

# SPECIFICATION

Product Name: Laser Particle Sensor Module

Item No.: PM2016

Version: V0.2

Date: June 25, 2021

# Revision

| No. | Version | Content                           | Date       |
|-----|---------|-----------------------------------|------------|
| 1   | V0.1    | The first version                 | 2019.03.01 |
| 2   | V0.2    | Update specification and protocol | 2021.06.25 |
|     |         |                                   |            |
|     |         |                                   |            |
|     |         |                                   |            |

# Laser Particle Sensor Module

PM2016



## Applications

- Air purifier
- Air quality monitor
- Air conditioner
- Ventilation system
- Consumer electronic products

## Description

PM2016 is a laser particle sensor module which uses light scattering principle. It measures and calculates the suspending particle number which is within unit volume on the air exactly and output particle mass concentration  $\mu\text{g}/\text{m}^3$  directly via mathematical algorithm and scientific calibration.

## Features

- The smallest size of available measurement:  $0.3\mu\text{m}$
- Real-time output particle mass concentration in  $\mu\text{g}/\text{m}^3$  is available
- VOC, temperature and humidity measuring function is reserved
- High accuracy, high sensitive and quick response ( $\leq 8\text{s}$ )
- Small size, compact structure, easy to install

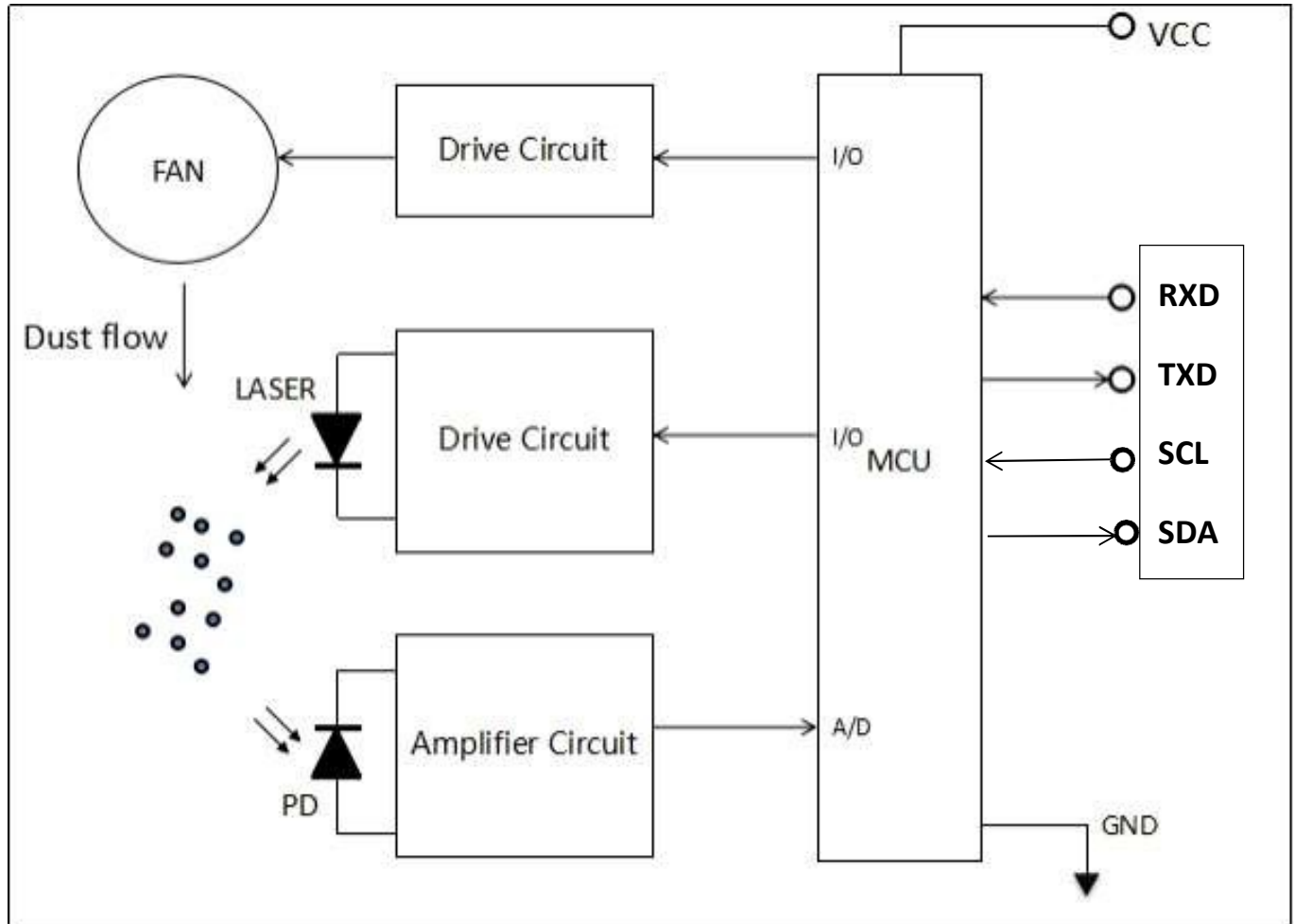
