OS HW3

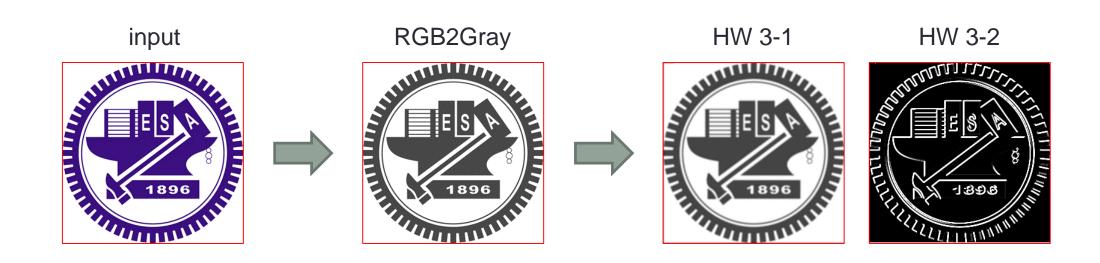
Operating System 106 Fall

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Goal

- Implement image processing by using threads and synchronization.
 - HW 3-1: Blur with Gaussian filter
 - HW 3-2: Edge Detection with Sobel filter



Introduction: Gaussian filter

$$ullet$$
 Gaussian filter: $G(u,v)=rac{1}{2\pi\sigma^2}e^{-(u^2+v^2)/(2\sigma^2)}$

- For convenience, use integer versions.
 - For example:

$$\frac{1}{16} \times \begin{array}{c|cccc}
 & 1 & 2 & 1 \\
 & 2 & 4 & 2 \\
\hline
 & 1 & 2 & 1
\end{array}$$

1	4	7	4	1
4	16	26	16	4
7	26	41	26	7
4	16	26	16	4
1	4	7	4	1

- Gaussian filter is written in "mask_Gaussian.txt"
 - The first number is the filter size
 - The second number is the filter scalar

Introduction: Blur algorithm

- Convert RGB image to grey image:
 - grey(i, j) = (R(i, j)+G(i, j)+B(i, j))/3
- 2. Do Gaussian blur: convolving the grey image with a Gaussian filter.
 - Convolving:

16	32	160	80	16
0	48	112	32	176
0	0	48	16	16
0	8	4	0	96
8	0	4	8	160

11	43	73	64	38
10	44			

- \rightarrow (16*1+32*2+160*1+0*2+48*4+112*2+0*1+0*2+48*1)/16 = 44
- 3. Extend the size of image from HxWx1 to HxWx3 (to save the image)
 - R(i, j) = grey(i, j)
 - G(i, j) = grey(i, j)
 - B(i, j) = grey(i, j)

Introduction: Blur algorithm (cont.)

- Convert RGB image to grey image:
 - grey(i, j) = (R(i, j)+G(i, j)+B(i, j))/3
- 2. Do Gaussian blur: convolving the grey image with a Gaussian filter.
 - Convolving:

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0	48	112	32	176
0	0	48	16	16
0	8	4	0	96
8	0	4	8	160

11	43	73	64	38
10	44	72		

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 - R(i, j) = grey(i, j)
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 - B(i, j) = grey(i, j)

Introduction: Blur algorithm (cont.)

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11	43	73	64	38
10	44	72	71	

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 - R(i, j) = grey(i, j)
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Introduction: Blur algorithm (cont.)

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16	32	160	80	16	
0	48	112	32	176	
0	0	48	16	16	*
0	8	4	0	96	•
8	0	4	8	160	

11	43	73	64	38
10	44	72	71	58

- \rightarrow (80*1+16*2+32*2+176*4+16*1+16*2)/16 = 58
- 3. Extend the size of image from HxWx1 to HxWx3 (to save the image)
 - R(i, j) = grey(i, j)
 - G(i, j) = grey(i, j)
 - B(i, j) = grey(i, j)

Introduction: Sobel filter

- Sobel filter:
 - Gradient of horizontal direction

$$\mathbf{G}_x = \begin{bmatrix} -1 & 0 & +1 \\ -2 & 0 & +2 \\ -1 & 0 & +1 \end{bmatrix}$$

Gradient of vertical direction

$$\mathbf{G}_y = \begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ +1 & +2 & +1 \end{bmatrix}$$

- Sobel filter is written in "mask_Sobel.txt"
 - The first number is the filter size
 - The second line is Gx
 - The third line is Gy
 - Note: the size of Gx and Gy must be the same.

