



Radar Data Assimilation with WRFDA

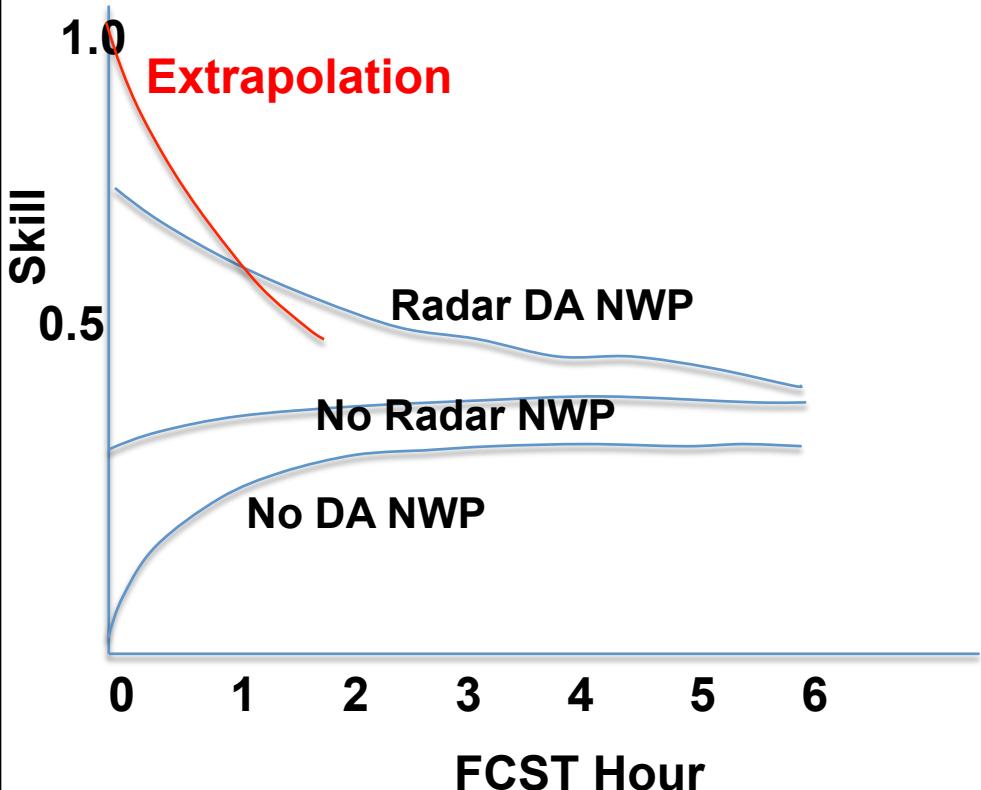
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OUTLINE

- Motivation, milestones, and current capabilities
- Radar DA method in WRFDA
- Configure and run WRFDA-radar
- Applications and ongoing research

Why radar data assimilation



Objectives of radar data assimilation

- Improve **short-term** prediction of high impact weather
- For the very short-term range, an ambitious goal is to forecast the **timing and location** of storms at **county/city scale**
- Improved understanding of mesoscale processes contributing to the formation of convective weather (may require advanced DA techniques)

Radar data: the good and the bad

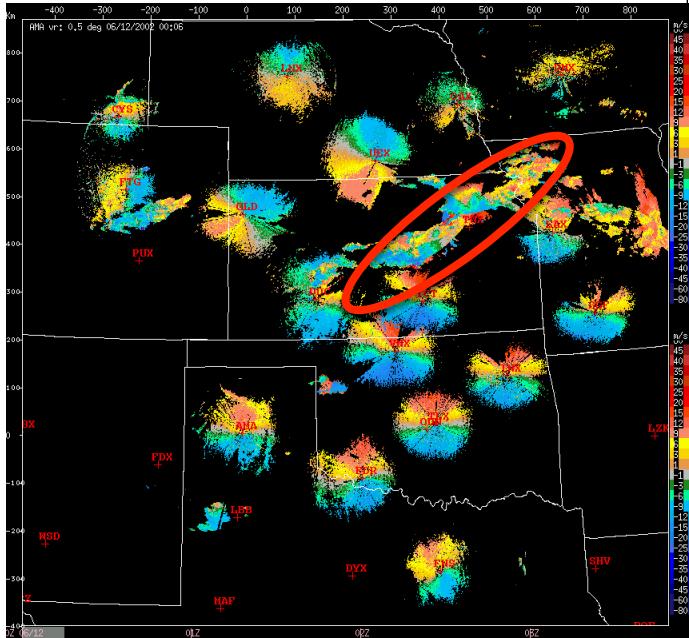
Good

- High spatial and temporal resolutions at the convective-scale
- Observes wind (radial velocity) as well as microphysics (reflectivity)
- Accurate observations
- Observations are mostly in the lower atmosphere

Not so good

- Indirect observations – need observation operators
- Incomplete coverage – limited range and limited detection ability in clear air
- Only radial velocity and reflectivity
- Nontrivial for QC
- Locally available

Radial velocities from 20 WSR-88D radars



Scientific issues for radar DA

- Impact of radar data assimilation on convective forecasting
(Xiao et al. 2005, 2007)
- Validity of the linearization of the observation operator for reflectivity
(Wang et al. 2013)
- Validity of the tangent linear model approximation for highly convective weather
(Wang et al. 2014)
- How well does 4DVar perform in comparison with 3DVar
(Sun and Wang 2014)
- Impact of the choice of momentum control variables
(Sun et al 2016)
- Controlling noise in high-resolution analysis with multi-scale balance
(Vendrasco et al. 2016, Tong et al. 2017)

WRFDA-radar development milestones

- 2005:** radial velocity data assimilation with WRFDA 3DVar ([Xiao et al. 2005](#))
- 2007:** reflectivity data assimilation using a partition scheme to obtain microphysics ([Xiao et al. 2007](#))
- 2013:** indirect assimilation of reflectivity using q_r and q_c as control variables ([Wang et al. 2013](#))
- 2014:** adjoint of Kessler scheme for 4DVar radar data assimilation ([Wang et al. 2014](#))
- 2015:** new momentum control variables (u/v) for radar data assimilation ([Sun et al. 2016](#))
- 2015:** a large-scale analysis constraint to maintain large-scale balance ([Vendrasco et al. 2016](#))
- 2017:** a strategy for hourly update cycles ([Tong et al. 2017](#))
- 2017:** a scheme for assimilating “no rain” reflectivity data ([Gao et al., submitted](#))

