Today, we are talking about statistical inference. Specifically, confidence intervals and hypothesis tests. The ideas in these sections may be a bit different from how you're wed to thinking about CIs and tests. The main difference is that we will now be thinking that about these tools as statisticians (i.e. from the perspective of how they were developed), rather than as every of statistics (i.e. only morrying about how to use them). This is a jump in cstatistical maturity that will help you understand the inner workings of much of statistical inference.

even many

I'm going to follow the book more closely than usual for this tutorial, because many examples that start simple end up being either very that long or outright impossible.

Confidence Intervals

Before we move on, thereon let's go over the standard disclaiment for CIs. Once we have calculated an interval, the probability that it contains O is either O or I. Our probability statement is about all the intervals we could have calculated, since frequentist probabilities are always statements about the infance infinite hypothetical resampling of data.

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There are a few standard mays to construct CIs. The One of the more natural methods is called the likelihood approach. The idea here is that larger values of the likelihood f'a correspond to parameter values that are better supported by our data. This suggests that he should choose all 0 with likelihood values above some thresholds. The details of the likelihood method then revolve around how we should choose this threshold. It's best to see this with an example.

e.g.I: Let χι,..., χη^{id} N(μ,\$σ²), with σ² known. Find an expression for the likelihood method (I for μ. First, we need the likelihood. An equivalent expression for the likelihood is

$$\mathcal{L}^{*}(\mu;\underline{X}) = \exp\left[\frac{-n}{2\sigma^{2}}(\bar{X}-\mu)^{2}\right]$$

(equivalent in the sense that we have only dropped multiplicative factors that do not depend on M). We want to find got which M make It larger than some threshold, k.

$$L^{*}(\mu;\underline{K}) \geq k$$

$$\exp\left[\frac{1}{2\sigma^{2}}(\overline{X},\mu)^{2}\right] \geq k$$

$$\frac{1}{2\sigma^{2}}(\overline{X},\mu)^{2} \geq \log(k)$$

$$(\overline{X},\mu)^{2} \leq 2\sigma^{2}\log(k)$$

$$-\overline{x} - \underline{\sigma}k_{i} \leq -\mu \leq -\overline{x} + k_{i} \underline{\sigma}$$
 where $k_{i} = \sqrt{\frac{1}{2}} \sqrt{\frac{$

X+kozMZX-kp

Therefore to get $L^*(\mu;X) \ge k$, we should choose μ between $L(X) := x - k \mu$ and $u(X) := x + k \mu$. This gives us the form of our interval, but we still need to choose k_1 . For this, we will use the significance level. Specifically, we want a not improve interval are better, so we will choose the equivalent value for k_1 that gives us the required significance level, V. It's not immediately obvious how to do this, but in one fortunately, in our model we know the distribution of a quantity that uses all the terms in our interval.

$$= p\left(-k_{1} \leq M - \overline{\lambda} \leq k_{1} \leq M\right)$$

$$= p\left(-k_1 \leq \frac{M-\bar{X}}{M-\bar{X}} \leq k_1\right) = p\left(k_1 \geq \frac{\bar{X}-M}{M-\bar{X}} \geq -k_1\right)$$

where $Z \sim N(0,1)$. The smallest value of k, that makes this prob. at least δ is $d \in \mathbb{Z} = \mathbb{$

Therefore, our likelihood based CI for M is $e(x) = (x - \overline{x} - (\xi)) = (x + \overline{x}) = (\xi)$.

Hypothesis Tests

- called a p-value

The core idea tehted behind testing a hypothesis, the based on a sample of data, &, is to assume that the probability of getting a sample similar to X, If this probe is small, we reject the If this probe is large, we do not reject the.

Here is the standard disclaimer for hypothesis tests: not rejecting to is different from accepting the we cannot accept the based on hypothesis testing. For example, consider the normal accepting the we cannot accept the based on hypothesis testing. For example, consider the normal accepting the weak to be and the property of the can't large p-value assuming the way we can't large p-value assuming the consideration we can't both be true. However, it does make sense to "not reject" accept both hypotheses because they can't both be true. However, it does make sense to "not reject" both hypotheses.

Now for some defails. Let $\alpha \in (0,1)$ be a significance level. Let $H_0: \theta \in \Theta_0$, $H_A: \theta \in \Theta \setminus \Theta_0$. The p-value based on a sample, X, is defined in two steps. First, we find for some $\theta \in \Theta_0$, we find the calculated

You can check by plugging in numbers that this prob. gets larger as μ gets larger, so our p-value is $e^{-1} = \pm \left(\frac{w-3}{\sigma/v^{-1}}\right)$, since 3 is the largest μ under the We then check if $e^{-1} = 0.02$ to decide if we should reject the or not.

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So for, everything has morked out for us because the normal distribution is well-suited for doing inference. What if things aren't as nice?

e.g. 2: Let $X_1, \dots, X_n \sim Exp(\lambda)$. Let's see what happens when ne try to construct a likelihood bused CI for λ . The likelihood f'n is

$$\mathcal{L}(\lambda;\underline{x})=\lambda^{n}\exp\left(-\frac{1}{\lambda}\xi_{i},\chi_{i}\right)$$
 where $S_{n}=\xi_{i},\chi_{i}$

Our interval should contain all A values with likelihood values above some threshold, #k.

$$\mathcal{L}(\lambda;X)>k$$

$$\lambda^n \exp\left(-\frac{1}{\lambda} \int_{x} \right) > k$$

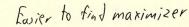
This inequality cannot be additionally for A. Even if we do get the intervals numerically, it's not clear how we would calculate the probability athat one will cover Al. Mespecially since the distribution of Sn depends on X we need a way to get CII (and tests) for X that doesn't involve solving for our intervals numerically. This is where asymptotic theory comes into very useful.