9 1 0 -1 2 0 -2 1 0 -1 -1 -2 -1 0 0 0 1 2 1

Introduction: Edge Detection algorithm

- 1. Convert RGB image to grey image:
 - grey(i, j) = (R(i, j)+G(i, j)+B(i, j))/3
- 2. Convolving the grey image with Gx filter and Gy filter, respectively.
 - → Get image_x and image_y
- 3. Compute:

```
Image(i, j) = sqrt( image_x(i, j)*image_x(i, j) + image_y(i, j)* image_y(i, j) )
```

- 4. Extend the size of image from HxWx1 to HxWx3 (to save the image)
 - R(i, j) = Image(i, j)
 - G(i, j) = Image(i, j)
 - B(i, j) = Image(i, j)

Thread

- Only use:#include <pthread.h>
- Declare: pthread_t thread1, thread2;
- Functions:
 - int pthread_create(pthread_t * thread, const pthread_attr_t * attr, void * (*start_routine)(void *), void *arg);
 - int pthread_join(pthread_t th, void **thread_return);
 - wait for termination of another thread
 - void pthread_exit(void *retval);

Synchronization - mutex lock

- Only use:#include <pthread.h>
- Declare: (global variable)
 pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
- Functions:
 - pthread_mutex_lock()
 - acquire a lock on the specified mutex variable. If the mutex is already locked by another thread, this
 call will block the calling thread until the mutex is unlocked.
 - pthread_mutex_unlock()
 - unlock a mutex variable. An error is returned if mutex is already unlocked or owned by another thread.
 - pthread_mutex_trylock()
 - attempt to lock a mutex or will return error code if busy. Useful for preventing deadlock conditions.

Synchronization - semaphore

- #include <pthread.h>
 - Declare: (global variable)
 pthread_cond_t cond1 = PTHREAD_COND_INITIALIZER;
 - Functions:
 - pthread_cond_wait
 - pthread_cond_signal
 - pthread_cond_broadcast
- #include <semaphore.h>
 - Declare: (global variable) sem_t sem1;
 - Functions:
 - int sem_post(sem_t *);
 - int sem_wait(sem_t *);
 - int sem_close(sem_t *);

Synchronization - semaphore (cont.)

- Only use:#include <pthread.h>#include <semaphore.h>
- Design your method to implement synchronization.
- See details below:
 - <pthread.h>
 http://www.yolinux.com/TUTORIALS/LinuxTutorialPosixThreads.html
 - <semaphore.h>
 http://pubs.opengroup.org/onlinepubs/7908799/xsh/semaphore.h.html

Synchronization

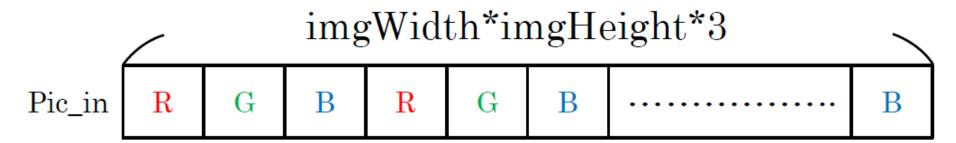
- In HW3, you need use BOTH mutex lock and semaphore.
- And for each part, you must use at least one of them.
- For example:
 - √ HW3-1 with mutex lock, and HW3-2 with semaphore.
 - √ HW3-1 with semaphore, and HW3-2 with mutex lock.
 - ✓ HW3-1 with mutex lock and semaphore, and HW3-2 with mutex lock.
 - OHW3-1 with mutex lock and semaphore, and HW3-2 without them.
 - OHW3-1 with mutex lock, and HW3-2 with mutex lock.

Synchronization (optional)

- Idea about synchronization (you can try other way):
 - Mutex lock:
 - Pthread: p1, p2, p3
 - Zero-matrix: Z (size = HxWx1)
 - p1, p2, p3 do convolve the R,G,B-image with filter, respectively.
 - p1, p2, p3 add their results into Z when doing convolve.
 - Semaphore:
 - Pthread: p1, p2
 - p1: convert RGB image to gray image.
 - p2: do convolve the grey image with filter.
 - After p1 has converted enough pixels (but p1 hasn't finished), p2 start.