Current capabilities

3DVar

- Assimilate both radial velocity and reflectivity
- Direct and Indirect assimilation of reflectivity
- “Warm start” by assimilating estimated humidity within cloud
- Options for choice of momentum control variables
- Constraint terms (J_c) for controlling analysis noise
- Operational 3h/1h cycles since 2014

4DVar

- Use WRF tangent linear model as constraint with multiple outer loops
- Can be run with multi-incremental option
- Adjoint of physics schemes: modified Kessler microphysics, large-scale condensation, a simple cumulus scheme, and diffusion scheme
- Assimilate both radar and rainfall data
- 4DVar framework is fully consistent with 3DVar

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Two methods for reflectivity DA

1. *Direct assimilation of reflectivity (Xiao et al. 2007)*

- Requires an observation operator to link the reflectivity with microphysics
- No cloud control variables
- Vertical velocity is diagnosed using the Richardson equation
- Microphysics are diagnosed using a warm rain partition scheme

2. *Indirect assimilation of reflectivity*

(Wang et al. 2013, preferred)

- Diagnose microphysics (q_r , q_s , q_g) and humidity from reflectivity
- Assimilate the diagnosed quantities
- Cloud control variables and vertical velocity control variable

Cost Function

Indirect method with cloud control variables

$$J = J_b + J_o + \underbrace{J_{v_r} + J_{q_r} + J_{q_v}}_{\text{For radar DA}}$$

- **Control variables :**
 u/v (or Ψ/X_u), T (or T_u), Ps (or Ps_u), RHs, q_c , q_r , and w
- **3DVar critically depends on a cloud analysis scheme that assimilates estimated in-cloud humidity**
- **A modified Kessler scheme along with its adjoint produces analyses of microphysics in 4DVar**

Radial velocity observation operators

$$J_{vr} = \frac{1}{2} \sum (V_r - V_r^{ob})^2 / \sigma_{vr}$$

V_r Radial velocity from the model

V_r^{ob} Radial velocity observations

σ_{vr} Observation error variance

v_r - (u, v, w, q_r) Relation:

$$v_r = \frac{x - x_r}{r} u + \frac{y - y_r}{r} v + \frac{z - z_r}{r} (w - V_T(q_r))$$

Radial velocity observation operator

$$J_{qr} = \frac{1}{2} \sum (q_r - q_r^{ob})^2 / \sigma_{qr}$$

q_r Model rainwater mixing ratio

q_r^{ob} Estimated rainwater mixing ratio from reflectivity

σ_{qr} Observation error variance

Z-q_r Relation (assume Marshal-Palmer DSD)

$$Z = 43.1 + 17.5 \log_{10}(\rho q_r) \quad \text{Sun and Crook (1997)}$$

Z-q_s and Z-q_h follow Gao and Stensrud (2012)

Pseudo humidity assimilation

$$J_{qv} = \frac{1}{2} \sum (q_v - q_v^{ob})^2 / \sigma_{qv}$$

q_v Model water vapor mixing ratio

q_v^{ob} Estimated water vapor mixing ratio by assuming near saturation above LCL within cloud

σ_{qv} Observation error variance

Namelist options:

cloudbase_calc_opt

Option for calculating cloud-base height: below this height retrieved humidity will not be assimilated for the `use_radar_rqv` option

0: fixed value of 1500 meters

1 (default): KNU scheme

2: NCAR scheme

radar_saturated_rf

rf value (dBz) used to indicate precipitation for rqv (default 25.0)

