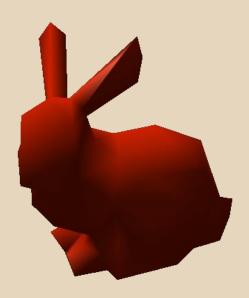
Subdivision

Project Overview

Surface Subdivision

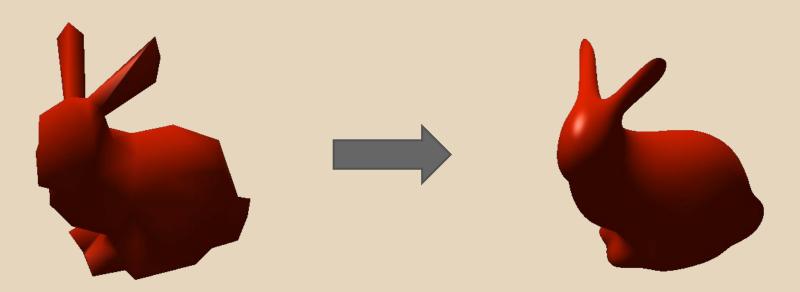
- Start with Polygon Mesh
- Refine mesh by creating new faces and vertices
- Repeat



Project Overview

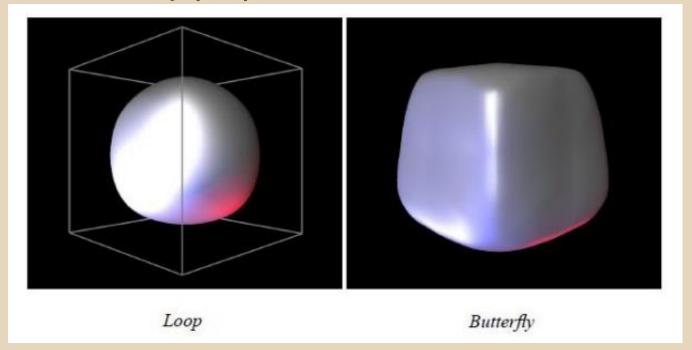
Surface Subdivision

- Start with Polygon Mesh
- Refine mesh by creating new faces and vertices
- Repeat



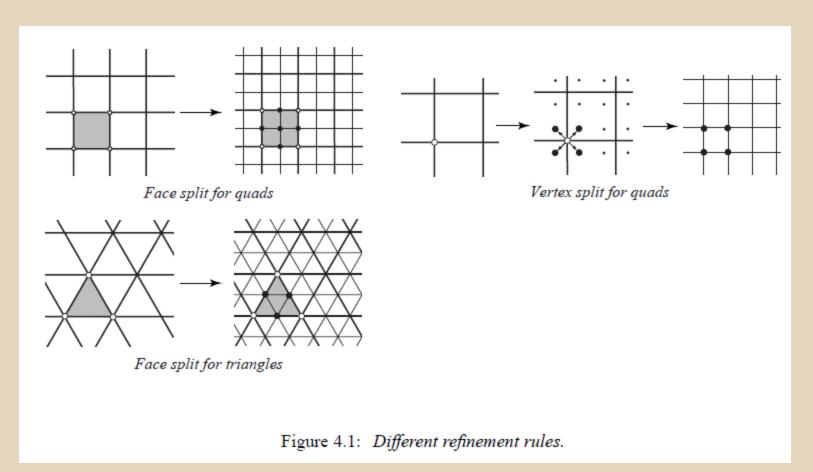
Subdivision

- Many different algorithms
 - Approximating v. Interpolating
 - Face Splitting v. Vertex Splitting
 - Continuity properties of final surface

