# **PCA and Kernel PCA basics**

Olivier J.J. MICHEL, Florent CHATELAINn

GIPSA-Lab, UMR 5216 CNRS

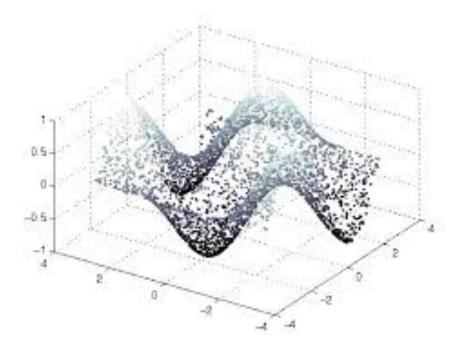




#### Continuous Latent variables, PCA

#### Motivations:

- Curse of dimensionality: it is not possible to get enough data to cover all the observation space. High dimensional spaces are mostly empty!
- Multivariate data live mostly in a (unknown) lower dimensional space : Intrinsic Dimensionality << representation dimensionality
- ullet Noise "visits" all possible dimensions : dimension reduction  $\simeq$  noise reduction

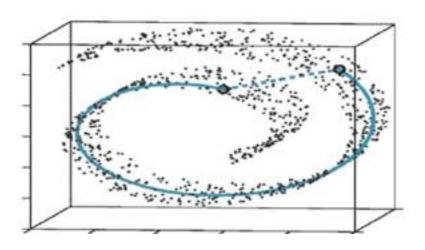


## Motivations (cont'd):

- features extraction (+ reduction of redundancy)
- Lossy compression (reduction of the size of the data)
- data visualization

## Extraction techniques (manifold learning)

- Physically based methods, geodesic distances
- Statistical methods, dictionary learning
- filtering (linear/non linear)



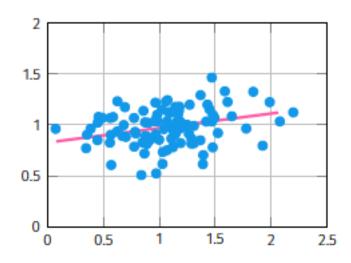
## Classical (non probabilistic) PCA

Simplest approach: assumes

- Euclidean subspace
- Gaussian dist. for latent variables
- linear Gaussian dependancies of observed variables and state of latent var.
- Find a linear transform to reduce the dimensionality of the data

$$z_i = \langle \mathbf{v}_i, \mathbf{x} \rangle$$

- Find ('new') low dimensional feature vector **z** that account most of the variability of the data:
  - $-z_1, z_2, z_3, \ldots$  are jointly uncorrelated
  - $\operatorname{var}(z_i)$  are as large as possible
  - $\operatorname{var}(z_1) \ge \operatorname{var}(z_2) \ge \operatorname{var}(z_3) \ge \dots$



## **Computing PCA**

• Find  $\mathbf{v}_1$  s.t.  $\operatorname{var}(z_1)$  is max, and constraint  $||\mathbf{v}_1||^2 = 1$ 

$$\operatorname{var}(z_1) = \operatorname{var}(\langle \mathbf{v}_1, \mathbf{x} \rangle) = \mathbf{v}_1^T \Gamma \mathbf{v}_1$$

• Form the Lagrangian

$$\mathcal{L}(\mathbf{v}_1, \lambda_1) = \mathbf{v}_1^T \Gamma \mathbf{v}_1 + \lambda_1 (1 - \mathbf{v}_1^T \mathbf{v}_1)$$

• Compute the gradient wrt  $\mathbf{v}_1$ 

$$\nabla_{\mathbf{v}_1} \mathcal{L} = 2\Gamma \mathbf{v}_1 - 2\lambda \mathbf{v}_1$$

•  $\mathbf{v}_1$  is an eigenvector of the cov. matrix of  $\mathbf{x}$ :

$$[\nabla_{\mathbf{v}_1} \mathcal{L} = 0] \Leftrightarrow [\Gamma \mathbf{v}_1 = \lambda \mathbf{v}_1]$$

• Maximize  $var(z_1)$ :

$$var(z_1) = \mathbf{v}_1^T \Gamma \mathbf{v}_1 = \lambda_1 \mathbf{v}_1^T \mathbf{v}_1 = \lambda_1$$