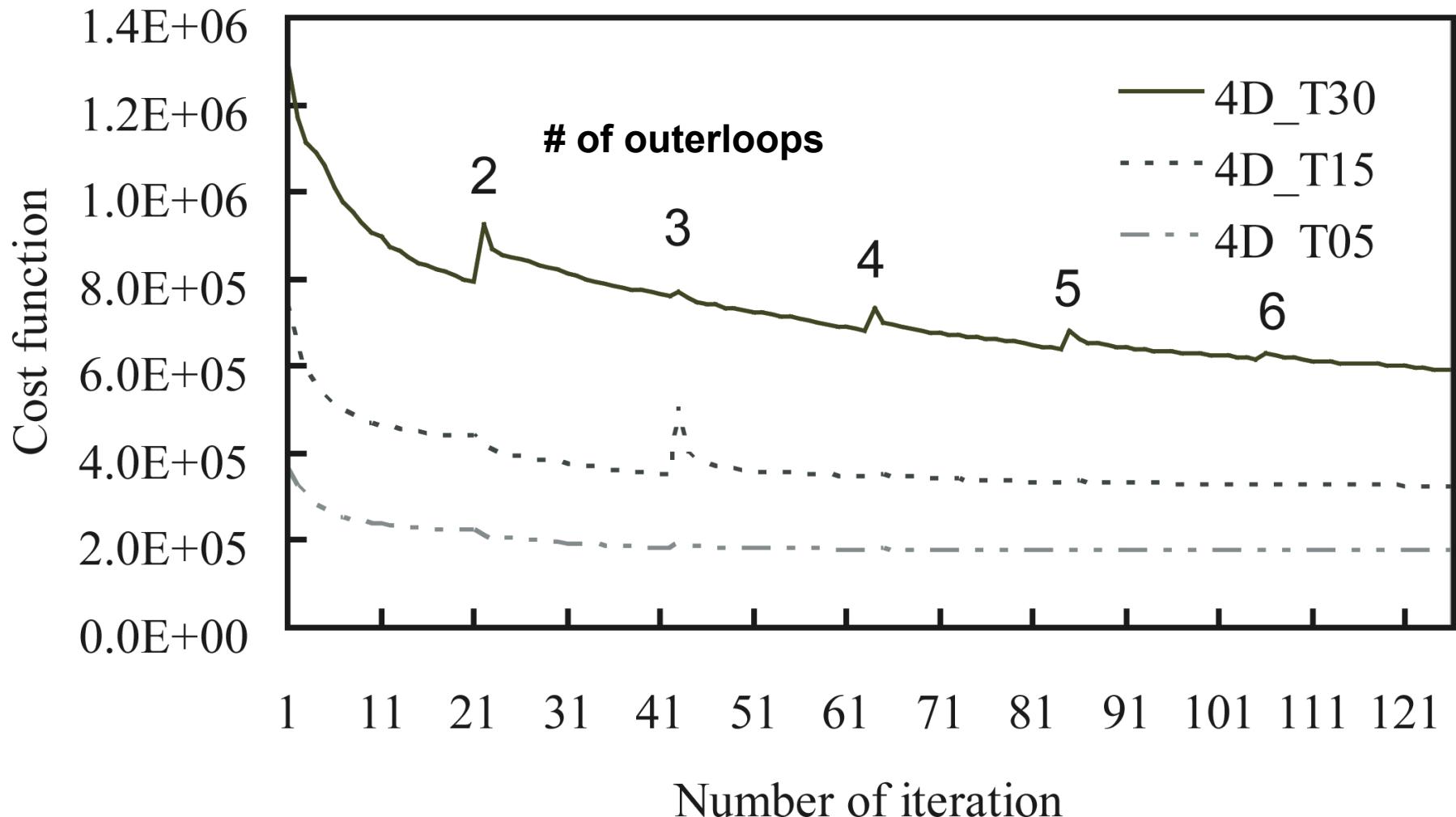
Multi-incremental 4DVar

Following Courtier et al. 1994, WRFDA uses a multi-incremental formulation, which means

- **The forward prediction model within the 4DVar window is an approximation of the nonlinear model**
- **The control variables are increments from the forward model trajectory**
- **The formulation requires the update of analysis increment in an inner loop but also the update of the nonlinear model in an outer loop**
- **It makes the cost function better conditioned and allows different spatial resolutions for the inner and outer loops – multi-incremental**

Details in Huang et al. (2010) and Wang et al (2013)

Cost function reduction with 6 outer loops and 3 different lengths of windows



4DVar physics options

	WRFTL & AD	WRFNL
mp_physics	mp_physics_ad=98 Large scale condensation Mp_physics_ad=99 Modified Kessler scheme	mp_physics can be set to any options for WRF It can also be set to 98 or 99, same as WRFTL & AD
cu_physics	cu_physics = 0: no cumulus scheme cu_physics=98: Simplified CU scheme Any other numbers will be Defaulted to 98	Same as the left column

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Radar DA options in Namelist

- **Read radar data**
`use_radarobs = true,`
- **Assimilate radial velocity**
`use_radar_rv=true,`
- **Two methods for reflectivity assimilation**
`use_radar_rf =true; (direct method; Xiao et al. 2007)`
`use_radar_rhv=true; (indirect method; Wang et al. 2013)`
- **Assimilate pseudo humidity**
`use_radar_rqv=true,`
- **3DVar (default) or 4DVar**
`var4d=true`
- **Microphysics control variables**
`cloud_cv_options = 3 BE of regular variables are from gen_be; cloud variables hard coded`
- **u/v momentum control variables**
`cv_options = 7 5: psi/chi CV 7: u/v CV (7 is recommended for radar)`
- **Several options for assimilating weak radar echoes – “no rain” data**
`See the user guide`

Basic steps for radar DA

Step 1: prepare radar data in the correct format and write the data into **ob.radar** (**ob01.radar**, **ob01.radar**, ... for 4DVar)

- Use your own QC software
- $(\varphi, r, \theta) \Rightarrow (x, y, \theta)$ => Lat/Ion profiles => merge the radars into one file

Step 2: produce 1-3 month WRF forecasts (12h & 24h) over the study domain, and then compute BE using the WRFDA utility **gen_be**

Step 3: modify the **namelist.input** to make radar DA choices

Step 4: conduct single observation tests to tune the length scale and variance for your specific domain

- 200km for GTS data and 30km for radar data are commonly used

Step 5: configure WRFDA: to invoke the “CLOUD_CV” option, do the following in the **configure script**

setenv CLOUD_CV 1 - for csh

Export CLOUD_CV = 1 - for both ksh and bash

STEP 6: link ob.radar and other other observation files and first guess

Data format

```
write(301,'(a14,i3)') 'Total number =', nrad
write(301,'(a)')
'-----#'
write(301,'(a)' )
do irad = 1, nrad ! nrad: total # of radar
!--- Write header
write(301,'(a5,2x,a12,2(f8.3,2x),f8.1,2x,a19,2i6)') 'RADAR', &
radar_name, rlonr(irad), rlatr(irad), raltr(irad)*1000., &
trim(radar_date), np, imdv_nz(irad)    write(301,'(a)' ) &
'-----#'
write(301,*)
!----Write data
do i = 1,np ! np: # of total horizontal data points
write(301,'(a12,3x,a19,2x,2(f12.3,2x),f8.1,2x,i6)') 'FM-128 RADAR', &
trim(radar_date), plat(i), plon(i), raltr(irad)*1000, count_nz(i)
do m = 1,count_nz(i) ! count_nz(i): # of vertical elevitions for each radar
write(301,'(3x,f12.1,2(f12.3,i4,f12.3,2x))') hgt(i,m), &
rv_data(i,m), rv_qc(i,m), rv_err(i,m), &
rf_data(i,m), rf_qc(i,m), rf_err(i,m)
enddo
enddo
enddo
```

Data format

Header

nrad: total number of radars

radar_name: name of the ith radar (irad)

rlonr, rlatr, raltr: longitude, latitude, and altitude of irad

radar_date: date of irad observation

np: number of total data points for irad

imdv_nz: number of total elevation angles of irad

Data

plat, plon, raltr: longitude, latitude, and altitude of the ith data point

count_nz: number of data levels at the ith data point

hgt(i,m): height of ith data point at m level

rv_data(i,m), rv_qc(i,m), rv_err(i,m): radial velocity value, qc index, and obs error. The qc index ≥ 0 means good data; otherwise bad data.

rf_data(i,m), rf_qc(i,m), rf_err(i,m): reflectivity value, qc index, and obs error

