

Lecture 09 3/1/21

$$\vec{b} = (X^T X)^{-1} X^T \vec{y}, \text{ the OLS linear model, } \vec{y} = X \vec{b},$$

$$g(\vec{x}_*) = \hat{y}_* = \vec{x}_* \vec{b}$$

What if we have no features? i.e. the null model case. Is this an OLS solution?

$$X = [\vec{1}_n] = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$\vec{b} = b_0 = (X^T X)^{-1} X^T \vec{y} = \frac{\sum y_i}{n} = \bar{y} = g_0$$

$$\underbrace{\begin{bmatrix} 1 & \dots & 1 \end{bmatrix}}_{\substack{n \\ \frac{1}{n}}} \underbrace{\begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}}_{\sum y_i} \vec{y}$$



\mathbb{R}^2 (of all)

$\text{span}[\vec{v}]$ is a 1-dim subspace of \mathbb{R}^2

$$\text{rank}[X] = \dim[\text{colsp}[X]]$$

$$\text{colsp}[X] := \text{span}[\vec{1}, \vec{x}_1, \dots, \vec{x}_p] := \vec{w} \in \mathbb{R}^{p+1}$$

$$= \{w_0 \vec{1}_n + w_1 \vec{x}_1 + \dots + w_p \vec{x}_p : w_0, w_1, \dots, w_p \in \mathbb{R}\}$$

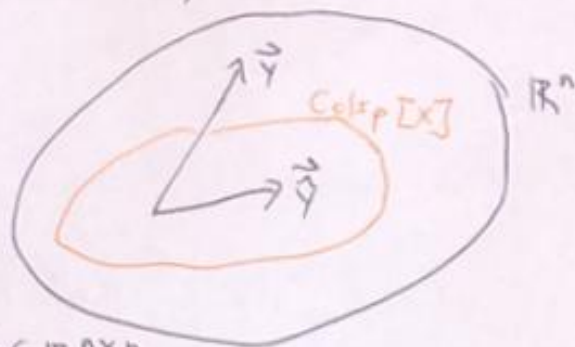
$p+1$ dimensional subspace of the entire n -dimensional "full space" (the number of dimensions of y which is n , the number of rows of X).

$\vec{y} \in \text{Colsp}[X]$? YES

$$\vec{y} = X\vec{b} \stackrel{\text{OLS solution}}{=} X(X^T X)^{-1} X^T \vec{y} = H\vec{y}$$

$$H \in \mathbb{R}^{n \times n}$$

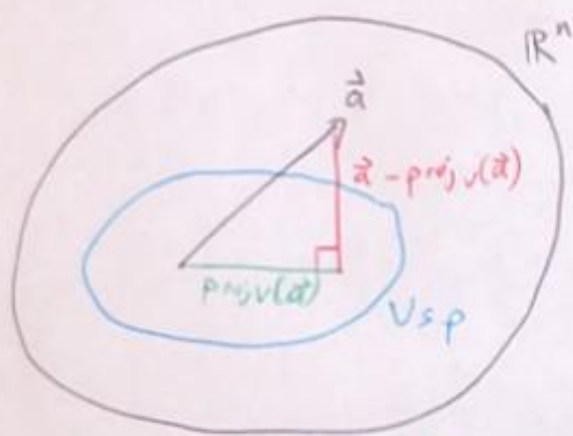
H for "hat" matrix, the linear operator turning y -vec into y -hat-vec.



$$X\vec{b} \in \text{colsp}[X]$$



$$H\vec{y} \in \text{colsp}[X] \Rightarrow \text{rank}[H] = p+1 \Rightarrow H \text{ is not invertible}$$



V is a K -dim subspace of the n -dim full space.

