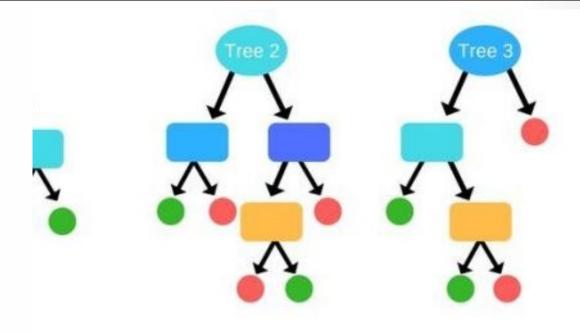
# TREE-BASED ENSEMBLE LEARNING: RANDOM FOREST...AND ITS VARIANTS

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uction To Random Forest Algorithm

dataspirant.com

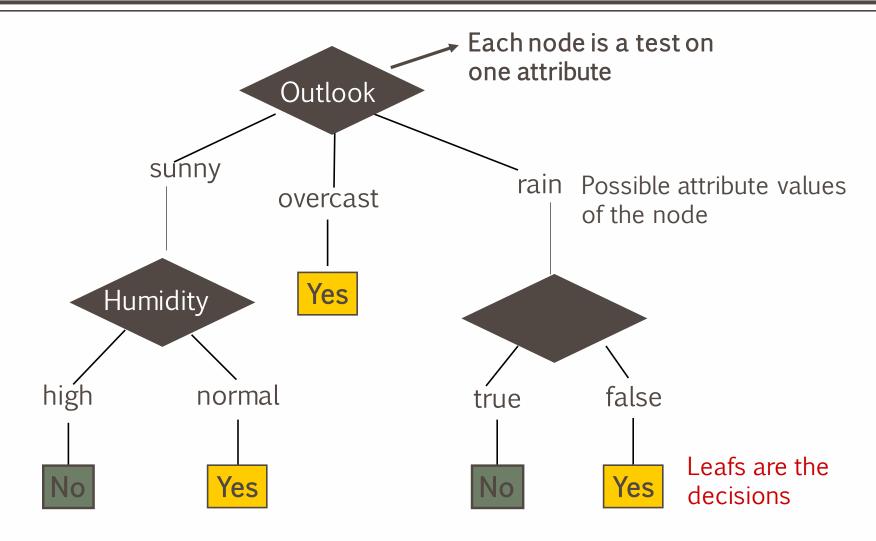


#### **Decision trees**

- Non-linear classifier
- Easy to use
- Easy to interpret
- Succeptible to overfitting but can be avoided.

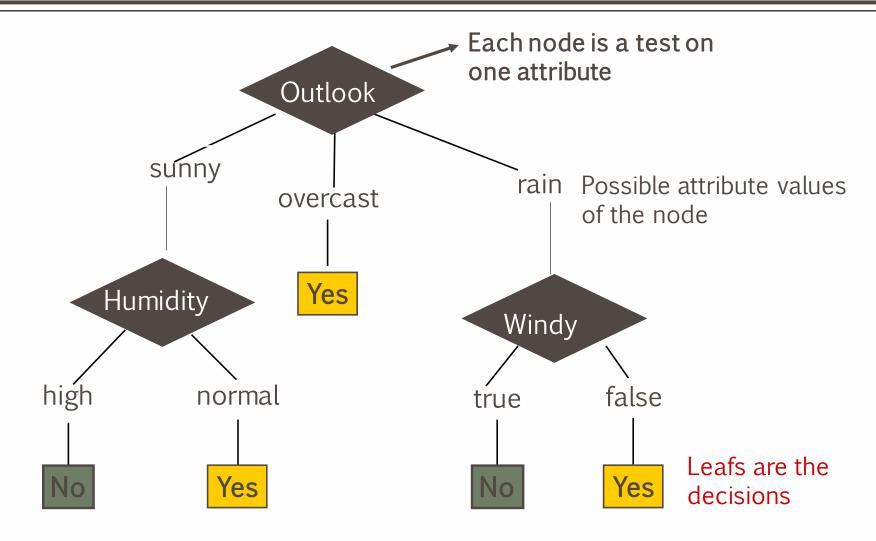


# Anatomy of a decision tree



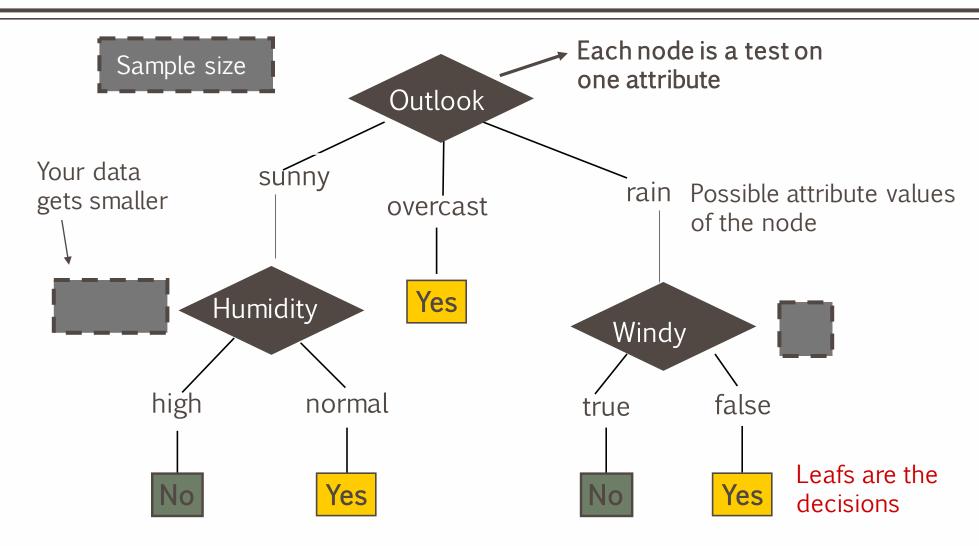


## Anatomy of a decision tree



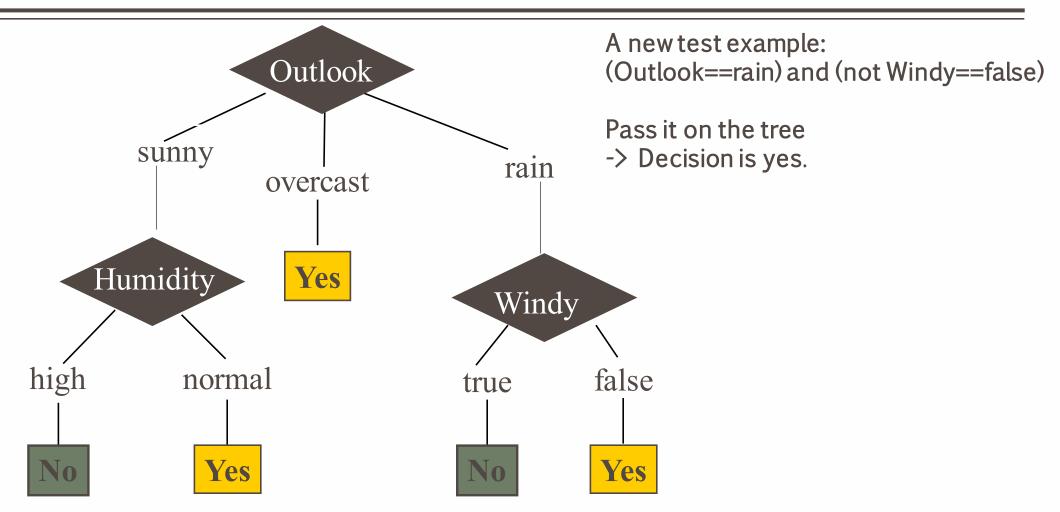


## Anatomy of a decision tree



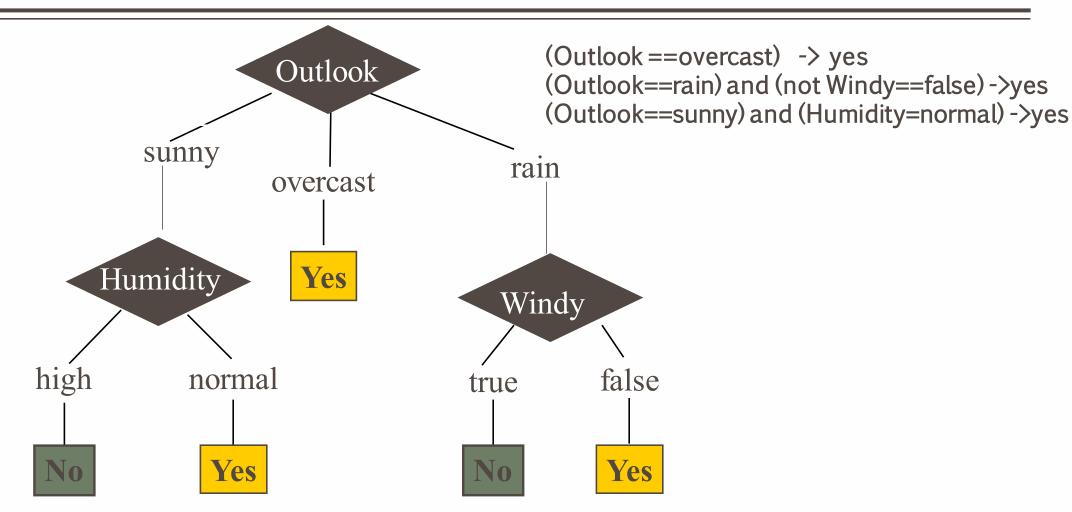


# To 'play tennis' or not.





## To 'play tennis' or not.





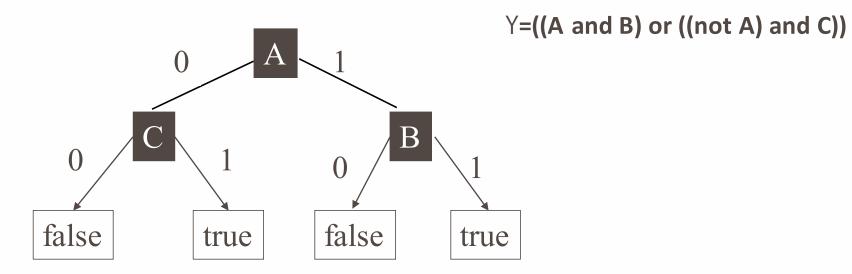
#### Decision trees

 Decision trees represent a disjunction of conjunctions of constraints on the attribute values of instances.

```
(Outlook ==overcast)
OR
((Outlook==rain) and (not Windy==false))
OR
((Outlook==sunny) and (Humidity=normal))
=> yes play tennis
```