Example of radar input data

TOTAL NUMBER = 16

#-----#

RADAR	KCYS	-104.806	41.152	1887.0	2015-07-07_21:00:00	5497	11
#-----#							
FM-128 RADAR	2015-07-07_21:00:00	41.165		-107.189	1887.0		3
3735.9	-888888.000	-88	-888888.000	10.288	0	0.576	
5128.9	-888888.000	-88	-888888.000	13.029	0	0.944	
6870.5	-888888.000	-88	-888888.000	8.192	0	1.229	
FM-128 RADAR	2015-07-07_21:00:00	41.192		-107.189	1887.0		3
3737.3	-888888.000	-88	-888888.000	10.262	0	0.746	
5130.6	-7.381	0	1.692	13.338	0	0.473	
6872.5	-888888.000	-88	-888888.000	8.373	0	0.626	
FM-128 RADAR	2015-07-07_21:00:00	41.219		-107.189	1887.0		3
3740.0	-888888.000	-88	-888888.000	9.447	0	1.072	
5133.9	-8.476	0	1.632	12.828	0	0.833	
6876.7	-888888.000	-88	-888888.000	8.969	0	0.991	
FM-128 RADAR	2015-07-07_21:00:00	41.246		-107.189	1887.0		3
3744.2	-888888.000	-88	-888888.000	12.750	0	1.918	
5139.0	-888888.000	-88	-888888.000	15.127	0	0.948	
6883.0	-888888.000	-88	-888888.000	11.409	0	0.932	
FM-128 RADAR	2015-07-07_21:00:00	41.138		-107.153	1887.0		3
3645.0	-888888.000	-88	-888888.000	11.011	0	0.882	
5017.0	-888888.000	-88	-888888.000	12.650	0	0.879	
