



Personal Proceeding on Time Series (2)

--Echo State Network and Temporal Kernel RNN

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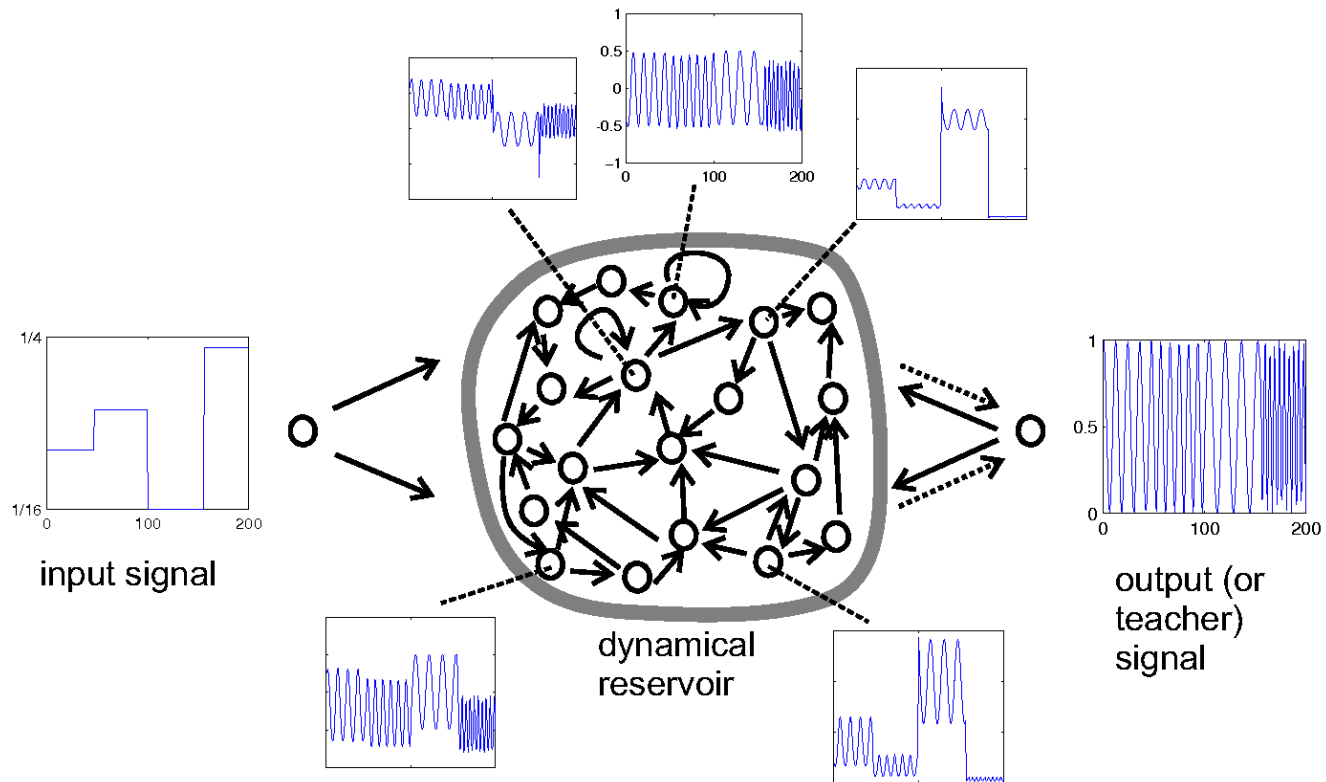
Outline

- **I. Echo State Network**
- **II. Temporal Kernel RNN**
- **III. Seasonal RNN**



• I. Echo State Network

- Intuition





• I. Echo State Network

- Just a Fancy Name for Random Initialization

- a) Step 1: Provide a random RNN.
 - Give a RNN model, randomly initialize the input weights and state weights.
 - Leave the output weight trainable.
- b) Step 2: Harvest reservoir states.
 - Compute the state w.r.t the input.
- c) Step 3: Compute output weights.
 - Train the output weights.
 - LMS is enough usually, so the training will be very fast.

Just a FANCY name:

Very similar to Extreme Learning Machine (ELM).



