

1

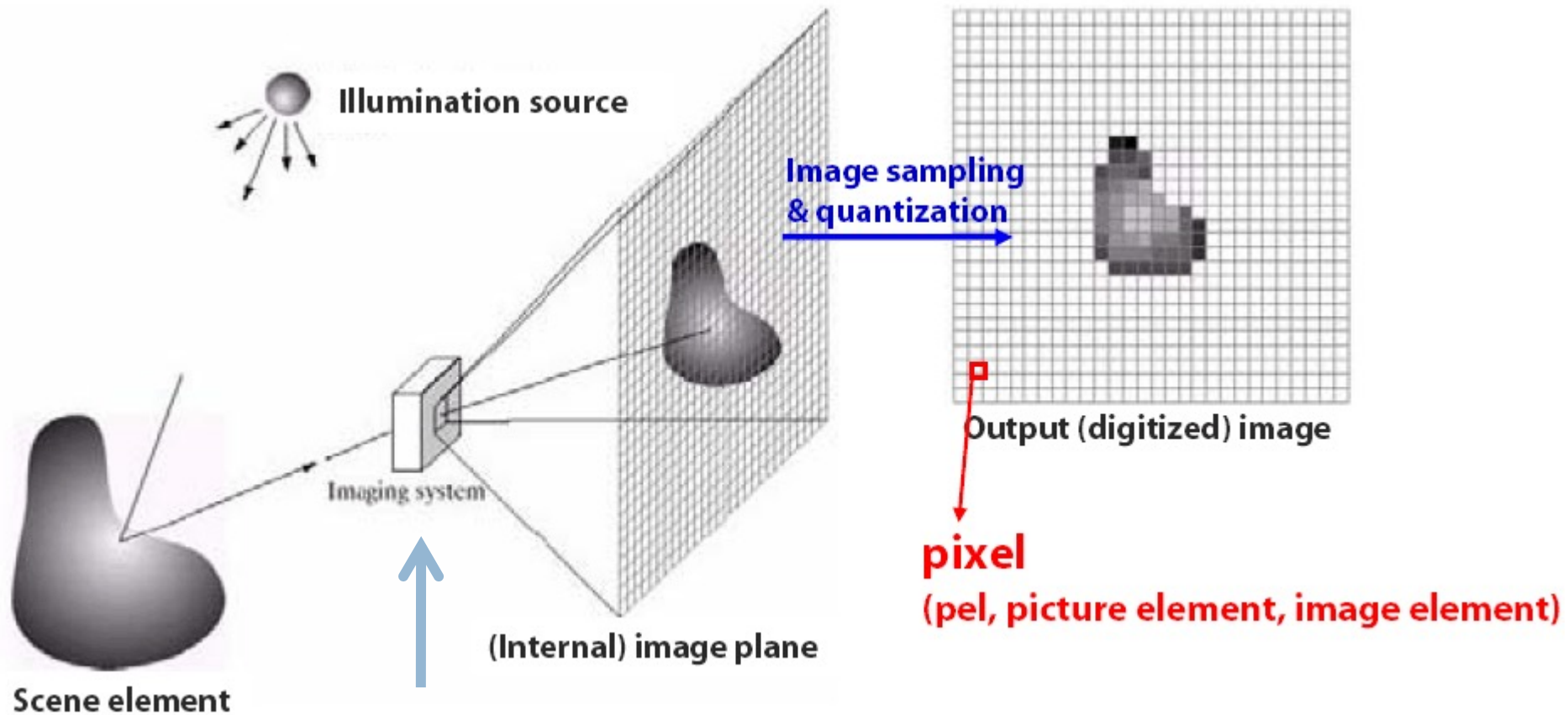
# Essence of Image

Wei-Ta Chu

Chapters 2 and 6 of “Digital Image Processing” by R.C. Gonzalez and R.E. Woods, Prentice Hall, 2<sup>nd</sup> edition, 2001

# Image Sensing and Acquisition

2



Collect the incoming energy and focus it onto an image plane.

# A Simple Image Formation Model

3

- Denote an image by a 2D function

$$0 < f(x, y) < \infty$$

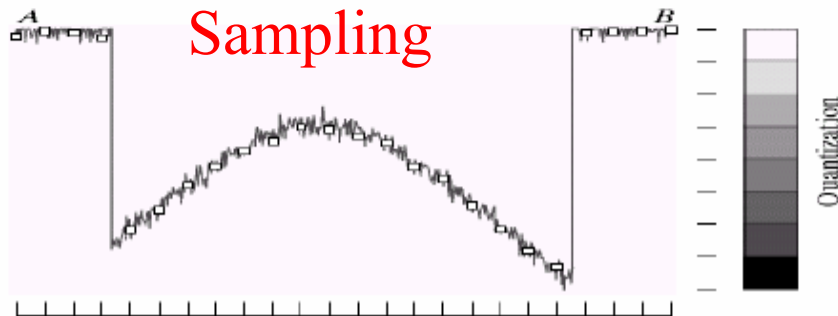
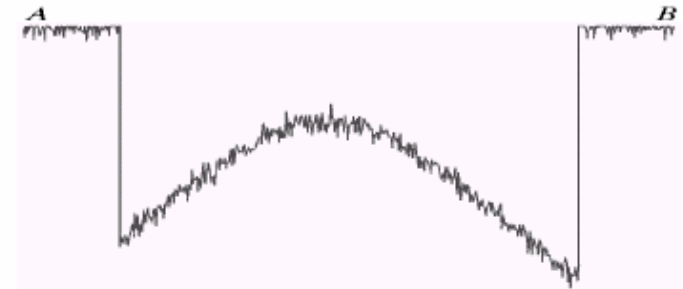
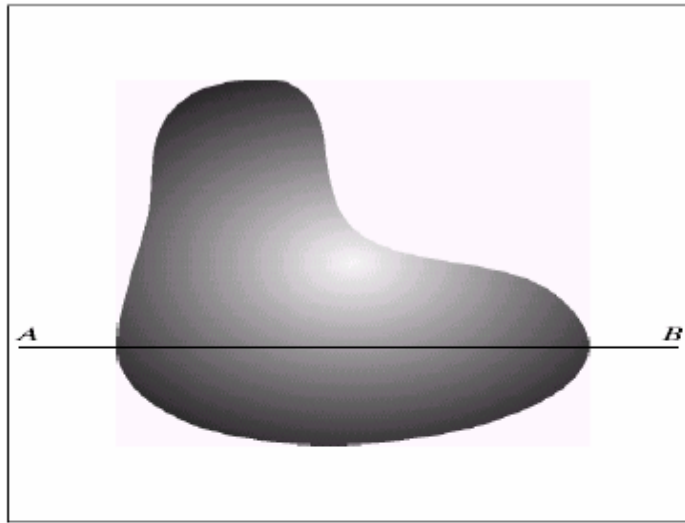
- Characterized by two components:

$$f(x, y) = i(x, y)r(x, y)$$

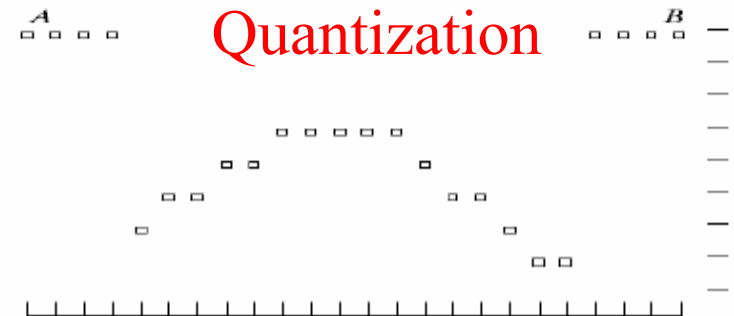
- Illumination:  $0 < i(x, y) < \infty$ , determined by the illumination source
- Reflectance:  $0 < r(x, y) < 1$ , determined by the characteristics of the imaged objects.