6732.4	-888888.000	-88	-888888.000	6.896	0	1.287	
FM-128 RADAR	2015-07-07_21:00:00	41.165		-107.153	1887.0		3
3645.0	-888888.000	-88	-888888.000	11.477	0	0.804	
5017.0	-5.278	0	1.641	13.550	0	0.990	
6732.4	-888888.000	-88	-888888.000	9.280	0	2.035	
FM-128 RADAR	2015-07-07_21:00:00	41.192		-107.153	1887.0		3
3646.4	-0.267	0	4.448	11.606	0	1.225	
5018.7	-5.217	0	1.843	14.294	0	0.731	
6734.5	-888888.000	-88	-888888.000	10.094	0	2.072	

Tuning BES parameters

To change BES variance and length scale, do the following in your namelist.input:

To decrease the weight of the background

VAR_SCALING1=2.0

VAR_SCALING2=2.0

VAR_SCALING3=2.0

VAR_SCALING4=2.0

VAR_SCALING5=2.0

To decrease the length scale

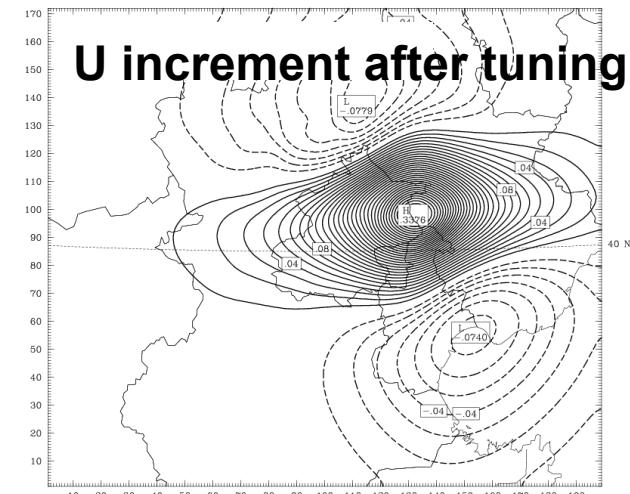
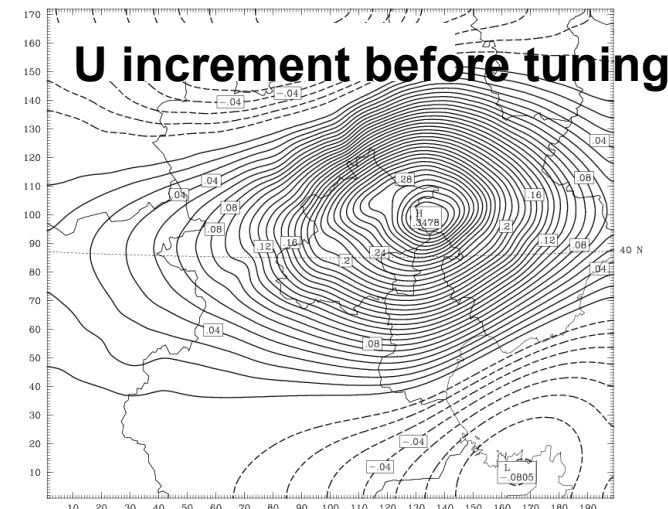
LEN_SCALING1=0.5

LEN_SCALING2=0.5

LEN_SCALING3=0.5

LEN_SCALING4=0.5

LEN_SCALING5=0.5



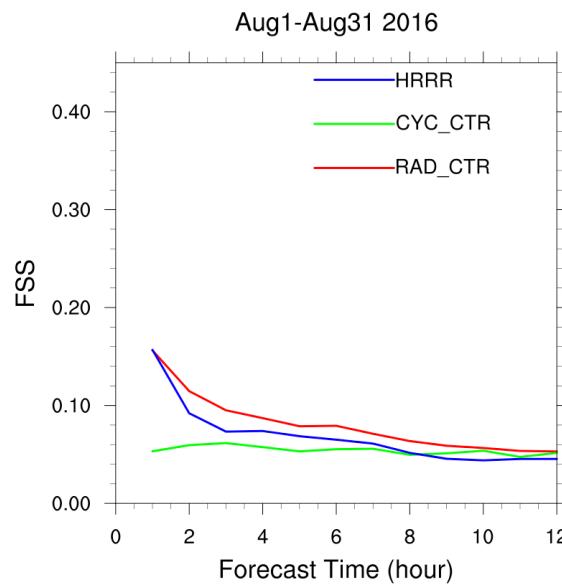
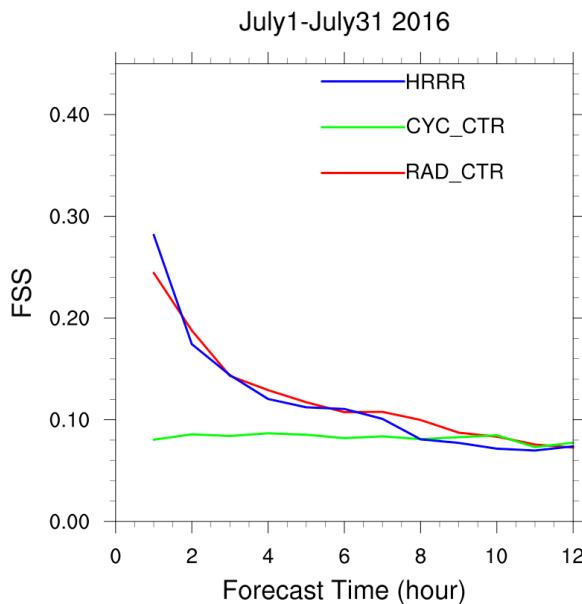
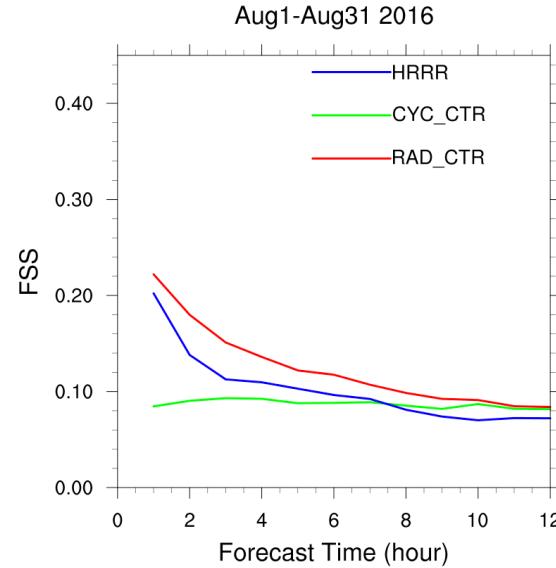
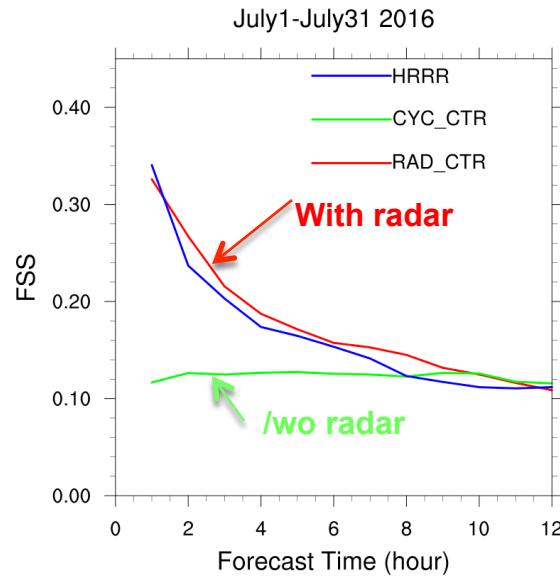
A note on u/v momentum CV