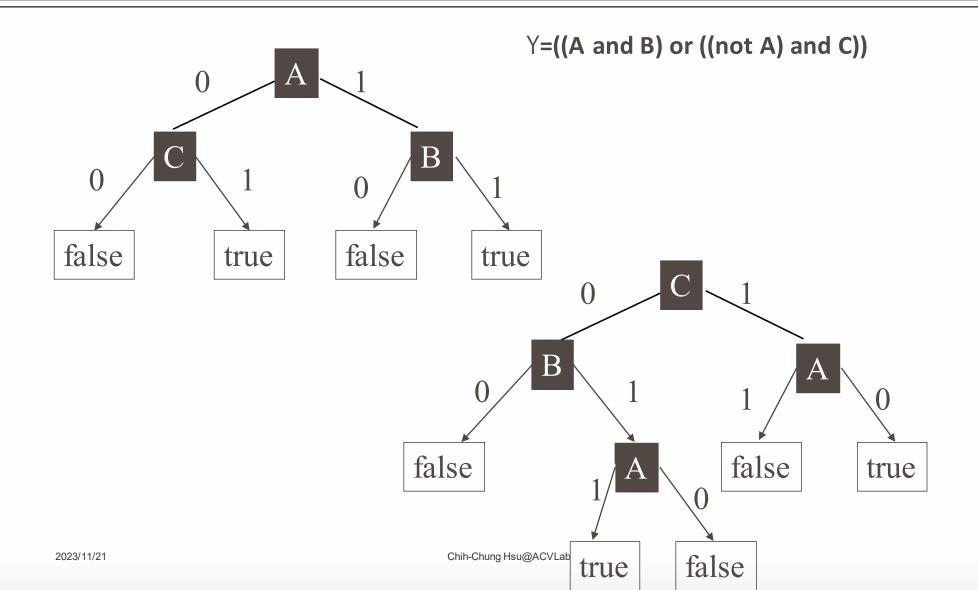


# Representation



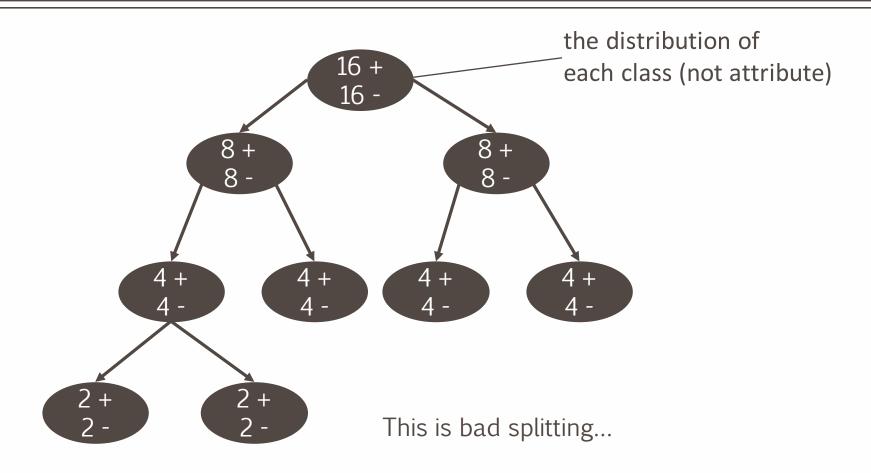


#### Same concept different representation





## Which attribute to select for splitting?

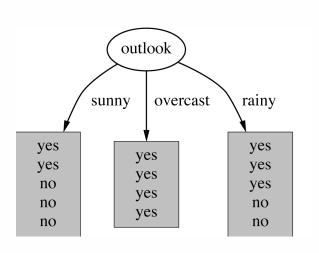


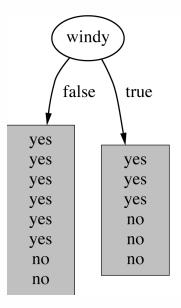


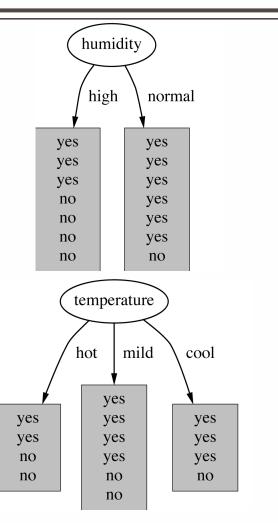
#### How do we choose the test?

Which attribute should be used as the test?

Intuitively, you would prefer the one that *separates* the training examples as much as possible.









#### **Information Gain**

■ Information gain is one criteria to decide on the attribute.



#### **Example**

#### Attributes Labels

X1	X2	Υ	Count
Т	Т	+	2
Т	F	+	2
F	Т	1	5
F	F	+	1

Which one do we choose? X1 or X2?

$$IG(X1,Y) = H(Y) - H(Y|X1)$$

$$H(Y) = -(5/10) \log(5/10) -5/10 \log(5/10) = 1$$
  
 $H(Y|X1) = P(X1=T)H(Y|X1=T) + P(X1=F) H(Y|X1=F)$   
 $= 4/10 (1 \log 1 + 0 \log 0) +6/10 (5/6 \log 5/6 +1/6 \log 1/6)$   
 $= 0.39$ 

Information gain (X1,Y)= 1-0.39=0.61



#### Which one do we choose?

X1	X2	Υ	Count
Т	Т	+	2
Т	F	+	2
F	Т	-	5
F	F	+	1

Information gain (X1,Y)=0.61Information gain (X2,Y)=0.12

Pick the variable which provides the most information gain about Y

Pick X1



#### **Recurse on branches**

X1	X2	Υ	Count
Т	Т	+	2
Т	F	+	2
F	Т	1	5
F	F	+	1

One branch

The other branch



#### **Notice**

• The number of possible values influences the information gain.

• The more possible values, the higher the gain (the more likely it is to form small, but pure partitions)



# Purity (diversity) measures

- Purity (Diversity) Measures:
- – Gini (population diversity)
- – Information Gain
- – Chi-square Test



#### **Overfitting**

- You can perfectly fit to any training data
  - Zero bias, high variance
- Two approaches:
  - 1. Stop growing the tree when further splitting the data does not yield an improvement
  - 2. Grow a full tree, then prune the tree, by eliminating nodes.



## Bagging

- Bagging or bootstrap aggregation
  - a technique for reducing the variance of an estimated prediction function.
- For classification, a committee of trees each
  - cast a vote for the predicted class.

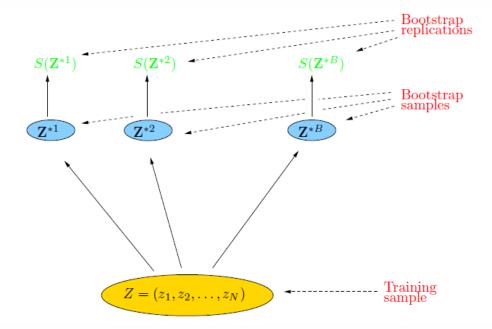


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#### **Bootstrap**

The basic idea:

randomly draw datasets with replacement from the training data, each sample the same size as the original training set

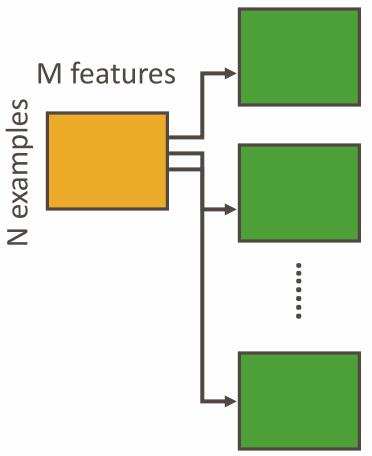




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# Bagging

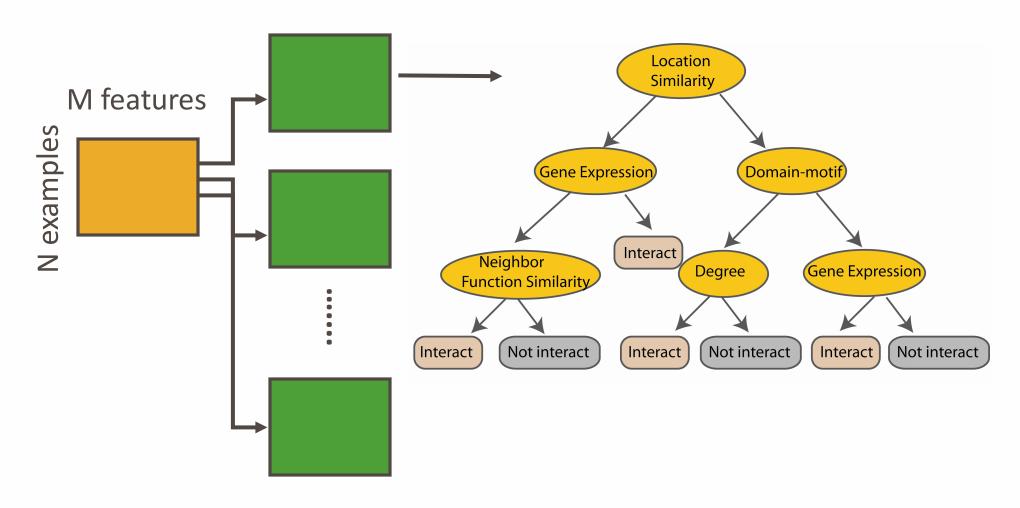
# Create bootstrap samples from the training data





