NIp 66

Sentiment Analysis for IMDB Movie Reviews

This assignment will work with the Large Movie Review Dataset and provide an understanding of how Deep Learning is used within the field of Natural Language Processing (NLP). The original paper published in 2011 discussing the dataset and a wide variety of techniques can be found here. We will train models to detect the sentiment of written text. More specifically, we will try to feed a movie review into a model and have it predict whether it is a positive or negative movie review.

The assignment starts off with how to preprocess the dataset into a more appropriate format followed by three main parts. Each part will involve training different types of models and will detail what you need to do as well as what needs to be turned in. The assignment is meant to provide you with a working knowledge of how to use neural networks with sequential data.

- Part one deals with training basic Bag of Words models.
- Part two will start incoporating temporal information by using LSTM layers.
- Part three will show how to train a language model and how doing this as a first step can sometimes improve results for other tasks

Make a new directory for yourself on BlueWaters. Do everything within this directory and this will ultimately contain most of what you need to turn in.

I'm not directly providing you with any finished python files. This is written more like a tutorial with excerpts of code scattered throughout. You will have to take these pieces of code, combine them, edit them, add to them, etc. and figure out how to run them on BlueWaters. You will also need to change a variety of hyperparameters and run them multiple times.

What to Turn In

Make a copy of the google sheet here. This is how you should summarize your results. Write a sentence or two for each model you train in parts 1a, 1b, 2a, 2b, and 3c. For part 3a, the assignment only requires you to train the model with the hyperparamters I give you. For part 3b, you will generate fake movie reviews (I've included a fake movie review I generated as an example).

Zip all of your code (excluding the dataset/preprocessed data/trained PyTorch models). Save your completed google sheet as a PDF. Submit the code and PDF on compass.

Some Basic Terminology

One-hot vector - Mathematically speaking, a one-hot vector is a vector of all zeros except for one element containing a one. There are many applications but they are of particular importance in natural language processing. It is a method of encoding categorical variables (such as words or characters) as numerical vectors which become the input to computational models.

Suppose we want to train a model to predict the sentiment of the following two sentences: "This movie is bad" and "This movie is good". We need a way of mathematically representing these as inputs to the model. First we define a dictionary (or vocabulary). This contains every word contained within the dataset.

```
vocab = ['this','movie','is','bad','good']
```

We can also add an "unknown token" to the dictionary in case words not present in the training dataset show up during testing.

```
unknown = ''
vocab = [unknown, 'this', 'movie', 'is', 'bad', 'good']
```

```
[0,1,0,0,0,0] # this
[0,0,1,0,0,0] # movie
[0,0,0,1,0,0] # is
[0,0,0,0,0,1] # good
```

There are many ways this data can be used. This assignment deals with two possibilities. These vectors could be processed one at a time (which is the basis of sections 2 and 3 of this assignment) by using a recurrent neural network or the full review could be processed all at once using a bag of words representation (section 1 of this assignment). The bag of words representation simply sums up the one-hot vectors and has a single vector input for each review. This is convenient for reducing the input size and making variable length reviews fixed length (all reviews become a single vector of length —vöcab—) but the input no longer contains sequence information. The order in which the words appear has no effect on a document's bag of words representation.

```
x1=[0,1,1,1,0,1] # bag of words for "this movie is good" x2=[0,1,1,1,1,0] # bag of words for "this movie is bad"
```

```
# model would successfully classify the unseen test sequence as negative x=[7,0,0,0,1,0] # bag of words for "I have never seen such a bad film" # model would incorrectly classify the unseen test sequence as negative x=[10,1,1,1,1,0] # bag of words for "This movie is not bad. In fact, I think it's great.
```

Word Embedding - The one-hot encoding is useful but notice the input size depends heavily on the vocabulary size which can cause problems considering there are millions of tokens in the English language. Additionally, many of these tokens are related to eachother in some way (like the words "good" and "great") and this relationship is not captured by the one-hot encoding. Word embeddings are another vector representation of fixed length (for example, length 300 is common) where the elements are real valued as opposed to just 1 or 0. Typically these word embeddings are generated from a language model which is the basis of part 3 of this assignment. Word2vec and GloVe are examples of word embeddings.

Preprocessing the Data

The IMDB dataset is located within the class directory under '/projects/training/bauh/NLP/aclImdb/'. Each review is contained in a separate .txt file and organized into separate directories depending on if they're positive/negative or part of the train/test/unlabeled splits. It's easier to re-work the data before training any models for multiple reasons.

- It's faster to combine everything into fewer files.
- We need to tokenize the dataset (split long strings up into individual words/symbols).
- We need to know how many unique tokens there are to decide on our vocabulary/model size.
- We don't want to constantly be converting strings to token IDs within the training loop (takes non-negligible amount of time).
- Storing everything as token IDs directly leads to the 1-hot representation necessary for input into our model.

The NLTK (Natural Language Toolkit) python package contains a tokenizer that we will use and needs to be installed.

```
pip install --user nltk 66
```

Within your assignment directory, create a file called preprocess_data.py.

```
import numpy as np
import os
import nltk
import itertools
import io

## create directory to store preprocessed data
if(not os.path.isdir('preprocessed_data')):
    os.mkdir('preprocessed_data')
```

These few lines of code written above import a few packages and creates a new directory if it's not already made.

```
## get all of the training reviews (including unlabeled reviews)
train_directory = '/projects/training/bauh/NLP/aclImdb/train/'
pos_filenames = os.listdir(train_directory + 'pos/')
neg_filenames = os.listdir(train_directory + 'neg/')
unsup_filenames = os.listdir(train_directory + 'unsup/')
pos_filenames = [train_directory+'pos/'+filename for filename in pos_filenames]
neg filenames = [train directory+'neg/'+filename for filename in neg filenames]
unsup_filenames = [train_directory+'unsup/'+filename for filename in unsup_filenames]
filenames = pos_filenames + neg_filenames + unsup_filenames
count = 0
x_{train} = []
for filename in filenames:
    with io.open(filename, 'r', encoding='utf-8') as f:
        line = f.readlines()[0]
    line = line.replace('<br />',' ')
    line = line.replace('\x96',' ')
    line = nltk.word_tokenize(line)
    line = [w.lower() for w in line]
    x_train.append(line)
    count += 1
    print(count)
```

The top part of the code simply results in a list of every text file containing a movie review in the variable filenames. The first 12500 are positive reviews, the next 12500 are negative reviews, and the remaining are unlabeled reviews. For each review, we remove text we don't want (' and '\x96'), tokenize the string using the nltk package, and make everything lowercase. Here is an example movie review before and after tokenization:

```
own stagy terms. Earle (Palance), fresh out of the pen near Chicago, drives west to spear aney', ',', 'jr.', 'knocking', 'over', 'a', 'post', 'mountain', 'resort', '.', 'en', 'rout
```

Notice how symbols like periods, parenthesis, etc. become their own tokens and it splits up contractions ("it's" becomes "it" and "'s"). It's not perfect and can be ruined by typos or lack of punctuation but works for the most part. We now have a list of tokens for every review in the training dataset in the variable x_{train} . We can do the same thing for the test dataset and the variable x_{train} .

```
## get all of the test reviews
test_directory = '/projects/training/bauh/NLP/aclImdb/test/'
pos_filenames = os.listdir(test_directory + 'pos/')
neg_filenames = os.listdir(test_directory + 'neg/')
pos_filenames = [test_directory+'pos/'+filename for filename in pos_filenames]
neg_filenames = [test_directory+'neg/'+filename for filename in neg_filenames]
filenames = pos_filenames+neg_filenames
count = 0
x_{test} = []
for filename in filenames:
    with io.open(filename, 'r', encoding='utf-8') as f:
        line = f.readlines()[0]
    line = line.replace('<br />',' ')
    line = line.replace('\x96',' ')
    line = nltk.word_tokenize(line)
    line = [w.lower() for w in line]
    x_test.append(line)
    count += 1
    print(count)
```

We can use the following to get a basic understanding what the IMDB dataset contains.

```
## number of tokens per review
no_of_tokens = []
for tokens in x_train:
    no_of_tokens.append(len(tokens))
no_of_tokens = np.asarray(no_of_tokens)
print('Total: ', np.sum(no_of_tokens), ' Min: ', np.min(no_of_tokens), ' Max: ', np.max(
```

Total: 20090526 Min: 10 Max: 2859 Mean: 267.87368 Std: 198.540647165

The mean review contains ~267 tokens with a standard deviation of ~200. Although there are over 20 million total tokens, they're obviously not all unique. We now want to build our dictionary/vocabulary.

```
### word_to_id and id_to_word. associate an id to every unique token in the training dat
all_tokens = itertools.chain.from_iterable(x_train)
word_to_id = {token: idx for idx, token in enumerate(set(all_tokens))}
all_tokens = itertools.chain.from_iterable(x_train)
id_to_word = [token for idx, token in enumerate(set(all_tokens))]
id_to_word = np.asarray(id_to_word)
```