- The new control variable (CV) option CV7 which uses u/v instead of psi/chi as momentum control variables is added in WRFDA3.7
- CV7 requires the computation of BES of u and v
- In the current version, correlation between variables is not considered
- But will be studied and included in a future release
- Sun et al. (2016, MWR)

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Impact of radar data assimilation (FSS)



1mm

2.5 mm



Comparing forecasts with/wo radar

2016080704

2016080705

2016080706

MRMS

MRMS

MRMS

CYC_CTR
 $t = 1\text{h}$

CYC_CTR
 $t = 2\text{h}$

CYC_CTR
 $t = 3\text{h}$

RAD_CTR
 $t = 1\text{h}$

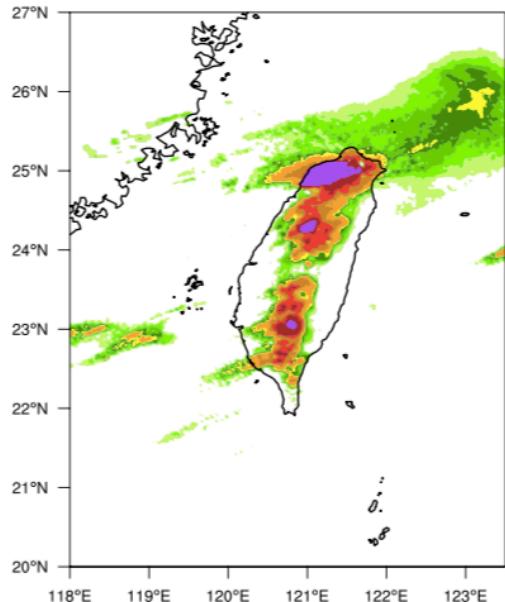
RAD_CTR
 $t = 2\text{h}$

RAD_CTR
 $t = 3\text{h}$

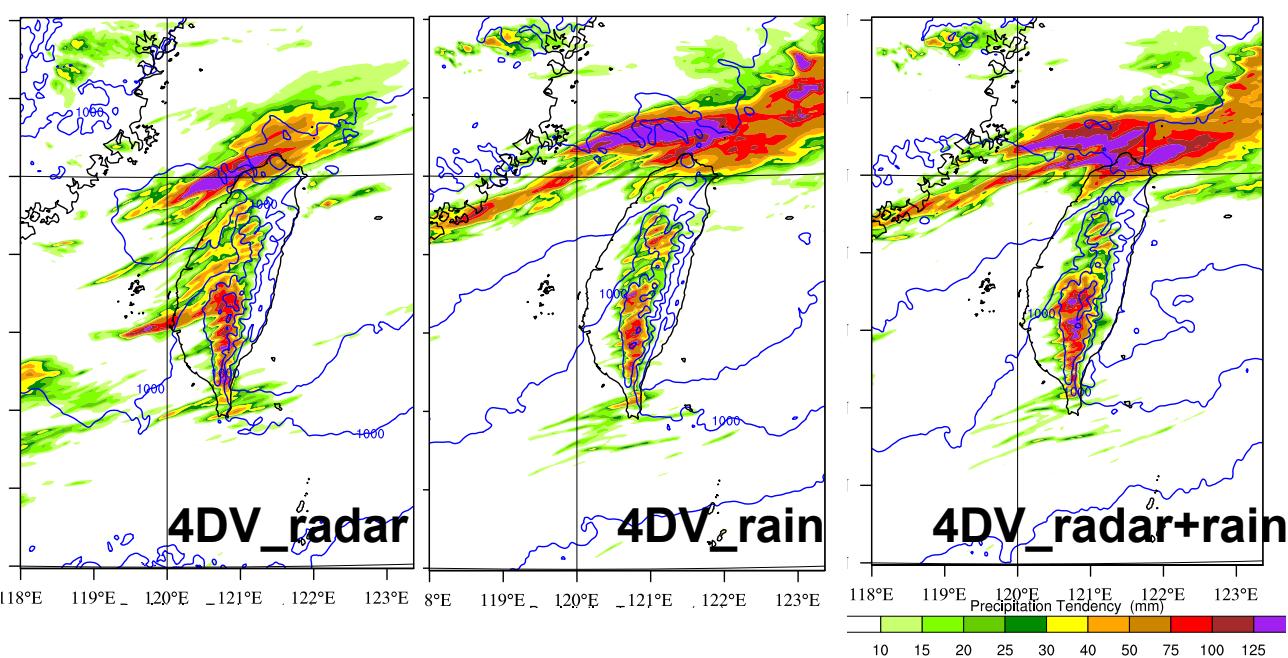


Impact of assimilating both radar and rainfall

6hour Precip(QPE): 2012061121

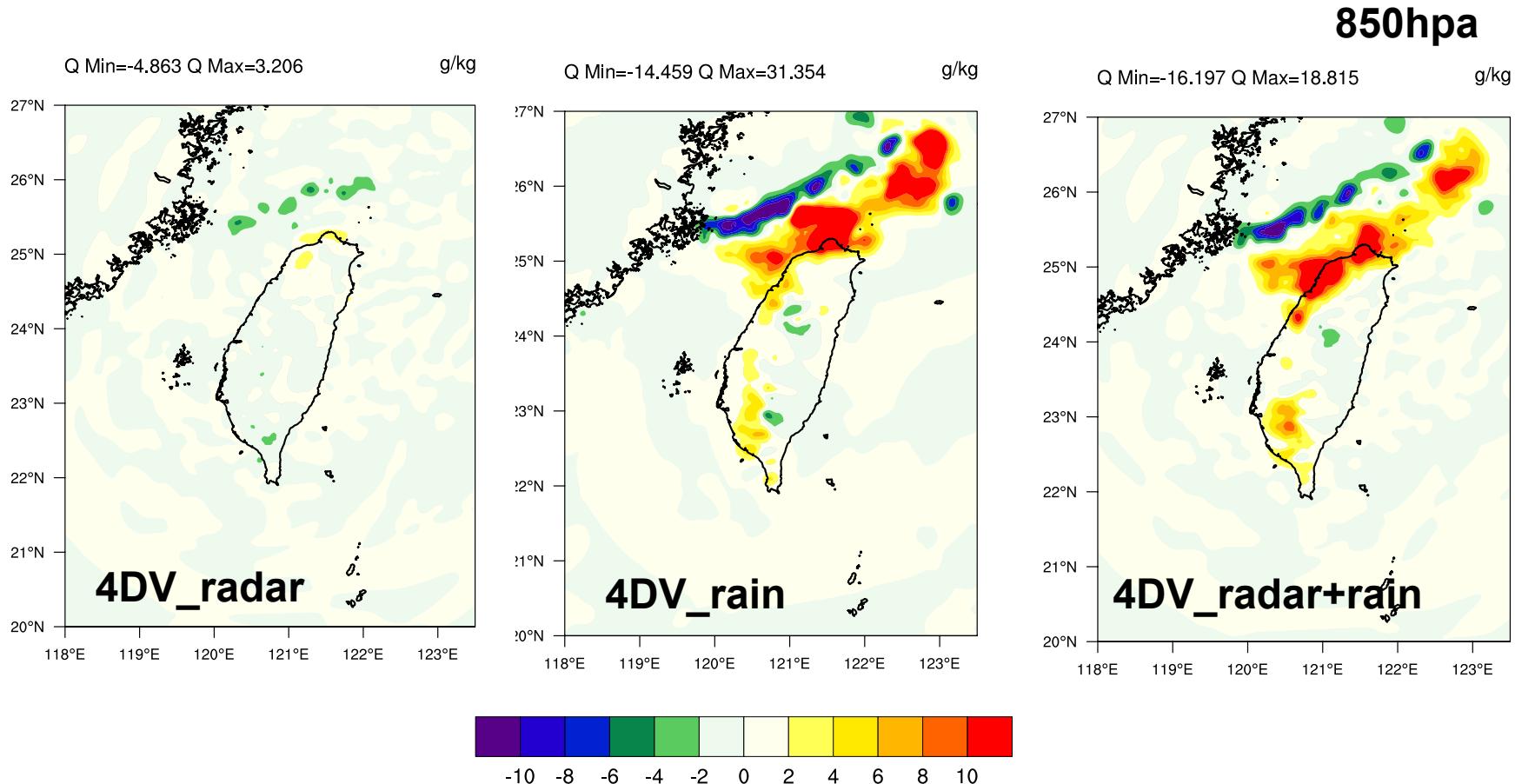


6h accumulated rainfall forecasts



- Radar+rain shifted the northern rain band to the land, agreeing better with QPE
- Radar+rain also improved the intensity of the precipitation on the mountains in southern Taiwan
- Combined assimilation of radar and 10min rainfall data with a 20min 4DVAR window is an innovative study; the result is promising