# Image Sampling and Quantization

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Digitizing the coordinate values

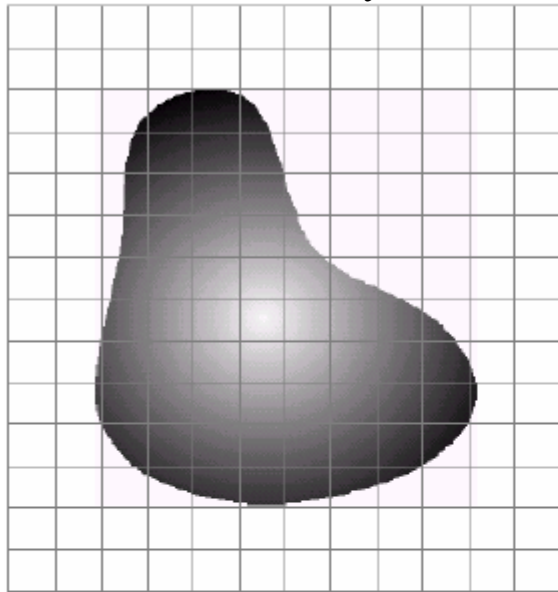


Digitizing the amplitude values

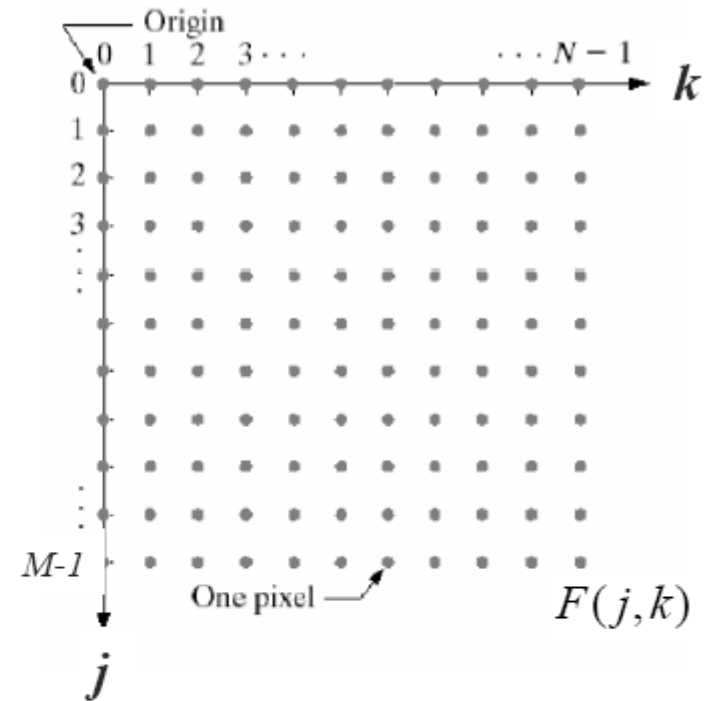
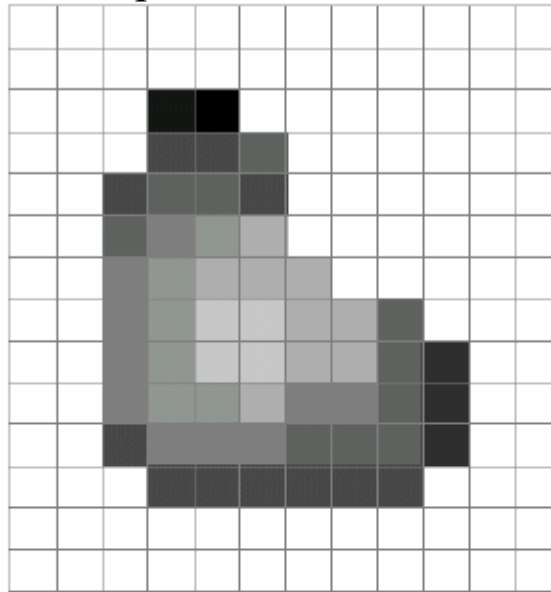
# Image Sampling and Quantization

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Continuous image projected  
onto a sensor array



Results of image sampling  
and quantization



$$A = \begin{bmatrix} a_{0,0} & a_{0,1} & \cdots & a_{0,N-1} \\ a_{1,0} & a_{1,1} & \cdots & a_{1,N-1} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M-1,0} & a_{M-1,1} & \cdots & a_{M-1,N-1} \end{bmatrix}$$

$$F(j,k) = \begin{bmatrix} F(0,0) & F(0,1) & \cdots & F(0,N-1) \\ F(1,0) & F(1,1) & \cdots & F(1,N-1) \\ \vdots & \vdots & \ddots & \vdots \\ F(M-1,0) & F(M-1,1) & \cdots & F(M-1,N-1) \end{bmatrix}$$

# Histogram

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- The histogram of an image with gray level in the range  $[0, L-1]$  is a discrete function

$$h(r_k) = n_k$$

$r_k$  is the  $k$ th gray level and  $n_k$  is the number of pixels in the image having gray level  $r_k$