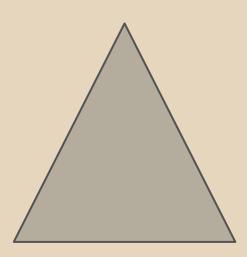


Subdivision

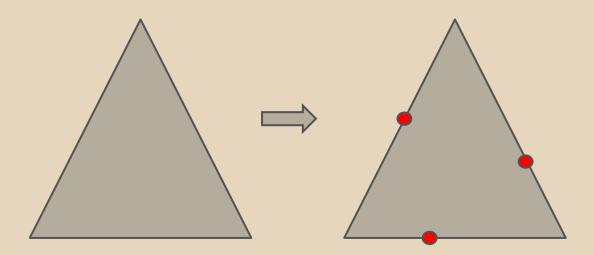
• Face split vs. Vertex split



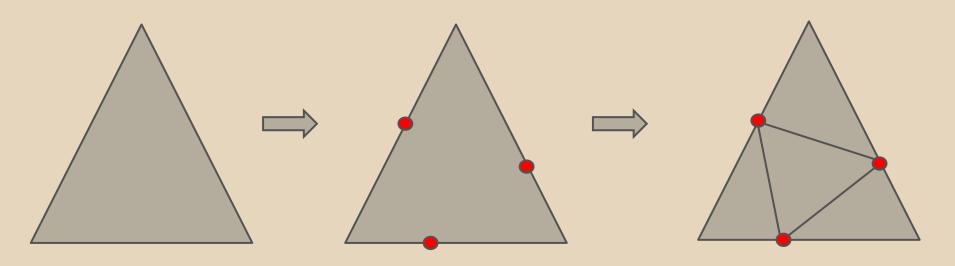
- Approximating
- Face Splitting
- C2 continuity on regular meshes



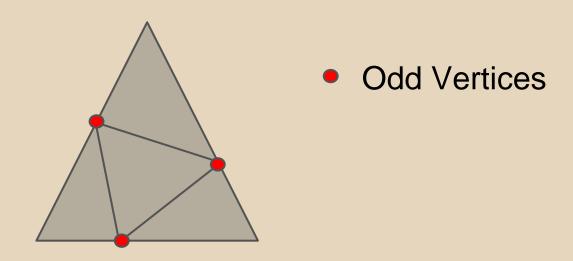
- Approximating
- Face Splitting
- C2 continuity on regular meshes



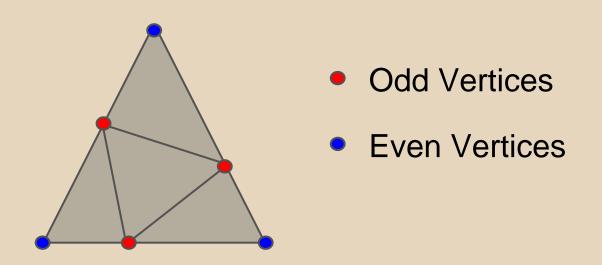
- Approximating
- Face Splitting
- C2 continuity on regular meshes



 Newly created vertices are called odd vertices

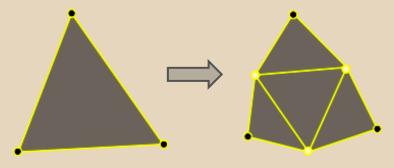


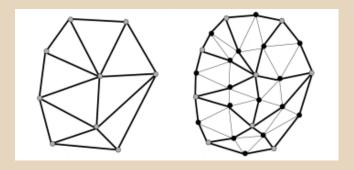
- Newly created vertices are called odd vertices
- Original vertices are called even vertices



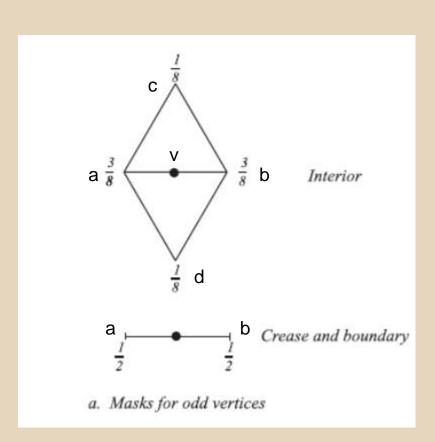
 But "Approximating" means we recompute positions of all vertices (even and odd)

