

# CISC 372: Parallel Computing

## OpenMP, Part 4

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# Synchronization constructs

These constructs control synchronization among threads.

- ▶ `barrier`
- ▶ `ordered`
- ▶ `critical`
- ▶ `atomic`
- ▶ `master`

Note:

- ▶ except for `barrier`, these do not impose barriers

## Synchronization constructs: `barrier`

```
#pragma omp barrier
```

- ▶ a stand-alone construct: does not modify subsequent block
- ▶ all threads in a team block until every thread in team has reached the barrier
- ▶ all threads in a team must encounter the same sequence of worksharing and barrier constructs
- ▶ note most constructs already impose a barrier at end
  - ▶ so explicit barrier is **usually unnecessary**
- ▶ main use: control accesses to **shared variables** to avoid **data races**
  - ▶ e.g., one thread writes, **barrier**, other threads read

## Synchronization constructs: `ordered`

```
#pragma omp ordered  
S
```

- ▶ must occur inside an omp `for` loop using clause `ordered`
- ▶ the block  $S$  will be executed in iteration order
  - ▶ write  $S[i]$  for execution of  $S$  in  $i$ -th iteration
  - ▶  $S[i]$  will complete before  $S[i + 1]$  begins ( $i = 0, 1, \dots$ )
- ▶ this essentially forces iterations to execute sequentially
  - ▶ except there can be some overlap of the non-ordered code
- ▶ typical use cases: print statements, debugging

# Synchronization constructs: `critical`

```
#pragma omp critical [ ( name ) ]  
S
```

- ▶ declares  $S$  to be a **critical section**
- ▶ at any time: at most one thread can be executing inside a critical region named *name*
- ▶ in order for a thread to **start** executing  $S$ :
  - ▶ no other thread can be **inside** a critical region with same name as  $S$
- ▶ other threads may execute concurrently
  - ▶ as long as they are not in a critical region with same name as  $S$
- ▶ *name* is optional
  - ▶ all critical regions with no name are considered to have the same name, distinct from all named critical regions
- ▶ common uses: printing, computation of max or min, ...
  - ▶ complex modifications to shared data
    - ▶ don't want any other thread to "see" the data in an intermediate state
    - ▶ all threads access the data through critical regions with the same name
    - ▶ very similar to use of locks or Java's **synchronized**

## Synchronization constructs: `atomic`

```
#pragma omp atomic  
S
```

- ▶ following statement executes in one atomic step
- ▶ no other threads can intervene
- ▶  $S$  must be a simple assignment statement of a certain form (see OpenMP 4.0 Sec. 2.12.6)
- ▶ acceptable examples
  - ▶  $x++$ ,  $x--$ ,  $++x$ , or  $--x$
  - ▶  $x = x \text{ binop } expr$
  - ▶  $x \text{ binop} = expr$
  - ▶  $x = expr \text{ binop } x$
- ▶ binary operators:  $+$ ,  $*$ ,  $-$ ,  $/$ ,  $\&$ ,  $\wedge$ ,  $|$ ,  $\ll$ , or  $\gg$
- ▶ no function calls or other kinds of expressions
- ▶ can be more efficient than `critical`
  - ▶ can take advantage of low-level atomic operations

## Synchronization constructs: `master`

```
#pragma omp master  
S
```

- ▶ the associated block is executed by only the master thread of the team
- ▶ no barrier
- ▶ similar to `single`, but recall:
  - ▶ `single` can choose **any** thread (not just master)
  - ▶ `single` has a barrier at end by default

# OpenMP locks

- ▶ a type and functions to lock/unlock, similar to Pthread's mutexes
- ▶ considered “lower-level” primitives than the directive-based constructs
- ▶ type: `omp_lock_t`
- ▶ functions
  - ▶ `void omp_init_lock(omp_lock_t *lock);`
  - ▶ `void omp_destroy_lock(omp_lock_t *lock);`
  - ▶ `void omp_set_lock(omp_lock_t *lock);`
  - ▶ `void omp_unset_lock(omp_lock_t *lock);`



# The `threadprivate` directive

- consider the program `semiprivate.c`. What is the output?

```
#include <stdio.h>
#include <omp.h>
int x = 99;
void f() {
    x=omp_get_thread_num();
}
int main() {
#pragma omp parallel private(x) num_threads(5)
{
    int tid = omp_get_thread_num();
    f();
    printf("Thread %d: x = %d\n", tid, x);
}
printf("Final x = %d\n", x);
}
```

## semiprivate.c: output

```
omp$ gcc-mp-4.8 -fopenmp semiprivate.c
omp$ ./a.out
Thread 1: x = -348111896
Thread 2: x = -348111896
Thread 3: x = -348111896
Thread 4: x = 19907219
Thread 0: x = 0
Final x = 0
omp$
```

Why?