- **Normalized histogram**

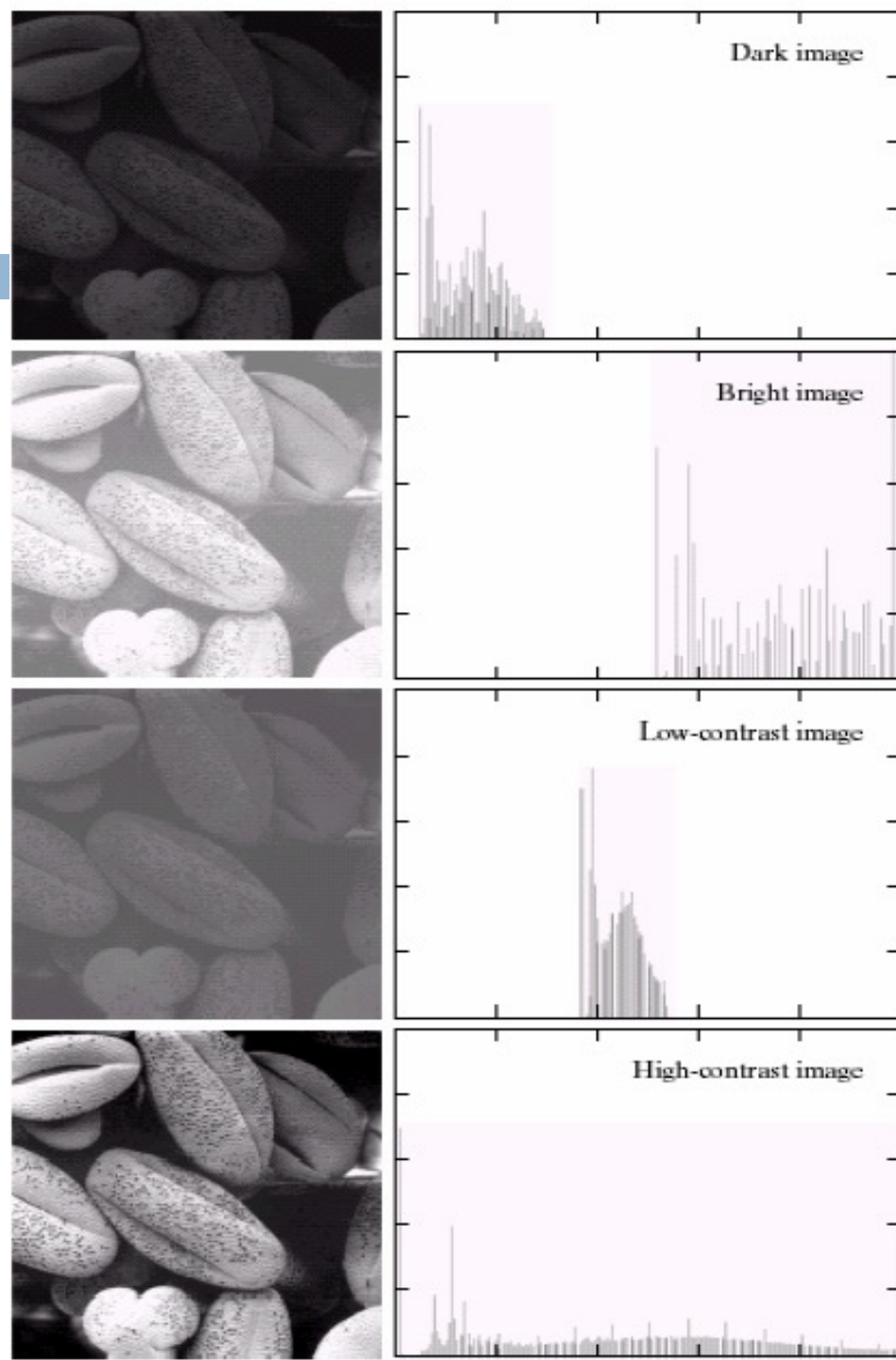
$$p(r_k) = n_k/n$$

$n$  is the total number of pixels in the image

# Histogram

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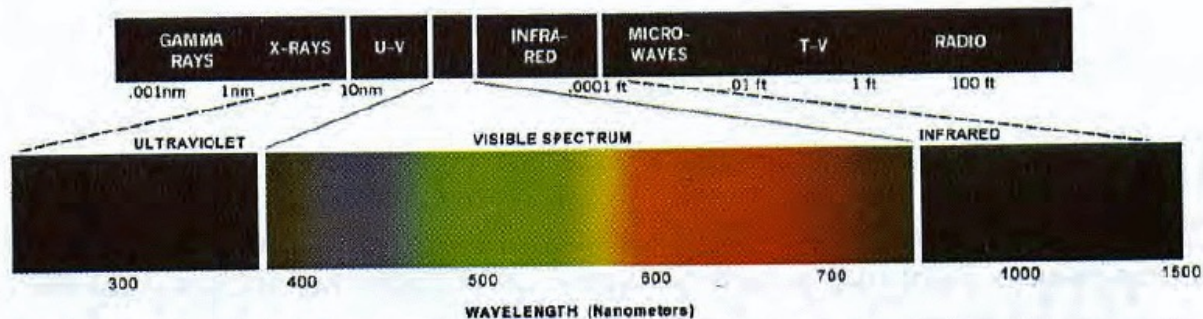
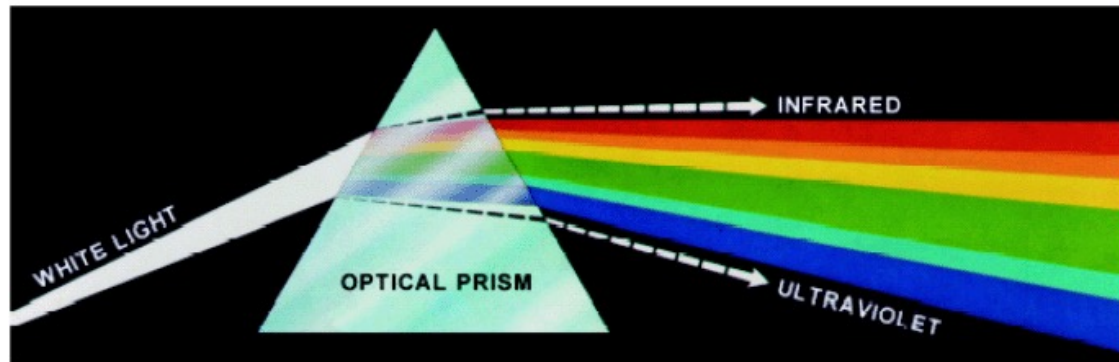
- Useful image statistics
- Image processing applications
  - ▣ Image enhancement
  - ▣ Image compression
  - ▣ Image segmentation



# Color Fundamentals

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- Color spectrum: violet, blue, green, yellow, orange & red
- Each color in the spectrum blends smoothly into the next
- The color perceived in an object are determined by the nature of the light reflected from the object

