

Personal Proceeding on Time Series (4)

--PLSTM implement and Fast weights

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Outline

- I. How to implement PLSTM
- II. Using Fast Weights to Attend to the Recent Past



• I. How to implement PLSTM

Review

$$\phi_t = \frac{(t-s) \bmod \tau}{\tau}, \qquad k_t = \begin{cases} \frac{2\phi_t}{r_{on}}, & \text{if } \phi_t < \frac{1}{2}r_{on} \\ 2 - \frac{2\phi_t}{r_{on}}, & \text{if } \frac{1}{2}r_{on} < \phi_t < r_{on} \\ \alpha\phi_t, & \text{otherwise} \end{cases}$$

$$\widetilde{c_i} = f_i \odot c_{i-1} + i_i \odot \sigma_c (x_i W_{xc} + h_{i-1} W_{hc} + b_c) \tag{7}$$

$$c_j = k_j \odot \widetilde{c_j} + (1 - k_j) \odot c_{j-1} \tag{8}$$

$$\widetilde{h_j} = o_j \odot \sigma_h(\widetilde{c_j}) \tag{9}$$

$$h_j = k_j \odot \widetilde{h_j} + (1 - k_j) \odot h_{j-1} \tag{10}$$



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gz = grad

• I. How to implement PLSTM

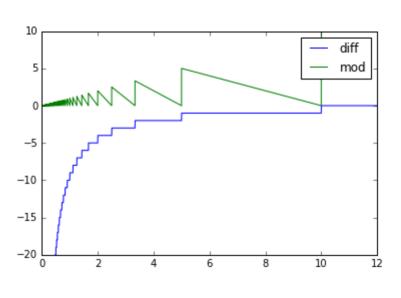
How to implement MOD: register gradient

$$f(x,y) = x\%y = x - y \left[\frac{x}{y} \right]$$

$$\frac{\partial f}{\partial x} = 1$$

$$\frac{\partial f}{\partial y} = -\left[\frac{x}{y} \right] - y \times \left(\frac{\partial}{\partial y} \left[\frac{x}{y} \right] \right)$$

$$\frac{\partial f}{\partial y} = \begin{cases} -\left[\frac{x}{y} \right], & x\%y \neq 0 \\ undefined, & x\%y = 0 \end{cases}$$



49 # Here we need to register the gradient for the mod operation @ops. RegisterGradient("FloorMod") def mod grad (op, grad): x, y = op. inputs

x grad = gz y_grad = tf.reduce_mean(-(x // y) * gz, axis=[0], keep_dims=True) return x grad, y grad



• I. How to implement PLSTM

How to implement MOD: write explicitly

$$f(x,y) = x\%y = x - y \left[\frac{x}{y} \right]$$

```
# modulo operation not implemented in Tensorflow backend, so write explicitly.

# a mod n = a - (n * int(a/n))

# phi = ((t - shift) % period) / period

phi = ((t - shift) - (period * ((t - shift) // period))) / period
```



• I. How to implement PLSTM

How to implement if

a) Use where or switch function

b) Write explicitly



Intuition

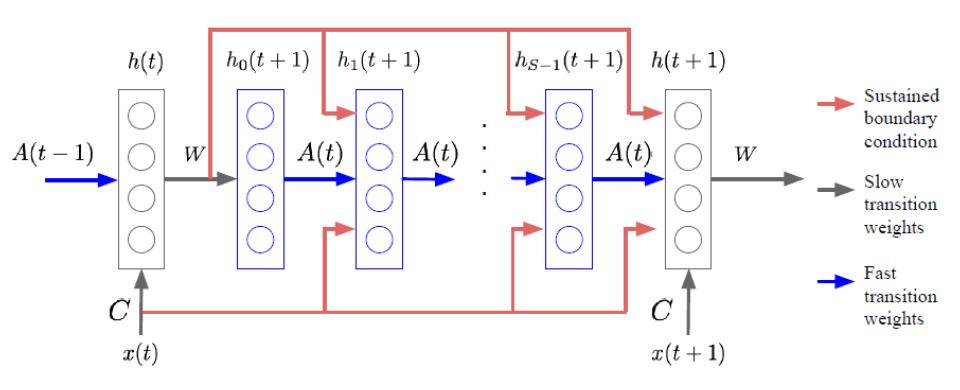


Figure 1: The fast associative memory model.

Slow weights < Fast weights < Activity
Distributed Memory < Intermediate Memory < Stateless



Easy Formula means trivial implementation

$$A(t+1) = \lambda A(t) + \eta h(t)h(t)^{T}$$
(1)

$$h_{s+1}(t+1) = f([Wh(t) + Cx(t)] + A(t)h_s(t+1)), \tag{2}$$

A Fast trick

$$A(t) = \eta \sum_{\tau=1}^{\tau=t} \lambda^{t-\tau} h(\tau) h(\tau)^{T}$$
(3)

$$A(t)h_{s+1}(t+1) = \eta \sum_{\tau=1}^{\tau=t} \lambda^{t-\tau} h(\tau) [h(\tau)^T h_s(t+1)]$$
(4)



• Experiment

Input string Target c9k8j3f1??c 9 j0a5s5z2??a 5

Model	R=20	R=50	R=100
IRNN	62.11%	60.23%	0.34%
LSTM	60.81%	1.85%	0%
A-LSTM	60.13%	1.62%	0%
Fast weights	1.81%	0%	0%

Table 1: Classification error rate comparison on the associative retrieval task.

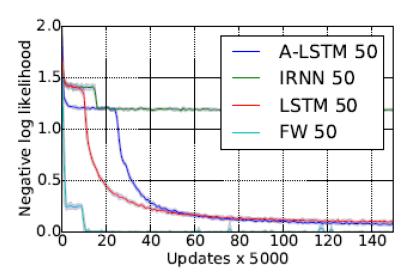


Figure 2: Comparison of the test log likelihood on the associative retrieval task with 50 recurrent hidden units.



Highlights

a) It strengthens IRNN

Fast weights: The fast weights learning rate, η , is set to 0.5 and the fast weights decay rate, λ , is set to 0.9. The fast weights are updated once at every time step. We experimented with more iterations for the "inner loop" and the performance are similar. The recurrent slow weights are initialized to an identity matrix scaled by 0.05. We use the ReLU activation for $f(\cdot)$ in the recurrent layer.

IRNN: The recurrent slow weights are initialized to an identity matrix scaled by 0.5. ReLU is used as the non-linearity in the recurrent layer.

b)
$$s = 1$$

c) Layer Normalization is good

$$h_{s+1}(t+1) = f(\mathcal{LN}[Wh(t) + Cx(t) + A(t)h_s(t+1)])$$
(5)

Bibliography

- PLSTM TensorFlow implement
- PLSTM Keras <u>implement</u>
- Using Fast Weights to Attend to the Recent Past (<u>arXiv</u>)
- Fast Weights TensorFlow implement



Thanks for listening!

