

n=0	1
n=1	1 1
n=2	1 2 1
n=3	1 3 3 1
n=4	1 4 6 4 1
n=5	1 5 10 10 5 1
	0 1 2 3 4 5

→ k successes

1. a. For  $N$  people with fair coins, the probability of an "odd-man-out" on the first flip is

$$P = B(1; N, P_{\text{flip}} = \frac{1}{2}) + B(4; N, P_{\text{flip}} = \frac{1}{2}) = 2 \frac{N!}{(N-1)!} \left(\frac{1}{2}\right)^1 \left(\frac{1}{2}\right)^{N-1}$$

$$= \boxed{\frac{N}{2^{N-1}}} \quad \left( \text{for } N=5, P(\text{success} | 1 \text{ flip}) = \frac{5}{16} \right)$$

- b. The mean number of flips required to achieve an "odd-man-out" is

$$E[n_{\text{flips}}] = n_{\text{flips}} P_{\text{single}} \quad \text{where } B(1; n_{\text{flips}}, P_{\text{single}} = \frac{N}{2^{N-1}})$$

$$E[B(1; n_{\text{flips}}, P_{\text{single}})] \Big|_{E=1} = n_{\text{flips}} P_{\text{single}} = 1 \quad \therefore \boxed{n_{\text{flips}} = \frac{2^{N-1}}{N}}$$

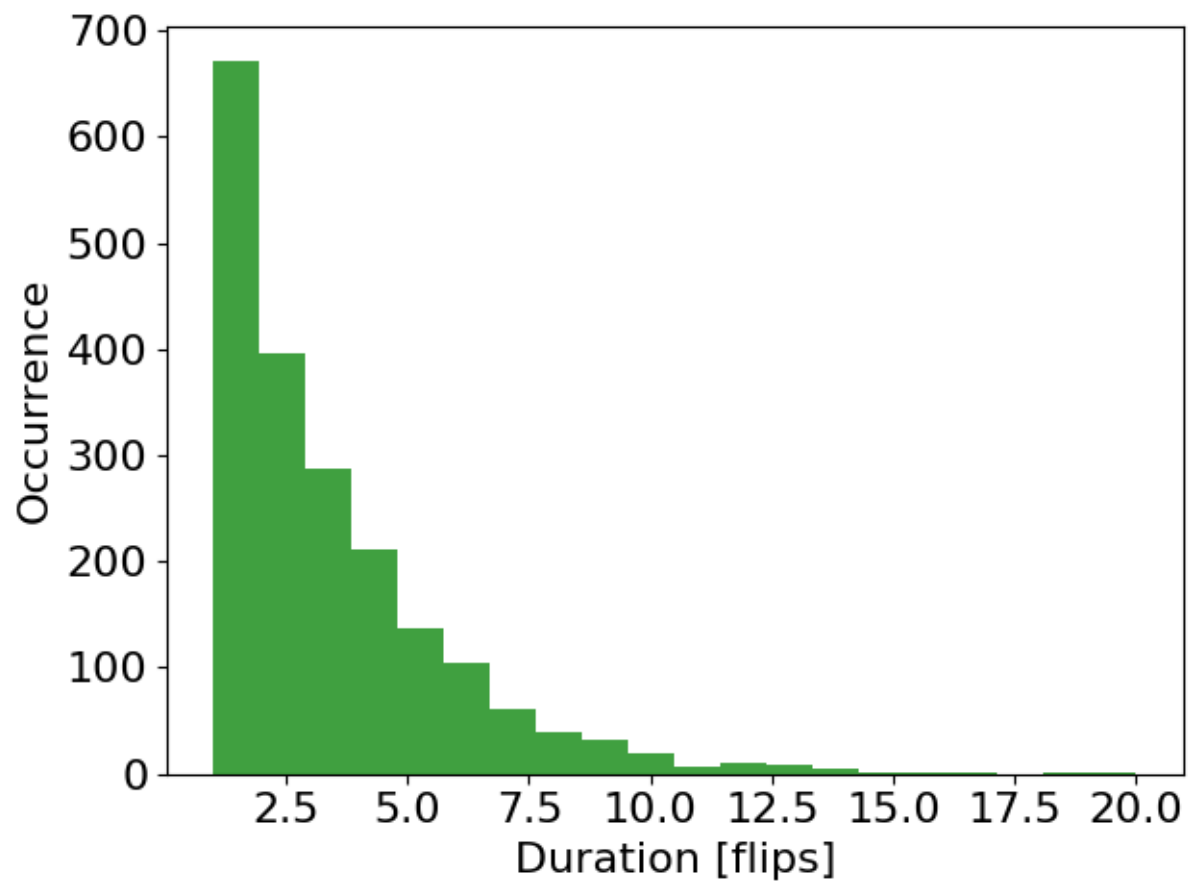
$$(\text{for } N=5, n_{\text{flips}} = \frac{16}{5} = 3.2)$$