We have two more variables: word_to_id and id_to_word. You can access id_to_word[index] to find out the token for a given index or access word_to_id[token] to find out the index for a given token. They'll both be used later on. We can also see there are roughly 200,000 unique tokens with len(id_to_word). Realistically, we don't want to use all 200k unique tokens. An embedding layer with 200k tokens and 500 outputs has 100 million weights which is far too many considering the training dataset only has 20 million tokens total. Additionally, the tokenizer sometimes creates a unique token that is actually just a combination of other tokens because of typos and other odd things. Here are a few examples from id_to_word ("majesty.these", "producer/director/star", "1¢")

We should organize the tokens by their frequency in the dataset to give us a better idea of choosing our vocabulary size.

```
## let's sort the indices by word frequency instead of random
x_train_token_ids = [[word_to_id[token] for token in x] for x in x_train]
count = np.zeros(id_to_word.shape)
for x in x_train_token_ids:
    for token in x:
        count[token] += 1
```

```
indices = np.argsort(-count)
id_to_word = id_to_word[indices]
count = count[indices]

hist = np.histogram(count,bins=[1,10,100,1000,10000])
print(hist)
for i in range(10):
    print(id_to_word[i],count[i])
```

Notice we used word_to_id to convert all of the tokens for each review into a sequence of token IDs instead (this is ultimately what we are going for but we want the IDs to be in a different order). We then accumulate the total number of occurrences for each word in the array count . Finally, this is used to sort the vocabulary list. We are left with id_to_word in order from most frequent tokens to the least frequent, word_to_id gives us the index for each token, and count simply contains the number of occurrences for each token.

```
(array([164036, 26990, 7825, 1367]), array([ 1, 10, 100, 10000]))
the 1009387
, 829574
. 819080
and 491830
a 488305
of 438545
to 405661
is 330904
it 285710
in 280618
```

The histogram output gives us a better understanding of the actual dataset. Over 80% (~160k) of the unique tokens occur between 1 and 10 times while only ~5% occur more than 100 times each. Using np.sum(count[0:100]) tells us over half of all of the 20 million tokens are the most common 100 words and np.sum(count[0:8000]) tells us almost 95% of the dataset is contained within the most common 8000 words.

```
## recreate word_to_id based on sorted list
word_to_id = {token: idx for idx, token in enumerate(id_to_word)}

## assign -1 if token doesn't appear in our dictionary
## add +1 to all token ids, we went to reserve id=0 for an unknown token
x_train_token_ids = [[word_to_id.get(token,-1)+1 for token in x] for x in x_train]
x_test_token_ids = [[word_to_id.get(token,-1)+1 for token in x] for x in x_test]
```

Here is where we convert everything to the exact format we want for training purposes. Notice the test dataset may have unique tokens our model has never seen before. We can anticipate this ahead of time by actually reserving index 0 for an unknown token. This is why I assign a -1 if the token isn't part of word_to_id and add +1 to every id. Just be aware of this that id_to_word is now off by 1 index if you actually want to convert ids to words.

We could also decide later on if we only want to use a vocabulary size of 8000 for training and just assign any other token ID in the training data to 0. This way it can develop its own embedding for unknown tokens which can help out when it inevitably sees unknown tokens during testing.

Here is the same review posted earlier. One uses the full dictionary and the other replaces the less frequent tokens with the unknown token:

[727	1203	844	85	23503	8	156	2	351	17
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3	44	30	4381	4	819	2	3430	4	212
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5009	14	337	10898	3188	164	313	215	50604	5
372	48	5	2147	2	4	397	44	17	637
12385	5	25011	48	119	204	1	7427	43	13
10	1	214	3	23	304	6	5009	80	92
5002	185207	2	18	5281	2982	80	92	668	6463
2	18	12795	10997	5805	6830	2	4	44	27
204	155	1	893	3	22	1	73	634	8

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```

To finish up, we save our token id based reviews to text files and save our dictionary in case we ever need a conversion of ID back to text.

```
## save dictionary
np.save('preprocessed_data/imdb_dictionary.npy',np.asarray(id_to_word))

## save training data to single text file
with io.open('preprocessed_data/imdb_train.txt','w',encoding='utf-8') as f:
    for tokens in x_train_token_ids:
        for token in tokens:
            f.write("%i " % token)
            f.write("\n")

## save test data to single text file
with io.open('preprocessed_data/imdb_test.txt','w',encoding='utf-8') as f:
```

```
for tokens in x_test_token_ids:
    for token in tokens:
        f.write("%i " % token)
    f.write("\n")
```

GloVe Features

The GloVe features already provide a text file with a 300 dimensional word embedding for over 2 million tokens. This dictionary is sorted by word frequency as well but for a different dataset. Therefore, we still need to have some way of using the IMDB dataset with their dictionary. Continue adding this code to preprocess_data.py

```
glove_filename = '/projects/training/bauh/NLP/glove.840B.300d.txt'
with io.open(glove_filename, 'r', encoding='utf-8') as f:
    lines = f.readlines()
glove_dictionary = []
glove_embeddings = []
count = 0
for line in lines:
    line = line.strip()
    line = line.split(' ')
    glove dictionary.append(line[0])
    embedding = np.asarray(line[1:],dtype=np.float)
    glove_embeddings.append(embedding)
    count+=1
    if(count>=100000):
        break
glove_dictionary = np.asarray(glove_dictionary)
glove_embeddings = np.asarray(glove_embeddings)
# added a vector of zeros for the unknown tokens
glove_embeddings = np.concatenate((np.zeros((1,300)),glove_embeddings))
```

We have two new arrays glove_dictionary and glove_embeddings. The first is the same as id_to_word but a different order and glove_embeddings contain the actual embeddings for each token. To save space, only the first 100k tokens are kept. Also, notice a 300 dimensional vector of 0s is prepended to the array of embeddings to be used for the unknown token.

```
word_to_id = {token: idx for idx, token in enumerate(glove_dictionary)}

x_train_token_ids = [[word_to_id.get(token,-1)+1 for token in x] for x in x_train]
x_test_token_ids = [[word_to_id.get(token,-1)+1 for token in x] for x in x_test]
```

We do exactly what we did before but with this new GloVe dictionary and finally save the data in the new format.

```
np.save('preprocessed_data/glove_dictionary.npy',glove_dictionary)
np.save('preprocessed_data/glove_embeddings.npy',glove_embeddings)

with io.open('preprocessed_data/imdb_train_glove.txt','w',encoding='utf-8') as f:
    for tokens in x_train_token_ids:
        for token in tokens:
            f.write("%i " % token)
        f.write("\n")

with io.open('preprocessed_data/imdb_test_glove.txt','w',encoding='utf-8') as f:
    for tokens in x_test_token_ids:
        for token in tokens:
            f.write("%i " % token)
        f.write("\n")
```

Part 1 - Bag of Words

A bag of words model is one of the most basic models for document classification. It is a way of handling varying length inputs (sequence of token ids) to get a single output (positive or negative sentiment).

The token IDs can be thought of as an alternative representation of a 1-hot vector. A word embedding layer is usually a **d by V** matrix where **V** is the size of the vocabulary and **d** is the embedding size. Multiplying a 1-hot vector (of length **V**) by this matrix results in a **d** dimensional embedding for a particular token. We can avoid this matrix multiplication by simply taking the column of the word embedding matrix corresponding with that particular token.

A word embedding matrix doesn't tell you how to handle the sequence information. In this case, you can picture the bag of words as simply taking the mean of all of the 1-hot vectors for the entire sequence and then multiplying this by the word embedding matrix to get a document embedding. Alternatively, you can take the mean of all of the word embeddings for each token and get the same document embedding. Now we are left with a single **d** dimensional input representing the entire sequence.

Note that the bag of words method utilizes all of the tokens in the sequence but loses all of the information about when the tokens appear within the sequence. Obviously the order of words carries a significant portion of the information contained within written text but this technique still works out rather well.

Create a new directory '1a/' within your assignment directory. You will create two python files, BOW_model.py and BOW_sentiment_analysis.py. The first is where we will define our bag of words pytorch model and the second will contain the train/test loops.

