

~~We~~ we have seen that the Hofer-Zehnder capacity c_H is indeed a capacity. We are now going to use this to obtain results of dynamical nature.

Consider a symplectic manifold (M, ω) and a Hamiltonian function $H \in C^\infty(M, \mathbb{R})$.

Suppose $S = H^{-1}(c)$ is a regular level set for some $c \in \mathbb{R}$,
and assume S is cpt.

$\Rightarrow S$ is a ~~compact~~ closed submanifold of M of dimension 1.

$$\text{and } TS = (\ker dH)|_S.$$

It is easy to see that the Hamiltonian vector field X_H is tangent to S . Indeed, $dH(X_H) = -\omega(X_H, X_H) = 0$ on S .

Problem Does X_H admit closed orbits on S ?

First, ~~note~~ note that the existence of closed orbits does not depend on the choice of H .

Indeed, suppose $S = \{H = c\} = \{F = c\}$ for two Hamiltonians

$H, F \in C^\infty(M, \mathbb{R})$ with $dH, dF \neq 0$ on S .

Then, $\forall x \in S$: $\ker d_x H = \ker d_x F \Leftrightarrow$ ~~$d_x F = p(x) d_x H$~~ $d_x F = p(x) d_x H$,
for a nonvanishing smooth function p on S .

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$$\Rightarrow X_F = pX_H \text{ on } S.$$

If φ^t is the flow of X_H on S / we have $\varphi^s(x) = \varphi^t(x)$
 φ^s is the flow of X_F on S $\forall x \in S$,

where $t = t(x, s)$ is a function determined by the ODE

$$\begin{cases} \frac{dt}{ds} = f(\varphi^t(x)). \\ t(x, 0) = 0. \end{cases}$$

$\Rightarrow X_H, X_F$ have the same flow lines and, in particular, the same periodic orbits.

Remark

There is a geometric way of viewing this problem, that also shows independence of H .

Let $S \subseteq (M, \omega)$ be any codimension 1 submanifold.

Define $\mathcal{L}_S = \ker \omega|_S$. By nondegeneracy of ω on M and the

fact that $\dim S = 2n-1$, \mathcal{L}_S is a line bundle.

~~Suppose~~ If S is a φ^t regular level set of some $H: M \rightarrow \mathbb{R}$,

~~then~~ $X_H(x) \in \mathcal{L}_S(x) \forall x \in S$. (as we showed earlier).

(note that the condition $dH \neq 0$ on S implies $X_H \neq 0$ on S)

$\Rightarrow \mathcal{L}_S$ is orientable (in particular trivial).

Conversely, suppose $\mathcal{L}_S \rightarrow S$ is orientable. We will construct

a function $H: U \rightarrow \mathbb{R}$, where U is a nbhd of S such that

$S = H^{-1}(0)$ is a regular level set.

II

Pick an almost complex structure on T compatible with ω .

In particular, $\langle \cdot, \cdot \rangle = \omega(\cdot, J\cdot)$ is a scalar product.

Let $N_S = \{ \xi \in T \times \mathbb{R} \mid \langle \xi, v \rangle = 0 \ \forall v \in TS \}$ be the normal bundle of S . Note that the map

$$\begin{aligned} L_S \rightarrow N_S & \text{ is a bundle isomorphism.} \\ \xi & \mapsto J\xi \end{aligned}$$

L_S is trivial by assumption ~~and~~ N_S is trivial.

Pick a nonvanishing section $\nu: S \rightarrow N_S$ and define

$$\begin{aligned} \psi: S \times (-\varepsilon, \varepsilon) &\rightarrow \mathbb{R} \\ (x, t) &\mapsto \exp_x(t\nu(x)) \end{aligned}$$

This is a diffeomorphism onto a nbhd U of S if $\varepsilon > 0$ is small enough (we are using the fact that S is cpt).

If $F: S \times (-\varepsilon, \varepsilon) \rightarrow \mathbb{R}$, the desired Hamiltonian is given by

$$H := F \circ \psi^{-1}: U \rightarrow \mathbb{R}.$$

~~into that this shows that~~ L_S is called "characteristic line bundle" of S .

Our problem of finding closed orbits of X_H on S is thus purely geometric, i.e. it is equivalent to finding ^{on} embedded circles $P \subseteq S$ such that $TP = L_S|_P$. Such a circle is called a "closed characteristic".

Note that our construction provides a abd of S that is foliated by hypersurfaces diffeomorphic to S . This prompts the following definition:

Def. Let S be a cpt hypersurface in (M, ω) . A parametrized ~~and~~ family of hypersurfaces ~~of~~ modeled on S is a diffeomorphism

$\psi: S \times I \rightarrow U \subseteq M$, I open interval containing $0 \in \mathbb{R}$
such that $\psi(x, 0) = x \quad \forall x \in S$.