- c. See my Github code; the mean of all 2000 games was  $\mu = 3.124$ , very close to the theoretical average, 3.2!

- d. Both theoretically and in Python game simulations, the biased coin does not affect the mean # of  $n_{\text{flips}}$ . This is because, with 1 coin fixed, 4 free coins may achieve the "odd man out" in the following ways:

$$B(0; 4, p = \frac{1}{2}) + B(3; 4, p = \frac{1}{2}) = \frac{1}{16} + \frac{4}{16} = \boxed{\frac{5}{16}}, \text{ the same as before.}$$

Problem 1c:



2a) Set of  $n=2$  random variables  $X = (X_1, \dots, X_n) \rightarrow (m, v)$   
with mean values of  $X_i$ ,  $\mu = (\mu_1, \dots, \mu_n) \rightarrow (\hat{m}, \hat{v})$ , and  
covariance matrix

$$V_{ij} = \begin{bmatrix} \text{cov}[m, m] & \text{cov}[v, m] \\ \text{cov}[m, v] & \text{cov}[v, v] \end{bmatrix} = \begin{bmatrix} \sigma_m^2 & 0 \\ 0 & \sigma_v^2 \end{bmatrix}$$

Then for a set of functions  $y = (y_1, \dots, y_n) \rightarrow (p, E)$  with  
mean values  $y_i$ ,  $\mu = (\hat{p}, \hat{E})$  such that  $y_i(X_1, X_2)$ .

Then the variance  $\sigma_y^2 \rightarrow \sigma_E^2$  or  $\sigma_p^2$  is approximately

$$\sigma_p^2 \approx \sum_{i,j=1}^{n=2} \frac{\partial p}{\partial x_i} \frac{\partial p}{\partial x_j} \bigg|_{\mu} V_{ij} = \frac{\partial p}{\partial m} \frac{\partial p}{\partial m} \bigg|_{\mu} V_{mm} + \frac{\partial p}{\partial m} \frac{\partial p}{\partial v} \bigg|_{\mu} V_{mv} + \frac{\partial p}{\partial v} \frac{\partial p}{\partial v} \bigg|_{\mu} V_{vv}$$

$$\frac{\partial p}{\partial v} \frac{\partial p}{\partial m} \bigg|_{\mu} V_{vm} + \frac{\partial p}{\partial v} \frac{\partial p}{\partial v} \bigg|_{\mu} V_{vv} = \sigma_m^2 \left[ \frac{\partial p}{\partial m} \right]^2 + \sigma_v^2 \left[ \frac{\partial p}{\partial v} \right]^2$$

so that

$$\sigma_p^2 \approx \sigma_m^2 V^2 + \sigma_v^2 m^2 = a^2 m^2 v^2 + b^2 v^2 m^2 = p^2 (a^2 + b^2)$$

