

水平集变分推导

SA20218108 聂文尚:

能量函数: $\epsilon_{g,\lambda,\nu} \lambda \mathcal{L}_g(\phi) + \nu \mathcal{A}_g(\phi)$

$$\mathcal{L}_g(\phi) = \int_{\Omega} g\delta(\phi)|\nabla\phi|dxdy,$$

$$\mathcal{A}_g(\phi) = \int_{\Omega} gH(-\phi)dxdy,$$

$$g = \frac{1}{1 + |\nabla G_{\sigma} * I|^2}$$

δ is the univariate Dirac function, and it is a non-derivable function

$$H(t) = \begin{cases} 0, & t < 0 \\ \frac{1}{2}, & t = 0 \\ 1, & t > 0 \end{cases}$$

Solution:

先解 $\mathcal{L}_g(\phi) = \int_{\Omega} g\delta(\phi)|\nabla\phi|dxdy$:

$$\text{记 } E(\phi) = \mathcal{L}_g(\phi) = \int_{\Omega} g\delta(\phi)|\nabla\phi|dxdy$$

$$\text{记 } F(\phi) = g\delta(\phi)|\nabla\phi| = g\delta(\phi)\sqrt{\phi_x^2 + \phi_y^2}$$

引入极小变量 t 和任意函数 h , 其中函数 h 满足: $h|_{\partial\Omega} = 0$

$$\begin{aligned} \therefore F(\phi + th) &= g\delta(\phi)\sqrt{(\phi + th)_x^2 + (\phi + th)_y^2} \\ \therefore \frac{\partial F(\phi + th)}{\partial t} &= g\delta(\phi) \frac{h_x(\phi + th)_x + h_y(\phi + th)_y}{2\sqrt{(\phi + th)_x^2 + (\phi + th)_y^2}} \\ &= \frac{1}{2}g\delta(\phi) \frac{\nabla h \cdot \nabla(\phi + th)}{\sqrt{(\phi_x^2 + \phi_y^2) + t^2(h_x^2 + h_y^2) + 2t\nabla h \cdot \nabla\phi}} \\ \therefore \frac{\partial F(\phi + th)}{\partial t}|_{t \rightarrow 0} &= \frac{1}{2}g\delta(\phi) \frac{\nabla h \cdot \nabla\phi}{\sqrt{\phi_x^2 + \phi_y^2}} \end{aligned}$$

$$\begin{aligned} \therefore \frac{\partial E(\phi + th)}{\partial t}|_{t \rightarrow 0} &= \int_{\Omega} \frac{1}{2}g\delta(\phi) \frac{\nabla h \cdot \nabla\phi}{\sqrt{\phi_x^2 + \phi_y^2}} dxdy \\ &= \frac{1}{2}\delta(\phi) \int_{\Omega} g \frac{\nabla h \cdot \nabla\phi}{\sqrt{\phi_x^2 + \phi_y^2}} dxdy \\ &= \frac{1}{2}\delta(\phi) \int_{\Omega} g \frac{h_x\phi_x + h_y\phi_y}{\sqrt{\phi_x^2 + \phi_y^2}} dxdy \end{aligned}$$

$$\begin{aligned} \therefore \frac{\partial}{\partial x}[g\phi_x h] &= gh_x\phi_x + gh\phi_{xx} \\ \frac{\partial}{\partial y}[g\phi_y h] &= gh_y\phi_y + gh\phi_{yy} \end{aligned}$$

$$\therefore \frac{\partial E(\phi + th)}{\partial t} \Big|_{t \rightarrow 0} = \frac{1}{2} \delta(\phi) \left[\int_{\Omega} \left(\frac{\partial}{\partial x} \left[g \frac{\phi_x}{|\nabla \phi|} h \right] + \frac{\partial}{\partial y} \left[g \frac{\phi_y}{|\nabla \phi|} h \right] \right) dx dy - \int_{\Omega} \left(\frac{\partial}{\partial x} \left[g \frac{\phi_x}{|\nabla \phi|} \right] h + h \frac{\partial}{\partial y} \left[g \frac{\phi_y}{|\nabla \phi|} \right] \right) dx dy \right]$$

$$\text{According to Green Equation: } \oint_{\partial \Omega} R dy + S dx = \iint_{\Omega} \left(\frac{dS}{dy} - \frac{dR}{dx} \right) dx dy$$

$$\therefore \int_{\Omega} \left(\frac{\partial}{\partial x} \left[g \frac{\phi_x}{|\nabla \phi|} h \right] + \frac{\partial}{\partial y} \left[g \frac{\phi_y}{|\nabla \phi|} h \right] \right) dx dy = \oint_{\partial \Omega} h g \left(\frac{\phi_y}{|\nabla \phi|} - \frac{\phi_x}{|\nabla \phi|} \right) dx dy = 0$$

$$\begin{aligned} \therefore \frac{\partial E(\phi + th)}{\partial \phi} \Big|_{t \rightarrow 0} &= -\frac{1}{2} \delta(\phi) \int_{\Omega} h \cdot \left(\frac{\partial}{\partial x} \left[g \frac{\phi_x}{|\nabla \phi|} \right] + \frac{\partial}{\partial y} \left[g \frac{\phi_y}{|\nabla \phi|} \right] \right) dx dy \\ &= -\frac{1}{2} \delta(\phi) \int_{\Omega} h \cdot \nabla \left[g \frac{\nabla \phi}{|\nabla \phi|} \right] dx dy \end{aligned}$$

$$\text{When } E(\phi) \text{ reach the minimal, } \frac{E(\phi + th)}{\phi t} \Big|_{t \rightarrow 0} = -\frac{1}{2} \delta(\phi) \int_{\Omega} h \cdot \nabla \left[g \frac{\nabla \phi}{|\nabla \phi|} \right] dx dy = 0$$

$$\text{Since function } h \text{ is arbitrary, we obtain: } \delta(\phi) \nabla \left[g \frac{\nabla \phi}{|\nabla \phi|} \right] = 0$$

再解 $\mathcal{A}_g(\phi) = \int_{\Omega} g H(-\phi) dx dy$:

$$\begin{aligned} \text{同样记 } E(\phi) &= \mathcal{A}_g(\phi) = \int_{\Omega} g H(-\phi) dx dy \\ \text{记 } F(\phi) &= g H(-\phi) \end{aligned}$$

引入极小变量 t 和任意函数 h , 其中函数 h 满足: $h|_{\partial \Omega} = 0$

$$\begin{aligned} F(\phi + th) &= g H(-\phi - th) \\ \therefore \frac{\partial F(\phi + th)}{\partial t} &= g \delta(-\phi - th)(-h) = -h \cdot g \delta(-\phi) = -h \cdot g \delta(\phi) \\ \therefore \frac{\partial E(\phi + th)}{\partial t} &= - \int_{\Omega} h g \delta(\phi) dx dy \end{aligned}$$

$$\text{When } E(\phi) \text{ reach the minimal, } \frac{E(\phi + th)}{\partial t} \Big|_{t \rightarrow 0} = - \int_{\Omega} h \cdot g \delta(\phi) dx dy = 0$$

$$\text{Since function } h \text{ is arbitrary, we obtain: } g \delta(\phi) = 0$$

综上所述演化方程:

$$\frac{\partial \phi}{\partial t} = \lambda \delta(\phi) \nabla \left[g \frac{\nabla \phi}{|\nabla \phi|} \right] + \nu g \delta(\phi)$$