• I. Echo State Network

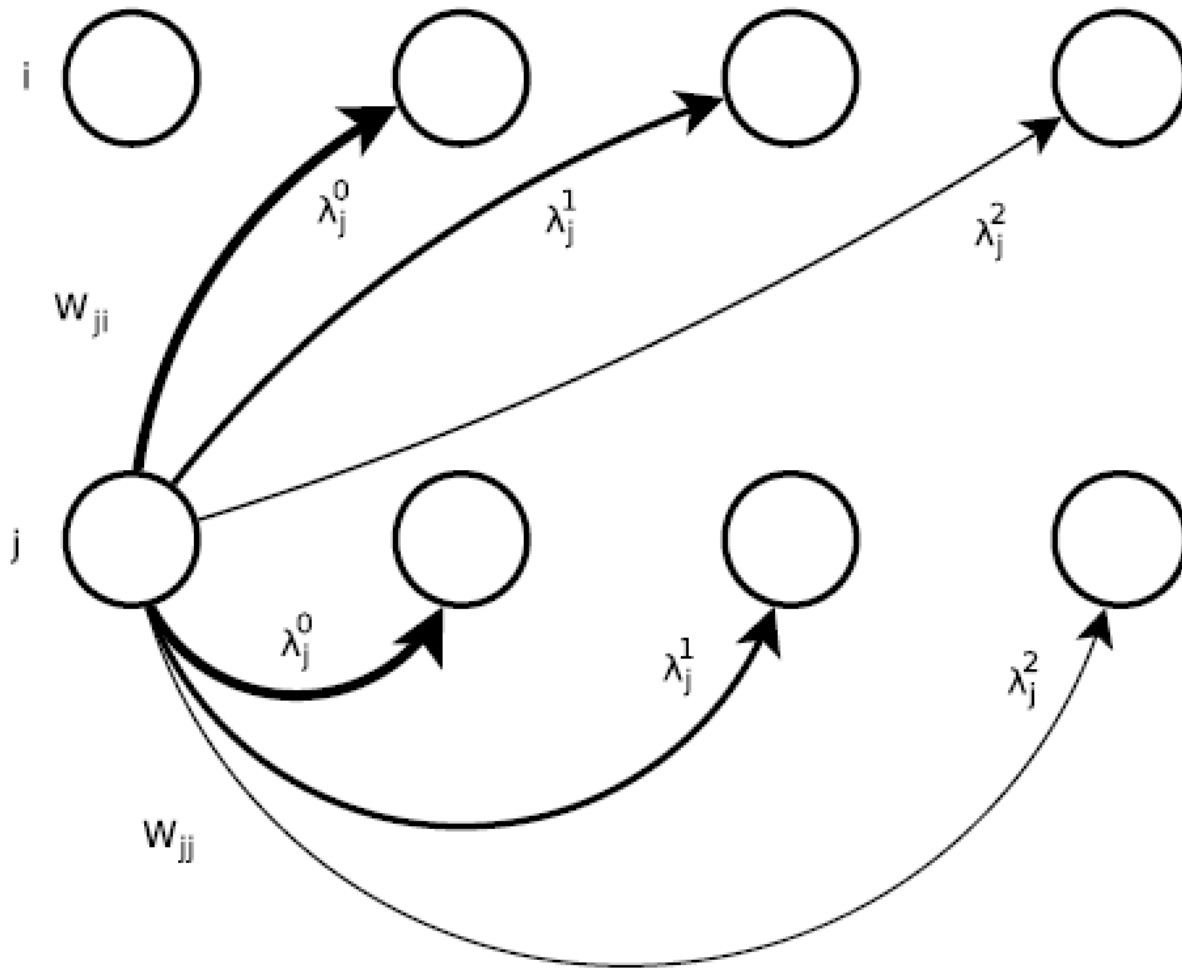
- **Highlights**

- a) The inner activation should be non-linear.
- b) The reservoir should be relatively large (usually 100~1000).
- c) Modest initialization is needed.
- d) Can well model one-dimensional time series, while poorly handle high-dimensional data.
- e) Model integration is easy, like Echo State Gaussian Process.



• II. Temporal Kernel RNN

- Idea





• II. Temporal Kernel RNN

- Formula

$$\mathbf{y}_t^{(i)} = f \left(\sum_{j=1}^{n_y} W_{y \rightarrow y}^{(j,i)} \sum_{k=1}^t (\lambda^{(j)})^{k-1} \mathbf{y}_{t-k}^{(j)} + \sum_{m=1}^{n_x} W_{x \rightarrow y}^{(m,i)} \sum_{k=1}^t (\lambda^{(m)})^{k-1} \mathbf{x}_{t-k}^{(m)} \right)$$

$$\mathbf{S}_t^{y(j)} = \sum_{k=1}^t (\lambda^{(j)})^{k-1} \mathbf{y}_{t-k}^{(j)}$$

$$\mathbf{S}_t^{y(j)} = \mathbf{y}_{t-1}^{(j)} + \lambda^{(j)} \mathbf{S}_{t-1}^{y(j)}$$

$$\mathbf{S}_t^{x(m)} = \sum_{k=1}^t (\lambda^{(m)})^{k-1} \mathbf{x}_{t-k}^{(m)}$$

$$\mathbf{S}_t^{x(m)} = \mathbf{x}_{t-1}^{(m)} + \lambda^{(m)} \mathbf{S}_{t-1}^{x(m)}$$



