A.(1) Y: observed & random

B: unobserved fixed, to be estimated

M: : unobserved & random

(2) An estimator in general is a rule for using sample information to measure unknown parameters in the model.

An old estimator is obtained by minimizing the Sum of squared loss.

- (3) An estimate is a realization of an estimator for the sample.
 - c4) A residual in general is the difference of the observed observed value and the fitted value. We get the DLS residual if an DLS estimator is used for estimation.

(5)
$$SO(\hat{\beta}_{i}) = \sqrt{Vor(\hat{\beta}_{i})} = \sqrt{\hat{\sigma}^{2}/h}$$

$$\hat{\sigma}^{2} = \frac{5\hat{\mu}_{i}^{2}}{h-1} = \frac{\Sigma(y_{i}-\hat{\beta}_{i})^{2}}{h-1}$$

$$\beta_1 = \overline{y} = \frac{\Sigma y_i}{n} = 0.1212$$

$$\hat{\sigma}^2 = \frac{\sum_{i} (y_i - \hat{R}_i)^2}{u - 1} = 0.0019$$