Device management

CS503: Operating systems, Spring 2019

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Previous lecture

- Paging
 - Processor modes
 - Virtual memory mechanisms:
 - Paging
 - Segmentation
 - Page tables, multi-level paging, PDEs/PTEs, etc.
 - TLB
 - Memory protection, memory layout with virtual memory

Previous lecture

- On demand paging:
 - Lazy loading of executables
 - Simulating/virtualizing more memory than the available physical RAM
- Intercepting page accesses using the valid bit
- Trapping on the page faults

Ancient history

- Device manager is part of OS (typically called device drivers)
- OS presents applications with uniform interface to all devices (as much as possible)
- IO is typically interrupt driven

Device manager in an operating system

- Manages peripheral resources
- Hides low-level hardware details
- Provides API to applications
- Synchronizes processes and IO

Review of hardware interrupts

- Processor:
 - Starts a device
 - Enables interrupts
- Device
 - Performs the requested operation
 - Raises an interrupt on bus
- Processor hardware
 - Checks for interrupts after each instruction is executed
 - Invokes an interrupt function, if an interrupt is pending
 - Provides a mechanism for return

Processes and interrupts

- Key ideas:
 - Recall: at any time a process is running
 - We think of an interrupt as a function call that occurs between two instructions
 - Processes are an OS abstraction, not part of the hardware
 - OS cannot afford to switch context whenever an interrupt occurs
- Consequence: the current process executes interrupt code

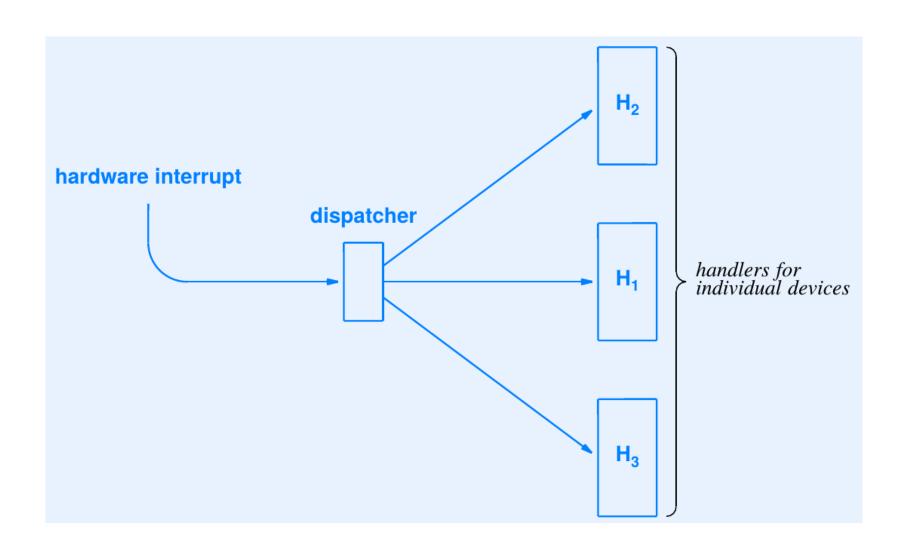
Interrupt software (two pieces)

- Interrupt dispatcher:
 - Single function common to all interrupts
 - Finds interrupting device on the bus
 - Calls a device-specific function
- Interrupt handler:
 - Separate code for each device
 - Invoked by the dispatcher
 - Performs all interaction with device

Interrupt dispatcher

- Low-level function
- Invoked by hardware when interrupt occurs
 - CPU has saved the instruction pointer (and a flag register)
- Dispatcher
 - Saves other machine state as necessary
 - Identifies interrupting device
 - Calls a device-specific function

Conceptual view of interrupt dispatching



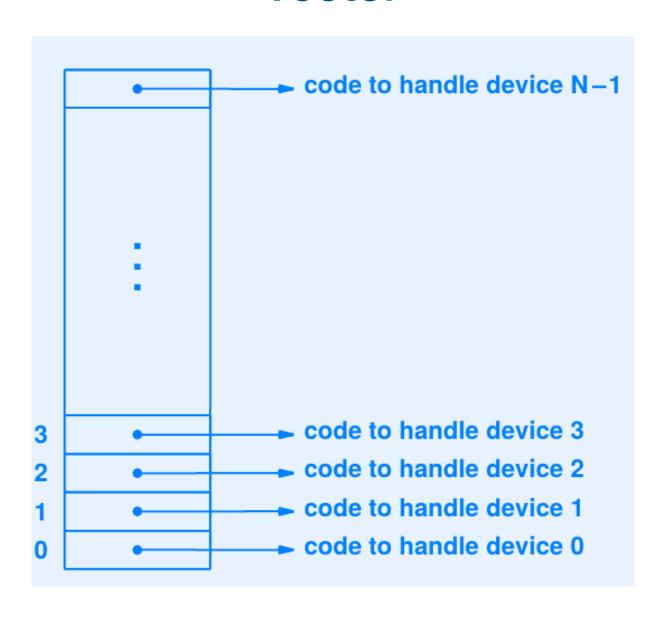
Return from an interrupt

- Interrupt dispatcher
 - Executes special hardware instruction known as return from interrupt:
 - e.g., **iret** in x86
- Interrupt handler
 - Communicates with device (sending and receiving data)
 - Eventually returns to interrupt dispatcher
- Return from interrupt instruction atomically
 - resets instruction pointer to save value
 - Enables interrupts

