

Video Shot Change Detection

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Abstract

This paper presents a method for video shot change detection. The proposed approach utilizes various visual features and a shot change detection algorithm to identify shot boundaries in video sequences. The program is implemented in Python and evaluated on three different video datasets. Experimental results demonstrate the effectiveness of the proposed method, achieving promising detection performance. The paper also discusses the program execution environment, the employed visual features, and the shot change detection algorithm in detail. Furthermore, the detection performance for each of the three videos is reported and analyzed. The source code and a detailed written report are provided as supplementary materials.

1. Introduction

Shot change detection is a fundamental task in video analysis and indexing. It aims to identify the transition points between different shots in a video sequence. Accurate shot change detection is crucial for various applications, such as video summarization, content-based retrieval, and video editing. In this paper, we implemented many feature extraction methods taught in class, such as color histograms and region histograms. Additionally, we plotted evaluation methods taught in class, such as RP curves and ROC curves, and calculated the F1 Score.

2. Related Work

Video shot change detection has been a fundamental task in multimedia content analysis, enabling efficient video indexing, retrieval, and summarization. Over the years, researchers have proposed various methods to identify the transition points between shots, focusing on abrupt changes and gradual transitions [1, 4].

One of the most widely used approaches for shot change detection is based on color histogram comparison [1, 2]. Boreczky et al. [1] conducted a comprehensive study com-

paring different histogram-based methods and found that they provide consistent performance across various video types. Smith [2] further investigated color descriptor metrics and demonstrated the effectiveness of histogram intersection (D1), Euclidean distance (D2), quadratic distance (D4), and Mahalanobis distance (D6) for measuring the dissimilarity between frames.

In addition to color histograms, researchers have explored other features for shot change detection. Zabih et al. [6] introduced the edge change ratio (ECR) to detect cuts and dissolves by measuring the percentage of entering and exiting edge pixels between consecutive frames. Pei et al. [5] utilized the direction of motion prediction as a cue for shot boundary detection, leveraging the motion information in compressed video streams. Zhang et al. [7] developed a twin-comparison approach that employs two thresholds for cut and gradual transition detection, analyzing frame differences over a sliding window.

Despite the progress made in shot change detection, challenges remain in accurately identifying gradual transitions and handling complex video content [4] [3]. Lienhart [4] highlighted the importance of considering both abrupt changes and gradual transitions, while Yuan et al. [3] emphasized the need for robust methods that can adapt to diverse video characteristics. Future research should focus on developing more sophisticated and adaptive techniques that can effectively address these challenges while maintaining computational efficiency.

3. Proposed Method

Here is a more concise version of the "Visual Features" section using LaTeX:

3.1. Features Extraction

We employ two primary visual features for shot change detection: color histograms and region-based methods [1, 4].

3.1.1 Color Histograms

Color histograms capture the color distribution in a frame. The RGB color space is quantized into N bins, and the histogram H is computed as:

$$H(i) = \sum_{x,y} \delta(I(x,y), i), \quad i = 1, 2, \dots, N \quad (1)$$

where $I(x,y)$ is the color value at position (x,y) , and $\delta(a,b)$ is the Kronecker delta function.

3.1.2 Region-based Methods

Region-based methods divide the frame into an $M \times M$ grid and compute color histograms for each region. The dissimilarity between two frames F_1 and F_2 is computed by averaging the distances between corresponding regions:

$$D_{\text{region}}(F_1, F_2) = \frac{1}{M^2} \sum_{r=1}^{M^2} D1(H_{1,r}, H_{2,r}) \quad (2)$$

where $H_{1,r}$ and $H_{2,r}$ are the color histograms of region r in frames F_1 and F_2 , respectively.

The combination of color histograms and region-based methods captures both global and local color information for shot change detection.

3.2. Color Descriptor Metrics

In this work, we utilize six color descriptor metrics for measuring the dissimilarity between color histograms: D1, D2, D5, D6, D7, and D8. These metrics have been selected based on their computational efficiency and their demonstrated effectiveness in shot change detection [1, 2].

These metrics quantify the dissimilarity between two color histograms in different ways. D1 measures the overlap between histograms, while D2 calculates the Euclidean distance between histogram bins. D5, D6, D7, and D8 are based on statistical measures of divergence and similarity between probability distributions.

By employing multiple color descriptor metrics, we aim to capture different aspects of histogram dissimilarity and enhance the robustness of the shot change detection algorithm. The choice of these specific metrics is motivated by their computational efficiency and their proven performance in previous studies.

