# Adaptive Pareto Smoothed Importance Sampling

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#### Introduction

- Importance sampling
- Measuring performance
- Improving performance
  - Modifications
  - Optimization

## Importance Sampling

- Need to compute an expected value
  - $\mathbb{E}_F \varphi(X)$
- Can't do the sum/integral
- Monte Carlo approximation
  - Simulating from F might be hard

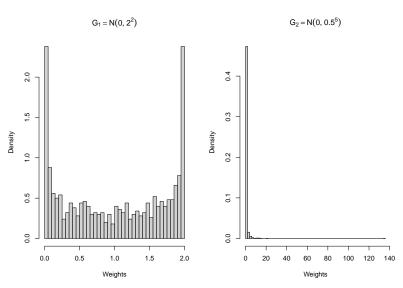
### Importance Sampling

• Introduce "proposal distribution", G:

$$\mathbb{E}_{F}\varphi(X) = \mathbb{E}_{G}\left[\varphi(X)\cdot\frac{f(X)}{g(X)}
ight] = \mathbb{E}_{G}\left[\varphi(X)\cdot w(X)
ight]$$

- G can be nearly anything\*
  - \*Some choices will be better than others

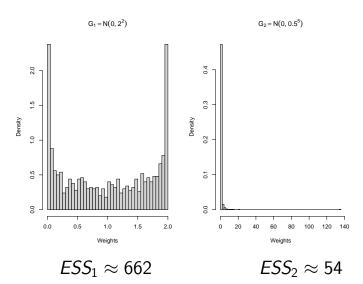
- f unknown, but can be evaluated
- $\varphi(X) = X^2$
- Try some proposals:
  - $G_1 \sim N(0, 2^2)$
  - $G_2 \sim N(0, 0.6^2)$
- Use M = 1000 samples from proposal
  - $\hat{\mathbb{E}}_1 = 0.99$ ,  $\hat{SD} = 1.97$
  - $\hat{\mathbb{E}}_2 = 1.10$ ,  $\hat{SD} = 2.32$



### Importance Sampling

- *G*<sub>1</sub> weights look fine
- G<sub>2</sub> weights dominated by one large value
- We can make this difference precise
- "Effective Sample Size":

$$ESS = \frac{\left[\sum_{i} w(X_{i})\right]^{2}}{\sum_{i} w(X_{i})^{2}}$$



## Importance Sampling

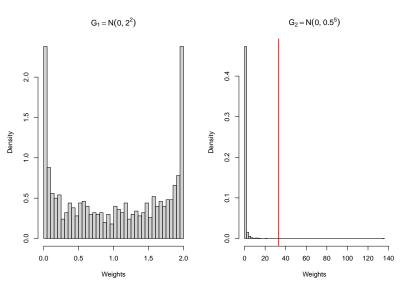
- ullet Problem: Low ESS o hard to estimate means
- But ESS is based on means
  - (Chatterjee and Diaconis, 2018)

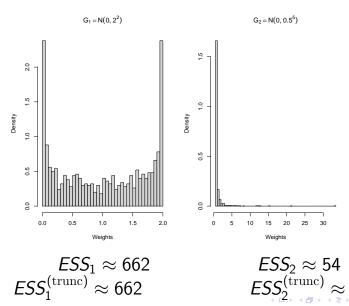
### Improving IS

- Choose a good proposal
- Modify large weights
  - Truncated IS
  - Pareto Smoothed IS

## Improving IS

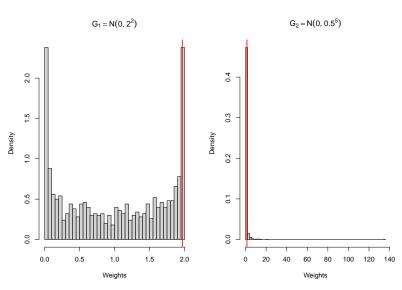
- Truncated Importance Sampling:
  - (lonides, 2008)
- 1. Choose a threshold
- 2. Apply hard thresholding to any large weights
  - Still consistent for the target

