WrightSim

Kyle Sunden

Goal

Theor

NISI

Algorithmic Improvement

Parallel Implementations

Limitations

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Features

Algorithmic Improvemen

Conclusion

Acknowledgements

References



# WrightSim

Kyle Sunden

University of Wisconsin-Madison

January 3, 2018

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Algorithmic Improvemen

Parallel Implementations Scaling Analysis Limitations

Features Usability

Algorithmic Improveme

Peferences



- ► Reproduce experimental spectra *in silico*.
- Designed with experimentalists in mind.
- Uses numerical integration for flexibility, accuracy and interpretability.
- ► Focus on Frequency-domain spectroscopy, but techniques in principle extend to time-domain.
- ▶ Output retains frequency and phase information, can be combined with other simulations and measured similar to a monochromator.
- ► Selectivity in what portions of the overall signal are simulated, providing deeper understanding.

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Goals

Theory

NISI

Algorithmic Improvements

Parallel Implementations

Limitations

Future Wo

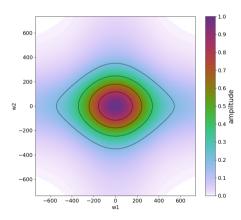
Features

Algorithmic Improveme

#### onclusion

Acknowledgement





Algorithmic Improvemen

Parallel
Implementation
Scaling Analysis

Limitations

Features
Usability
Algorithmic Improvement

Acknowledgement

Reference



Presented here is a description of *what* is done to perform these simulations, to understand *why* it works, please refer to Kohler, Thompson, and Wright[1]. The simulation uses a set number of electric fields (3, in the case of the simulation presented here).

These electric fields interact in combinatorially large different fashions. Interactions create superposition coherences and/or populations in material systems.

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Algorithmic

Parallel Implementations Scaling Analysis

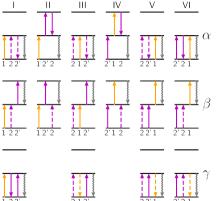
Future Wo

Features Usability

Conclusions

References





There are six time orderings for interactions to occur (I-VI).

There are 16 independent pathways possible for two positive (solid up/dashed down) and one negative (dashed up/solid down) interactions.

Originally from [1].

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Goal

Theory

Algorithmic Improvemen

Parallel Implementation: Scaling Analysis

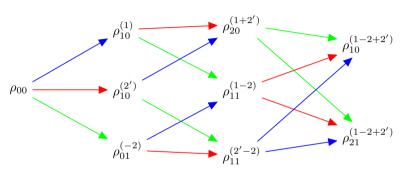
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Features
Usability
Algorithmic Improvemen

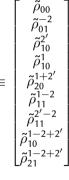
Conclusion Acknowledgemen

Reference





Density elements, encoded with quantum state (subscript) and the electric fields which have interacted (superscript). Colored arrows represent the different electric fields. All possible states which have the desired conditions for the process simulated are included. These form the state vector (right).[1]



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Goal

Theory

NIS

Algorithmic Improvemen

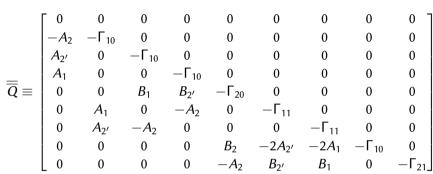
Parallel Implementation Scaling Analysis Limitations

Future Work
Features
Usability

Conclusion

Reference





Defines the transition between states, dependant on the electric field.  $\Gamma$  represents the dephasing/population decay. A and B variables incorporate the dipole moment and electric field terms.[1]

The dot product of this matrix and the density vector,  $\overline{\rho}$ , gives the change in in the density vector. This is repeated over many small time periods to achieve the recorded results.

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NISE

Improvemen

Implementation
Scaling Analysis

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Usability Algorithmic Improvements

Conclusions

Acknowledgements

Reference



NISE (Numerical Integration of the Schrödinger Equation) is an existing open-source implementation of the simulation for these kinds of spectra.[2] It was written by Kohler and Thompson while preparing their manuscript.[1] NISE uses a slight variation on the algorithm presented, which allows for a 7-element state vector, but requires two simulations. The end result is the same.

NISE is included as a reference for prior implementations.

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NISE

Algorithmic Improvements

Parallel Implementations Scaling Analysis Limitations

Future Work

Usability
Algorithmic Improvement

Conclusions

Acknowledgement

References



- ▶ Use single 9 x 9 matrix rather than two 7 x 7 matrices.
- ▶ 99.5% of time is spent in highly parallelizable loop.
- ▶ 1/3 of time is spent in a single function, ix\_.
  - Removed entirely, in favor of a simpler communication of what to record.
- ▶ Significant time in rotor function which computes  $cos(\theta) + i * sin(\theta)$ .
  - ▶ Replaced with  $exp(i * \theta)$ , equivalent, more efficient, removed function call.
- Use variables to store and reuse redundant computations.

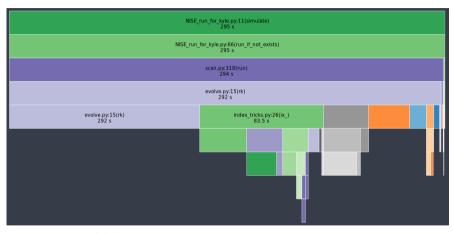
Resulted in almost an order of magnitude speed-up from algorithmic improvements alone. Remained highly parallelizable.

