

WILLIAM HARRINGTON

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EDUCATION

B.S., Computer Engineering, Minor, Mathematics

Portland State University, Portland Oregon

GPA: 3.42/4.00

2013-2016

A.A., General studies

St. Petersburg College, St. Petersburg, Florida

GPA: 3.80/4.00

2009-2012

TECHNICAL SKILLS

- **Programming:** C/C++, Python, Verilog, Objective-C, MATLAB, Assembly (ARM, x86)
- **Development tools:** Git, GNU tools (Emacs, gcc, gdb, etc.), Make, avrdude, OpenOCD
- **IDEs:** Spyder, Xcode, Visual Studio, Arduino
- **CAD:** EagleCAD
- **Project management:** Scrum, Trello
- **OS:** Linux, Mac OSX, Windows XP/7/8

WORK \ VOLUNTEER EXPERIENCE

Digital Signal Processing Intern – APDM, Inc. – *Portland, Oregon*

6/2015 - Present

- Embedded system design and development
 - System level design
 - Schematic capture and PCB layout using EagleCAD
 - Firmware development in C/C++
 - Assembly (soldering) and debug/testing
 - Project documentation (project proposal, requirements, test plan, etc.)
 - Manage projects using Scrum framework and Trello
- Customer support
 - Managed RMA process
 - Implemented out of warranty program to generate revenue from RMAs
 - Developed software utilities for customers in python
- Used git for version control on all software, CAD designs, and documentation

Embedded Systems Engineer – **Portland State Aerospace Society** – *Portland, Oregon*

7/2015 - Present

- Designed and developed Command, Control, and Communication module for CubeSat
 - System level design
 - Schematic capture and PCB layout using EagleCAD
 - Firmware development in C
 - Assembly, debug and testing
 - Project documentation (project proposal, requirements, test plan, etc.)

Engineering Intern I – APDM, Inc. – *Portland, Oregon*

6/2014 - 1/2015

- Algorithm development
 - Implemented Unscented Kalman Filter in C++ for kinematic tracking
 - Made heavy use of MATLAB and Python for verification and validation
 - Used git for version control
 - Participated in Scrum framework
- Software development
 - Developed iOS app for motion tracking in Objective-C that utilizes OpenCV
 - Used git for version control

Control Systems Engineer – **Portland State Aerospace Society** – *Portland, Oregon*

6/2014 - 7/2015

- Roll control for LV2.3 airframe
 - PID algorithm
 - Simulation
 - Code for flight computer
 - Video of Launch-12
 - Analysis pt 1, Analysis pt 2

IEEE Computer Engineering Tutor – **Portland State University** – *Portland, Oregon*

9/2013 - 06/2015

- Topics: Mathematics, programming, digital design, and circuit analysis.
 - Differential equations workshop (*Workshop materials*)
 - Intro to Verilog (*Part 1, Part 2*)

CONFERENCE PAPERS

- **Alleviating Freezing of Gait using phase-dependent tactile biofeedback** - *IEEE-EMBC 2016*
- **Development of a Low-Cost, Open Software/Hardware Command, Control and Communications Module for CubeSats** - *AIAA SPACE 2016*