BOW_model.py

```
import numpy as np
import torch
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
from torch.autograd import Variable
import torch.distributed as dist

class BOW_model(nn.Module):
    def __init__(self, vocab_size, no_of_hidden_units):
        super(BOW_model, self).__init__()
        ## will need to define model architecture

def forward(self, x, t):
    # will need to define forward function for when model gets called
```

The inputs for defining our model object are vocab_size and no_of_hidden_units (we can decide on actual values for these later). We will need to define an embedding layer, a single hidden layer with batch normalization, an output layer, a dropout layer, and the loss function.

```
def __init__(self, vocab_size, no_of_hidden_units):
    super(BOW_model, self).__init__()

    self.embedding = nn.Embedding(vocab_size,no_of_hidden_units)

    self.fc_hidden = nn.Linear(no_of_hidden_units,no_of_hidden_units)
    self.bn_hidden = nn.BatchNorm1d(no_of_hidden_units)
    self.dropout = torch.nn.Dropout(p=0.5)

    self.fc_output = nn.Linear(no_of_hidden_units, 1)

    self.loss = nn.BCEWithLogitsLoss()
```

Mathematically speaking, there is nothing unique about a word embedding layer. It's a matrix multiplication with a bias term. A word embedding layer actually has the exact same number of weights as a linear layer. The difference comes down to the PyTorch implementation. The input to the embedding layer is just an index while a linear layer requires an appropriately sized vector. We could use a linear layer if we wanted but we'd have to convert our token IDs to a bunch of 1-hot vectors and

do a lot of unnecessary matrix multiplication since most of the entries are 0. As mentioned above, a matrix multiplying a 1-hot vector is the same as just extracting a single column of the matrix, which is a lot faster. Embedding layers are used frequently in NLP since the input is almost always a 1-hot representation.

Even though you will never explicitly see a 1-hot vector in the code, it is very useful intuitively to view the input as a 1-hot vector.

```
def forward(self, x, t):
    bow_embedding = []
    for i in range(len(x)):
        lookup_tensor = Variable(torch.LongTensor(x[i])).cuda()
        embed = self.embedding(lookup_tensor)
        embed = embed.mean(dim=0)
        bow_embedding.append(embed)
    bow_embedding = torch.stack(bow_embedding)

h = self.dropout(F.relu(self.bn_hidden(self.fc_hidden(bow_embedding))))
h = self.fc_output(h)

return self.loss(h[:,0],t), h[:,0]
```

When we call our model, we will need to provide it with an input \times and target labels t.

This implementation is not typical in the sense that a föř Íööp is used for the embedding layer as opposed to the more typical batch processing. Assume the input \times is a list of length batch_size and each element of this list is a numpy array containing the token ids for a particular sequence. These sequences are different length which is why \times is not simply a torch tensor of size batch_size by sequence_length. Within the loop, the lookup_tensor is a single sequence of token ids which can be fed into the embedding layer. This returns a torch tensor of length sequence_length by embedding_size. We take the mean over the dimension corresponding to the sequence length and append it to the list bow_embedding. This mean operation is considered the bag of words. Note this operation returns the same vector embed regardless of how the token ids were ordered in the lookup_tensor.

The torch.stack() operation is a simple way of converting a list of torch tensors of length embedding_size to a single torch tensor of length batch_size by embedding_size. The bow_embedding is passed through a linear layer, a batch normalization layer, a ReLU operation, and dropout.

Our output layer has only one output even though there are two classes for sentiment (positive and negative). We could've had a separate output for each class but I actually saw an improvement of around 1-2% by using the nn.BCEWithLogitsLoss() (binary cross entropy with logits loss) as opposed to the usual nn.CrossEntropyLoss() you usually see with multi-class classification problems.

Note that two values are returned, the loss and the logit score. The logit score can be converted to an actual probability by passing it through the sigmoid function or it can be viewed as any score greater than 0 is considered positive sentiment. The actual training loop ultimately determines what will be done with these two returned values.

BOW_sentiment_analysis.py

This is the file you'll actually run for training the model.

```
import numpy as np
import torch
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
from torch.autograd import Variable
import torch.distributed as dist
import time
import os
import sys
```

```
import io
from BOW_model import BOW_model
```

Import all of the basic packages we need as well our BOW_model we defined previously.

```
#imdb_dictionary = np.load('../preprocessed_data/imdb_dictionary.npy')
vocab_size = 8000

x_train = []
with io.open('../preprocessed_data/imdb_train.txt','r',encoding='utf-8') as f:
    lines = f.readlines()
for line in lines:
    line = line.strip()
    line = line.split(' ')
    line = np.asarray(line,dtype=np.int)

line[line>vocab_size] = 0

x_train.append(line)
x_train = x_train[0:25000]
y_train = np.zeros((25000,))
y_train[0:12500] = 1
```

Here is where we can much more quickly load in our data one time in the exact format we need. We can also choose our dictionary size at this point. I suggest starting out with 8000 as it was shown earlier (in the preprocessing data section) how this greatly reduces the number of weights in the word embedding layer without ignoring too many unique tokens within the actual dataset. Note that each line within our imdb_train.txt file is a single review made up of token ids. We can convert any token id greater than the dictionary size to the unknown token ID 0. Remember also we actually had 75,000 total training files but only the first 25,000 are labeled (we will use the unlabeled data in part 3). The last three lines of code just grab the first 25,000 sequences and creates a vector for the labels (the first 125000 are labeled 1 for positive and the last 12500 are labeled 0 for negative).

```
x_test = []
with io.open('../preprocessed_data/imdb_test.txt','r',encoding='utf-8') as f:
    lines = f.readlines()
for line in lines:
    line = line.strip()
    line = line.split(' ')
    line = np.asarray(line,dtype=np.int)

line[line>vocab_size] = 0

x_test.append(line)
y_test = np.zeros((25000,))
y_test[0:12500] = 1
```

Do the same for the test dataset.

```
vocab_size += 1
model = BOW_model(vocab_size,500)
model.cuda()
```

Here we actually define the model with no_of_hidden_units equal to 500. Note I added 1 to vocab_size. Remember we actually added 1 to all of the token ids so we could use id 0 for the unknown token. The code above kept tokens 1 through 8000 as well as 0 meaning the vocab_size is actually 8001.

```
# opt = 'sgd'
# LR = 0.01
opt = 'adam'
LR = 0.001
if(opt=='adam'):
    optimizer = optim.Adam(model.parameters(), lr=LR)
```

```
elif(opt=='sgd'):
    optimizer = optim.SGD(model.parameters(), lr=LR, momentum=0.9)
```

Define the optimizer with some desired learning rate.

```
batch_size = 200
no_of_epochs = 6
L_Y_train = len(y_train)
L_Y_test = len(y_test)

model.train()

train_loss = []
train_accu = []
test_accu = []
```

Define some parameters such as the batch_size and no_of_epochs . Put the model in training mode (this allows batch normalization to work correctly as well as dropout). Create a few lists to store any variables of interest.

```
for epoch in range(no_of_epochs):
    # training
    model.train()
    epoch_acc = 0.0
    epoch_loss = 0.0
    epoch_counter = 0
    time1 = time.time()
    I_permutation = np.random.permutation(L_Y_train)
    for i in range(0, L_Y_train, batch_size):
        x_input = [x_train[j] for j in I_permutation[i:i+batch_size]]
        y_input = np.asarray([y_train[j] for j in I_permutation[i:i+batch_size]],dtype=n
        target = Variable(torch.FloatTensor(y_input)).cuda()
        optimizer.zero_grad()
        loss, pred = model(x_input, target)
        loss.backward()
        optimizer.step()
                          # update weights
        prediction = pred >= 0.0
        truth = target >= 0.5
        acc = prediction.eq(truth).sum().cpu().data.numpy()
        epoch_acc += acc
        epoch_loss += loss.data.item()
        epoch_counter += batch_size
    epoch_acc /= epoch_counter
    epoch_loss /= (epoch_counter/batch_size)
    train_loss.append(epoch_loss)
    train_accu.append(epoch_acc)
    print(epoch, "%.2f" % (epoch_acc*100.0), "%.4f" % epoch_loss, "%.4f" % float(time.ti
    # ## test
    model.eval()
    epoch_acc = 0.0
    epoch_loss = 0.0
    epoch_counter = 0
    time1 = time.time()
    I_permutation = np.random.permutation(L_Y_test)
```

```
for i in range(0, L Y test, batch size):
        x_input = [x_test[j] for j in I_permutation[i:i+batch_size]]
        y_input = np.asarray([y_test[j] for j in I_permutation[i:i+batch_size]],dtype=nc
        target = Variable(torch.FloatTensor(y_input)).cuda()
        with torch.no_grad():
            loss, pred = model(x_input, target)
        prediction = pred >= 0.0
        truth = target >= 0.5
        acc = prediction.eq(truth).sum().cpu().data.numpy()
        epoch_acc += acc
        epoch_loss += loss.data.item()
        epoch_counter += batch_size
    epoch_acc /= epoch_counter
    epoch_loss /= (epoch_counter/batch_size)
    test_accu.append(epoch_acc)
    time2 = time.time()
    time_elapsed = time2 - time1
    print(" ", "%.2f" % (epoch_acc*100.0), "%.4f" % epoch_loss)
torch.save(model, 'BOW.model')
data = [train_loss,train_accu,test_accu]
data = np.asarray(data)
```

There is nothing particularly unique about this training loop compared to what you've seen in the past and it should be pretty self explanatory. The only interesting part is the variable x_input we send to the model is not actually a torch tensor at this moment. It's simply a list of lists containing the token ids. Remember that this is dealt with in the BOW_model.forward() function.