## Working Principle

Sampling by the internal pressure which occurs by fan, when sampling particles pass through light beam (laser), there will be light scattering phenomenon. Scattered light will be converted into electrical signal (pulse) via photoelectric transformer. The bigger particles will obtain stronger pulse signal (peak value). Through peak value and pulse value quantity concentration of particles in each size can be calculate. Thus, real-time measured data is obtained through measuring quantity and strength of scattered light.

## PM2016 Specifications

| Laser Particle Sensor Specification |  |
|-------------------------------------|--|
| Operating principle                 | Laser scattering   |
| Measured particle range             | 0.3 $\mu$ m~10 $\mu$ m   |
| Measurement range                   | 0~5,000 $\mu$ g/m <sup>3</sup>   |
| Resolution                          | 1 $\mu$ g/m <sup>3</sup>   |
| Working condition                   | -10°C ~ 60°C, 0-95%RH (non-condensing)   |
| Storage condition                   | -40°C ~ 70°C, 0-95%RH (non-condensing)   |
| Measurement accuracy <sup>1</sup>   | Mass concentration<br>PM1.0/PM2.5: 0~100 $\mu$ g/m <sup>3</sup> , $\pm$ 10 $\mu$ g/m <sup>3</sup><br>101~500 $\mu$ g/m <sup>3</sup> , $\pm$ 10% reading<br>PM10: 0~100 $\mu$ g/m <sup>3</sup> , $\pm$ 25 $\mu$ g/m <sup>3</sup><br>101~500 $\mu$ g/m <sup>3</sup> , $\pm$ 25% reading (GRIMM 11-A, 25 $\pm$ 2°C, 50 $\pm$ 10%RH) |
| Response time                       | 1second  |
| Time to first reliable reading      | $\leq$ 8 seconds   |
| Power supply                        | DC 5V $\pm$ 0.1V, ripple wave $<$ 100mV  |
| Working current                     | $\leq$ 80mA  |
| Dimensions                          | W40.7*H40.7*D12.2 mm   |
| Weight                              | 26.5g  |
| Digital output                      | UART/IIC: 3.3V   |
| MTTF                                | 128,000 hrs (continuous turn on)   |