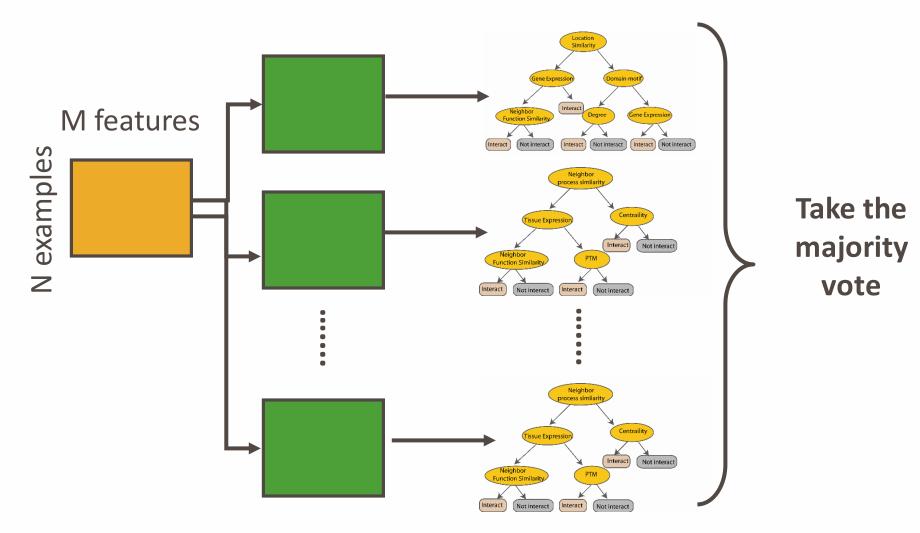
#### Random Forest Classifier

#### Construct a decision tree





#### Random Forest Classifier





#### **Bagging**

$$Z = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}$$

 $Z^{*b}$  where = 1,.., B..

$$\hat{f}_{\text{bag}}(x) = \frac{1}{B} \sum_{b=1}^{B} \hat{f}^{*b}(x).$$

The prediction at input x when bootstrap sample b is used for training

http://www-stat.stanford.edu/~hastie/Papers/ESLII.pdf (Chapter 8.7)



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#### Bagging: an simulated example

- Generated a sample of size N = 30, with two classes and p = 5 features, each having a standard Gaussian distribution with pairwise Correlation 0.95.
- The response Y was generated according to
  - $Pr(Y = 1|x1 \le 0.5) = 0.2$ ,
  - Pr(Y = 0|x1 > 0.5) = 0.8.

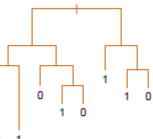


# Bagging

## Notice the bootstrap trees are different than the original tree

#### Original Tree

x.1 < 0.395

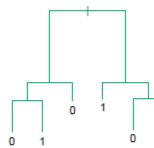


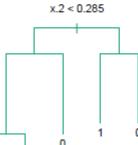
b = 1



x.2 < 0.205

b = 2

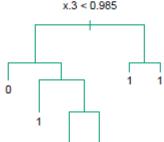




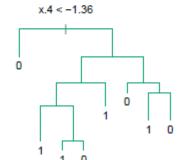
b = 4

0

0



b = 5





#### **Bagging**

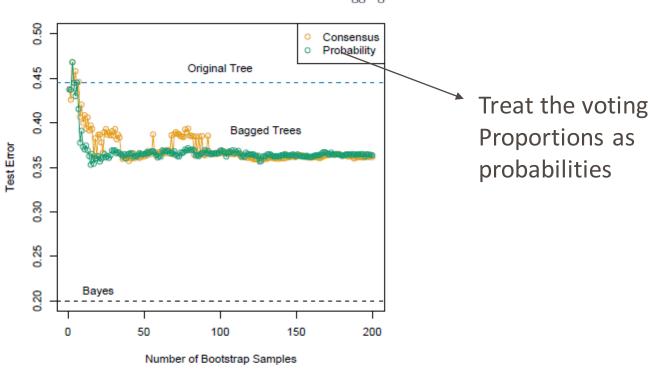


FIGURE 8.10. Error curves for the bagging example of Figure 8.9. Shown is the test error of the original tree and bagged trees as a function of the number of bootstrap samples. The orange points correspond to the consensus vote, while the

bagging helps under squared-error loss, in short because averaging reduces

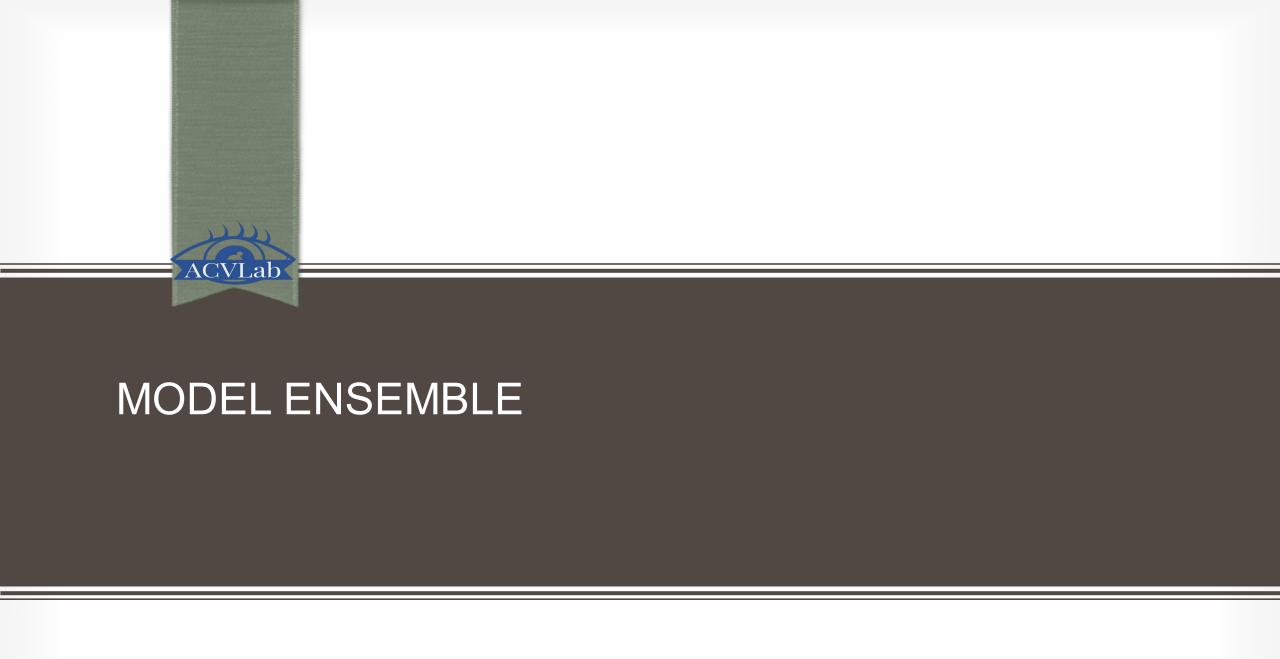
Hastie

green points average the probabilities.



#### Random forest classifier

- Random forest classifier, an extension to
- bagging which uses *de-correlated* trees.





# **TRICKS**

source: https://homes.cs.washington.edu/~pedrod/papers/cacm12.pdf reading moderator: Ondrej Kaššák



#### Kaggle Competition

■ Objective: Predict whether customers will respond to a direct mail loan offer

Customers: 145,231

■ Independent variables: 1932

"Anonymous" features

Dependent variable:

■ target = 0: DID NOT RESPOND

■ target = 1: RESPONDED

■ Training sets: 96,820 obs.

■ Testing sets: 48,411 obs.





#### Dataset facts

■ Target=0 obs.: 111,458

■ Target=1 obs.: 33,773

■ Numerical variables: 1,876

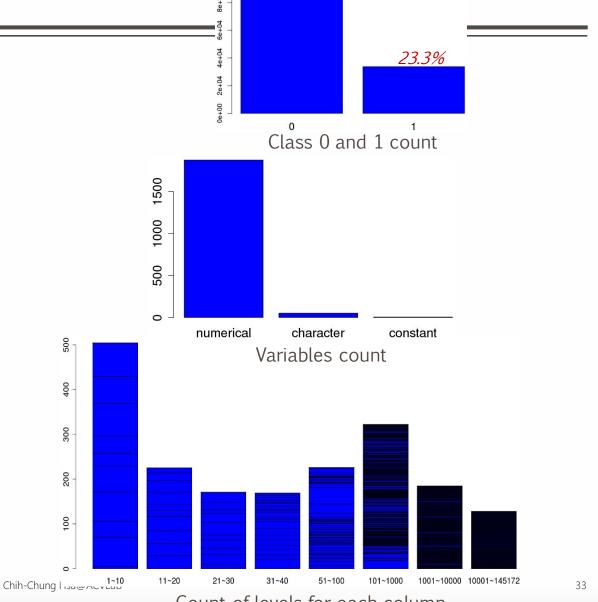
Character variables: 51

Constant variables: 5

Variable level counts:

• 67.0% columns have

levels <= 100



76.7%

Count of levels for each column



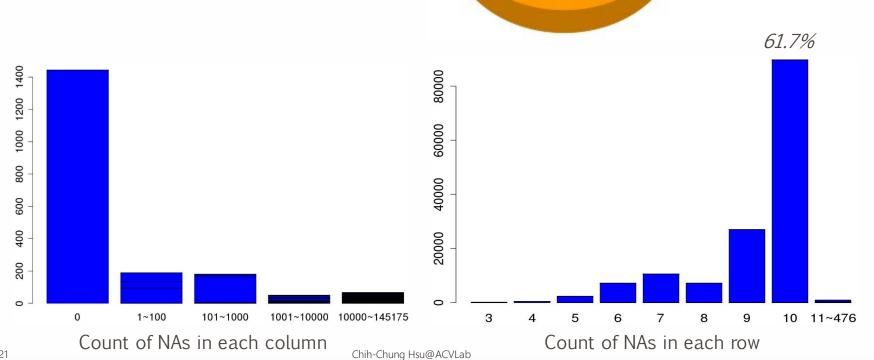
"", "NA" [], -1

24.9%

99,999,9998,999... Normal Value

# Missing values

- "", "NA": 0.6%
- **"**[]", -1: 2.0%
- **■** -99999, 96, ..., 999, ..., 99999999: 24.9%
- 25.3% columns have missing values



