

# Python For Data Science Cheat Sheet

## SciPy - Linear Algebra

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### SciPy

The SciPy library is one of the core packages for scientific computing that provides mathematical algorithms and convenience functions built on the NumPy extension of Python.



### Interacting With NumPy

Also see NumPy

```
>>> import numpy as np
>>> a = np.array([1,2,3])
>>> b = np.array([(1+5j,2j,3j), (4j,5j,6j)])
>>> c = np.array([(1.5,2,3), (4,5,6)], [(3,2,1), (4,5,6)])
```

### Index Tricks

```
>>> np.mgrid[0:5,0:5]
>>> np.ogrid[0:2,0:2]
>>> np.r_[3,[0]*5,-1:1:10]]
>>> np.c_[b,c]
```

Create a dense meshgrid  
Create an open meshgrid  
Stack arrays vertically (row-wise)  
Create stacked column-wise arrays

### Shape Manipulation

```
>>> np.transpose(b)
>>> b.flatten()
>>> np.hstack((b,c))
>>> np.vstack((a,b))
>>> np.hsplit(c,2)
>>> np.vsplit(d,2)
```

Permute array dimensions  
Flatten the array  
Stack arrays horizontally (column-wise)  
Stack arrays vertically (row-wise)  
Split the array horizontally at the 2nd index  
Split the array vertically at the 2nd index

### Polynomials

```
>>> from numpy import polyld
>>> p = polyld([3,4,5])
```

Create a polynomial object

### Vectorizing Functions

```
>>> def myfunc(a):
    if a < 0:
        return a*2
    else:
        return a/2
>>> np.vectorize(myfunc)
```

Vectorize functions

### Type Handling

```
>>> np.real(b)
>>> np.imag(b)
>>> np.real_if_close(c,tol=1000)
>>> np.cast['F'](np.pi)
```

Return the real part of the array elements  
Return the imaginary part of the array elements  
Return a real array if complex parts close to 0  
Cast object to a data type

### Other Useful Functions

```
>>> np.angle(b,deg=True)
>>> g = np.linspace(0,np.pi,num=5)
>>> g[3:] += np.pi
>>> np.unwrap(g)
>>> np.logspace(0,10,3)
>>> np.select([c<4],[c*2])

>>> misc.factorial(a)
>>> misc.comb(10,3,exact=True)
>>> misc.central_diff_weights(3)
>>> misc.derivative(myfunc,1,0)
```

Return the angle of the complex argument  
Create an array of evenly spaced values (number of samples)  
Unwrap  
Create an array of evenly spaced values (log scale)  
Return values from a list of arrays depending on conditions  
Factorial  
Combine N things taken at k time  
Weights for Np-point central derivative  
Find the n-th derivative of a function at a point

## Linear Algebra

Also see NumPy

You'll use the linalg and sparse modules. Note that `scipy.linalg` contains and expands on `numpy.linalg`.

```
>>> from scipy import linalg, sparse
```

### Creating Matrices

```
>>> A = np.matrix(np.random.random((2,2)))
>>> B = np.asmatrix(b)
>>> C = np.mat(np.random.random((10,5)))
>>> D = np.mat([[3,4], [5,6]])
```

### Basic Matrix Routines

<b>Inverse</b> >>> A.I >>> linalg.inv(A)	Inverse Inverse
<b>Transposition</b> >>> A.T >>> A.H	Transpose matrix Conjugate transposition
<b>Trace</b> >>> np.trace(A)	Trace
<b>Norm</b> >>> linalg.norm(A) >>> linalg.norm(A,1) >>> linalg.norm(A,np.inf)	Frobenius norm L1 norm (max column sum) L inf norm (max row sum)
<b>Rank</b> >>> np.linalg.matrix_rank(C)	Matrix rank
<b>Determinant</b> >>> linalg.det(A)	Determinant
<b>Solving linear problems</b> >>> linalg.solve(A,b) >>> E = np.mat(a).T >>> linalg.lstsq(F,E)	Solver for dense matrices Solver for dense matrices Least-squares solution to linear matrix equation
<b>Generalized inverse</b> >>> linalg.pinv(C)  >>> linalg.pinv2(C)	Compute the pseudo-inverse of a matrix (least-squares solver) Compute the pseudo-inverse of a matrix (SVD)