## Internal Architecture Description

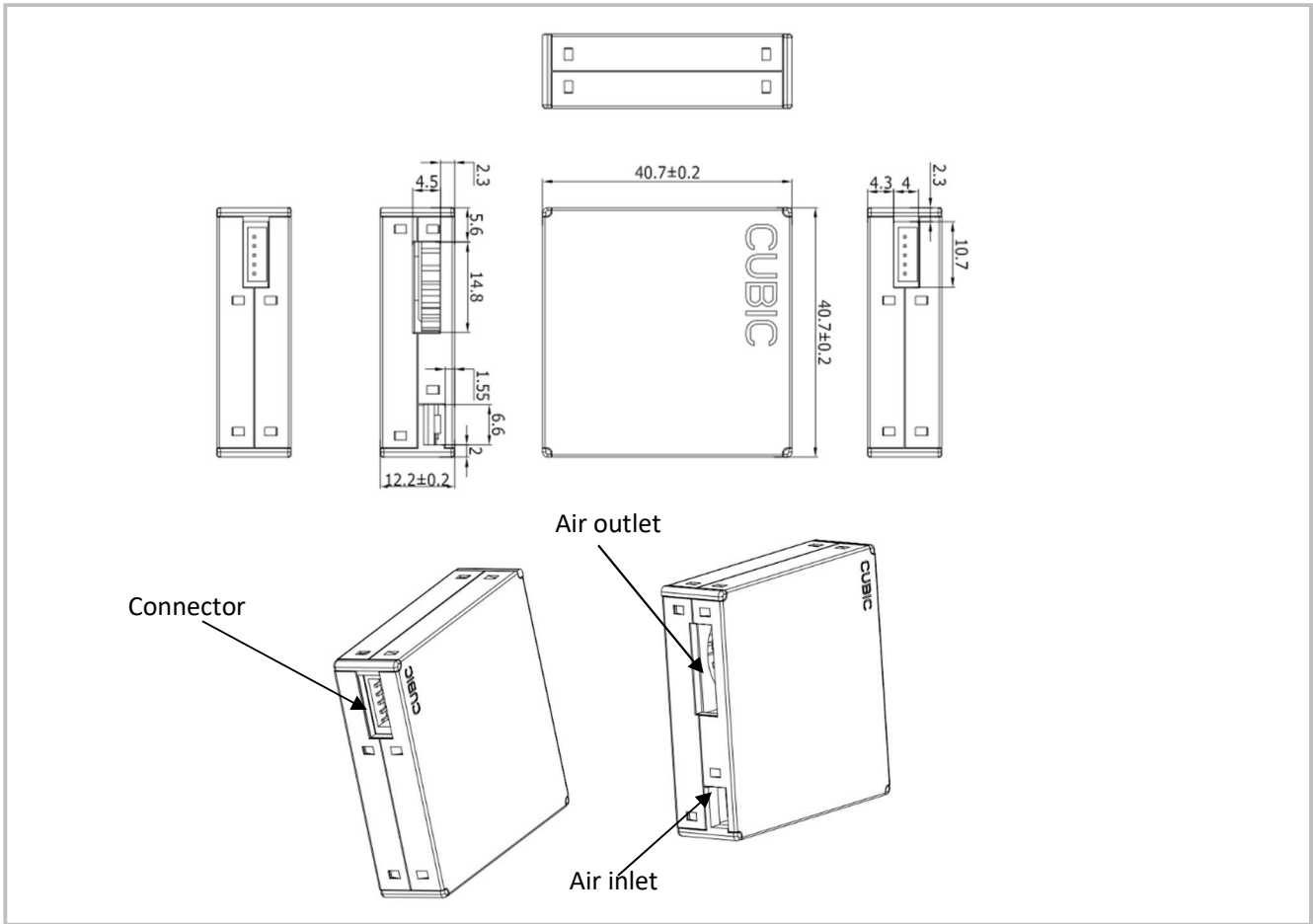


According to the above figure, the light source part of PM2016 is composed of a laser tube and a driving circuit. The detection part of the sensor is composed of light sensitive part which receives reflected light and amplifying circuit. Data processing and communication output are completed by microprocessor.

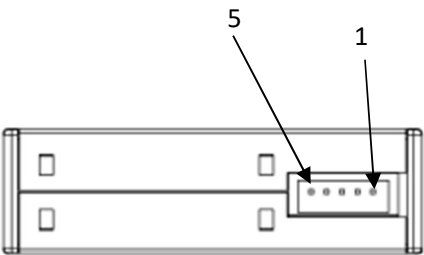
The gas flows into the module through the fan, when sampling particles pass through light beam (laser), there will be light scattering phenomenon, and scattered light will be converted into electrical signal (pulse) via light sensitive part. Electrical signal will be transformed into digital signals after amplifying circuit, smoothing and MCU processed.