72.5%

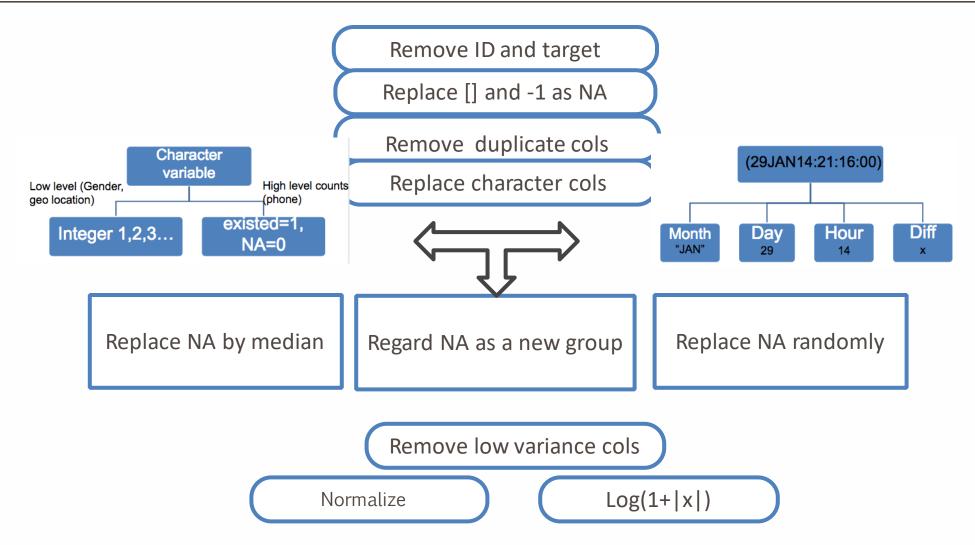


## Challenges for classification

- Huge Dataset (145,231 X 1932)
- "Anonymous" features
- Uneven distribution of response variable
- 27.6% of missing values
- Deal with both numerical and categorical variables
- Undetermined portion of Categorical variables
- Data pre-processing complexity



#### Data preprocessing



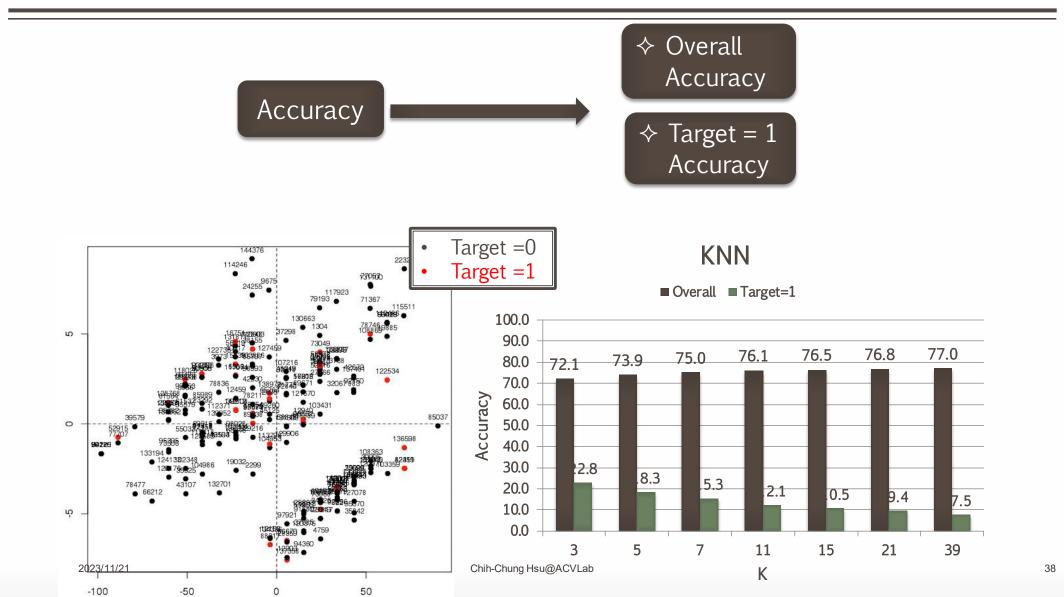


### Methodology

- K Nearest Neighbor (KNN)
- Support Vector Machine (SVM)
- Logistic Regression
- Random Forest
- XGBoost (eXtreme Gradient Boosting)
- Stacking



### K Nearest Neighbor (KNN)





### Support Vector Machine (SVM)

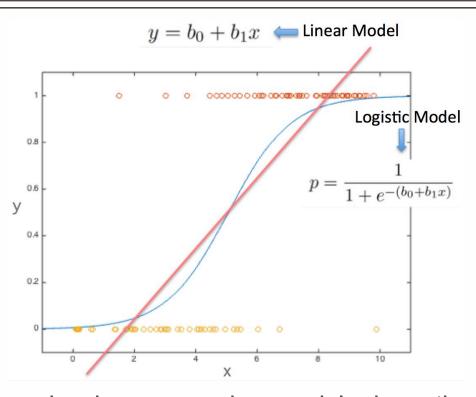
- Expensive; takes long time for each run
- Good results for numerical data

Confusion matrix		Prediction	
		0	1
Truth	0	19609	483
	1	5247	803

	Accuracy
Overall	78.1%
Target = 1	13.3%
Target = 0	97.6%



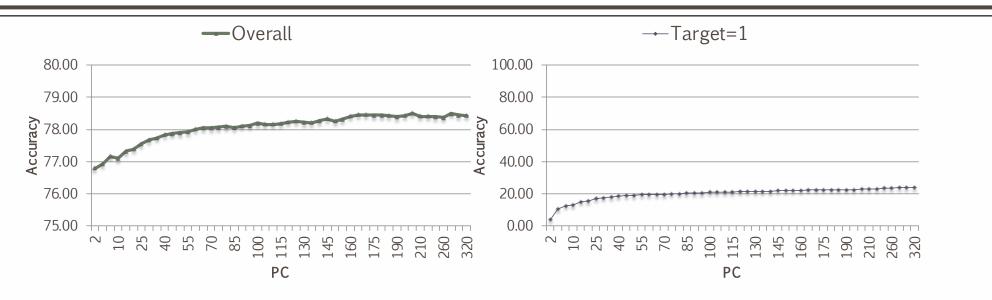
### Logistic Regression



- Logistic regression is a regression model where the dependent variable is categorical.
- Measures the relationship between dependent variable and independent variables by estimating probabilities



### Logistic Regression



Confusion matrix		Prediction	
		0	1
Truth	0	53921	3159
	1	12450	4853

	Accuracy
Overall	79.2 %
Target = 1	28.1 %
Target = 0	94.5 %

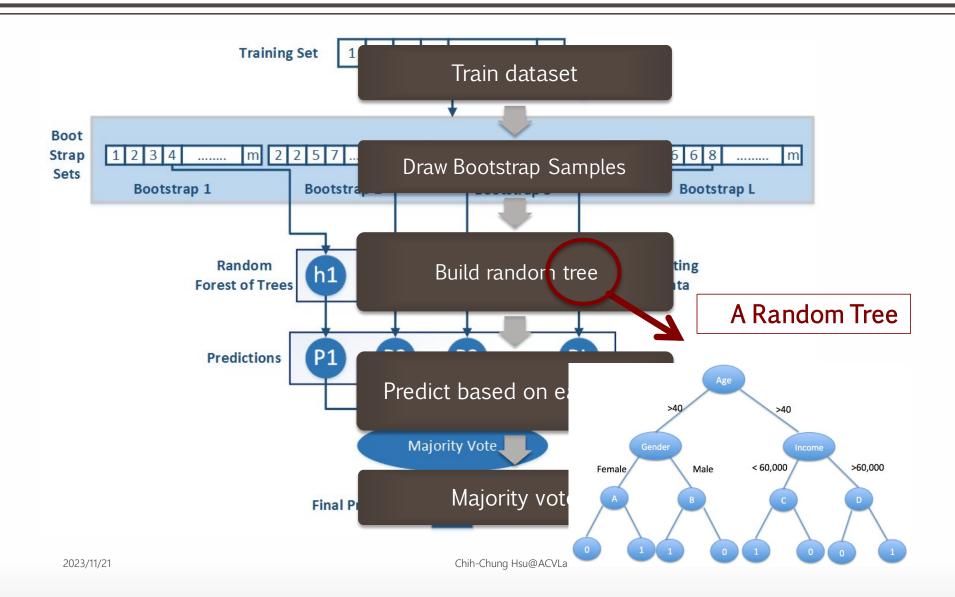


### Random Forest

- Machine learning ensemble algorithm
- Combining multiple predictors
- Based on tree model
- For both regression and classification
- Automatic variable selection
- Handles missing values
- Robust, improving model stability and accuracy

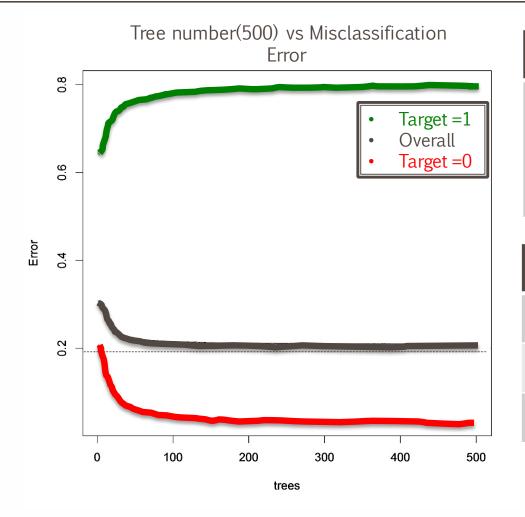


### Random Forest





### Random Forest



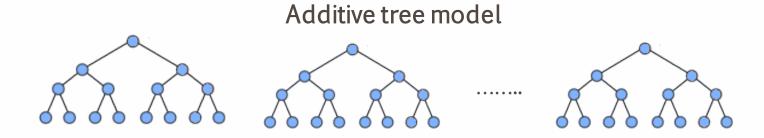
Confusion matrix		Prediction	
		0	1
Truth	0	36157	1181
	1	8850	2223

	Accuracy
Overall	79.3%
Target = 1	20.1%
Target = 0	96.8%

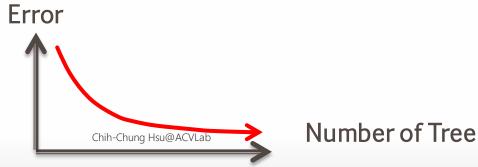


### **XGBoost**

- Additive tree model: add new trees that complement the already-built ones
- Response is the optimal linear combination of all decision trees
- Popular in Kaggle competitions for efficiency and accuracy