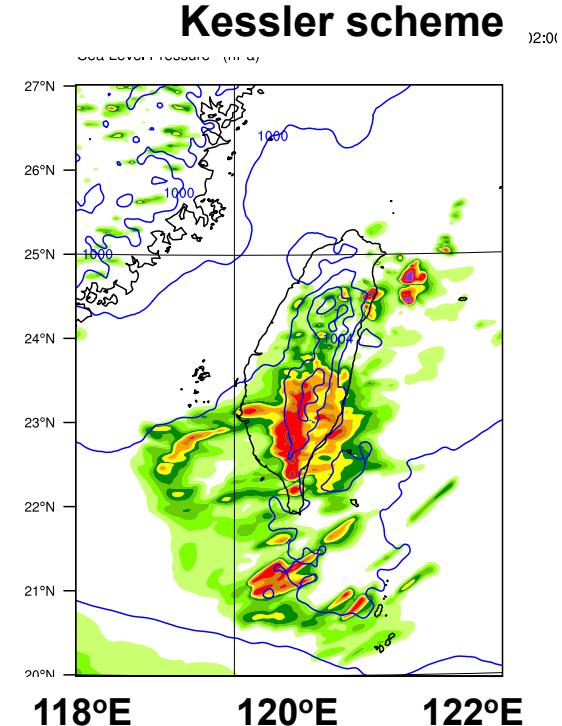
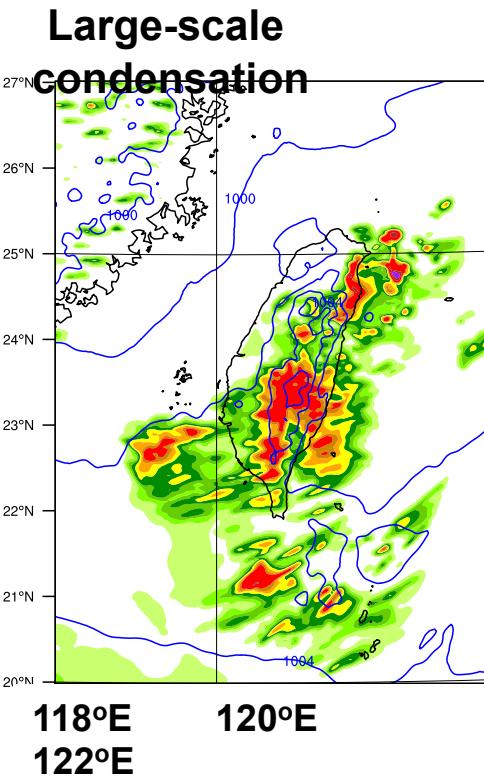
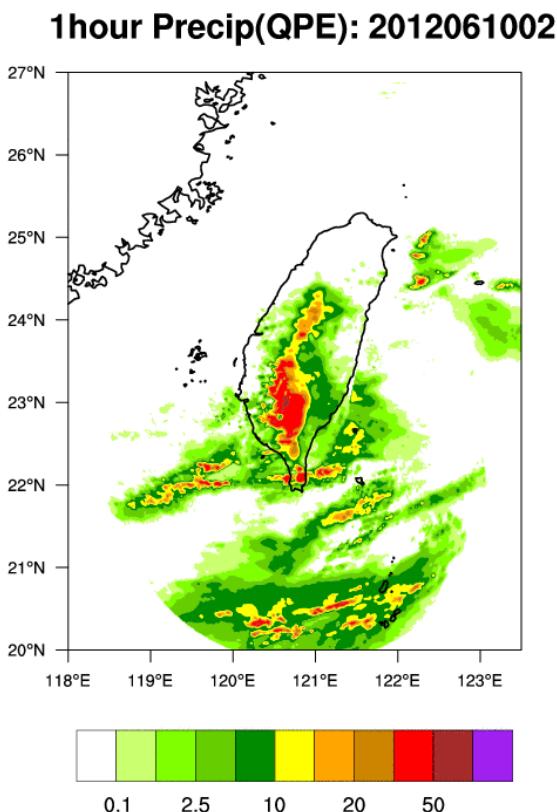
Comparison of humidity increments



- Combined assimilation of radar and rainfall tuned down the overly large humidity increment from that of the rainfall only experiment
- Combined assimilation also moved the humidity increment to the land

Sensitivity of physics in the TL and AD models

Precipitation forecasts at $t = 2\text{h}$ for a Meiyu case occurred in Taiwan

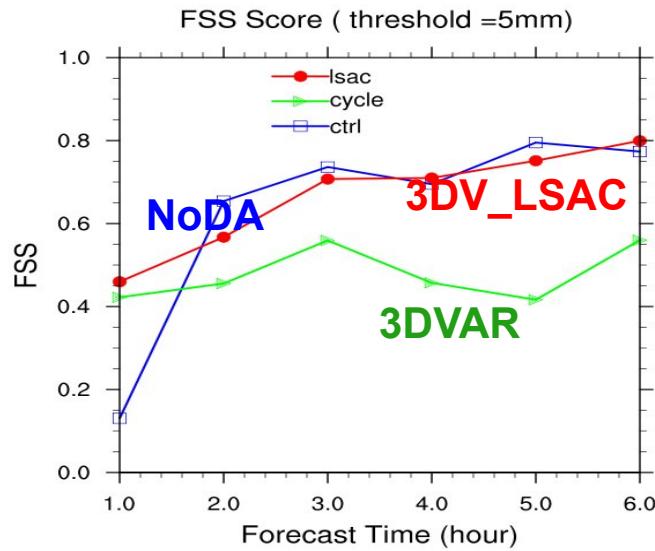


Impact of LSAC on 3DVAR DA (future release)

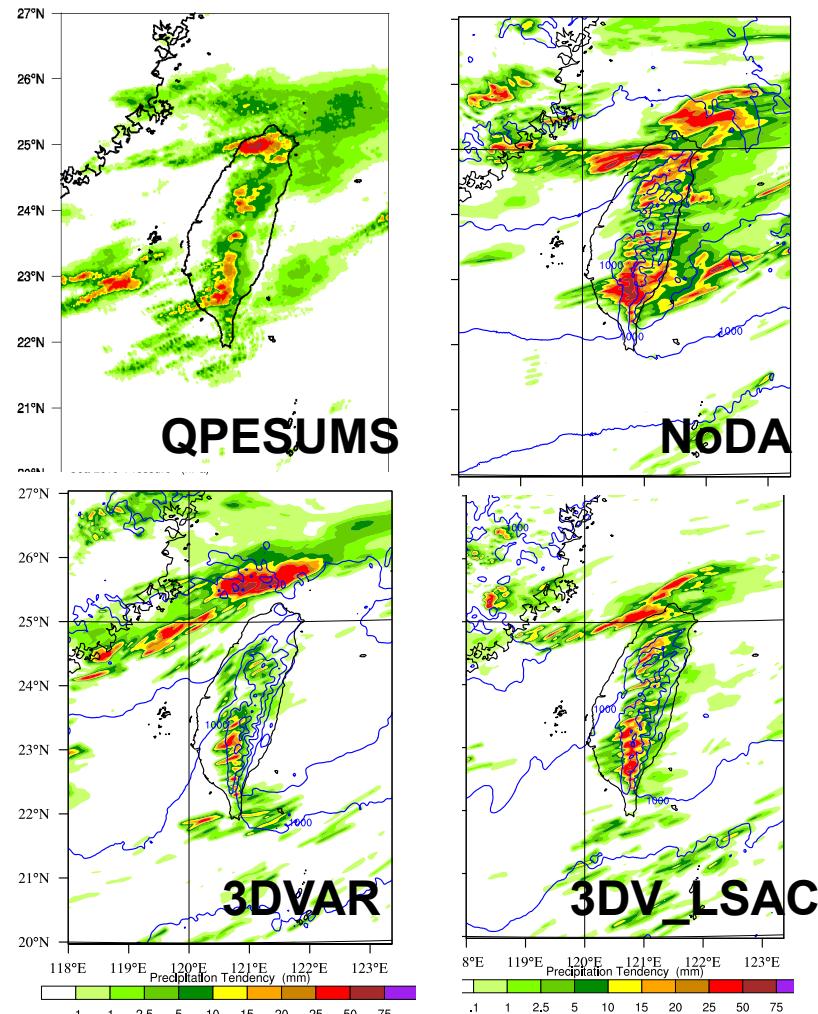
$$J = J_b + J_o + \frac{1}{2} (\mathbf{x}_0 - \mathbf{x}_0^{la}) \mathbf{A}^{-1} (\mathbf{x}_0 - \mathbf{x}_0^{la})$$