- ▶ the **private** clause affects only references to the variable inside the **construct** (the static extent), not the **region** (dynamic extent).
- ▶ if you want **x** to be **private** everywhere, you need to use the **threadprivate** directive.

## threadprivate.c

```
#include <stdio.h>
#include <omp.h>
int x;
#pragma omp threadprivate(x)
void f() {
    // this updates the private copy of x...
    x=omp_get_thread_num();
}
int main() {
#pragma omp parallel num_threads(5)
{
    int tid = omp_get_thread_num();
    f();
    printf("Thread %d: x = %d\n", tid, x);
}
printf("Final x = %d\n", x);
}
```

## threadprivate.c: output

```
omp$ ./a.out
Thread 1: x = 1
Thread 2: x = 2
Thread 0: x = 0
Thread 3: x = 3
Thread 4: x = 4
Final x = 0
omp$
```

- ▶ use this when you have a global variable you wish to share between functions
  - ▶ **and** you want it private
- ▶ you can even make the shared variable **persist between parallel regions**
  - ▶ certain requirements must be met
  - ▶ in particular, all the parallel regions in which variable is used must have same number of threads
- ▶ note the variable must be initialized inside a parallel region before it is used

# MPI/OpenMP hybrid programs

- ▶ for clusters of multicore nodes, you may
  - ▶ use **MPI everywhere**: one MPI process per core, or
  - ▶ use an **MPI+threads “hybrid”** model
    - ▶ one MPI process per node
    - ▶ threads within a node map to cores
    - ▶ threads may be specified by Pthreads, OpenMP, or some other thread API
- ▶ advantages of “MPI everywhere”
  - ▶ simpler
  - ▶ re-use all your old MPI programs with no changes!
  - ▶ performance often pretty good
    - ▶ sends and receives within a node implemented using **memcpy** or similar
- ▶ advantages of MPI+threads
  - ▶ might get better time performance
  - ▶ often uses **less memory**
    - ▶ in MPI everywhere, common data structures must be duplicated on every process, i.e., core
    - ▶ in MPI+threads, need only one copy of data structure on each node

## MPI with threads

- ▶ MPI does not have threads, but it does specify how MPI may interact with threads
- ▶ an MPI implementation may or may not be thread-compliant
- ▶ a process can request a certain level of thread support from MPI
- ▶ MPI will respond with the best thread support it can provide for that request
- ▶ different processes can request (and receive) different levels of support
- ▶ the interfaces for messages, etc., are the same whether or not there are multiple threads
  - ▶ hence a message sent by one thread on process  $p$  looks exactly the same as a message sent by another thread on  $p$
  - ▶ there is no way for another process to tell which thread it came from
  - ▶ a message sent by  $p$  to another process  $q$  cannot target a particular thread on  $q$
  - ▶ to participate in a collective routine, only one thread in  $p$  should call the collective functions

## Four levels of thread support are specified

1. `MPI_THREAD_SINGLE`: only one thread will execute
2. `MPI_THREAD_FUNNELED`
  - ▶ multiple threads may execute, but only the master thread will call MPI functions
3. `MPI_THREAD_SERIALIZED`
  - ▶ multiple threads may execute and call MPI functions, but at any time only one thread will be calling MPI
  - ▶ user needs to synchronize threads properly to ensure this
4. `MPI_THREAD_MULTIPLE`
  - ▶ multiple threads may call MPI functions at the same time
  - ▶ the implementation will ensure these calls are sequentialized

The following function should be called **instead of** `MPI_Init`:

```
int MPI_Init_thread(int *argc, char ***argv,  
                    int required, int *provided)
```

## Thread queries

```
int MPI_Query_thread(int *provided);
```

- ▶ returns provided level of thread support

```
int MPI_Is_thread_main(int *flag)
```

- ▶ true if calling thread is main thread, false otherwise