Shuaihu WU

Email: wsh20@mails.tsinghua.edu.cn Mobile: +86-18800109330 Personal Website: shuaihu-wu.com

EDUCATION

Tsinghua University

Beijing, China 2020 - July, 2023

Master in Mechanical Engineering - Lab of Precision Equipment & Control; GPA: 3.63/4.0

- Core Courses: Introduction to Modern Control Theories and Methods, Advanced Numerical Analysis, Mechatronic Intelligent Control Engineering, Modern Mechatronics System
- Research Field: Sensorless Control, Ultra-precision Control, Motor Driver Design
- Scholarship: Outstanding Postgraduate Students Award of Tsinghua University (First Prize)

École CentraleSupélec

Paris, France

Master in Engineering (Dual degree); GPA: 4.00/4.3

2018 - July, 2023

• Core Courses: Algorithm, Machine Learning, Statistic Learning, Enterprise Management, Financial Management, Philosophy, Electronics, Quantum Physics

Université Paris-Saclav

Paris. France 2019 - 2020

Bachelor in Mathematics (Dual degree); GPA: 3.00/4.0

• Core Courses: Measure and Probability, Topology, Ordinary Differential Equation, Abstract Algebra, Holomorphic Function

Tsinghua University

Beijing, China

Bachelor in Mechanical Engineering; GPA: 3.37/4.0

- 2016 2020
- Core Courses: Theoretical Mechanics, Calculus, Linear Algebra, Discrete Mathematics, Basic Program Design, Electrical and Electronics Technologies
- Program: Selected for "Sino-France 4+4" Program(a dual degree program with 2 years in China as a bachelor student, 2 years in France as an engineer student, and 3 years in China as a master's student. Diplomas of two schools will be awarded upon finish.
- Scholarship: China Scholarship Council (CSC) Scholarship

Publications and Patents

- [1] S. Wu, C. Hu, Z. Zhao, R. Zhou, and Y. Zhu, "A Novel Flux Estimator using α - β Orthogonality Drift Elimination for High Performance Full-speed-range Sensorless Control," 2022 IEEE/ASME AIM (Oral Report)
- [2] Z. Zhao, C. Hu, Z. Wang, S. Wu, Z. Liu, Y. Zhu, "Back EMF-Based Dynamic Position Estimation in the Whole Speed Range for Precision Sensorless Control of PMLSM," IEEE Trans. Ind. Inform., 2022
- [3] S. Wu, C. Hu, Z. Zhao, and Y. Zhu, "High Accuracy Sensorless Control of Permanent Magnet Linear Synchronous Motors for Variable Speed Trajectories," Submitted to IEEE Trans. Ind. Electron.
- [4] C. Hu, S. Wu, Z. Zhao, "Method and Device to Find Motor Position," CN115632588A, 2023-01-20.
- [5] E. Wang, C. Hu, X. Liu, B, Feng, S. Wu, "Crawling Robot," CN114248252A,2022-03-29.
- [6] E. Wang, X. Liu, C. Hu, S. Wu, B, Feng, "Pole Climbing Device," CN114161439A, 2022-03-11.

Research and Projects

Research on sensorless control

2021-2023, Tsinghua, Beijing

- Proposed a novel flux estimator that can improve the performance of sensorless control in full speed range, with high accuracy and dynamic response.
- Theoretical proof of stability and criteria of parameter selection was given.
- Built an experiment set including a permanent magnet linear synchronous motor, a motor driver and a controller.
- Achieved a sensorless position estimation accuracy less than 50 micro meters.
- Author or co-authored 3 papers. (1 Journal paper and 1 conference paper accepted [1-2], 1 journal paper under review [3])
- Drafted and submitted 1 patents [4].

Under-mine Robot Design and Prototype Manufacturing

2020, Tsinghua, Beijing

- Designed and manufactured a moving robot prototype to conduct coal-rock identification and mining condition monitoring.
- Special design for extreme under-mine environment, with flexible structure and a novel displacement strategy.
- Designed and built a high load (>10kg) gimbal and its auto-balance system.
- Drafted and submitted 2 patents [5-6].

Sensor Data Analysis of Wind Farms

2019, CentraleSupélec, Paris

- Work including data cleaning, machine learning, presentation and communication with experts from EDF.
- Produced a script which can analysis the sensor data and predict future failure of wind turbines.

AFM Project

2019, CentraleSupélec, Paris

- To build a low-budget Atomic Force Microscope (AFM) by using an optical pick-up unit (OPU) and a piezoelectric plate.
- Designed the circuit board and realized the control algorithm of the AFM tip.

Production Internship

2019, Renault, Paris

- Worked in the production line as a ordinary worker; made interviews with line manager.
- Written a report on factory organization and modern production line management.

Virtual Design of an Electron Synchrotron

2019, CentraleSupélec, Paris

- Work including literature research, magnetic field design, presentation and communication with experts.
- Written a report on principle and engineering realization of an electron synchrotron.

Analysis and Visualization of Social Media Data

2018, TNP Consult, Paris

- Work including customer Profiling, coding and UI design.
- programmed an application which can produce a dashboard on customer's reputation on social media.

ACTIVITIES

Volunteer of 2022 Beijing Winter Olympics

Feb 2022 - Apr 2022, Beijing, China

- Worked in the anti-doping team during the Olympic and Paralympic game.
- Honored as "Outstanding Volunteer in Olympics of Tsinghua University" (10% of the volunteers).

President of Chinese-French Association of Tsinghua University

Sep 2020 - Sep 2021, Beijing, China

- Organized several activities about French culture and volunteered at French embassy to help to promote French education.
- Invited to attend the national day dinner party at French embassy.

Work-exchange in a Swiss Family

Aug 2019, Sion, Switzerland

• Living with local people, worked in a Swiss farm in exchange of food and accommodation.

Class Leader

Sep 2017 - Jun 2018, Beijing, China

- Elected as the class leader serving 30 students at Tsinghua University.
- Organized several meetings to discuss concerned issues and several activities to increase the sense of belonging.

Half Marathon

April 2018, Beijing, China

• Finished a half marathon of 21km.

Practical Skills

• Languages English(IELTS 7.5), French(level B2), Chinese(Native)

• Coding Python, C++, LATEX

• Software MATLAB, Simulink, SolidWorks, AutoCAD