With the current hyperparameters I've provided, this model should achieve around 86%-88% on the test dataset. If you check the original paper that came out with this dataset back in 2011, you'll see this model performs just as well as nearly all of the techniques shown on page 7.

This should only take about 15-30 minutes to train. Report results for this model as well as at least two other trials (run more but only report on two interesting cases). Try to get a model that overfits (high accuracy on training data, lower on testing data) as well as one that underfits (low accuracy on both). Overfitting is easily achieved by greatly increasing the no_of_hidden_units, removing dropout, adding a second or third hidden layer in BOW_model.py as well as a few other things. Underfitting can be easily done by using significantly less hidden units.

Other things to consider:

np.save('data.npy',data)

- Early stopping notice how sometimes the test performance will actually get worse the longer you train
- Longer training this might be necessary depending on the choice of hyperparameters
- Learning rate schedule after a certain number of iterations or once test performance stops increasing, try reducing the learning rate by some factor
- Larger models may take up too much memory meaning you may need to reduce the batch size
- Play with the dictionary size see if there is any difference utilizing a large portion of the dictionary (like 100k) compared to very few words (500)
- You could try removing stop words, nltk.corpus.stopwords.words('english') returns a list of stop words. You can find their corresponding index using the imdb_dictionary and convert any of these to 0 when loading the data into x_train (remember to add 1 to the index to compensate for the unknown token)
- Try SGD optimizer instead of adam. This might take more epochs. Sometimes a well tuned SGD with momentum performs better

Try to develop a basic intuition for selecting these parameters yourself and see how big of an effect you can have on the performance. There are four more vastly different models you will train

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throughout the rest of this assignment and this intuition will help.

1b - Using GloVe Features

We will now train another bag of words model but use the pre-trained GloVe features in place of the word embedding layer from before. Typically by leveraging larger datasets and regularization techniques, overfitting can be reduced. The GloVe features were pretrained on over 840 billion tokens. Our training dataset contains 20 million tokens and $^2/_3$ of the 20 million tokens are part of the unlabeled reviews which weren't used in part 1a. The GloVe dataset is over 100 thousand times larger.

The hope is then that these 300 dimensional GloVe features already contain a significant amount of useful information since they were pre-trained on such a large dataset and that will improve performance for our sentiment classification.

Create a directory '1b/'. I would go ahead and copy **BOW_model.py** and **BOW_sentiment_analysis.py** from part 1a here as most of the code is the same.

BOW_model.py

```
class BOW_model(nn.Module):
    def __init__(self, no_of_hidden_units):
        super(BOW_model, self).__init__()
        self.fc_hidden1 = nn.Linear(300,no_of_hidden_units)
        self.bn_hidden1 = nn.BatchNorm1d(no_of_hidden_units)
        self.dropout1 = torch.nn.Dropout(p=0.5)
        # self.fc_hidden2 = nn.Linear(no_of_hidden_units,no_of_hidden_units)
        # self.bn_hidden2 = nn.BatchNorm1d(no_of_hidden_units)
        # self.dropout2 = torch.nn.Dropout(p=0.5)
        self.fc_output = nn.Linear(no_of_hidden_units, 1)
        self.loss = nn.BCEWithLogitsLoss()
    def forward(self, x, t):
        h = self.dropout1(F.relu(self.bn_hidden1(self.fc_hidden1(x))))
        # h = self.dropout2(F.relu(self.bn_hidden2(self.fc_hidden2(h))))
        h = self.fc_output(h)
        return self.loss(h[:,0],t), h[:,0]
```

This is actually simpler than part 1a considering it doesn't need to do anything for the embedding layer. We know the input x will be a torch tensor of batch_size by 300 (the mean GloVe features over an entire sequence).

BOW_sentiment_analysis.py

```
glove_embeddings = np.load('../preprocessed_data/glove_embeddings.npy')
vocab\_size = 100000
x_{train} = []
with io.open('../preprocessed_data/imdb_train_glove.txt','r',encoding='utf-8') as f:
    lines = f.readlines()
for line in lines:
    line = line.strip()
    line = line.split(' ')
    line = np.asarray(line,dtype=np.int)
    line[line>vocab_size] = 0
    line = line[line!=0]
    line = np.mean(glove_embeddings[line],axis=0)
    x_train.append(line)
x_train = np.asarray(x_train)
x train = x train[0:25000]
y_{train} = np_zeros((25000,))
```

```
Preprocessing the ...
  GloVe Features
Part 1 - Bag of V'
  1a - Without 66
     BOW_model.py
     BOW_sentime...
  1b - Using GloV...
     BOW_model.py
     BOW_sentime...
Part 2 - Recurren...
  2a - Without Glo...
     RNN_model.py
     RNN_sentime...
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  2b - With GloVe ...
     RNN_model.py
     RNN_sentime...
     RNN_test.py
Part 3 - Languag...
  3a - Training th...
     RNN_languag...
    train_languag...
  3b - Generating...
```

3c - Learning S...

```
y_{train}[0:12500] = 1
x test = []
with io.open('../preprocessed_data/imdb_test_glove.txt','r',encoding='utf-8') as f:
    lines = f.readlines()
for line in lines:
    line = line.strip()
    line = line.split(' ')
    line = np.asarray(line,dtype=np.int)
    line[line>vocab_size] = 0
    line = line[line!=0]
    line = np.mean(glove_embeddings[line],axis=0)
    x_test.append(line)
x_test = np.asarray(x_test)
y_{\text{test}} = np.zeros((25000,))
y_{test}[0:12500] = 1
vocab_size += 1
model = BOW_model(500) # try 300 as well
model.cuda()
```

This first part is nearly the same besides the fact that we can actually go ahead and do the mean operation for the entire sequence one time when loading in the data. We load in the glove_embeddings matrix, convert all out-of-dictionary tokens to the unknown token for each review, extract the embedding for each token in the sequence from the matrix, take the mean of these emeddings, and append this to the x_train or x_test list.

The rest of the code is the same besides grabbing the data for each batch within the actual train/test loop. The code below is for training and you'll need to modify it slightly for testing by changing x_{train} to x_{test} .

```
## within the training loop
    x_input = x_train[I_permutation[i:i+batch_size]]
    y_input = y_train[I_permutation[i:i+batch_size]]

data = Variable(torch.FloatTensor(x_input)).cuda()
    target = Variable(torch.FloatTensor(y_input)).cuda()

optimizer.zero_grad()
    loss, pred = model(data,target)
    loss.backward()
```

Just like before, try a few different hyperparameter settings and report the results.

Against the intuition laid out in the beginning of this section, this model actually seems to perform worse on average than the one in part a. This seems to achieve anywhere between 81-87%.

Let's take a look at what's happening. In part 1a, test accuracy typically seems to achieve its max after the 3rd epoch and begins to decrease with more training while the training accuracy continues to increase well into 90+%. This is a sure sign of overfitting. The training accuracy for part 1b stops much earlier (around 86-88%) and doesn't seem to improve much more.

Nearly 95% of the weights belong to the embedding layer in part 1a. We're training significantly less in part 1b and can't actually fine-tune the word embeddings at all. Using only 300 hidden weights for part 1b results in very little overfitting while still achieving decent accuracy.

Part 2 - Recurrent Neural Network

Take the following two reviews: * "Although the movie had great visual effects, I thought it was terrible." * "Although the movie had terrible visual effects, I thought it was great."

The first review clearly has an overall negative sentiment while the bottom review clearly has an overall positive sentiment. Both sentences would result in the exact same output if using the bag of

Clearly there is a lot of useful information which could maybe be utilized more effectively if we didn't discard the sequence information like we did in part 1. By designing a model capable of capturing this additional source of information, we can potentially achieve better results but also greatly increase the risk of overfitting. This is heavily related to the curse of dimensionality.

A recurrent neural network can be used to maintain the temporal information and process the data as an actual sequence. Part 2 will consist of training recurrent neural networks built with LSTM layers. We will train two separate models again, one from scratch with a word embedding layer and one with GloVe features.

2a - Without GloVe Features

Create a directory '2a/'. You will need three files, RNN_model.py, RNN_sentiment_analysis.py, and RNN_test.py.