 But "Approximating" means we recompute positions of all vertices (even and odd)





Computing odd vertices



Interior:

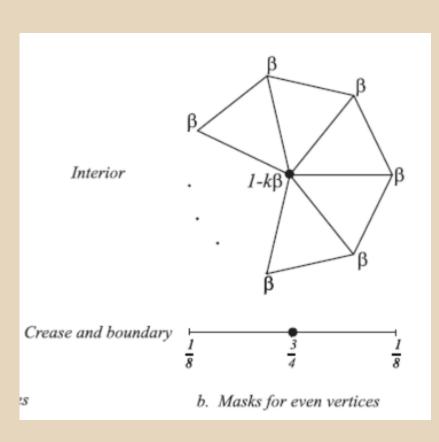
$$v = 3.0/8.0*(a + b) + 1.0/8.0*(c + d)$$

Boundary:

$$v = 1.0/2.0*(a + b)$$

Notice that to compute v we need some to know the nearby vertices.

Computing even vertices



Interior:

v = v*(1-k*BETA) +(sum of all k neighbor vertices) *BETA

Boundary:

$$v = 1.0/8.0*(a + b) + 3.0/4.0*(v)$$

Notice that to compute v we need know all neighboring vertices

Loop Subdivision - Picking Beta

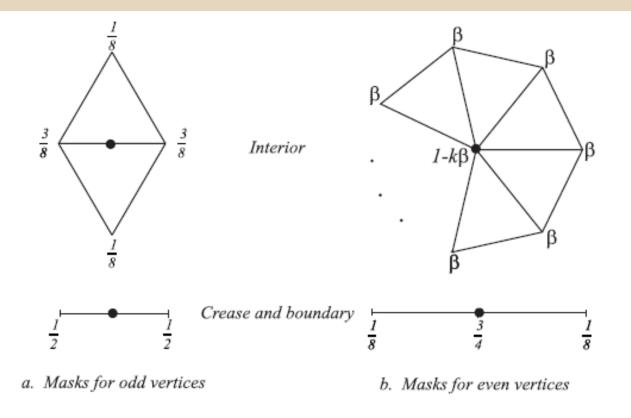


Figure 4.3: Loop subdivision: in the picture above, β can be chosen to be either $\frac{1}{n}(5/8-(\frac{3}{8}+\frac{1}{4}\cos\frac{2\pi}{n})^2)$ (original choice of Loop [16]), or, for n>3, $\beta=\frac{3}{8n}$ as proposed by Warren [33]. For n=3, $\beta=3/16$ can be used.

- Computing odd vertices
- Computing even vertices

Important:

- 1. We need to be able to query adjacency information about the mesh.
- 2. We need to be able to tell if a vertex is a boundary or interior vertex.

Algorithm (one iteration)

- 1. Build adjacency data structure Tricky
- 2. Compute odd vertices

 Straightforward once you finish step 1.
- 3. Compute even vertices

 Straightforward once you finish step 1.
- 4. Rebuild mesh / Connect vertices to create new faces

Similar to Project 1 (when you created a mesh from a heightmap)

What properties do you want?

- Efficient traversal and lookup
 - o get adjacent faces (&mesh, &edge)
 - o get neighbor vertices (&mesh, &vertex)
- Efficient memory usage
- Efficient creation and update

What data do you need in the structure? Mesh Data

- Some combination of Vertices, Faces, Edges
- Adjacency information

Loop Subdivision Metadata

- implicit
 - o all edges of index < i have been subdivided
- explicit

```
o if (!mesh.edge[i].is_subdivided) ...
```

Useful Mesh Attributes

- Every triangle has 3 vertices
- Every triangle is adjacent to up to 3 other triangles

Useful Mesh Attributes

- Every triangle has 3 vertices
- Every triangle is adjacent to up to 3 other triangles
- A given vertex has N neighbor vertices
- The same vertex is part of either N-1 or N triangles
 - O Why?
 - There is a useful implication of this for Loop Subdivision

Useful Adjacency Attributes

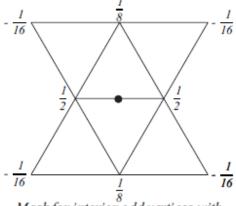
- Triangle -> Vertex
- Triangle -> Triangle
- Vertex -> Vertex
- Vertex -> Triangle

This is a simple representation that can handle the queries you need.

