## 2.5 Gayssian Elimination (unt.)

We can also find the exact Solutions to systems which have infinitely many solutions.

Desermine the solution set to

 $5x_1 - 6x_2 + x_3 = 4$   $2x_1 - 3x_2 + x_3 = 1$   $4x_1 - 3x_2 - x_3 = 5$ 

$$\begin{bmatrix}
5 - 6 & 1 & 4 \\
2 - 3 & 1 & 1
\end{bmatrix}$$

$$\begin{bmatrix}
4 - 3 - 1 & 5
\end{bmatrix}$$

$$A_{31}(-1)$$

$$\begin{bmatrix}
1 - 3 & 2 & | -17 \\
2 - 3 & 1 & | 1 \\
4 - 1 - 1 & 5
\end{bmatrix}$$

$$A_{12}(-2)$$

$$\begin{bmatrix}
1 - 3 & 7 & | -17 \\
0 & 3 - 3 & | 3 \\
0 & 9 - 9 & | 9
\end{bmatrix}$$

$$M_2(1)$$
  $\begin{bmatrix} 1 - 7 & 7 & | -1 \\ 0 & 1 & -1 & | 1 \\ 0 & 9 & -9 & | 9 \end{bmatrix}$ 

$$M_{23}(-9)$$
  $\begin{bmatrix} 1-3 & 2 & | & -1 \\ 0 & 1 & | & -1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$ 

equation is the last row the Ox, + Ox, = O, which is for any X, , Xz and Xz, although we have three variables we only have the equations relating and we are free to specify third veriable arbitrarily The veriable we chose to specify is Celled a frec variable

Rule

Choose free variables for every column which has no corresponding leading 1.

Lif 
$$X_3 = \xi$$
 $X_7 - \xi = 1 \Rightarrow X_7 = 1 + \xi$ 
 $X_4 - 3(1 + \xi) + 7\xi = -1 \Rightarrow$ 

The solution set S to the system is  $S = \{(Z_{+}t_{i}, t_{i} + t_{i}) | t \in \mathbb{R}^{3}\}$   $= \{(Z_{+}t_{i}, t_{i}) | t \in \mathbb{R}^{3}\}$ 

Ex Ve Gaussan elimination to solve the

System

$$X_1 - Z_{X_2} + Z_{X_3} - X_{X_4} = 3$$
 $3x_1 + X_2 + 6x_3 + 11x_4 = 16$ 
 $2x_1 - X_2 + 9x_3 + 9x_4 = 9$ 

Lift 
$$x_4 = \xi$$
  
 $x_7 = 5$   
 $x_2 + 7\xi = 1 = 1$   $x_2 = 1 - 7\xi$   
 $x_1 - 7(1 - 7\xi) + 7\xi - \xi = 3$   
 $x_1 = 7\xi - 7\xi + \xi + 3$   
 $x_1 = 7\xi - 7\xi - 3\xi$ 

$$S = \{(5-7s-3c, 1-7t, s, t) \mid s, t \in \mathbb{R}^{5}\}$$

$$= \{(5,1,0,0) \mid s(-7,0,1,0) \mid t \in (-3,-7,91) \mid s, t \in \mathbb{R}^{5}\}$$

HW6 Vsing Gauss - Jurdan elimination

determine the solution set to

$$\chi_1 + 2\chi_2 + \chi_3 = 1$$

$$3x_1 + 5x_2 + x_3 = 3$$

HW7

$$Z_{x_1} - X_{x_2} + 3_{x_3} = 14$$
 $3_{x_1} + x_{z_2} - Z_{x_3} = -1$ 
 $7_{x_1} + 2_{x_2} - 3_{x_3} = 3$ 
 $5_{x_1} - x_{z_2} - 2_{x_3} = 5$ 

$$\begin{array}{c} X_{1} + 2x_{2} + x_{3} + x_{4} - 2x_{5} = 3 \\ X_{3} + 4x_{4} - 3x_{5} = 7 \end{array}$$

$$\begin{array}{c} X_{3} + 4x_{4} - 3x_{5} = 7 \\ 2x_{4} + 4x_{2} - x_{3} - 10x_{4} + 5x_{5} = 0 \end{array}$$

S.l., the following systems

HWIO

$$2x_1 - x_2 + 3x_3 - x_4 = 3$$
  
 $3x_1 + 2x_2 + x_3 - 5x_4 = -6$   
 $x_1 - 2x_2 + 3x_3 + x_4 = 6$ 

## 7.6 The Inverse of a Square Matrix

Ju this section we consider a different viewpoint for solving a system of linear equations. Although computationally it is no more efficient than previous methods it sives us a much better conceptual understanding of linear algebra

In this section we assume all matrices are wan square matrices

Say we want to solve a system

Ax=6

Assume we know a matrix B where

AB = BA = In

Then instead of using Gaussian elimination, we can easily solve the system using the fact that

BAx = B6

Ix = Bb = x = Bb

Unfortunately finding this matrix B

(if it exists) is no more computationally efficient than our earlier methods for solving systems of equations.

Let A be an nxn matrix if there exists
a matrix A-1 satisfying

AA-1: A-1A = In

then we call A-1 the inverse of A

We say A is invertible if A' exists

Note if there is an inverse matrix it is unique

To see this note if AB = BA = In

AC = CA = In

(=CI= (AB)= (A)B=I.B=B

The existence of an inverse (even if we don't know explicitly what it is ) allows us to establish many important properties without working directly with explicit metrices

Than

If A-1 exists, there is a unique

solution to the system of equations

Ax= 6

A = b  $A^{-1}Ax = A^{-1}b = 0$ 

x - A-16

Ix = A-16 =

(Un. gueness)

/- Ksunc

Ax, = 6

Ax7 = 6

Then

 $A^{-1}A_{X_1} = A^{-1}b \Rightarrow A^{-1}A_{X_2} = A^{-1}b$ 

X, = A-16 = X2

The following is a very important equivalence we use throughout the semester.

Thm A is invertible = rank (A) = h

Note so far we haven't soid how to explicitly find what  $A^{-1}$  is

One method is essentially the same thing as Gauss-Jordan elimination We call it the Gauss-Jordan technique.

Write the matrices A and I wext to each other

L A I

Then use Gars-Judan elimination on both A and I to rewrite A in reduced row echelon form.

The resulting matrix on the right is

A-1

[AII] ~ ... ~ [IIA-']

$$E_{X}/F_{ind}A^{-1}: fA: \begin{bmatrix} 1 & 13 \\ 0 & 12 \\ 3 & 5-1 \end{bmatrix}$$

$$A^{-1} = \frac{1}{14} \begin{bmatrix} 11 & -16 & 1 \\ -6 & 10 & 2 \\ t & 3 & 2 & -1 \end{bmatrix}$$