RNN_model.py

An LSTM Cell in pytorch needs a variable for both the internal cell state c(t) as well as the hidden state h(t). Let's start by creating a StatefullSTM() class that can maintain these values for us.

```
class StatefulLSTM(nn.Module):
    def __init__(self,in_size,out_size):
        super(StatefulLSTM, self).__init__()
        self.lstm = nn.LSTMCell(in_size,out_size)
        self.out_size = out_size
        self.h = None
        self.c = None
    def reset_state(self):
        self.h = None
        self.c = None
    def forward(self,x):
        batch_size = x.data.size()[0]
        if self.h is None:
            state_size = [batch_size, self.out_size]
            self.c = Variable(torch.zeros(state_size)).cuda()
            self.h = Variable(torch.zeros(state_size)).cuda()
        self.h, self.c = self.lstm(x,(self.h,self.c))
        return self.h
```

This module uses self.h and self.c to maintain the necessary information while processing a sequence. We can reset the layer at anytime by calling <code>reset_state()</code>. The <code>nn.LSTMCell()</code> contains all of the actual LSTM weights as well as all of the operations.

When processing sequence data, we will need to apply dropout after every timestep. It has been shown to be more effective to use the same dropout mask for an entire sequence as opposed to a different dropout mask each time. More details as well as a paper reference can be found here. Pytorch doesn't have an implementation for this type of dropout so we will make it ourselves.

```
class LockedDropout(nn.Module):
    def __init__(self):
        super(LockedDropout,self).__init__()
        self.m = None

def reset_state(self):
        self.m = None

def forward(self, x, dropout=0.5, train=True):
        if train==False:
            return x
        if(self.m is None):
            self.m = x.data.new(x.size()).bernoulli_(1 - dropout)
```

```
mask = Variable(self.m, requires_grad=False) / (1 - dropout)
return mask * x
```

Note that if this module is called with train set to False, it will simply return the exact same input. If train is True, it checks to see if it already has a dropout mask self.m. If it does, it uses this same mask on the data. If it doesn't, it creates a new mask and stores it in self.m. As long as we reset our LockedDropout() layer at the beginning of each batch, we can have a single mask applied to the entire sequence.

```
class RNN_model(nn.Module):
    def __init__(self,vocab_size,no_of_hidden_units):
        super(RNN_model, self).__init__()
        self.embedding = nn.Embedding(vocab_size,no_of_hidden_units)#,padding_idx=0)
        self.lstm1 = StatefulLSTM(no_of_hidden_units,no_of_hidden_units)
        self.bn_lstm1= nn.BatchNorm1d(no_of_hidden_units)
        self.dropout1 = LockedDropout() #torch.nn.Dropout(p=0.5)
       # self.lstm2 = StatefulLSTM(no_of_hidden_units,no_of_hidden_units)
        # self.bn_lstm2= nn.BatchNorm1d(no_of_hidden_units)
        # self.dropout2 = LockedDropout() #torch.nn.Dropout(p=0.5)
        self.fc_output = nn.Linear(no_of_hidden_units, 1)
        #self.loss = nn.CrossEntropyLoss()
        self.loss = nn.BCEWithLogitsLoss()
    def reset_state(self):
       self.lstm1.reset_state()
        self.dropout1.reset_state()
       # self.lstm2.reset_state()
        # self.dropout2.reset_state()
    def forward(self, x, t, train=True):
        embed = self.embedding(x) # batch_size, time_steps, features
        no_of_timesteps = embed.shape[1]
        self.reset_state()
        outputs = []
        for i in range(no_of_timesteps):
           h = self.lstm1(embed[:,i,:])
            h = self.bn_lstm1(h)
            h = self.dropout1(h,dropout=0.5,train=train)
           \# h = self.lstm2(h)
            # h = self.bn_lstm2(h)
            # h = self.dropout2(h,dropout=0.3,train=train)
            outputs.append(h)
        outputs = torch.stack(outputs) # (time_steps,batch_size,features)
        outputs = outputs.permute(1,2,0) # (batch_size,features,time_steps)
        pool = nn.MaxPool1d(no of timesteps)
        h = pool(outputs)
        h = h.view(h.size(0),-1)
       #h = self.dropout(h)
        h = self.fc_output(h)
        return self.loss(h[:,0],t), h[:,0]#F.softmax(h, dim=1)
```

We create an embedding layer just like in part 1a. We can create a StatefulLSTM() layer we created above as well as a LockedDropout() layer. The reset_state() function is used so we can easily reset the state of any layer in our model that needs it.

The forward() function has a few new features. First notice we have an additional input variable train. We can't rely on model.eval() to handle dropout appropriately for us anymore so we will need to do it ourselves by passing this variable to the LockedDropout() layer.

Assume our input x is batch_size by sequence_length. This means we will be training everything with a fixed sequence length (we will go over how this is done in the actual training loop). By passing this tensor into the embedding layer, it will return an embedding for every single value meaning embed is batch_size by sequence_length by no_of_hidden_units. We then loop over the sequence one step at a time and append h to the outputs list every time.

The list outputs is converted to a torch tensor using torch.stack() and we transform the tensor to get back the shape batch_size by no_of_hidden_units by no_of_timesteps. We need it in this ordering because the nn.MaxPool1d() operation pools over the last dimension of a tensor. After pooling, the h.view() operation removes the last dimension from the tensor (it's only length 1 after the pooling operation) and we're left with a vector h of size batch_size by no_of_hidden_units. We now pass this into the output layer.

This is a good time to mention how there isn't actually a whole lot of difference between what we're doing here and what we did with the bag of words model. The mean embedding over an entire sequence can be thought of as simply a mean pooling operation. It just so happens that we did this mean pooling operation on a bunch of separate words without a word knowing anything about its surrounding context. We pooled before processing any of the temporal information.

This time we are processing the word embeddings in order such that each subsequent output actually has the context of all words preceding it. Eventually we still need to get to a single output for the entire sequence (positive or negative sentiment) and we do this by now using a max pooling operation over the number of timesteps. As opposed to the bag of words technique, we pooled after processing the temporal information.

We could use average pooling instead of max pooling if we wanted. Max pooling seems to work a little better in practice but it depends on the dataset and problem. Intuitively one can imagine the recurrent network processing a very long sequence of short phrases. These short phrases can appear anywhere within the long sequence and carry some important information about the sentiment. After each important short phrase is seen, it outputs a vector with some large values. Eventually all of these vectors are pooled where only the max values are kept. You are left with a vector for the entire sequence containing only the important information related to sentiment as all of the unimportant information was thrown out. For classifying a sequence with a single label, we will always have to eventually collapse the temporal information. The decision in relation to network design deals with where within the model this should be done.

RNN_sentiment_analysis.py

Create a training loop similar to part 1a for training the RNN model. The majority of the code is the same as before. You'll typically need more epochs (about 20) to train this time depending on the chosen hyperparameters. Start off using 500 hidden units. The following code is the only major change about constructing a batch of data during the training loop.

```
x_input2 = [x_train[j] for j in I_permutation[i:i+batch_size]]
sequence_length = 100
x_input = np.zeros((batch_size, sequence_length), dtype=np.int)
for j in range(batch_size):
    x = np.asarray(x_input2[j])
    sl = x.shape[0]
    if(sl < sequence_length):</pre>
        x_{input[j,0:sl]} = x
    else:
        start_index = np.random.randint(sl-sequence_length+1)
        x_input[j,:] = x[start_index:(start_index+sequence_length)]
y_input = y_train[I_permutation[i:i+batch_size]]
data = Variable(torch.LongTensor(x_input)).cuda()
target = Variable(torch.FloatTensor(y_input)).cuda()
optimizer.zero_grad()
loss, pred = model(data,target,train=True)
loss.backward()
```

In the RNN_model.py section, I mentioned assuming the input x was batch_size by sequence_length. This means we're always training on a fixed sequence length even though the reviews have varying length. We can do this by training on shorter subsequences of a fixed size. The variable x_input2 is a list with each element being a list of token ids for a single review. These lists within the list are different lengths. We create a new variable x_input which has our appropriate dimensions of batch_size by sequence_length which here I've specified as 100. We then loop through each review, get the total length of the review (stored in the variable sl), and check if it's greater or less than our desired sequence_length of 100. If it's too short, we just use the full review and the end is padded with 0s. If sl is larger than sequence_length (which it usually is), we randomly extract a subsequence of size sequence_length from the full review.