Image read & write

- Only use "bmpReader.h" and "bmpReader.cpp" we provide to read or write images. (Don't modify "bmpReader.h" and "bmpReader.cpp".)
- Unsigned char Pic_in[x] array
- Each pixel is represented by three values.
 R G B R G B.....
- Accessing the i-th row, j-th col pixel :
 - pic_in[3*(i*imgWidth+j)+color], color = 0,1,2
- Be careful of the conversion between integer, double (float), and unsigned char.



Input & output format

- Input: 5 BMP images and a mask file
 - Image name: input1.bmp, input2.bmp, input3.bmp, input4.bmp, input5.bmp
 - Mask file name:

HW 3-1: mask_Gaussian.txt

HW 3-2: mask_Sobel.txt

Input location:
 In the same folder with cpp file.

- Output: 5 BMP images for each part
 - Name:

HW 3-1: Blur1.bmp, Blur2.bmp, Blur3.bmp, Blur4.bmp, Blur5.bmp

HW 3-2: Sobel1.bmp, Sobel2.bmp, Sobel3.bmp, Sobel4.bmp, Sobel5.bmp

Output location:
 In the same folder with cpp file.

Score

- 1. Correctness: from 0 to 10 pts for each part
 - Mean Absolute Error: MAE(X,Y) = $\frac{1}{W \cdot H \cdot 3} \Sigma |X(i,j,c) Y(i,j,c)|$, where c=0,1,2
 - If MAE==0, then your output is correct.
 - We will give you "MAE.out". Then you can use it to check the correctness.
 Use the following command:
 ./MAE.out [image 1] [image 2]

```
② □ viplab@viplab: ~

17:43 chungce@linux1 [~/106_0S/hw3/test] >./MAE.out ANS/Blur1.bmp Blur1.bmp

MAE = 0

17:44 chungce@linux1 [~/106_0S/hw3/test] >
```

• If you get "Permission denied" (拒絕不符權限操作), use the following command: chmod +x MAE.out

Score (cont.)

- 2. Speed: from 0 to 40 pts for each part
 - We will provide "example_hw3-1.cpp", which doesn't use multithread programming and synchronized, as a speed baseline.
 - We will give you "Speed.sh".
 Use the following command: sh Speed.sh

	HW3-1	HW3-2
Baseline	1544042 µs	1430390 µs
filter size	5*5	3*3

⊗ □ viplab@viplab: ~	
17:44 chungce@linux1 [~/106_OS/hw3/test] >g++ -std=c++11 -pthr 17:45 chungce@linux1 [~/106_OS/hw3/test] >sh Speed.sh Input a number of times to run './a.out' : 10	ead example_hw3-1.cpp
Run time: Finished once. Avg time: 1544042 µs 17:45 chungce@linux1 [~/106_0S/hw3/test] >	

Speedup	HW3-1	HW3-2
< 0.9	0	0
0.9~1.1	0	20
1.1~1.5	20	25
1.5~2	30	30
2~3	35	35
> 3	40	40

*This is a provisional standard table, we may modify after checking all students' HW3.

We will use it to compute your average run time. (Input = 10 fixed.)

Score (cont.)

- 3. Report (20 pts):
 - Format is in "report.docx"
 - Written in English or Chinese, up to 2 pages
- 4. Final score (Total 100 pts):
 Speed score 1 * Correctness score 1 /10 +
 Speed score 2 * Correctness score 2 /10 +
 Report score

5. Others:

- Must use thread, mutex lock and semaphore. (otherwise -10pts)
- Use other library NOT in "example_hw3-1.cpp": will get 0pt directly
- Wrong input/output format: -10pts
- Wrong hand-in file name: -10pts
- Copy or be copied: will get 0pt directly

```
(you only can use these library)
"example_hw3-1.cpp":
#include "bmpReader.h"
#include "bmpReader.cpp"
#include <stdio.h>
#include <iostream>
#include <math.h>
#include <pthread.h>
#include <semaphore.h>
using namespace std;
```

Requirements

- Use NCTU CS Workstation linux1~linux6 as your programming environment.
 (No bsd1~bsd6)
- We only use these commends on NCTU CS Workstation linux2:
 - g++ -std=c++11 -pthread StudentID_hw3-1.cpp
 - g++ -std=c++11 -pthread StudentID_hw3-2.cpp
 - ./a.out↑ no argument
- Put the 3 files into a compressed file named "StudentID_OS_hw3.zip"
 - StudentID_hw3-1.cpp
 - StudentID_hw3-2.cpp
 - report.docx (or report.pdf)
- Deadline: 2017/12/02 (Saturday) 23:59