# Profile trace of NISE

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# Algorithmic Improvements





Python cProfile trace, Single Core implementation, visualized with SnakeViz.[3]

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# Profile trace of WrightSim

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# Algorithmic Improvements

Parallel Implementation

Limitations

## Future Wo

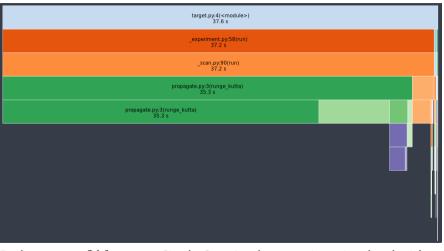
Features
Usability
Algorithmic Improvement

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Python cProfile trace, Single Core implementation, visualized with SnakeViz.[3]

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# Parallel Implementations

Limitations

Future Wo

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Usability Algorithmic Improvemen

Conclusion

Acknowledgemen



- ▶ NISE already had CPU multiprocessed parallelism, using Python standard library interfaces.
  - ► WrightSim inherited this CPU parallel implementation
  - Results in a 4x speed-up on a 4-core machine, almost no reduction due to Amdahl's law.
- ▶ A new Nvidia CUDA [4] implementation.
  - Uses PyCUDA to call the kernel from within Python.
  - ▶ Just-in-time compiled (using nvcc) from C source code stored in Python strings.
  - ▶ Implementation differs slightly from pure Python implementation.
    - Only actively used Hamiltonians are held in memory, Python implementation computes all time steps ahead of time.
    - Similarly, only the actively used electric fields are held in memory.
    - Hand written dot product and vector addition, rather than the numpy implementations.

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Algorithmic Improvements

Parallel Implementation

Scaling Analysis

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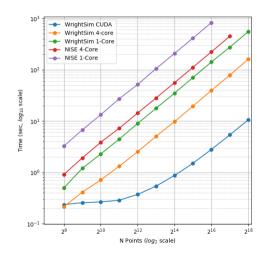
Features

Algorithmic Improvemen

onclusions

Acknowledgement





Theory

Algorithmic Improvemen

Parallel Implementations Scaling Analysis

Limitations

Features

Usability Algorithmic Improvements

Conclusions
Acknowledgement



- ▶ For low number of points, the CUDA implementation is of limited use.
  - ► Around 200 ms required for compilation.
  - ▶ 4-Core multiprocessed becomes faster below approximately 256 points.
  - CUDA implementation currently uses a hard coded block size of 256.
  - ▶ Only multiples of 256 may be used at present to avoid illegal memory access.
- Independent CUDA simulations are memory limited.
  - only a certain amount of memory can be allocated for a single CUDA process.
  - ► Each point in the simulation requires 500 complex numbers (represented as doubles) to be allocated
  - ▶ Additional data is needed, but dominated by this array.
  - ► This array must be transferred back to the host.
  - ► The limit is between 2<sup>18</sup> and 2<sup>19</sup> points

Theory

Algorithmic Improvemen

Parallel Implementation

Limitations

Future Wo

Features
Usability
Algorithmic Improvem

Conclusions

Acknowledgement



- Nonidealities like chirped pulses.
- Inhomogeneous samples
  - Results in broader peaks.
  - Can be modelled by translating a single computed response and adding.
- Measuring signal using Fourier transforms similar to how a monochromator selects a signal.
- Saving intermediate response values (Using HDF5 based file format)
- ▶ Saving compiled CUDA binary for more than one run at a time

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Parallel Implementation

Scaling Analysis

Future Wo

Features Usability

Conclusions
Acknowledgement

References



Metaprogramming techniques are those which modify the code that is run as the program executes.

Just-in-time compilation enables many opportunities for metaprogramming.

- Using same-named functions to change the exact algorithms, while other calling functions do not need to be edited.
- ▶ Resolving shortcuts taken for statically allocated arrays.
- ▶ Potentially, entire C functions could be dynamically generated by inspecting the Python code, resulting in new Hamiltonians only being required to be implemented once, in Python.

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Algorithmic Improvement

Parallel Implementation

Scaling Analysis Limitations

Future Wo

Features Usability

Conclusions

Acknowledgement

References



One important thing to do is to take a step back and think about how users interact with the program.

- ► Ensure the API is sensible, easy to follow, and well documented.
- ▶ Provide ways of configuring via configuration files instead of code.
- ▶ Think about implementing a GUI interface, targeted to experimentalists.
- ► Implement new Hamiltonians.
- ► Ensure code is robust, with proper values being transferred to and from the CUDA Device with different Hamiltonian instances.
- Resolve hard-coded initial values.

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Parallel Implementation

Limitations

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Features

Usability

Algorithmic Improvements

Conclusion

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Theory

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Algorithmic Improvement

Parallel Implementations

Limitations

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Usability

Algorithmic Improvement

# Conclusions

Acknowledgements

References



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Parallel Implementation: Scaling Analysis Limitations

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Features
Usability
Algorithmic Improve

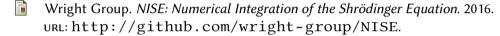
Conclusions

Acknowledgement

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