- Find  $\mathbf{v}_2$  s.t.  $\operatorname{var}(z_2)$  is max, but  $||\mathbf{v}_2||^2 = 1$  and  $\langle \mathbf{v}_1, \mathbf{v}_2 \rangle = 0$ 
  - Form the Lagrangian

$$\mathcal{L}(\mathbf{v}_2, \lambda_2, \beta_{12}) = \mathbf{v}_2^T \Gamma \mathbf{v}_2 + \lambda_2 (1 - \mathbf{v}_2^T \mathbf{v}_2) + \beta_{12} (0 - \mathbf{v}_1^T \mathbf{v}_2)$$

• Compute the gradient wrt  $\mathbf{v}_2$ 

• Solve 
$$\nabla_{\mathbf{v}_1} \mathcal{L} = 0$$

 $\nabla_{\mathbf{v}_2} \mathcal{L} = 2\Gamma \mathbf{v}_2 - 2\lambda_2 \mathbf{v}_2 - \beta_{12} \mathbf{v}_1$ 

• Use orthogonality constraint  $\langle \mathbf{v}_1, \mathbf{v}_2 \rangle = 0$ , multiplying the equation below by  $\mathbf{v}_1^T$ :

below by 
$$\mathbf{v}_1^T$$
: 
$$\Gamma \mathbf{v}_2 = \lambda_2 \mathbf{v}_2 + \frac{\beta_{12}}{2} \mathbf{v}_1$$

$$\mathbf{v}_1^T \Gamma \mathbf{v}_2 = \frac{\beta_{12}}{2}$$

$$\lambda_1 \mathbf{v}_1^T \mathbf{v}_2 = \frac{\beta_{12}}{2}$$

$$0 = \beta_{12}$$

• Finaly:  $\Gamma \mathbf{v}_2 = \lambda_2 \mathbf{v}_2 \Rightarrow \mathbf{v}_2$  is the 2<sup>nd</sup> largest eigenvalue of  $\Gamma$ 

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# **Computing PCA in practice**

1. Estimate (ML) the mean of  $\mathbf{x} \ (\in \mathbb{R}^d)$ 

$$\mu = \frac{1}{N} \sum_{i=1}^{N} \mathbf{x}_i$$

2. Estimate (ML) the covariance matrix:

$$\Gamma = \frac{1}{N-1} \sum_{i=1}^{N} (\mathbf{x}_i - \mu)(\mathbf{x}_i - \mu)^T$$

3. Compute the p largest eigenvalues and eigenvectors of  $\Gamma$ , and select p < d wrt "explained variance":

$$\frac{\sum_{k=1}^{p} \lambda_k}{\sum_{k=1}^{d} \lambda_k}$$

!Note! : STANDARDIZATION or SCALING MATTER

RK : Step 3 may be difficult / costly

## PCA for high dimensional data (N<d)

$$\mathbf{X} = \begin{bmatrix} (\mathbf{x}_1 - \mu)^T \\ (\mathbf{x}_2 - \mu)^T \\ \vdots \\ (\mathbf{x}_N - \mu)^T \end{bmatrix} \in \mathbb{R}^N \times \mathbb{R}^d \Rightarrow \Gamma = \frac{1}{N-1} \mathbf{X}^T \mathbf{X}$$

Eigendecomposition équation  $(\Gamma \in \mathbb{R}^d \times \mathbb{R}^d)$ 

$$\Gamma \mathbf{v}_i = \lambda_i \mathbf{v}_i$$

$$\frac{1}{N-1} \mathbf{X} \mathbf{X}^T \mathbf{X} \mathbf{v}_i = \lambda_i \mathbf{X} \mathbf{v}_i$$

Equivalent to  $S\mathbf{u}_i = \lambda_i \mathbf{u}_i$  where  $\mathbf{u}_i = \mathbf{X}\mathbf{v}_i$  and  $S = \frac{1}{N-1}\mathbf{X}\mathbf{X}^T \in \mathbb{R}^N \times \mathbb{R}^N$ : Eigenproblem in  $O(N^2)$  instead of  $O(d^2)$ 

In practice: Compute  $\mathbf{u}_i$  then  $\mathbf{v}_i$  s.t.  $||\mathbf{v}_i|| = 1$ 

$$\mathbf{v}_i = \frac{1}{\sqrt{(N-1)\lambda_i}} \mathbf{X}^T \mathbf{u}_i$$

#### **Kernel PCA: PCA with the KERNEL Trick!**

(as PCA depends only on inner products)