(where  $a^2 = \frac{\sigma_m^2}{m^2}$  and  $b^2 = \frac{\sigma_v^2}{v^2}$  are the fractional uncertainties)

$$\text{and } \sigma_E^2 \approx \frac{\partial E}{\partial m} \frac{\partial E}{\partial m} \bigg|_{\mu=\hat{m}} V_{mm} + \frac{\partial E}{\partial v} \frac{\partial E}{\partial v} \bigg|_{\mu=\hat{v}} V_{vv} = \frac{1}{4} v^4 \sigma_m^2 + \frac{1}{4} m^2 (2v)^2 \sigma_v^2$$

$$\sigma_E^2 \approx \left[ \frac{1}{4} v^4 \sigma_m^2 + m^2 v^2 \sigma_v^2 \right] = \frac{1}{4} v^4 a^2 m^2 + m^2 v^2 b^2 v^2$$

$$= E^2 (a^2 + 4b^2)$$

Likewise, the covariance is

$$\begin{aligned} \text{cov}[p, E] &\approx \sum_{i,j=1}^{n=2} \left. \frac{\partial p}{\partial x_i} \frac{\partial E}{\partial x_j} \right|_{\hat{\mu}} V_{ij} \\ &\approx \frac{\partial p}{\partial m} \frac{\partial E}{\partial m} \sigma_m^2 + \frac{\partial p}{\partial v} \frac{\partial E}{\partial v} \sigma_v^2 = v \frac{1}{2} v^2 \sigma_m^2 + m \frac{1}{2} m^2 v \sigma_v^2 \\ &\approx \frac{1}{2} v^3 a^2 m^2 + \frac{1}{2} 2 m^2 v b^2 v^2 = E p a^2 + 2 E p b^2 \\ &= \boxed{E p (a^2 + 2 b^2)} \end{aligned}$$

The correlation coefficient  $\rho(p, E)$  is  $\frac{\text{cov}(p, E)}{\sigma(p) \sigma(E)} =$

$$= \frac{E p (a^2 + 2 b^2)}{p^2 (a^2 + b^2) E^2 (a^2 + 4 b^2)} = \boxed{\frac{(a^2 + 2 b^2)}{(a^2 + b^2)(a^2 + 4 b^2)} \frac{1}{E p}}$$

For the special cases  $a=0$  or  $b=0$ ,

$$\rho(p, E) \Big|_{a=0} = \frac{2 b^2}{b^2 4 b^2} \frac{1}{E p} = \boxed{\frac{1}{2 b^2} \frac{1}{E p}}$$

$$\rho(p, E) \Big|_{b=0} = \frac{a^2}{a^2 a^2} \frac{1}{E p} = \boxed{\frac{1}{a^2} \frac{1}{E p}}$$

When there is no uncertainty in  $a$ , the uncertainty in  $b$  cannot be zero, and vice versa. Furthermore, to keep  $|\rho| < 1$ , the maximum/min values of  $|a|/|b|$  are  $\sqrt{\frac{1}{2 E p}} = |b_{\text{max/min}}|$ ,  $\sqrt{\frac{1}{E p}} = |a|$ .



b)  $E, p$  and covariance matrix  $\text{cov}[p, E]_{lk}$  are known.

$$U = A V A^T$$

$$U A = A V A^T A$$

$$A^T U A = A^T A V A^T A = V$$

$$A = \begin{bmatrix} \frac{\partial p}{\partial m} & \frac{\partial p}{\partial v} \\ \frac{\partial E}{\partial m} & \frac{\partial E}{\partial v} \end{bmatrix}, \quad A^T = \begin{bmatrix} \frac{\partial p}{\partial m} & \frac{\partial E}{\partial m} \\ \frac{\partial p}{\partial v} & \frac{\partial E}{\partial v} \end{bmatrix}, \quad U = \begin{bmatrix} \sigma_p^2 & \text{cov}[p, E] \\ \text{cov}[p, E] & \sigma_E^2 \end{bmatrix}$$

where  $\text{cov}[p, E] = \frac{a^2 + 2b^2}{(a^2 + b^2)(a^2 + 4b^2)} \frac{1}{E p}$

$$V = \begin{bmatrix} \frac{\partial p}{\partial m} & \frac{\partial E}{\partial m} \\ \frac{\partial p}{\partial v} & \frac{\partial E}{\partial v} \end{bmatrix} \begin{bmatrix} \sigma_p^2 & \text{cov}[p, E] \\ \text{cov}[p, E] & \sigma_E^2 \end{bmatrix} \begin{bmatrix} \frac{\partial p}{\partial m} & \frac{\partial p}{\partial v} \\ \frac{\partial E}{\partial m} & \frac{\partial E}{\partial v} \end{bmatrix}$$

