

Calibration results

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Camera-system parameters:

cam0 (/color):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [0.10927442 -0.23448282 0.00135765 0.00109836] +- [0.00536684 0.00930779 0.00058286 0.00110435]

projection: [914.91912767 915.1587166 643.1500963 359.53871968] +- [4.0447777 4.0507955 2.64701211
1.74704591]

reprojection error: [0.000001, 0.000001] +- [0.236413, 0.198075]

Target configuration

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Type: aprilgrid

Tags:

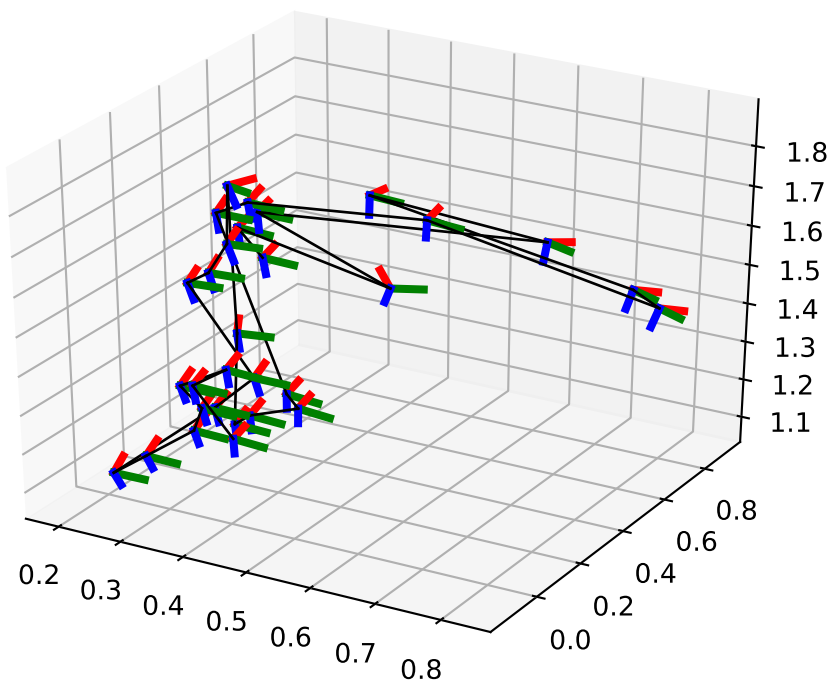
Rows: 6

Cols: 6

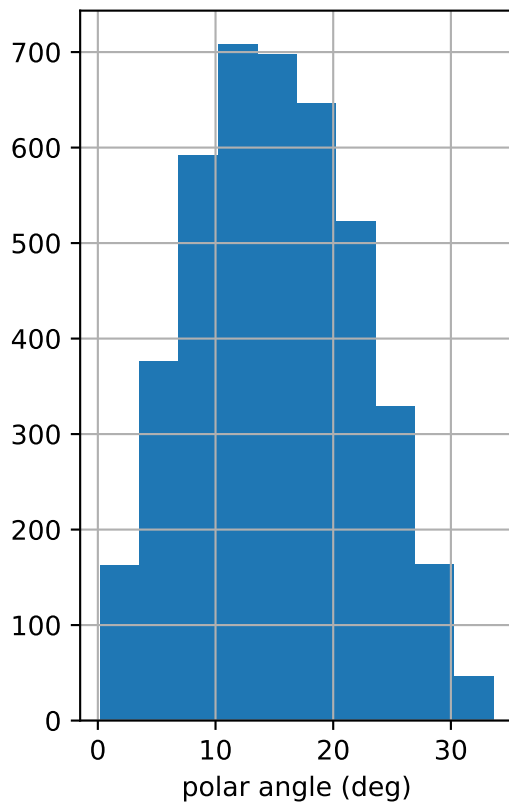
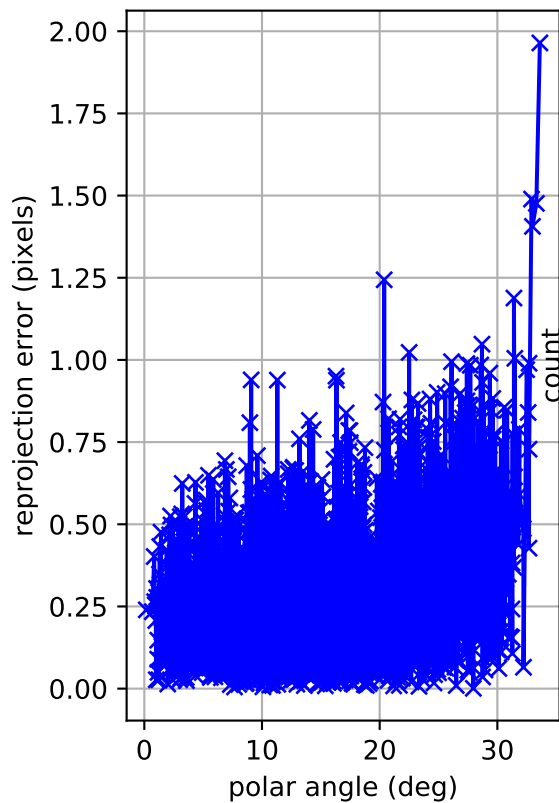
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