## Dimensions and Connector

### 1. Dimensions (Unit mm, tolerance $\pm 0.2$ mm)



### 2. I/O Connector Pin out

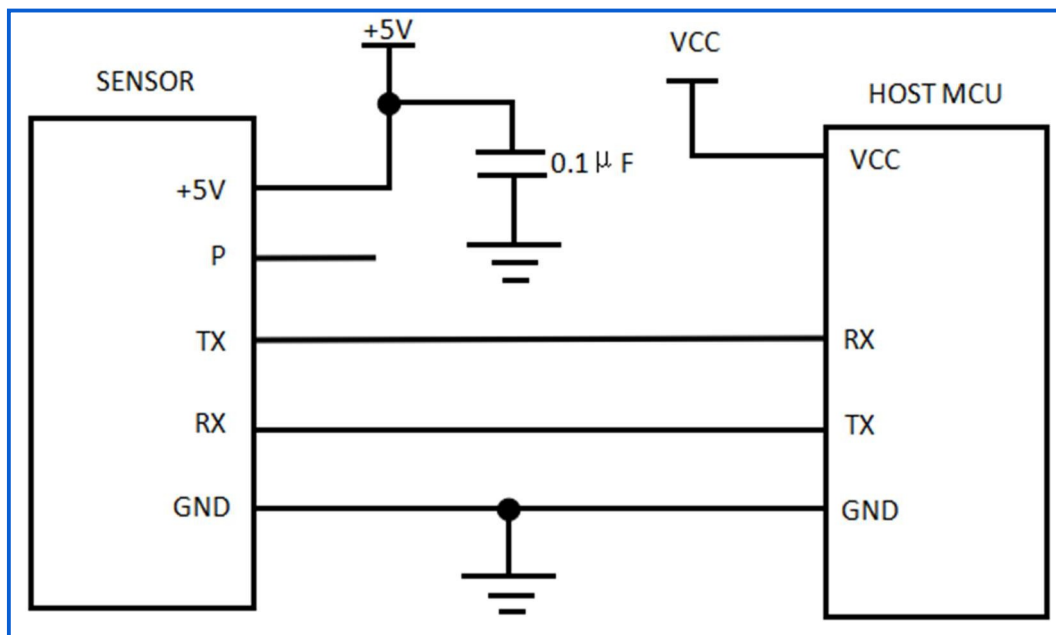


| No. | Pin    | Description  |
|-----|--------|--|
| 1   | VCC    | Power input (+5V)  |
| 2   | RX/SDA | UART receiving/IIC data  |
| 3   | TX/SCL | UART sending/IIC clock   |
| 4   | P      | Output mode exchange TTL level @3.3V<br>High level or floating is UART<br>communication mode, low level is IIC<br>communication mode |
| 5   | GND    | Power input (ground terminal)  |

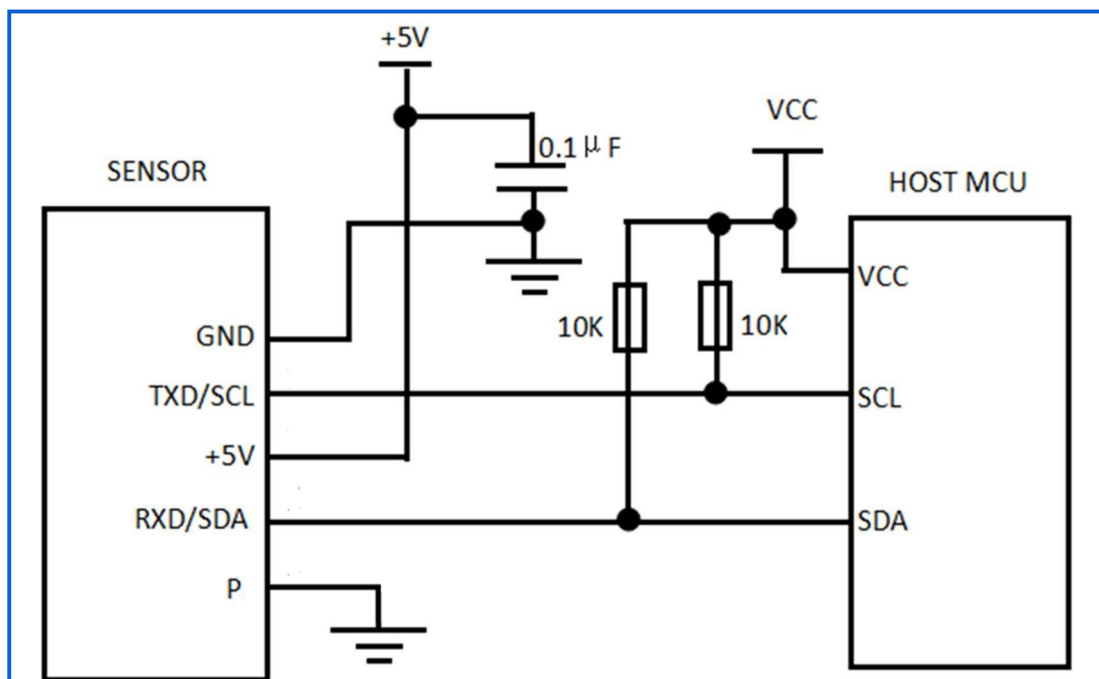
| Item      | Part Number      | Pitch  |
|-----------|------------------|--------|
| Connector | CJT A1501WR-S-5P | 1.5 mm |