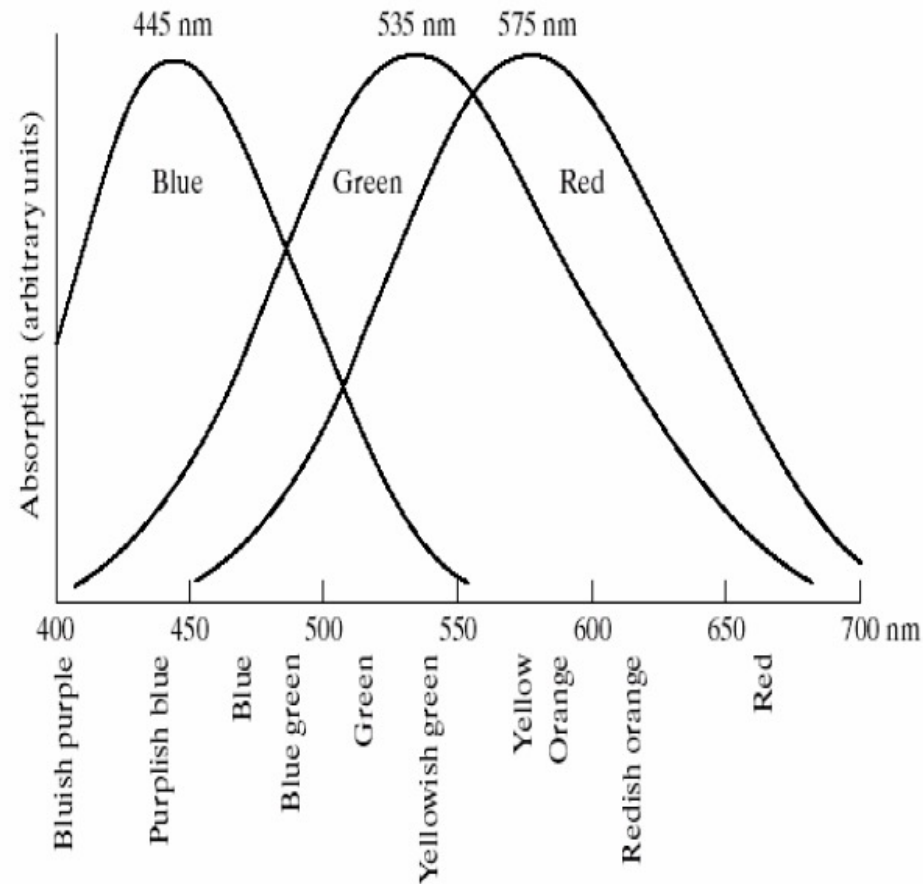




# Color Fundamentals

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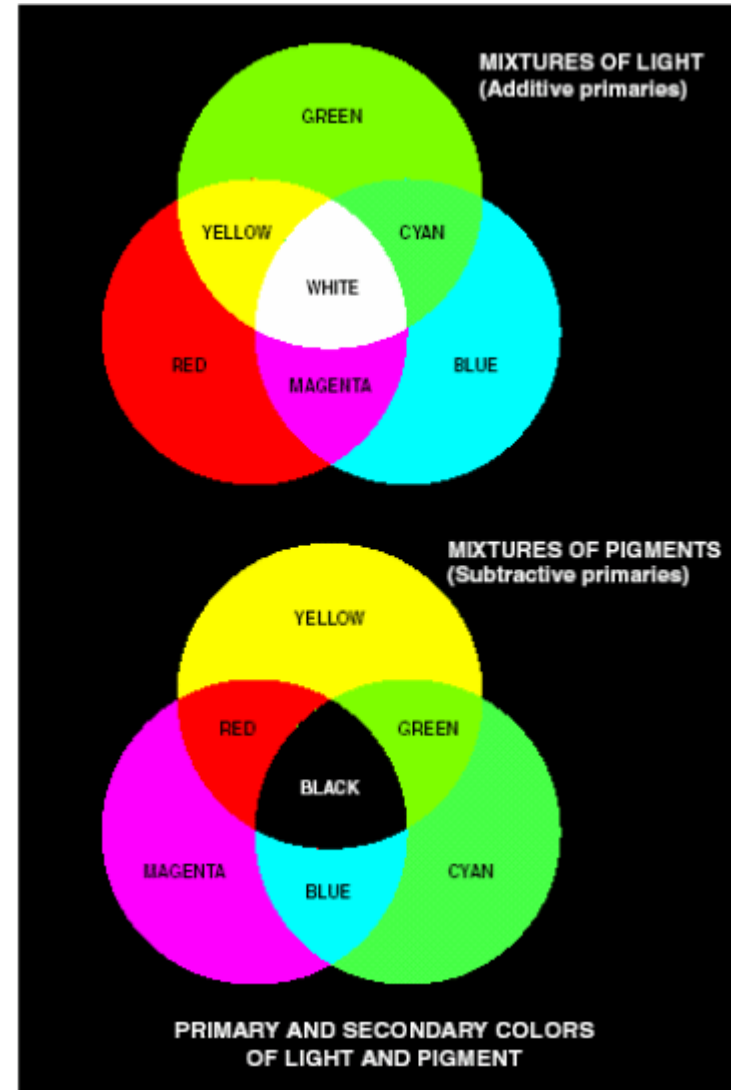
- Cones can be divided into three principal sensing categories
- Due to the absorption of the human eyes, colors are seen as variable of three primary colors (red, green, blue)
- Approximately 65% of all cones are sensitive to red light, 33% to green light, 2% to blue light.



# Color Fundamentals

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- Secondary colors of light
  - ▣ Magenta (R + B)
  - ▣ Cyan (G + B)
  - ▣ Yellow (R + G)
- The primary color of pigments subtract a primary color of light and reflects the other two.



# Color Fundamentals

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- Brightness
  - ▣ Embodies the chromatic notion of intensity
- Hue
  - ▣ Attribute associated with the dominant wavelength in a mixture of light waves
  - ▣ Dominant color as perceived by an observer
- Saturation
  - ▣ The relative purity of the amount of white light mixed with a hue
  - ▣ Less saturated: e.g. pink (red+white), lavender (violet+white)
- Hue and saturation taken together as called chromaticity.

# Specifying Colors

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- The amounts of red, green, and blue needed to form any particular color are called the tristimulus values and are denoted  $X$ ,  $Y$ ,  $Z$ , respectively.

- A color is then specified by its trichromatic coefficients, defined as

$$x = \frac{X}{X + Y + Z} \quad y = \frac{Y}{X + Y + Z} \quad z = \frac{Z}{X + Y + Z}$$