We are going to denote ~~the~~ such a family by $(S_\varepsilon)_{\varepsilon \in I}$.

~~We have thus shown the following~~

Rephrasing as work is for, we have shown that the following statement are equivalent:

- (i) $\mathcal{L}_S \rightarrow S$ is orientable
- (ii) $\mathcal{N}_S \rightarrow S$ is orientable
- (iii) S is orientable
- (iv) There exists a parametrized family of hypersurfaces modeled on S .
- (v) $\exists H: \bigcup_{\substack{U \\ \cap \\ \mathbb{R}}} \rightarrow \mathbb{R}$, U abd of S satisfying $dH \neq 0$ on S .

Our ~~search~~ search for closed characteristics starts with the following theorem by Hofer and Zehnder.

Theorem [Hofer-Zehnder]

Let S be a cpt hypersurface and (S_ε) a parametrized family of surfaces modeled on S . Let $P(S_\varepsilon)$ be the set of closed characteristics on S_ε . Then, if $\omega(U, \omega) < \infty$, there exists a dense set $\Sigma \subseteq I$ such that $P(S_\varepsilon) \neq \emptyset \quad \forall \varepsilon \in \Sigma$.

(IV)

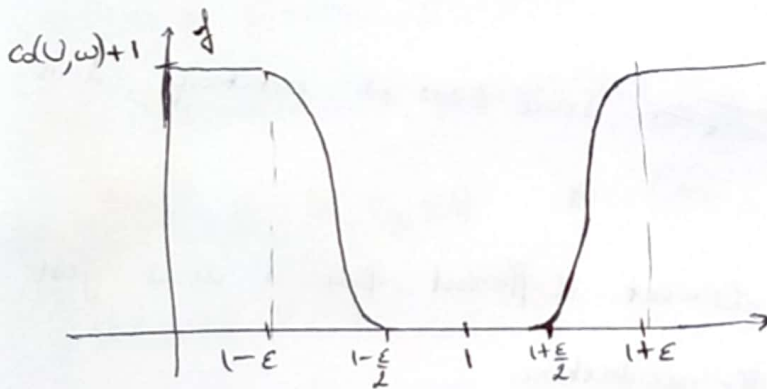
Proof: we are going to construct a special Hamiltonian on U that belongs to the set $\mathcal{H}(U, \omega)$ of functions used to define \mathcal{C}_0 .

~~Let S_λ be a surface in the family~~

~~Suppose~~ If $I = \{\lambda \mid 1-p < \lambda < 1+p\}$ for some $p > 0$, choose $0 < \varepsilon < p$.

~~Choose~~ Choose a smooth function $f: \mathbb{R} \rightarrow \mathbb{R}$ satisfying

$$\begin{cases} f(s) = \mathcal{C}_0(U, \omega) + 1 & \text{for } s \leq 1-\varepsilon, s \geq 1+\varepsilon \\ f(s) = 0 & \text{for } 1-\frac{\varepsilon}{2} \leq s \leq 1+\frac{\varepsilon}{2} \\ f'(s) < 0 & \text{for } 1-\varepsilon < s < 1-\frac{\varepsilon}{2} \\ f'(s) > 0 & \text{for } 1+\frac{\varepsilon}{2} < s < 1+\varepsilon \end{cases}$$



Define $F: U \rightarrow \mathbb{R}$
 $x \mapsto f(H(x)).$

$\Rightarrow F$ is constant on each S_λ
 and $F \in \mathcal{H}(U, \omega).$

Note that the oscillation $osc(F) = \max(F) - \min(F) = \mathcal{C}_0(U, \omega) + 1 > \mathcal{C}_0(U, \omega).$

By definition of \mathcal{C}_0 , there exists a nonconstant periodic orbit $x(t)$ having period $0 < T \leq 1$ of the system $\dot{x} = X_F(x)$, $x \in U$.

It is easy to show that $X_F(x) = f'(H(x)) X_H(x)$. (*)

Moreover, $H(x(t))$ is constant w.t. Indeed,

$$\frac{d}{dt} H(x(t)) = dH(X_F(x(t))) = -\omega(X_H(x(t)), X_F(x(t))) = 0.$$

$$\Rightarrow \text{Hence } H(x(t)) \equiv \lambda.$$

Since $x(t)$ is nonconstant, we have (in view of (*))

$$1 - \varepsilon < \lambda < 1 + \frac{\varepsilon}{2} \quad \text{or} \quad 1 + \frac{\varepsilon}{2} < \lambda < 1 + \varepsilon.$$

If $f'(\lambda) = \tau \neq 0$, define $y: \mathbb{R} \rightarrow S_\lambda$, $y(t) = x\left(\frac{t}{\tau}\right)$.

y has period τT and satisfies $\dot{y} = X_H(y)$.

