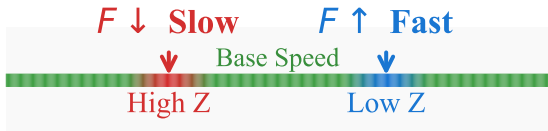


## Strategy B0: Feed Planning ( $F$ )



## Strategy B1: Path Re-planning

