

1 1.1

1. $\begin{bmatrix} 8 & -4 & 20 \\ 12 & 16 & 4 \end{bmatrix}.$

3. $\begin{bmatrix} 6 & -4 & 24 \\ 8 & 10 & -4 \end{bmatrix}.$

5. $\begin{bmatrix} 2 & 4 \\ 0 & 6 \\ -4 & 8 \end{bmatrix}.$

9. $\begin{bmatrix} 2 & 3 \\ -1 & 4 \\ 5 & 1 \end{bmatrix}.$

17. $A - B$ is undefined.

19. $\begin{bmatrix} 7 & 1 \\ -3 & 0 \\ 3 & -3 \\ 4 & -4 \end{bmatrix}.$

23. $\begin{bmatrix} -7 & -1 \\ 3 & 0 \\ -3 & 3 \\ -4 & 4 \end{bmatrix}.$

25. $-2.$

37-56. (T=True, F=False) TTTFFTFFFTFTTTFTTTTTT

71. For example, the zero and identity matrices of size 2×2 and 3×3 are both symmetric.

75. $(B + B^T)^T = B^T + (B^T)^T = B^T + B = B + B^T.$

79. The (i, i) -th entry of A^T is the same as the (i, i) -th entry of A . By skew-symmetry, it is also the negative of the (i, i) -th entry of A , hence it must be 0.

81. For any 3×3 matrix A , $A = \frac{1}{2}(A + A^T) + \frac{1}{2}(A - A^T).$

82. (a) This is because the (i, i) -th entry of $A + B$ is the sum of the (i, i) -th entry of A and the (i, i) -th entry of B .

(b) This is because the (i, i) -th entry of cA is c times the (i, i) -th entry of A .

(b) This is because the (i, i) -th entry of A^T equals the (i, i) -th entry of A .

2 1.2

1. $\begin{bmatrix} 12 \\ 14 \end{bmatrix}.$

3. $\begin{bmatrix} 11 \\ 0 \\ 10 \end{bmatrix}.$

9. $\begin{bmatrix} as \\ bt \\ cu \end{bmatrix}.$

15. $\begin{bmatrix} 21 \\ 13 \end{bmatrix}.$

17. $\begin{bmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix}.$

19. $\begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{3\sqrt{3}-1}{2} \\ \frac{3+\sqrt{3}}{2} \end{bmatrix}.$

29. $u = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$

31. u is not a linear combination of elements of \mathcal{S} .

35. $u = 3 \begin{bmatrix} 1 \\ 3 \end{bmatrix} - 2 \begin{bmatrix} 2 \\ -1 \end{bmatrix}.$

37. The answer is not unique, e.g. $u = 7 \begin{bmatrix} 1 \\ 2 \end{bmatrix} - 2 \begin{bmatrix} 2 \\ 3 \end{bmatrix}.$

39. u is not a linear combination of elements of \mathcal{S} .

45-63. TFFTTFFFFTFTTFTFTFFT

67. $A_\theta(A_\beta v) = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \left(\begin{bmatrix} \cos(\beta) & -\sin(\beta) \\ \sin(\beta) & \cos(\beta) \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \right)$
 $= \begin{bmatrix} (\cos(\theta)\cos(\beta) - \sin(\theta)\sin(\beta))v_1 - (\sin(\theta)\cos(\beta) + \cos(\theta)\sin(\beta))v_2 \\ (\cos(\theta)\cos(\beta) - \sin(\theta)\sin(\beta))v_2 + (\sin(\theta)\cos(\beta) + \cos(\theta)\sin(\beta))v_1 \end{bmatrix} = A_{\theta+\beta}v.$

68. $A_\theta^T = A_{-\theta}$, hence by 67. both are u .

75. $Au = \begin{bmatrix} a \\ 0 \end{bmatrix}.$

76. $A(Au) = A \begin{bmatrix} a \\ 0 \end{bmatrix} = \begin{bmatrix} a \\ 0 \end{bmatrix} = Au.$

77. Such a vector v must be of the form $\begin{bmatrix} a \\ 0 \end{bmatrix}$, hence $Av = \begin{bmatrix} a \\ 0 \end{bmatrix} = v.$

78. $B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}.$

3 1.3

1. $\begin{bmatrix} 0 & -1 & 2 \\ 1 & 3 & 0 \end{bmatrix}, \begin{bmatrix} 0 & -1 & 2 & 0 \\ 1 & 3 & 0 & -1 \end{bmatrix}.$

3. $\begin{bmatrix} 1 & 2 \\ -1 & 3 \\ -3 & 4 \end{bmatrix}, \begin{bmatrix} 1 & 2 & 3 \\ -1 & 3 & 2 \\ -3 & 4 & 1 \end{bmatrix}.$

7. $\begin{bmatrix} 0 & 2 & -4 & 4 & 2 \\ -2 & 6 & 3 & -1 & 1 \\ 1 & -1 & 0 & 2 & -3 \end{bmatrix}.$

9. $\begin{bmatrix} 1 & -1 & 0 & 2 & -3 \\ 0 & 4 & 3 & 3 & -5 \\ 0 & 2 & -4 & 4 & 2 \end{bmatrix}.$

11. $\begin{bmatrix} 1 & -1 & 0 & 2 & -3 \\ -2 & 6 & 3 & -1 & 1 \\ 0 & 1 & -2 & 2 & 1 \end{bmatrix}.$

23. Yes.

25. No.

39. $x_1 = 2 + x_2$, x_2 free.

41. $x_1 = 2x_2 + 6$, x_2 free.