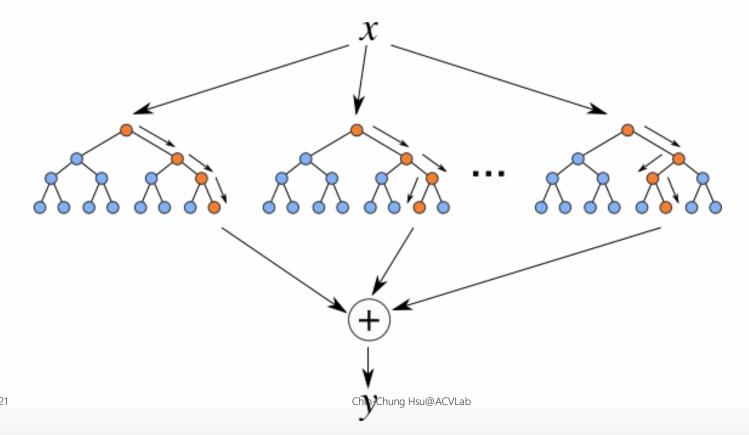
### **Greedy Algorithm**





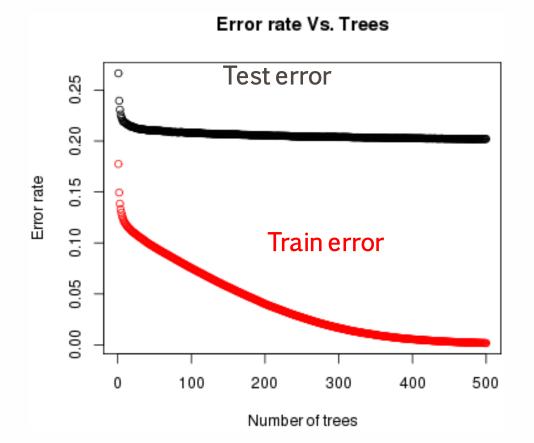
### **XGBoost**

- Additive tree model: add new trees that complement the already-built ones
- Response is the optimal linear combination of all decision trees
- Popular in Kaggle competitions for efficiency and accuracy





### **XGBoost**



Confusion matrix		Prediction	
		0	1
Truth	0	35744	1467
	1	8201	2999

	Accuracy
Overall	80.0%
Target = 1	26.8%
Target = 0	96.1%



### Methods Comparison

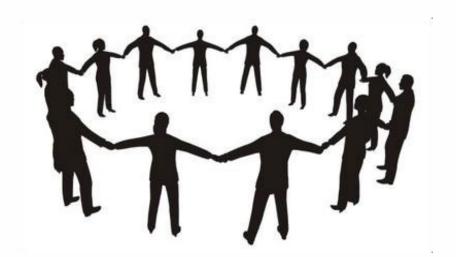
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## Winner or Combination?

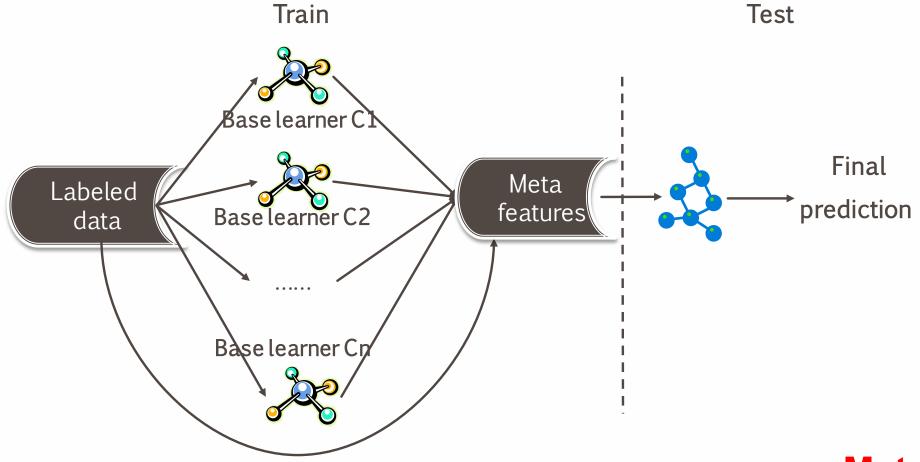






### Stacking

Main Idea: Learn and combine multiple classifiers





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### Generating Base and Meta Learners

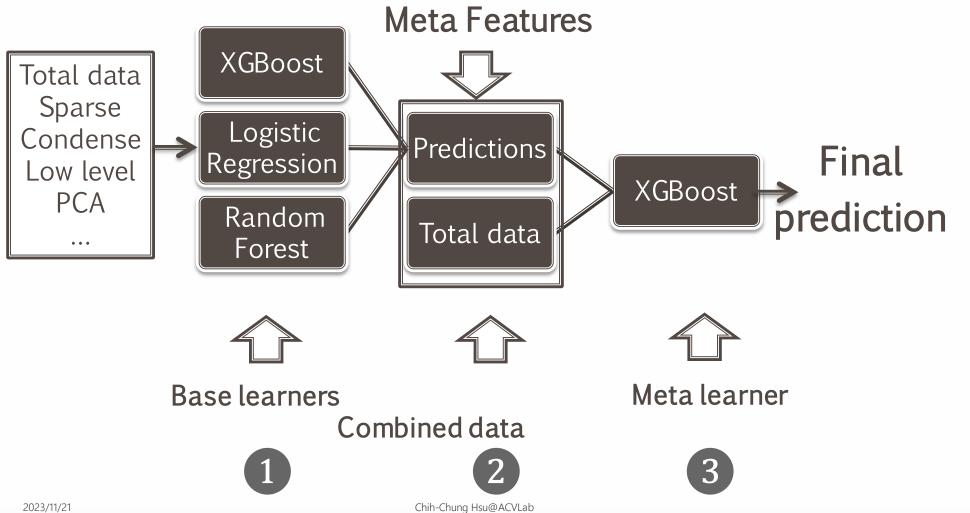
- Base model—efficiency, accuracy and diversity
  - Sampling training examples
  - Sampling features
  - Using different learning models

- Meta learner
  - Majority voting
  - Weighted averaging
  - Kmeans
  - Higher level classifier Supervised(XGBoost)



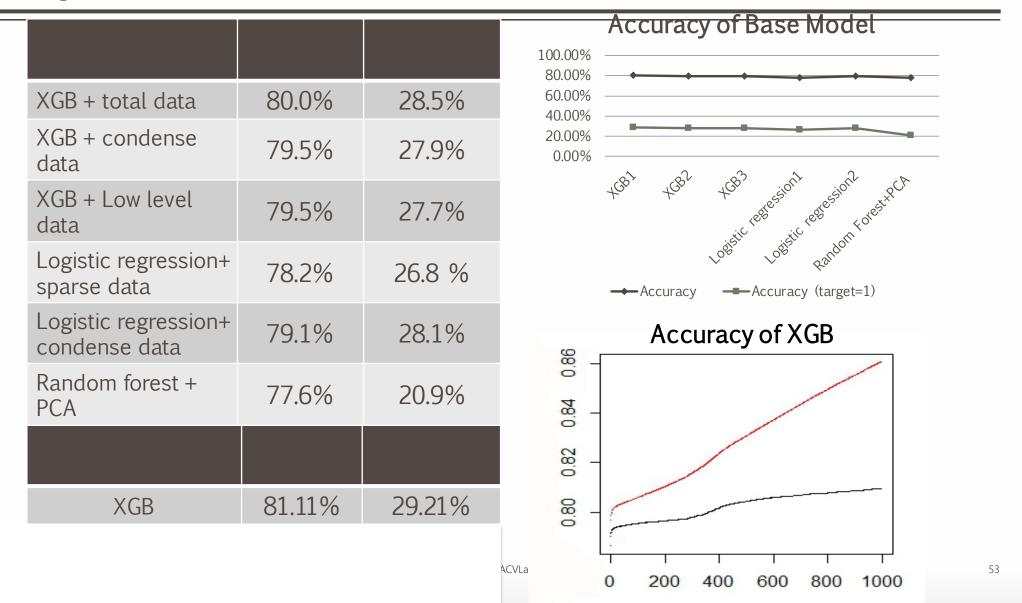


### Stacking model





### Stacking Results

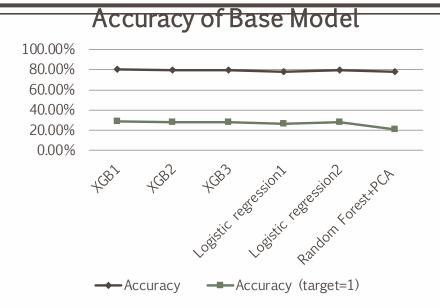


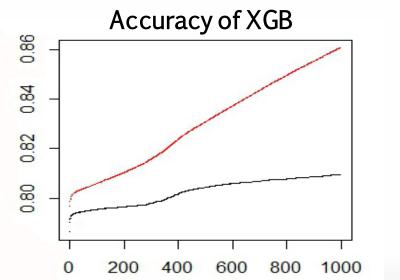


### Stacking Results

Base Model	Accuracy	Accuracy (target=1)
XGB + total data	80.0%	28.5%
XGB + condense data	79.5%	27.9%
XGB + Low level data	79.5%	27.7%
Logistic regression+ sparse data	78.2%	26.8 %
Logistic regression+ condense data	79.1%	28.1%
Random forest + PCA	77.6%	20.9%

Meta Model	Accuracy	Accuracy (target=1)
XGB	81.11%	29.21%
Averaging	79.44%	27.31%
Kmeans	77.45%	23.91%





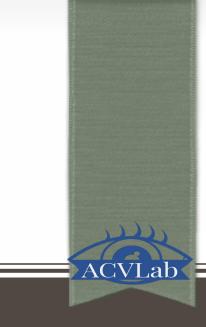
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### Summary and Conclusion

- Data mining project in the real world
  - Huge and noisy data
- Data preprocessing
  - Feature encoding
  - Different missing value process:
  - New level, Median / Mean, or Random assignment
- Classification techniques
  - Classifiers based on distance are not suitable
  - Classifiers handling mixed type of variables are preferred
  - Categorical variables are dominant
  - Stacking makes further promotion
- Biggest improvement came from model selection, parameter tuning, stacking
- Result comparison: Winner result: 80.4%
- Our result: 79.5%