\mathbf{x}_0^{la} : large-scale analysis (GFS)

LSAC: Large Scale Analysis Constraint



6th hour rainfall forecasts



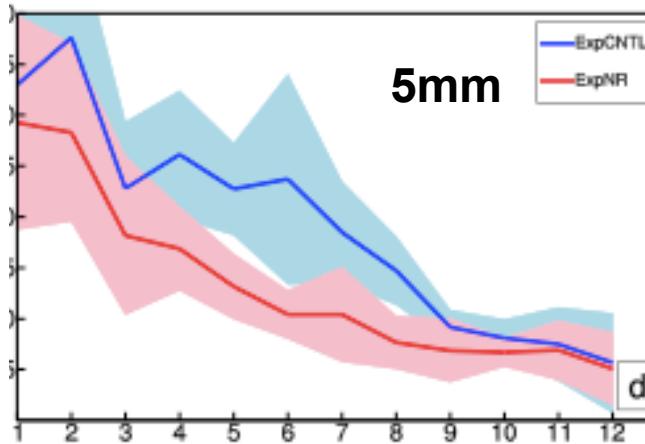
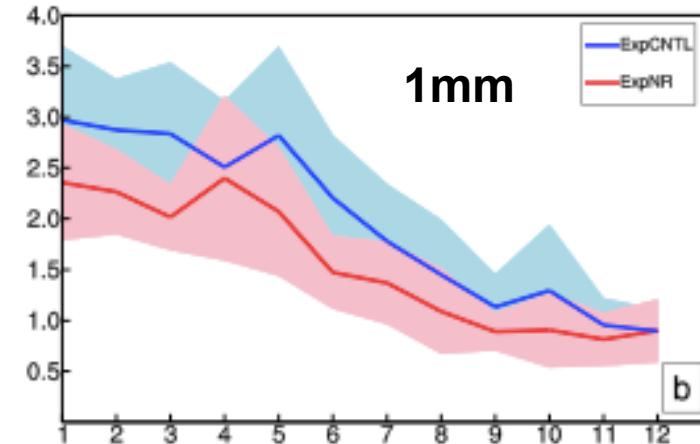
- 3DVAR w/o LSAC eliminates noise in NoDA, but also some signals
- 3DVAR_LSAC is able to keep the analysis close to high resolution observations while still maintaining large-scale balance, resulting in improved rainfall forecast



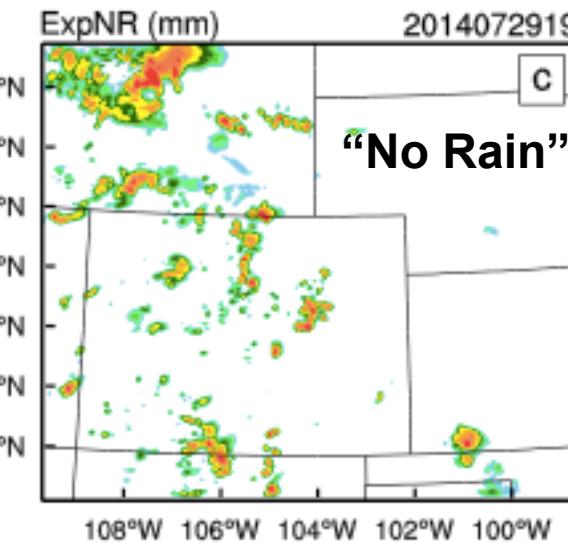
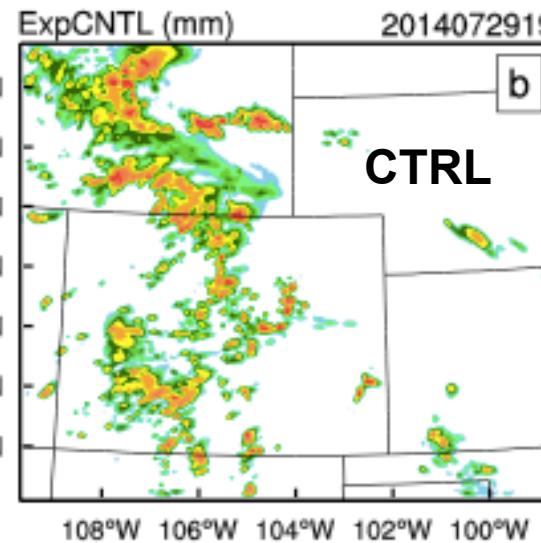
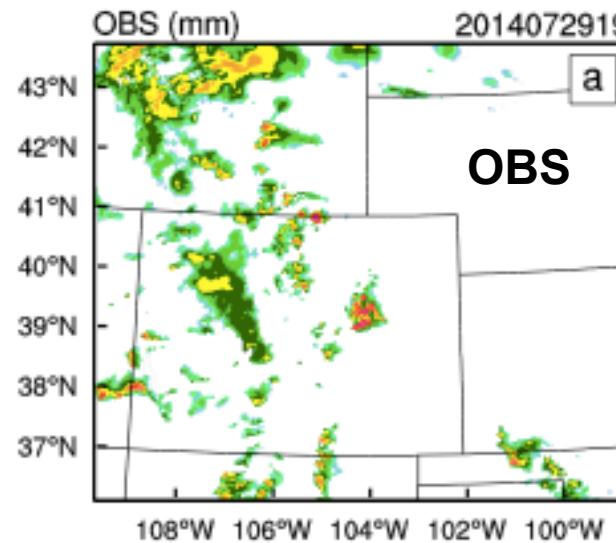
Reducing BIAS by assimilating “no rain” reflectivity data (future release)



BIAS July 1 – August 31 2016



Red: “no rain” DA
Blue: Control



Ongoing research

- How to configure 4DVar for radar data assimilation and short-term convective forecasting?
 - *physics options*
 - *cycling strategy*
 - *multi-incremental method*
- Improve flow-dependent BE (error of the day) using the ensemble method
 - *Application of WRFDA hybrid-3DVar to radar data assimilation*
 - *Benefit of using EnKF to update perturbation (En3DVar vs. 3DEnVar)*
- Combined assimilation of radar and rainfall
 - *How to define rainfall error*
 - *Assimilate radar QPE and surface rainfall*