4. Experimental Results

The experimental results for video shot change detection on three different videos are presented here. The performance is evaluated using precision-recall curves and receiver operating characteristic (ROC) curves for both color and region features.

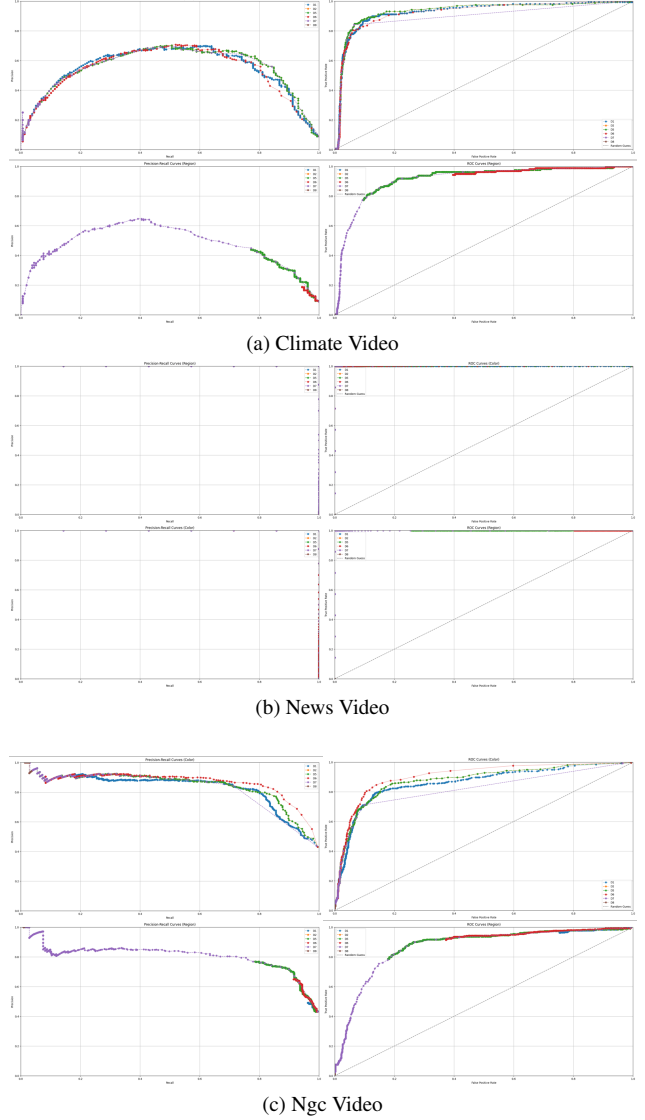


Figure 1. Precision-recall and ROC curves for shot change detection

For the first video (Figure 1a), the precision-recall curves for color and region features show relatively poor performance, with the curves staying close to the bottom-left corner. This indicates that the shot change detection algorithm struggles to achieve high precision and recall rates on this video. The ROC curves further confirm the suboptimal performance, with the curves deviating only slightly from the diagonal line representing random guessing.

The second video (Figure 1b) exhibits better performance compared to the first video. The precision-recall curves, especially for the color feature, show a more desirable trend, with higher precision values achieved for a wider range of recall rates. The ROC curves also depict improved performance, with the curves rising more steeply towards

the top-left corner, indicating better trade-offs between true positive and false positive rates.

For the third video (Figure 1c), the performance is generally the best among the three videos. The precision-recall curves for both color and region features demonstrate a more desirable shape, with high precision values maintained over a relatively wide range of recall rates. The ROC curves also show the best performance, with the curves approaching the top-left corner more closely, indicating a better balance between true positive and false positive rates.

Overall, the experimental results suggest that the shot change detection algorithm performs better on certain videos compared to others. The variations in performance could be attributed to factors such as the video content, lighting conditions, camera movements, and the effectiveness of the chosen visual features and algorithm for different video characteristics.

5. Conclusion

In this study, we successfully accomplished the task of shot change detection in videos. We utilized feature extraction and color descriptor metrics to compute distances, and ultimately evaluated the performance using RP curves and ROC curves. Overall, our detection results were satisfactory, and the entire process was conducted thoroughly. Through this assignment, I acquired a wealth of technical knowledge and theoretical understanding, which enabled me to accomplish the task with a strong sense of achievement.

References

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