## Typical Application Circuit

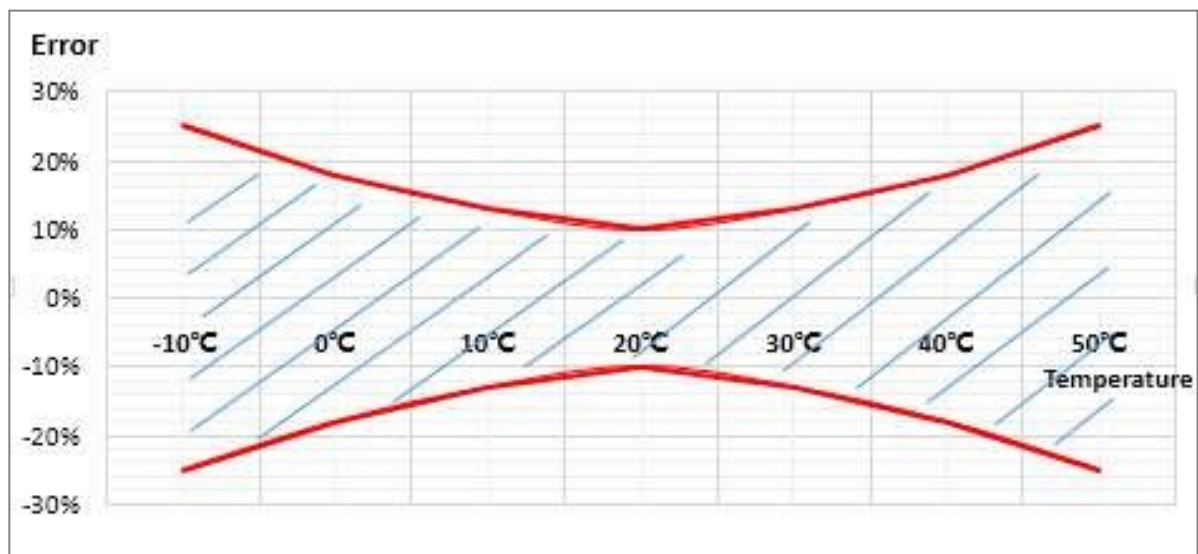
### Case 1. UART Application



### Case 2. IIC Application



## Temperature Influence

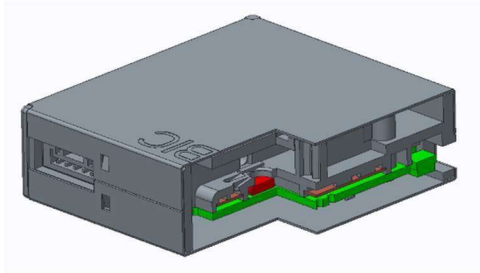


Particle measured error: under  $25\pm 2^{\circ}\text{C}$ ,  $50\pm 10\%\text{RH}$ ,  $0\sim 500\mu\text{g}/\text{m}^3$ , consistency and accuracy of  $\text{PM}_{1.0}/\text{PM}_{2.5}$  is  $\pm 10\%$  reading or  $\pm 10\mu\text{g}/\text{m}^3$ , whichever is larger (GRIMM 11-A, Cigarette+A1 Dust).



## User Attention

- It is for household electronics products. For application of medical, mining, disaster preparedness, which needs high security and high dependence, this sensor is not suitable.
- Please do not use it in bad dusty environment and close sampling port.
- Avoid using the sensor under situation with strong magnetic, such as situation close to stereo speaker, microwave oven, induction cooking.
- When installing to system, make sure the inlet and outlet is unobstructed, and cannot be touched against by large air stream. There are two sides cannot be put downwards (As below pictures), In case of dust deposition on the surface of sensitive device, dust deposition will affect accuracy of sensor.



Inner crossing section drawn



Recommend installation

- The metal case of sensor connects with the DC ground of inner circuit directly, which will cause safety problem if touching with DC ground. To avoid this problem, Sensor should be internally installed and no permit for touching sensor before power off.
- There is no high pressure transient protection circuit of the sensor. The power supply of the sensor should be stable 5V and low noise. Please refer to the working current in specification table.
- The sensor itself is safe to use. What the user should be cautious is the safety of power supply and structure design on the sensor.
- This product is defined as 3R laser product according to 《GB7247.1-2012 laser product safety》 with laser radiation inside. Please avoid direct illumination on the eye. The warning label is as below.