Notice during testing, you can choose a longer sequence_length such as 200 to get more context. However, due to the increased computation from the LSTM layer and the increased number of epochs, you may way to wrap the testing loop in the following to prevent it from happening everytime.

```
if((epoch+1)%3)==0:
    # do testing loop
```

Choosing the sequence length is an important aspect of training RNNs and can have a very large impact on the results. By using long sequences, we provide the model with more information (it can learn longer dependencies) which seems like it'd always be a good thing. However, by using short sequences, we are providing less of an opportunity to overfit and artificially increasing the size of the dataset. There are more subsequences of length 50 than there are of length 100. Additionally, although we want our RNN to learn sequences, we don't want it to overfit on where the phrases are within a sequence. By using subsequences, we are kind of training the model to be invariant about where it starts within the review which can be a good thing.

To make matters more complicated, you now have to decide how to test your sequences. If you train on too short of sequences, the internal state c may not have reached some level of steady state as it can grow unbounded if the network is never forced to forget any information. Therefore, when testing on long sequences, this internal state becomes huge as it never forgets things which results in an output distribution later layers have never encountered before in training and it becomes wildly inaccurate. This depends heavily on the application. For this particular dataset, I didn't notice too many issues.

I'd suggest trying to train a model on short sequences (50 or less) as well as long sequences (250+) just to see the difference in its ability to generalize. The amount of GPU memory required to train an RNN is dependent on the sequence length. If you decide to train on long sequences, you may need to reduce your batch size.

Make sure to save your model after training.

```
torch.save(rnn,'rnn.model')
```

RNN_test.py

These typically take longer to train so you don't want to be testing on the full sequences after every epoch as it's a huge waste of time. It's easier and quicker to just have a separate script to test the model as you only need a rough idea of test performance during training.

Additionally, we can use this to see how the results change depending on the test sequence length. Copy the majority of the code from RNN_sentiment_analysis.py. Replace the line where you create your model with the following:

```
model = torch.load('rnn.model')
```

This is your trained model saved from before. Remove the training portion within the loop while keeping only the evaluation section. Change number of epochs to around 10. Within the test loop, add the following:

This way it will loop through the entire test dataset and report results for varying sequence lengths. Here is an example I tried for a network trained on sequences of length 100 with 300 hidden units for the LSTM and a dictionary size of 8000 (+1 for unknown token).

```
sequence length, test accuracy, test loss, elapsed time 50 76.14 0.7071 17.5213  
100 81.74 0.5704 35.1576  
150 84.51 0.4760 57.9063  
200 86.10 0.4200 84.7308  
250 86.69 0.3985 115.8944  
300 86.98 0.3866 156.6962  
350 87.00 0.3783 203.2236  
400 87.25 0.3734 257.9246  
450 87.22 0.3726 317.1263
```

The results here might go against the intuition of what was expected. It actually performs worse than the bag of words model from part 1a. However, this does sort of make sense considering we were already overfitting before and we vastly increased the capabilities of the model. It performs nearly as well and with enough regularization/dropout, you can almost certainly achieve better results. Training on shorter sequences can also potentially help to prevent overfitting.

Report the results with the initial hyperparameters I provided as well as two more interesting cases.

2b - With GloVe Features

You should copy RNN_model.py, RNN_sentiment_analysis.py, and RNN_test.py from part 2a over here as a starting point.

RNN_model.py

You'll still need the LockedDropout() and StatefulLSTM().

```
class RNN_model(nn.Module):
    def __init__(self,no_of_hidden_units):
        super(RNN_model, self).__init__()
        self.lstm1 = StatefulLSTM(300,no_of_hidden_units)
        self.bn_lstm1= nn.BatchNorm1d(no_of_hidden_units)
        self.dropout1 = LockedDropout() #torch.nn.Dropout(p=0.5)
       # self.lstm2 = StatefulLSTM(no_of_hidden_units,no_of_hidden_units)
        # self.bn_lstm2= nn.BatchNorm1d(no_of_hidden_units)
        # self.dropout2 = LockedDropout() #torch.nn.Dropout(p=0.5)
        self.fc_output = nn.Linear(no_of_hidden_units, 1)
        #self.loss = nn.CrossEntropyLoss()
        self.loss = nn.BCEWithLogitsLoss()
    def reset_state(self):
        self.lstm1.reset_state()
        self.dropout1.reset_state()
        # self.lstm2.reset_state()
        # self.dropout2.reset_state()
    def forward(self, x, t, train=True):
        no of timesteps = x.shape[1]
        self.reset_state()
        outputs = []
        for i in range(no_of_timesteps):
            h = self.lstm1(x[:,i,:])
            h = self.bn_lstm1(h)
            h = self.dropout1(h,dropout=0.5,train=train)
```

```
# h = self.lstm2(h)
# h = self.bn_lstm2(h)
# h = self.dropout2(h,dropout=0.3,train=train)

outputs.append(h)

outputs = torch.stack(outputs) # (time_steps,batch_size,features)
outputs = outputs.permute(1,2,0) # (batch_size,features,time_steps)

pool = nn.MaxPool1d(x.shape[1])
h = pool(outputs)
h = h.view(h.size(0),-1)
h = self.fc_output(h)

return self.loss(h[:,0],t), h[:,0]#F.softmax(h, dim=1)
```

This is the same model besides the embedding layer is removed from before.

RNN_sentiment_analysis.py

Modify the RNN_sentiment_analysis.py from part 2a to work with GloVe features.

```
glove_embeddings = np.load('../preprocessed_data/glove_embeddings.npy')
vocab_size = 100000
x_{train} = []
with io.open('../preprocessed_data/imdb_train_glove.txt','r',encoding='utf-8') as f:
    lines = f.readlines()
for line in lines:
    line = line.strip()
    line = line.split(' ')
    line = np.asarray(line,dtype=np.int)
    line[line>vocab_size] = 0
    x_train.append(line)
x_{train} = x_{train}[0:25000]
y_{train} = np_{zeros}((25000,))
y_{train}[0:12500] = 1
x_{test} = []
with io.open('../preprocessed_data/imdb_test_glove.txt','r',encoding='utf-8') as f:
    lines = f.readlines()
for line in lines:
    line = line.strip()
    line = line.split(' ')
    line = np.asarray(line,dtype=np.int)
    line[line>vocab_size] = 0
    x_test.append(line)
y_{test} = np.zeros((25000,))
y_{test}[0:12500] = 1
vocab_size += 1
model = RNN model(500)
model.cuda()
```

Load in all of the data.

```
x_input2 = [x_train[j] for j in I_permutation[i:i+batch_size]]
sequence_length = 100
x_input = np.zeros((batch_size,sequence_length),dtype=np.int)
for j in range(batch_size):
    x = np.asarray(x_input2[j])
    sl = x.shape[0]
    if(sl < sequence_length):
        x_input[j,0:sl] = x
    else:
        start_index = np.random.randint(sl-sequence_length+1)</pre>
```

```
x_input[j,:] = x[start_index:(start_index+sequence_length)]
x_input = glove_embeddings[x_input]
y_input = y_train[I_permutation[i:i+batch_size]]

data = Variable(torch.FloatTensor(x_input)).cuda()
target = Variable(torch.FloatTensor(y_input)).cuda()

optimizer.zero_grad()
loss, pred = model(data,target,train=True)
loss.backward()
```

For each batch, make sure to extract the glove_embeddings as shown above before sending it into the model.

RNN_test.py

Here is an example output from one of the models I trained.

```
50 78.94 0.5010 24.4657

100 84.63 0.3956 48.4858

150 87.62 0.3240 75.0972

200 89.18 0.2932 109.8104

250 89.90 0.2750 149.9544

300 90.50 0.2618 193.7136

350 90.83 0.2530 245.5717

400 90.90 0.2511 299.2605

450 91.08 0.2477 360.4909

500 91.19 0.2448 428.9970
```

We see some progress here and the results are the best yet. Although the bag of words model with GloVe features performed poorly, we now see the GloVe features are much better utilized when allowing the model to handle the temporal information and overfitting seems to be less of a problem since we aren't retraining the embedding layer. As we saw in part 2a, the LSTM seems to be overkill and the dataset doesn't seem to be complex enough to train a model completely from scratch without overfitting.

Part 3 - Language Model

This final section will be about training a language model by leveraging the additional unlabeled data and showing how this pretraining stage typically leads to better results on other tasks like sentiment analysis.

A language model gives some probability distribution over the words in a sequence. We can essentially feed sequences into a recurrent neural network and train the model to predict the following word. Note that this doesn't require any additional data labeling. The words themselves are the labels. This means we can utilize all 75000 reviews in the training set.

3a - Training the Language Model

This section will have two files, RNN_language_model.py and train_language_model.py.

