2.4 Row Echelon Matrices and Elementary Row Operations (ant.)

Algorithm for reducing an man matrix

A to vow echelon form.

- 1. Start with an mxn matrix. If A=O so to (7).
- 7. Determine the left most nonzero column (this is called the pivot rolumn)

 and the topmost position in the pivot column (this is ralled the pivot position)

- 3 Use elementary vow operations to put a 1 in the pivot position.
- 4. Use elementary sow operations to put zeros below the piret position
- 5. If there are no more nonzero

 tows below the pivot position

 50 to (7), otherwise go to (6).
 - 6. Apply (2).(5) to the submatrix

 (ousisting of the rows that lie

 below the pivot position.
 - 7. The matrix is a row echelon matrix.

The number of nouszero rows in any row echelon form of a matrix A is called the rank of A and is denoted rank(A).

$$\begin{array}{c}
A_{12}(-2) \\
A_{2}(-4) \\
0 - 1 - 2 \\
0 - 1 - 2
\end{array}$$

$$A_{2}(1) \begin{bmatrix} 1 & 12 \\ 0 & -1 & -7 \\ 0 & 0 & 0 \end{bmatrix}$$

HW4 Determine the rank of [2-1]

Determine the vank of

0 1 2 1 0 3 1 2 1 0 7 0 1

2.5 Gayssian Elimination

It is easy to find the solution set of a system of linear equations once its corresponding augmented matrix has been reduced to row echelon or reduced to row echelon.

Simplest case: A is an uxu matrix and rank (A) = u.

$$4x_1 - 3x_2 + 6x_3 = 2$$

 $4x_1 - 3x_2 + 6x_3 = 5$
 $4x_1 - 3x_2 - 8x_3 = 6$

$$N_{i}$$

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$$x_1 - 3x_2 + 6x_3 = 5$$

Which can easily be solved using back substitutions.

This process of reduction to row echelm form and back substitutions is called Gaussian elimination

We can also encode the back substitution into matrix calculations by reducing A to a metrix with reduced vow echelon form.

This process is alled Gauss-Jordan Climination. In all examples whose wive found a system of equations there has been a unique solution

How can we tell if there are infinitely many solutions (or no solution), and determine what three solutions are?

It is easy to determine the number of solutions if we know that rank.

Then (ousides the maximal linear system)

Ax=b. Let Att be the augmented matrix

for the system.

(i) If rank(A) = n, the system has

a unique solution

(ii) If rank (A) = rank (A*) = r < h, then

the system has an infinite number

of solutions undered by u-r free

veriables

is inconsistent and has no solutions,

Cov A homogeneous system Ax= O

is consistent (it has at least

one solution)

Led X=0.