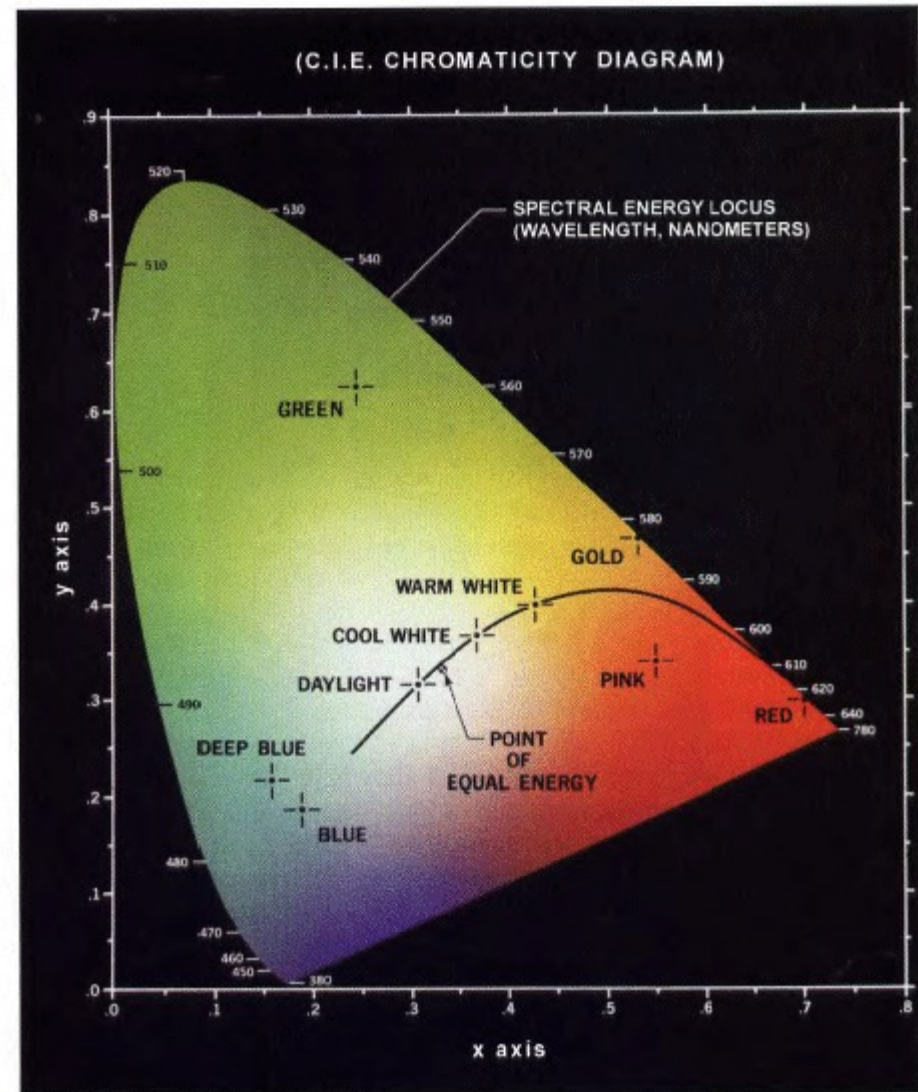
$$x + y + z = 1$$

- Using CIE chromaticity diagram, which shows color composition as a function of  $x$  (red) and  $y$  (green)

# Specifying Colors

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- The point marked green has approximately 63% green and 25% red content. The composition of blue is approximately 13%.



# Color Models (Color Spaces)

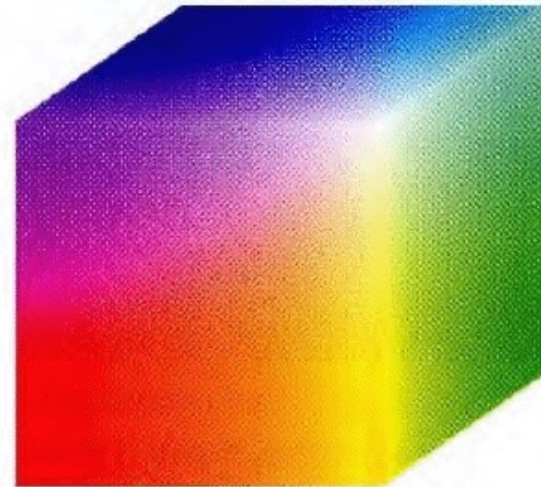
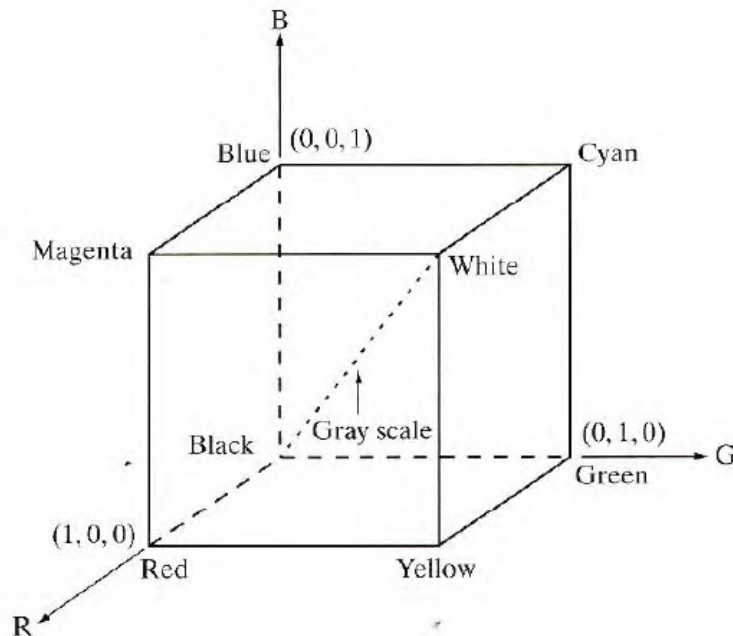
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- A color model is a specification of a coordinate system and a subspace within that system where each color is represented by a single point.
- Hardware-oriented & application-oriented
  - ▣ RGB – color monitor, color video cameras
  - ▣ CMY (cyan, magenta, yellow) – color printing
  - ▣ CMYK (cyan, magenta, yellow, black) – color printing
  - ▣ HSI (hue, saturation, intensity) – closely matching with human perception

# The RGB Color Model

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- Based on Cartesian coordinate system
- Different colors are points on or inside the cube
- Full color image: 8 bits for each component, total 24 bits