Interrupt mechanism: a vector

- Each possible interrupt is assigned a unique IRQ
- Hardware uses IRQ as an index into an interrupt vector array
 - See `set_evec()` how Xinu initializes the vector

Conceptual organization of the interrupt vector



Basic rules for interrupt processing

• 1. Data consistency:

- Need synchronization mechanism to ensure data consistency
- Sharing data between:
 - Interrupt handler and device drivers
 - Interrupt handler and kernel threads
- Possible synchronization mechanisms in the interrupt handler
 - Disable interrupt
 - Considering SMP makes the synchronization problem complicated
 - Q: How about using:
 - Spin lock
 - Semaphores / mutex?

Basic rules for interrupt processing

- 2. Speed: interrupt processing has to be quick
 - Linux: top and bottom halves, where top-half quickly handles the interrupt and the bottom-half processes heavy long tasks

Interrupts and processes

- When an interrupt occurs, I/O has completed
- Either:
 - Data has arrived
 - Space has become available in an output buffer
- A process may have been blocked waiting
 - To read data
 - To write data
- The blocked process may have a higher priority than the currently executing process
- The scheduling invariant needs to be upheld

A question about scheduling

- Suppose process X is executing when an interrupt occurs
- Process X remains executing when the interrupt dispatcher is invoked and when the dispatcher calls a handler
- Suppose data has arrived and a higher-priority process Y is waiting for the data
- If the handler merely returns from an interrupt, process X will continue to execute
- Should the interrupt handler call resched()
- If not, how is the scheduling variant established?

Possible solutions

- An OS may:
 - Arrange for the dispatcher to reestablish the scheduling invariant just before returning from the interrupt
 - Postpone rescheduling until a later time (e.g., when the current process's time-splice expires)
- Any of the above works

Interrupts and the null process

- In the concurrent processing world:
 - A process is always running
 - Interrupts can occur asynchronously
 - The currently executing process executes interrupt code
- An important consequence
 - The null process may be running when an interrupt occurs
 - If interrupted, the null process will execute the interrupt handler
- Keep in mind: the null process must always remain eligible to run

A restriction imposed by the null process

- Because an interrupt can occur while the null process is executing:
 - -> an interrupt hander can only call functions that leave the executing process in the current or ready states.
- For example: an interrupt handler can call send or signal, but cannot call wait

Scheduling and interrupts

- Recall that interrupts are disabled when dispatcher calls device-specific interrupt handler
- To remain safe:
 - A device-specific interrupt handler must keep further interrupts disabled until it completes changes to global data structures
 - Q: Would acquire locks also work in this situation?

Rescheduling during interrupt processing

- Suppose:
 - Interrupt handler calls signal
 - Signal calls resched()
 - Resched() switches to a new process
 - The new process executes the interrupts enabled
- Q: will interrupts pile up indefinitely?

An example

- Let T be the current process
- When interrupt occurs, T executes an interrupt handler
- The interrupt handler calls signal
- Signal calls resched
- A context switch occurs and process S runs
- S may run with interrupts enabled

The answer

- Rescheduling during interrupt processing is safe provided that:
 - each interrupt handler leaves global data in a valid state before rescheduling AND
 - no function enables interrupts unless it previously disabled them

Device driver in Xinu

- Set of functions that perform IO on a given device
- Contains device-specific code
- Includes functions used to read or write data and control the device as well as interrupt handler code
- Code divided into two parts

Two parts of a device driver

Upper half:

- Functions executed by applications
- Used to request IO
- May copy data between user and kernel address space

Lower half:

- Device specific interrupt handler
- Invoked by interrupt when operation completes
- Executed by whatever process is executing
- May restart the device for next operation

Devision of duties in a driver

- Upper half:
 - Minimal interaction with device hardware
 - Enqueues request
 - Starts devices if idle
- Lower half
 - Minimal interaction with application
 - Talks to the device
 - Obtains incoming data

Coordination of processes performing IO

 Processes may need to block when attempting to perform IO

- Example:
 - Application waits for incoming data to arrive
 - Other examples?
- How should coordination be done?

Retrofitting process coordination mechanism

- Answer: Retrofitting process coordination mechanism
 - Message passing
 - Semaphores

Using semaphores for input synchronization

- A shared buffer is created with N slots
- A semaphore is created with initial count 0
- Upper-half
 - Calls `wait` on the semaphore
 - Extracts the next item from buffer and returns
 - Can restart the device if the device is idle
- Lower-half
 - Places the incoming item in the buffer
 - Calls `signal` on the semaphore
- Note: the semaphore counts the # of items in the buffer

More device management topics

- API for devices
- Device independent IO
- Xinu primitives
- Driver examples
- Internal communication