# WILLIAM HARRINGTON

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## **EDUCATION**

### B.S., Computer Engineering, Minor, Mathematics GPA: 3.4/4.00 Portland State University, Portland Oregon 2013-2016 A.A., General studies GPA: 3.8/4.00 St. Petersburg College, St. Pete, FL 2009-2012 TECHNICAL SKILLS • Programming: C/C++, Verilog, Objective-C, Python, MATLAB, ARM assembly, x86 assembly • Dev tools: Git, GNU tools (Make, GCC, Emacs, gdb, gnroff, etc.), Spyder/Anaconda, Xcode, Visual Studio, Arduino, EagleCAD, OpenOCD • Project management: Scrum, Trello • OS: Linux, Mac OSX, Windows XP/7/8 WORK EXPERIENCE Digital Signal Processing Intern - APDM, Inc. - Portland, Oregon 6/2015 - Present • Embedded system design and development Schematic capture and PCB layout using EagleCAD Firmware development in C/C++ Assembly (soldering) and debug/testing Project documentation (project proposal, requirements, test plan, etc.) Manage projects using Scrum framework and Trello • Customer support - Managed RMA process - Implemented out of warranty program to generate revenue from RMAs - Developed software utilities for customers in python • Used git for version control on all software, CAD designs, and documentation Engineering Intern I – APDM, Inc. – Portland, Oregon 6/2014 - 1/2015 • Algorithm development Implemented kinematic tracker in C++ that utilizes Unscented Kalman Filter - Made heavy use of MATLAB and Python for verification and validation Used git for version control Participated in Scrum framework • Software development Developed ioS app for motion tracking in Objective-C that utilizes OpenCV - Used git for version control IEEE Computer Engineering Tutor - Portland State University - Portland, Oregon 9/2013 - 06/2015 • Topics: Mathematics, programming, digital design, and circuit analysis. - Differential equations workshop (Workshop materials) - Intro to Verilog (Part 1, Part 2) Extracurricular activies Embedded Systems Engineer - Portland State Aerospace Society - Portland, Oregon 7/2015 - Present • Designed and developed C3 avionics module for CubeSat Schematic capture and PCB layout using EagleCAD Firmware development, written in C Project documentation (project proposal, requirements, test plan, etc.) Control Systems Engineer - Portland State Aerospace Society - Portland, Oregon 6/2014 - 7/2015 Roll control for LV2.3 airframe PID algorithm (Python) - Python simulation Code for flight computer Video of Launch-12 - Analysis pt 1, Analysis pt 2

#### Honors

## ECE Faculty scholarship - Portland State University - 5/2014

• Awarded for academic excellence.

## Rohde and Schwarz Case Study Competition - USA Finalist - 4/2014

- First round USA winner with team Droning On
- Travelled to Munich, Germany and competed internationally

#### William Ketchum Mathematics Award – St. Petersburg College – 2012

Awarded for works in applied mathematics sponsored by the Mathematics department and the Honors college