$\Rightarrow y$ is periodic orbit of X_H on S_λ .

By construction, $\|\lambda - 1\| < \varepsilon$. Since $\varepsilon > 0$ is arbitrary, λ is arbitrarily close to 1.

To get the statement for any other element different from 1 we just replace 1 with element and repeat the construction.

~~Question~~ Question we have found solutions on a dense set of S_λ 's. Does there exist a solution on $S_1 = S$?

If we know that the periods T_j of the orbits x_j on S_{λ_j} for $\lambda_j \rightarrow 1$ are bounded $\hat{=}$ uniformly, then the answer is positive.

Let us make this more precise.

Let g be a ^{minimum} vector in M .
 $\langle \cdot, \cdot \rangle$

If $x(t)$ is a period solution, we define its length

$$l(x) = \int_0^T \| \dot{x}(t) \| dt$$

Possibly after shrinking U , we can assume $\frac{1}{C} \leq \|X_H\| \leq C$ on U .

for some $C > 0$.

$$\Rightarrow \frac{T_j}{C} \leq l(x_j) \leq CT_j \quad \forall j.$$

Proposition. Let $\lambda_j \rightarrow 1$ and assume (1_j) is bounded. Then $S = S_1$ admits a periodic solution.

Proof: rescale the periods to 1 by defining $y_j(t) = x_j(T_j t)$, $t \in [0, 1]$.

$$\Rightarrow \begin{cases} \dot{y}_j(t) = T_j X_H(y_j(t)) \\ H(y_j(t)) \equiv \lambda_j. \end{cases} \quad (*)$$

Note that $T_j X_H(y_j(t))$ is bounded by assumption.

$\Rightarrow (y_j)$ is equibounded and bounded. By the Arzelà-Ascoli theorem,

we can assume $y_j \xrightarrow{C^0} y$. By using $(*)$, we see that this convergence is actually in the C^1 -topology. \Rightarrow we get a 1-periodic solution y ,

~~with~~ i.e. $\dot{y}(t) = X_H(y(t))$ with $H(y(t)) = 1$.

If the period T of y is not 0, we are done.

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VII

Suppose $T=0 \Rightarrow y_j \rightarrow y^*$, where $y^* \in S$ is a point.

$$\Rightarrow X_H(y_j(t)) \rightarrow X_H(y^*) =: V.$$

Since S is a regular level set, $X_H \neq 0$ on $S \Rightarrow V \neq 0$.

Note that $\langle X_H(y_j(t)), V \rangle \geq (1-\epsilon) \|V\|^2$ for large j and ϵ small.

$$\Rightarrow \frac{1}{T_j} \langle y_j(t), V \rangle \geq (1-\epsilon) \|V\|^2 \quad \left(\text{this makes sense in local coordinates} \right. \\ \left. \text{and we are using the standard} \right. \\ \left. \text{euclidean product} \right)$$

$$\text{However, } 0 = \int_0^{T_j} \frac{1}{T_j} \langle y_j(t), V \rangle dt = \int_0^{T_j} \frac{d}{dt} \left(\frac{1}{T_j} \langle y_j(t), V \rangle \right) dt = T_j (1-\epsilon) \|V\|^2$$

$\Rightarrow \|V\|=0$, contradiction ■

Remark We can apply Hofer-Zehnder to ~~cpt~~ cpt hypersurfaces in $(\mathbb{R}^{2n}, \omega_0)$. Since we can always embed such surfaces in large enough balls, which have finite capacity, we can apply the theorem.

We are now going to restrict the class of hypersurfaces we consider in order to ~~be~~ be able to apply the previous proposition.

~~Since S is the boundary of some~~ We are going to consider two classes ~~of~~ ~~actually~~ ~~as~~ the second is a subclass of the first).

(I): Let $S \subseteq (M, \omega)$ be a cpt hypersurface and assume S is the boundary of some compact symplectic manifold $(B, \omega) \subseteq (M, \omega)$.

Let (S_ϵ) be a parametrized family of surfaces modeled on S .

$\Rightarrow S_\epsilon$ bounds a manifold B_ϵ . Assume the parametrization is such that $\epsilon < \epsilon' \Rightarrow B_\epsilon \subseteq B_{\epsilon'}$.

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