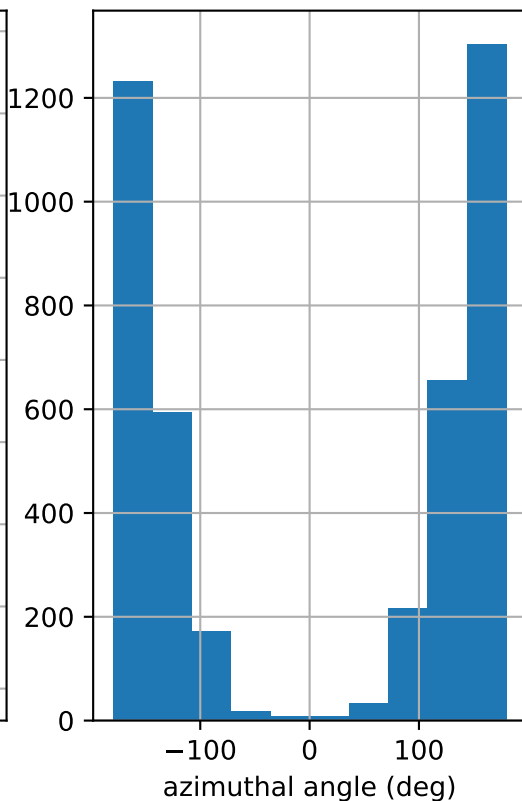
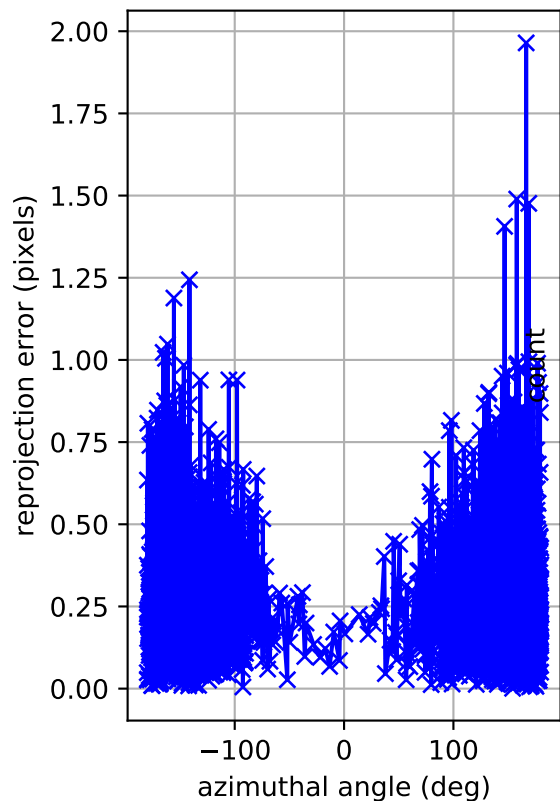
cam0: estimated poses



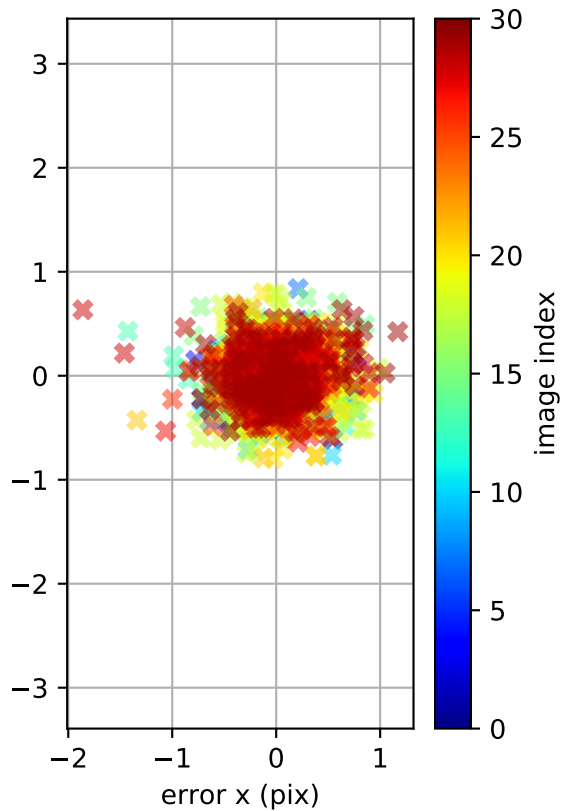
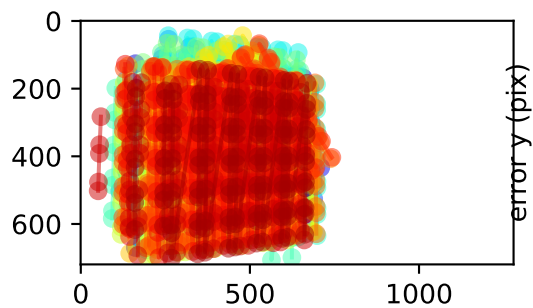
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