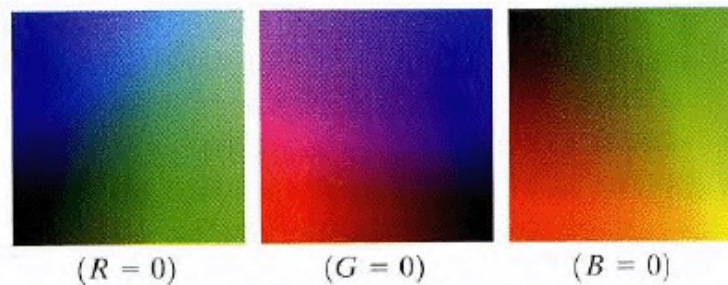
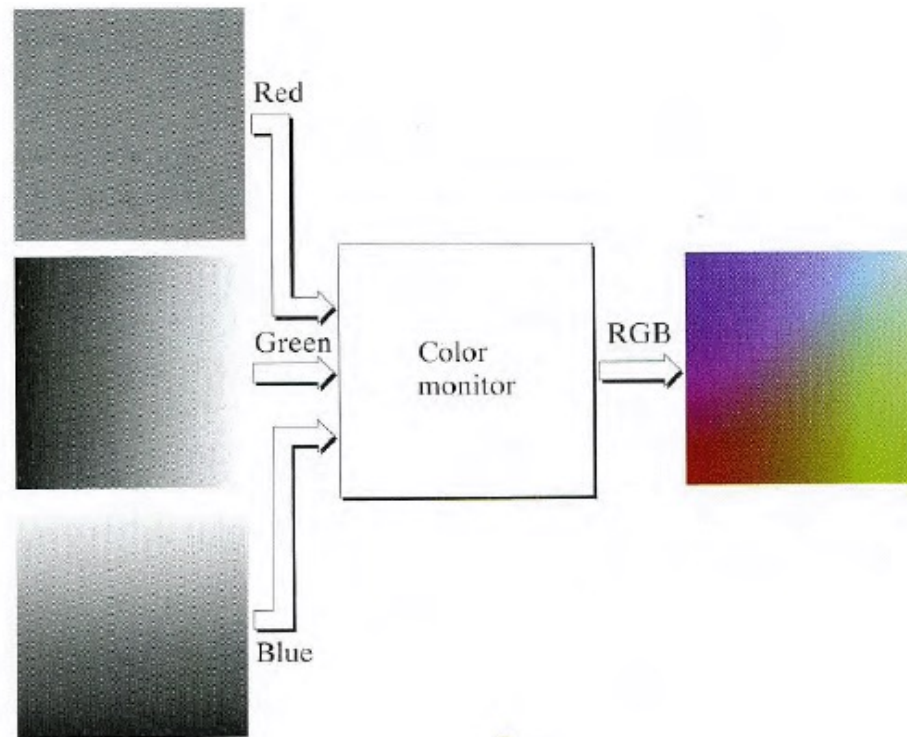
# The RGB Color Model

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a  
b

**FIGURE 6.9**

(a) Generating the RGB image of the cross-sectional color plane  $(127, G, B)$ .  
(b) The three hidden surface planes in the color cube of Fig. 6.8.





# The CMY and CMYK Color Models

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- When a surface coated with cyan pigment is illuminated with white light, no red light is reflected from the surface.
  - ▣ Cyan subtracts red light
- Most devices that deposit colored pigments on paper require CMY data input or perform RGB to CMY conversion.
- Equal amounts of CMY pigments should produce black.

$$\begin{bmatrix} C \\ M \\ Y \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

# The HSI Color Model

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- RGB/CMY color systems are suited for hardware implementations.
- RGB system matches nicely with the fact that the human eye is strongly perceptive to red, green, and blue primaries.
- But RGB and CMY are not well suited for *describing* colors for human interpretation.

# The HSI Color Model

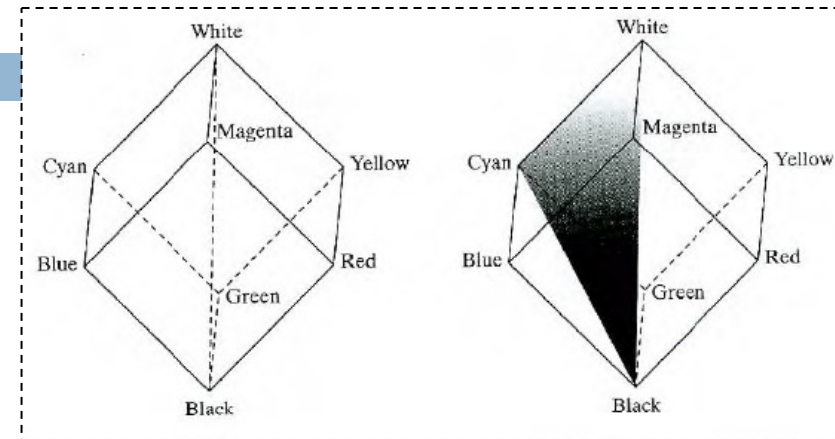
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- We describe a color object by its hue, saturation, and brightness.
  - ▣ Hue: color attribute that describes a pure color
  - ▣ Saturation: degree of pure color diluted by white light
  - ▣ Brightness: measured by intensity
- HSI color model decouples the intensity component from the color-carrying information

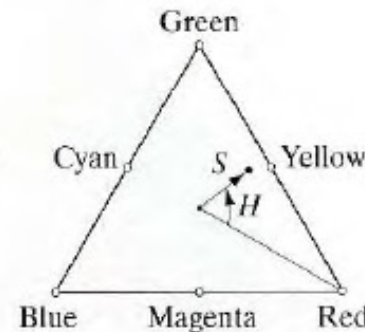
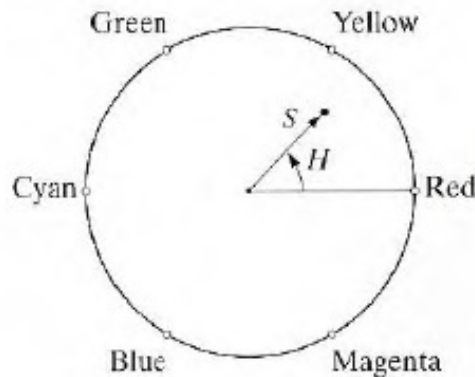
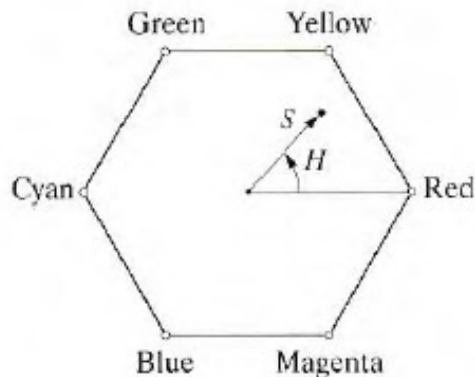
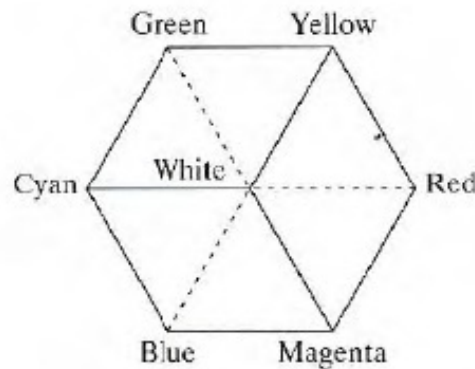
# The HSI Color Model

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- Take the RGB cube, stand on the black vertex, with the white vertex above it.



