

4.3 Subspaces (cont.)

Let S be a nonempty subset of a vector space V . If S is itself a vector space under the same operations of addition and scalar multiplication as used in V , then we say S is a subspace of V .

Thm / Let S be a nonempty subset of a vector space V . Then S is a subspace of V if and only if S is closed under the operations of addition and scalar multiplication.

Ex Let S be the set of all solutions
to

$$\begin{aligned}x_1 - 4x_2 + 6x_3 &= 0 \\ -3x_1 + 10x_2 - 10x_3 &= 0\end{aligned}$$

Express S in set notation and verify

S is a subspace of \mathbb{R}^3 .

$$\left[\begin{array}{ccc|c} 1 & -4 & 6 & 0 \\ -3 & 10 & -10 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & -6 & 0 \\ 0 & 1 & -4 & 0 \end{array} \right]$$

$$\text{let } x_3 = t$$

$$x_2 - 4t = 0 \Rightarrow x_2 = 4t$$

$$x_1 - 10t = 0 \Rightarrow x_1 = 10t$$

$$S_0 \quad S = \{t \langle 10, 4, 1 \rangle \mid t \in \mathbb{R}\}$$

Claim: S is a subspace of \mathbb{R}^3 .

Pf: Check (A1) and (A2)

(A1) Pick $t_1 \langle 10, 4, 1 \rangle$ and

$t_2 \langle 10, 4, 1 \rangle$ in S .

Then $t_1 \langle 10, 9, 1 \rangle + t_2 \langle 10, 9, 1 \rangle =$

$$(t_1 + t_2) \langle 10, 9, 1 \rangle \in S$$

(42) Pick $t_1 \langle 10, 9, 1 \rangle \in S$

and pick $r \in \mathbb{R}$.

Then $(rt_1) \langle 10, 9, 1 \rangle \in S$

So S is a subspace of \mathbb{R}^3 .

Thm / Let V be a vector space with zero vector 0 . Then $S = \{0\}$ is a subspace of V .

Pf / (i) $0 + 0 = 0 \in S$

(ii) Pick $r \in \mathbb{R}$

$$r \cdot 0 = 0 \in S$$

Let A be an $m \times n$ matrix. The solution set to the corresponding homogeneous linear system $Ax = 0$ is called the null space of A and is denoted

$$\text{nullspace}(A) = \{x \in \mathbb{R}^n : Ax = 0\}$$

Thm / The nullspace of A is a subspace of \mathbb{R}^n .

(i) Pick $x, y \in \text{nullspace}(A)$

$$\text{Thm } Ax = 0 \text{ and } Ay = 0$$

$$\text{But } Ax + Ay = 0$$

$$A(x+y) = 0$$

$$x+y \in \text{nullspace}(A)$$

(ii) Pick $r \in \mathbb{R}$, $x \in \text{nullspace}(A)$

$$\text{Thm } Ax = 0 \text{ and } r \cdot Ax = 0$$

$$A(rx) = 0 \Rightarrow rx \in \text{nullspace}(A)$$

HW10

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{bmatrix}$$

Calculate nullspace (A).

HW11

Let $V = M_2(\mathbb{R})$ and S be the subset of all 2×2 matrices with $\det(A) = 1$. Determine whether S is a subspace of V .

HW12

Let $V = P_2$ and S be the subset consisting of all polynomials of the form $p(x) = ax^2 + b$. Determine whether S is a subspace of V .

4.4 Spanning Sets

Since the only operations defined in a vector space V are addition and scalar multiplication the most complicated elements in V have the form:

$$c_1 v_1 + c_2 v_2 + c_3 v_3 + \dots + c_k v_k$$

We give a special name for this

An expression of the form:

$$c_1 v_1 + c_2 v_2 + \dots + c_k v_k$$

is called a linear combination of v_1, v_2, \dots, v_k

It is natural to ask what vectors can be written as linear combinations of v_1, v_2, \dots, v_k .

If every vector in a vector space V can be written as a linear combination of v_1, v_2, \dots, v_k we say V is spanned or generated by v_1, v_2, \dots, v_k and call the set of vectors $\{v_1, v_2, \dots, v_k\}$ a spanning set of V . In this case we say $\{v_1, v_2, \dots, v_k\}$ spans V .

Ex / Show \mathbb{R}^2 is spanned by vectors

$$v_1 = (1, 1)$$

$$v_2 = (-3, 1)$$

Pick $(c, d) \in \mathbb{R}^2$

Want to write (c, d) as

$$x(1, 1) + y(-3, 1) = (c, d) \Rightarrow$$

$$a - 3b = x$$

$$a + b = y \Rightarrow$$

$$A = \begin{bmatrix} 1 & -3 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} c \\ d \end{bmatrix}$$

We can find a solution for $\begin{bmatrix} x \\ y \end{bmatrix}$ if

A is invertible $\Leftrightarrow \det(A) \neq 0$

$$\det(A) = 4$$

So $\{v_1, v_2\}$ is a spanning set.