CISC 372: Parallel Computing

Wildcards and Nondeterminism

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"Wildcard" receives: MPI ANY SOURCE

MPI_Recv(buf, count, datatype, source, tag, comm, status)

- source argument can be MPI_ANY_SOURCE
 - special constant defined by MPI
 - means "receive message from any source"
 - use with care
 - introduce nondeterminism into the parallel program
 - program can produce different results on different executions
 - sometimes this is necessary (dynamic load-balancing)
 - do not use unless necessary for algorithm
- can use in combination with MPI_ANY_TAG

Wildcard receive: example using MPI_ANY_SOURCE: anysource.c

```
#include<stdio h>
#include<mpi.h>
int main() {
 int message, rank;
 MPI_Init(NULL, NULL);
 MPI_Comm_rank(MPI_COMM_WORLD, &rank);
 if (rank == 0) {
   message = 0; MPI_Send(&message, 1, MPI_INT, 2, 0, MPI_COMM_WORLD);
 } else if (rank == 1) {
   message = 1: MPI_Send(&message, 1, MPI_INT, 2, 0, MPI_COMM_WORLD);
 } else if (rank == 2) {
   for (int i=0; i<2; i++) {
     MPI_Recv(&message, 1, MPI_INT, MPI_ANY_SOURCE, 0, MPI_COMM_WORLD, MPI_STATUS_IGNORE);
     printf("Proc 2 received: %d\n", message);
 MPI_Finalize():
```

```
> mpiexec -n 3 ./anysource.exec
Proc 2 received: 0
Proc 2 received: 1
```

```
> mpiexec -n 3 ./anysource.exec
Proc 2 received: 1
Proc 2 received: 0
```

Semantics: matching

A send operation and a receive operation match if all of the following hold:

- 1 the communicators are the same
- 2. the rank of the receiver equals the dest argument in the send
- 3. the rank of the sender equals the source argument in the receive
 - ► OR the source argument is MPI_ANY_SOURCE
- 4. the tag in the send equals the tag argument in the receive
 - ► OR the tag argument is MPI_ANY_TAG

Note:

- ▶ the receiver can determine if an incoming message matches
 - by examining only the message envelope
- the message data plays no role in determining a match
- ▶ the message datatype plays no role in determining a match

Semantics: matching, cont.

- messages within a channel are ordered
 - a receive can only be matched with the oldest matching message in the channel
- messages in different channels are not ordered
 - ▶ a wildcard (MPI_ANY_SOURCE) receive can choose any incoming channel with a matching message
 - and select the oldest matching message from that channel

Message Ordering Example 1

```
Rank 0:
 MPI_Recv(MPI_ANY_SOURCE);
 MPI_Recv(MPI_ANY_SOURCE);
Rank 1:
 MPI_Send(to process 0);
Rank 2:
 MPI_Send(to process 0);
```

Which message gets matched with which receive?

Answer: either way — no order on messages in different channels

Message Ordering Example 2

```
Rank 0:
 MPI_Recv(MPI_ANY_SOURCE);
 MPI_Recv(MPI_ANY_SOURCE);
Rank 1:
 MPI_Send(to process 0);
 MPI_Send(to process 2);
Rank 2:
 MPI_Recv(from process 1);
 MPI_Send(to process 0);
```

Now process 1 sends its message to 0 before process 2 does. Which message gets matched with which receive? Answer: either way — no order on messages in different channels It doesn't matter that proc 1 sent before proc 2.

Message Ordering Example 3

```
Rank 0:
    MPI_Recv(MPI_ANY_SOURCE);
    MPI_Recv(MPI_ANY_SOURCE);

Rank 1:
    MPI_Send(to process 0);
    MPI_Send(to process 0);
```

Which message gets matched with which receive?

Answer: first send is matched with first receive, second send is matched with second receive Messages within a channel are ordered

Determinism and nondeterminism

- Programs restricted to
 - deterministic sequential operations
 - only one process performs I/O
 - MPI_Send. MPI_Recv, MPI_Sendrecv, MPI_Init, MPI_Finalize, MPI_Comm_rank, MPI Comm size MPI ANY TAG
 - collective operations other than reductions on floating-point numbers
 - ▶ but not MPI ANY SOURCE
- are guaranteed to be deterministic
 - given the same input twice, same output will be produced
 - even though the paths from input to output may be differ
- ► But if you add MPI_ANY_SOURCE
 - the program may be nondeterministic
 - given same input twice, two different outputs possible
 - see simplend.c