### Creating Sparse Matrices

```
>>> F = np.eye(3, k=1)
>>> G = np.mat(np.identity(2))
>>> C[C > 0.5] = 0
>>> H = sparse.csr_matrix(C)
>>> I = sparse.csc_matrix(D)
>>> J = sparse.dok_matrix(A)
>>> E.todense()
>>> sparse.isspmatrix_csc(A)
```

Create a 2X2 identity matrix  
Create a 2x2 identity matrix  
Compressed Sparse Row matrix  
Compressed Sparse Column matrix  
Dictionary Of Keys matrix  
Sparse matrix to full matrix  
Identify sparse matrix

### Sparse Matrix Routines

<b>Inverse</b> >>> sparse.linalg.inv(I)	Inverse
<b>Norm</b> >>> sparse.linalg.norm(I)	Norm
<b>Solving linear problems</b> >>> sparse.linalg.spsolve(H,I)	Solver for sparse matrices

### Sparse Matrix Functions

>>> sparse.linalg.expm(I)	Sparse matrix exponential
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### Asking For Help

```
>>> help(scipy.linalg.diagsvd)
>>> np.info(np.matrix)
```

### Matrix Functions

<b>Addition</b> >>> np.add(A,D)	Addition
<b>Subtraction</b> >>> np.subtract(A,D)	Subtraction
<b>Division</b> >>> np.divide(A,D)	Division
<b>Multiplication</b> >>> A @ D  >>> np.multiply(D,A) >>> np.dot(A,D) >>> np.vdot(A,D) >>> np.inner(A,D) >>> np.outer(A,D) >>> np.tensordot(A,D) >>> np.kron(A,D)	Multiplication operator (Python 3) Multiplication Dot product Vector dot product Inner product Outer product Tensor dot product Kronecker product
<b>Exponential Functions</b> >>> linalg.expm(A) >>> linalg.expm2(A) >>> linalg.expm3(D)	Matrix exponential Matrix exponential (Taylor Series) Matrix exponential (eigenvalue decomposition)
<b>Logarithm Function</b> >>> linalg.logm(A)	Matrix logarithm
<b>Trigonometric Functions</b> >>> linalg.sinm(D) >>> linalg.cosm(D) >>> linalg.tanm(A)	Matrix sine Matrix cosine Matrix tangent
<b>Hyperbolic Trigonometric Functions</b> >>> linalg.sinhm(D) >>> linalg.coshm(D) >>> linalg.tanhm(A)	Hyperbolic matrix sine Hyperbolic matrix cosine Hyperbolic matrix tangent
<b>Matrix Sign Function</b> >>> np.signm(A)	Matrix sign function
<b>Matrix Square Root</b> >>> linalg.sqrtm(A)	Matrix square root
<b>Arbitrary Functions</b> >>> linalg.funm(A, lambda x: x*x)	Evaluate matrix function

### Decompositions

<b>Eigenvalues and Eigenvectors</b> >>> la, v = linalg.eig(A)  >>> l1, l2 = la >>> v[:,0] >>> v[:,1] >>> linalg.eigvals(A)	Solve ordinary or generalized eigenvalue problem for square matrix Unpack eigenvalues First eigenvector Second eigenvector Unpack eigenvalues
<b>Singular Value Decomposition</b> >>> U,s,Vh = linalg.svd(B) >>> M,N = B.shape >>> Sig = linalg.diagsvd(s,M,N)	Singular Value Decomposition (SVD) Construct sigma matrix in SVD
<b>LU Decomposition</b> >>> P,L,U = linalg.lu(C)	LU Decomposition

### Sparse Matrix Decompositions

>>> la, v = sparse.linalg.eigs(F,1)	Eigenvalues and eigenvectors
>>> sparse.linalg.svds(H, 2)	SVD

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