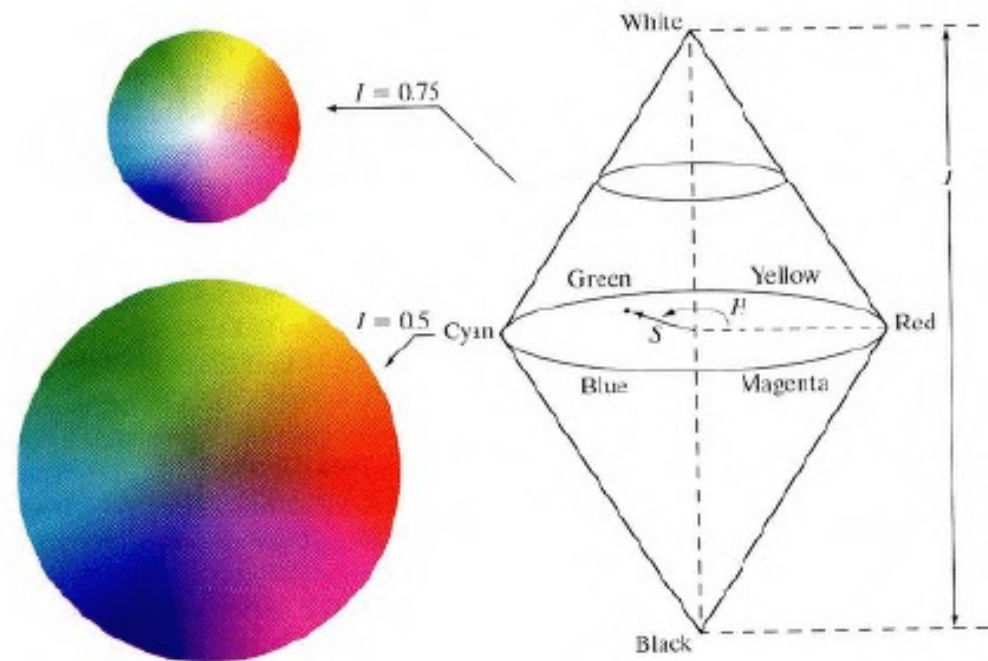
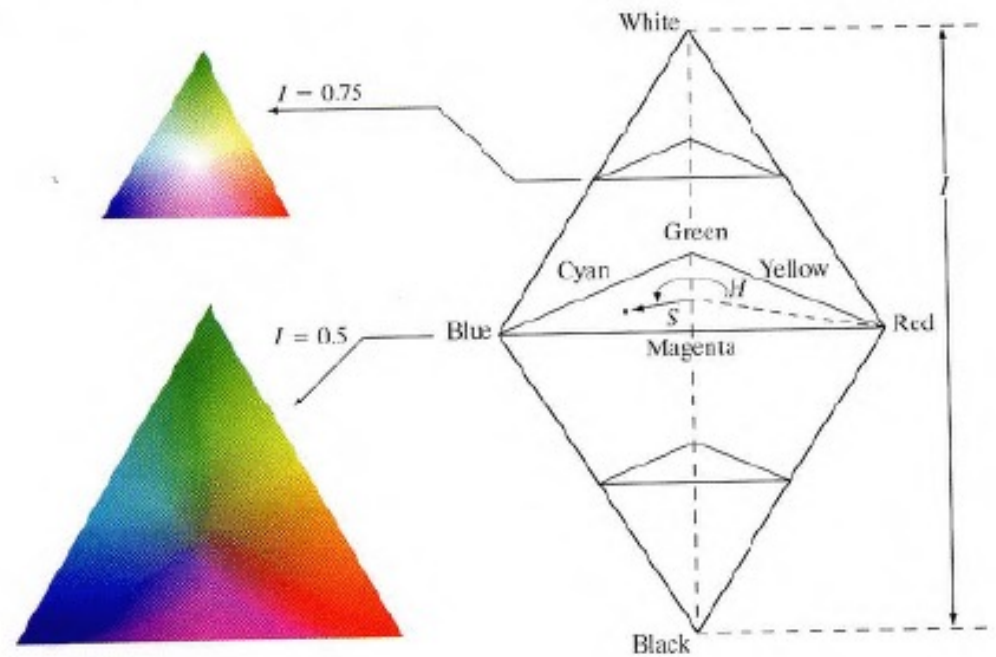
The intensity (gray scale) is along the line joining these two vertices.



# HSI

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- HSI is also known as HSL, HLS
- HSV color space



# Converting colors from RGB to HSI

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Given an image in RGB color format, the  $H$  component of each RGB pixel is obtained using the equation

$$H = \begin{cases} \theta & \text{if } B \leq G \\ 360 - \theta & \text{if } B > G \end{cases} \quad (6.2-2)$$

with

$$\theta = \cos^{-1} \left\{ \frac{\frac{1}{2}[(R - G) + (R - B)]}{[(R - G)^2 + (R - B)(G - B)]^{1/2}} \right\}.$$

The saturation component is given by

$$S = 1 - \frac{3}{(R + G + B)} [\min(R, G, B)]. \quad (6.2-3)$$

Finally, the intensity component is given by

$$I = \frac{1}{3} (R + G + B). \quad (6.2-4)$$

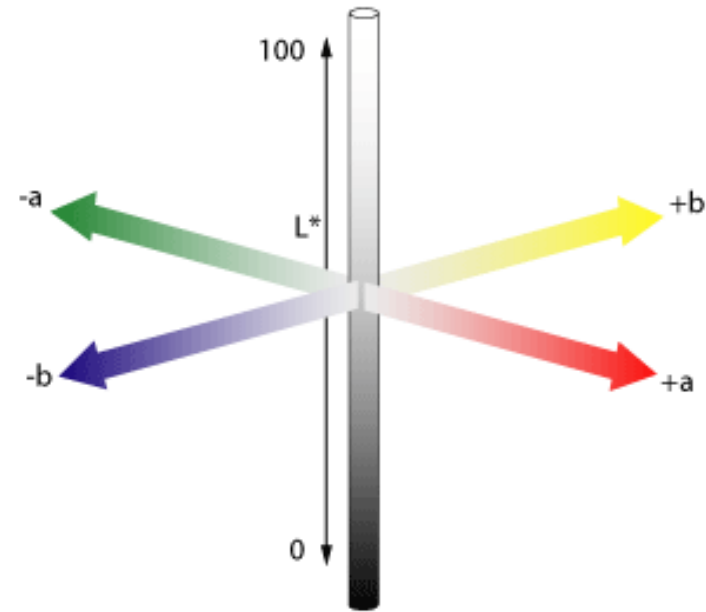
RGB values have been normalized to the range  $[0,1]$

The angle  $\theta$  is measured with respect to the red axis of the HSI space.