RNN_language_model.py

Once again you will need LockedDropout() and StatefulLSTM().

```
class RNN_language_model(nn.Module):
    def __init__(self,vocab_size, no_of_hidden_units):
        super(RNN_language_model, self).__init__()

    self.embedding = nn.Embedding(vocab_size,no_of_hidden_units)#,padding_idx=0)

    self.lstm1 = StatefulLSTM(no_of_hidden_units,no_of_hidden_units)
        self.bn_lstm1= nn.BatchNorm1d(no_of_hidden_units)
        self.dropout1 = LockedDropout() #torch.nn.Dropout(p=0.5)

    self.lstm2 = StatefulLSTM(no_of_hidden_units,no_of_hidden_units)
```

```
self.bn_lstm2= nn.BatchNorm1d(no_of_hidden_units)
   self.dropout2 = LockedDropout() #torch.nn.Dropout(p=0.5)
   self.lstm3 = StatefulLSTM(no_of_hidden_units,no_of_hidden_units)
   self.bn_lstm3= nn.BatchNorm1d(no_of_hidden_units)
   self.dropout3 = LockedDropout() #torch.nn.Dropout(p=0.5)
   self.decoder = nn.Linear(no_of_hidden_units, vocab_size)
   self.loss = nn.CrossEntropyLoss()#ignore_index=0)
   self.vocab_size = vocab_size
def reset_state(self):
   self.lstm1.reset_state()
   self.dropout1.reset_state()
   self.lstm2.reset_state()
   self.dropout2.reset_state()
   self.lstm3.reset_state()
   self.dropout3.reset_state()
def forward(self, x, train=True):
   embed = self.embedding(x) # batch_size, time_steps, features
   no_of_timesteps = embed.shape[1]-1
   self.reset_state()
   outputs = []
   for i in range(no_of_timesteps):
        h = self.lstm1(embed[:,i,:])
       h = self.bn_lstm1(h)
        h = self.dropout1(h,dropout=0.3,train=train)
       h = self.lstm2(h)
       h = self_bn_lstm2(h)
        h = self.dropout2(h,dropout=0.3,train=train)
       h = self.lstm3(h)
       h = self.bn_lstm3(h)
        h = self.dropout3(h,dropout=0.3,train=train)
        h = self.decoder(h)
        outputs.append(h)
   outputs = torch.stack(outputs) # (time_steps,batch_size,vocab_size)
   target prediction = outputs.permute(1,0,2) # batch, time, vocab
   outputs = outputs.permute(1,2,0) # (batch_size,vocab_size,time_steps)
   if(train==True):
        target_prediction = target_prediction.contiguous().view(-1,self.vocab_size)
        target = x[:,1:].contiguous().view(-1)
        loss = self.loss(target_prediction, target)
        return loss, outputs
   else:
        return outputs
```

Unlike before, the final layer has more outputs (called decoder) and we no longer do any sort of pooling. Each output of the sequence will be used separately for calculating a particular loss and all of the losses within a sequence will be summed up. The decoder layer has an input dimension the same size as no_of_hidden_states and the output size is the same as the vocab_size. After every timestep, we have an output for a probability distribution over the entire vocabulary.

After looping through from i=0 to $i=no_of_timesteps-1$, we have outputs for i=1 to $i=no_of_timesteps$ stored in target_prediction. Notice the variable target is simply the input sequence x[:,1:] without the first index.

Lastly, we'll start off with three stacked LSTM layers. The task of predicting the next word is far more complicated than predicting sentiment for the entire phrase. We don't need to be as worried about overfitting since the dataset is larger (although it's still an issue).

train_language_model.py

Copy RNN_sentiment_analysis.py from part 2a. Make sure to import the RNN_language_model you made above.

```
print('begin training...')
for epoch in range(0,75):
    if(epoch==50):
        for param_group in optimizer.param_groups:
            param_group['lr'] = LR/10.0
    model.train()
    epoch_acc = 0.0
    epoch_loss = 0.0
    epoch_counter = 0
    time1 = time.time()
    I_permutation = np.random.permutation(L_Y_train)
    for i in range(0, L_Y_train, batch_size):
        x_input2 = [x_train[j] for j in I_permutation[i:i+batch_size]]
        sequence_length = 50
        x_input = np.zeros((batch_size, sequence_length), dtype=np.int)
        for j in range(batch_size):
            x = np.asarray(x_input2[j])
            sl = x.shape[0]
            if(sl<sequence_length):</pre>
                x_{input[j,0:sl]} = x
            else:
                start_index = np.random.randint(sl-sequence_length+1)
                x_input[j,:] = x[start_index:(start_index+sequence_length)]
        x_input = Variable(torch.LongTensor(x_input)).cuda()
        optimizer.zero_grad()
        loss, pred = model(x_input)
        loss.backward()
        norm = nn.utils.clip_grad_norm_(model.parameters(),2.0)
        optimizer.step() # update gradients
        values,prediction = torch.max(pred,1)
        prediction = prediction.cpu().data.numpy()
        accuracy = float(np.sum(prediction==x_input.cpu().data.numpy()[:,1:]))/sequence_
        epoch_acc += accuracy
        epoch_loss += loss.data.item()
        epoch_counter += batch_size
        if (i+batch_size) % 1000 == 0 and epoch==0:
           print(i+batch_size, accuracy/batch_size, loss.data.item(), norm, "%.4f" % flc
    epoch_acc /= epoch_counter
    epoch_loss /= (epoch_counter/batch_size)
    train_loss.append(epoch_loss)
    train_accu.append(epoch_acc)
    print(epoch, "%.2f" % (epoch_acc*100.0), "%.4f" % epoch_loss, "%.4f" % float(time.ti
    ## test
    if((epoch+1)%1==0):
        model.eval()
        epoch_acc = 0.0
        epoch_loss = 0.0
```

```
epoch_counter = 0
        time1 = time.time()
        I_permutation = np.random.permutation(L_Y_test)
        for i in range(0, L_Y_test, batch_size):
            sequence_length = 100
            x_input2 = [x_test[j] for j in I_permutation[i:i+batch_size]]
            x_input = np.zeros((batch_size, sequence_length), dtype=np.int)
            for j in range(batch_size):
                x = np.asarray(x_input2[j])
                sl = x.shape[0]
                if(sl<sequence_length):</pre>
                    x_{input}[j,0:sl] = x
                else:
                    start_index = np.random.randint(sl-sequence_length+1)
                    x_input[j,:] = x[start_index:(start_index+sequence_length)]
            x_input = Variable(torch.LongTensor(x_input)).cuda()
            with torch.no_grad():
                pred = model(x_input,train=False)
            values,prediction = torch.max(pred,1)
            prediction = prediction.cpu().data.numpy()
            accuracy = float(np.sum(prediction==x_input.cpu().data.numpy()[:,1:]))/seque
            epoch_acc += accuracy
            epoch_loss += loss.data.item()
            epoch counter += batch size
            #train_accu.append(accuracy)
            if (i+batch_size) % 1000 == 0 and epoch==0:
               print(i+batch_size, accuracy/batch_size)
        epoch_acc /= epoch_counter
        epoch_loss /= (epoch_counter/batch_size)
        test_accu.append(epoch_acc)
        time2 = time.time()
        time_elapsed = time2 - time1
        print(" ", "%.2f" % (epoch_acc*100.0), "%.4f" % epoch_loss, "%.4f" % float(time
    torch.cuda.empty_cache()
    if(((epoch+1)%2)==0):
        torch.save(model,'temp.model')
        torch.save(optimizer, 'temp.state')
        data = [train_loss,train_accu,test_accu]
        data = np.asarray(data)
        np.save('data.npy',data)
torch.save(model, 'language.model')
```

Gradient clipping is added in this training loop. Recurrent neural networks can sometimes experience extremely large gradients for a single batch which can cause them to be difficult to train without the gradient clipping.

This model takes much longer to train, about a day. The accuracy will be relatively low (which makes sense considering it's trying to predict one of 8000 words) but this doesn't actually tell you much. It's better to go by the loss. Perplexity is typically used when comparing language models. More about how the cross entropy loss and perplexity are related can be read about here.

I trained multiple models with various results. The model here trained for 75 epochs with a sequence length of 50.