• II. Temporal Kernel RNN

• Matrix Form

$$\mathbf{y}_t^{(i)} = f \left(\sum_{j=1}^{n_y} W_{y \rightarrow y}^{(j,i)} \sum_{k=1}^t (\lambda^{(j)})^{k-1} \mathbf{y}_{t-k}^{(j)} + \sum_{m=1}^{n_x} W_{x \rightarrow y}^{(m,i)} \sum_{k=1}^t (\lambda^{(m)})^{k-1} \mathbf{x}_{t-k}^{(m)} \right)$$

$$\mathbf{y}_t = f \left(W_{yy} \underbrace{\underbrace{\boldsymbol{\lambda}^y}_{n_y \times n_y} \cdot \underbrace{\mathbf{Y}_{t-1:t-k}}_{k \times 1}}_{n_y \times n_y} + W_{xy} \underbrace{\underbrace{\boldsymbol{\lambda}^x}_{n_x \times n_x} \cdot \underbrace{\mathbf{X}_{t-1:t-k}}_{k \times 1}}_{n_x \times n_x} \right)$$

$n_y \times 1$ $n_y \times n_y$ $n_y \times k$ $k \times 1$ $n_x \times n_x$ $n_x \times k$ $k \times 1$

where,

$$\boldsymbol{\lambda}^y = \begin{pmatrix} \lambda_1^{y0} & \lambda_1^{y1} & \dots & \lambda_1^{y_{k-1}} \\ \lambda_2^{y0} & \lambda_2^{y1} & \dots & \lambda_2^{y_{k-1}} \\ \vdots & \vdots & \ddots & \vdots \\ \lambda_{n_y}^{y0} & \lambda_{n_y}^{y1} & \dots & \lambda_{n_y}^{y_{k-1}} \end{pmatrix}, \quad \mathbf{Y}_{t-1:t-k} = \begin{pmatrix} y_{t-1} \\ y_{t-2} \\ \vdots \\ y_{t-k} \end{pmatrix}$$

So as $\boldsymbol{\lambda}^x$ and $\mathbf{X}_{t-1:t-k}$.

if we state $\boldsymbol{\lambda}^y = (\lambda_1^y, \lambda_2^y, \dots, \lambda_{n_y}^y)^T$.

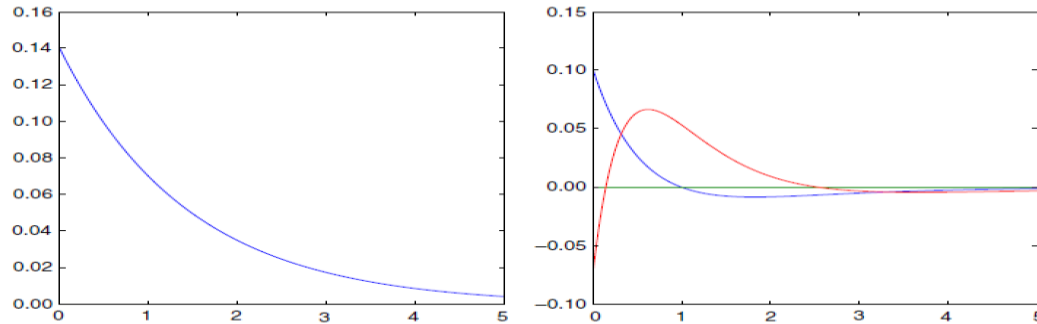
$$\underline{S_t^y = y_{t-1} + \boldsymbol{\lambda}^y S_{t-1}}$$



• II. Temporal Kernel RNN

- Some Details

a) The impact of λ to the state



b) λ is trainable variable, w.r.t. $0 \leq \lambda \leq 1$

c) How to implement Λ ?

$$L = \text{tf.Variable(hidden_size)}$$

↓ sigmoid: 0 ~ 1

$$\lambda = \sigma(L)$$

↓

$$\Lambda = (\lambda^0 \lambda^1 \lambda^2 \dots \lambda^K)$$



- **III. Seasonal RNN**

- **No Public**



Bibliography

- [More Recurrent Neural Networks by Geoffrey Hinton \(Neural Network for Machine Learning Week 8\)](#)
- [Temporal-Kernel Recurrent Neural Networks \(ScienceDirect\)](#)
- Clockwork RNN non-official code ([GitHub](#))



Thanks for listening!