The need for barrier synchronization

- ▶ programs that use MPI_ANY_SOURCE sometimes require barrier synchronization!
- ▶ this is one of the few times barriers are absolutely needed

Wildcard deadlock example: function f

```
/* Each non-root process sends a message to root.
  Root receives using MPI_ANY_SOURCE.
  This is a perfectly fine deadlock-free function.
*/
void f() {
 if (myrank == 0) {
   MPI_Status status;
   int x:
   for (int i = 1; i < nprocs; i++) {</pre>
      MPI_Recv(&x, 1, MPI_INT, MPI_ANY_SOURCE, 0, comm, &status);
      printf("Proc 0: received %d from proc %d\n", x, status.MPI_SOURCE);
 } else {
   MPI_Send(&myrank, 1, MPI_INT, 0, 0, comm);
```

Wildcard deadlock example: function g

```
/* Each non-root process sends a message to root.
   Root receives in order of increasing rank.
   This is a perfectly fine deadlock-free function.
*/
void g() {
  if (myrank == 0) {
    MPI_Status status;
    int x:
    for (int i = 1; i < nprocs; i++) {</pre>
      MPI_Recv(&x, 1, MPI_INT, i, 0, comm, &status);
      printf("Proc 0: received %d from proc %d\n", x, status.MPI_SOURCE);
  } else {
    MPI_Send(&myrank, 1, MPI_INT, 0, 0, comm);
```

Wildcard deadlock example: function main

What happens when I call the two deadlock-free functions in sequence?

```
int main() {
 MPI_Init(NULL, NULL);
 MPI_Comm_size(comm, &nprocs);
 MPI_Comm_rank(comm, &myrank);
 f();
 g();
 MPI_Finalize();
```

```
mpiexec -n 4 ./wcdl.exec
Proc 0: received 1 from proc 1
Proc 0: received 1 from proc 1
Proc 0: received 2 from proc 2
^C[mpiexec@basie.local]
```

Deadlock!

Wildcard deadlock example: what happened?

- 1. proc 1 in function f sent message to proc 0
- 2. proc 1 in function g sent message to proc 0
- 3. proc 1 terminates
- 4. proc 2 in function f sent message to proc 0
- 5. proc 0 in function f received message from proc 1 at MPI_ANY_SOURCE
- 6. proc 0 in function f received message from proc 1 at MPI_ANY_SOURCE
- 7. proc 0 in function f received message from proc 2 at MPI_ANY_SOURCE
- 8. proc 0 in function g waits for message from proc 1

A message from proc 1 in g was received by proc 0 in f.

not what the programmer intended

Wildcard deadlock example: a solution

- place a barrier between f and g
- no one will be able to enter g until everyone has completed f

```
int main() {
  MPI_Init(NULL, NULL);
  MPI_Comm_size(comm, &nprocs);
  MPI_Comm_rank(comm, &myrank);
  f():
  MPI_Barrier(comm);
  g();
  MPI_Finalize():
```

```
mpiexec -n 4 ./wcdl.exec
Proc 0: received 3 from proc 3
Proc 0: received 1 from proc 1
Proc 0: received 2 from proc 2
Proc 0: received 1 from proc 1
Proc 0: received 2 from proc 2
Proc 0: received 3 from proc 3
```

Wildcards and nondeterminism

Load Balancing

- load balancing crucial to performance
- some problems can be broken up in a predictable way
 - ightharpoonup diffusion, π , sat
 - each process does (roughly) same amount of work
- for other problems this is difficult
 - no way to predict how long a task will take
 - many numerical algorithms require iterating until convergence
 - example: numerical integration
 - heterogenous hardware: processors running at different speeds
 - cyclic distributions are not always going to solve this problem

The Manager-Worker pattern

- break up problem into finite set of tasks
- there should be many more tasks than processes
- one process plays role of manager
- remaining processes are workers
- manager
 - distributes one task to each worker
 - 2. waits for any worker to send back result
 - 3. processes result and sends new task to that worker
 - 4. if no tasks remain, sends termination signal to worker instead
 - 5. when all results have been returned and termination signals sent, finished
- worker
 - 1. waits for task from manager
 - 2. solves the task and sends result to manager
 - 3. repeat until termination signal received