### WHY SO GOOD?



### Gradient Boost Decision Tree (GBDT)

- Gradient boosting is an ensemble method widely used for regression, classification and ranking tasks, developed in 2001
- Proposed by Friedman. [1]
- This type of algorithm trains the basic learner of this round by using the negative gradient of the error of the previous round of basic learners as the training target.
- Continuously reduce the deviation of the integrated model on the training set to achieve high-precision integration



### Intro to GBDT

- The learner based on the Gradient Boosting algorithm is called Gradient Boosting Machine (GBM).
  - The class method was originally proposed in the regression problem, and later extended to the field of classification. If AdaBoost is Boosting
  - The pioneering work of the method, then GBM is the master of the Boosting method.
- GBM has almost refreshed the accuracy records of many datasets in various fields.
   Some people think that GBM is the best performing
  - Machine learning algorithms, this statement is a bit radical, but usually the strategies of the winners of various data competitions are also
  - There will indeed be methods or ideas for such algorithms



### CART (Classification and Regression tree)

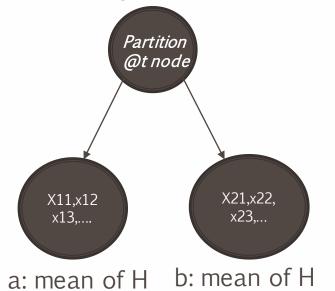
- The full name of the Cart tree is the classification and regression tree, which is a binary tree that can handle both classification and regression problems.
  - The strategies for dealing with the two types of problems are different, but the framework is generally the same. [2]
- The generation framework of regression tree and decision tree is the same, the only difference is the attribute selection criteria of nodes.
- The selection criterion used by the **classification tree** is the Gini coefficient, and it is considered that the attribute with a small Gini coefficient is better.
- The **regression tree** uses least squares error to calculate the division error of each attribute, and attributes with small division errors are better.

<sup>[2]</sup> Breiman, L., J. Friedman, C.J. Stone, and R. A. Olshen (1984). Classification and regression Trees. Chapman & Hall/CRC, Boca Raton, FL.



### Least-squared Solution for CART

- The regression tree will get a predicted value at each division node. Taking the label as height (H) of a person as an example, this predicted value
  - It is the average of the heights of all samples on this node.
- When branching, traverse all attributes for binary division, and select the division attribute that minimizes the squared error as this
  - Partitioning properties of nodes



The formula for calculating the squared error of the t-th attribute

loss\_t = 
$$\sum_{i} (x_{1i} - a)^2 + \sum_{j} (x_{2j} - b)^2$$

Traverse each features to find the attribute that minimizes loss, and let it be the current node properties of



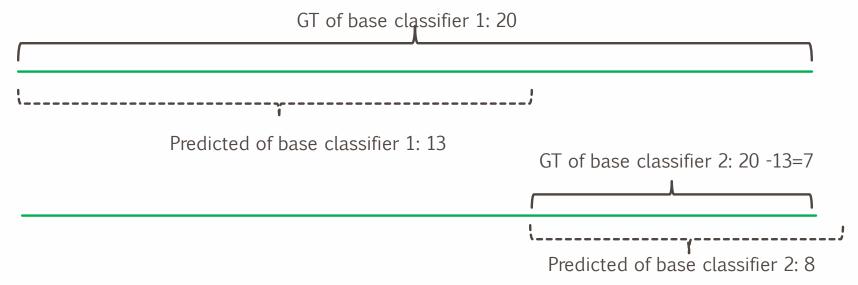
### Least-squared Solution for CART

- If the attribute has multiple possible values, you need to traverse all possible segmentation points to find the loss
  - The smallest split point is used as the binary split point of the attribute
- (Final) Continue to select new optimal features to divide the subset until there is only one sample per leaf node
  - Continue to select new optimal features to divide the subset until each leaf node has only one sample (this situation is rare or difficult to achieve, usually a parameter that allows leaf nodes to retain the minimum number of samples is set, If the condition is met, it can be stopped. If the leaf node has multiple sample values, the mean value is used as the predicted value of the leaf node)



### **Boosting Tree**

- Using the error of the previous round of basic learners as the training target to train the basic learners of this round, and continuously reduces the deviation of the integrated model on the training set to achieve high-precision integration
  - For example: For regression problem, if our predicted label value is 20



- The predicted label for the third time is 20-13-8 = -1, and this process is repeated until the specified number of base classifiers are generated
- Finally, adding all the prediction results is the prediction result of the integrated model



### Additive Model and Forward-Step Algorithm

Most boosting algorithms use additive (weighting-sum) for assembling weak classifiers

$$H(x) = \sum_{m=1}^{M} \beta_m * h_m (x; a_m)$$

 $h_m$  is m-th classifier,  $\beta_m$  is m-th coefficient,  $a_m$  is m classifiers parameters, M is the number of classifiers.

Let 
$$\beta_m = 1$$
 we have 
$$H(x) = \sum_{m=1}^{M} h_m(x; a_m)$$

<sup>[3]</sup> Friedman J, Hastie T, Tibshirani R. Additive logistic regression: a statistical view of boosting (With discussion and a rejoinder by the authors)[J]. Annals of Statistics, 2000, 28(2):337-374.



### Additive Model and Forward-Step Algorithm

■ It is an optimization issue. Given L and training data, we want to find a parameter

$$min_{\alpha} \sum_{i=1}^{N} L(y_i; \sum_{m=1}^{M} h_m(x_i; a_m))$$

- Directing solving this optimization problem is very hard.
- We use a forward-step algorithm (a type of greedy algorithm)
  - Rewriting the additive model to be

$$H_m(x) = H_{m-1}(x) + h_m(x; a_m)$$

### Additive Model and Forward-Step Algorithm

Only optimizing the loss at m-step (like regression tree)

$$min_{\alpha_m} \sum_{i=1}^{N} L(y_i, H_{m-1}(x_i) + h_m(x_i; \alpha_m))$$

■ With squared loss, we have  $L(y, H_m) = (y - H_m)^2$  and

• 
$$L(y, H_{m-1}(x) + h_m(x; a_m))$$

$$\blacksquare = [y - H_{m-1}(x) - h_m(x; a_m)]^2$$

$$\bullet = [r - h_m(x; a_m)]^2$$

• where  $r = y - H_{m-1}(x)$ , it is just like to the boosting tree



### **Gradient Boosting**

- What's different between gradient boosting and boosting tree?
- Boosting Tree:
  - Fit the current weak classifier with the residual for each step.
- GBDT:
  - Fit the current weak classifier with the negative gradient of the residue of the label for each step.



### What's the negative gradient of the residual

■ The negative gradient of residual for i = 1,2,3...,N samples is

$$r_{mi} = -\frac{\partial L(y_i, H_{m-1}(x_i))}{H_{m-1}(x_i)}$$

■ With the squared loss, we have  $L(y, H(x)) = \frac{1}{2}(y - H(x))^2$ , the negative gradient of the residual is y - H(x)

Setting	Loss Function	$-\partial L(y_i, f(x_i))/\partial f(x_i)$
Regression	$\frac{1}{2}[y_i - f(x_i)]^2$	$y_i - f(x_i)$
Regression	$ y_i - f(x_i) $	$sign[y_i - f(x_i)]$
Regression	Huber	$y_i - f(x_i)$ for $ y_i - f(x_i)  \le \delta_m$ $\delta_m \text{sign}[y_i - f(x_i)]$ for $ y_i - f(x_i)  > \delta_m$ where $\delta_m = \alpha \text{th-quantile}\{ y_i - f(x_i) \}$

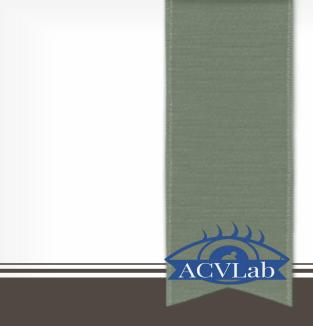


### Extreme Gradient GBDT (XGBoost)

- XGBoost: Fast and accurate GBDT
  - Add the regularization term of the computational complexity in the loss function

GBDT: 
$$Obj = \sum_{i=1}^{n} L(y_i, H_M(x_i))$$
 
$$XGBoost: Obj = \sum_{i=1}^{n} L(y_i, H_M(x_i)) + \sum_{m=1}^{M} \Omega(h_m)$$

where M is the number of the weak classifiers  $\Omega(h_m)$  is the complexity of m-th tree