Implementation

- How you implement (storing and building) the adjacency data structure can be more important than what you represent.
- Stick to C data structures (arrays and structs) for the best speed
- Be mindful that malloc/new and free/delete are slow

• Modified Butterfly: interpolating algorithm

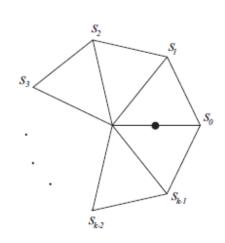


Mask for interior odd vertices with regular neighbors



Mask for crease and boundary vertices

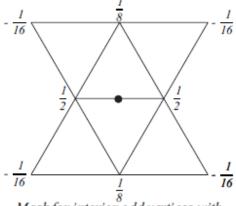
a. Masks for odd vertices



b. Mask for odd vertices adjacent to an extraordinary vertex

Figure 4.5: Modified Butterfly subdivision. The coefficients s_i are $\frac{1}{k} \left(\frac{1}{4} + \cos \frac{2i\pi}{k} + \frac{1}{2} \cos \frac{4i\pi}{k} \right)$ for k > 5. For k = 3, $s_0 = \frac{5}{12}$, $s_{1,2} = -\frac{1}{12}$; for k = 4, $s_0 = \frac{3}{8}$, $s_2 = -\frac{1}{8}$, $s_{1,3} = 0$.

• Modified Butterfly: interpolating algorithm

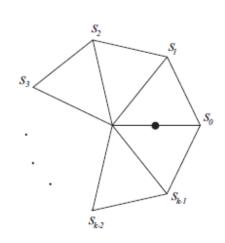


Mask for interior odd vertices with regular neighbors



Mask for crease and boundary vertices

a. Masks for odd vertices



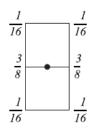
b. Mask for odd vertices adjacent to an extraordinary vertex

Figure 4.5: Modified Butterfly subdivision. The coefficients s_i are $\frac{1}{k} \left(\frac{1}{4} + \cos \frac{2i\pi}{k} + \frac{1}{2} \cos \frac{4i\pi}{k} \right)$ for k > 5. For k = 3, $s_0 = \frac{5}{12}$, $s_{1,2} = -\frac{1}{12}$; for k = 4, $s_0 = \frac{3}{8}$, $s_2 = -\frac{1}{8}$, $s_{1,3} = 0$.

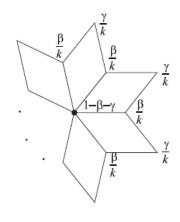
Catmull-Clark: approximating



Mask for a face vertex



Interior



Mask for an edge vertex



Crease and boundary



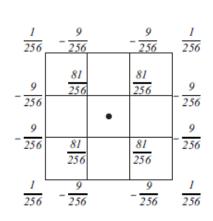
Mask for a boundary odd vertex

a. Masks for odd vertices

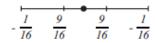
b. Mask for even vertices

Figure 4.8: Catmull-Clark subdivision. Catmull and Clark [4] suggest the following coefficients for rules at extraordinary vertices: $\beta = \frac{3}{2k}$ and $\gamma = \frac{1}{4k}$