43. Inconsistent.

45. $x_1 = 4 + 2x_2$, $x_3 = 1/3$, x_2 free.

47. $x_4 \begin{bmatrix} 3 \\ 4 \\ -5 \\ 1 \end{bmatrix}.$

49. $\begin{bmatrix} -3 \\ -4 \\ 5 \\ 0 \end{bmatrix} + x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

51. $\begin{bmatrix} 6 \\ 0 \\ 7 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2 \\ 0 \\ -4 \\ 1 \end{bmatrix}$

53 Inconsistent.

55. $n - k$, because a variable is either free or basic.

57-76. FFTFTTFTTFTTFTTFTTFTT

81. There are 3 cases when the last row is non-zero, 3 when the last row is 0 and the first row isn't, and 1 when the matrix is zero, so 7 in total.

4 1.4

1 $x_1 = -2 - 3x_2$, x_2 free.

3 $x_2 = -5$, $x_1 = 4$.

5 Inconsistent.

7 $x_3 = 2$, $x_1 = 2x_2 - 1$, x_2 free.

- 11 $x_1 = -3x_2 + x_4 - 4$, $x_3 = 3 - 2x_4$, x_2 , x_4 free.
- 13 Inconsistent.
- 17 -12.
- 19 Anything non-zero.
- 23 By row reduction one gets $\begin{bmatrix} -1 & r & 2 \\ 0 & r^2 - 9 & 6 + 2r \end{bmatrix}$. Hence 3.
- 27 When r is not 2 it has exactly one solution, when r is 2 and s is 15 it has infinitely many solutions, when r is 2 and s is not 15 it has no solution.
- 35 Rank 3, nullity 1.
- 37 Rank 2, nullity 3.
- 43 (a) Mine 1: 10 days, Mine 2: 20 days, Mine 3: 25 days. (b) The system of equations has a unique solution which is not non-negative, hence no.
- 53-72. TFTTTTFFTTTFFTTFTTFT
74. 0. 0 matrix has rank 0.
75. 4. There can be at most one pivot per row.
76. 4. There can be at most one pivot per column.
77. 3. Because of problem 75.
78. 0. Because of problem 76.
81. No. Do row reduction of A , the last row must be 0. Do the reverse of the row reduction to the vector e_4 , then it is a b for which $Ax = b$ has no solution.
82. The rank of A must be n so that there aren't any free variable.
83. It can never have just one solution.
84. (a) $x_1 = 1$, $x_1 = 2$. (b) $x_1 = 1$, $2x_1 = 2$. (c) $x_1 + x_2 = 0$, $2x_1 + 2x_2 = 0$, $3x_1 + 3x_2 = 0$.
87. Yes. Because $A(cu) = c(Au) = c0 = 0$.
88. Yes. Because $A(u + v) = Au + Av = 0 + 0 = 0$.
89. $A(u - v) = Au - Av = b - b = 0$.
90. $A(u + v) = Au + Av = 0 + b = b$.
91. If there is some v so that $Av = b$, then $A(cv) = cb$ hence $Ax = cb$ is consistent.

5 1.6

1. Yes, $-1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 4 \\ 7 \end{bmatrix}.$

3. No, write the system of linear equation and you can see that it is inconsistent.

17. This is equivalent to finding r so that the system of equations with augmented matrix $\begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 3 & r \\ -1 & 2 & -1 \end{bmatrix}$

is consistent. By Gaussian elimination, $r = 3$.

19. Same approach as 17, $r = -6$.

21. No, because for example $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is not in the span.

25. Yes. Form a matrix with the three vectors as columns, do Gaussian elimination, one sees that there is a pivot at each row.

29. Yes. There is a pivot at each row when turn it into row echelon form.

31. No. There is only one pivot in its row echelon form.

39. Use them as columns one sees that there are pivots on the first and third columns. Hence $\left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}.$

43. Same approach as 39. $\left\{ \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \right\}.$

The solution of 39 and 43 are not unique. What are other possible answers?

45-64. TTTFTTTFFFTTTTTTTTTTT

70. $u + v$ and $u - v$ are both linear combinations of u and v , hence the span of $u + v$ and $u - v$ must be contained in the span of u and v . On the other hand, $u = \frac{1}{2}(u + v) + \frac{1}{2}(u - v)$, $v = \frac{1}{2}(u + v) - \frac{1}{2}(u - v)$, so the span of u and v are contained in the span of $u + v$ and $u - v$.

72. Follow the same argument as 70, use $u_1 = (u_1 + cu_2) - cu_2$.

6 1.7

1. Yes, they are linearly dependent.

5. No.

13. $\left\{ \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} \right\}.$

15. $\left\{ \begin{bmatrix} -3 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 6 \\ 0 \end{bmatrix} \right\}.$

23. No.

25. Yes.

29. No.

33. $\begin{bmatrix} 4 \\ 5 \\ 1 \end{bmatrix} = 5 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + 4 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}.$

39. $-4.$

41. $-2.$

51. $x_2 \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}.$

53. $x_2 \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -2 \\ 0 \\ 6 \\ 1 \end{bmatrix}.$

57. $x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1 \\ 0 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_6 \begin{bmatrix} -3 \\ 0 \\ -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}.$

63-82. TFTTTTFTFFFTTTFTFTTT

87. If $c_1(u + v) + c_2(u - v) = 0$, because u, v are linearly independent, $c_1 + c_2 = c_1 - c_2 = 0$, hence $c_1 = c_2 = 0$.

89. Same argument as 87.