$$= \begin{bmatrix} \left( \frac{\partial p}{\partial m} \sigma_p^2 + \frac{\partial E}{\partial m} \text{cov}[p, E] \right) & \left( \frac{\partial p}{\partial m} \text{cov}[p, E] + \frac{\partial E}{\partial m} \sigma_E^2 \right) \\ \left( \frac{\partial p}{\partial v} \sigma_p^2 + \frac{\partial E}{\partial v} \text{cov}[p, E] \right) & \left( \frac{\partial p}{\partial v} \text{cov}[p, E] + \frac{\partial E}{\partial v} \sigma_E^2 \right) \end{bmatrix} \begin{bmatrix} \frac{\partial p}{\partial m} & \frac{\partial p}{\partial v} \\ \frac{\partial E}{\partial m} & \frac{\partial E}{\partial v} \end{bmatrix}$$

so the uncertainty on the mass is  $\sqrt{V_{mm}}$  or

$$\sigma_m^2 = \left[ \frac{\partial p}{\partial m} \left( \frac{\partial p}{\partial m} \sigma_p^2 + \frac{\partial E}{\partial m} \text{cov}[p, E] \right) + \frac{\partial E}{\partial m} \left( \frac{\partial p}{\partial m} \text{cov}[p, E] + \frac{\partial E}{\partial m} \sigma_E^2 \right) \right]^{1/2}$$

$$\sigma_m^2 = \left( \frac{\partial p}{\partial m} \sigma_p \right)^2 + 2 \frac{\partial p}{\partial m} \frac{\partial E}{\partial m} \text{cov}[p, E] + \left( \frac{\partial E}{\partial m} \sigma_E \right)^2, \text{ so errors add in quadrature.}$$

$$E = \frac{1}{2} v p$$

$$E = \frac{1}{2} m v \cdot v$$

$$mE = \frac{1}{2} m^2 v^2 \rightarrow 2mE = p^2$$

$$p = mv$$

$$\frac{p}{m} = v$$

$$v = \frac{p}{\left(\frac{p^2}{2E}\right)} = \frac{2E}{p}$$

$$E = \frac{1}{2} m v^2, p = mv$$

$$\frac{\partial E}{\partial m} = \frac{1}{2} v^2 = \frac{1}{2} \left( \frac{4E^2}{p^2} \right) = \frac{2E^2}{p^2}$$

$$\frac{\partial p}{\partial m} = v = \frac{2E}{p}$$

then

estimate of the  
mass in terms of

$$\bar{y} = (p, E)$$

$$\sigma_m^2 = \frac{4E^2}{p^2} \sigma_p^2 + 2 \left( \frac{2E}{p} \right) \left( \frac{2E^2}{p^2} \right) \text{cov}[p, E] + \frac{4E^4}{p^4} \sigma_E^2$$

$$= \frac{4E^2}{p^2} (p^2(a^2 + b^2)) + \frac{8E^3}{p^3} E_p(a^2 + 2b^2) + \frac{4E^4}{p^4} E^2(a^2 + 4b^2)$$

$$= 4E^2(a^2 + b^2) + \frac{8E^4}{p^2}(a^2 + 2b^2) + \frac{4E^6}{p^4}(a^2 + 4b^2)$$