We want to "project" a -vec onto V such that the difference between a -vec and its projection is ~~perpendicular~~ perpendicular. This is called an "orthogonal projection". We want a formula for this projection as a function of the space V .

$$V_{sp} = \text{span}\{\vec{v}_1, \dots, \vec{v}_K\}, K < n$$

$$\text{proj}_V(\vec{a}) \in \text{span}\{\vec{v}_1, \dots, \vec{v}_K\} \Rightarrow \exists \vec{w}$$

$$\text{proj}_V(\vec{a}) = w_1 \vec{v}_1 + \dots + w_K \vec{v}_K = V\vec{w}$$

$$\text{Such that } V = [\vec{v}_1 | \dots | \vec{v}_K], \vec{w} \in \mathbb{R}^K$$

due to orthogonal constraint, $\vec{a} - \text{proj}_V(\vec{a}) \perp \vec{v}_j \forall j$

$$\Rightarrow (\vec{a} - V\vec{w})^T \vec{v}_j = 0 \quad \forall j \Leftrightarrow \vec{v}_j^T (\vec{a} - V\vec{w}) = 0 \quad \forall j$$

$$\Rightarrow \vec{v}_1^T (\vec{a} - V\vec{w}) = 0$$

$$\vec{v}_2^T (\vec{a} - V\vec{w}) = 0$$

$$\Rightarrow \begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vdots \\ \vec{v}_K^T \end{bmatrix} (\vec{a} - V\vec{w}) = \vec{0}_K \Rightarrow V^T (\vec{a} - V\vec{w}) = \vec{0}_K$$

$$\vec{v}_K^T (\vec{a} - V\vec{w}) = 0$$

$$\Rightarrow V^T \vec{a} - V^T V \vec{w} = \vec{0}_K \Rightarrow (V^T V)^{-1} V^T V \vec{w} = V^T \vec{a} \Rightarrow \vec{w} = (V^T V)^{-1} V^T \vec{a}$$

$$\text{proj}_V(\vec{a}) = V \vec{w} = \underbrace{V(V^T V)^{-1} V^T}_{H} \vec{a} = H \vec{a}$$

orthogonal projection onto $\text{colsp}[V]$

We call the $n \times n$ matrix H , the orthogonal projection matrix onto the subspace $V_{sp} = \text{colsp}[V]$.

$H = X(X^T X)^{-1} X^T$ is the orthogonal projection matrix onto $\text{colsp}[X]$.

Properties that define orthogonal projection matrices, H

(1) H is symmetric, $H^T = H$

$$H^T = (V(V^T V)^{-1} V^T)^T = V^T ((V^T V)^{-1})^T V^T = V^T (V^T V)^{-1} V^T = V^T \underbrace{(V^T V)^{-1}}_{(V^T V)^{-1}} V^T = H \checkmark$$

Let A be square, invertible, and symmetric.

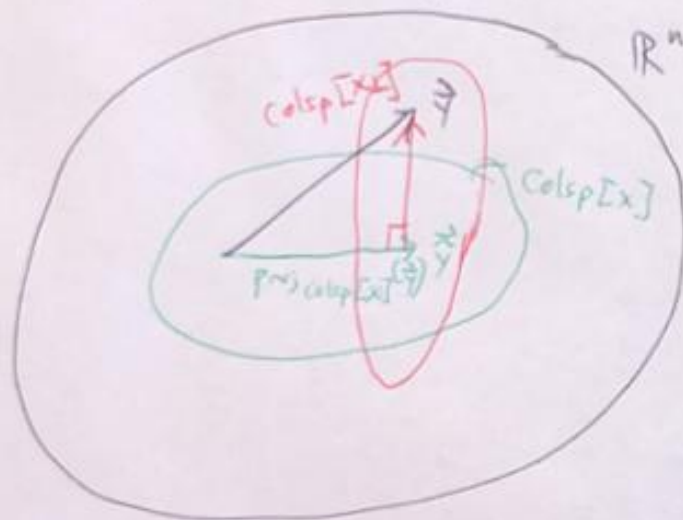
$$A^{-1} A = I \Rightarrow (A^{-1} A)^T = I^T = I \Rightarrow A^T (A^{-1})^T = I \Rightarrow (A^{-1})^T = (A^T)^{-1}$$

