1000 tickets are sold out from the minimal circulation.
- $M(X|A) = \sum_{x \in R} x * P_{X|A}(x) =$
 $= 1000 * 1/1000 * P(1000\text{-ticket is sold}) +$
 $+ 100 * 1/1000 * P(1 \text{ of } 100\text{-tickets is sold}) + \dots$
 $+ 100 * 10/1000 * P(10 \text{ of } 100\text{-tickets are sold}) +$
 $+ 1 * 1/1000 * P(1 \text{ of } 1\text{-tickets is sold}) + \dots$
 $+ 1 * 100/1000 * P(10 \text{ of } 100\text{-tickets are sold}) =$
 $= 1000/9001 + \dots > 0.1111 + \dots > 0.1 + \dots = 0.21.$

Memoryless Property

- *Memorylessness* refers to the cases when the distribution of a waiting until a certain event does not depend on time.
- Only two kinds of distributions are memoryless: exponential and geometric distributions.

Memorylessness of Geometrical Distribution

- Let
 - $X = \text{Geom}(p)$ and
 - $(X > m) = \{\omega \in \Omega : X(\omega) > m\}$.
- $P(X = (m+n) \mid X > m) = P(X = m+n) / P(X > m) = P(n)$

Mean for Geometric Distribution

- If $X = \text{Geom}(p)$ then $M(X) = \sum_{k>0} k * p * (1-p)^{(k-1)}$.
 - Using total expectation formula with
 - $H_1 = (X=1)$, $P(H_1)=p$,
 - $H_2 = (X>1)$, $P(H_2)=q = (1-p)$:
- $$M(X) = M(X|H_1) * P(H_1) + M(X|H_2) * P(H_2).$$

Mean for Geometric Distribution (cont.)

- Due to memorylessness:
 $P(X=(1+n) \mid X>1) = P(X=n)$ for all $n>0$;
- hence $M(X \mid H_2) = M(1 + X) = 1 + M(X)$;
- It implies that $M(X) = 1 \cdot p + (1 + M(X)) \cdot q$;
- hence $M(X) = 1/p$.