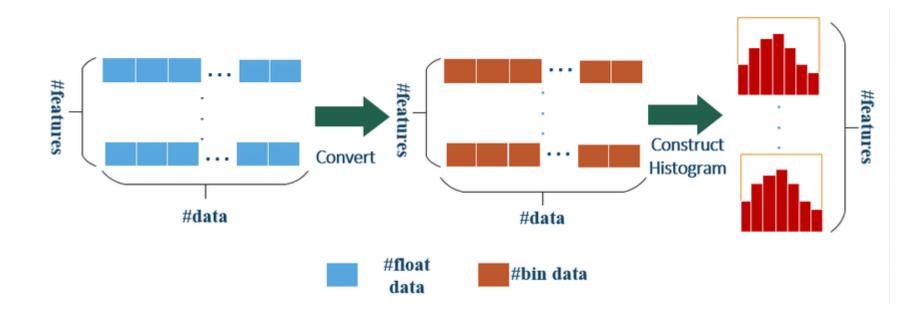
# LIGHTGBM

A Highly Efficient Gradient Boosting Decision Tree



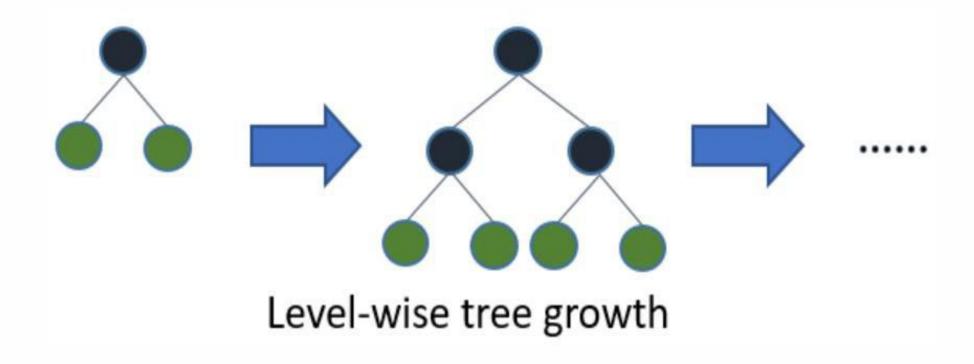
### Histogram-based Algorithm

- Discretize the feature...
  - Moving averaging



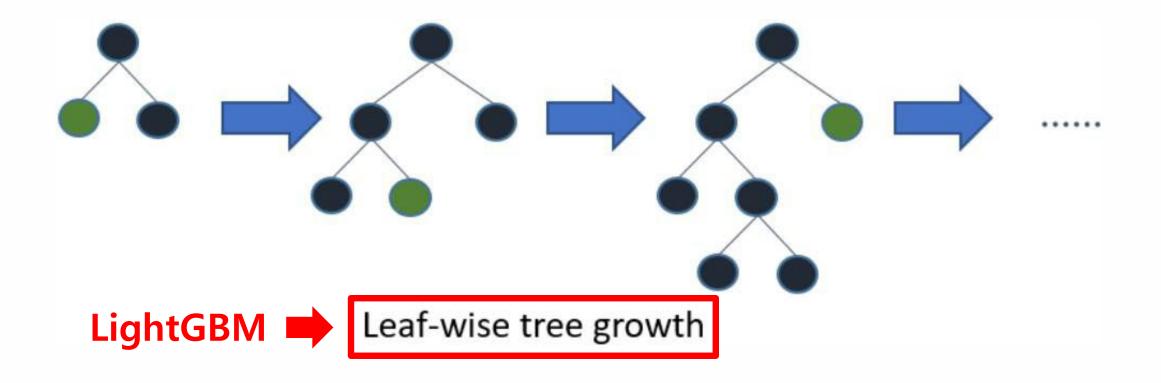


### Growing Mechanisms of Decision Tree





### Growing Mechanisms of Decision Tree





### An Advantages of Leaf-wise Tree Growth

- Leaf-wise Tree Growth (Best-First)
- Choose the leaf with Max  $\Delta \mathcal{L}$  (loss) to grow
- → Holding # of leaves fixed, tend to achieve lower loss
- May cause over-fitting when # of data is small
- → includes the max\_depth parameter to limit tree depth



## A Problem of Gradient Boosting Decision Tree

- GBDT
- Gradient for each data instance in GBDT provides the importance of data instance.
- An instance with Large Gradient → Important
- An instance with Small Gradient → Discard (Problem)



#### New Novel Techniques of LightGBM

GOSS (Gradient-based One-Side Sampling)

Amplified by Multiplying a Constant  $\frac{1-a}{b}$ 

Random  $b \times 100\%$  instances

Top  $a \times 100\%$  instances

Data	Data		Data	Data
Instance 1	Instance 2	•••	Instance (n-1)	Instance n



**Large Gradient** 





### New Novel Techniques of LightGBM

## EFB (Exclusive Feature Bundling)

- High-dimensional data are usually very spare
  - → Many features are mutually exclusive
  - → Bundling exclusive features into a single feature safely
    - → Speed up the training of GBDT without hurting the accuracy



# CATBOOST

Designed for categorical data...



### CatBoost advantages

- Good quality with default parameters
- Good GPU training speed
- Sophisticated categorical, text and embedding features support
- Model analysis tools
- Set of tools to make GBDT usage easier



#### CatBoost in the Wild



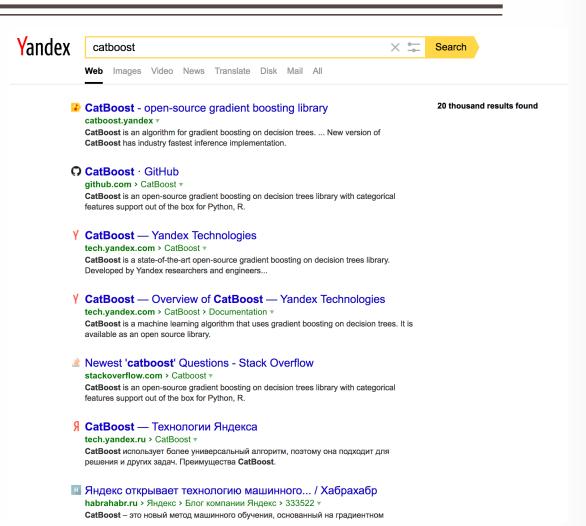
- Recommendations at Netflix
- Hotel ranking in Aviasales
- Protection against bots in CloudFlare
- Particle classification in CERN
- Medical research at University of NSW Sydney
- Destination prediction in Careem taxi service
- ML competitions on Kaggle
- Join our Awesome Users List! ©





#### Yandex.Search

- Task?
  - Search document order prediction
- Task type: ranking
- Dataset features:
  - Classic features (PageRank, BM25 and others)
  - Neural Networks output
- CatBoost features used:
  - YetiRankPairwise target
  - Distributed GPU training
  - Model blending
  - Feature importance analysis
  - Ranking analysis





#### Yandex.Weather

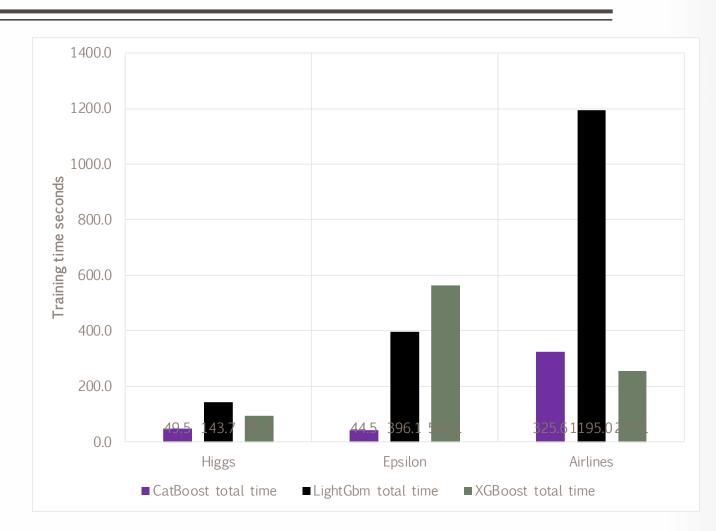
- Task?
  - Cloudiness type and temperature prediction
- Task type: multiclassification and regression
- Dataset features
  - Physical weather model output
  - Neural network output
  - Online-data from weather stations
  - Weather historical data
- CatBoost features used:
  - Multiclassification target and RMSE (for temperature)
  - GPU training
  - Feature importance analysis
  - Training process visualization





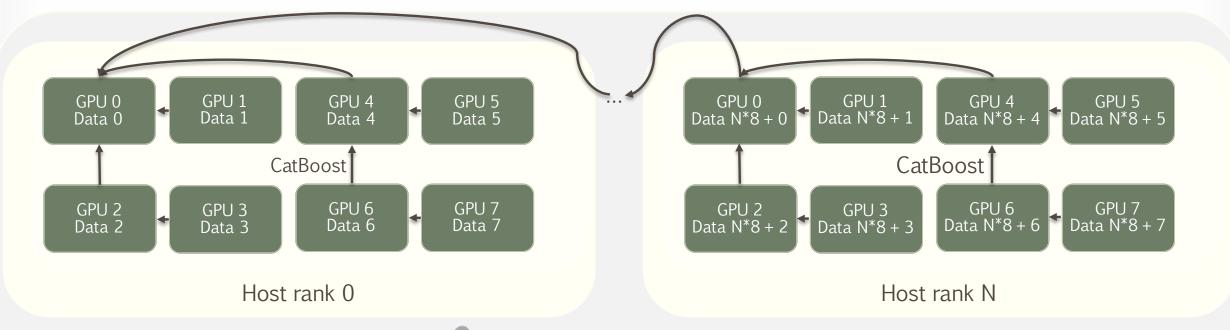
## V100 Training performance: 1000 trees

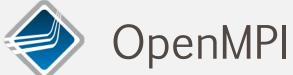
- GPU training time on single NVIDIA Tesla V100
  - Higgs
  - 10.5mln objects
- 28 features
  - Epsilon
- 400k objects
- 2k features
  - Airlines
  - 23mln objects
  - 13 features
  - CatBoost v0.24.1, Lightgbm 2.3.1, XGBoost 1.0.2

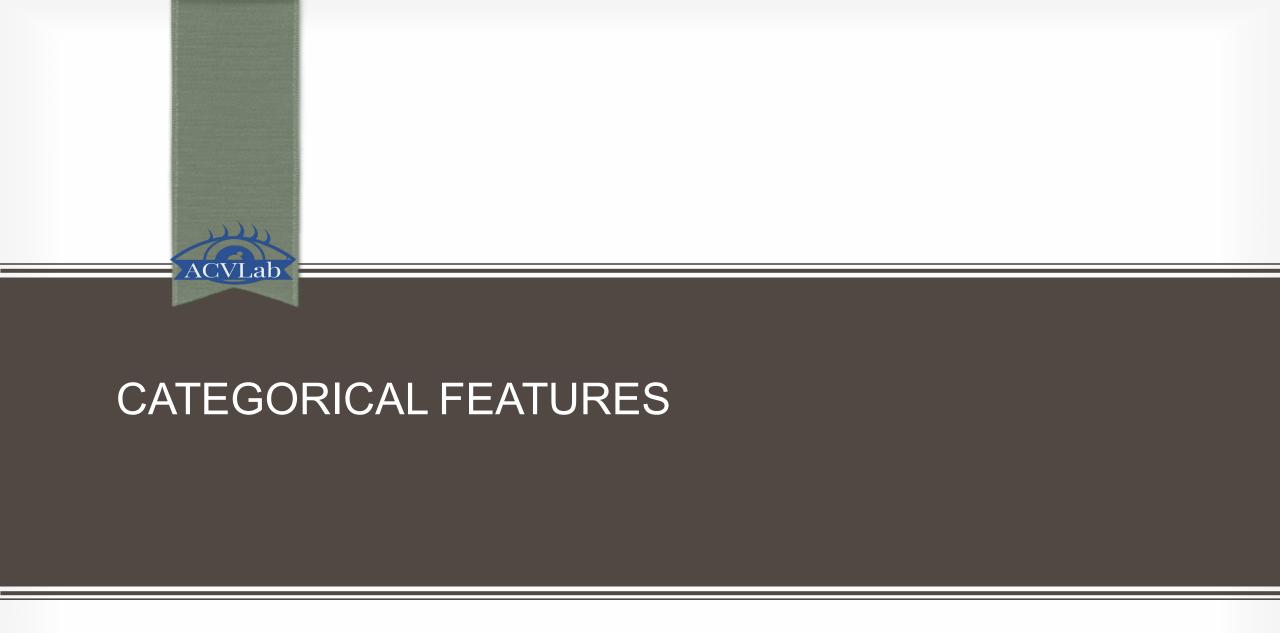




## Distributed training: multi-host multi-GPU









#### Categorical Encoding

- One-hot encoding: create new variables as many as the number of categories in the variable
  - When the categories are high (high cardinality), too many variables are created.
- Label encoding: create a variable so that one category is one integer
  - The size of the variable has no meaning, but it is difficult to reflect in the model
- Target encoding: Create a new variable with representative values (average, median...) of target values belonging to the same category
  - Greedy, Holdout, Ordered...