# UART Communication Protocol

## 1. General Statement

- 1) The data in this protocol is all hexadecimal data. For example, "46" for decimal [70].
- 2) [xx] is for single-byte data (unsigned, 0-255); for double data, high byte is in front of low byte.
- 3) Baud rate: 9600; Data Bits: 8; Stop Bits: 1; Parity: No

## 2. Format of Serial Communication Protocol

Sending format of software:

| Start Symbol | Length | Command | Data 1 | ..... | Data n. | Check Sum |
|--------------|--------|---------|--------|-------|---------|-----------|
| HEAD         | LEN    | CMD     | DATA1  | ...   | DATAn   | CS        |
| 11H          | XXH    | XXH     | XXH    | ...   | XXH     | XXH       |

Detail description on protocol format:

| Protocol Format | Description   |
|-----------------|---|
| Start symbol    | Sending by software is fixed as [11H], module respond is fixed as [16H] |
| Length          | Length of frame bytes= data length + 1 (including CMD+DATA)             |
| Command         | Command   |
| Data            | Data of writing or reading, length is not fixed                         |
| Check sum       | Cumulative sum of data = 256- (HEAD+LEN+CMD+DATA)                       |

## 3. Command Table of Serial Protocol

| Item No. | Function Description                            | Command |
|----------|---|---------|
| 1        | Read particle measurement result                | 0x0B    |
| 2        | Open/close particle measurement                 | 0x0C    |
| 3        | Set up and read particle calibrated coefficient | 0x07    |
| 4        | Read software version number                    | 0x1E    |
| 5        | Read serial number                              | 0x1F    |

## 4. Detail Description of UART Protocol

### 3.1 Read Particle Measurement Result

**Send:** 11 02 0B 07 DB

**Response:** 16 35 0B DF1- DF52 [CS]

**Function:** Read concentration of particle

**Note:** Read particle concentration (ug/m3)

$PM_{1.0} = DF1 * 256^3 + DF2 * 256^2 + DF3 * 256^1 + DF4$

$PM_{2.5} = DF5 * 256^3 + DF6 * 256^2 + DF7 * 256^1 + DF8$

$PM_{10} = DF9 * 256^3 + DF10 * 256^2 + DF11 * 256^1 + DF12$

DF13~DF48: Reserved

DF49:

Alarm of sensor module working condition:

| Bit              | Bit 7                        | Bit 6 | Bit 5                       | Bit 4                | Bit 3                      | Bit 2                       | Bit 1                         | Bit 0                          |
|------------------|------------------------------|-------|-----------------------------|----------------------|----------------------------|-----------------------------|-------------------------------|--------------------------------|
| Alarm definition | 1: Laser diode short circuit |       | 1: Laser diode open circuit | 1: dust accumulation | 1: low working temperature | 1: high working temperature | 1: Fan at low revolving speed | 1: Fan at high revolving speed |

DF50, DF51, DF52: Reserved

**Note:** Part of reserved bytes is used for Cubic internal testing and not related to function.

### 3.2 Open/Close Particle Measurement

**Send:** 11 03 0C DF1 1E CS

**Response:** 16 02 0C DF1 CS

**Function:** Open/close measurement

**Note:**

1. When sending command, DF1=02 means opening measurement, DF1=01 means closing measurement;
2. When receiving response, DF1=02 means measuring opened, DF1=01 means measuring closed;

### 3.3 Set up and Read Particle Calibrated Coefficient

**Send:** 11 02 07 DF1 [CS] // Set up particle calibrated coefficient

**Send:** 11 01 07 E7 // Read particle calibrated coefficient

**Response:** 16 02 07 DF1 [CS]

**Function:** Read/set up particle calibrated coefficient

**Note:**

1. Range 70~150, corresponding coefficient: 0.7~1.5

**Description:**

1. When there is difference between standard device, calibrated coefficient can be set to correct the final value.
2. When calibrated coefficient is set, the value of PM1.0, PM2.5, and PM10 will be all corrected by this coefficient.

### 3.4 Read Software Version Number

**Send:** 11 01 1E D0

**Response:** 16 0E 1E DF1~DF13 [CS]

**Function:** Read software version

**Note:**

Software version="DF1~DF13", should change the HEX code to ASCII code.