3b - Generating Fake Reviews

Although a general language model assigns a probability P(w_0, w_1, ..., w_n) over the entire sequence, we've actually trained ours to predict P(w_n|w_0, ..., w_n-1) where each output is conditioned only on previous inputs. This gives us the ability to sample from P(w_n|w_0, ..., w_n-1), feed this sampled token back into the model, and repeat this process in order to generate fake movie reviews. This section will walk you through this process.

outputs.append(h)

```
import numpy as np
  import torch
  import torch.nn as nn
  import torch.nn.functional as F
  import torch.optim as optim
  #from torchvision import datasets, transforms
  from torch.autograd import Variable
  import torch.distributed as dist
  import h5py
  import time
  import os
  import io
  import sys
  from RNN_language_model import RNN_language_model
  imdb_dictionary = np.load('../preprocessed_data/imdb_dictionary.npy')
  vocab\_size = 8000 + 1
  word_to_id = {token: idx for idx, token in enumerate(imdb_dictionary)}
We will actually utilize the vocabulary we constructed earlier to convert sampled indices back to their
corresponding words.
 model = torch.load('language.model')
  print('model loaded...')
  model.cuda()
 model.eval()
Load the trained language model from part 3a and set it to eval() mode.
 ## create partial sentences to "prime" the model
  ## this implementation requires the partial sentences
  ## to be the same length if doing more than one
 # tokens = [['i','love','this','movie','.'],['i','hate','this','movie','.']]
  tokens = [['a'],['i']]
  token_ids = np.asarray([[word_to_id.get(token,-1)+1 for token in x] for x in tokens])
  ## preload phrase
  x = Variable(torch.LongTensor(token_ids)).cuda()
  embed = model.embedding(x) # batch_size, time_steps, features
  state_size = [embed.shape[0],embed.shape[2]] # batch_size, features
  no_of_timesteps = embed.shape[1]
  model.reset_state()
  outputs = []
  for i in range(no_of_timesteps):
      h = model.lstm1(embed[:,i,:])
      h = model.bn_lstm1(h)
      h = model.dropout1(h,dropout=0.3,train=False)
      h = model.lstm2(h)
      h = model.bn_lstm2(h)
      h = model.dropout2(h,dropout=0.3,train=False)
      h = model.lstm3(h)
      h = model.bn_lstm3(h)
      h = model.dropout3(h,dropout=0.3,train=False)
      h = model.decoder(h)
```

```
outputs = torch.stack(outputs)
outputs = outputs.permute(1,2,0)
output = outputs[:,:,-1]
```

We can start sampling at the very start or after the model has processed a few words already. The latter is akin to autocomplete. In this example, I'm generating two reviews. The first starts simply with the letter/word 'a' and the second starts with the letter/word 'i'. These are both stored in tokens and converted to token_ids in order to be used as the inputs.

The bottom portion of code then loops through the sequences (both sequences at the same time using batch processing) and "primes" the model with our partial sentences. The variable output will be size batch_size by vocab_size. Remember this output is not a probability. After passing it through the softmax function, we can interpret it as a probability and sample from it.

```
temperature = 1.0 # float(sys.argv[1])
length_of_review = 150
review = []
####
for j in range(length_of_review):
   ## sample a word from the previous output
    output = output/temperature
    probs = torch.exp(output)
    probs[:,0] = 0.0
    probs = probs/(torch.sum(probs,dim=1).unsqueeze(1))
    x = torch.multinomial(probs,1)
    review.append(x.cpu().data.numpy()[:,0])
    ## predict the next word
    embed = model.embedding(x)
   h = model.lstm1(embed)
    h = model.bn_lstm1(h)
   h = model.dropout1(h,dropout=0.3,train=False)
   h = model.lstm2(h)
   h = model.bn_lstm2(h)
    h = model.dropout2(h,dropout=0.3,train=False)
   h = model.lstm3(h)
   h = model.bn_lstm3(h)
    h = model.dropout3(h,dropout=0.3,train=False)
    output = model.decoder(h)
```

Here is where we will actually generate the fake reviews. We use the previous output, perform the softmax function (assign probability of 0.0 to token id 0 to ignore the unknown token), randomly sample based on probs, save these indices to the list review, and finally get another output.

```
review = np.asarray(review)
review = review.T
review = np.concatenate((token_ids,review),axis=1)
review = review - 1
review[review<0] = vocab_size - 1
review_words = imdb_dictionary[review]
for review in review_words:
    prnt_str = ''
    for word in review:
        prnt_str += word
        prnt_str += ' '
    print(prnt_str)</pre>
```

Here we simply convert the token ids to their corresponding string. Remember all of the indices need -1 to account for the unknown token we added before using it with imdb_dictionary.

```
\# temperature 1.0 a hugely influential , very strong , nuanced stand up comedy part all too much . this is
```

Although these reviews as a whole don't make a lot of sense, it's definitely readable and the short phrases seem quite realistic. The temperature parameter from before essentially adjusts the confidence of the model. Using temperature=1.0 is the same as the regular softmax function which produced the reviews above. As the temperature increases, all of the words will approach having the same probability. As the temperature decreases, the most likely word will approach a probability of 1.0.

```
# temperature 1.3
a crude web backdrop from page meets another eastern story ( written by an author bought
i wanted to walk out on featuring this expecting even glued and turd make . he genius or
```

Note here with a higher temperature, there is still some sense of structure but the phrases are very short and anything longer than a few words doesn't begin to make much sense. Choosing an even larger temperature would result in random words being chosen from the dictionary.

```
## temperature 0.25
a little slow and i found myself laughing out loud at the end . the story is about a you
i was a fan of the original , but i was very disappointed . the plot was very weak , the
```

With a lower temperature, the predictions can get stuck in loops. However, it is interesting to note how the top review here happened to be a "good" review while the bottom review happened to be a "bad" review. It seems that once the model becomes confident with the tone of the review, it sticks with it. Remember that this language model was trained to simply predict the next word in 12500 positive reviews, 12500 negative reviews, and 50000 neutral reviews. It seems to naturally be taking into consideration the sentiment without explicitly being told to do so.

```
# temperature = 0.5
a very , very good movie , but it is a good movie to watch . the plot is great , the act
i usually like this movie , but this is one of those movies that i could n't believe . i
```

We're not necessarily generating fake reviews here for any particular purpose (although there are applications that call for this). This is more to simply show what the model learned. It's simple enough to see the accuracy increasing and the loss function decreasing throughout part 3a, but this helps us get a much better intuitive understanding of what the model is focusing on.

Create some of your own movie reviews with your trained model. The temperature parameter can be sensitive depending on how long the model was trained for. Try "priming" the model with longer phrases ("I hate this movie."/"I love this movie.") to see if the sentiment is maintained throughout the generated review.

3c - Learning Sentiment

After getting a basic understanding in part 3b of what sort of information the language model has captured so far, we will use it as a starting point for training a sentiment analysis model.

Copy all your code from part 2a. Modify RNN_model.py to have three lstm layers just like your language model. There are two small differences to be made in RNN_sentiment_analysis.py.

```
model = RNN_model(vocab_size,500))
language_model = torch.load('language.model')
model.embedding.load_state_dict(language_model.embedding.state_dict())
model.lstm1.lstm.load_state_dict(language_model.lstm1.lstm.state_dict())
model.bn_lstm1.load_state_dict(language_model.bn_lstm1.state_dict())
model.lstm2.lstm.load_state_dict(language_model.lstm2.lstm.state_dict())
```

```
model.bn_lstm2.load_state_dict(language_model.bn_lstm2.state_dict())
model.lstm3.lstm.load_state_dict(language_model.lstm3.lstm.state_dict())
model.bn_lstm3.load_state_dict(language_model.bn_lstm3.state_dict())
model.cuda()
```

You are creating a new RNN_model for sentiment analysis but copying all of the weights for the embedding and LSTM layers from the language model.

```
params = []
# for param in model.embedding.parameters():
      params.append(param)
# for param in model.lstm1.parameters():
      params.append(param)
#
# for param in model.bn_lstm1.parameters():
#
      params.append(param)
# for param in model.lstm2.parameters():
      params.append(param)
# for param in model.bn_lstm2.parameters():
      params.append(param)
for param in model.lstm3.parameters():
    params.append(param)
for param in model.bn_lstm3.parameters():
    params.append(param)
for param in model.fc_output.parameters():
    params.append(param)
opt = 'adam'
LR = 0.001
if(opt=='adam'):
    optimizer = optim.Adam(params, lr=LR)
elif(opt=='sgd'):
    optimizer = optim.SGD(params, lr=LR, momentum=0.9)
```

Before defining the optimizer, we're going to make a list of parameters we want to train. The model will overfit if you train everything (you can and should test this yourself). However, you can choose to just fine-tune the last LSTM layer and the output layer.

Train and test the model now just as you did in part 2a.

Here is an example output of mine for a particular model:

```
50 80.98 0.4255 17.0083

100 87.17 0.3043 30.2916

150 90.18 0.2453 45.0554

200 91.15 0.2188 59.9038

250 91.96 0.2022 74.8118

300 92.34 0.1960 89.7251

350 92.64 0.1901 104.7904

400 92.83 0.1863 119.8761

450 92.95 0.1842 134.8656

500 93.01 0.1828 150.3047
```

This performs better than all of the previous models. By leveraging the additional unlabeled data and pre-training the network as a language model, we can achieve even better results than the GloVe features trained on a much larger dataset. To put this in perspective, the state of the art on the IMDB sentiment analysis is around 94.1%.