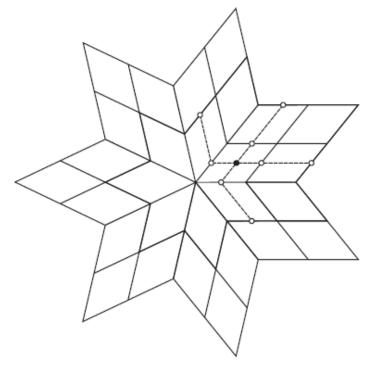
• Kobbelt: approximating



Mask for a face vertex



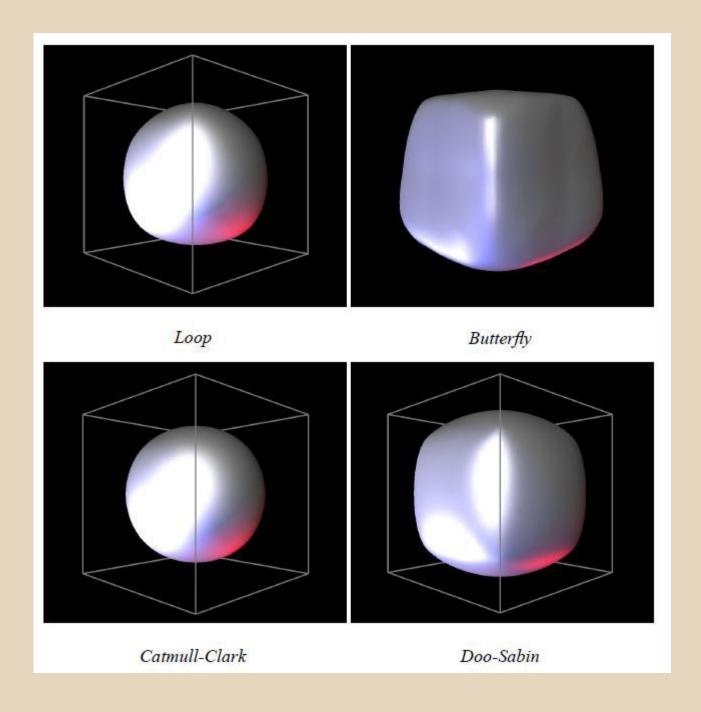
Mask for edge, crease and boundary vertices



b. Computing a face vertex adjacent to an extraordinary vertex

a. Regular masks

Figure 4.11: Kobbelt subdivision.



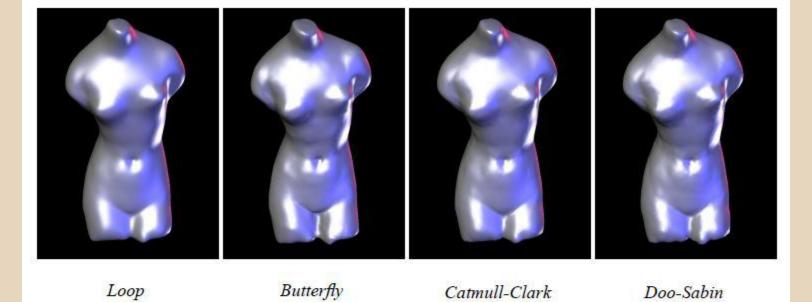
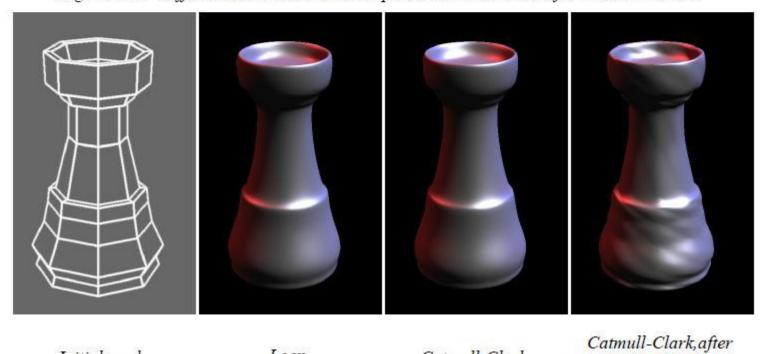


Figure 4.20: Different subdivision schemes produce similar results for smooth meshes.



triangulation

Initial mesh Loop Catmull-Clark