	x1	x2	•••	xn	target
1	2	40		rock	1
2	3	55		indie	0
3	5	34	•••	pop	1
4	2	45		rock	0
5	4	53	•••	rock	0
6	2	48		indie	1
7	5	42		rock	1



xn_1	xn_2	xn_3
1	0	0
0	1	0
0	0	1
1	0	0
1	0	0
0	1	0
1	0	0

xn
1
2
3
1
1
2
1

xn	
0.5	
0.5	
1	
0.5	
0.5	
0.5	
0.5	

•••

<one-hot>

<label>

<target>



#### Target Statistics

#### Target encoding

$$\hat{x}_k^i \approx \mathbb{E}(y|x^i = x_k^i)$$

1. Greedy TS: The purpose of smoothing for infrequent categories

$$\hat{x}_k^i = \frac{\sum_{j=1}^n \mathbb{I}_{\{x_j^i = x_k^i\}} \cdot y_i + ap}{\sum_{j=1}^n \mathbb{I}_{\{x_j^i = x_k^i\}} + a}$$

- a is the parameter, p is the target mean
- Target leakage: Information about the target enters the training data, and overfitting may occur.
- Conditional shift: Because the distribution of train/test data is different, overfitting may occur.
  - Let's say the size of the train dataset is 1000 and the number of user IDs is 1000. If you create a variable using greedy TS, DT for the training dataset can be classified with 100% accuracy as one variable, but it can be a useless variable in reality.
  - As a way to avoid conditional shift, when calculating the TS of  $x_k$ , subset  $D_k \subset D \setminus \{x_k\}$



#### **Target Statistics**

- 2. Holdout TS: How to divide the train dataset and the dataset for TS calculation
  - 2. The number of available data is greatly reduced
- 3. Leave-one-out TS: How to use  $D_k = D \setminus \{x_k\}$  as train dataset and  $D_k = D$  as test dataset
  - Target leakage can't get out of trouble
- 4. Ordered TS: A method to solve the problem of target leakage and conditional shift
  - 1) offline -> online Randomly change the situation to solve the problem
  - 2) For the train dataset, apply "Artificial time" with random permutation

$$\hat{x}_k^i = \frac{\sum_{j=1}^n \mathbb{I}_{\{x_j^i = x_k^i\}} \cdot y_i + ap}{\sum_{j=1}^n \mathbb{I}_{\{x_j^i = x_k^i\}} + a}$$

	x1	x2	•••	xn	target	
1	2	40		rock	1	
2	3	55		indie	0	
3	5	34	***	pop	1	
4	2	45		rock	0	
5	4	53		rock	0	
6	2	48	•••	indie	1	ре
7	5	42		rock	1	



random permutation

		ΧΙ	XZ	•••	XII	target
	1	4	53		rock	0
	2	3	55		indie	0
	3	2	40	•••	rock	1
	4	5	42		rock	1
	5	5	34		pop	1
1	6	2	48		indie	1
	7	2	45	***	rock	0



target

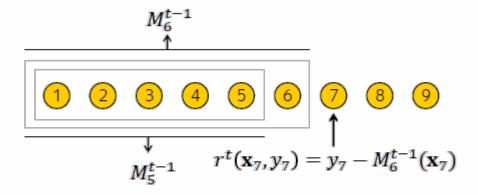
calculating ordered TS prior = 0.05

	x1	x2	•••	xn	target
1	4	53		(0+0.05)/(0+1)=0.05	0
2	3	55		(0+0.05)/(0+1)=0.05	0
3	2	40		(0+0.05)/(1+1)=0.025	1
4	5	42	•••	(1+0.05)/(2+1)=0.35	1
5	5	34	•••	(0+0.05)/(0+1)=0.05	1
6	2	48	•••	(0+0.05)/(1+1)=0.025	1
7	2	45	•••	(2+0.05)/(3+1)=0.5125	0



## **Ordered Boosting**

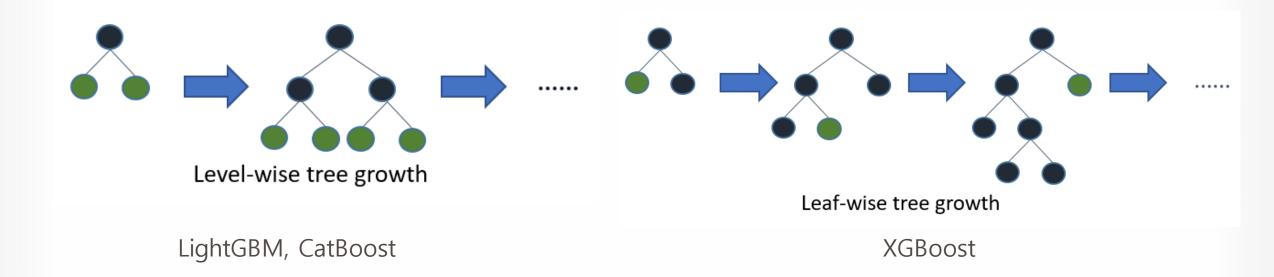
GBDT learning using "Artificial time" concept to solve target leakage/prediction shift problem



- 1. Perform random permutation s times (within 10 times in the experiment) to create multiple timelines
- 2. Gradient boosting is implemented.
  - 1) to find the gradient
    - 1) Choose one of the random permutations and,
    - 2 For each object, the gradient is computed only for objects that exist in the time period preceding itself.
  - 2) Using cosine similarity, choose a branching criterion with a negative gradient!



## XGBoost, LightGBM, CatBoost



- CatBoost is not sensitive to parameters compared to LightGBM and XGBoost.
- However, in the case of a sparse matrix, learning is difficult, and when there are many numeric variables, it is slower than LightGBM.



### **Experiments**

Table 2: Comparison with baselines: logloss / zero-one loss (relative increase for baselines).

Table 3: Plain boosting mode: logloss, zeroone loss and their change relative to Ordered boosting mode.

	CatBoost	LightGBM	XGBoost
Adult	0.270 / 0.127	+2.4% / +1.9%	+2.2% / +1.0%
Amazon	0.139 / 0.044	+17% / +21%	+17% / +21%
Click	0.392 / 0.156	+1.2% / +1.2%	+1.2% / +1.2%
Epsilon	0.265 / 0.109	+1.5% / +4.1%	+11% / +12%
Appetency	0.072 / 0.018	+0.4% / +0.2%	+0.4% / +0.7%
Churn	0.232 / 0.072	+0.1% / +0.6%	+0.5% / +1.6%
Internet	0.209 / 0.094	+6.8% / +8.6%	+7.9% / +8.0%
Upselling	0.166 / 0.049	+0.3% / +0.1%	+0.04% / +0.3%
Kick	0.286 / 0.095	+3.5% / +4.4%	+3.2% / +4.1%

	Logloss	Zero-one loss
Adult	0.272 (+1.1%)	0.127 (-0.1%)
Amazon	0.139 (-0.6%)	0.044 (-1.5%)
Click	0.392 (-0.05%)	0.156 (+0.19%)
Epsilon	0.266 (+0.6%)	0.110 (+0.9%)
Appetency	0.072 (+0.5%)	0.018 (+1.5%)
Churn	0.232 (-0.06%)	0.072 (-0.17%)
Internet	0.217 (+3.9%)	0.099 (+5.4%)
Upselling	0.166 (+0.1%)	0.049 (+0.4%)
Kick	0.285 (-0.2%)	0.095 (-0.1%)



#### Experiments

Table 4: Comparison of target statistics, relative change in logloss / zero-one loss compared to ordered TS.

	Greedy	Holdout	Leave-one-out
Adult	+1.1% / +0.8%	+2.1% / +2.0%	+5.5% / +3.7%
Amazon Click	+40% / +32% +13% / +6.7%	+8.3% / +8.3% +1.5% / +0.5%	+4.5% / +5.6% +2.7% / +0.9%
Appetency	+24% / +0.7%	+1.6% / -0.5%	+8.5% / +0.7%
Churn	+12% / +2.1%	+0.9% / +1.3%	+1.6% / +1.8%
Internet	+33% / +22%	+2.6% / +1.8%	+27% / +19%
Upselling	+57% / +50%	+1.6% / +0.9%	+3.9% / +2.9%
Kick	+22% / +28%	+1.3% / +0.32%	+3.7% / +3.3%

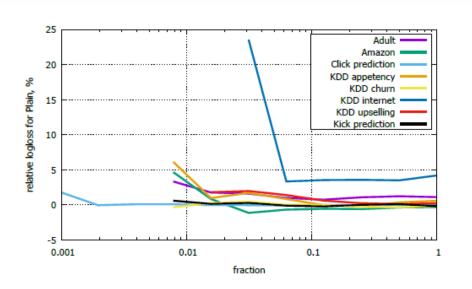


Figure 2: Relative error of Plain boosting mode compared to Ordered boosting mode depending on the fraction of the dataset.