Non-determinism

- algorithm is inherently non-deterministic
- everything depends on the order in which workers send back results
- ▶ it is possible for one worker to do all but nprocs-2 tasks
- it is possible for workers to do same number of tasks
- manager must use some nondeterminisitic MPI construct, e.g.
 - ► MPI_ANY_SOURCE
 - ► MPI_Waitany
 - ► MPI_Waitsome
 - ► MPI Test
 - ► MPI_Testany
 - ► MPI Testsome
 - ► MPI Probe
 - MPI_Iprobe
- a correct program should return same result independent of these choices

Manager-worker example: matrix-matrix multiplication

 $A: N \times L$

 $B: L \times M$

 $C: N \times M$

Example: ${\cal N}=4$, ${\cal L}=3$, ${\cal M}=2$

$$\begin{bmatrix} a_{00} & a_{01} & a_{02} \\ a_{10} & a_{11} & a_{12} \\ a_{20} & a_{21} & a_{22} \\ a_{30} & a_{31} & a_{32} \end{bmatrix} \times \begin{bmatrix} b_{00} & b_{01} \\ b_{10} & b_{11} \\ b_{20} & b_{21} \end{bmatrix} = \begin{bmatrix} a_{00}b_{00} + a_{01}b_{10} + a_{02}b_{20} & a_{00}b_{01} + a_{01}b_{11} + a_{02}b_{21} \\ a_{10}b_{00} + a_{11}b_{10} + a_{12}b_{20} & a_{10}b_{01} + a_{11}b_{11} + a_{12}b_{21} \\ a_{20}b_{00} + a_{21}b_{10} + a_{22}b_{20} & a_{20}b_{01} + a_{21}b_{11} + a_{22}b_{21} \\ a_{30}b_{00} + a_{31}b_{10} + a_{32}b_{20} & a_{30}b_{01} + a_{31}b_{11} + a_{32}b_{21} \end{bmatrix}$$

- problem can be viewed as a series of matrix-vector multiplications
 - lacktriangle multiply row i of A by B to get row i of C $(i=0,\ldots N-1)$

$$\begin{bmatrix} A[0] \\ A[1] \\ A[2] \\ A[3] \end{bmatrix} \times B = \begin{bmatrix} A[0] \times B \\ A[1] \times B \\ A[2] \times B \\ A[3] \times B \end{bmatrix}$$

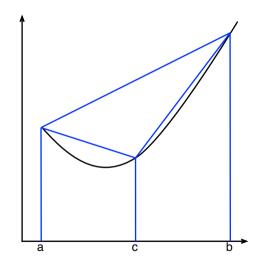
Matrix-matrix multiplication: matmat.c matmat_mpi.c

- sequential solution: matmat.c
- parallel solution: matmat_mpi.c
 - uses manager-worker pattern
 - ▶ a task: one row of A times B to get one row of C

Other sources of nondeterminism: floating-point

- addition and multiplication of real numbers are associative operations
- this is not true for floating-point numbers!
 - ► a+(b+c) does not necessarily equal (a+b)+c
 - whv?
 - round-off error
 - $ightharpoonup ext{ROUND}(a + ext{ROUND}(b + c))$ does not necessarily equal $ext{ROUND}(ext{ROUND}(a + b) + c)$
- ▶ this is a problem with MPI_Reduce used with floating-point numbers and MPI_SUM
 - could run the code twice and get two different answers
 - for most applications, differences are "small"
 - but not always
 - in any case: makes testing hard
- to parallelize sequential programs with floating point operations, for greatest assurance . . .
 - floating point operations should be identical in both programs
 - ▶ if one computes a+(b+c) the other must compute a+(b+c), not (a+b)+c
 - then they will get exact same result in all cases

Example: Numerical Integration with Trapezoid Rule



- ightharpoonup compute area A of large trapezoid
- divide interval in half
- ightharpoonup compute areas A_l and A_r of left and right trapezoids
- ightharpoonup compare $A_l + A_r$ with A
- if difference is "sufficiently small" return $A_l + A_r$
- else call recursively on left and right subintervals and return sum

Characteristics of Algorithm

- it is not known beforehand how many subdivisions will be required to achieve convergence
- the number of subdivisions may differ at different points on the x-axis
 - where curve is close to a straight line, fast converence
 - where higher derivatives are high, slower convergence
- balanced static partitioning of work not possible
- manager-worker pattern called for
 - break up [a, b] into subintervals in exact same way as sequential
 - \triangleright many more subintervals than processes (e.g., $100\times$)
 - task: compute integral over one subinterval
 - give each worker one task. . . .
 - manager sums results in exact same order as sequential

See integral_mpi.c