# The LAB (CIELAB) Color Models

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- CIELAB ( $L^*a^*b^*$ ) color space
  - $L^*$ : lightness dimension
  - $a^*, b^*$ : two chromatic dimensions that are roughly red-green and blue-yellow.
  - $L^*a^*b^*$  color is designed to approximate human vision



[http://en.wikipedia.org/wiki/Lab\\_color\\_space](http://en.wikipedia.org/wiki/Lab_color_space)

<http://coatings.specialchem.com.cn/tc/color/index.aspx?id=cielab>

# Other Color Models

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- YUV, YIQ, YCbCr color spaces
  - ▣ YCbCr is widely used in video/image compression schemes such as MPEG and JPEG
- Please refer to
  - ▣ [http://en.wikipedia.org/wiki/Color\\_space](http://en.wikipedia.org/wiki/Color_space)

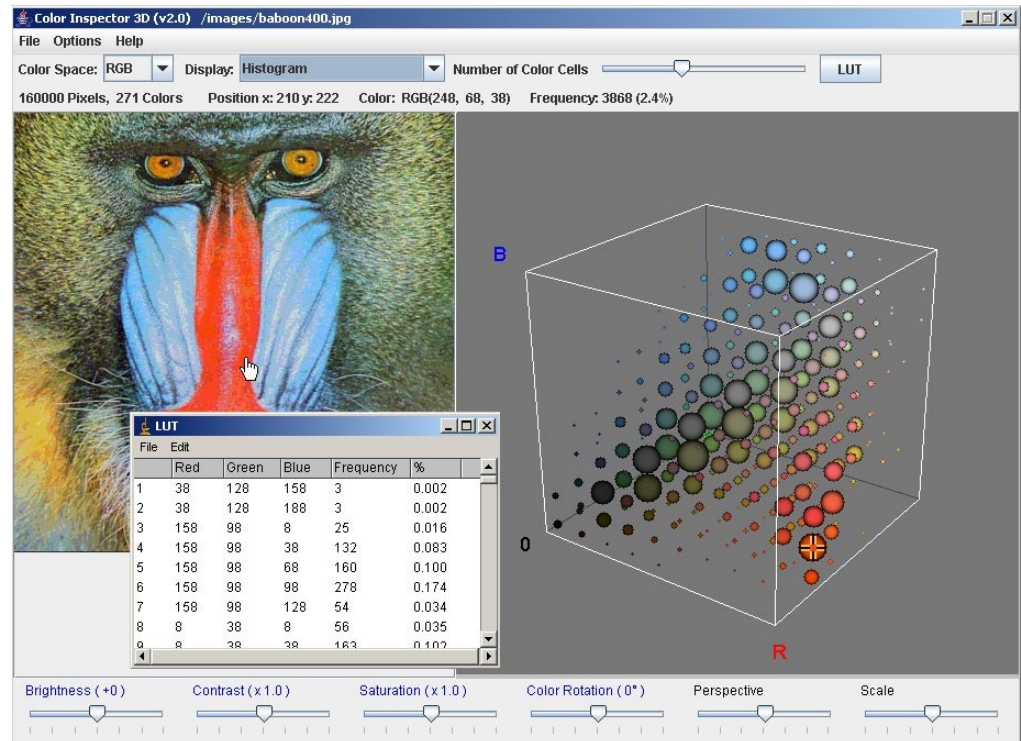
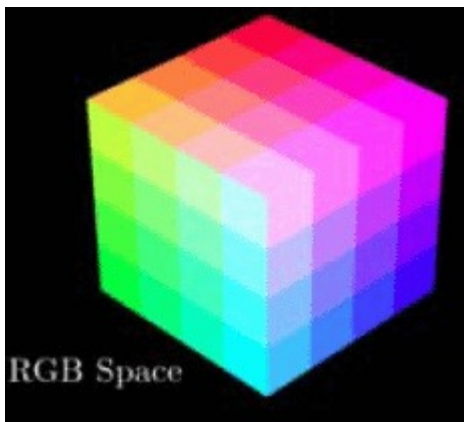


# Color Histogram

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- A representation of the distribution of colors in an image.
- Discretize colors into a number of bins, and counting the number of pixels with colors in each bin.

		red			
		0-63	64-127	128-191	192-255
blue	0-63	43	78	18	0
	64-127	45	67	33	2
	128-191	127	58	25	8
	192-255	140	47	47	13



<http://rsb.info.nih.gov/ij/plugins/color-inspector.html>

# Nonuniform Quantization

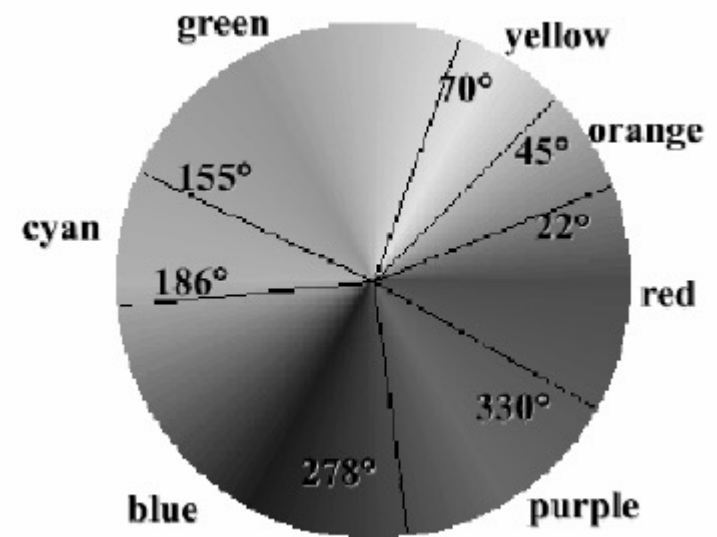
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- An example in HLS (HSI) space
  - ▣ Considering human perception

NUMBER OF QUANTIZATION LEVELS FOR EACH COMPONENT IN THE THREE SUBREGIONS

Regions # of colors	<i>Achromatic</i>			<i>Low chromatic</i>			<i>High Chromatic</i>		
	<i>H</i>	<i>L</i>	<i>S</i>	<i>H</i>	<i>L</i>	<i>S</i>	<i>H</i>	<i>L</i>	<i>S</i>
32	1	4	1	7	3	1	7	1	1

Lee, et al. “Spatial color descriptor for image retrieval and Video summarization”, IEEE Trans. on Multimedia, 2003.



# Characteristics of Histogram

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- The color histogram of an image represents the global statistics (color distribution) of pixels' colors
- Histogram is one of the most useful feature to describe images or be the basis for similarity measure

# Histogram-based Difference

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- Bin-wise histogram difference between Image  $I_1$  and  $I_2$

$$D_j(I_1, I_2) = \sum_{i=1}^B |H_j^1(i) - H_j^2(i)|$$

$$D(I_1, I_2) = w_1 D_1 + w_2 D_2 + w_3 D_3$$

# Short Introduction to Image Features

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- Color features
  - ▣ Color histogram
  - ▣ Color moments
  - ▣ Color coherence vectors (CCV)
  - ▣ Color correlogram

Ma, et al. “Benchmarking image features content-based image retrieval”, Record of the 32nd Asilomar Conf. on Signals, Systems & Computers, vol 1., 1998.

# Short Introduction to Image Features

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- Texture features
  - ▣ Tamura features (coarseness, directionality, contrast)
  - ▣ Multi-resolution simultaneous auto-regressive model
  - ▣ Canny edge histogram
  - ▣ Gabor texture feature
  - ▣ Pyramid-structured wavelet transform (PWT) feature
  - ▣ Tree-structured transform (TWT) feature

Ma, et al. “Benchmarking image features content-based image retrieval”, Record of the 32nd Asilomar Conf. on Signals, Systems & Computers, vol 1., 1998.