**Example:**

HEX code: 16 0E 1E 50 4D 20 56 31 2E 32 36 2E 35 2E 32 38 E9

ASCII code: PM V1.26.5.28

### 3.5 Read Serial Number

**Send:** 11 01 1F CF

**Response:** 16 0B 1F DF1 DF2 DF3 DF4 DF5 DF6 DF7 DF8 DF9 DF10 CS

**Function:** Read serial number

**Note:**

Serial number = (DF1\*256+DF2), (DF3\*256+DF4), (DF5\*256+DF6), (DF7\*256+DF8), (DF9\*256+DF10)

**Example:**

Response: 16 0B 1F 00 00 00 7E 09 07 07 0E 0D 72 9E

Serial number: 0000 0126 2311 1806 3442

# IIC Communication Protocol

## 1. Brief Introduction

- a. This is an IIC protocol for PM2016. The sensor module is lower computer, which is not able to initiate communication automatically. Communication is initiated via main controlled board, which reads data and sends control commands.
- b. Communication clock frequency  $\leq 100\text{Khz}$

## 2. Communication Common Command

START: start signal, send by main controlled board;

STOP: stop signal, send by main controlled board;

ACK: acknowledge signal, send by the sensor module if in bold; otherwise, send by main controlled board;

NACK: non-acknowledge signal, send by the sensor module if in bold; otherwise, send by main controlled board;

Px: receive and send data; send by the sensor module if in bold; otherwise, send by main controlled board.

## 3. Protocol Detailed Description

### 3.1 Send Command Data

Send by main controlled board:

START+WRITE+ACK+P1+ACK+P2+ACK+..... +P7+ACK+STOP

| Data           | Byte content                   | Description  |
|----------------|--------------------------------|--|
| Device address | Sensor address and writing bit | This byte is 0x50 when write data  |
| P1             | 0x16                           | Frame header   |
| P2             | Frame length                   | Number of byte, not including length of device address (From P1 to P7, 7 bytes in total)                             |
| P3             | Data 1                         | Control command of the sensor as:<br>Close measurement: 1<br>Open measurement: 2<br>Set up calibration coefficient:6 |
| P4             | Data 2, high byte              | Calibration coefficient:(Range: 70~150, Corresponding: 0.7~1.5)  |
| P5             | Data 2, low byte               |  |
| P6             | Data 3                         | Reserved   |
| P7             | Data check code                | Check code= $(P1 \wedge P2 \wedge \dots \wedge P6)$  |

### 3.2 Read Data Command

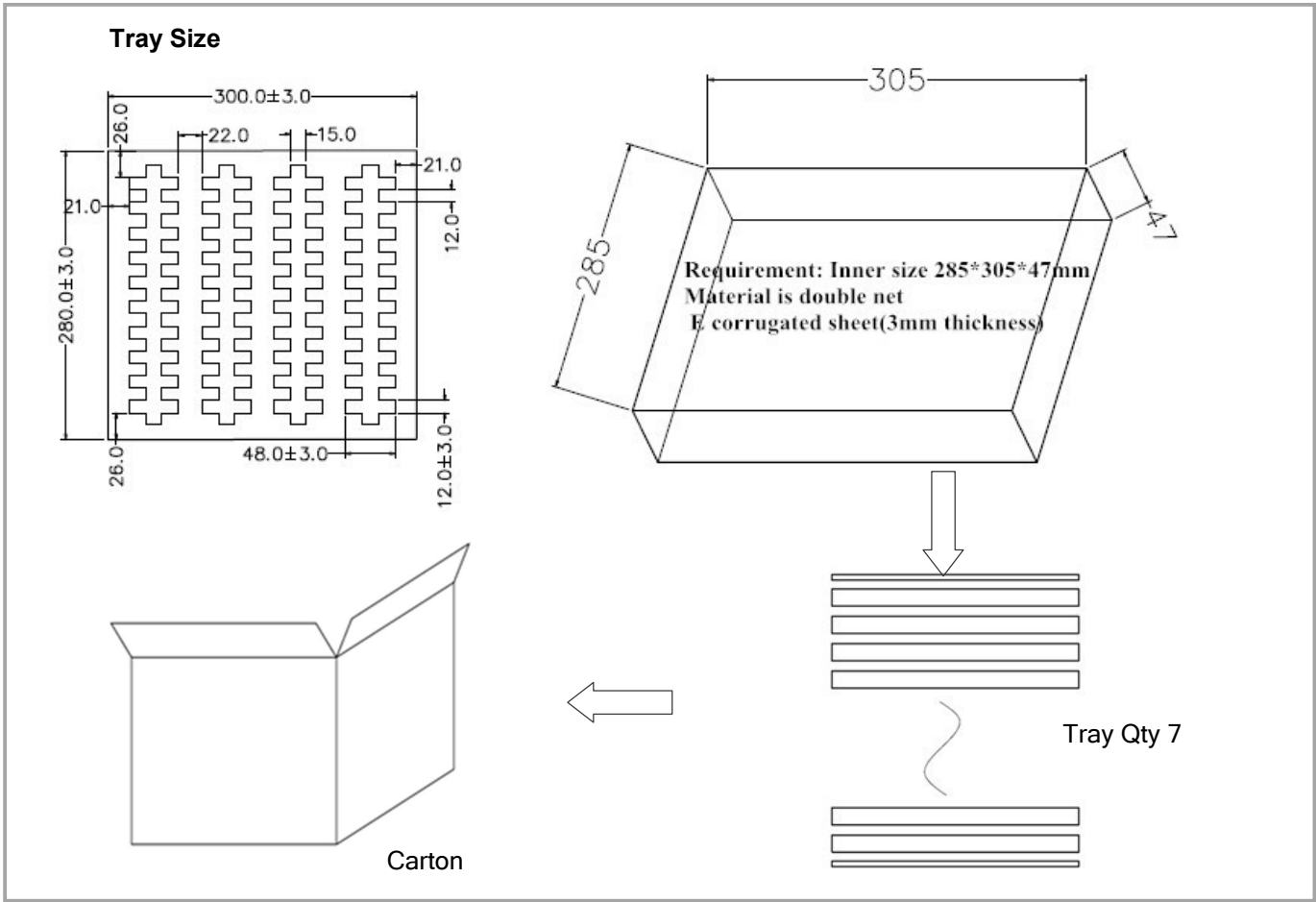
Send by main controlled board:

