

# WILLIAM HARRINGTON

245 SW Lincoln St, Apt. 108, Portland, OR 97201 • (727) 537-9224  
wrh2@pdx.edu • github.com/wrh2

## EDUCATION

---

<b>B.S., Computer Engineering, Minor, Mathematics</b> <i>Portland State University, Portland Oregon</i>	<b>GPA: 3.42/4.00</b> <i>2013-2016</i>
<b>A.A., General studies</b> <i>St. Petersburg College, St. Petersburg, Florida</i>	<b>GPA: 3.80/4.00</b> <i>2009-2012</i>

## TECHNICAL SKILLS

- 
- **Programming:** C/C++, Python, Verilog, Objective-C, MATLAB, Assembly (ARM, x86)
  - **Development tools:** Git, GNU tools (Emacs, gcc, gdb, etc.), Make, avrdude, OpenOCD
  - **IDEs:** Spyder, Xcode, Visual Studio, Arduino
  - **CAD:** EagleCAD
  - **Project management:** Scrum, Trello
  - **OS:** Linux, Mac OSX, Windows XP/7/8

## WORK \ VOLUNTEER EXPERIENCE

---

<b>Digital Signal Processing Intern</b> – APDM, Inc. – <i>Portland, Oregon</i>	<i>6/2015 - Present</i>
<ul style="list-style-type: none"><li>• Embedded system design and development<ul style="list-style-type: none"><li>– System level design</li><li>– Schematic capture and PCB layout using EagleCAD</li><li>– Firmware development in C/C++</li><li>– Assembly (soldering) and debug/testing</li><li>– Project documentation (project proposal, requirements, test plan, etc.)</li><li>– Manage projects using Scrum framework and Trello</li></ul></li><li>• Customer support<ul style="list-style-type: none"><li>– Managed RMA process</li><li>– Implemented out of warranty program to generate revenue from RMAs</li><li>– Developed software utilities for customers in python</li></ul></li><li>• Used git for version control on all software, CAD designs, and documentation</li></ul>	
<b>Embedded Systems Engineer</b> – Portland State Aerospace Society – <i>Portland, Oregon</i>	<i>7/2015 - Present</i>
<ul style="list-style-type: none"><li>• Designed and developed Command, Control, and Communication module for CubeSat<ul style="list-style-type: none"><li>– System level design</li><li>– Schematic capture and PCB layout using EagleCAD</li><li>– Firmware development in C</li><li>– Assembly, debug and testing</li><li>– Project documentation (project proposal, requirements, test plan, etc.)</li></ul></li></ul>	
<b>Engineering Intern I</b> – APDM, Inc. – <i>Portland, Oregon</i>	<i>6/2014 - 1/2015</i>
<ul style="list-style-type: none"><li>• Algorithm development<ul style="list-style-type: none"><li>– Implemented Unscented Kalman Filter in C++ for kinematic tracking</li><li>– Made heavy use of MATLAB and Python for verification and validation</li><li>– Used git for version control</li><li>– Participated in Scrum framework</li></ul></li><li>• Software development<ul style="list-style-type: none"><li>– Developed iOS app for motion tracking in Objective-C that utilizes OpenCV</li><li>– Used git for version control</li></ul></li></ul>	
<b>Control Systems Engineer</b> – Portland State Aerospace Society – <i>Portland, Oregon</i>	<i>6/2014 - 7/2015</i>
<ul style="list-style-type: none"><li>• Roll control for LV2.3 airframe<ul style="list-style-type: none"><li>– PID algorithm</li><li>– Simulation</li><li>– Code for flight computer</li><li>– Video of Launch-12</li><li>– Analysis pt 1, Analysis pt 2</li></ul></li></ul>	
<b>IEEE Computer Engineering Tutor</b> – Portland State University – <i>Portland, Oregon</i>	<i>9/2013 - 06/2015</i>
<ul style="list-style-type: none"><li>• Topics: Mathematics, programming, digital design, and circuit analysis.<ul style="list-style-type: none"><li>– Differential equations workshop (Workshop materials)</li><li>– Intro to Verilog (Part 1, Part 2)</li></ul></li></ul>	

## CONFERENCE PAPERS

- 
- **Alleviating Freezing of Gait using phase-dependent tactile biofeedback** - *IEEE-EMBC 2016*
  - **Development of a Low-Cost, Open Software/Hardware Command, Control and Communications Module for CubeSats** - *AIAA SPACE 2016*