## Generalized Filter

Suppose  $x=(x_1,x_2,...,x_n)^T\in\Re^n$  is a time series, the general form of finite impulse response is thus:

$$y_i = \sum_{k=0}^{m} \phi_k x_{i+k} \tag{1}$$

Let

$$\Phi = (\Phi_{i,j}) 
= \begin{pmatrix}
\phi_0 & \phi_1 & \cdots & \phi_{n-1} \\
\phi_{-1} & \phi_0 & \cdots & \phi_{n-2} \\
\vdots & \vdots & \ddots & \vdots \\
\phi_{m-n+1} & \phi_{m-n+2} & \cdots & \phi_m
\end{pmatrix} \in \Re^{(n-m)\times n},$$
(2)

where

$$\Phi_{i,j} = \phi_{i-j} = \begin{cases} \phi_{i-j} & \text{if } 0 \le i - j \le m \\ 0 & \text{otherwise} \end{cases}$$
 (3)

Therefore,

$$\Phi x = y = (y_1, y_2, ..., y_{n-m})^T.$$
(4)

Moreover, we let

$$\Lambda = \Phi^T \Phi 
= (\Lambda_{i,j}) \in \Re^{n \times n},$$
(5)

where

$$\Lambda_{i,j} = \sum_{k=1}^{n-m} \Phi_{k,i} \Phi_{k,j} 
= \sum_{k=1}^{n-m} \phi_{k-i} \phi_{k-j}.$$
(6)

## Moments of filtered error

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$$E\Phi e = 0 \tag{7}$$

$$Ee^{T}\Phi^{T}\Phi e = Ee^{T}\Lambda e$$

$$= E\sum_{i,j=1}^{n} \Lambda_{i,j}e_{i}e_{j}$$

$$= M_{2}\sum_{i=1}^{n} \Lambda_{i,i}$$

$$= M_{2}\sum_{i=1}^{n} \sum_{k=1}^{n-m} \phi_{k-i}^{2}$$

$$= M_{2}(n-m)\sum_{k=1}^{m} \phi_{k}^{2}$$
(8)

 $E\Phi e e^T \Phi^T \Phi e = \Phi E e e^T \Phi^T \Phi e.$ 

Since

$$Eee^{T}\Phi^{T}\Phi e = Ee\sum_{i,j=1}^{n} \Lambda_{i,j}e_{i}e_{j}$$
$$= M_{3}\begin{pmatrix} \Lambda_{1,1} \\ \Lambda_{2,2} \\ \vdots \\ \Lambda_{n,n} \end{pmatrix},$$

$$E\Phi e e^{T} \Phi^{T} \Phi e = M_{3} \Phi \begin{pmatrix} \Lambda_{1,1} \\ \Lambda_{2,2} \\ \vdots \\ \Lambda_{n,n} \end{pmatrix}$$

$$= M_{3} \begin{pmatrix} \sum_{j=1}^{n} \Phi_{1,j} \Lambda_{j,j} \\ \sum_{j=1}^{n} \Phi_{2,j} \Lambda_{j,j} \\ \vdots \\ \sum_{j=1}^{n} \Phi_{n-m,j} \Lambda_{j,j} \end{pmatrix}.$$

Note that  $\Phi_{i,j} \neq 0$  only if

$$0 \le i - j \le m$$

$$\Rightarrow i - m \le j \le i \tag{9}$$

, so

$$E\Phi e e^T \Phi^T \Phi e = M_3 \begin{pmatrix} \sum_{j=1}^n \Phi_{1,j} \Lambda_{j,j} \\ \sum_{j=1}^n \Phi_{2,j} \Lambda_{j,j} \\ \vdots \\ \sum_{j=1}^n \Phi_{n-m,j} \Lambda_{j,j} \end{pmatrix}$$
(10)