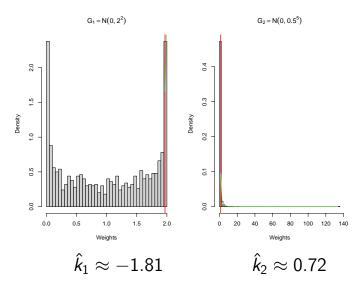




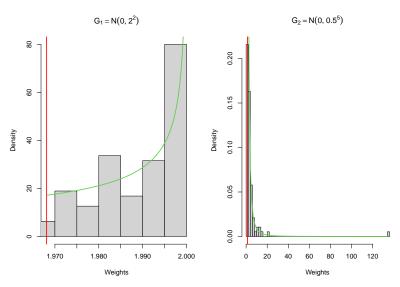
### Improving IS

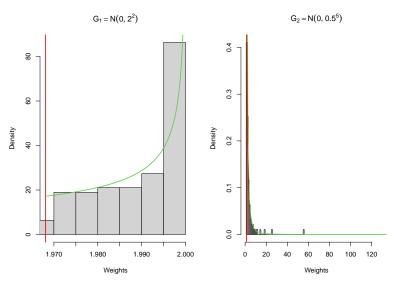
- Pareto Smoothed Importance Sampling:
  - (Vehtari et al., 2024)
- 1. Choose a threshold
  - Weights above threshold represent tail of their dist.
- 2. Approximate tail with Generalized Pareto Dist.
  - Fit GPD to weights above threshold
  - (Zhang and Stephens, 2009)
- 3. Replace large weights with quantiles of fitted GPD

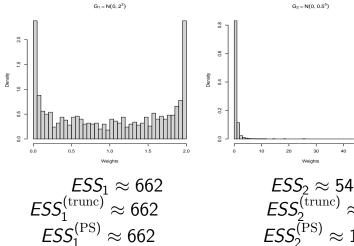




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#### Adaptive IS

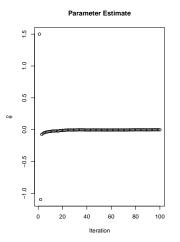
- Alternative approach: directly optimize ESS
- Adaptive Importance Sampling:
  - (Akyildiz and Míguez, 2021)
- 1. Choose a (parametric) family of proposals
- 2. Iteratively update the proposal to maximize ESS

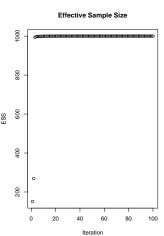
#### Stochastic Approximation

- Actually, we want to maximize a population-level analog: ESS\*
- If we had ESS\*, we would do gradient ascent
  - $\theta_{k+1} = \theta_k + \alpha \nabla ESS^*(\theta_k)$
- Instead, do gradient ascent on ESS
  - $\hat{\theta}_{k+1} = \hat{\theta}_k + \alpha_k \nabla ESS(\hat{\theta}_k)$

#### Stochastic Approximation

- Originally developed for root finding with noise
  - (Robbins and Monro, 1951)
- Quickly adapted for optimization
  - Use noisy evaluations for finite difference
  - (Kiefer and Wolfowitz, 1952)
- Very well developed theory
- Stochastic gradient descent





$$\hat{\theta}_{\rm end}^{(ESS)} \approx -8 \times 10^{-4}$$

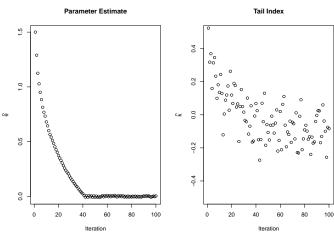
$$\textit{ESS}_{\mathrm{end}} pprox 1000 - (7 imes 10^{-4})$$

#### Our Method

- Recall: Be careful using IS means to diagnose IS
- Vehtari et al. give an alternative
  - Shape parameter of fitted tail distribution,  $\hat{k}$

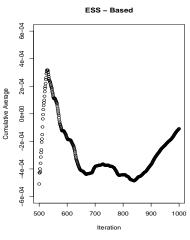
#### Our Method

- Use diagnostic as objective function
- Apply stochastic approximation to minimize  $\hat{k}$ 
  - More precisely,  $k(\theta)$

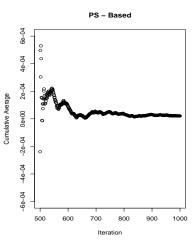


$$\hat{ heta}_{\mathrm{end}}^{(PS)} pprox 4 imes 10^{-3}$$

- Performance tends to be better if we average all the estimates
- ullet Call this  $ar{ heta}$



$$\bar{\theta}_{\rm end}^{(ESS)} \approx -1 \times 10^{-4}$$



$$ar{ heta}_{
m end}^{(PS)}pprox 2 imes 10^{-5}$$

### Another Example

#### Recap

- Importance sampling and extensions
  - Truncation
  - Pareto Smoothing
- Diagnostics for importance sampling
  - Effective sample size
  - Pareto tail index
- Adaptive importance sampling
  - Stochastic approximation



## Thank You

#### Some References

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