Asymptotic Inference

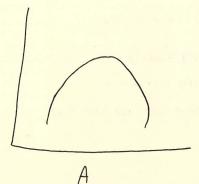
The idea behind asymptotic theory is that as $n \to \infty$, distributions tend to get simpler. We already know as some asymptotic theorems, e.g. the CLT. This thin says that, regardless of how complicated the distribution of X_i is, $X_i \to X_i$ Dy N(0,1). Another very useful asymptotic theorem

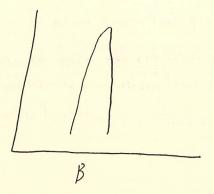
(which is actually based on the CLT), is that MLEs also restrict that converge to normals. Specifically, if ô is an MLE, then ô- was D, N(0,1). If ne can get Ecotomat V(ô) then ne can start

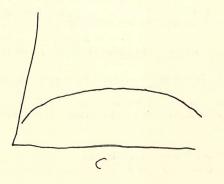
to do inference. Fortunately, there is already general theory for the calculating V(0). The extreme that Before getting into any formular, let's think about V(0). We calculate 0 by maximizing the likelihood f'n, but some likelihoods are easier to maximize than others.



Horder to find maximizer







The difference between these & three likelihoods is their per second derivative euroit
second derivative (i.e. curviture) at the maximizer. Specifically, the negative second derivative
derivative is much larger in B than in C. This makes ô easier to estimate in B than in
C and thus, $V(\hat{\theta})$ should be smaller in B than in C. The important quantity here,
of the log-likelihood observed
the negative second derivative at ô, is called the Fisher Information. The population
the negative second derivative at ô, is called the Fisher Information. The population
Fisher Information is just the expected value of this quantity evaluated at the true ô.

The information is just the expected value of this quantity evaluated at the true ô.

Fisher Information at different o, so
ne treat it as a fa of o.

Fisher Information: $\overline{E(0;X)} := E_0 \left[-\frac{\partial^2 l(0;X)}{\partial \theta^2} \right]$

Note: Pon? t forget the minus sign! where O_0 is the true O_0 It turns out that $V(\hat{O}) \rightarrow \frac{1}{\sqrt{I(O_0)} \times I}$ as $n \rightarrow \infty$. This makes sense, since larger Fisher Information

gives smaller we asymptotic variance. In practice, ne don't know Oo, but we still must to know the limit for $V(\vec{\theta})$, so we need to estimate I(O;X). One may to do this is with the observed Fisher Information, $\widehat{I}(X)$. Another option is to calculate the true Fisher Information at our enMLF, $I(\vec{O};X)$. This is called the plug-in estimator because we take the thing ne must to know, I(O;X), and plug-in our estimate for the thing we don't know, \widehat{O} for Oo.

It turns out that asymptotic normality still holds for \widehat{O} if ne replace the true Fisher Information

It turns out that asymptotic normality still holds for \$\tilde{O}\$ if ne replace the true Fisher Information with its plug-in estimator. I-e. \$\tilde{O} - 0 \\ \tilde{VI(\tilde{O};\X)} \\ \tilde{X}\).

One more observation about Fisher Information, then ne'll do an example so for, we have only discussed the F.I. based on a sample .It turns out that, for a sample of size n, $I(0;X) = nI(0;X_i)$. This is nice, because $I(0;X_i)$ only requires finding the second derivative of the log-density, which is often easier to work with. This simplification is so common that people often just write $I(0) := I(0;X_i)$ for the F.I. based on a single observation. Putting this all together, we get that

Now let's return to our exponential CI example.

e-9.2 cont.: We saw previously that a likelihood based CI in this model seems hopeless. We know from previous nork that the MLE of λ is $\hat{X}=V\bar{X}$. Next, we need the F.I.Let's find $I(\theta)$ (i.e. bused on a single obs.)

A Cops! Let O=1 A

$$\begin{array}{l}
 \{(0; x) \in \{0\} \\
 \{(0; x) \in \{0\} \\
 \{(0; x) \in \{0\} \\
 = \{0\} \\
 \{(0; x) \in$$

The derivative of this mare

$$\frac{\partial \mathcal{L}(0;\pi)}{\partial \theta} = \frac{1}{\theta} - \pi \qquad \frac{\partial^2 \mathcal{L}(0;\pi)}{\partial \theta^2} = \frac{1}{\theta^2}$$

Therefore, the F.I. is

$$E(G) = E\left[-\left(-\frac{1}{\theta^2}\right)\right] = \frac{1}{\theta^2} = \frac{1}{\lambda^2}$$

The plug-in estimate of the F.I. is

$$I(\widehat{\lambda}) = \frac{1}{\widehat{\lambda}^2} = \Re \widehat{\lambda}^2$$

The plug-in estimate of the F.I. based on a sample of size n is $nI(\widehat{A}) = n\widehat{X}^2$.

Therefore, the asymptotic variance of (X) is $\frac{1}{nI(X)} = \frac{1}{nX^2}$. We can construct an asymptotic (I) for X by just treating (X) as morn(X). In e.g. 1, we can what how to get a (I) based on a normally distributed statistic: (X) (X

Note: If the observed F.I., Extremier
$$\widehat{f}(X)$$
, is easier to mark with, you can instead do everything we just forever, replacing $\widehat{\Phi}$ $nI(\widehat{\delta}) = \widehat{I}(\widehat{O};X)$ with $\widehat{f}(X)$ (this is true in general, not just for our example).