(2) H is ~~independent~~ is idempotent i.e. $HH = H$

$$HH = (V(V^T V)^{-1} V^T)(V(V^T V)^{-1} V^T) = V(V^T V)^{-1} (V^T V) (V^T V)^{-1} V^T = V(V^T V)^{-1} V^T = H \checkmark$$

$$\text{proj}_V(\text{proj}_V \vec{a}) = \text{proj}_V(H \vec{a}) = HH \vec{a} = H \vec{a} = \text{proj}_V(\vec{a})$$

$$\hat{y} = H \vec{q} = \text{proj}_{\text{colsp}[X]}(\vec{q})$$



$$\vec{q} = \vec{\hat{y}} + \vec{e}, \quad \vec{\hat{y}} \cdot \vec{e} = 0$$

$$\vec{e} = \vec{q} - \vec{\hat{y}} = \vec{q} - H \vec{q} = I \vec{q} - H \vec{q} = (I - H) \vec{q}$$

$$\begin{aligned} \vec{q} \cdot \vec{e} &= (H \vec{q})^T (I - H) \vec{q} = \vec{q}^T H^T (I \vec{q} - H \vec{q}) \\ &= \vec{q}^T H (I \vec{q} - H \vec{q}) = \vec{q}^T H I \vec{q} - \vec{q}^T H H \vec{q} \\ &= \vec{q}^T H \vec{q} - \vec{q}^T H \vec{q} = 0 \end{aligned}$$

Let's verify $I - H$ is a projection matrix by demonstrating that it is (1) symmetric and (2) idempotent.

$$(I - H)^T = I^T - H^T = I - H \checkmark$$

$$(I - H)(I - H) = II - IH - HI + HH = I - H - H + H = I - H$$

$$(I-H)\vec{e} = \vec{e}$$

$$H\vec{e} = \vec{0}_n$$

$$(I-H)\vec{y} = \vec{0}_n$$

$$H\vec{y} = \vec{y}$$

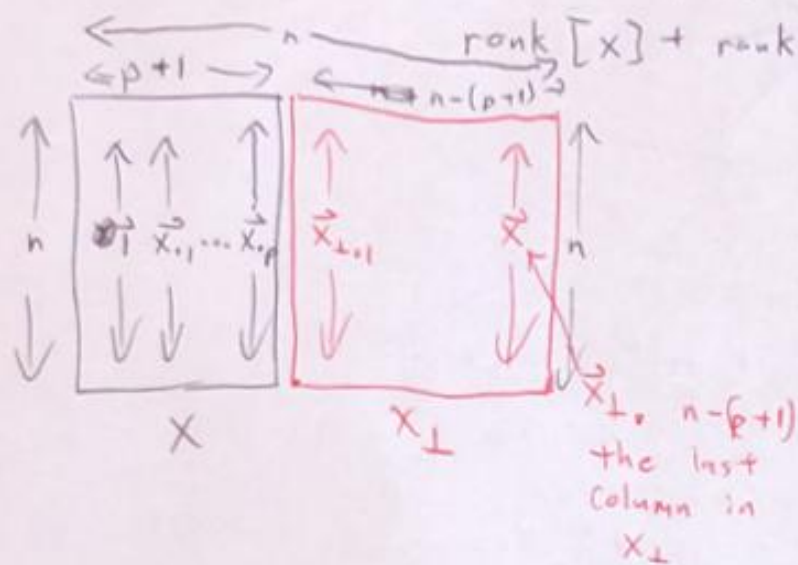
$$\text{colsp}[X] \oplus \text{colsp}[X_{\perp}] = \mathbb{R}^n$$

the "residual space" since it's the space the residuals e-vec live inside.

$$\text{rank}[X] = p+1, \quad \text{rank}[X_{\perp}] = n - (p+1)$$

$$\text{rank}[X] + \text{rank}[X_{\perp}] = n$$

degrees of freedom of the residuals.



The column vectors in X_{\perp} are vectors that span the "rest of the space". They're not unique. And you can construct them computationally.