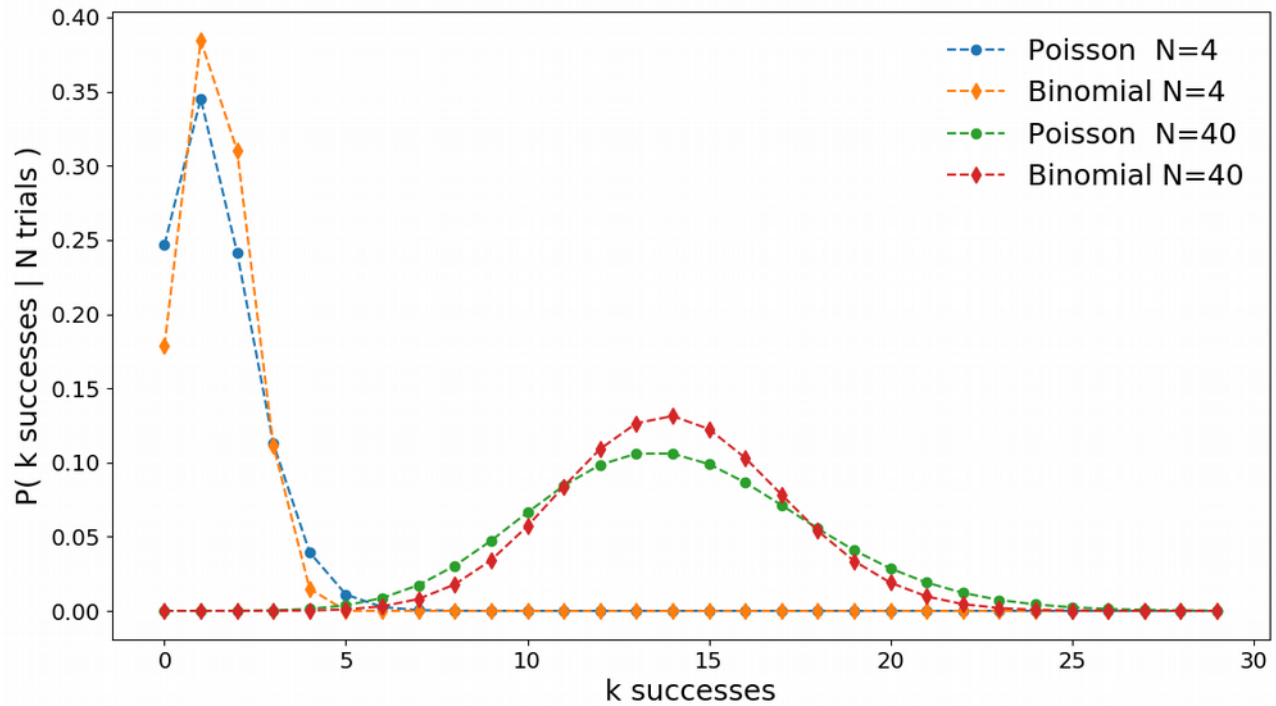
which is some kind of series expansion that doesn't seem to simplify properly... hmm... I give up for now.

- As an alternate "check", I can use Cowen's  $\sigma_y^2 \approx \frac{\partial y}{\partial x_i} \sigma_i^2$  for  $\sigma_p^2, \sigma_E^2$  in terms of  $\sigma_m^2, \sigma_v^2$ , then re-arrange and subtract off  $\sigma_v^2$  for something like:

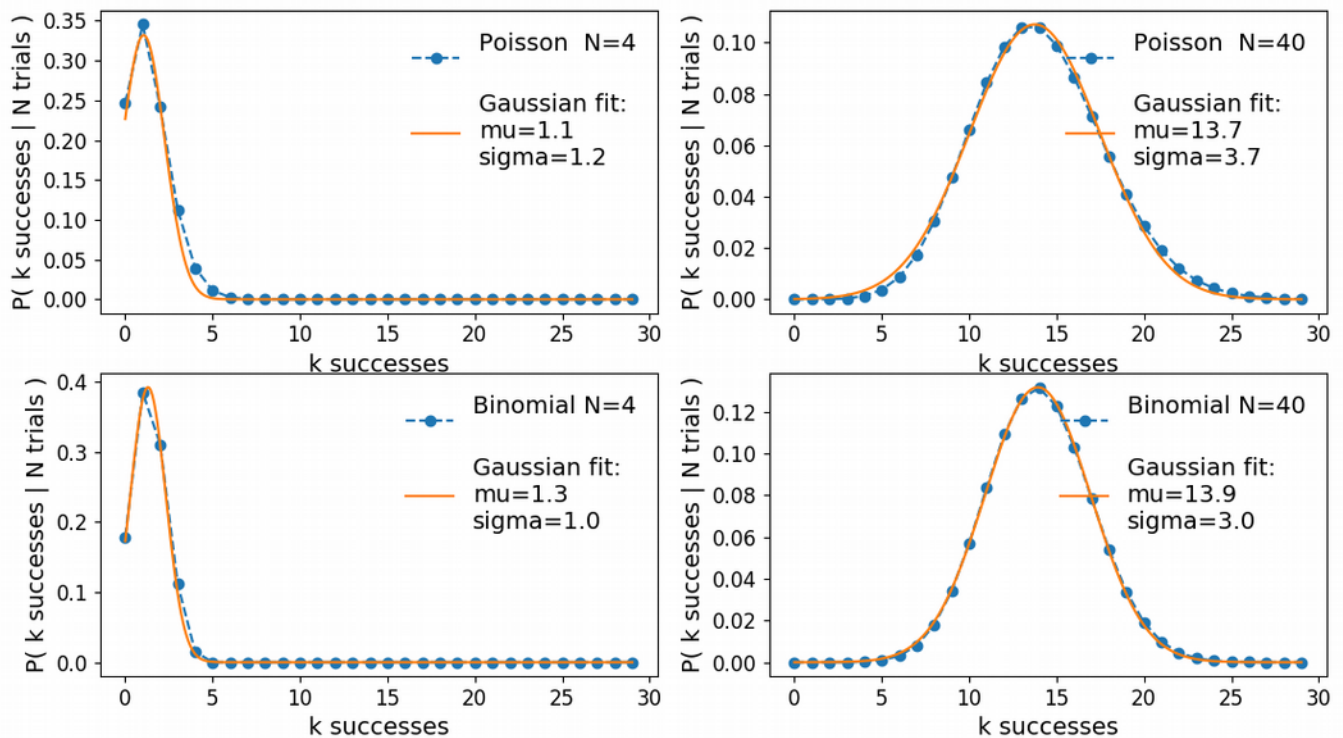
$$\sigma_m^2 \approx -2 \left( \frac{p}{2E} \right)^2 \left[ \sigma_E^2 - \left( \frac{2E}{p} \right) \sigma_p^2 \right]$$

## Problem 3:

a)

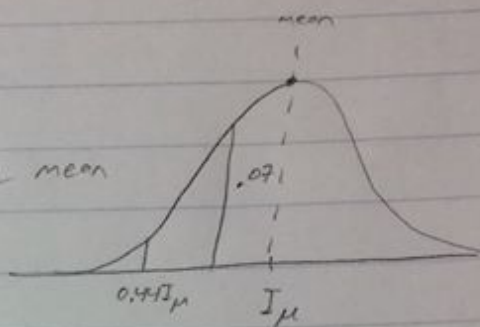


b)



4. a.  $P(0.44I_\mu | 0.07I_\mu) =$

$$\frac{0.56I_\mu}{0.07I_\mu} = 8\sigma \text{ away from the mean}$$



$$P = 1 - \int_{-8\sigma}^{8\sigma} N(I_\mu, \sigma) dx'$$

$$1 - 2 \int_0^{8\sigma} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x')^2}{2\sigma^2}} dx' \rightarrow 1 - \frac{2}{\sqrt{2\pi}} \int_0^{\frac{8}{\sqrt{2}}} e^{-\chi^2} d\chi$$

where  $\chi = \frac{x'}{\sqrt{2}\sigma}$ ,  $d\chi = \frac{1}{\sqrt{2}\sigma} dx'$

$$= 1 - \frac{2}{\sqrt{\pi}} \int_0^{8/\sqrt{2}} e^{-\chi^2} d\chi = \boxed{1 - \text{erf}(8/\sqrt{2})} = 1 - \text{erf}(5.6577)$$

$$P(\text{total}, 10^3 \text{ events}) \approx 10^5 \cdot 10^{-15} = \boxed{10^{-10} \text{ for 1 such "fluke"}}$$

b.  $\frac{0.56I_\mu}{0.14I_\mu} = 4\sigma$  away from the mean,  $P_{\text{single}} = \frac{1}{15787}$

$$P_{\text{total}} = P_{\text{single}} \times 10^5 \text{ events} \cdot 10^{-2} \text{ fraction} + (\text{other distribution} = 0)$$

$$= 10^3 \cdot \frac{1}{15787} = \boxed{0.063}, \text{ so much more likely, if}$$

1% of the  $10^5$  events have  $2\sigma$  the  $\sigma$ . Very non-linear  
dependence on sigma!