START+READ+ACK+P1+ACK+P2+ACK+.....+P32+NACK+STOP

| Data           | Byte content                   | Description   |
|----------------|--------------------------------|---|
| Device address | Sensor address and reading bit | This byte is 0x51 when read data  |
| P1             | 0x16                           | Frame header  |
| P2             | Frame length                   | Number of byte, not including length of device address (from P1 to P32, 32 bytes in total)  |
| P3             | Sensor status                  | Close: 01; Alarm: 07, means the temperature is too high or too low, or fan speed is too high or too low.; Measuring: 02; Other data is invalid. |
| P4             | Data 1, high byte              | Reserved  |

|     |                    |  |
|-----|--------------------|--|
| P5  | Data 1, low byte   |  |
| P6  | Data 2, high byte  | Calibration coefficient: (Range: 70~150, Corresponding: 0.7~1.5) |
| P7  | Data 2, low byte   |  |
| P8  | Data 3, high byte  | PM1.0, unit: $\mu\text{g}/\text{m}^3$                            |
| P9  | Data 3, low byte   |  |
| P10 | Data 4, high byte  | PM2.5, unit: $\mu\text{g}/\text{m}^3$                            |
| P11 | Data 4, low byte   |  |
| P12 | Data 5, high byte  | PM10, unit: $\mu\text{g}/\text{m}^3$                             |
| P13 | Data 5, low byte   |  |
| P14 | Data 6, high byte  | Reserved   |
| P15 | Data 6, low byte   |  |
| P16 | Data 7, high byte  |  |
| P17 | Data 7, low byte   |  |
| P18 | Data 8, high byte  |  |
| P19 | Data 8, low byte   |  |
| P20 | Data 9, high byte  |  |
| P21 | Data 9, low byte   |  |
| P22 | Data 10, high byte |  |
| P23 | Data 10, low byte  |  |
| P24 | Data 11, high byte |  |
| P25 | Data 11, low byte  |  |
| P26 | Data 12, high byte |  |
| P27 | Data12, low byte   |  |
| P28 | Data 13, high byte |  |
| P29 | Data 13, low byte  |  |
| P30 | Data 14, high byte |  |
| P31 | Data 14, low byte  |  |
| P32 | Data check code    | Check code = $(P1 \wedge P2 \wedge \dots \wedge P31)$            |

## Package Information



| Sensor per Tray | Tray Qty | Sensor per | Carton Dimensions | Packing Material    |
|-----------------|----------|------------|-------------------|---------------------|
| 40 pcs          | 7 layers | 280 pcs    | 395*310*330 mm    | Red anti-static EPE |

## After-Sales Services and Consultancy

Cubic Sensor and Instrument Co.,Ltd.

Tel: +86 (0)27 81628827 Fax: +86 (0)27 81628821

Add: Fenghuang No.3 Road, Fenghuang Industrial Park, Eastlake Hi-tech  
Development Zone, Wuhan 430205, China

E-mail: info@gassensor.com.cn