Let k be a positive semi-definitive kernel function

$$k : \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}$$

$$(\mathbf{x}, \mathbf{x}') \mapsto k(\mathbf{x}, \mathbf{x}') \equiv \langle \Phi(\mathbf{x}), \Phi(\mathbf{x}') \rangle$$

$$\Gamma = \frac{1}{N} \sum_{n=1}^{N} \mathbf{x}_n \mathbf{x}_n^T \leftarrow C = \frac{1}{N} \sum_{n=1}^{N} \Phi(\mathbf{x}_n), \Phi(\mathbf{x}_n)^T$$

New eigenproblem:

$$C\mathbf{v}_i = \lambda_i \mathbf{v}_i \Leftrightarrow \frac{1}{N} \sum_n \Phi(\mathbf{x}_n) [\Phi(\mathbf{x}_n)^T \mathbf{v}_i] = \lambda_i \mathbf{v}_i$$

but  $\mathbf{v}_i = \sum_m a_{im} \Phi(\mathbf{x}_n)$  thus the eigenequation becomes

$$\left(\frac{1}{N}\sum_{n=1}^{N}\Phi(\mathbf{x}_n)\Phi(\mathbf{x}_n)^T\right)\left(\sum_{m}a_{im}\Phi(\mathbf{x}_n)\right) = \lambda_i\sum_{m}a_{im}\Phi(\mathbf{x}_n)$$

Multiplying both rhs and lhs terms in the preceding equality. by  $\Phi(\mathbf{x}_l)$ :

$$\frac{1}{N} \sum_{n} k(\mathbf{x}_{l}, \mathbf{x}_{n})^{T} \sum_{m} a_{im} k(\mathbf{x}_{n}, \mathbf{x}_{m}) = \lambda_{i} \sum_{m} a_{im} k(\mathbf{x}_{l}, \mathbf{x}_{m})$$

or in matrix form:

$$K^{2}\mathbf{a}_{i} = \lambda_{i}NK\mathbf{a}_{i}$$

$$\Rightarrow K\mathbf{a}_{i} = \lambda_{i}N\mathbf{a}_{i}$$

In practice:

normalization

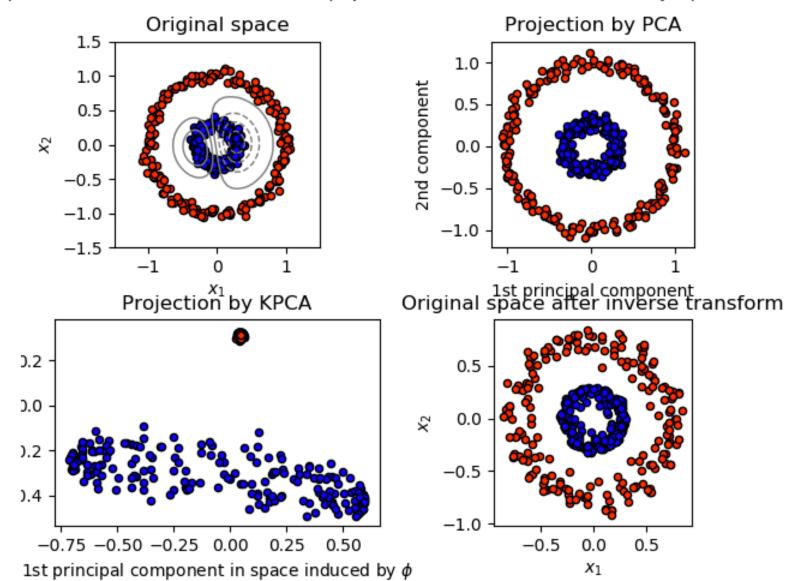
$$1 = \mathbf{v}_i^T \mathbf{v}_i = \mathbf{a}_i^T K \mathbf{a}_i = \lambda_i N \mathbf{a}_i^T \mathbf{a}_i$$

• Projection on eigenvector

$$\mathbf{y}_i(\mathbf{x}_i) = \phi(\mathbf{x}_i) = \sum_{n=1}^{N} a_{in} k(\mathbf{x}, \mathbf{a}\mathbf{x}_n)$$

#### Example of Kernel PCA with RBF (from Scikit-learn documentation)

This example shows that Kernel PCA is able to find a projection of the data that makes data linearly separable.



See PCA\_IRIS\_example.ipynb

See PCA\_sonardata\_example.ipynb